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Guo(10) **Pub. No.: US 2015/0201959 A1**(43) **Pub. Date: Jul. 23, 2015**(54) **METHOD AND APPARATUS FOR THREAD
TRANSECTION OF A LIGAMENT****Publication Classification**(71) Applicant: **Joseph Guo**, Monterey Park, CA (US)(72) Inventor: **Joseph Guo**, Monterey Park, CA (US)(21) Appl. No.: **14/674,501**(22) Filed: **Mar. 31, 2015**(51) **Int. Cl.***A61B 17/32* (2006.01)*A61B 17/34* (2006.01)(52) **U.S. Cl.**CPC *A61B 17/320036* (2013.01); *A61B 17/3403*
(2013.01); *A61B 2017/32006* (2013.01); *A61B*
2017/3413 (2013.01)

(57)

ABSTRACT

A method and apparatus for transecting soft tissue, such as a ligament, and more particularly, the transverse carpal ligament. An hollow introducer needle and a threadlike cutting element enable the method to performed in a minimally invasive manner. The cutting element is routed into position about the target ligament such that the cutting element both enters and exits the body from the same side of the ligament. The substantially smooth exterior surface of the cutting element serves to provide for a kerf-less cut.

Related U.S. Application Data

(60) Division of application No. 13/870,291, filed on Apr. 25, 2013, which is a continuation-in-part of application No. 13/460,246, filed on Apr. 30, 2012.

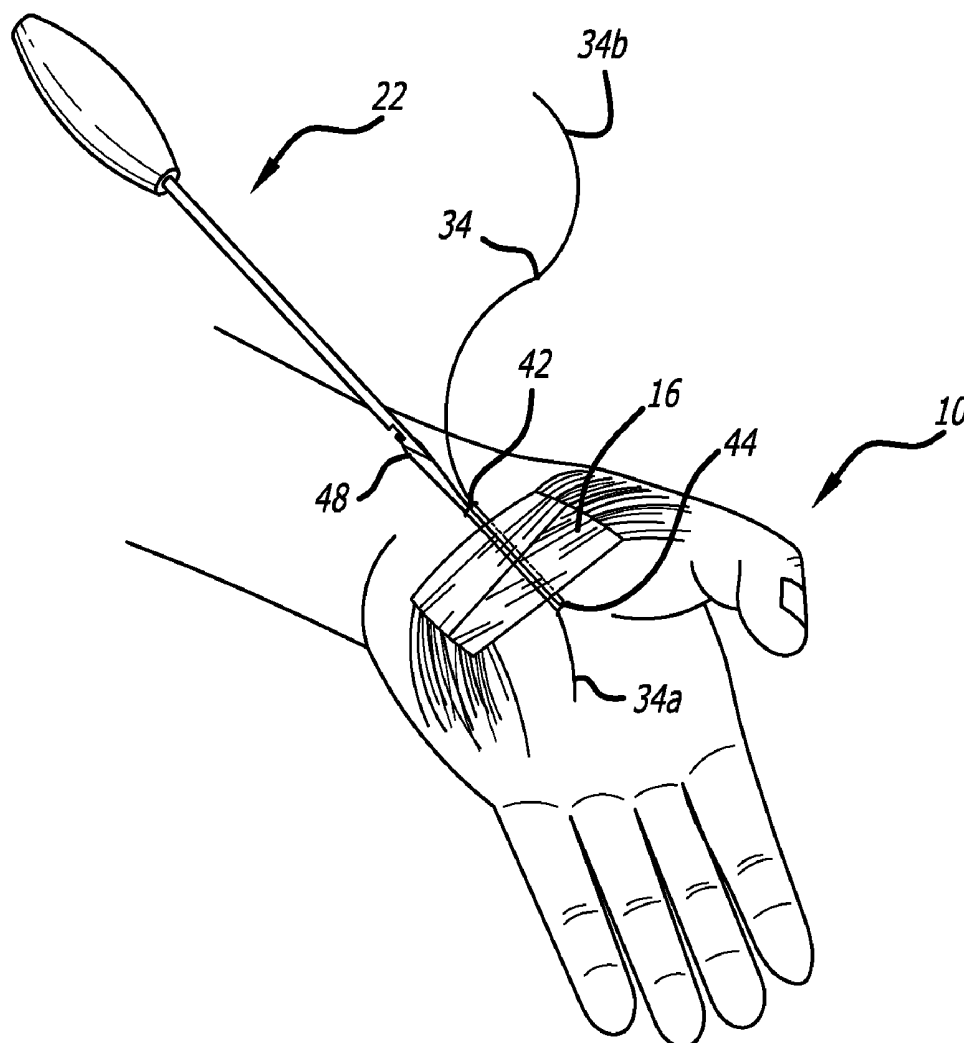


FIG. 1

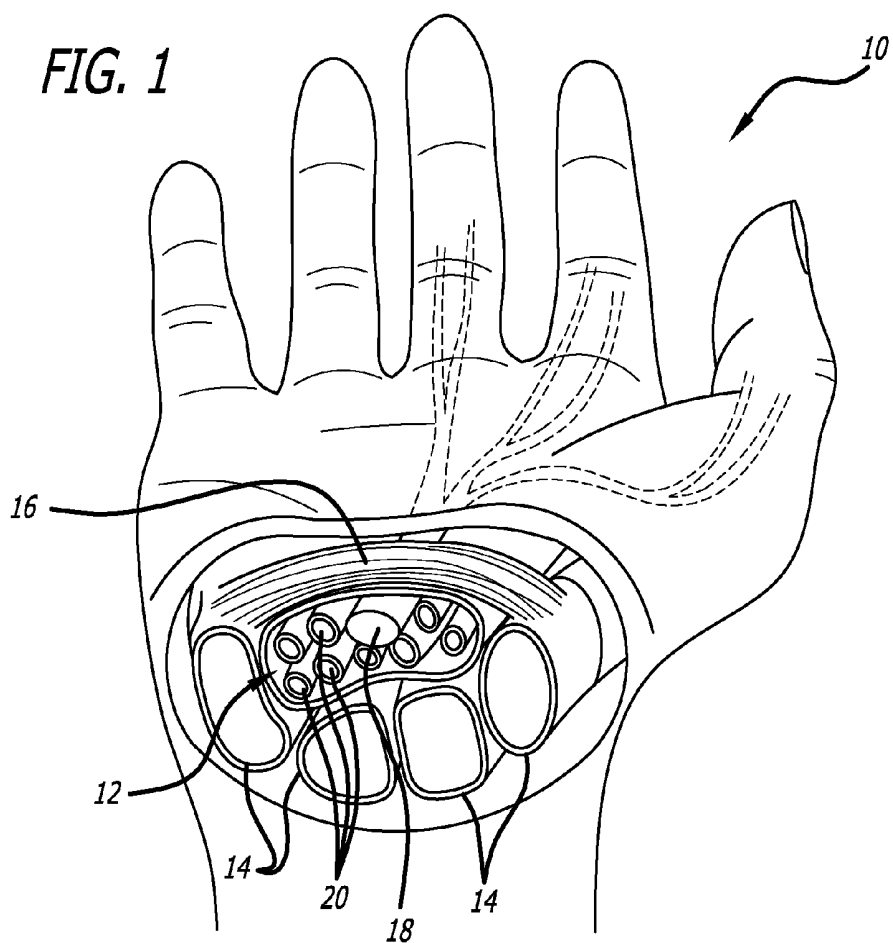
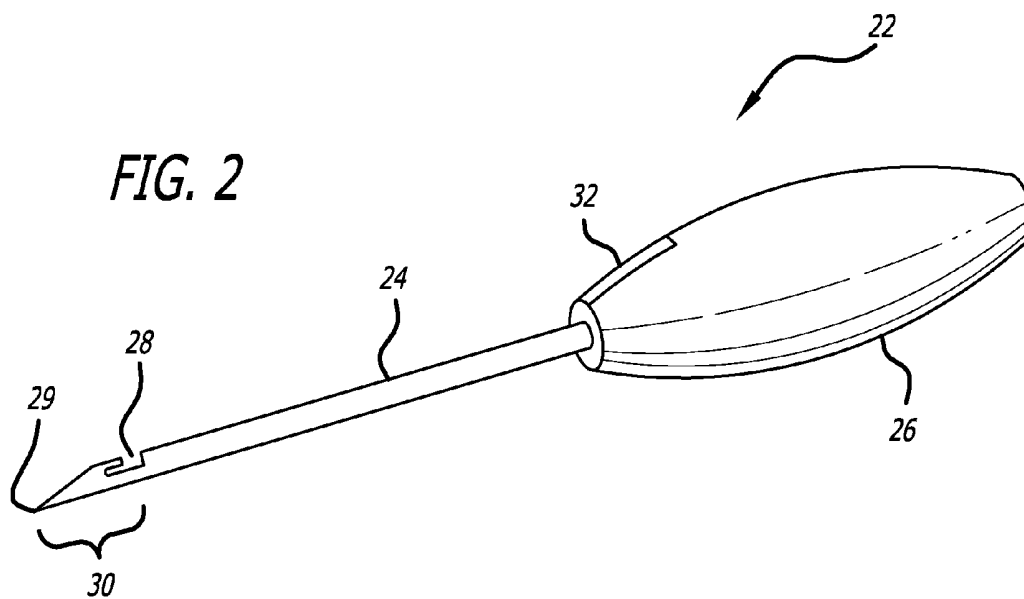
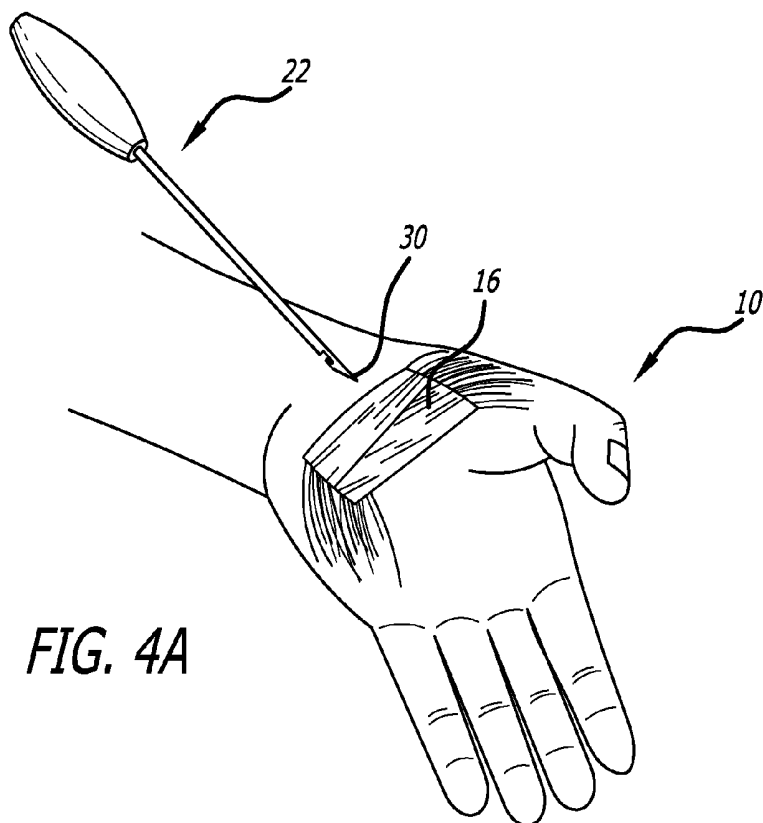
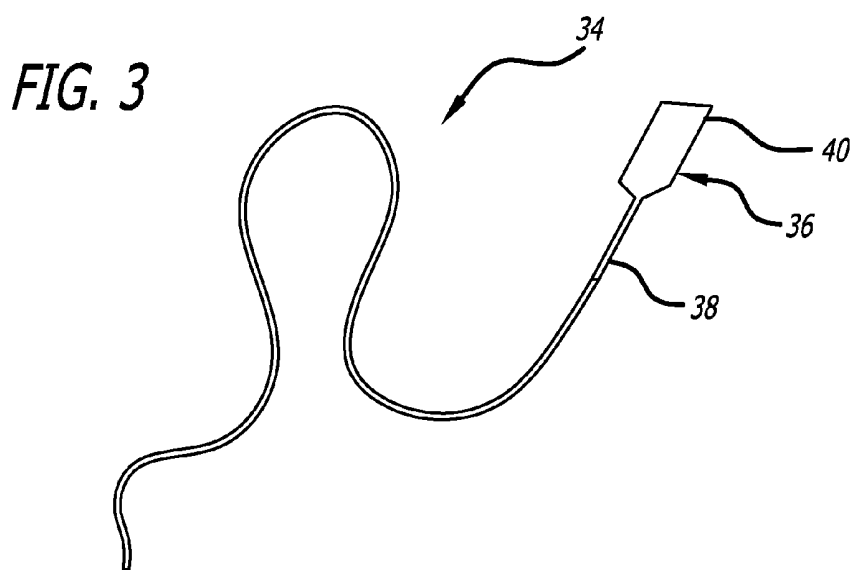
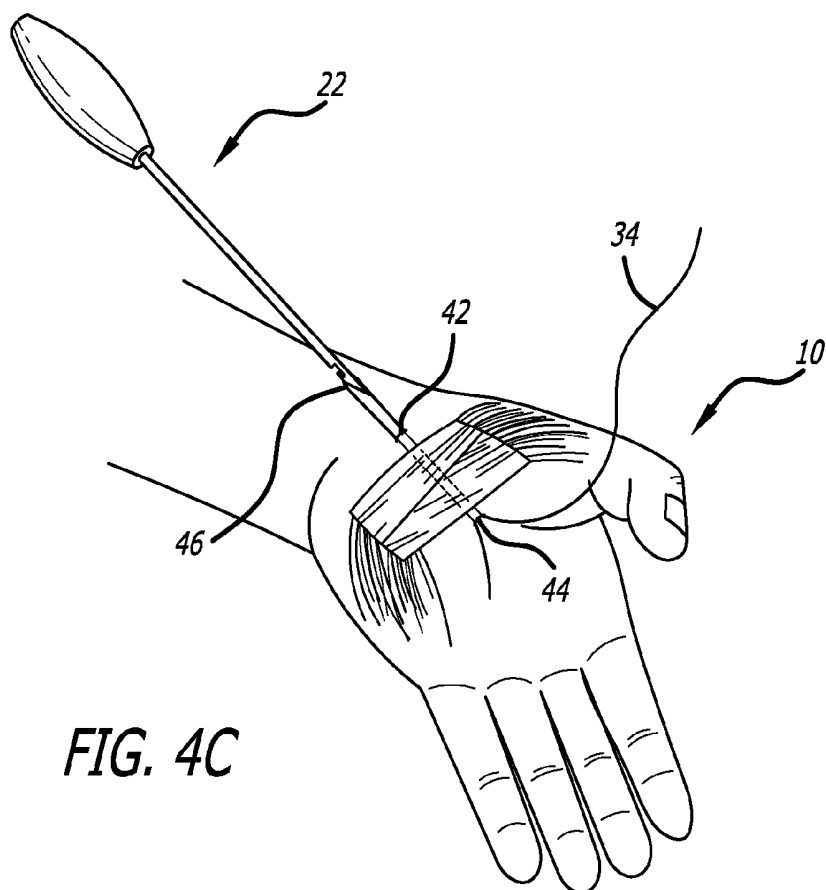
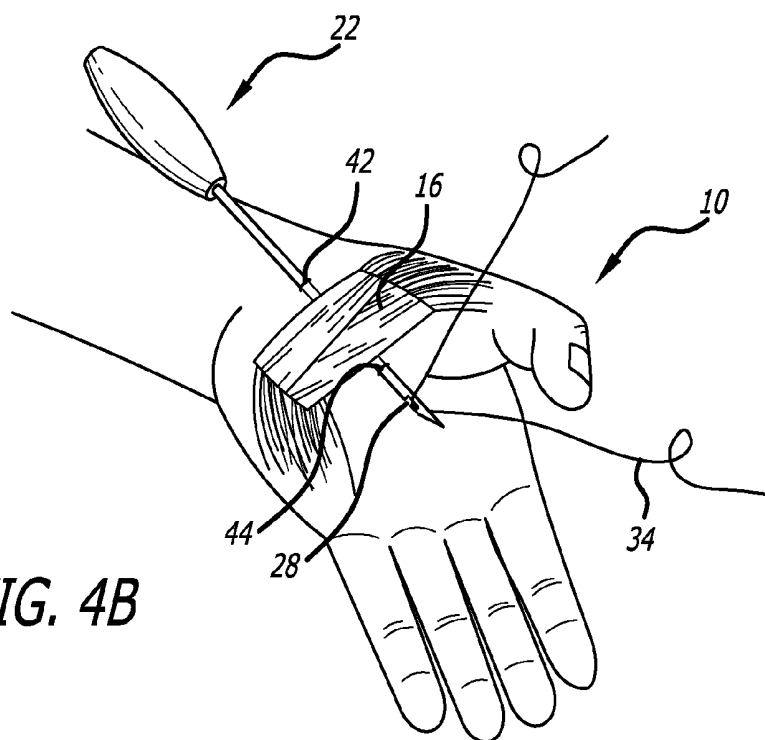


FIG. 2







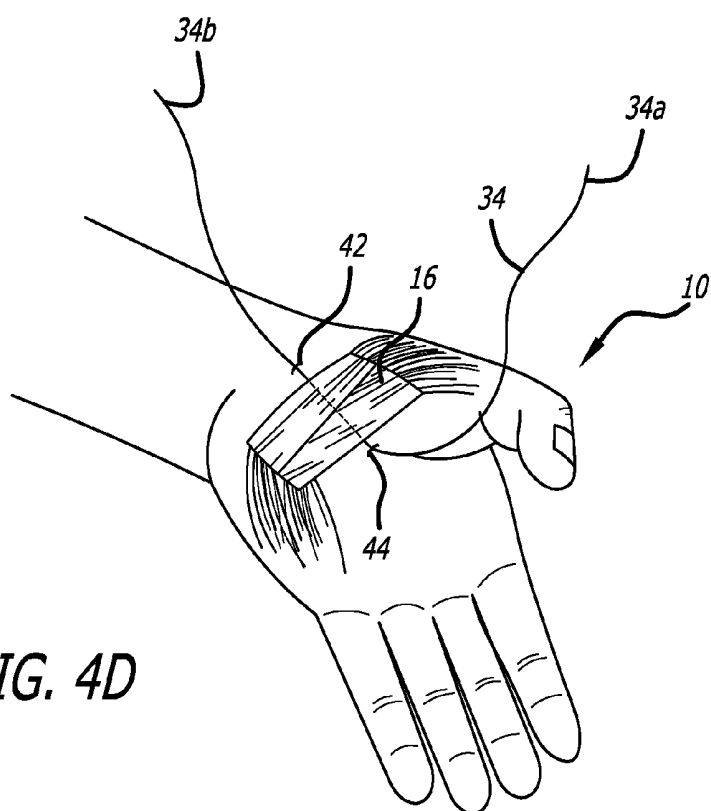


FIG. 4D

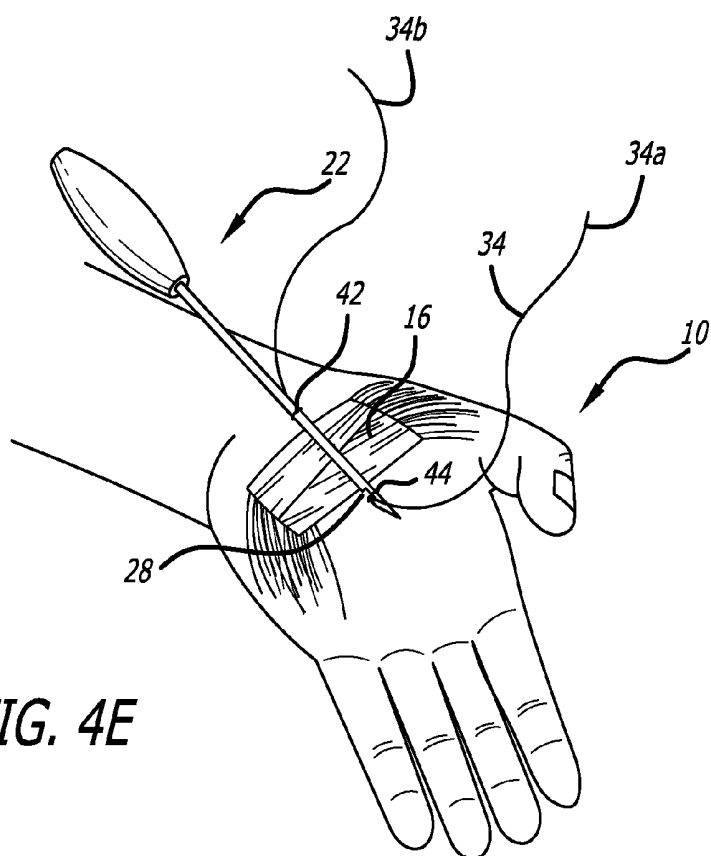
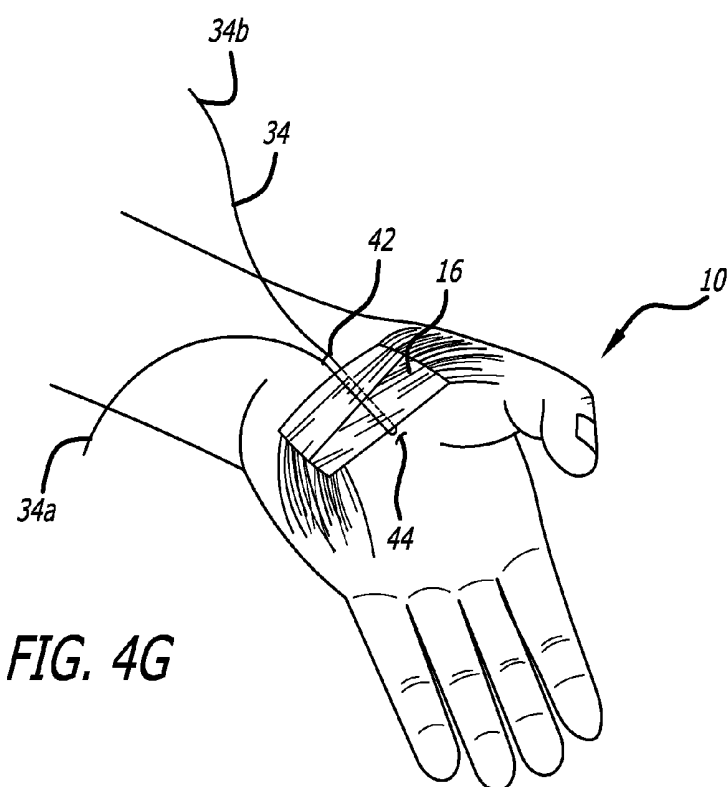
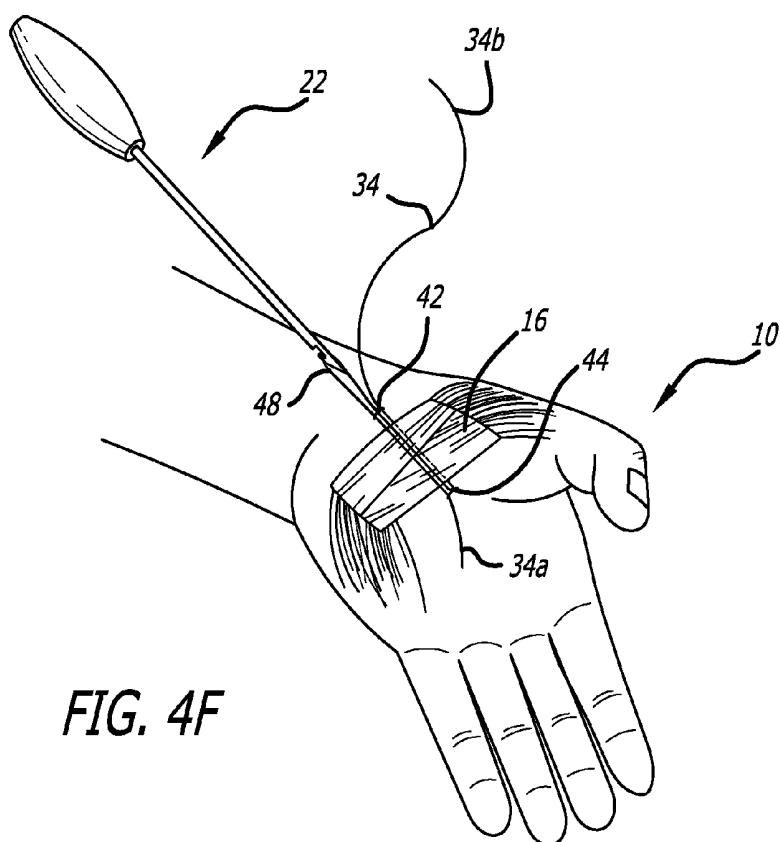


FIG. 4E



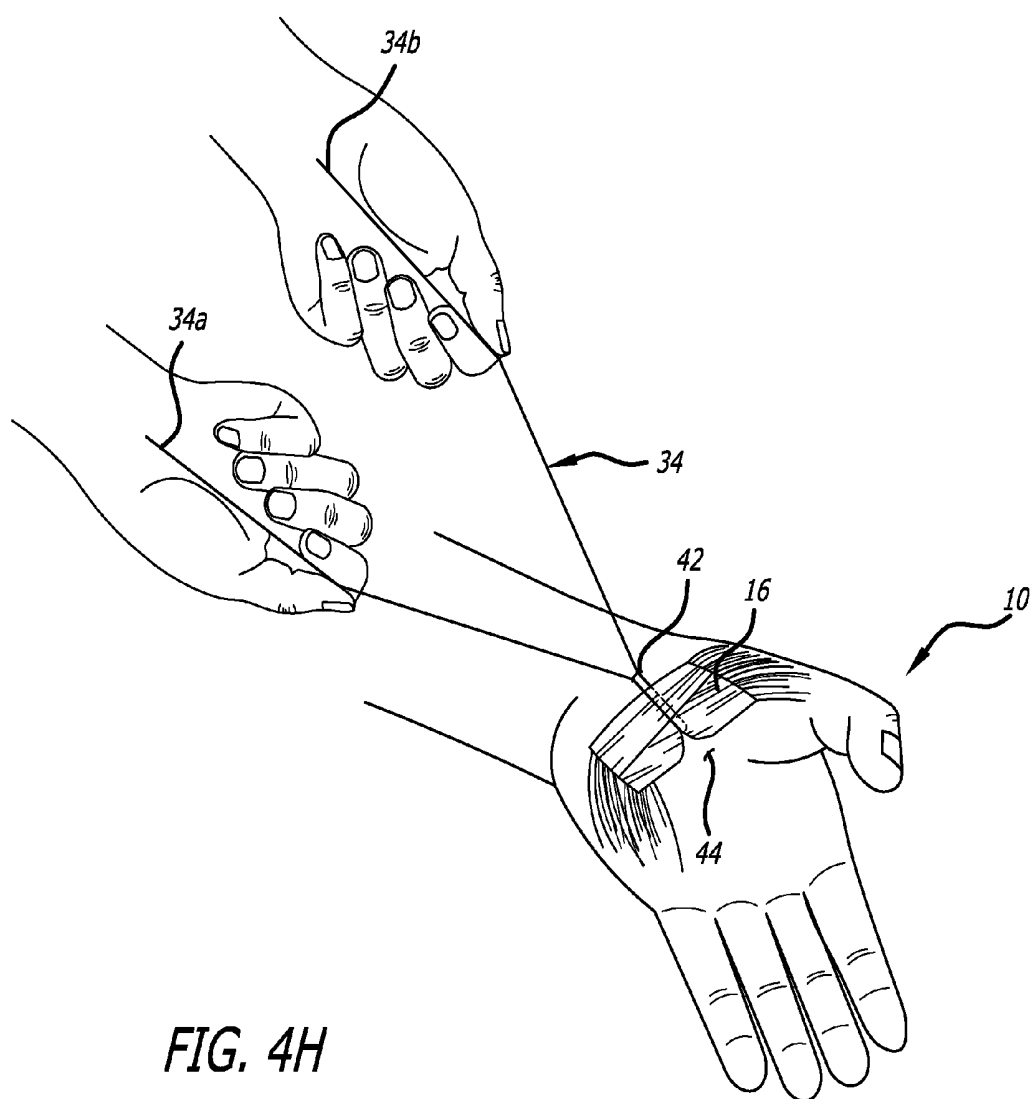
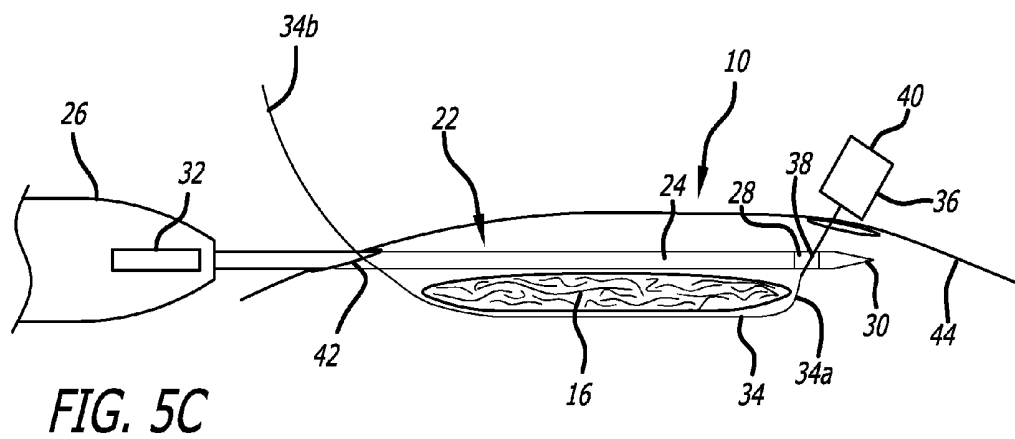
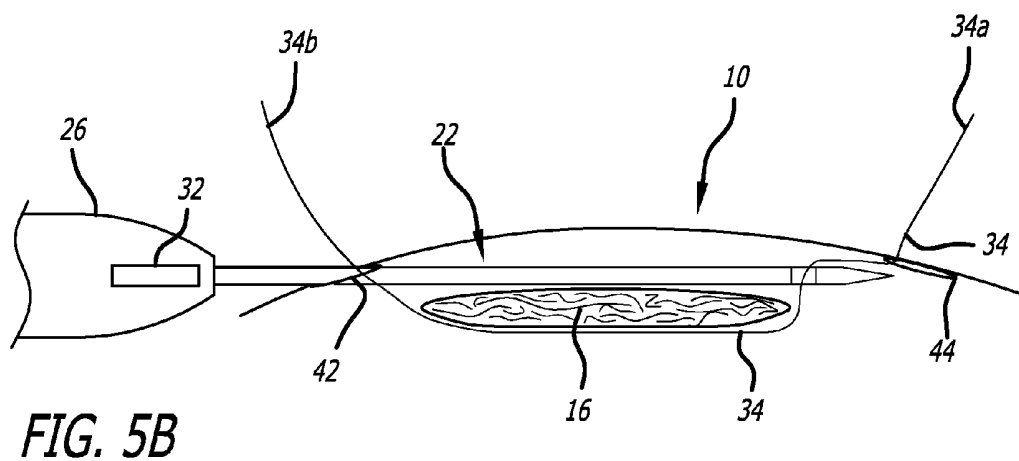
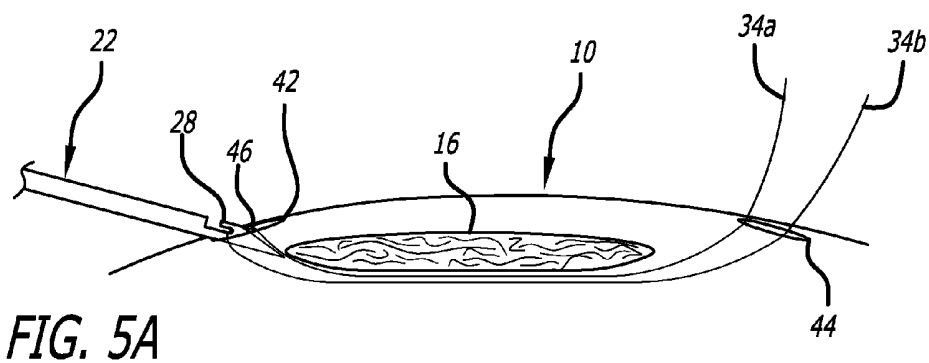
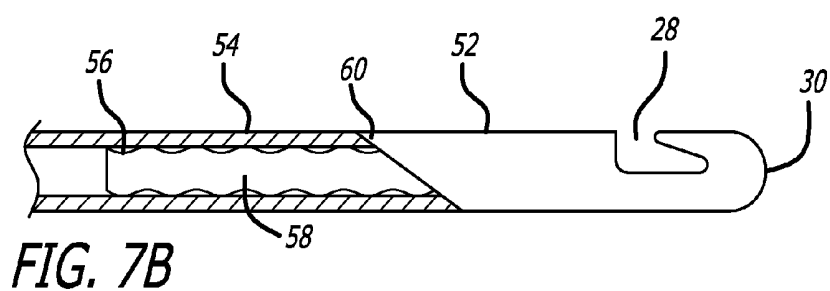
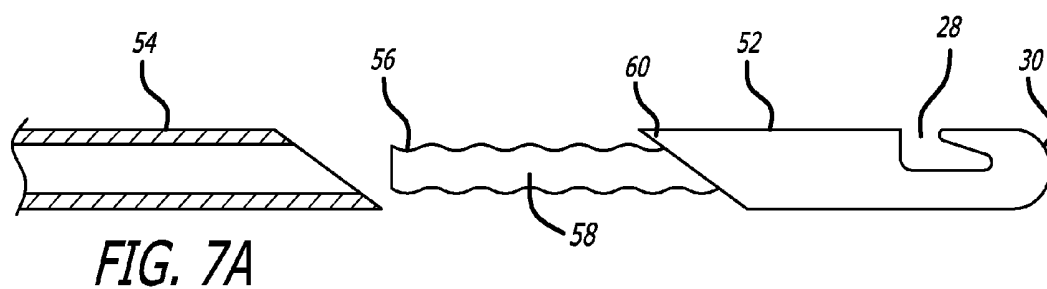
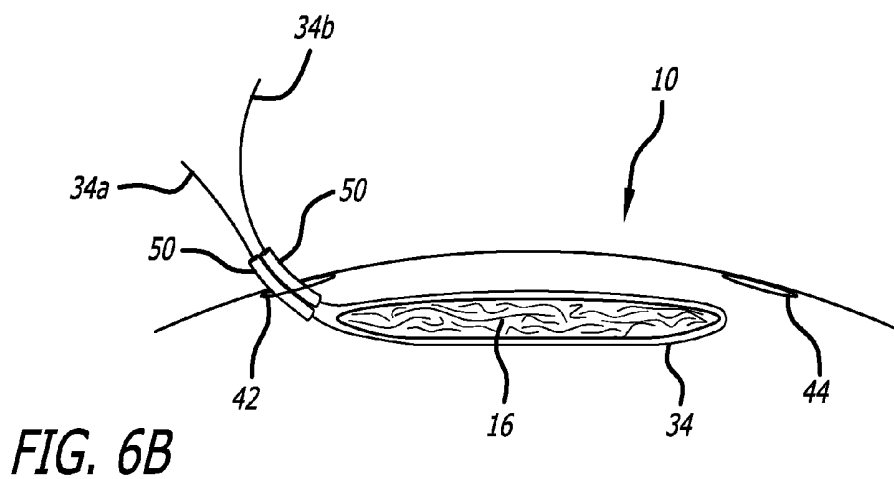
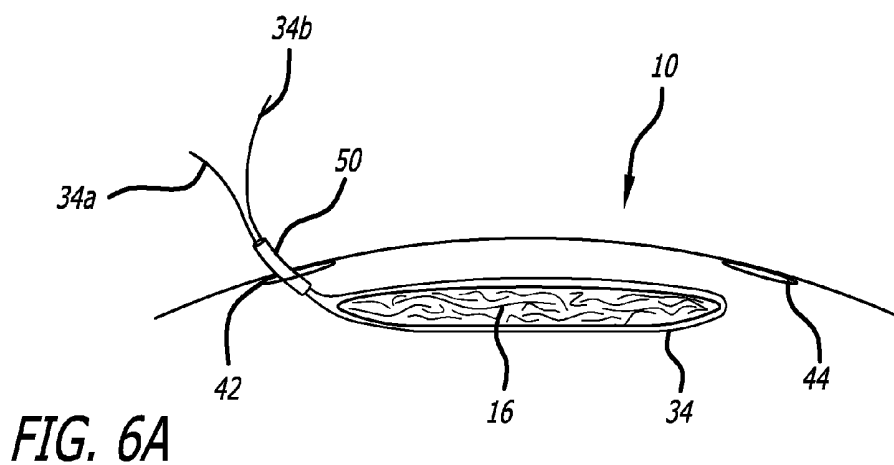
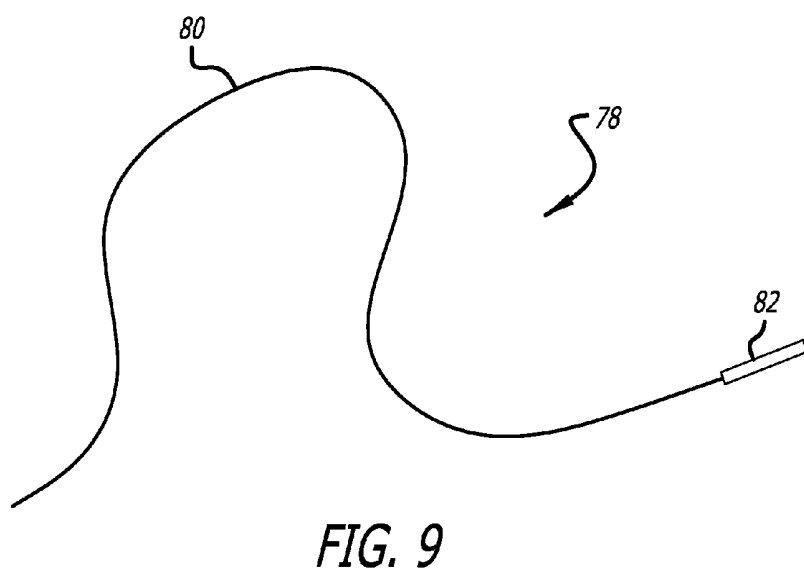
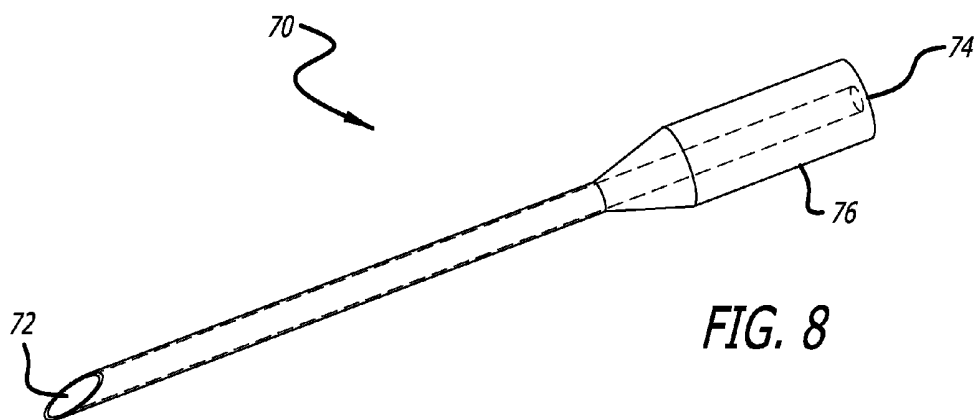
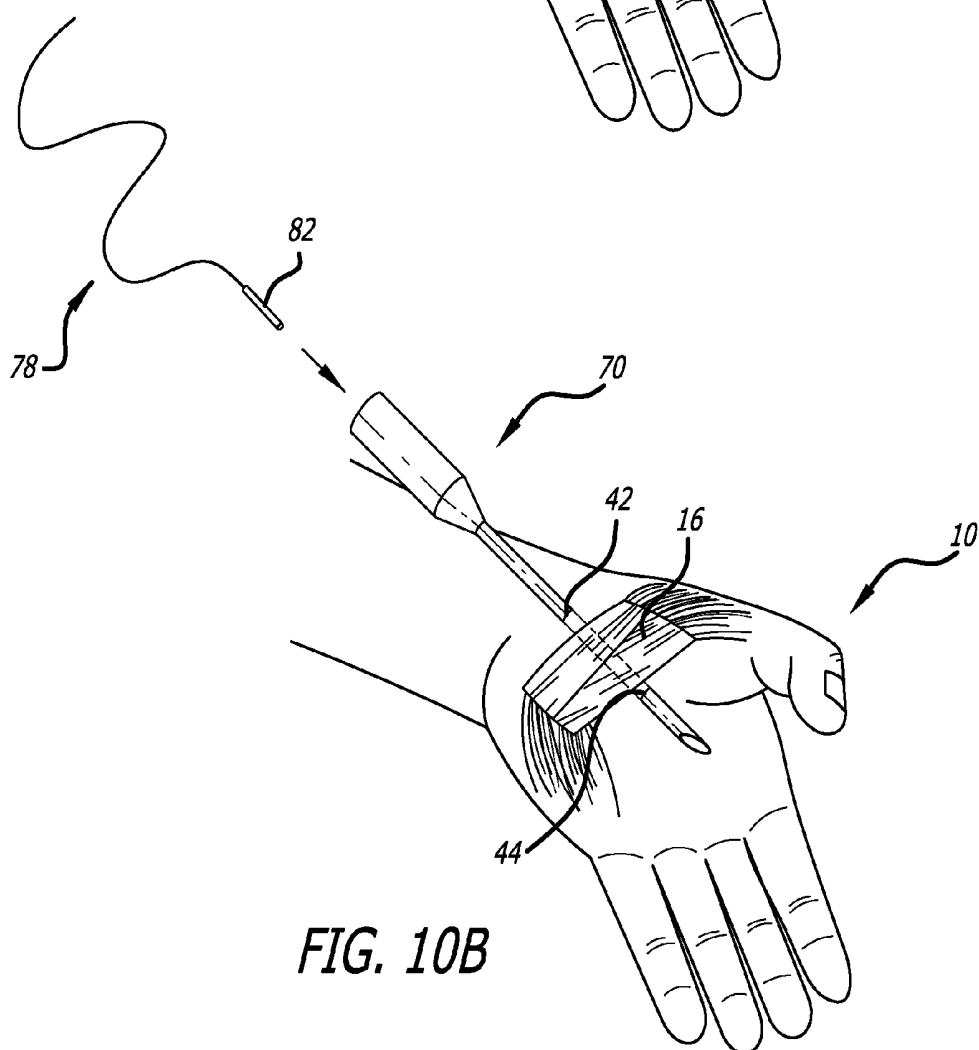
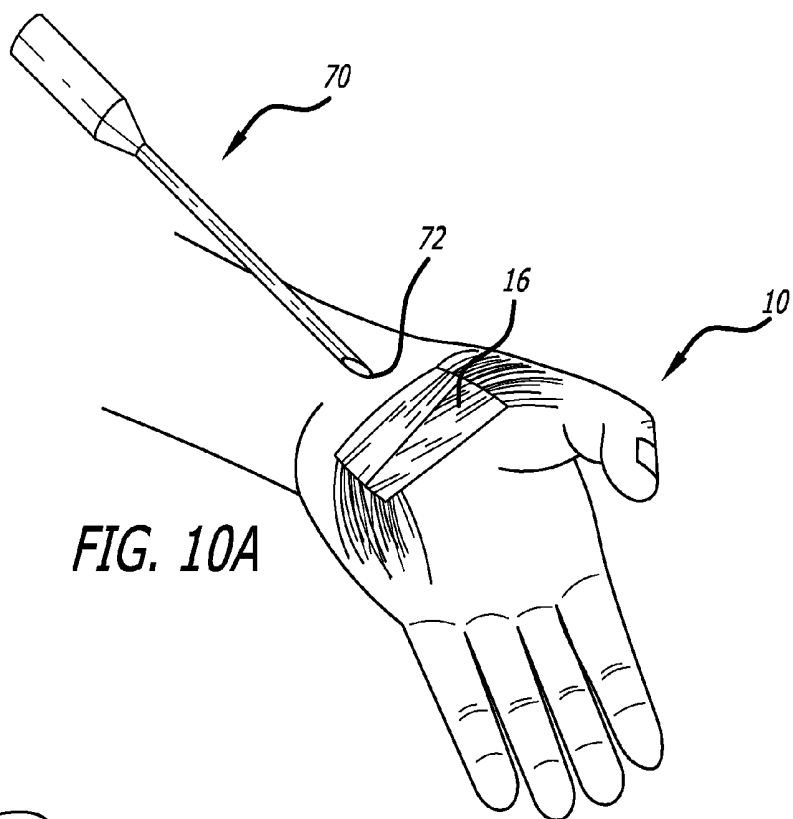


FIG. 4H









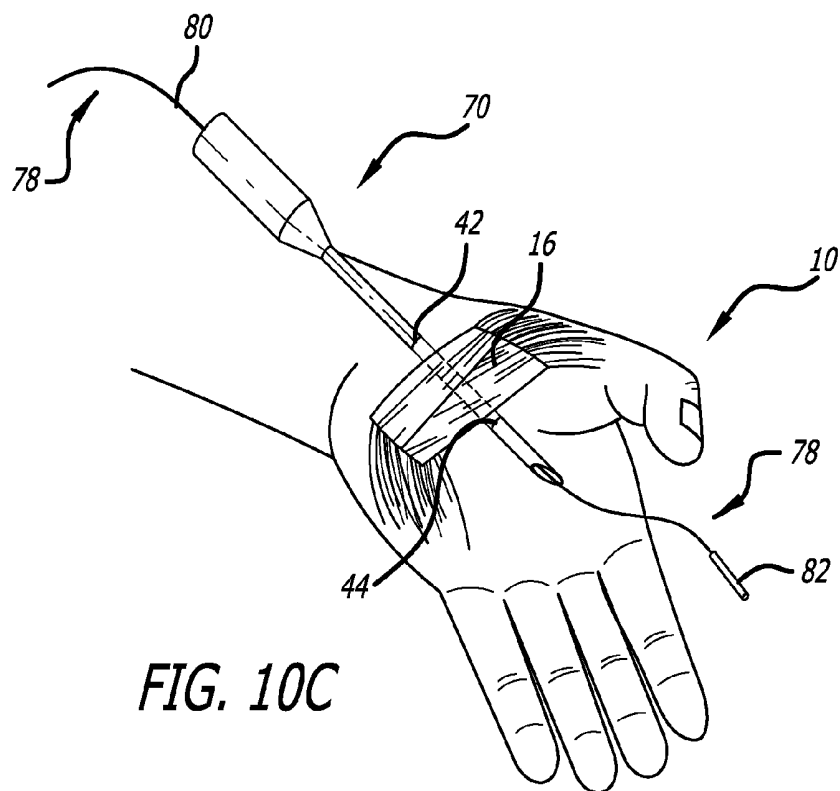


FIG. 10C

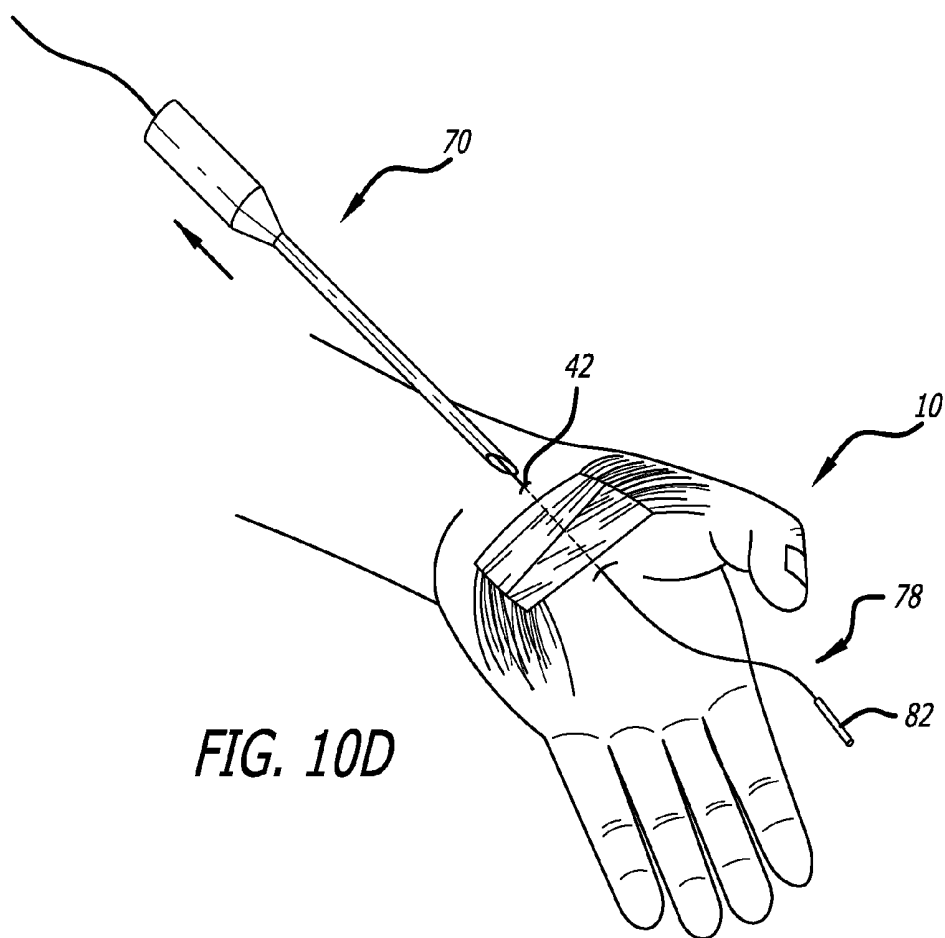
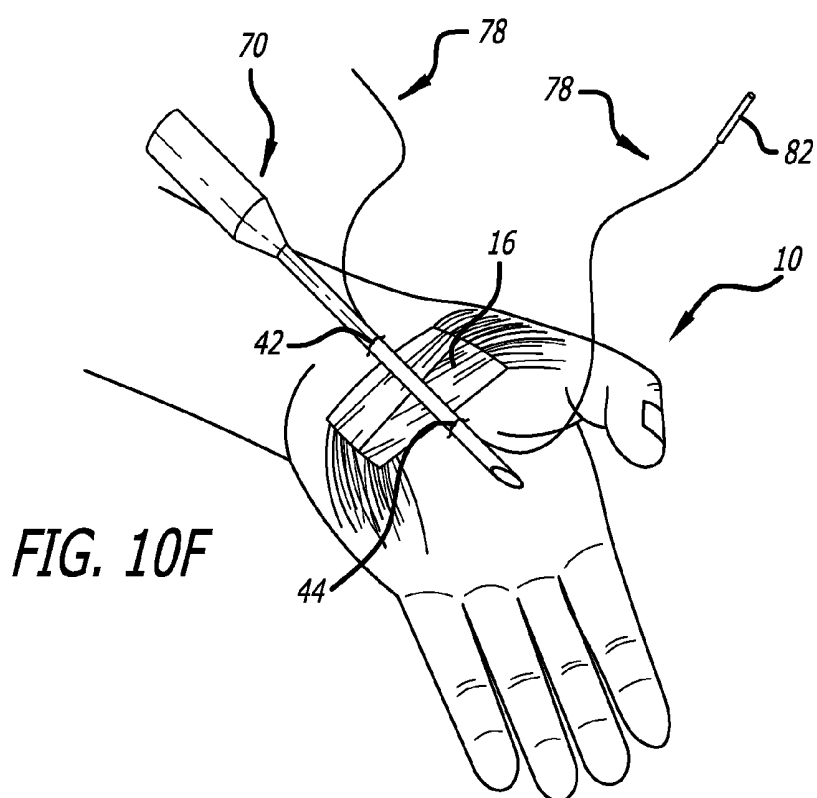
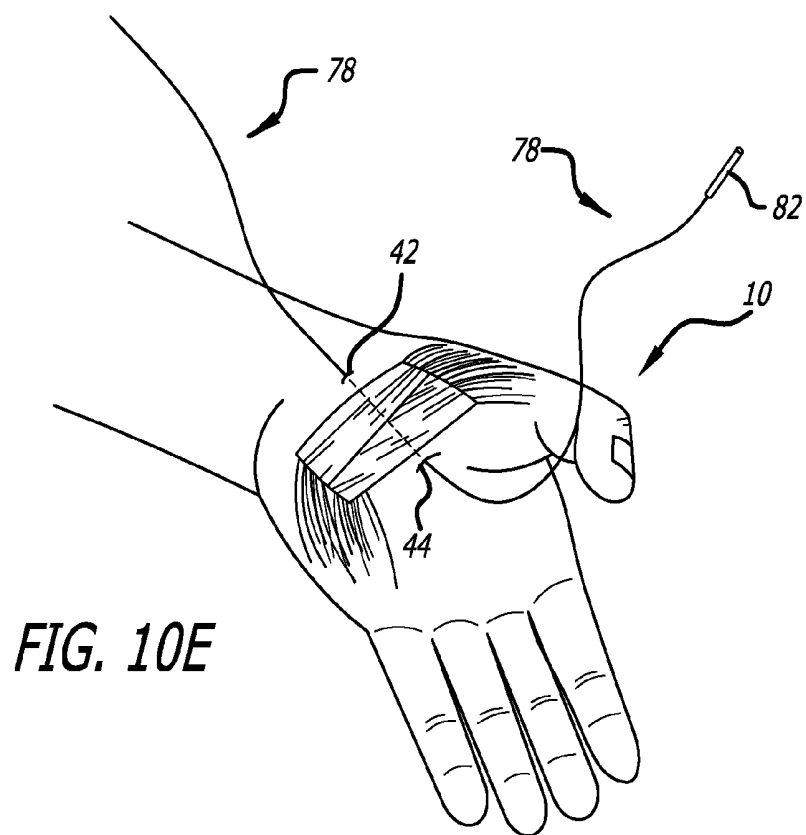
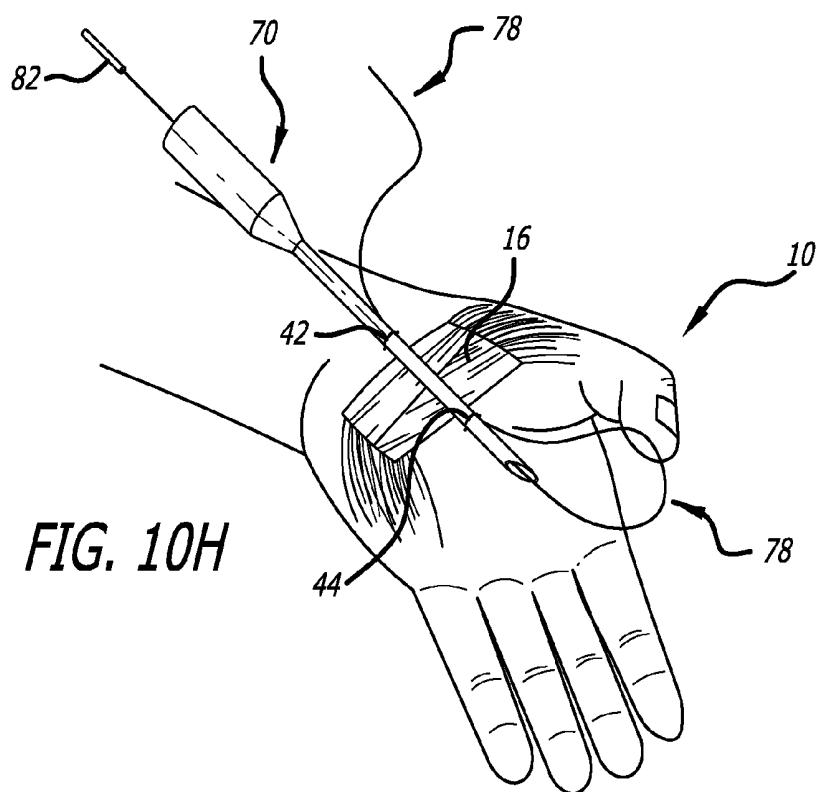
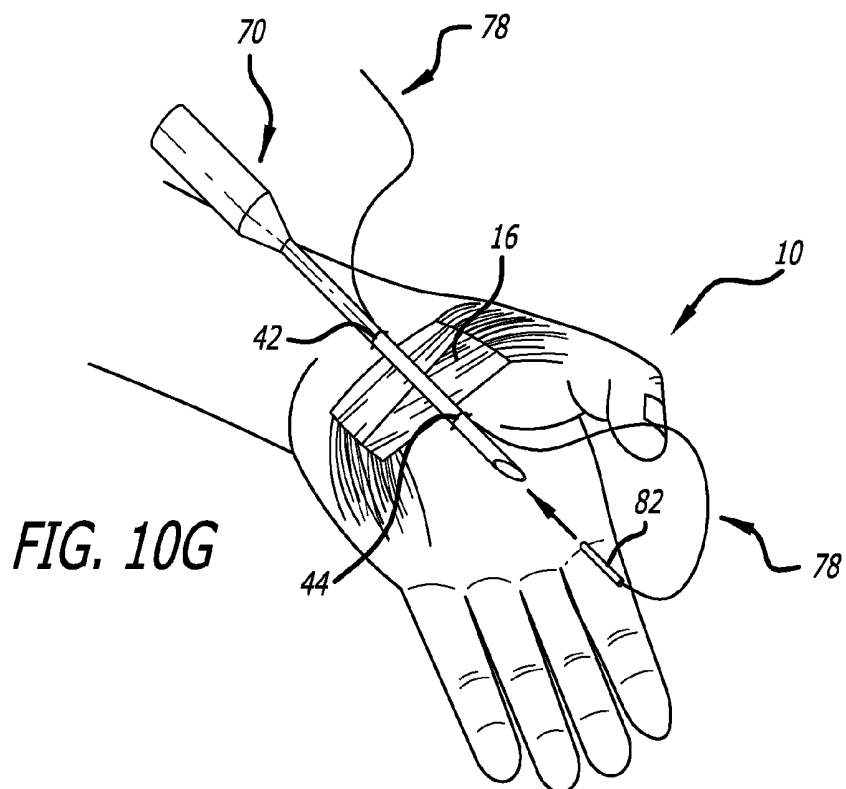
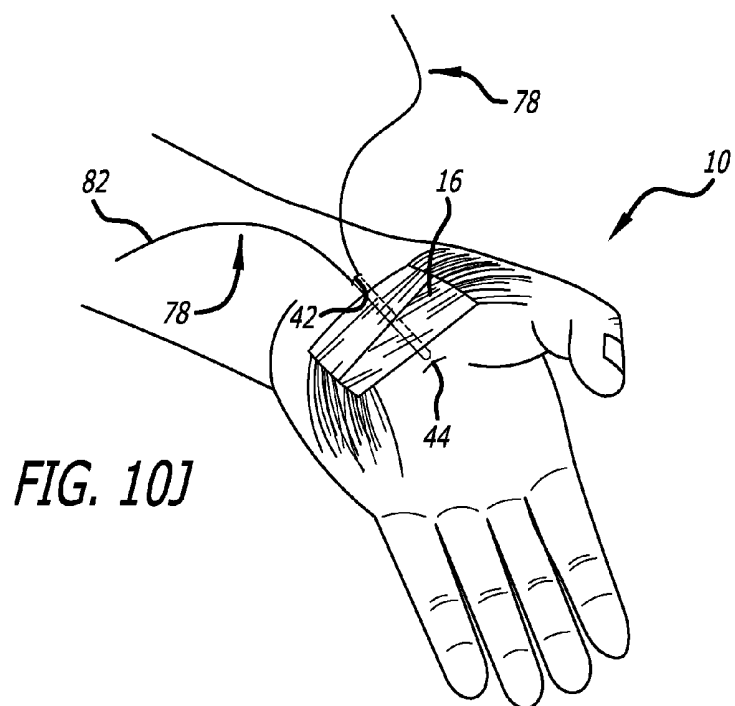
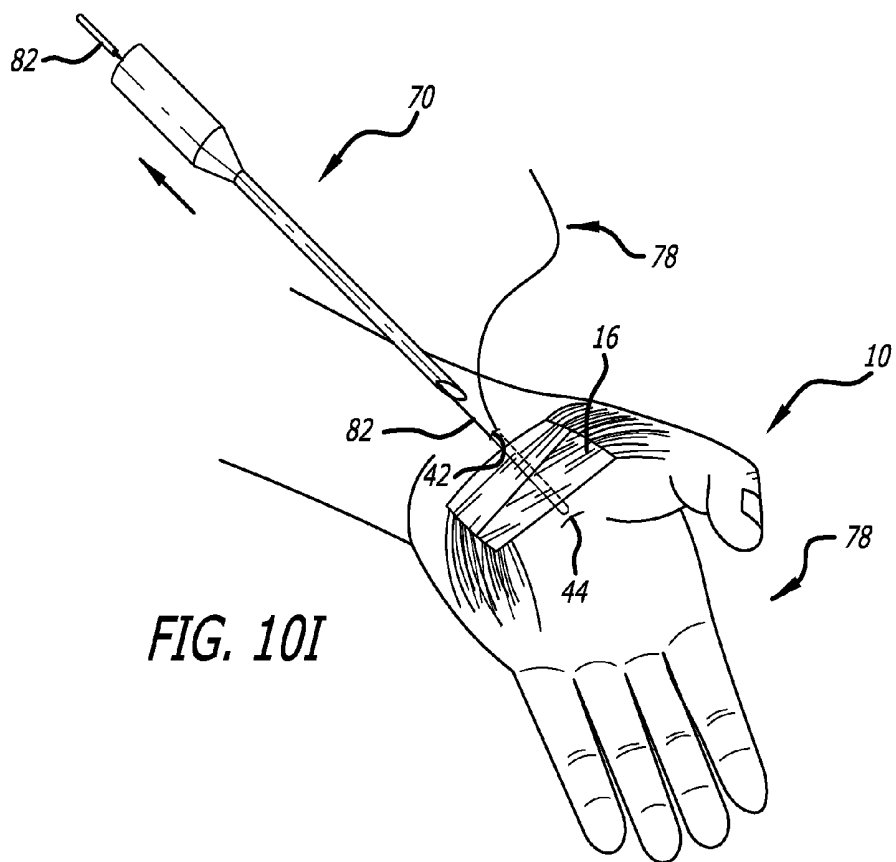


FIG. 10D







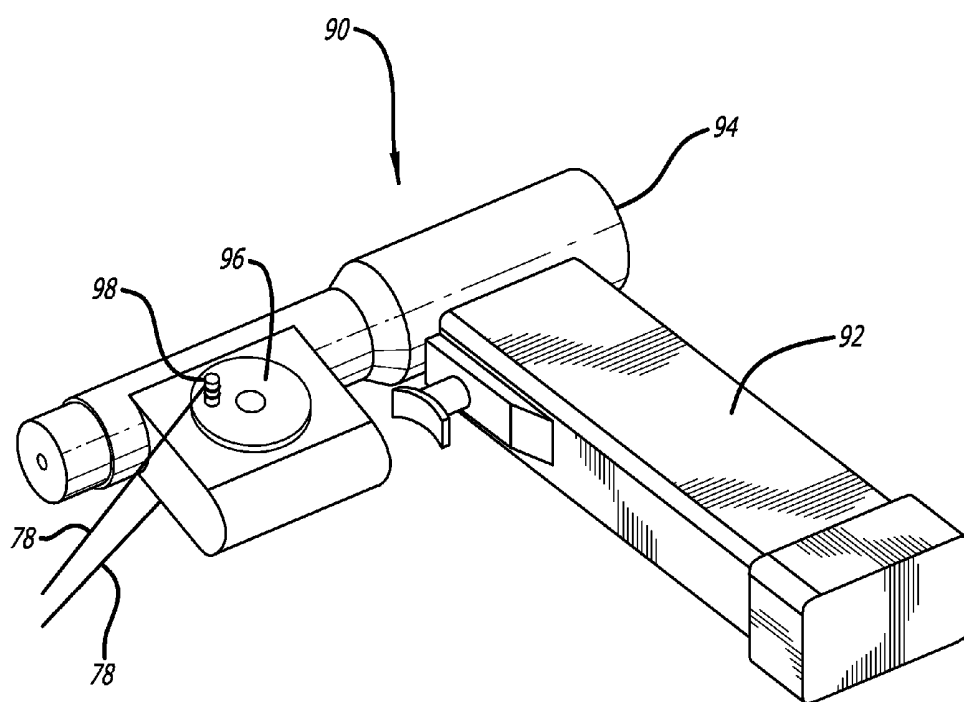
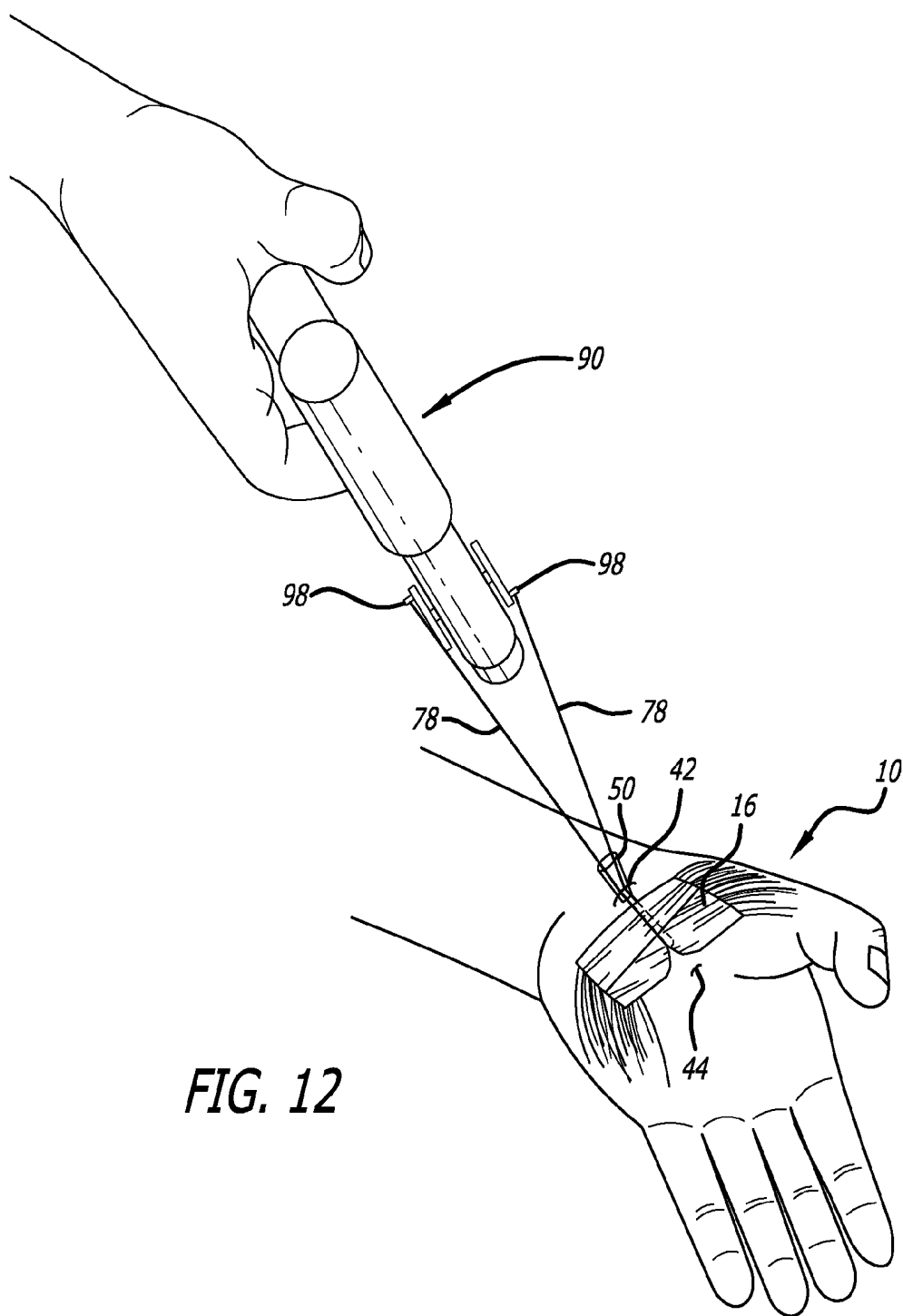


FIG. 11



METHOD AND APPARATUS FOR THREAD TRANSECTION OF A LIGAMENT

CROSS-REFERENCES TO RELATED APPLICATIONS

[0001] This application is a division of U.S. Ser. No. 13/879,291 filed Apr. 25, 2013, which is a continuation-in-part of U.S. Ser. No. 13/460,246, filed on Apr. 30, 2012, incorporated by reference herein in its entirety.

[0002] The present invention is generally directed to a surgical method and to an apparatus for performing such method. More particularly, the invention provides for the transection, by minimally invasive means, of a ligament such as for example the transverse carpal ligament that is commonly released as a treatment for carpal tunnel syndrome.

BACKGROUND

[0003] Many people suffer from injury to the soft tissues of the wrist and carpal tunnel, often caused by frequent, sustained repetitive motion involving the hands. Repetitive activities which require the same or similar hand/wrist action can result in injuries which have been collectively referred to as Cumulative Repetitive Stress Syndrome or Repetitive Strain Injury. The most familiar and common of such wrist injuries is known as carpal tunnel syndrome which produces pain, discomfort, nerve conduction disturbances, and impairment of function of the hand and sometimes the arm as well. The most common symptoms of this condition include intermittent pain and numbness of the hand.

[0004] Carpal tunnel syndrome occurs when the median nerve which runs from the forearm into the hand, becomes pressed or squeezed at the wrist. The median nerve provides feeling in one's thumb and along with index, middle and ring fingers. The median nerve controls sensations to the palmar side of the thumb and these fingers as well as impulses to some muscles in the hand which allow the fingers and thumb to move. The median nerve receives blood, oxygen and nutrients through a microvascular system which is present in the connective tissue surrounding the nerve fiber. Increased pressure on the nerve fiber can constrict these microvessels and will reduce the blood flow to the median nerve. Any prolonged deprivation of oxygen and nutrients can result in severe nerve damage.

[0005] The median nerve passes through the carpal tunnel, a canal in the wrist surrounded by the carpal bones on three sides and a fibrous sheath called the transverse carpal ligament on the fourth side. In addition to the median nerve, the nine flexor tendons in the hand pass through this canal. When compressed, the median nerve will cause pain, weakness or numbness in the hand and wrist which may also radiate up along the arm. The median nerve can be compressed by a decrease in the size of the carpal canal itself or an increase in the size of its contents (i.e. such as the swelling of the flexor tendons and of the lubrication tissue surrounding these flexor tendons), or both. For example, conditions that irritate or inflame the tendons can cause them to swell. The thickening of irritated tendons or swelling of other tissue within the canal narrows the carpal canal, causing the median nerve to be compressed. The cross-sectional area of the tunnel also changes when the hand and wrist changes positions. Wrist flexion or extension can decrease the cross-sectional area, thus increasing the pressure exerted on the median nerve. Flexion also causes the flexor tendons to somewhat rearrange

which can also compress the median nerve. For example, simple bending of the wrist at a 90 degree angle will decrease the size of the carpal canal. Without treatment, carpal tunnel syndrome can lead to chronic neural muscular disorders of the hand and sometimes the arm.

[0006] Treatment for carpal tunnel syndrome includes a variety of non-surgical as well as surgical procedures, wherein carpal tunnel release is one of the most common surgical procedures that is performed. Such surgery involves the severing of the transverse carpal ligament to relieve the pressure on the median nerve and is commonly performed via either open or endoscopic methods. In open methods, the skin lying over the carpal tunnel is incised after which the transverse carpal ligament is transected under direct vision. The skin is then reapproximated with sutures. Endoscopic methods require incision of the skin in one or more locations to allow for the insertion of an endoscope along with various tools that are needed to transect the ligament. Such tools typically include a combination of a specially configured scalpel and guide instrument. The insertion of such tools into proper position below, above or both below and above the target ligament further requires the formation of one or more pathways in the hand with attendant trauma to the surrounding tissue and the potential for nerve damage as well as a more protracted post-surgical healing process. Additionally, the use of a scalpel typically requires multiple passes thereof in order to complete a transection which causes a complex pattern of cuts to be imparted onto the severed ligament surfaces.

[0007] Less invasive techniques have been proposed including for example the use of flexible saw elements that are introduced into the hand and positioned adjacent to or wrapped about a portion of the target ligament after which the saw element is reciprocated to cut the tissue. A substantial disadvantage of a cut that is made by a saw-like instrument as opposed to a knife-like instrument is inherent in the fact that a kerf is created. The material that is removed from the kerf is either deposited in and around the surgical site or additional steps must be taken to retrieve such material. Additionally, the cut surfaces that are created by a saw tend to be relatively rough and abraded with microtrauma on the cutting surface that may increase inflammatory response (edema, erythema, heat and pain), could result in local tissue adhesions and scarring which can delay or complicate the healing process.

[0008] Alternatively, techniques have been proposed wherein a taut wire, string or filament is used to cut a ligament. The cut is achieved either by the tautening of the cutting element or alternatively, by reciprocating the taut element. Disadvantages associated with such an approach are inherent in the less than optimal geometry by which a taut wire can be brought to bear on the target ligament and by the invasiveness of the tightening apparatus.

[0009] A new method and apparatus is needed with which tissue such as a ligament can be percutaneously accessed and transected so as to cause a very minimal amount of disruption to the surrounding tissue and by which a smooth, kerf-less cut is achieved.

SUMMARY OF THE INVENTION

[0010] The present invention provides for the minimally-invasive transection of tissue such as a ligament. The method and apparatus obviate the need for any incisions, minimizes disruption of the tissue surrounding the target ligament,

enables a smooth kerf-less cut of the target ligament to be achieved, requires no suturing and can be easily and quickly performed in a clinic setting.

[0011] More particularly, the invention provides for the introduction of a thin and flexible thread-like cutting element into the body and its routing about the target ligament. Subsequent manipulation of the protruding ends of the smooth cutting element serves to transect the ligament by a smooth kerf-less cut. A routing tool component of the invention enables the cutting element to be easily and quickly introduced and routed into position about the target ligament with minimal disruption or trauma to the surrounding tissue. The routing tool component may take the form of a hollow introducer needle or a specially configured hooked retrieval needle comprising a thin, rigid and elongated needle-like element having near its distal end a hook-like feature formed therein that is dimensioned to engage the cutting element and configured to maintain engagement therewith when being pulled proximally.

[0012] In the transection of the transverse carpal ligament, the routing tool component is initially used to puncture the skin of the hand so as to form a first access port at a location proximal to the ligament and laterally adjacent thereto. The tool is then extended into the hand through the carpal tunnel along a path immediately below the ligament and is caused to emerge from the hand through a second access port formed thereby just distal to the ligament. The position of the routing tool in the hand and especially in relation to the ligament is preferably visualized throughout the placement procedure using for example an ultrasound imaging device to enable precise maneuvering of the tool.

[0013] Should a hooked retrieval needle serve as the routing tool and once it is in the position within the hand as is described above, a length of the cutting element is engaged by the hooking element of the retrieval needle and a loop thereof is drawn into the hand via the second access port. The zero bend radius of the cutting element allows the loop that is formed to be as compact as possible. The loop is drawn under the ligament and out of the first access port where it is disengaged from the retrieval needle and its free end pulled through. Reextension of the retrieval needle into the hand and along the top surface of the ligament to the second access port allows a second length of the cutting element to be engaged and a loop thereof drawn into the hand, over the ligament and out of the first access port. By pulling the second free end of the cutting element through the hand over the ligament and out of the first access port, the routing of the cutting element about the ligament is complete leaving the cutting element in position for the transection.

[0014] Should a hollow introducer needle serve as the router tool, the cutting element is inserted into the needle's proximal end while the needle is in the position described above. The cutting element is extended through the length of the needle and approximately one half of the cutting element is pulled from the distal end of the needle. The needle is then proximally retracted from the hand to leave the cutting element in place in the hand such that a sizable portion thereof protrudes from the first access port as well as from the second access port. The hollow needle is then reinserted into the first access port and adjacent to the proximally protruding length of cutting element, is extended through the hand immediately above the ligament and out of the second access port. The distally protruding portion of the cutting element is then fed into the distal end of the hollow needle in place within the

hand and extended through its length so as to emerge from the proximal end of the needle after which the needle is retracted from the hand. The routing of the cutting element about the ligament is thereby complete leaving the cutting element in position for the transection. Alternatively, one end of the cutting element may be initially introduced into the distal end of the needle and extended there through. After retraction of the needle and reinsertion into and through the hand above the ligament, the second end of the cutting element is introduced into the distal end of the needle and fed there through. Retraction of the needle leaves the cutting element in place for the transection. As a further alternative, the needle may be reinserted into the hand via the second access port.

[0015] The physical characteristics of the cutting element are selected to facilitate a kerf-less cut through the ligament. The small diameter and high tensile strength of the cutting element provides for the transection of the ligament by the manipulation of the ends of the cutting element. Unequal forces can alternately be applied to the two ends of the cutting element to induce a reciprocating cutting action. Alternatively, one end can be pulled with greater force than the other element so as to pull the cutting element in a single direction as it cuts through the ligament. As a further alternative, both ends can be pulled simultaneously with equal force to simply pull the cutting element through the ligament. The substantially smooth, none abrasive surface of the cutting element causes a knife-like cut to be achieved without the formation of a kerf and thus without an attendant deposition of detached material in and about the surgical site. Reciprocation may preferably be achieved with the use of a power tool, by which the two ends of the cutting element are alternating pulled. A stiffened section one or both ends of the cutting element facilitates the introduction of the cutting element into the hollow introducer needle.

[0016] The very small cross-section of the routing tool, whether it takes the form of the hollow introducer needle or the hooked retrieval needle, and of the cutting element, as well as minimally invasive method by which such hardware is introduced and positioned within the hand greatly reduces the risk of injury to the median nerve as well as to the smaller nerves that branch out therefrom. Additionally, the fact that the cutting element is positioned via only two tiny punctures and that the transection is performed via only one of those punctures, recovery time is minimal and scarring is essentially negligible.

[0017] The invention can additionally be modified in order to further simplify the surgical procedure. For example the sequence of steps can be altered in the routing of the cutting element about the ligament such that the routing tool is first extended across the top of the ligament before the tool is subsequently extended through the carpal tunnel for the routing of the cutting element about the ligament. Additionally, a rigid alignment tool may be attached to the second end of the cutting element to facilitate engagement of the cutting element by the hooked retrieval needle embodiment of the routing tool component at a location completely within the hand and thus much closer to the distal edge of the ligament in order to minimize the transection of any tissue adjacent to the ligament. A retrieval needle may further be marked so as to allow the rotational orientation of the hooking element to be ascertained while within the hand and thereby enhance the ability to engage the cutting element. Additionally, a protective sleeve about a portion of the cutting element may be employed to protect tissue located between the proximal

entry port and the ligament. Both ends of the cutting element may be caused to extend through a single sleeve or each end may be caused to extend about its own protective sleeve.

[0018] These and other advantages of the present invention will become apparent from the following detailed description of preferred embodiments which, taken in conjunction with the drawings illustrate by way of example the principles of the invention.

BRIEF DESCRIPTION OF THE DRAWINGS

[0019] FIG. 1 is a cross-sectional view of the carpal tunnel area of the hand;

[0020] FIG. 2 is a perspective view of a preferred embodiment of the routing tool component of the present invention in the form of a hooked retrieval needle;

[0021] FIG. 3 is a perspective view of a preferred embodiment of the cutting element of the present invention;

[0022] FIGS. 4A-H are cross-sectional views of the hand with a revealed transverse carpal ligament illustrating a preferred sequence of steps for practicing the method of the present invention using a hooked retrieval needle as the routing tool component;

[0023] FIGS. 5A-C are cross-sectional views of the hand and the transverse carpal ligament illustrating alternative preferred steps for practicing the method of the present invention;

[0024] FIGS. 6A and B are cross-sectional views of the hand and the transverse carpal ligament illustrating an alternative preferred embodiment in which protective tubes are used;

[0025] FIGS. 7A and 7B are greatly enlarged cross-sectional views of an alternative preferred embodiment of the hooked retrieval needle;

[0026] FIG. 8 is a perspective view of another preferred embodiment of the routing tool component of the present invention in the form of a hollow introducer needle;

[0027] FIG. 9 is a perspective view of another preferred embodiment of the cutting element of the present invention;

[0028] FIGS. 10A-J are cross-sectional views of the hand with a revealed transverse carpal ligament illustrating a preferred sequence of steps for practicing the method of the present invention using a hooked retrieval needle as the routing tool component;

[0029] FIG. 11 is a perspective view of a power tool for reciprocating the cutting element once in position about the target ligament; and

[0030] FIG. 12 illustrates the power tool being used to reciprocate the cutting element in place about the ligament.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

[0031] The present invention provides for the minimally invasive transection of tissue and obviates the need for scalpels, saws or endoscopes. The invention is especially applicable for the transection of ligaments and most particularly, for the release of the transverse carpal ligament in the treatment of carpal tunnel syndrome.

[0032] FIG. 1 is a cross-sectional view of the carpal tunnel area of the hand 10. The carpal tunnel 12 is the area of the wrist and palm of the hand 10 formed by a U-shaped cluster of bones 14 that form a hard floor and two walls of the tunnel. The roof of the tunnel is formed by the transverse carpal ligament 16 which attaches to the wrist bones. Within the

confines of the tunnel is the median nerve 18 and the flexor tendons 20 of the thumb and fingers. Carpal tunnel syndrome is caused by a compression of the median nerve by either a decrease in the size of the tunnel or an increase in the size of its contents. Such pressure may be relieved by a release of the ligament such as by a transection thereof.

[0033] FIG. 2 is perspective view of a preferred embodiment of the routing tool of the present invention wherein such tool takes the form of a hooked retrieval needle 22. The tool generally includes a thin, rigid and elongated distal section 24 and a handle 26 at its proximal end. The distal section has hooking element 28 disposed near its distal end 30. The hooking element is preferably defined by a void formed within the outer diameter of the elongated distal section of the retrieval tool so as to present a substantially smooth outer surface and thereby minimize the potential for trauma as the tool is extended into or retracted from tissue. The distal end may have a sharp tip 29 as is shown in the illustrated embodiment. Alternatively, the tip may have a more blunted configuration. The hooking element is spaced slightly back (reference numeral 30) from the distal end. A marking 32 on the handle may be included demarking the rotational position of the hook-like feature near the tool's distal end. The length of the distal section is selected to be greater than the width of the transverse carpal ligament. Its diameter is selected to be no greater than about 1 mm.

[0034] FIG. 3 is a perspective view of the cutting element 34 of the present invention with the optional locator tool 36 attached thereto. The cutting element has a flexible, small diameter, thread-like structure with a high tensile strength and a smooth surface, preferably with an average surface roughness no greater than 50 micrometers. The cutting element may comprise a monofilament or a plurality of braided or otherwise joined fibers or strands wherein each strand has a smooth surface so as to present a relatively smooth, non-abrasive surface. Its physical characteristics include a bend radius of less than half the thickness of the ligament and preferably a zero bend radius, a diameter of less than about 1.0 mm, and a breaking strength of over 2 lbs. The cutting element may comprise fiber or yarn formed of cotton, silk, glass fiber, carbon fiber, various plastic fibers or metal. More particularly, textile fiber, synthetic fiber, mineral fiber, polymer fiber, microfibers may be used. The optional locator tool includes a rigid distal end 38 of a diameter sufficiently small to be extended into the access port and to be captured within the hooking element 28 of the retrieval tool 22. A handle 40 is disposed near its proximal end to enable the tool to be grasped and manipulated.

[0035] FIGS. 4A-4H illustrate a preferred method of practicing the present invention. After anesthetizing the area of the hand 10 near and about the transverse carpal ligament 16, the distal end 30 of the retrieval needle 22 is brought into contact with the hand just proximal to the proximal edge of the target ligament as is shown in FIG. 4A. The ligament is visible in the Figures for purposes of clarity only as no incision is made throughout the entire procedure to in any way expose the ligament to view. Additionally, an imaging device, such as an ultrasound device, such as is commonly used for a variety of imaging applications, is used to visualize the position of the retrieval needle relative to the ligament but is not shown so as not to obscure the surgical site again for purposes of clarity. It is preferable to enter the hand at a position about 30 mm proximal of the proximal edge of the transverse carpal ligament as the carpal tunnel can then be entered at a shallower

angle obviating the need to adjust the angle of the needle after the tunnel has been reached and thereby minimizing trauma to tissue in addition to allowing the retrieval needle to be more easily imaged.

[0036] In FIG. 4B, the retrieval needle has been advanced into the hand via entry port 42, through the carpal tunnel just under the ligament and out through exit port 44. The entry and exit ports may be formed by the direct extension of the retrieval needle through the skin in the event the retrieval needle 22 is selected to have a sharp distal tip 29. In the event a retrieval tool is used with a blunt tip, a sharp instrument is necessary for forming the access ports and guide the retrieval tool into the hand. The Figure additionally shows the cutting element 34 having been engaged in the hooking element 28 near the tool's distal end. In this particular embodiment, the cutting element is devoid of a locator tool attached to its distal.

[0037] Once the cutting element 34 is engaged, the retrieval needle 22 is retracted from the hand so as to draw a loop 46 of the cutting element into the hand via port 44, through the carpal tunnel and out of entry port 42 as is shown in FIG. 4C. The loop is then disengaged from the retrieval needle and while one end of the cutting element 34a is restrained, the loop is pulled so as to draw the opposite end 34b of the cutting element free of the hand as is shown in FIG. 4D.

[0038] FIG. 4E illustrates the subsequent step of the method wherein the retrieval needle 22 is readvanced into the hand via access port 42, is guided across the top surface of ligament 16 to remerge from the hand via access port 44. The section of cutting element 34 extending from under the ligament is engaged with the hooking element 28 of the retrieval needle.

[0039] Once the cutting element 34 is again engaged, the retrieval needle 22 is retracted from the hand so as to draw a loop 48 of the cutting element into the hand via port 44, through the carpal tunnel and out of entry port 42 as is shown in FIG. 4F. The loop is then disengaged from the retrieval needle and while end 34b of the cutting element is restrained, the loop is pulled so as to draw the end 34a of the cutting element free of the hand as is shown in FIG. 4G. The cutting element is thereby in position about ligament 16 for subsequent manipulation to effect the transection. As is shown in FIG. 4H, the ends 34a, 34b of the cutting element may simply be grasped by the user, may be wound around the hands or fingers of the user for a firmer grip or alternatively, may be fitted with handles to provide for maximum grip and control. Unequal forces can alternately be applied to the two ends of the cutting element to induce a reciprocating cutting action either by hand or with the use of an appropriately configured power tool. Alternatively, one end can be pulled with greater force than the other element so as to pull the cutting element in a single direction as it cuts through the ligament. As a further alternative, both ends can be pulled simultaneously with equal force to simply pull the cutting element through the ligament. When transection has been achieved, the cutting element is simply withdrawn through access port 42. Application of a small bandage over each of the access ports 42, 44 completes the procedure.

[0040] In an alternative embodiment, and as a modification to the step shown in FIG. 4C, the retrieval needle 22 is not completely withdrawn from access port 42 as illustrated in FIG. 5A. The needle is retracted just enough to expose the hooking element 28 and allow the loop 46 of the cutting element 22 to be disengaged and withdrawn, while most of

the distal end 30 remains below the skin. As a result, it is more likely that the needle will follow the same pathway to the ligament 16 before traversing its top surface resulting in less trauma and disruption to intervening tissue both while advancing the needle as well as at the completion of the transection step.

[0041] In another alternative embodiment, and as a modification of the step shown in FIG. 4E, the retrieval needle 22 is not extended through port 44 to engage cutting element 34 as is illustrated in FIG. 5B. Rather the cutting element is engaged within the hand, preferably as close to possible to the distal edge of the transverse carpal ligament 16. The needle is shown with its hooking element rotated toward the viewer. The marking 32 on the handle 26 allows the user to ascertain the rotational orientation of the hooking element without a direct view of the distal end of the retrieval needle. By engaging the cutting element 34 closer to the distal edge of the ligament before drawing it across the top surface of the ligament, less extraneous tissue is apt to be captured between the cutting element and the ligament and thus less trauma thereto will be caused during the transection of the ligament.

[0042] As a further alternative to the preferred embodiment shown in FIG. 5B, FIG. 5C illustrates the step using the cutting element 34 having the locator tool 40 attached thereto. Once the distal end 30 of the tool is in position such that the hooking element is located just distal of the distal edge of the transverse carpal ligament as confirmed by the ultrasound image, the cutting element 34 is pulled from the end 34b projecting from access port 42 so as to draw its opposite end 34a and the locator tool that is attached thereto into access port 44. Once the locator tool is extended to the approximate depth that is illustrated, the ability to more readily engage the retrieval needle is enhanced by virtue of the locator tool's visibility under ultrasound imaging and by virtue of the tactile feedback that is provided when contact is made between the rigid distal section 24 of the retrieval needle and the rigid distal end 38 of the locator tool. Once engagement with the hooking element 28 of the retrieval needle is confirmed, the locator tool is withdrawn from access port 44, leaving the cutting element in place within the hooking element. Subsequent retraction of the retrieval needle causes a loop of the cutting element to be drawn through the pathway above the ligament and out of access port 42. Severing the cutting element from the locator tool allows the free end 34a of the cutting element to be drawn through the hand and out of the access port to complete the routing of the cutting element about the target ligament.

[0043] In the event a cutting element 34 is selected that has a larger than zero bend radius, it may be desirable to first introduce a zero bend radius pilot thread into the hand and position it about the ligament in the manner as was described above with regard to placement of the actual cutting element. Once such pilot thread is in place, one end is attached directly to one end of the cutting element and simply pulled through so as to replace the pilot thread with the cutting element. Such approach allows the size of the access ports to be minimized that would otherwise have to be enlarged in order to accommodate the larger loops 46, 48 that are formed by a cutting element having a non-zero bend radius.

[0044] A further alternative preferred method of practicing the present invention includes the use of protective tube or tubes 50 that are positioned about the cutting element at access point 42 as is illustrated in FIGS. 6A and B. Both ends of the cutting element may be passed through a single tube

(FIG. 6A) or each end may be passed through its own tube (FIG. 6B). The tube or tubes serve to protect the surrounding tissue from injury as tension is applied to the cutting element and it is drawn or reciprocated to effect the transection. The tubes are especially effective when the cutting element undergoes some curvature in and about access point 42. The thin-walled tubing is selected to be flexible but resistant to being cut by the cutting element.

[0045] In another alternative preferred embodiment, a modified retrieval tool 52 is configured for capture within a hypodermic needle 54 as is shown in FIGS. 7A and 7B. The hypodermic needle is initially used to form access port 42, to inject anesthetic and/or a liquid, such as saline solution, to inflate the surgical site so as to separate the various tissues and components to provide easier access for routing the cutting element into place. After the injection is complete, the hypodermic needle is extended out of the body to form access port 44. The specially configured blunt tipped retrieval tool is inserted into the hypodermic needle and locked into place (FIG. 7B) via locking mechanism 56. Such locking mechanism may take any of various forms including the interference fit that is created by the slightly wavy configuration of the shank 58 that is shown in the Figure. After the cutting element is engaged by the hooking element 28 of the retrieval tool, the hypodermic needle is retracted to draw loop 46 into the hand as is shown in FIG. 4C. The distal section 60 of the retrieval tool 52 may have its outer diameter selected to substantially match the outer diameter of the hypodermic needle to create a smooth transition.

[0046] FIG. 8 is perspective view of another preferred embodiment of routing tool component of the present invention wherein the tool takes the form of a hollow introducer needle 70. The hollow needle includes a sharp or blunt distal end 72 and has hollow interior extending from its distal end to its proximal end 74. A handle 76 may be disposed about its proximal section to facilitate its manipulation. The length of the section of introducer needle distal to the handle is selected to be greater than the width of the target transverse carpal ligament. Its diameter is selected to be no greater than about 2 mm.

[0047] FIG. 9 is a perspective view of a preferred embodiment of the cutting element 78 of the present invention. Substantially the entire length 80 of the cutting element has a flexible, small diameter, thread-like structure with a high breaking strength and a smooth surface, preferably with an average surface roughness no greater than 50 micrometers. The cutting element may comprise a monofilament or a plurality of braided, twisted or otherwise joined fibers or strands wherein each strand has a smooth surface so as to present a relatively smooth, non-abrasive surface. Its physical characteristics include a bend radius of less than half the thickness of the ligament and preferably a zero bend radius, a diameter of less than about 1.0 mm, and a breaking strength of over 2 lbs. The cutting element may comprise fiber or yarn formed of cotton, silk, glass fiber, carbon fiber, various plastic fibers or metal. More particularly, textile fiber, synthetic fiber, mineral fiber, polymer fiber, microfibers may be used. At least one end of the cutting element has a stiffened section 82 to facilitate the introduction into and the extension through the hollow introducer needle. 70. The stiffened section may be formed by covering the section with relatively stiff tubing, by subjecting a synthetic fiber to heat, by the infusion of for example a resin or by the attachment of for example a suture needle. The stiffened section 82 preferably has a diameter less than the

inner diameter of the introducer needle. The enhanced diameter shown in the drawing is for illustration purposes only.

[0048] FIGS. 10A-J illustrate a preferred method of practicing the present invention. After anesthetizing the area of the hand 10 near and about the transverse carpal ligament 16, the distal end 72 of the hollow introducer needle 70 is brought into contact with the hand just proximal to the proximal edge of the target ligament as is shown in FIG. 10A. The ligament is visible in the Figures for purposes of clarity only as no incision is made throughout the entire procedure to in any way expose the ligament to view. Additionally, an imaging device, such as an ultrasound device, such as is commonly used for a variety of imaging applications, is used to visualize the position of the introducer needle relative to the ligament but is not shown so as not to obscure the surgical site again for purposes of clarity. It is preferable to enter the hand at a position about 30 mm proximal of the proximal edge of the transverse carpal ligament as the carpal tunnel can then be entered at a shallower angle obviating the need to adjust the angle of the needle after the tunnel has been reached and thereby minimizing trauma to tissue in addition to allowing the introducer needle to be more easily imaged.

[0049] In FIG. 10B, the introducer needle has been advanced into the hand via entry port 42, through the carpal tunnel just under the ligament and out through exit port 44. The entry and exit ports may be formed by the direct extension of the introducer needle through the skin. The Figure additionally shows the cutting element 78 being advanced toward the proximal opening of introducer needle wherein the stiffened section 82 of the cutting element serves to facilitate the threading of the cutting element into the needle's hollow interior.

[0050] FIG. 10C shows the cutting element emerging from the introducer needle's distal end while FIG. 10D illustrates the subsequent retraction of the needle to leave the cutting element in place as is shown in FIG. 10E. As such, a section of cutting element 78 is left projecting from entry port 42 and from access port 44 while its central section extends through the carpal tunnel just below the transverse carpal ligament 16.

[0051] FIG. 10F illustrates the subsequent step of the method wherein the introducer needle has been reintroduced into the hand via entry port 42 immediately adjacent to the placed cutting element 78. The introducer needle has been advanced through the hand immediately above the transverse carpal ligament 16 to reemerge from access port 44. Alternatively, the introducer needle may be reintroduced into the hand via access port 44 to reemerge from port 42.

[0052] Once the introducer needle 70 is again in place, the cutting element 78 is fed into the distal end of the introducer needle, is extended along the needle's hollow interior to project from its proximal end as is shown in FIG. 10H. Subsequent retraction of the introducer needle as per FIG. 10I leaves the cutting element in position about the ligament 16 as is shown in FIG. 10J. The cutting element is thereby in position for subsequent manipulation to effect the transection of the ligament.

[0053] Alternatively, a cutting element having a stiffened section at both ends allows the cutting element to be initially introduced into the distal end of the introducer needle and extended there through. After retraction of the needle and reintroduction into the hand and extension above the ligament to re-emerge from the hand, the second stiffened end of the cutting element can be inserted into the distal end of the

needle and extended there through. Subsequent retraction of the needle again leaves the cutting element in position for the transection.

[0054] The cutting element may simply be grasped by the user, may be wound around the hands or fingers of the user for a firmer grip or alternatively, may be fitted with handles to provide for maximum grip and control. Unequal forces can alternately be applied to the two ends of the cutting element to induce a reciprocating cutting action either by hand or with the use of an appropriately configured power tool. Alternatively, one end can be pulled with greater force than the other element so as to pull the cutting element in a single direction as it cuts through the ligament. As a further alternative, both ends can be pulled simultaneously with equal force to simply pull the cutting element through the ligament. When transection has been achieved, the cutting element is simply withdrawn through access port **42**. Application of a small bandage over each of the access ports **42**, **44** completes the procedure.

[0055] FIG. **11** generally illustrates a power tool **90** for reciprocating the ends of the cutting element **78**. The power tool may include a hand grip section **92**, which may house a battery pack. An electric motor would be housed in section **94**, rotation of which is mechanically converted to a reciprocating effect. In the embodiment shown, reciprocation is achieved by the rotation of a crankshaft wherein a pin **98** extends from a rotatable disc on each side of the device wherein the pins are diametrically opposed relative one another and to which the ends of the cutting element **78** are attached. Converting the rotation of a longitudinally positioned electric motor to a transversely disposed crankshaft can be achieved in any of various well known ways including for example geared, cammed or desmodromic mechanisms among many others.

[0056] FIG. **12** illustrates the power tool **90** being used to reciprocate the cutting element **78** in place about the transverse carpal ligament. A protective sleeve **50** may be fitted so as to maintain the two ends of the cutting element in alignment with one another and minimize trauma to the surrounding tissue.

[0057] While particular forms of the invention have been described and illustrated, it will also be apparent to those skilled in the art that various modifications can be made without departing from the spirit and scope of the invention. For example, the sequence of steps may be altered so as to cause the retrieval tool to traverse and then retrieve a loop of the cutting element across the top surface of the transverse carpal ligament before traversal of the bottom surface is achieved. Additional access ports may be formed for easier looping of the cutting element. Any of various ports can be used as the final exiting port of the two ends of the cutting element. Additionally, the method and appropriately dimensioned retrieval tool can be used to transect other tissue so as to perform for example, but not limited to, trigger finger release surgery, tarsal tunnel release surgery and plantar fascia release surgery. The apparatus and method can readily be adapted to transect other soft tissue such as for example muscle, tendon, vessels and nerves in humans as well as animals. Accordingly, it is not intended that the invention be limited except by the appended claims.

1. A method for transecting a soft tissue within a body, comprising the steps of:

- providing a flexible thread-like cutting element having a substantially smooth surface;
- providing a hollow introducer needle;

- extending said hollow introducer needle into said body at a first location transversely adjacent said soft tissue and out of said body at a second location transversely adjacent to said soft tissue and opposite said first location so as to traverse said soft tissue on a first side thereof;
- extending said cutting element through said hollow introducer needle to leave said cutting element projecting proximally and distally from said introducer needle;
- retracting said introducer needle from said body so as to leave said cutting element in place;
- re-extending said hollow introducer needle into said body at said first location and out of said body at said second location or into said body at said second location and out of the body at said first location so as to traverse said soft tissue on a second side thereof opposite said first side;
- extending an end of said cutting element through said hollow introducer needle such that said end portion projects from said hollow introducer needle;
- retracting said introducer needle from said body to thereby leave said cutting element in place looped about said soft tissue with both end portions extending from the same location of said body; and
- exerting force on the ends of said cutting element so as to achieve a kerf-less transection of said soft tissue.

2. The method of claim **1**, wherein unequal forces are exerted on the ends of said cutting element to alternately pull said cutting element in opposite directions to transect said soft tissue.

3. The method of claim **2**, further comprising the steps of providing a powered hand tool for alternately reciprocating ends of a cutting element and attaching said projecting ends thereto.

4. The method of claim **1**, wherein unequal forces are exerted on the ends said cutting element so as to pull said cutting element in a single direction to transect said soft tissue.

5. The method of claim **1**, wherein substantially equal forces are simultaneously exerted on both ends of said cutting element to transect said soft tissue.

6. The method of claim **1**, wherein an imaging device is relied upon to visualize said extensions of said hollow retrieval needle within said body.

7. The method of claim **6**, wherein said imaging device comprises an ultrasound imaging device.

8. The method of claim **1**, wherein a liquid is injected into the body in and around such soft tissue prior to said routing of said cutting element about said soft tissue so as to provide space for the extension of the hollow introducer needle thereinto.

9. The method of claim **1**, further comprising the step of positioning a protective tube about both end portions of said cutting element projecting from said body.

10. The method of claim **1**, wherein one end of said cutting element is first extended through said hollow needle from its first end and wherein said same end of the cutting element is subsequently re-extended through said needle from its second end.

11. The method of claim **1**, wherein one end of said cutting element is first extended through said hollow needle from its first end and wherein its opposite end of the cutting element is subsequently re-extended through said needle from its first end.

12. The method of claim **1**, wherein said soft tissue comprises a ligament.

13. The method of claim **12**, wherein said ligament comprises the transverse carpal ligament.

14. A system for transecting a soft tissue within a body, comprising:

a flexible cutting element having a substantially smooth surface; and

an introducer needle having a hollow interior extending from its proximal end to its distal end with an internal diameter sufficient to receive said flexible cutting element, having a distal tip, and having a length sufficient to extend from a first location transversely adjacent to such soft tissue to a second location transversely adjacent to such soft tissue and opposite to such first location.

15. The system of claim **14** further comprising an imaging device capable of visualizing said hollow introducer needle with said body relative to said soft tissue.

16. The system of claim **15**, wherein said visualizing device comprises an ultrasound imaging device.

17. The system of claim **14**, wherein said cutting element has stiffened end sections to facilitate insertion into and extension through said hollow introducer needle.

18. The system of claim **14**, wherein said cutting element has a diameter less than 1.0 mm.

19. The system of claim **14**, wherein said cutting element has a zero bend radius.

20. The system of claim **14**, wherein said cutting element has a bend radius less than about half the thickness of said soft tissue.

21. The system of claim **14**, wherein said cutting element has a breaking strength of greater than 2 lbs.

22. The system of claim **14**, wherein said cutting element has a braided or twisted structure or comprises a monofilament.

23. The system of claim **14**, further comprising a power tool for alternately reciprocating ends of said cutting element.

24. The system of claim **14**, further comprising a hollow sleeve dimensioned to receive both ends of said cutting element and configured for retaining said cutting element therein during its reciprocation.

* * * * *

专利名称(译)	用于韧带线切断的方法和设备		
公开(公告)号	US20150201959A1	公开(公告)日	2015-07-23
申请号	US14/674501	申请日	2015-03-31
[标]申请(专利权)人(译)	郭学则		
申请(专利权)人(译)	郭, JOSEPH		
当前申请(专利权)人(译)	郭, JOSEPH		
[标]发明人	GUO JOSEPH		
发明人	GUO, JOSEPH		
IPC分类号	A61B17/32 A61B17/34		
CPC分类号	A61B17/320036 A61B2017/3413 A61B2017/32006 A61B17/3403 A61B17/149 A61B17/34 A61B2017/320733		
其他公开文献	US10022141		
外部链接	Espacenet USPTO		

摘要(译)

用于横切软组织（例如韧带）的方法和设备，更具体地，横切腕骨韧带。中空的插入器针和线状切割元件使得该方法能够以微创方式执行。切割元件被引导到围绕目标韧带的位置，使得切割元件从韧带的同一侧进入和离开身体。切割元件的基本上光滑的外表面用于提供无切口切割。

