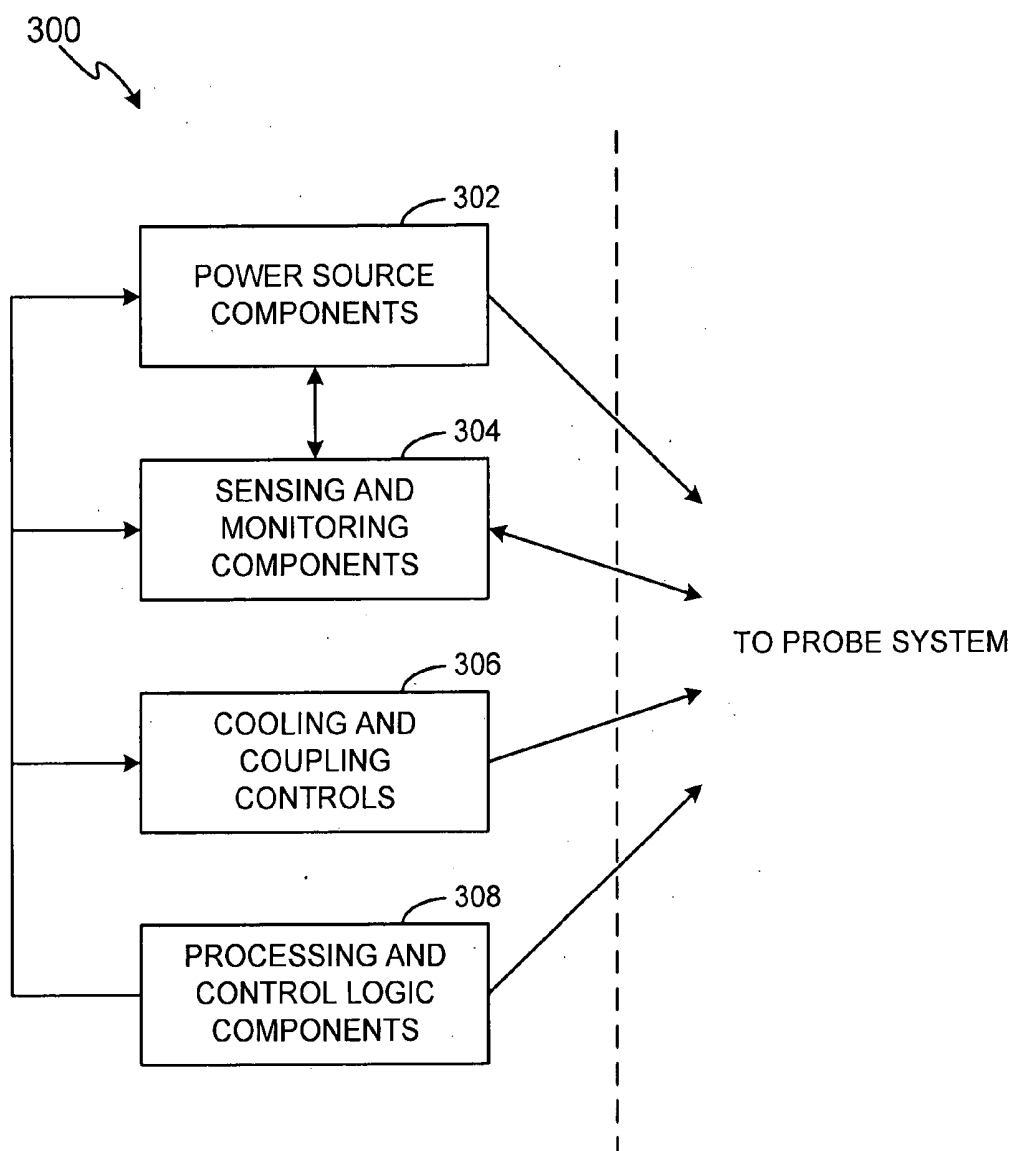


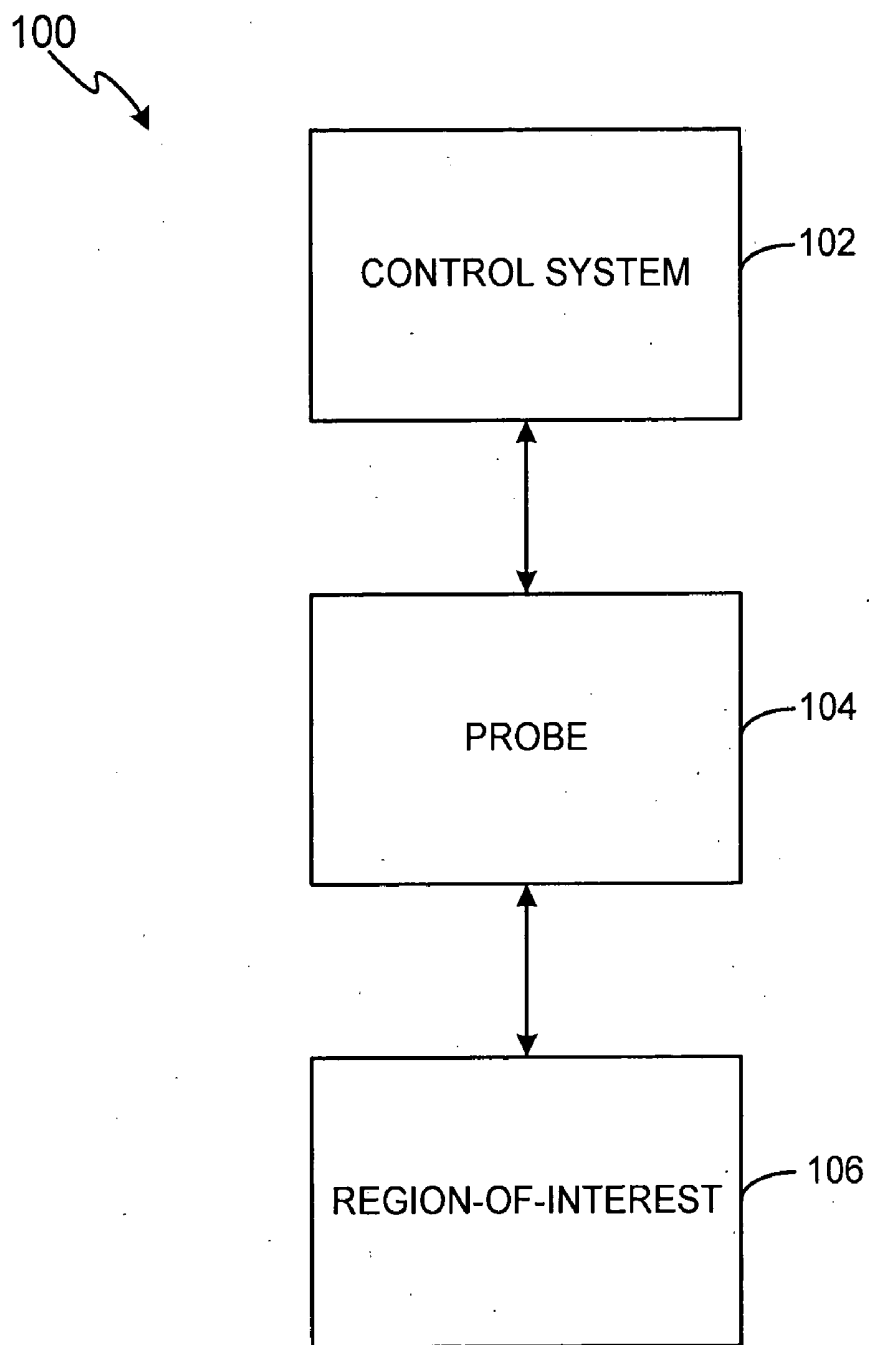


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**Slayton et al.**(10) **Pub. No.: US 2006/0116671 A1**(43) **Pub. Date: Jun. 1, 2006**(54) **METHOD AND SYSTEM FOR CONTROLLED  
THERMAL INJURY OF HUMAN  
SUPERFICIAL TISSUE**(75) Inventors: **Michael H. Slayton**, Tempe, AZ (US);  
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**PHOENIX, AZ 850040001**(73) Assignee: **GUIDED THERAPY SYSTEMS,**  
**L.L.C.**, Mesa, AZ (US)(21) Appl. No.: **11/163,148**(22) Filed: **Oct. 6, 2005****Related U.S. Application Data**(60) Provisional application No. 60/616,754, filed on Oct.  
6, 2004.**Publication Classification**(51) **Int. Cl.**  
**A61B 18/04** (2006.01)  
(52) **U.S. Cl.** ..... **606/27**(57) **ABSTRACT**

A method and system for controlled thermal injury of human superficial tissue based on the ability to controllably create thermal lesions of variable shape, size, and depth via precise spatial and temporal control of acoustic energy deposition. The apparatus includes a control system and probes that facilitate treatment planning, control and delivery of energy, and monitoring of treatment conditions.





**FIG. 1**

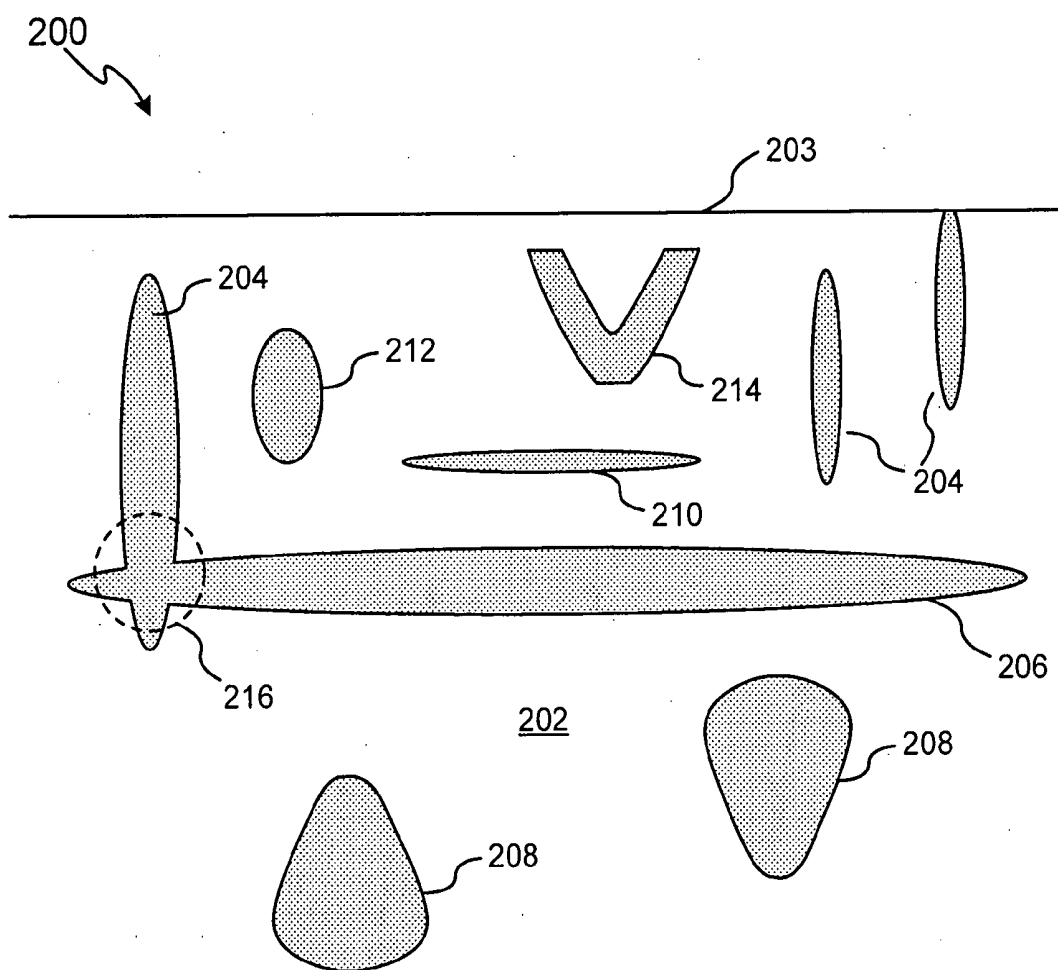
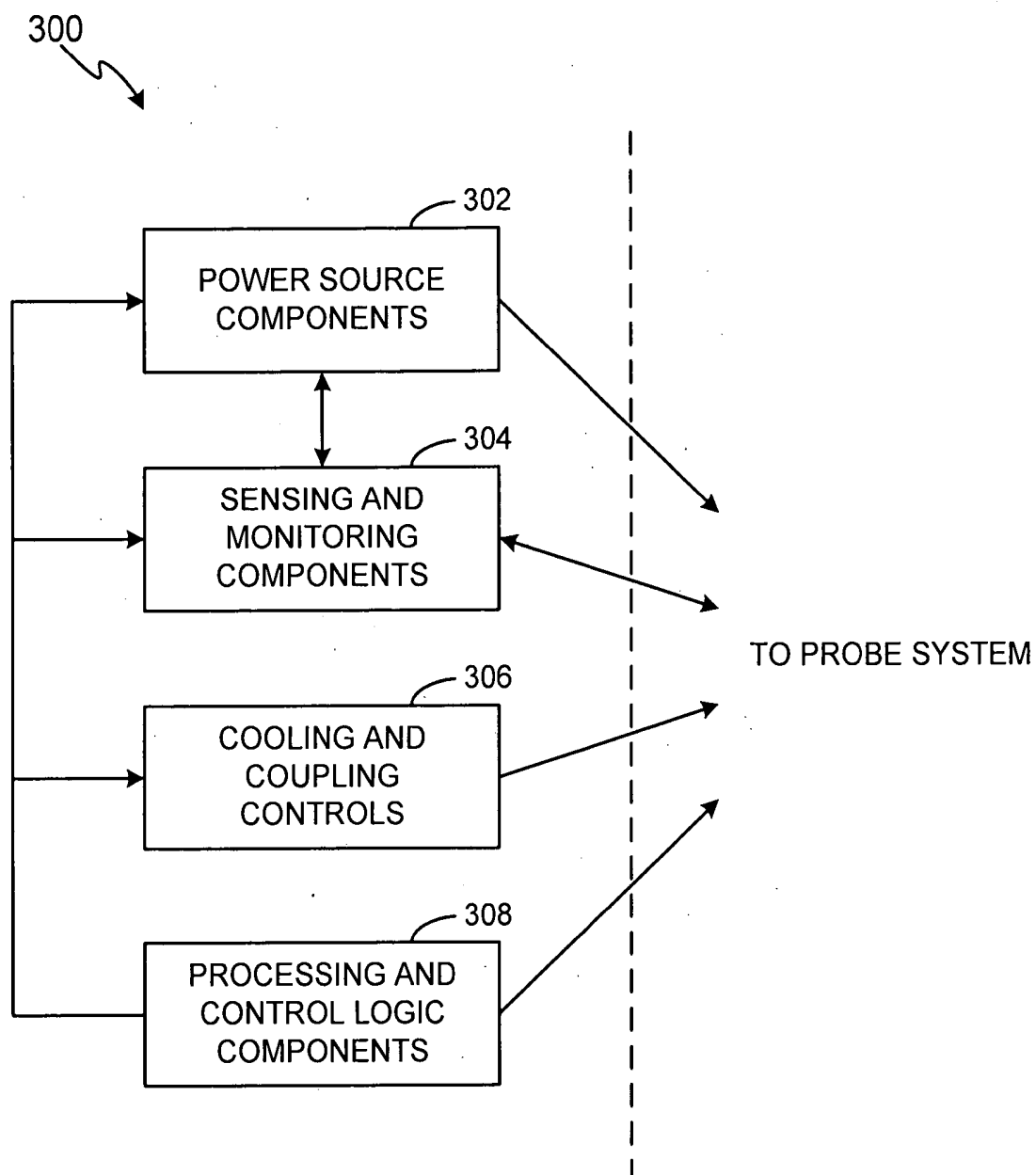
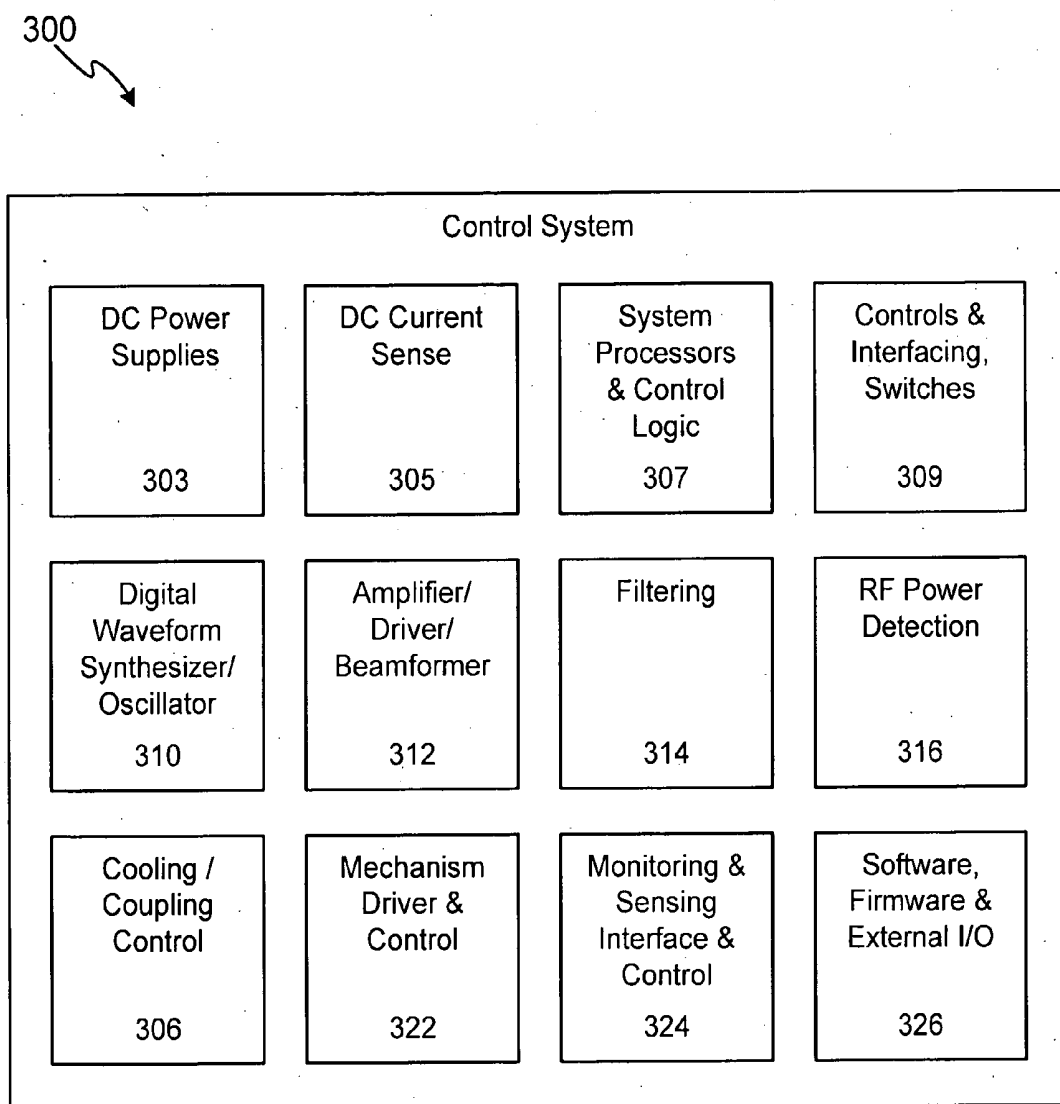


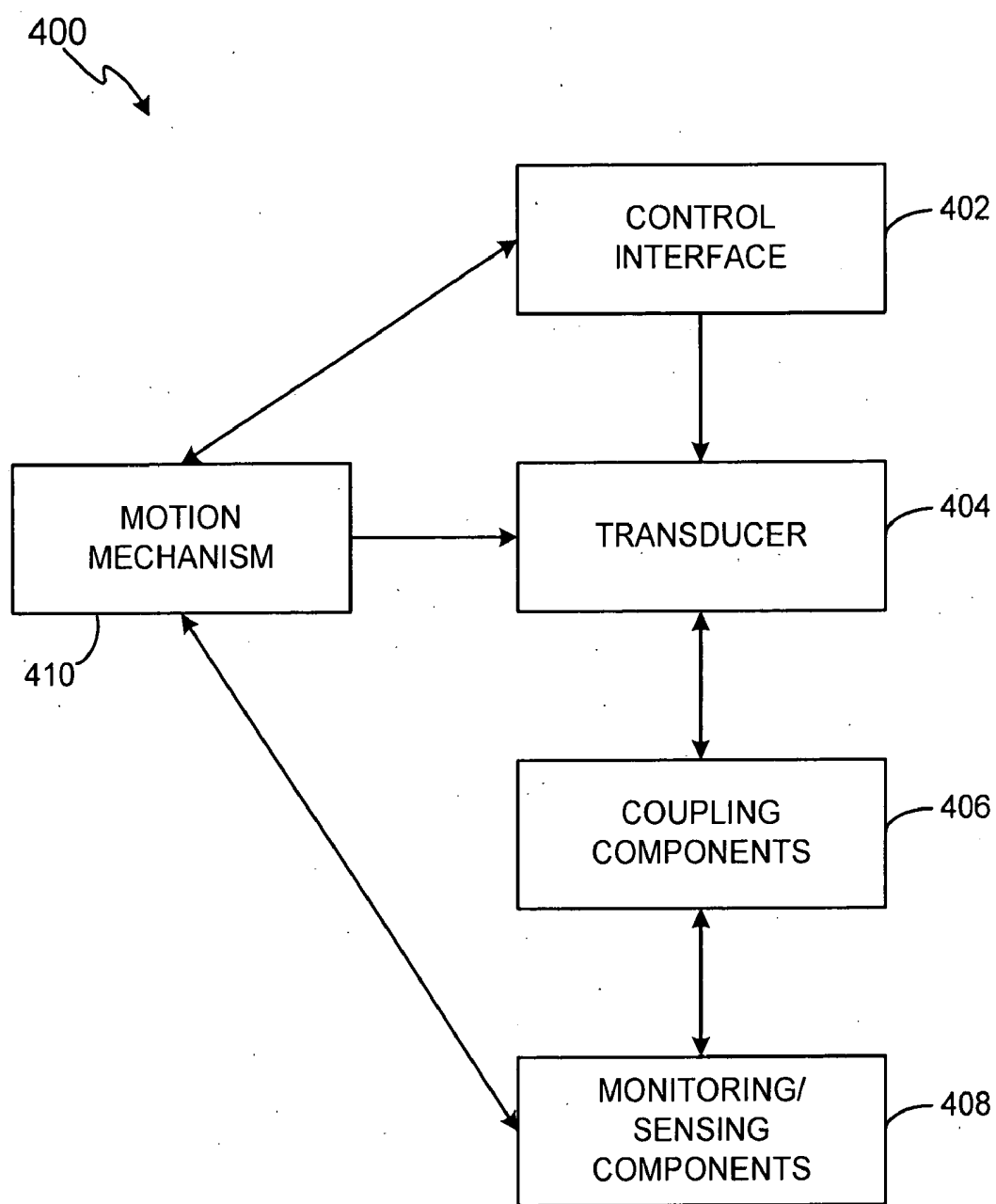
FIG. 2



**FIG. 3A**

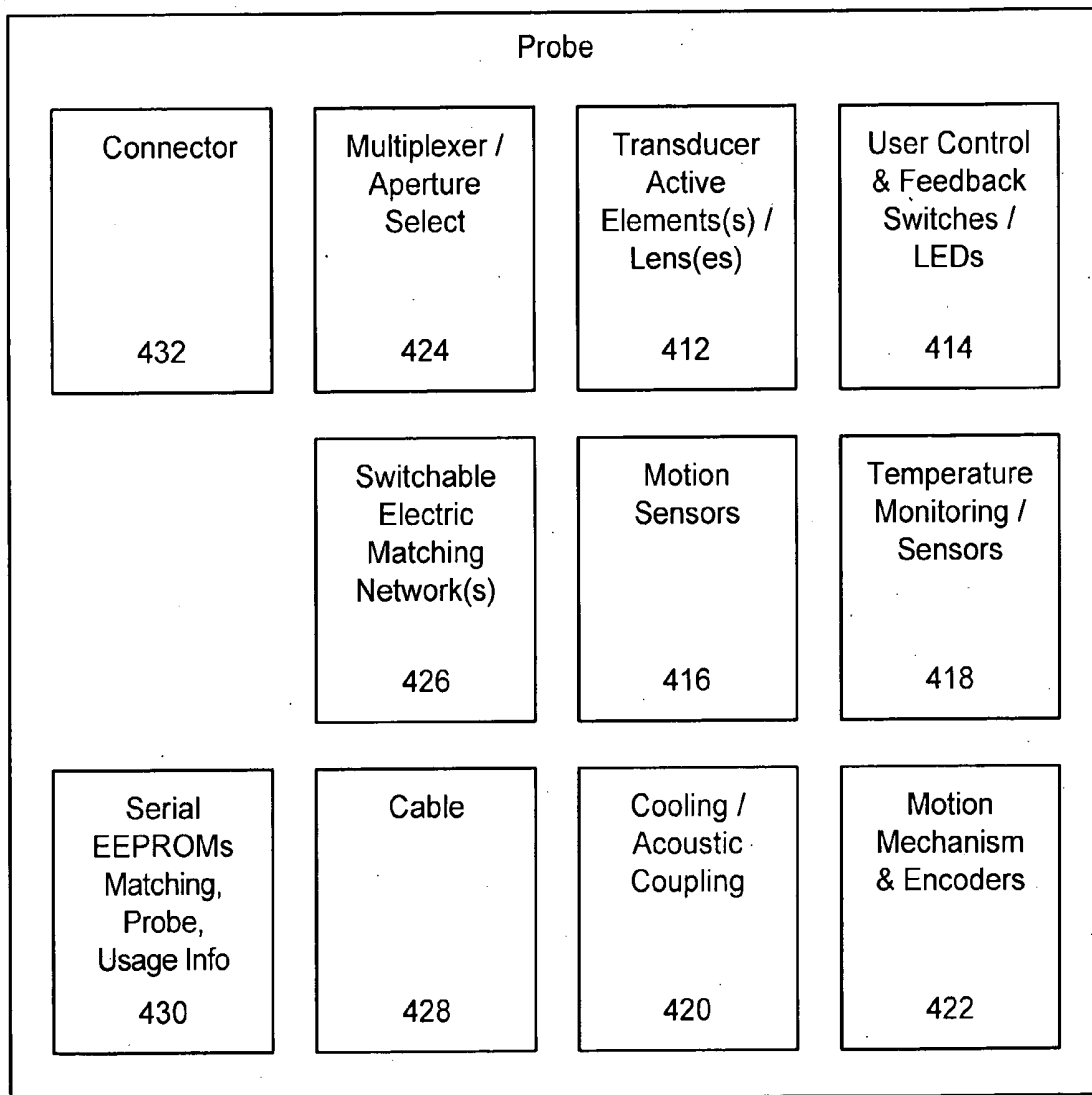


**FIG. 3B**



**FIG. 4A**

400  
↘



**FIG. 4B**

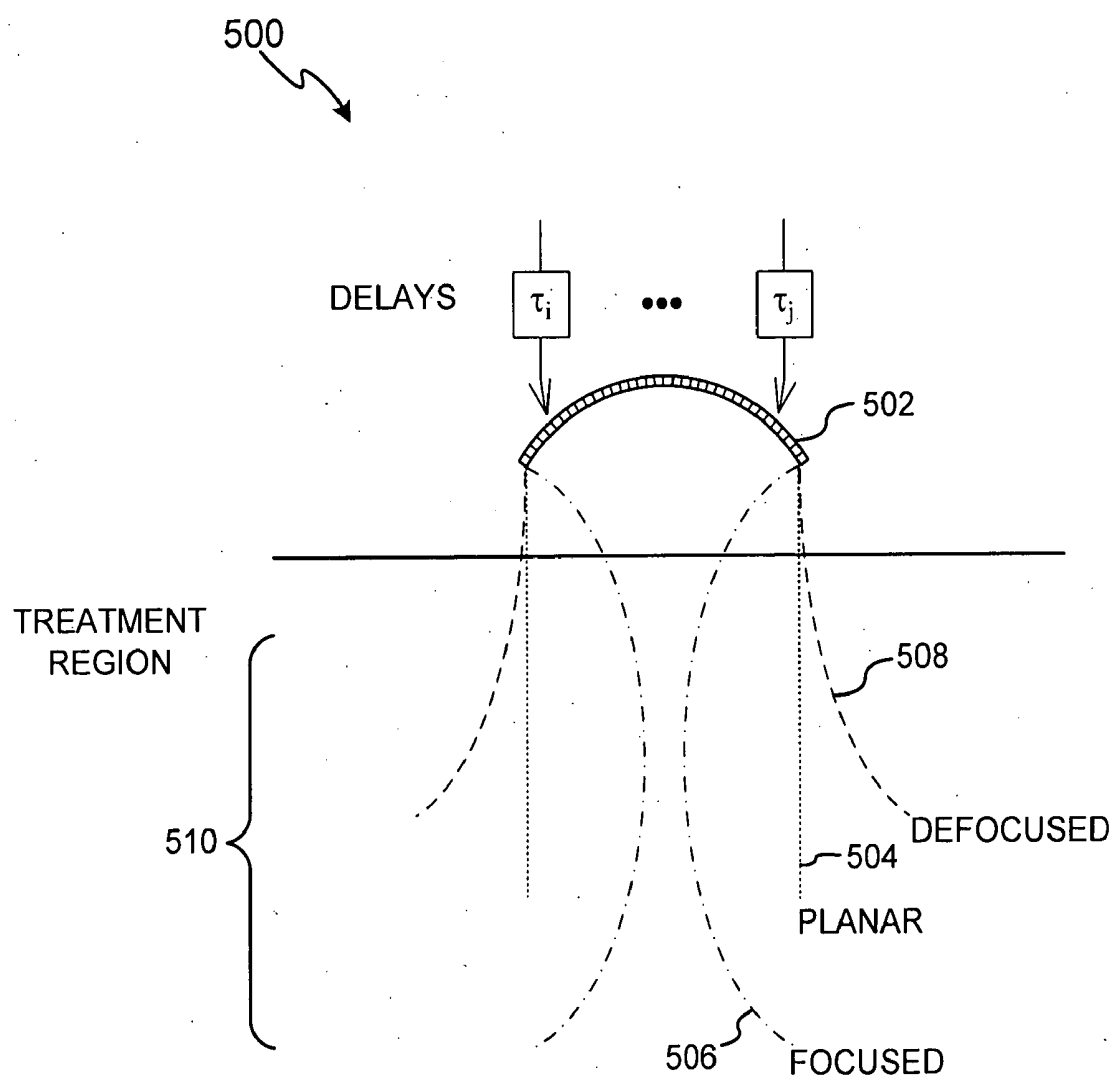


FIG. 5



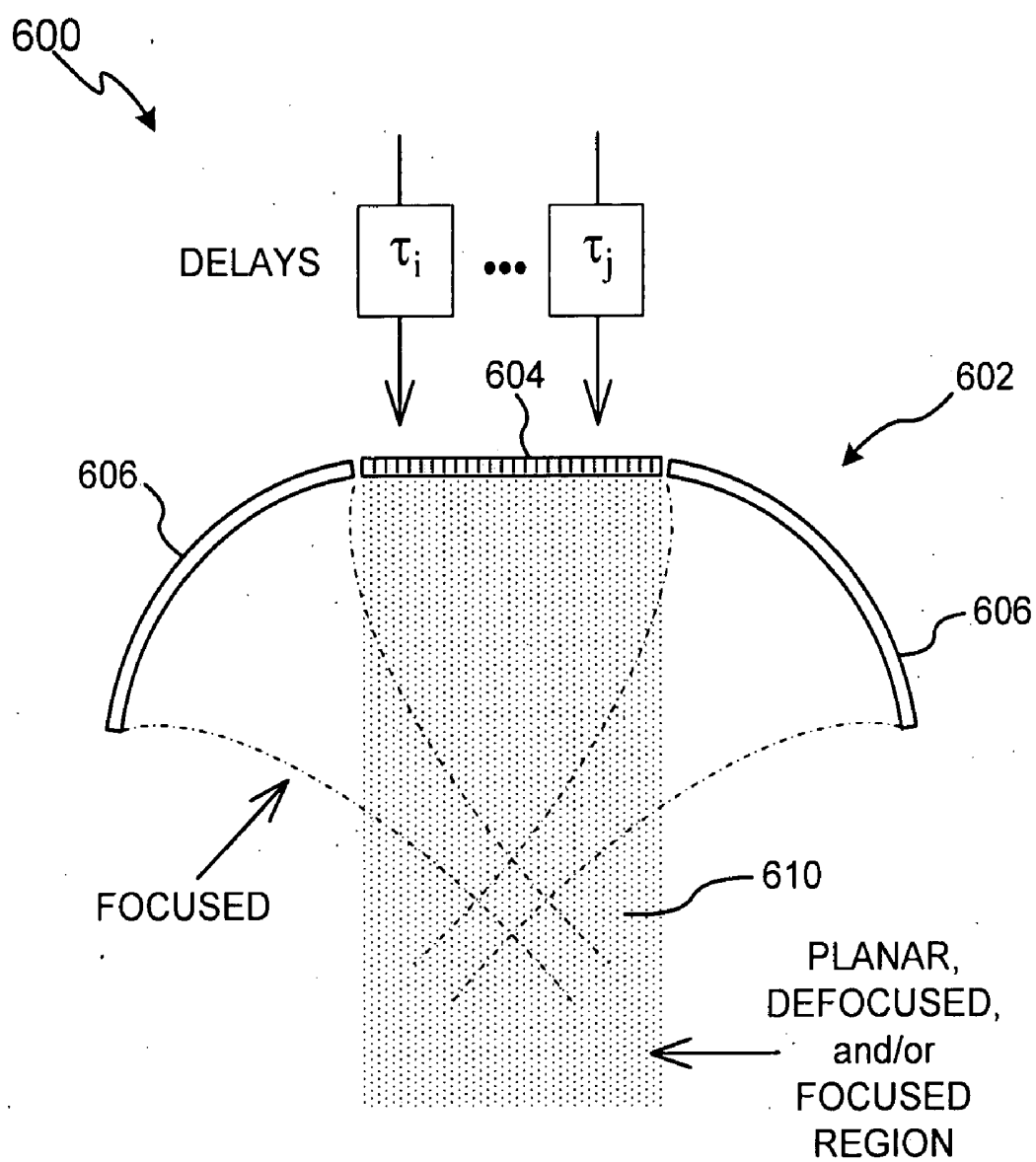
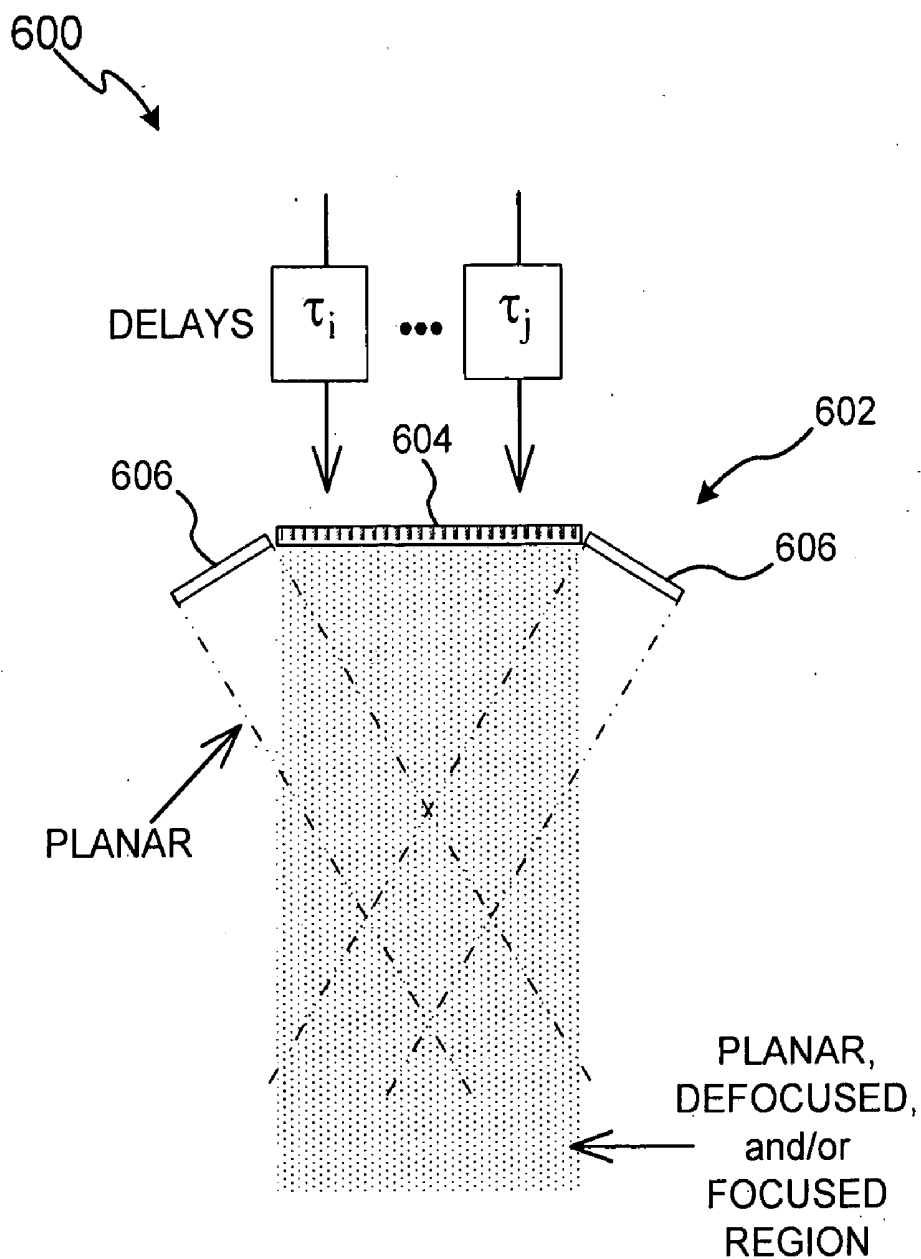
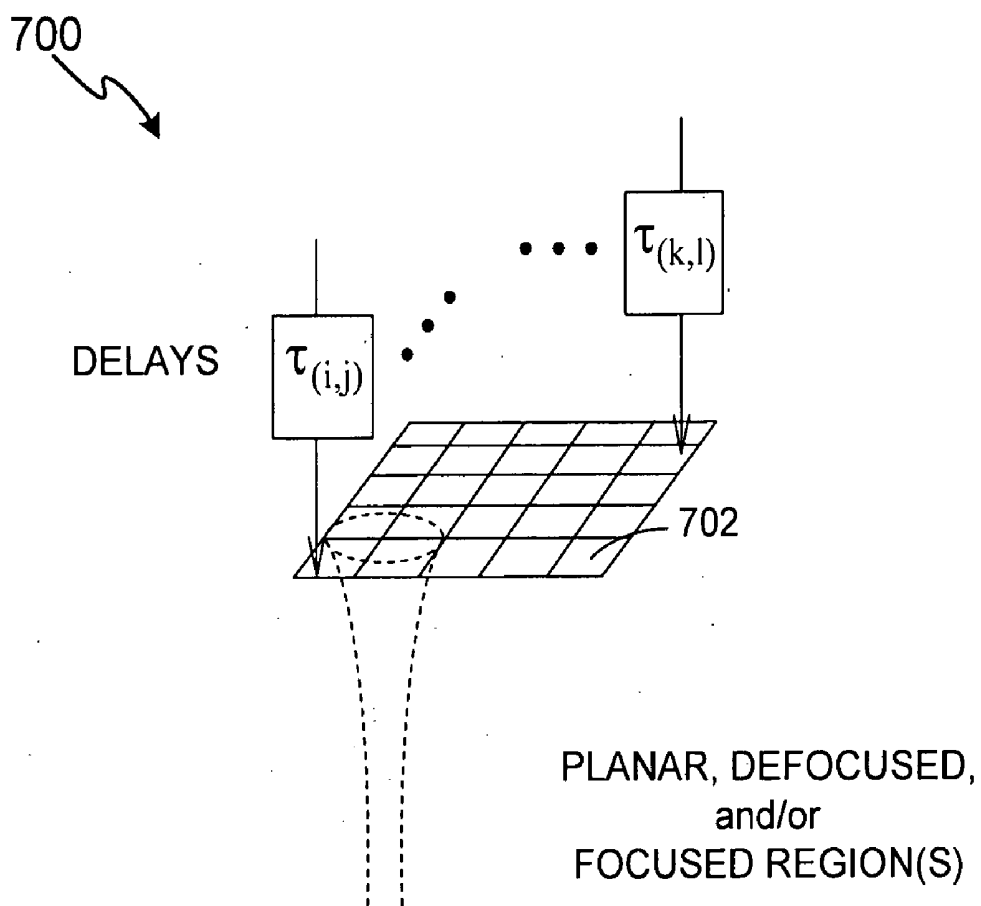


FIG. 6A



**FIG. 6B**



**FIG. 7**

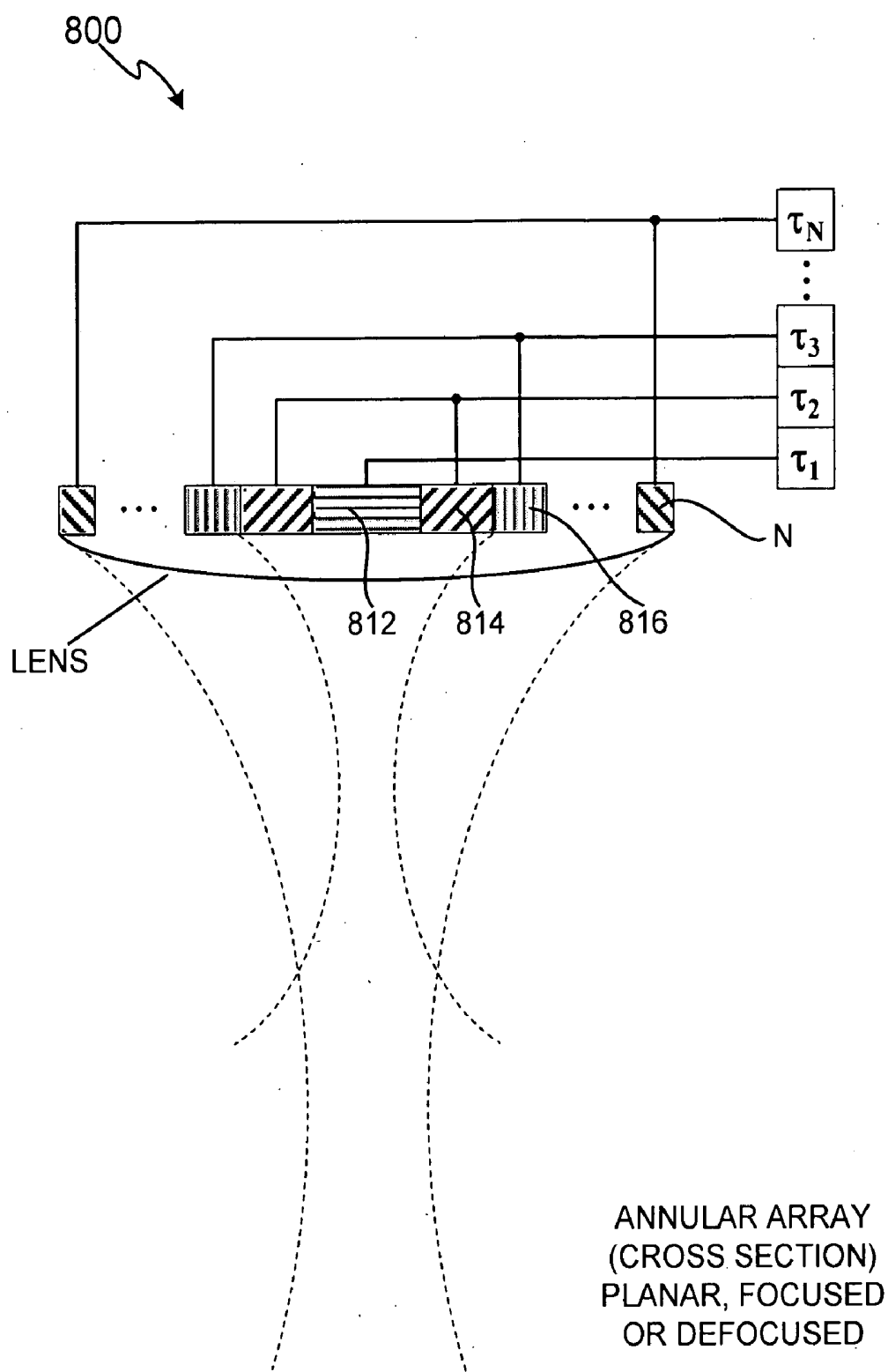


FIG. 8A

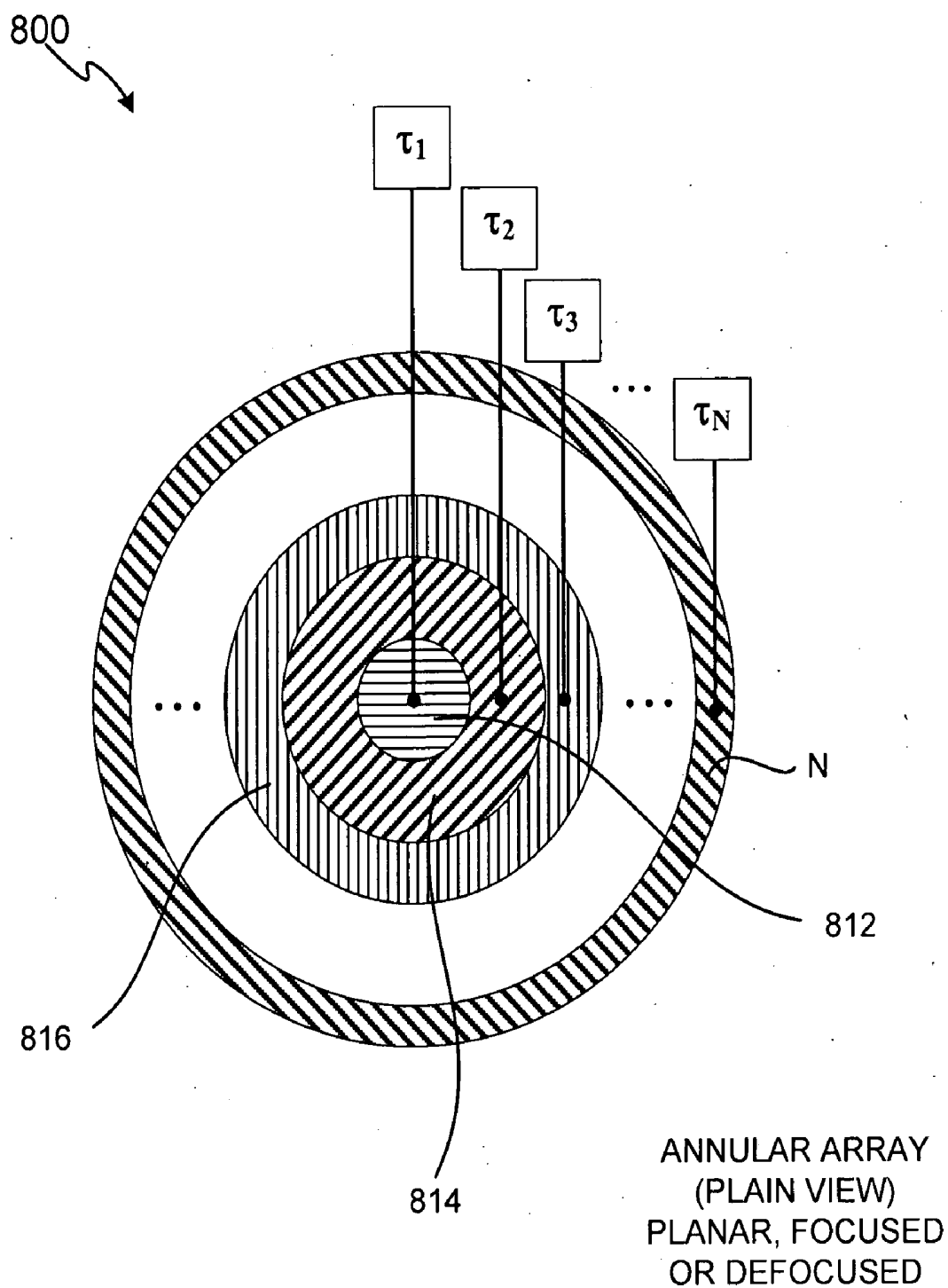
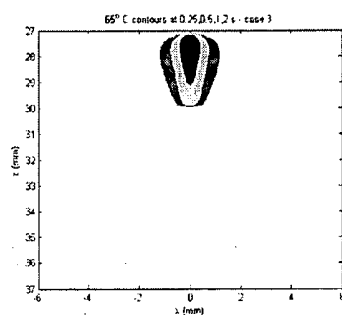
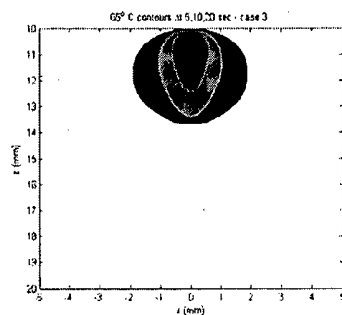


FIG. 8B

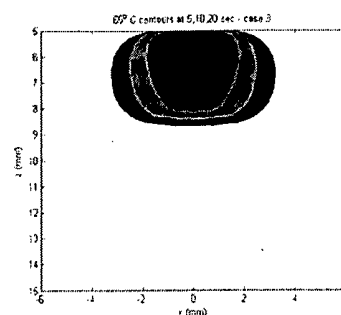
**Spherically Focused**  
Tissue Depth = 27 mm



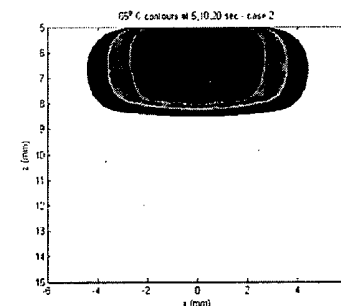
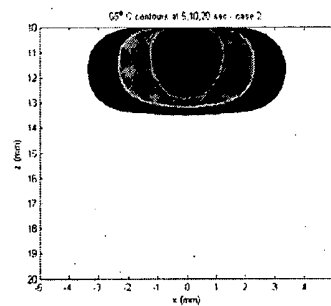
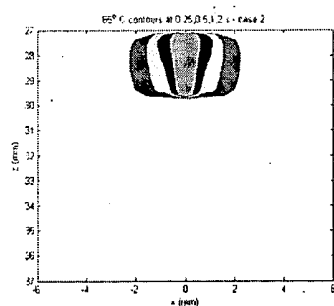
**Cylindrically Focused**  
Tissue Depth = 10 mm



**Planar (Unfocussed)**  
Tissue Depth = 5 mm



**Source Power Level =  $W_0$**



**Spatiotemporal Thermal Contour Growth**

**FIG. 9**

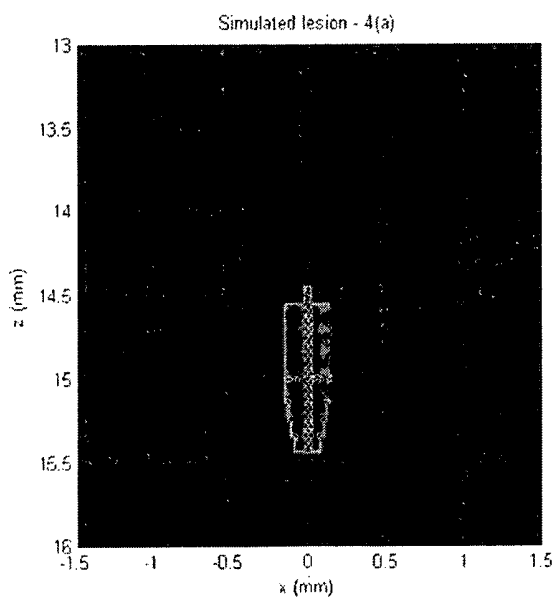
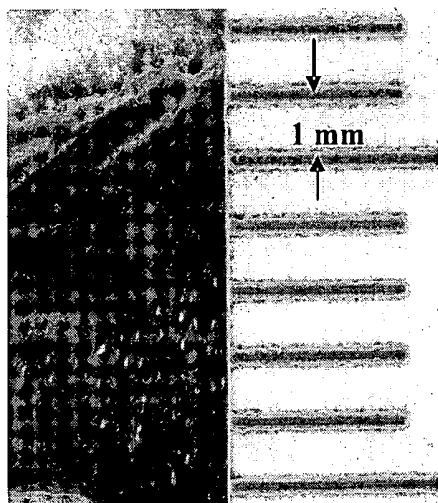
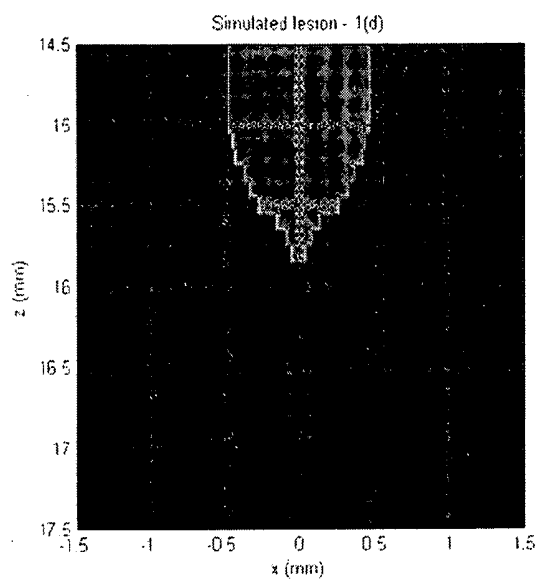
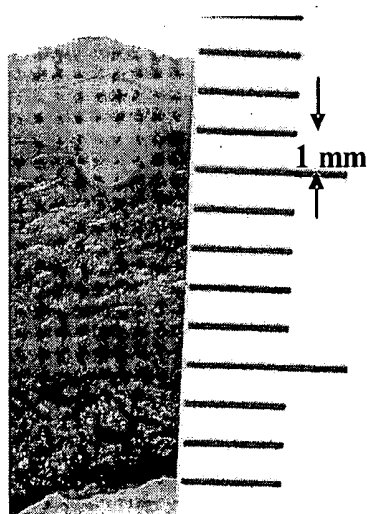
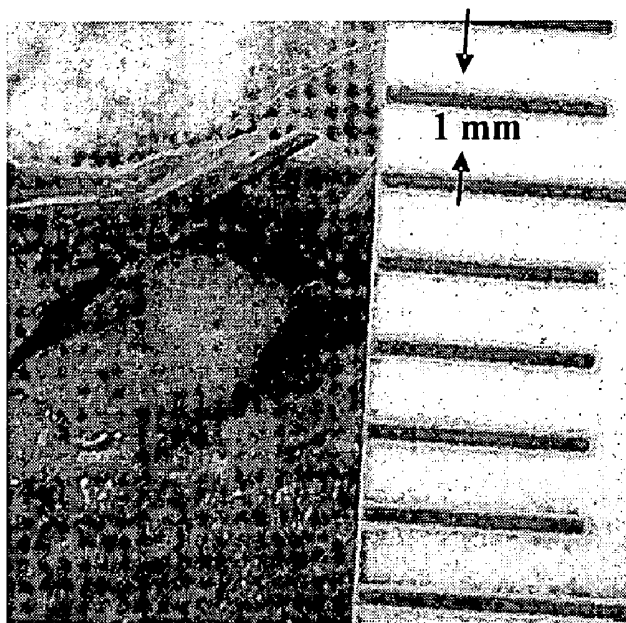
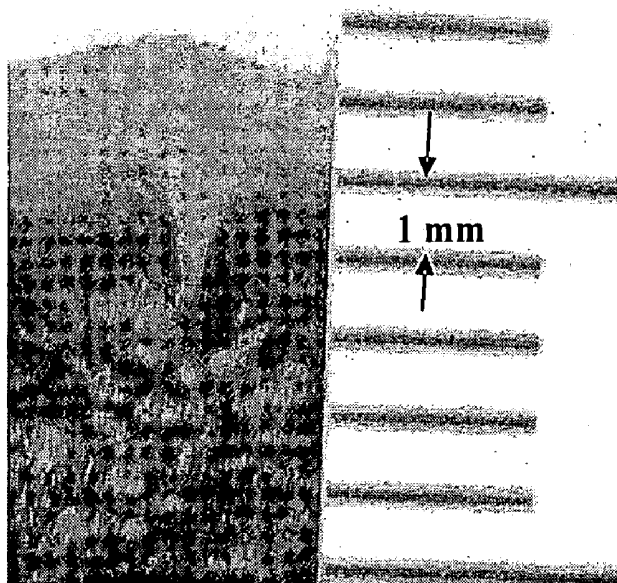


FIG. 10



**FIG. 11**



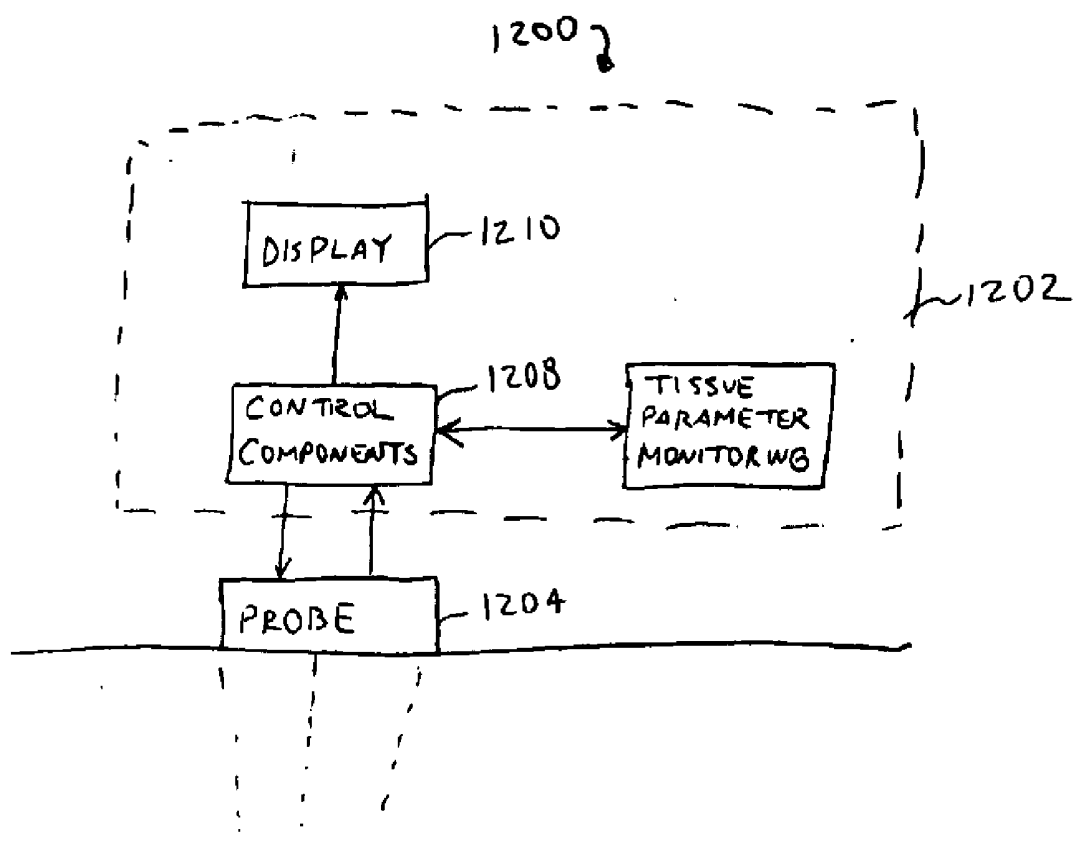


FIG. 12A

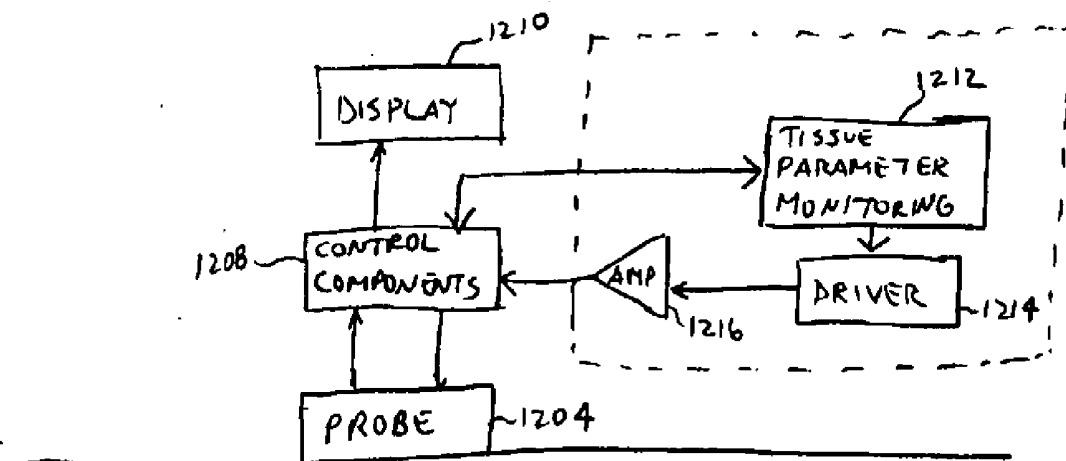
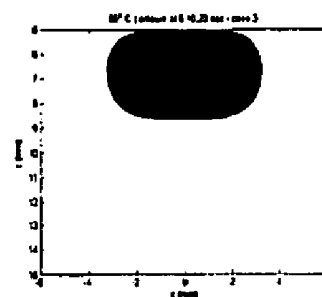
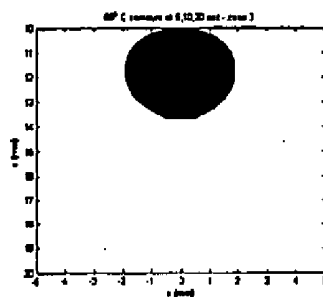
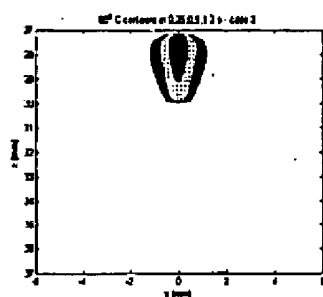


FIG. 12B

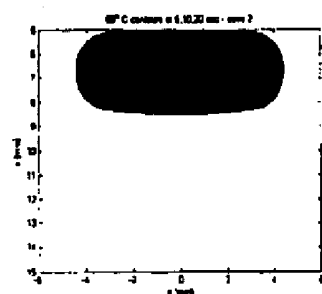
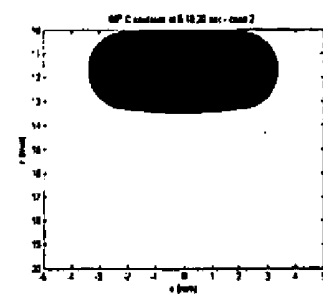
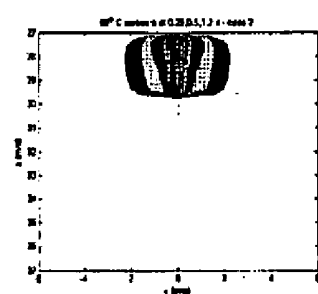
**Spherically Focused**  
Tissue Depth = 27 mm

**Cylindrically Focused**  
Tissue Depth = 10 mm

**Planar (Unfocused)**  
Tissue Depth = 5 mm



Source Power Level =  $W_0$



**Spatiotemporal Thermal Contour Growth**

FIG. 13

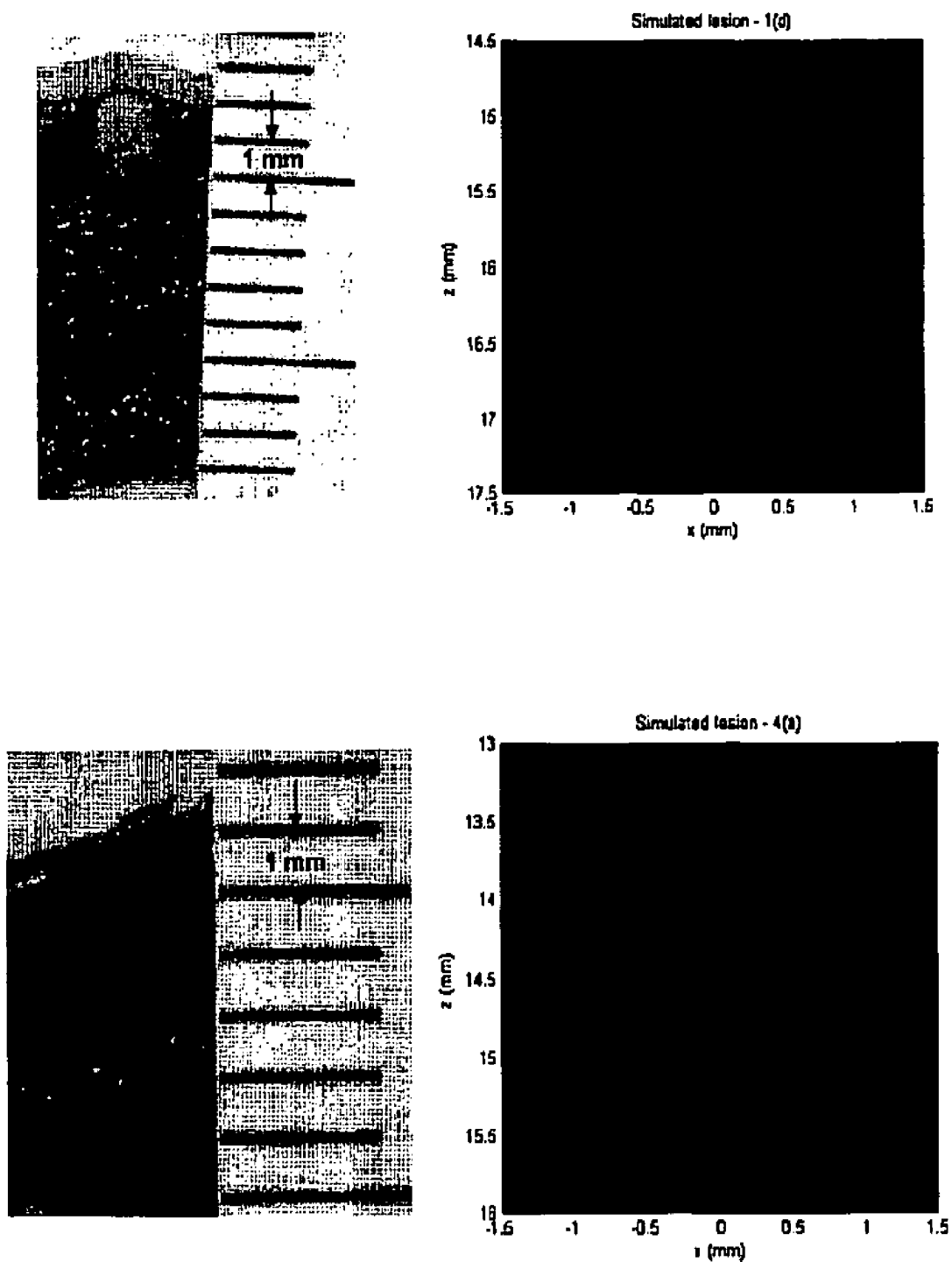


FIG. 14

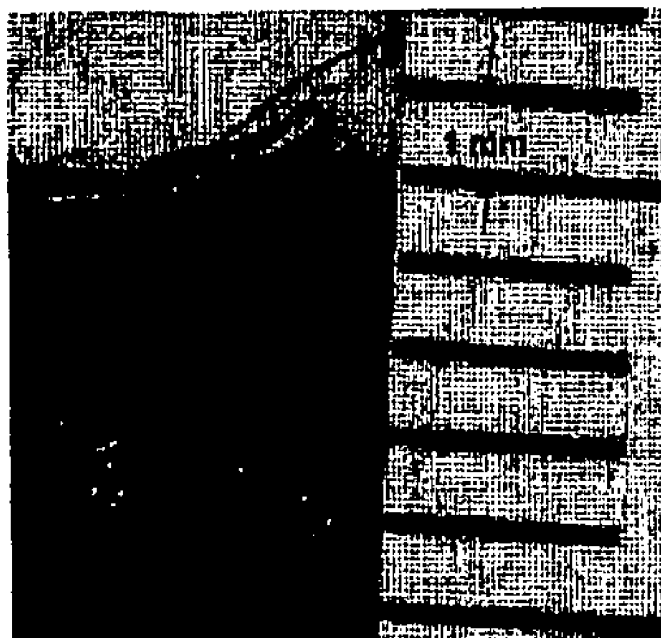
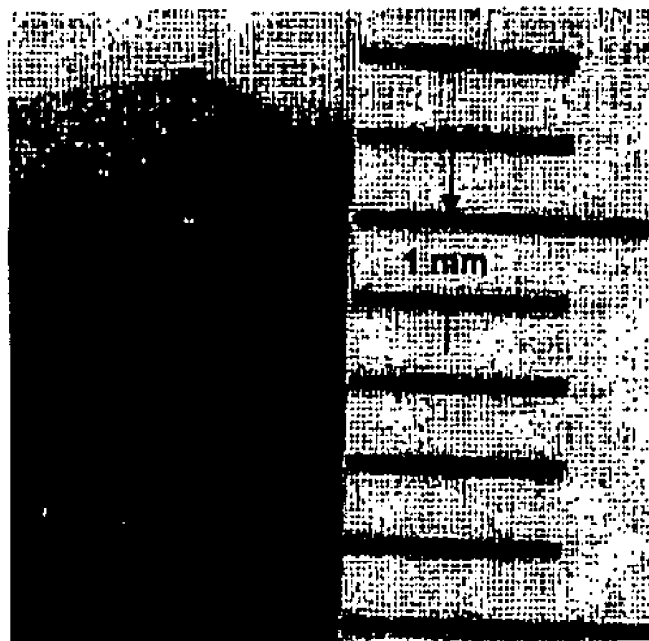


FIG. 15

## METHOD AND SYSTEM FOR CONTROLLED THERMAL INJURY OF HUMAN SUPERFICIAL TISSUE

### CROSS-REFERENCE TO RELATED APPLIATIONS

[0001] This Application claims priority to and benefit of U.S. Provisional Application No. 60/616,754, entitled "Method and System for Controlled Thermal Injury of Human Superficial Tissue", and filed on Oct. 6, 2004.

### FIELD OF INVENTION

[0002] This invention generally relates to therapeutic treatment systems, and more particularly, to a method and system for controlled thermal injury of human superficial tissue.

### BACKGROUND OF INVENTION

[0003] Current techniques of therapeutic treatment of human superficial tissue for cosmetic applications utilize several different energy sources. Some exemplary conventional energy sources include ablative and non-ablative lasers, radio frequency (RF) energy, and more recently some ultrasound-based techniques. Current examples of ultrasound-based treatment techniques include those disclosed in Klopotek (U.S. Pat. No. 6,113,559 and its related continuation, U.S. Pat. No. 6,325,769), Hissong et al. (U.S. Pat. No. 6,595,934), and Coleman (U.S. Pat. No. 6,692,450).

[0004] Klopotek initially suggests in U.S. Pat. No. 6,113,559 a method of reducing skin wrinkles by applying a focused ultrasound beam so that the dermis layer is "gently stimulated or irritated" without adversely damaging the outer epidermis by using "dosages that are significantly lower than conventional hyperthermia therapies." The disclosed methodology merely alleges a non-thermal injury since energy is applied for a time duration of only 10 ns-200  $\mu$ s at a focal intensity of 500-1500 W/cm<sup>2</sup>, i.e. 5  $\mu$ J/cm<sup>2</sup>-0.3 joule/cm<sup>2</sup>. Despite such a low amount of energy, Klopotek alleges that the tissue temperature would rise to temperatures between 47-75° C., sufficient enough to cause injury as opposed to gently stimulating or irritating. Klopotek later discloses in U.S. Pat. No. 6,325,769 the use of pulsed (as opposed to continuous wave) ultrasound, but at the same low focal intensities (500-1500 W/cm<sup>2</sup>) and pulse duration (10 ns-200  $\mu$ s), and alleges that such an acoustic excitation will create an acoustic shock wave and cavitation effects in the dermis layer. In reality, it would be extremely difficult if not impossible as collectively taught in the '559 and '769 patents for one skilled in the art to induce such cavitation, temperature rise or shock wave in tissue with such "gentle stimulation or irritation" due to fundamental limits of the thermal capacity of tissue, e.g., the specific heat capacity of skin is approximately 3430 J/kg/K, as well as acoustic wave propagation effects.

[0005] Hissong discloses a method of skin rejuvenation at frequencies from 0.5-12 MHz in which the step of ablating includes forming a focal lesion "to begin at a beginning margin located 50-100  $\mu$ m below the external surface of the skin" and to have a lesion "depth of 50-150  $\mu$ m," i.e. lesions extending from a depth of 50  $\mu$ m to 250  $\mu$ m deep from the skin's surface. Hissong also alleges that heating the skin for

a "duration of 2 to 60 seconds" will form the focal lesions. However, a number of shortcomings limit the utility of the Hissong technique.

[0006] For example, such a long duration of energy delivery would result in significant thermal diffusion and lesion growth, both laterally and axially, drastically hindering placement of focal lesions over a shallow 50  $\mu$ m to 250  $\mu$ m depth. Second, if the highest frequency of Hissong, namely 12 MHz, were considered in an application, then the corresponding wavelength in tissue would be approximately 128  $\mu$ m. Considering that the depth-of-focus for an acoustic beam profile, i.e., the axial focal beam length, comprises several wavelengths, it is not practical to produce such short/sub-wavelength, thermally induced lesions, such as from 50 to 150  $\mu$ m in length, for even the tightest, diffraction-limited focusing. Furthermore, at lower frequencies it would be more difficult to produce such short/sub-wavelength, thermally induced lesions. Still further, the use of strong focusing requires relatively large aperture transducers such that the multi-element applicator taught by Hissong would be very large and difficult to acoustically couple over facial skin and neck tissue, and it would be extremely difficult to fuse lesions together as alleged. Finally, lesions restricted to such shallow depths and long treatment times as disclosed by Hissong have a limited scope of utility and clinical throughput, which would be further encumbered by the requirement of maintaining of a hand-held probe stationary to micron levels over a long period of time.

[0007] Coleman alleges that focused ultrasound ablation initiated from separate, single elements combined mechanically together at the active surface and forming a multi-element unit with "a plurality of individual ultrasound emitting elements arranged in an array" and alleged "to emit ultrasound energy and focus the emitted ultrasound energy a predetermined distance from ultrasound emitting member." Coleman further teaches "a plurality of individual ultrasound emitting elements enclosed in an array," and configured with "each focusing zone being separate and distinct from one another and located the same fixed predetermined distance outwardly." Finally, Coleman describes forming lesions within the tissue by the "ultrasound emitting elements in said array being selectively, independently actuable to emit ultrasound energy therefrom and being selectively, independently non-actuable to not emit ultrasound energy therefrom."

[0008] Thus, it appears that Coleman, recognizing a real need for flexibility in lesion forming proposes, is attempting to create various shapes of the lesion by combining separate lesions from fixed-focus single elements housed together in a multi-element transducer array actuated separately. Unfortunately, such a technique is severely limited spatially and temporally as well as in its precision due to a heavy reliance on thermal expansion. Moreover, since the multiple-element array is configured to cover a large area, and the targeted tissue is most often curved, it would be difficult to acoustically couple the focused ultrasound ablation device taught by Coleman. Furthermore, since the focused dish transducer elements or at least flat disks need to be large for good intensity gain, it is necessary to have such elements spaced on the order of a wavelength to achieve good focusing, i.e. high intensity gain, low side lobes and grating lobes, thus making the array cumbersome for operation. Finally, although Coleman attempts to form a planar lesion, the

lesion uncontrollably grows vertically as well since such a lesion is formed through the lateral thermal diffusion of the energy.

[0009] Accordingly, conventional therapeutic treatment techniques have numerous fundamental physical limits, technological difficulties, and practical utility issues that prevent the flexible, precise creation and control of lesions of arbitrary shape, size and depth within human superficial tissue.

#### SUMMARY OF INVENTION

[0010] In accordance with various aspects of the present invention, a therapeutic treatment method and system for controlled thermal injury of human superficial tissue is based on the ability to controllably create thermal lesions of a variable shape, size, and depth through precise spatial and temporal control of acoustic energy deposition. In accordance with an exemplary embodiment, an exemplary therapeutic treatment system includes a control system and a probe system that can facilitate treatment planning, controlling and/or delivering of acoustic energy, and/or monitoring of treatment conditions to a region of interest. As a result, the ability to controllably produce conformal lesions of thermal injury in superficial human tissue can be realized.

[0011] In accordance with an exemplary embodiment, an exemplary treatment method can enable the regions of thermal injury to comprise controlled conformal shapes and sizes and allow the tissue to be destroyed (ablated) in a controlled spatial and temporal manner. For example, the thermal lesions may be suitably and selectively created with narrow or wide lateral extent, long or short axial length, and/or deep or shallow placement, including up to the tissue outer surface. Moreover, separate islands of destruction may also be created over part or whole of the tissue region-of-interest, and/or contiguous or overlapping structures may be produced out of discrete lesions. In accordance with other exemplary embodiments of the present invention, exemplary methods can comprise scanning over part or whole of the region-of-interest to produce contiguous thermal injury. The conformal lesions can be achieved not only through the independent selection and control of transducer acoustic energy spatial distribution, such as selection of transducer configuration and placement, but also through temporal control, such as through drive amplitude levels, frequency/waveform selection, and timing sequences that can be adjusted and optimized to control thermal ablation of tissue. In addition, the temperature at the acoustic coupling interface can be controlled, thus further enabling another exemplary method of lesion formation control.

#### BRIEF DESCRIPTION OF THE DRAWINGS

[0012] The subject matter of the invention is particularly pointed out and distinctly claimed in the concluding portion of the specification. The invention, however, both as to structure and method of operation, may best be understood by reference to the following description taken in conjunction with the claims and the accompanying drawing figures, in which like parts may be referred to by like numerals:

[0013] **FIG. 1** illustrates a block diagram of an exemplary therapeutic treatment system for controlled thermal injury of human superficial tissue in accordance with an exemplary embodiment of the present invention;

[0014] **FIG. 2** illustrates a cross sectional diagram of a human superficial tissue region of interest including a plurality of lesions of controlled thermal injury in accordance with an exemplary embodiment of the present invention;

[0015] **FIGS. 3A and 3B** illustrate block diagrams of an exemplary control system in accordance with exemplary embodiments of the present invention;

[0016] **FIGS. 4A and 4B** illustrate block diagrams of an exemplary probe system in accordance with exemplary embodiments of the present invention;

[0017] **FIG. 5** illustrates a cross-sectional diagram of an exemplary transducer in accordance with an exemplary embodiment of the present invention;

[0018] **FIGS. 6A and 6B** illustrate cross-sectional diagrams of an exemplary transducer in accordance with exemplary embodiments of the present invention;

[0019] **FIG. 7** illustrates exemplary transducer configurations for ultrasound treatment in accordance with various exemplary embodiments of the present invention;

[0020] **FIGS. 8A and 8B** illustrate cross-sectional diagrams of an exemplary transducer in accordance with another exemplary embodiment of the present invention;

[0021] **FIG. 9** illustrates an exemplary transducer configured as a two-dimensional array for ultrasound treatment in accordance with an exemplary embodiment of the present invention;

[0022] **FIGS. 10A-10F** illustrate cross-sectional diagrams of exemplary transducers in accordance with other exemplary embodiments of the present invention;

[0023] **FIG. 11** illustrates a schematic diagram of an acoustic coupling and cooling system in accordance with an exemplary embodiment of the present invention;

[0024] **FIGS. 12A and 12B** illustrate block diagrams of exemplary open-loop and closed-loop feedback systems in accordance with exemplary embodiments of the present invention;

[0025] **FIG. 13** illustrates an exemplary diagram of simulation results for various spatially controlled configurations in accordance with exemplary embodiments of the present invention;

[0026] **FIG. 14** illustrates an exemplary diagram of simulation results of a pair of lesioning and simulation results in accordance with the present invention; and

[0027] **FIG. 15** illustrates another exemplary diagram of simulation results of a pair of lesioning results in accordance with the present invention.

#### DETAILED DESCRIPTION

[0028] The present invention may be described herein in terms of various components and processing steps. It should be appreciated that such components and steps may be realized by any number of hardware components configured to perform the specified functions. For example, the present invention may employ various medical treatment devices, visual imaging and display devices, input terminals and the like, which may carry out a variety of functions under the control of one or more control systems or other control

devices. In addition, the present invention may be practiced in any number of medical or treatment contexts and that the exemplary embodiments relating to a therapeutic treatment method and system for controlled thermal injury of human superficial tissue as described herein are merely a few of the exemplary applications for the invention. For example, the principles, features and methods discussed may be applied to any other medical or other tissue or treatment application.

[0029] In accordance with various aspects of the present invention, a therapeutic treatment method and system for controlled thermal injury of human superficial tissue is based on the ability to controllably create thermal lesions of conformally variable shape, size, and depth through precise spatial and temporal control of acoustic energy deposition. With reference to FIG. 1, in accordance with an exemplary embodiment, an exemplary therapeutic treatment system 100 includes a control system 102 and a probe system 104 that can facilitate treatment planning, controlling and/or delivering of acoustic energy, and/or monitoring of treatment conditions to a region of interest 106. Region-of-interest 106 is configured within the human superficial tissue comprising from just below the tissue outer surface to approximately 30 mm or more in depth.

[0030] Therapeutic treatment system 100 is configured with the ability to controllably produce conformal lesions of thermal injury in superficial human tissue within region of interest 106 through precise spatial and temporal control of acoustic energy deposition, i.e., control of probe 104 is confined within selected time and space parameters, with such control being independent of the tissue. In accordance with an exemplary embodiment, control system 102 and probe system 104 can be suitably configured for spatial control of the acoustic energy by controlling the manner of distribution of the acoustical energy. For example, spatial control may be realized through selection of the type of one or more transducer configurations insonifying region of interest 106, selection of the placement and location of probe system 104 for delivery of acoustical energy relative to region-of-interest 106, e.g., probe system 104 being configured for scanning over part or whole of region-of-interest 106 to produce contiguous thermal injury having a particular orientation or otherwise change in distance from region-of-interest 106, and/or control of other environment parameters, e.g., the temperature at the acoustic coupling interface can be controlled, and/or the coupling of probe 104 to human tissue. In addition to the spatial control parameters, control system 102 and probe system 104 can also be configured for temporal control, such as through adjustment and optimization of drive amplitude levels, frequency/waveform selections, e.g., the types of pulses, bursts or continuous waveforms, and timing sequences and other energy drive characteristics to control thermal ablation of tissue. The spatial and/or temporal control can also be facilitated through open-loop and closed-loop feedback arrangements, such as through the monitoring of various spatial and temporal characteristics. As a result, control of acoustical energy within six degrees of freedom, e.g., spatially within the X, Y and Z domain, as well as the axis of rotation within the XY, YZ and XZ domains, can be suitably achieved to generate conformal lesions of variable shape, size and orientation.

[0031] For example, through such spatial and/or temporal control, an exemplary treatment system 100 can enable the

regions of thermal injury to possess arbitrary shape and size and allow the tissue to be destroyed (ablated) in a controlled manner. With reference to FIG. 2, one or more thermal lesions may be created within a tissue region of interest 200, with such thermal lesions having a narrow or wide lateral extent, long or short axial length, and/or deep or shallow placement, including up to a tissue outer surface 203. For example, cigar shaped lesions may be produced in a vertical disposition 204 and/or horizontal disposition 206. In addition, raindrop-shaped lesions 208, flat planar lesions 210, round lesions 212 and/or other v-shaped/ellipsoidal lesions 214 may be formed, among others. For example, mushroom-shaped lesion 220 may be provided, such as through initial generation of a an initial round or cigar-shaped lesion 222, with continued application of ablative ultrasound resulting in thermal expansion to further generate a growing lesion 224, such thermal expansion being continued until mushroom-shaped lesion 220 is achieved. The plurality of shapes can also be configured in various sizes and orientations, e.g., lesions 208 could be rotationally oriented clockwise or counterclockwise at any desired angle, or made larger or smaller as selected, all depending on spatial and/or temporal control. Moreover, separate islands of destruction, i.e., multiple lesions separated throughout the tissue region, may also be created over part of or the whole portion within tissue region-of-interest 200. In addition, contiguous structures and/or overlapping structures 216 may be provided from the controlled configuration of discrete lesions. For example, a series of one or more crossed-lesions 218 can be generated along a tissue region to facilitate various types of treatment methods.

[0032] The specific configurations of controlled thermal injury are selected to achieve the desired tissue and therapeutic effect(s). For example, any tissue effect can be realized, including but not limited to thermal and non-thermal streaming, cavitation, hydrodynamic, ablative, hemostatic, diathermic, and/or resonance-induced tissue effects. Such effects can be suitably realized at treatment depths over a range of approximately 0-30000  $\mu\text{m}$  within region of interest 200 to provide a high degree of utility.

[0033] With reference again to FIG. 1, an exemplary therapeutic treatment system 100 comprising control system 102 and probe system 104 may also comprise various configurations and can be subdivided into various separate subsystems and components. For example, therapeutic treatment system 100 may be divided into various system and probe components disposed in a suitable position for facilitating spatial and/or temporal distribution of acoustical energy. In addition, control system 102 and probe system 104 can comprise other subsystems, such as an imaging subsystem within control system 102 configured to operate and control an imaging transducer within probe system 104, e.g., a separate imaging transducer and a separate therapy transducer or a combined imaging/therapy transducer configured for tissue parameter monitoring.

[0034] With reference to FIGS. 3A and 3B, in accordance with exemplary embodiments, an exemplary control system 300 can be configured for coordination and control of the entire therapeutic treatment process in accordance with the adjustable settings made by a therapeutic treatment system user. For example, control system 300 can suitably comprise power source components 302, sensing and monitoring components 304, cooling and coupling controls 306, and/or

processing and control logic components **308**. Control system **300** can be configured and optimized in a variety of ways with more or less subsystems and components to implement the therapeutic system for controlled thermal injury, and the embodiment in **FIGS. 3A and 3B** are merely for illustration purposes.

[0035] For example, for power sourcing components **302**, control system **300** can comprise one or more direct current (DC) power supplies **303** configured to provide electrical energy for entire control system **300**, including power required by a transducer electronic amplifier/driver **312**. A DC current sense device **305** can also be provided to confirm the level of power going into amplifiers/drivers **312** for safety and monitoring purposes.

[0036] Amplifiers/drivers **312** can comprise multi-channel or single channel power amplifiers and/or drivers. In accordance with an exemplary embodiment for transducer array configurations, amplifiers/drivers **312** can also be configured with a beamformer to facilitate array focusing. An exemplary beamformer can be electrically excited by an oscillator/digitally controlled waveform synthesizer **310** with related switching logic.

[0037] The power sourcing components can also include various filtering configurations **314**. For example, switchable harmonic filters and/or matching may be used at the output of amplifier/driver **312** to increase the drive efficiency and effectiveness. Power detection components **316** may also be included to confirm appropriate operation and calibration. For example, electric power and other energy detection components **316** may be used to monitor the amount of power going to an exemplary probe system.

[0038] Various sensing and monitoring components **304** may also be suitably implemented within control system **300**. For example, in accordance with an exemplary embodiment, monitoring, sensing and interface control components **324** may be configured to operate with various motion detection systems implemented within transducer probe **104** to receive and process information such as acoustic or other spatial and temporal information from a region of interest. Sensing and monitoring components can also include various controls, interfacing and switches **309** and/or power detectors **316**. Such sensing and monitoring components **304** can facilitate open-loop and/or closed-loop feedback systems within treatment system **100**. Still further, monitoring, sensing and interface control components **324** may comprise imaging systems configured for one-dimensional, two-dimensional and/or three dimensional imaging functions. Such imaging systems can comprise any imaging modality based on at least one of photography and other visual optical methods, magnetic resonance imaging (MRI), computed tomography (CT), optical coherence tomography (OCT), electromagnetic, microwave, or radio frequency (RF) methods, positron emission tomography (PET), infrared, ultrasound, acoustic, or any other suitable method of visualization, localization, or monitoring of a region-of-interest **106**. Still further, various other tissue parameter monitoring components, such as temperature measuring devices and components, can be configured within monitoring, sensing and interface control components **324**, such monitoring devices comprising any modality now known or hereinafter devised.

[0039] Cooling/coupling control systems **306** may be provided to remove waste heat from an exemplary probe **104**,

provide a controlled temperature at the superficial tissue interface and deeper into the tissue, and/or provide acoustic coupling from transducer probe **104** to region-of-interest **106**. Such cooling/coupling control systems **306** can also be configured to operate in both open-loop and/or closed-loop feedback arrangements with various coupling and feedback components.

[0040] Processing and control logic components **308** can comprise various system processors and digital control logic **307**, such as one or more of microcontrollers, microprocessors, field-programmable gate arrays (FPGAs), computer boards, and associated components, including firmware and control software **326**, which interfaces to user controls and interfacing circuits as well as input/output circuits and systems for communications, displays, interfacing, storage, documentation, and other useful functions. System software and firmware **326** controls all initialization, timing, level setting, monitoring, safety monitoring, and all other system functions required to accomplish user-defined treatment objectives. Further, various control switches **308** can also be suitably configured to control operation.

[0041] An exemplary transducer probe **104** can also be configured in various manners and comprise a number of reusable and/or disposable components and parts in various embodiments to facilitate its operation. For example, transducer probe **104** can be configured within any type of transducer probe housing or arrangement for facilitating the coupling of transducer to a tissue interface, with such housing comprising various shapes, contours and configurations depending on the particular treatment application. For example, in accordance with an exemplary embodiment, transducer probe **104** can be depressed against a tissue interface whereby blood perfusion is partially or completely cut-off, and tissue flattened in superficial treatment region-of-interest **106**. Transducer probe **104** can comprise any type of matching, such as for example, electric matching, which may be electrically switchable; multiplexer circuits and/or aperture/element selection circuits; and/or probe identification devices, to certify probe handle, electric matching, transducer usage history and calibration, such as one or more serial EEPROM (memories). Transducer probe **104** may also comprise cables and connectors; motion mechanisms, motion sensors and encoders; thermal monitoring sensors; and/or user control and status related switches, and indicators such as LEDs. For example, a motion mechanism in probe **104** may be used to controllably create multiple lesions, or sensing of probe motion itself may be used to controllably create multiple lesions and/or stop creation of lesions, e.g. for safety reasons if probe **104** is suddenly jerked or is dropped. In addition, an external motion encoder arm may be used to hold the probe during use, whereby the spatial position and attitude of probe **104** is sent to the control system to help controllably create lesions. Furthermore, other sensing functionality such as profilometers or other imaging modalities may be integrated into the probe in accordance with various exemplary embodiments.

[0042] With reference to **FIGS. 4A and 4B**, in accordance with an exemplary embodiment, a transducer probe **400** can comprise a control interface **402**, a transducer **404**, coupling components **406**, and monitoring/sensing components **408**, and/or motion mechanism **410**. However, transducer probe **400** can be configured and optimized in a variety of ways with more or less parts and components to provide ultra-



sound energy for controlled thermal injury, and the embodiment in FIGS. 4A and 4B are merely for illustration purposes.

[0043] Control interface 402 is configured for interfacing with control system 300 to facilitate control of transducer probe 400. Control interface components 402 can comprise multiplexer/aperture select 424, switchable electric matching networks 426, serial EEPROMs and/or other processing components and matching and probe usage information 430 and interface connectors 432.

[0044] Coupling components 406 can comprise various devices to facilitate coupling of transducer probe 400 to a region of interest. For example, coupling components 406 can comprise cooling and acoustic coupling system 420 configured for acoustic coupling of ultrasound energy and signals. Acoustic cooling/coupling system 420 with possible connections such as manifolds may be utilized to couple sound into the region-of-interest, control temperature at the interface and deeper into tissue, provide liquid-filled lens focusing, and/or to remove transducer waste heat. Coupling system 420 may facilitate such coupling through use of various coupling mediums, including air and other gases, water and other fluids, gels, solids, and/or any combination thereof, or any other medium that allows for signals to be transmitted between transducer active elements 412 and a region of interest. In addition to providing a coupling function, in accordance with an exemplary embodiment, coupling system 420 can also be configured for providing temperature control during the treatment application. For example, coupling system 420 can be configured for controlled cooling of an interface surface or region between transducer probe 400 and a region of interest and deeper into tissue by suitably controlling the temperature of the coupling medium. The suitable temperature for such coupling medium can be achieved in various manners, and utilize various feedback systems, such as thermocouples, thermistors or any other device or system configured for temperature measurement of a coupling medium. Such controlled cooling can be configured to further facilitate spatial and/or thermal energy control of transducer probe 400.

[0045] In accordance with an exemplary embodiment, with additional reference to FIG. 11, acoustic coupling and cooling 1140 can be provided to acoustically couple energy and imaging signals from transducer probe 1104 to and from the region of interest 1106, to provide thermal control at the probe to region-of-interest interface 1110 and deeper into the tissue to control lesioning, and to remove potential waste heat from the transducer probe at region 1144. Temperature monitoring can be provided at the coupling interface via a thermal sensor 1146 to provides a mechanism of temperature measurement 1148 and control via control system 1102 and a thermal control system 1142. Thermal control may consist of passive cooling such as via heat sinks or natural conduction and convection or via active cooling such as with peltier thermoelectric coolers, refrigerants, or fluid-based systems comprised of pump, fluid reservoir, bubble detection, flow sensor, flow channels/tubing 1144 and thermal control 1142.

[0046] With continued reference to FIG. 4, monitoring and sensing components 408 can comprise various motion and/or position sensors 416, temperature monitoring sensors 418, user control and feedback switches 414 and other like components for facilitating control by control system 300,

e.g., to facilitate spatial and/or temporal control through open-loop and closed-loop feedback arrangements that monitor various spatial and temporal characteristics.

[0047] Motion mechanism 410 can comprise manual operation, mechanical arrangements, or some combination thereof. For example, a motion mechanism 422 can be suitably controlled by control system 300, such as through the use of accelerometers, encoders or other position/orientation devices 416 to determine and enable movement and positions of transducer probe 400. Linear, rotational or variable movement can be facilitated, e.g., those depending on the treatment application and tissue contour surface.

[0048] Transducer 404 can comprise one or more transducers configured for producing conformal lesions of thermal injury in superficial human tissue within a region of interest through precise spatial and temporal control of acoustic energy deposition. Transducer 404 can also comprise one or more transduction elements and/or lenses 412. The transduction elements can comprise a piezoelectrically active material, such as lead zirconate titanate (PZT), or any other piezoelectrically active material, such as a piezoelectric ceramic, crystal, plastic, and/or composite materials, as well as lithium niobate, lead titanate, barium titanate, and/or lead metaniobate. In addition to, or instead of, a piezoelectrically active material, transducer 404 can comprise any other materials configured for generating radiation and/or acoustical energy. Transducer 404 can also comprise one or more matching layers configured along with the transduction element such as coupled to the piezoelectrically active material. Acoustic matching layers and/or damping may be employed as necessary to achieve the desired electroacoustic response.

[0049] In accordance with an exemplary embodiment, the thickness of the transduction element of transducer 404 can be configured to be uniform. That is, a transduction element 412 can be configured to have a thickness that is substantially the same throughout. In accordance with another exemplary embodiment, the thickness of a transduction element 412 can also be configured to be variable. For example, transduction element(s) 412 of transducer 404 can be configured to have a first thickness selected to provide a center operating frequency of a lower range, for example from approximately 1 kHz to 3 MHz. Transduction element 404 can also be configured with a second thickness selected to provide a center operating frequency of a higher range, for example from approximately 3 to 100 MHz or more. Transducer 404 can be configured as a single broadband transducer excited with at least two or more frequencies to provide an adequate output for generating a desired response. Transducer 404 can also be configured as two or more individual transducers, wherein each transducer comprises one or more transduction element. The thickness of the transduction elements can be configured to provide center-operating frequencies in a desired treatment range. For example, transducer 404 can comprise a first transducer configured with a first transduction element having a thickness corresponding to a center frequency range of approximately 1 kHz to 3 MHz, and a second transducer configured with a second transduction element having a thickness corresponding to a center frequency of approximately 3 MHz to 100 MHz or more.

[0050] Transducer 404 may be composed of one or more individual transducers in any combination of focused, pla-

nar, or unfocused single-element, multi-element, or array transducers, including 1-D, 2-D, and annular arrays; linear, curvilinear, sector, or spherical arrays; spherically, cylindrically, and/or electronically focused, defocused, and/or lensed sources. For example, with reference to an exemplary embodiment depicted in **FIG. 5**, transducer **500** can be configured as an acoustic array to facilitate phase focusing. That is, transducer **500** can be configured as an array of electronic apertures that may be operated by a variety of phases via variable electronic time delays. By the term “operated,” the electronic apertures of transducer **500** may be manipulated, driven, used, and/or configured to produce and/or deliver an energy beam corresponding to the phase variation caused by the electronic time delay. For example, these phase variations can be used to deliver defocused beams, planar beams, and/or focused beams, each of which may be used in combination to achieve different physiological effects in a region of interest **510**. Transducer **500** may additionally comprise any software and/or other hardware for generating, producing and or driving a phased aperture array with one or more electronic time delays.

[0051] Transducer **500** can also be configured to provide focused treatment to one or more regions of interest using various frequencies. In order to provide focused treatment, transducer **500** can be configured with one or more variable depth devices to facilitate treatment. For example, transducer **500** may be configured with variable depth devices disclosed in U.S. patent application Ser. No. 10/944,500, entitled “System and Method for Variable Depth Ultrasound”, filed on Sep. 16, 2004, having at least one common inventor and a common Assignee as the present application, and incorporated herein by reference. In addition, transducer **500** can also be configured to treat one or more additional ROI **510** through the enabling of sub-harmonics or pulse-echo imaging, as disclosed in U.S. Patent Application Ser. No. 10/944,499, entitled “Method and System for Ultrasound Treatment with a Multi-directional Transducer”, filed on Sep. 16, 2004, having at least one common inventor and a common Assignee as the present application, and also incorporated herein by reference.

[0052] Moreover, any variety of mechanical lenses or variable focus lenses, e.g. liquid-filled lenses, may also be used to focus and or defocus the sound field. For example, with reference to exemplary embodiments depicted in **FIGS. 6A and 6B**, transducer **600** may also be configured with an electronic focusing array **604** in combination with one or more transduction elements **606** to facilitate increased flexibility in treating ROI **610**. Array **604** may be configured in a manner similar to transducer **502**. That is, array **604** can be configured as an array of electronic apertures that may be operated by a variety of phases via variable electronic time delays, for example,  $T_1, T_2 \dots T_j$ . By the term “operated,” the electronic apertures of array **604** may be manipulated, driven, used, and/or configured to produce and/or deliver energy in a manner corresponding to the phase variation caused by the electronic time delay. For example, these phase variations can be used to deliver defocused beams, planar beams, and/or focused beams, each of which may be used in combination to achieve different physiological effects in ROI **610**.

[0053] Transduction elements **606** may be configured to be concave, convex, and/or planar. For example, in an exemplary embodiment depicted in **FIG. 6A**, transduction

elements **606A** are configured to be concave in order to provide focused energy for treatment of ROI **610**. Additional embodiments are disclosed in U.S. Patent Application Ser. No. 10/944,500, entitled “Variable Depth Transducer System and Method”, and again incorporated herein by reference.

[0054] In another exemplary embodiment, depicted in **FIG. 6B**, transduction elements **606B** can be configured to be substantially flat in order to provide substantially uniform energy to ROI **610**. While **FIGS. 6A and 6B** depict exemplary embodiments with transduction elements **604** configured as concave and substantially flat, respectively, transduction elements **604** can be configured to be concave, convex, and/or substantially flat. In addition, transduction elements **604** can be configured to be any combination of concave, convex, and/or substantially flat structures. For example, a first transduction element can be configured to be concave, while a second transduction element can be configured to be substantially flat.

[0055] With reference to **FIGS. 8A and 8B**, transducer **404** can be configured as single-element arrays, wherein a single-element **802**, e.g., a transduction element of various structures and materials, can be configured with a plurality of masks **804**, such masks comprising ceramic, metal or any other material or structure for masking or altering energy distribution from element **802**, creating an array of energy distributions **808**. Masks **804** can be coupled directly to element **802** or separated by a standoff **806**, such as any suitably solid or liquid material.

[0056] An exemplary transducer **404** can also be configured as an annular array to provide planar, focused and/or defocused acoustical energy. For example, with reference to **FIGS. 10A and 10B**, in accordance with an exemplary embodiment, an annular array **1000** can comprise a plurality of rings **1012, 1014, 1016** to N. Rings **1012, 1014, 1016** to N can be mechanically and electrically isolated into a set of individual elements, and can create planar, focused, or defocused waves. For example, such waves can be centered on-axis, such as by methods of adjusting corresponding transmit and/or receive delays,  $\tau_1, \tau_2, \tau_3 \dots \tau_N$ . An electronic focus can be suitably moved along various depth positions, and can enable variable strength or beam tightness, while an electronic defocus can have varying amounts of defocusing. In accordance with an exemplary embodiment, a lens and/or convex or concave shaped annular array **1000** can also be provided to aid focusing or defocusing such that any time differential delays can be reduced. Movement of annular array **800** in one, two or three-dimensions, or along any path, such as through use of probes and/or any conventional robotic arm mechanisms, may be implemented to scan and/or treat a volume or any corresponding space within a region of interest.

[0057] Transducer **404** can also be configured in other annular or non-array configurations for imaging/therapy functions. For example, with reference to **FIGS. 10C-10F**, a transducer can comprise an imaging element **1012** configured with therapy element(s) **1014**. Elements **1012** and **1014** can comprise a single-transduction element, e.g., a combined imaging/therapy element, or separate elements, such as an imaging element **1012** configured within a hole or opening between therapy elements **1014** as illustrated in **FIG. 10C**, can be electrically isolated **1022** within the same

transduction element or between separate imaging and therapy elements such as illustrated in FIG. 10D, and/or can comprise standoff 1024 or other matching layers, or any combination thereof. For example, with particular reference to FIG. 10F, a transducer can comprise an imaging element 1012 having a surface 1028 configured for focusing, defocusing or planar energy distribution, with therapy elements 1014 including a stepped-configuration lens configured for focusing, defocusing, or planar energy distribution.

[0058] In accordance with various exemplary embodiments of the present invention, transducer 404 may be configured to provide one, two and/or three-dimensional treatment applications for focusing acoustic energy to one or more regions of interest. For example, as discussed above, transducer 404 can be suitably diced to form a one-dimensional array, e.g., transducer 602 comprising a single array of sub-transduction elements.

[0059] In accordance with another exemplary embodiment, transducer 404 may be suitably diced in two-dimensions to form a two-dimensional array. For example, with reference to FIG. 9, an exemplary two-dimensional array 900 can be suitably diced into a plurality of two-dimensional portions 902. Two-dimensional portions 902 can be suitably configured to focus on the treatment region at a certain depth, and thus provide respective slices 904 of the treatment region. As a result, the two-dimensional array 900 can provide a two-dimensional slicing of the image plane of a treatment region, thus providing two-dimensional treatment.

[0060] In accordance with another exemplary embodiment, transducer 404 may be suitably configured to provide three-dimensional treatment. For example, to provide three-dimensional treatment of a region of interest, with reference again to FIG. 1, a three-dimensional system can comprise a transducer within probe 104 configured with an adaptive algorithm, such as, for example, one utilizing three-dimensional graphic software, contained in a control system, such as control system 102. The adaptive algorithm is suitably configured to receive two-dimensional imaging, temperature and/or treatment or other tissue parameter information relating to the region of interest, process the received information, and then provide corresponding three-dimensional imaging, temperature and/or treatment information.

[0061] In accordance with an exemplary embodiment, with reference again to FIG. 9, an exemplary three-dimensional system can comprise a two-dimensional array 900 configured with an adaptive algorithm to suitably receive 904 slices from different image planes of the treatment region, process the received information, and then provide volumetric information 906, e.g., three-dimensional imaging, temperature and/or treatment information. Moreover, after processing the received information with the adaptive algorithm, the two-dimensional array 900 may suitably provide therapeutic heating to the volumetric region 906 as desired.

[0062] In accordance with other exemplary embodiments, rather than utilizing an adaptive algorithm, such as three-dimensional software, to provide three-dimensional imaging and/or temperature information, an exemplary three-dimensional system can comprise a single transducer 404 configured within a probe arrangement to operate from various rotational and/or translational positions relative to a target region.

[0063] To further illustrate the various structures for transducer 404, with reference to FIG. 7, ultrasound therapy transducer 700 can be configured for a single focus, an array of foci, a locus of foci, a line focus, and/or diffraction patterns. Transducer 700 can also comprise single elements, multiple elements, annular arrays, one-, two-, or three-dimensional arrays, broadband transducers, and/or combinations thereof, with or without lenses, acoustic components, and mechanical and/or electronic focusing. Transducers configured as spherically focused single elements 702, annular arrays 704, annular arrays with damped regions 706, line focused single elements 708, 1-D linear arrays 710, 1-D curvilinear arrays in concave or convex form, with or without elevation focusing, 2-D arrays, and 3-D spatial arrangements of transducers may be used to perform therapy and/or imaging and acoustic monitoring functions. For any transducer configuration, focusing and/or defocusing may be in one plane or two planes via mechanical focus 720, convex lens 722, concave lens 724, compound or multiple lenses 726, planar form 728, or stepped form, such as illustrated in FIG. 10F. Any transducer or combination of transducers may be utilized for treatment. For example, an annular transducer may be used with an outer portion dedicated to therapy and the inner disk dedicated to broadband imaging wherein such imaging transducer and therapy transducer have different acoustic lenses and design, such as illustrated in FIG. 10C-10F.

[0064] With a better understanding of the various transducer structures, and with reference again to FIG. 2, how the geometric configuration of the transducer or transducers that contributes to the wide range of lesioning effects can be better understood. For example, cigar-shaped lesions 204 and 206 may be produced from a spherically focused source, and/or planar lesions 210 from a flat source. Concave planar sources and arrays can produce a "V-shaped" or ellipsoidal lesion 214. Electronic arrays, such as a linear array, can produce defocused, planar, or focused acoustic beams that may be employed to form a wide variety of additional lesion shapes at various depths. An array may be employed alone or in conjunction with one or more planar or focused transducers. Such transducers and arrays in combination produce a very wide range of acoustic fields and their associated benefits. A fixed focus and/or variable focus lens or lenses may be used to further increase treatment flexibility. A convex-shaped lens, with acoustic velocity less than that of superficial tissue, may be utilized, such as a liquid-filled lens, gel-filled or solid gel lens, rubber or composite lens, with adequate power handling capacity; or a concave-shaped, low profile, lens may be utilized and composed of any material or composite with velocity greater than that of tissue. While the structure of transducer source and configuration can facilitate a particular shaped lesion as suggested above, such structures are not limited to those particular shapes as the other spatial parameters, as well as the temporal parameters, can facilitate additional shapes within any transducer structure and source.

[0065] The physiological effects created in tissue are not only affected by the spatial distribution of energy, such as transducer structure, distance/placement, orientation, and/or movement, but also its temporal, time-varying characteristics. For example, as to temporal control, each array, two-dimensional array, or single element transducer may be used at various transmit frequencies, and may be either broadband or relatively narrowband, with center frequencies ranging

from approximately 1 MHz to 40 MHz, or even with single broadband pulses of energy. Amplitude levels and frequency selection may be changed during treatment to further enhance options. Transmit duration and energy levels are configured to overcome tissue thermal capacity and create controlled thermal injury (necrosis) and/or ablation. Thermal capacity is the minimum amount of energy/heat that is sufficient for live tissue to lose function. In this context, thermal capacity is the minimum amount of energy to result in live tissue destruction.

[0066] Such spatial and/or temporal control can also be enhanced through open-loop and/or closed loop feedback systems. For example, with reference to **FIG. 12A**, treatment system **1200** can comprise an open-loop feedback structure having a control system **1102** configured with a probe **1204** to treat a region-of-interest **1206**. Control system **1202** can comprise control components **1208**, such as the various control components within control system **300**, a display **1210**, and tissue parameter monitoring components **1212**, or any other sensing or monitoring components. Display **1210** can comprise any display configured for illustrating images, such as of the treatment region, and/or any spatial or temporal parameter. In such an open-loop system, a system user can suitably monitor the imaging and/or other spatial or temporal parameters and then adjust or modify same to accomplish a particular treatment objective. Instead of, or in combination with open-loop feedback configurations, with reference to an exemplary embodiment illustrated in **FIG. 12B**, an exemplary treatment system **1200** can comprise a closed-loop feedback system, wherein images and/or spatial/temporal parameters can be suitably monitored within monitoring component **1212** to generate signals, e.g., within a driver **1214** and amplifier **1216**, or any other controllable aspect of treatment system **1100**, to provide to control components **1208**. As a result, a closed-loop control of the output and operation of probe **1204** can be realized.

[0067] During operation of an exemplary treatment system, a lesion configuration of a selected size, shape, orientation is determined. Based on that lesion configuration, one or more spatial parameters are selected, along with suitable temporal parameters, the combination of which yields the desired conformal lesion. Operation of the transducer can then be initiated to provide the conformal lesion or lesions. Open and/or closed-loop feedback systems can also be implemented to monitor the spatial and/or temporal characteristics, and/or other tissue parameter monitoring, to further control the conformal lesions.

[0068] With reference to **FIG. 13**, a collection of simulation results, illustrating thermal lesion growth over time are illustrated. Such lesion growth was generated with a spherically focused, cylindrically focused, and planar (unfocused) source at a nominal source acoustic power level,  $W_0$  and twice that level,  $2W_0$ , but any configurations of transducer can be utilized as disclosed herein. The thermal contours indicate where the tissue reached  $65^\circ\text{C}$ . for different times. The contour for the cylindrically focused source is along the short axis, or so-called elevation plane. The figure highlights the different shapes of lesions possible with different power levels and source geometries. In addition, with reference to **FIG. 14**, a pair of lesioning and simulation results is illustrated, showing chemically stained porcine tissue photomicrographs adjacent to their simulation results. In addition,

with reference to **FIG. 15**, another pair of lesioning results is illustrated, showing chemically stained porcine tissue photomicrographs, highlighting a tadpole shaped lesion and a wedge shaped lesion.

[0069] In summary, adjustment of the acoustic field spatial distribution via transducer type and distribution, such as size, element configuration, electronic or mechanical lenses, acoustic coupling and/or cooling, combined with adjustment of the temporal acoustic field, such as through control of transmit power level and timing, transmit frequency and/or drive waveform can facilitate the achieving of controlled thermal lesions of variable size, shape, and depths. Moreover, the restorative biological responses of the human body can further cause the desired effects to the superficial human tissue.

[0070] The present invention has been described above with reference to various exemplary embodiments. However, those skilled in the art will recognize that changes and modifications may be made to the exemplary embodiments without departing from the scope of the present invention. For example, the various operational steps, as well as the components for carrying out the operational steps, may be implemented in alternate ways depending upon the particular application or in consideration of any number of cost functions associated with the operation of the system, e.g., various of the steps may be deleted, modified, or combined with other steps. These and other changes or modifications are intended to be included within the scope of the present invention, as set forth in the following claims.

What is claimed is:

1. A therapeutic treatment system for controlled thermal injury in human superficial tissue within a region-of-interest, said treatment system comprising:

a control system configured for control of said treatment system;

a probe configured for generating a conformal lesion within the region-of-interest, said control system and said probe being configured for spatial and temporal control to generate the conformal lesion.

2. The therapeutic treatment system according to claim 1, wherein said spatial control comprises operational control of one or more spatial parameters comprising transducer configuration, distance, placement, orientation, and movement.

3. The therapeutic treatment system according to claim 1, wherein said temporal control comprises operational control of one or more temporal parameters comprising drive amplitude levels, frequency/waveforms, and timing sequences.

4. The therapeutic treatment system according to claim 1, wherein said spatial and temporal control is facilitated through an open-loop feedback control loop.

5. The therapeutic treatment system according to claim 1, wherein said spatial and temporal control is facilitated through a closed-loop feedback control loop.

6. The therapeutic treatment system according to claim 1, wherein said control system comprises:

power source components configured to provide energy to said control system and said probe;

sensing and monitoring components configured for monitoring said spatial and temporal parameters;

cooling and coupling controls configured to facilitate temperature control at superficial human tissue interface and deeper into tissue; and

processing and control logic components for overall control of said therapeutic treatment system.

7. The therapeutic treatment system according to claim 1, wherein said probe comprises:

a control interface for interfacing with said control system;

a transducer configured for providing ablative ultrasound energy to the region-of-interest;

coupling components for acoustically coupling said transducer to the region of interest;

monitoring and sensing components for facilitating control by said control system; and

motion mechanism comprising one of manual and automated movement of said probe.

8. The therapeutic treatment system according to claim 2, wherein said transducer configuration comprises one or more structures of focused, planar, unfocused elements, one or more single-element, multi-element, and array transducers, one or more 1-D, 2-D, annular arrays, linear, curvilinear, sector, and spherical arrays.

9. The therapeutic treatment system according to claim 8, wherein said transducer configuration comprises one or more spherically, cylindrically, electronically focused, concave-shaped and low-profile lens, composed of at least one of plastics, polyurethanes, ceramics, metals, liquids, and composite materials.

10. The therapeutic treatment system according to claim 2, wherein said transducer configuration comprises a broadband transducer excited at one or more frequencies.

11. The therapeutic treatment system of claim 7, wherein said probe comprises at least one of sensors, motion sensors, switches, actuators, indicators, encoders, probe identification, memory devices, aperture selection and multiplexers, electric matching networks, and switching, interconnect, connectors, handle, and disposable members.

12. The therapeutic treatment system according to claim 6, wherein said control system comprises at least one of treatment planning, display, switches, microcontroller, microprocessor, computer, control firmware, user and control software.

13. The therapeutic treatment system of claim 6, whereby said control system comprises one or more of DC power supplies, current sensors, power detection and measurement, waveform synthesizer, oscillator, digital programmable logic, amplifier/driver, beamformer, harmonic filter, matching networks, cooling/acoustic coupling/thermal control/acoustic focusing control hardware, motion mechanism drivers and control, motion sensors, monitoring and closed loop control, interfacing and control, external input/output hardware and external interfaces.

14. The therapeutic treatment system according to claim 6, wherein said probe comprises transducer acoustic coupling, cooling, and/or liquid-filled acoustic lensing mechanisms configured to regulate temperature at an interface between said transducer and the region-of-interest, and into region-of-interest.

15. The therapeutic treatment system according to claim 1, wherein said probe can be depressed against a tissue

interface whereby blood perfusion is at least partially cut-off, and tissue flattened in the superficial treatment region-of-interest.

16. The therapeutic treatment system according to claim 1, wherein said controlled thermal injury is deposited in a continuous or discrete manner to trigger biological repair mechanisms.

17. The therapeutic treatment system according to claim 1, wherein said controlled thermal injury is deposited to facilitate an optimized cycle of recovery by way of varying of shapes and depths of thermal injuries in at least one location of said superficial human tissue.

18. The therapeutic treatment system according to claim 2, wherein said transducer configuration comprises a convex-shaped lens, in the form of at least one of a liquid-filled, gel-filled, solid gel lens, rubber or composite lens or any material with velocity less than that of superficial tissue and/or acoustic coupling medium and with adequate power handling capacity.

19. The therapeutic treatment system according to claim 2, wherein said transducer configuration comprises a combined imaging/therapy transducer within a single transduction element, wherein said imaging transducer is electrically isolated from said therapy transducer.

20. The therapeutic treatment system according to claim 1, wherein said control system comprises an imaging system configured for facilitating at least one of one-dimensional, two-dimensional and three-dimensional imaging or treatment.

21. A method for controlled thermal injury in human superficial tissue within a region-of-interest, said method comprising:

selecting at least one shape, size and orientation of a thermal lesion from a variety of selection choices;

providing a control system and a probe with one or more spatial parameters;

providing said control system and said probe with one or more temporal parameters;

controlling operation of said control system and said probe based on said spatial parameters and said temporal parameters to produce said selected shape, size and orientation of the thermal lesion within the region-of-interest.

22. The method according to claim 20, wherein said controlling operation comprises utilizing an open-loop feedback loop to determine when said thermal lesion has achieved said selected shape, size and orientation.

23. The method according to claim 20, wherein said controlling operation comprises utilizing a closed-loop feedback loop to determine when said thermal lesion has achieved said selected shape, size and orientation.

24. The method according to claim 20, wherein said spatial parameters comprise transducer configuration, distance, placement, orientation, and movement.

25. The method according to claim 20, wherein said temporal parameters comprise drive amplitude levels, frequency/waveforms, and timing sequences.

26. The method according to claim 20, wherein said control system and probe are controlled to generate the thermal lesion within a variable depth of 0-30 mm and a frequency range of 1 to 40 MHz, with a time duration and energy level sufficient to overcome tissue thermal capacity.

**27.** A treatment system configured for controlled thermal injury within a region-of-interest, said treatment system comprising:

a control system configured for facilitating spatial and temporal control of said treatment system;

a probe comprising a transducer configured for spatial and temporal control, said probe being configured for generating conformal lesions of variable shape, size and orientation, said lesions being configured within a depth of superficial human tissue between zero and 30 mm and through operation of said transducer at a frequency of between 1 MHz and 40 MHz and for a time duration and energy level sufficient to overcome tissue thermal capacity for the region-of-interest.

**28.** The treatment system according to claim 26, wherein said control system is configured to control operation of more than one spatial parameters comprising transducer configuration, distance, placement, orientation, and movement and control operation of more than one temporal parameters comprising drive amplitude levels, frequency/waveforms, and timing sequences.

**29.** The treatment system according to claim 27, wherein said treatment system is configured within at least one of an open-loop and a closed-loop feedback system.

**30.** The treatment system according to claim 26, wherein said transducer comprises an combined imaging/therapy transducer.

\* \* \* \* \*

|               |   |         |            |
|---------------|---|---------|------------|
| 专利名称(译)       | 用于控制人表面组织热损伤的方法和系统  |         |            |
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#### 摘要(译)

一种用于控制人表面组织热损伤的方法和系统, 其基于通过声能沉积的精确空间和时间控制可控制地产生可变形状, 大小和深度的热损伤的能力。该装置包括控制系统和探针, 其有助于治疗计划, 控制和输送能量, 以及监测治疗条件。

