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**Gallagher et al.**

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(54) **MINIMALLY INVASIVE NO TOUCH (MINT)  
PROCEDURE FOR HARVESTING THE  
GREAT SAPHENOUS VEIN (GSV) AND  
VENOUS HYDRODISSECTOR AND  
RETRACTOR FOR USE DURING THE MINT  
PROCEDURE**

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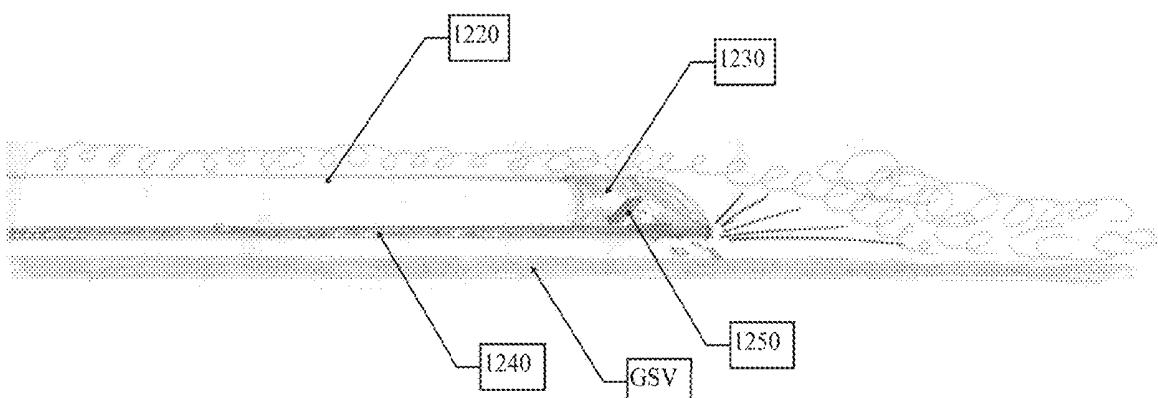
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(57) **ABSTRACT**

A hydrodissector for hydrodissecting a vein, the hydrodissector comprising a handle, a shaft extending from the handle at an angle and including a tip at a distal end thereof, at least one port configured to be coupled to a fluid supply for supplying fluid at a substantially constant pressure, and provided at the distal end of the shaft, and an image capturing assembly configured to provide direct visualization of the vein during hydrodissection. A minimally invasive method for dissecting a greater saphenous vein (GSV) from surrounding tissues using the hydrodissector is also described.

**32 Claims, 26 Drawing Sheets**



- Side view of dissector in situ hydro dissecting connective tissue off of underlying GSV

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See application file for complete search history.

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FIG. 1A

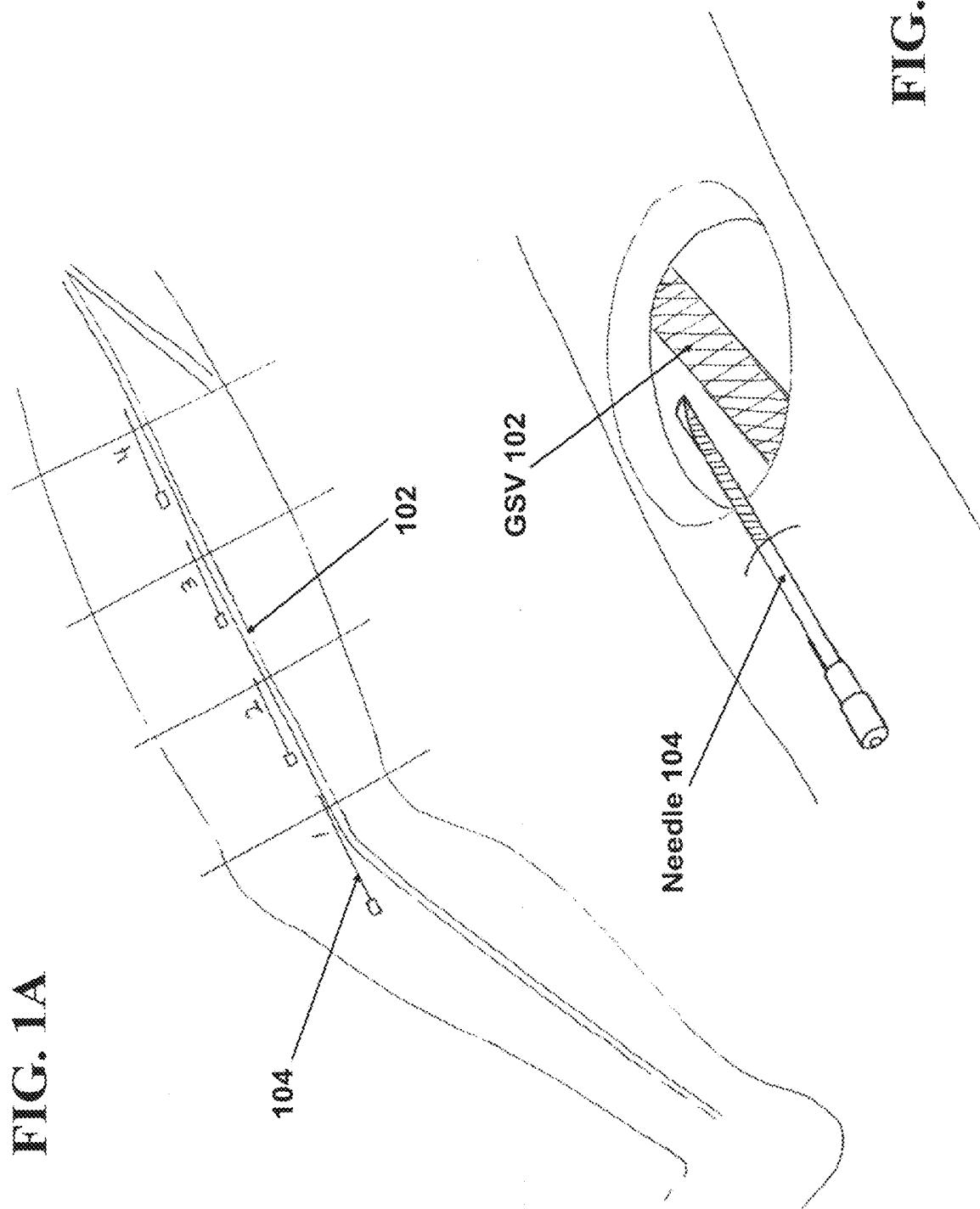


FIG. 1B

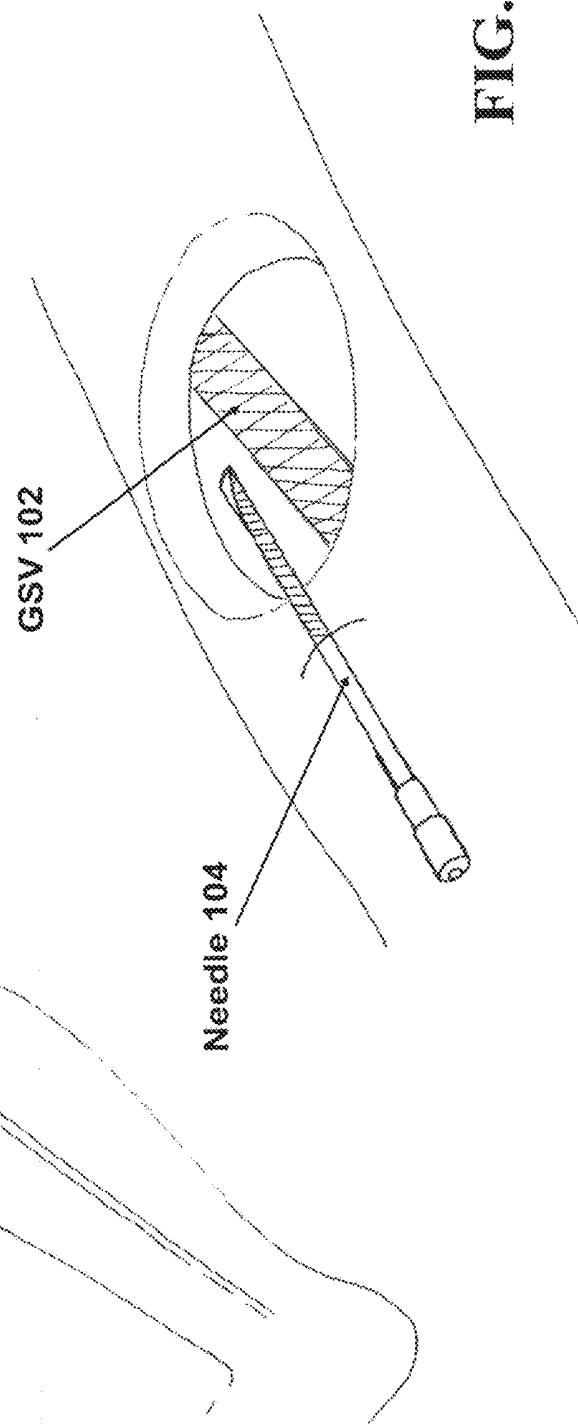


FIG. 2B

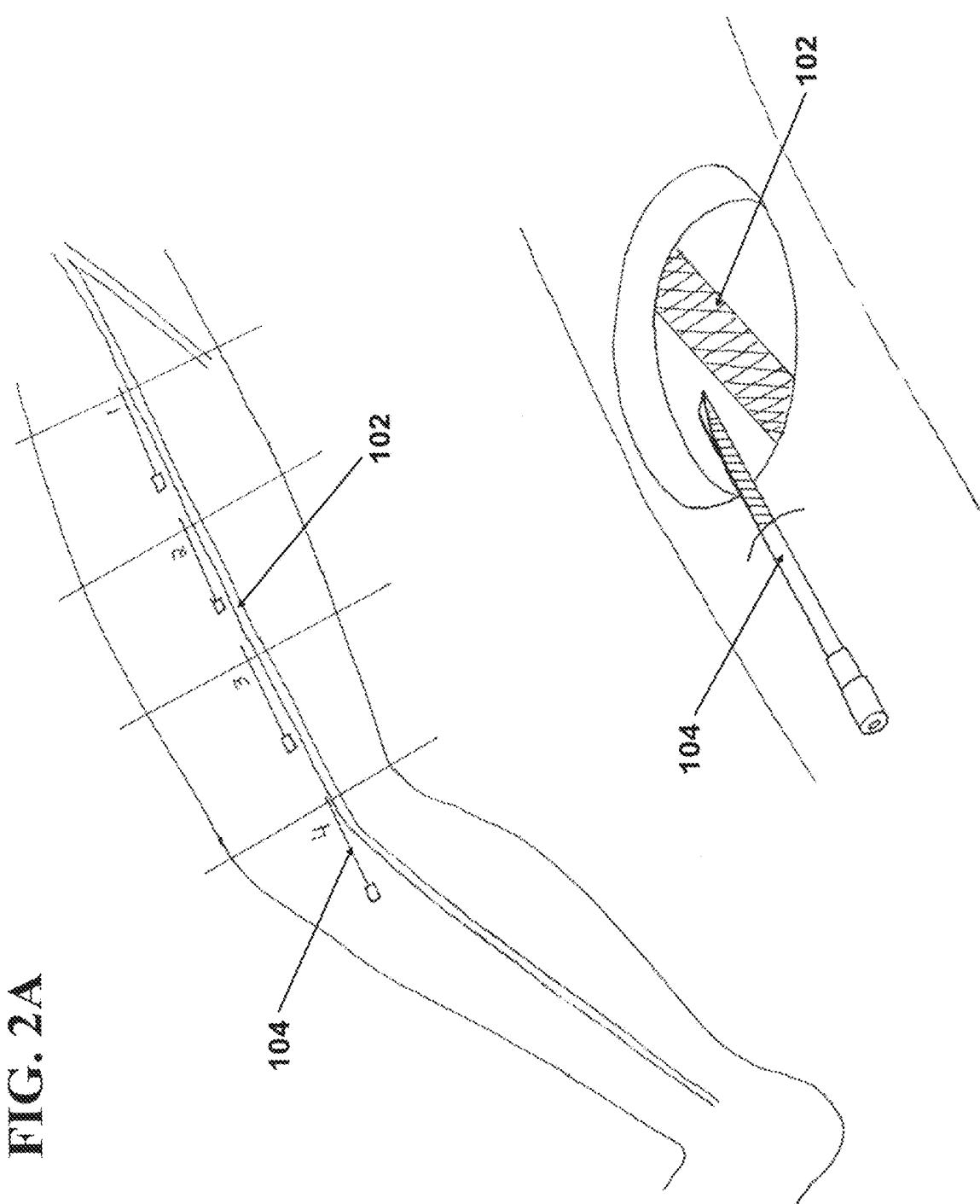
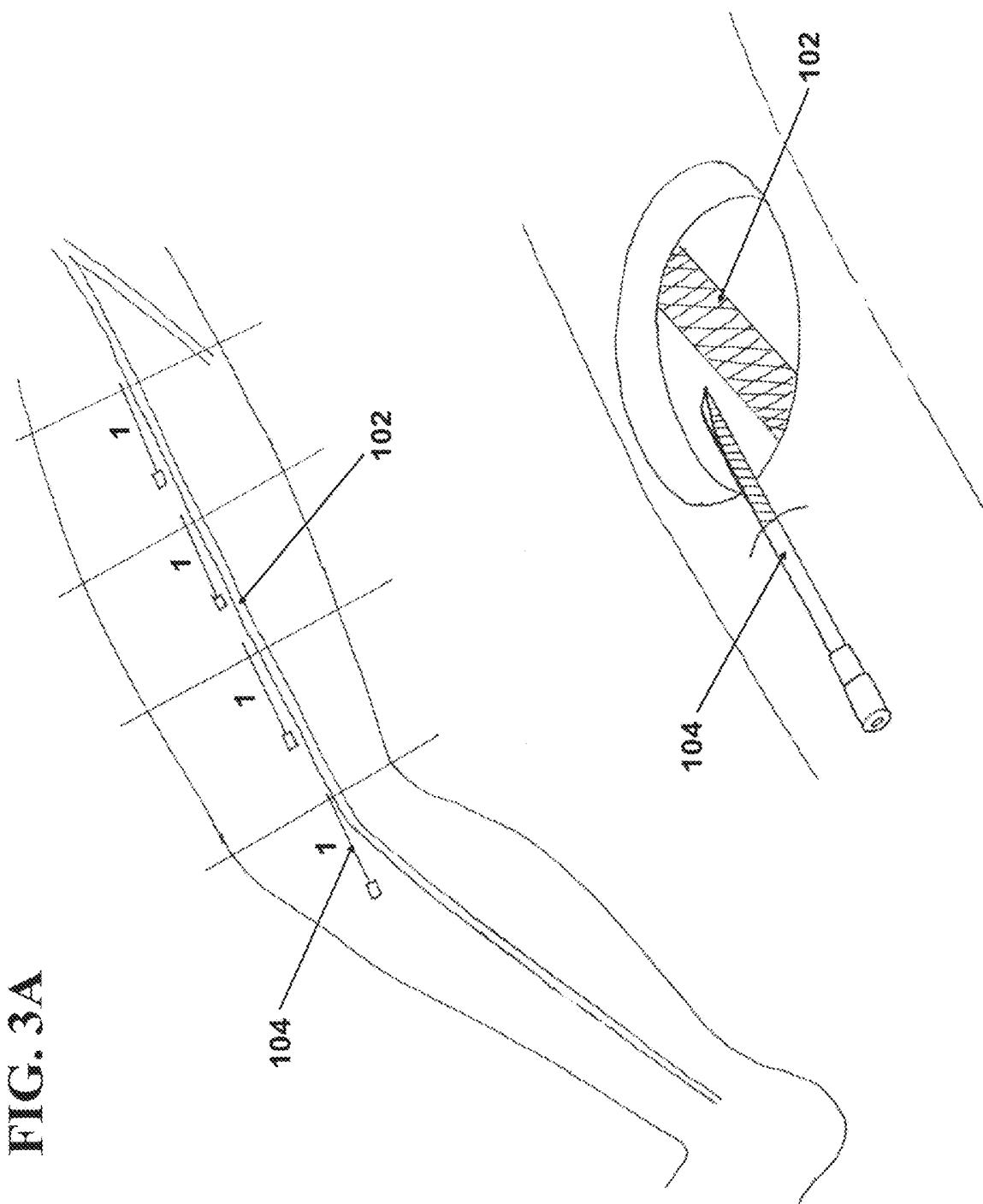
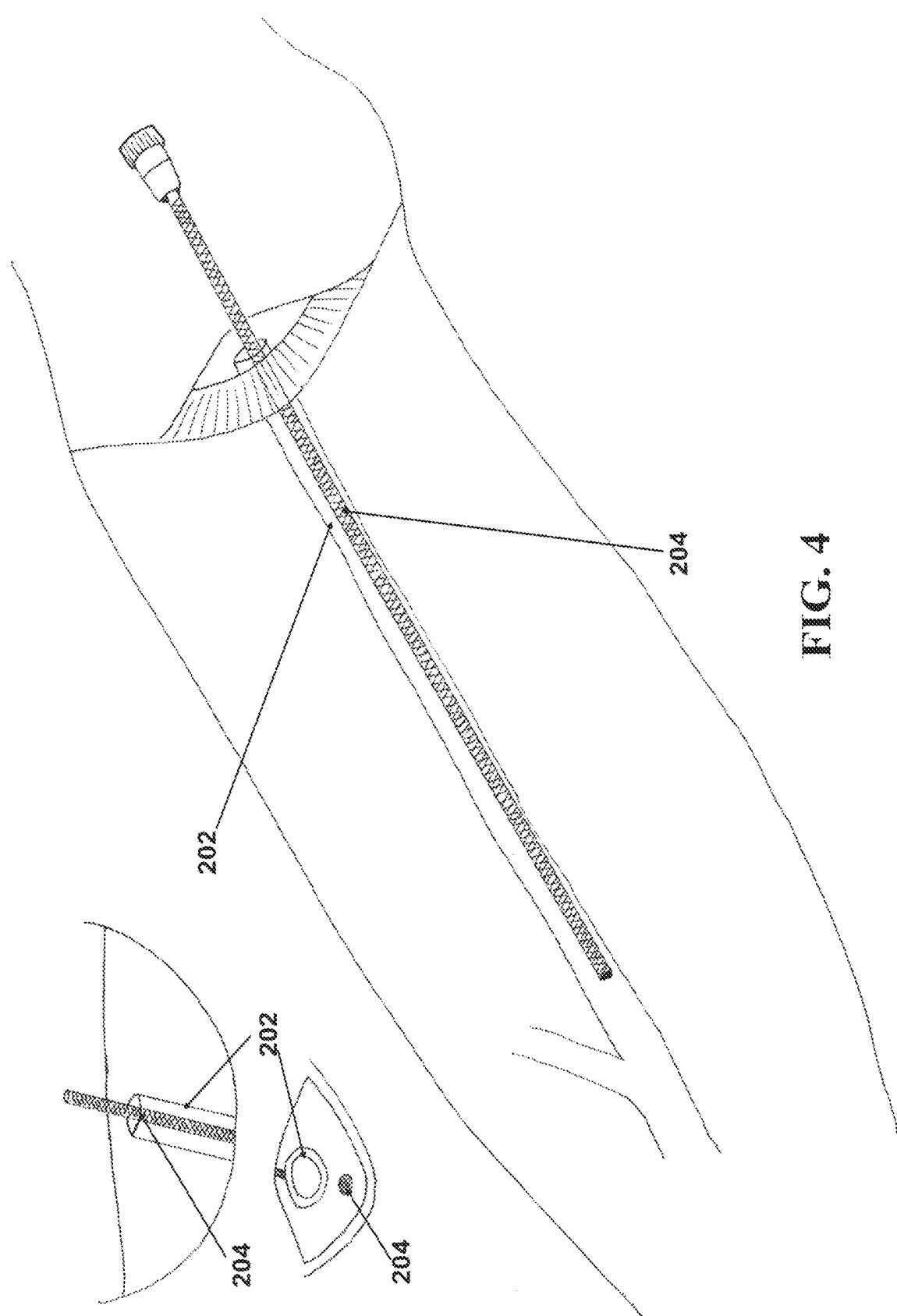
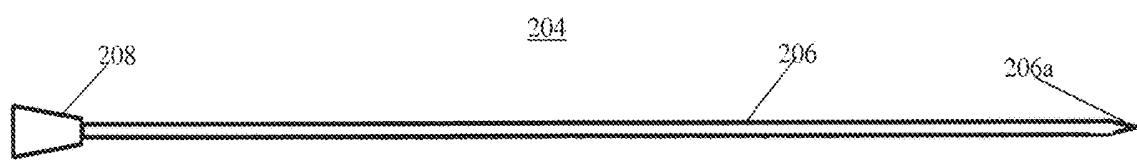


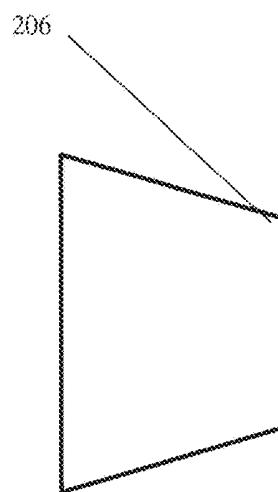
FIG. 3B



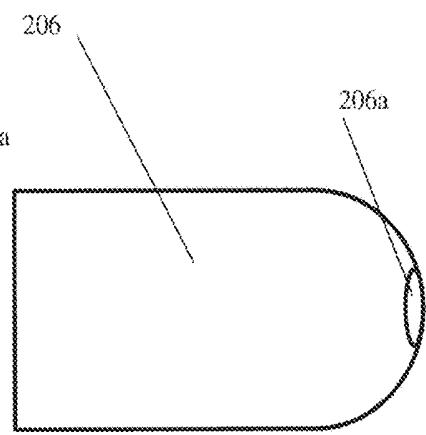




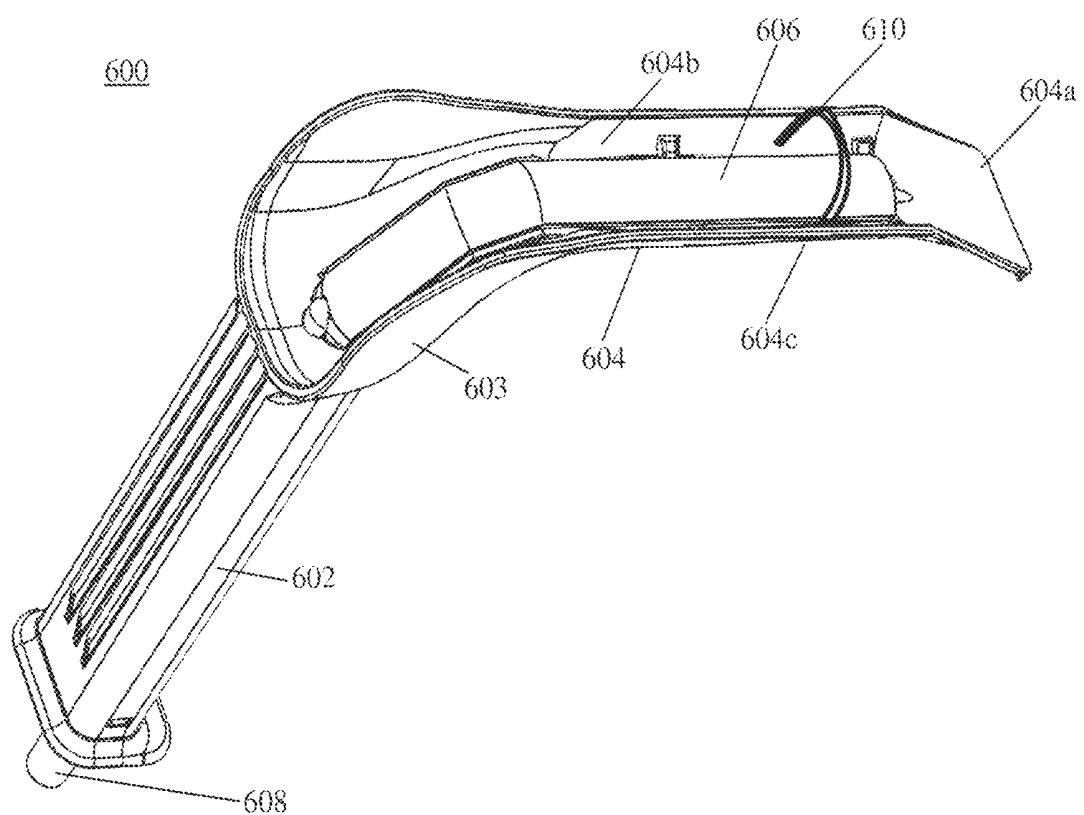
**FIG. 5A**



**FIG. 5B**



**FIG. 5C**



**FIG. 6**

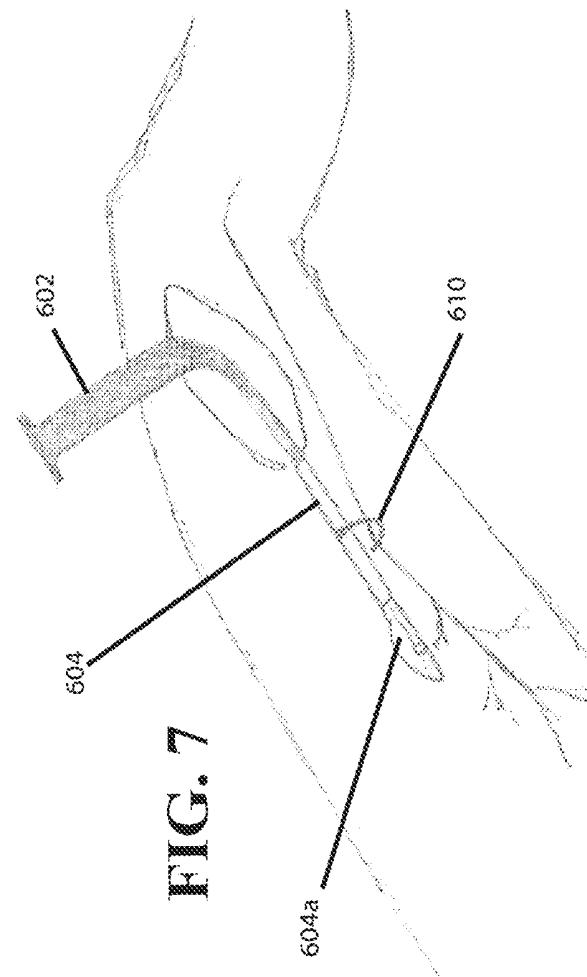


FIG. 8A

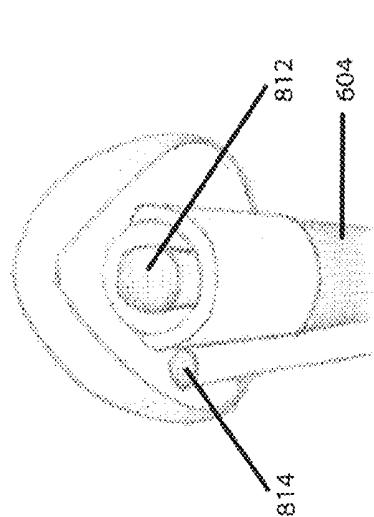
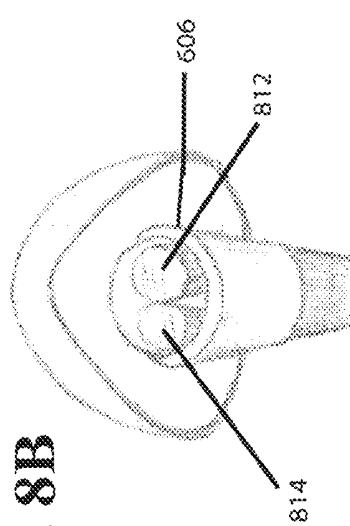
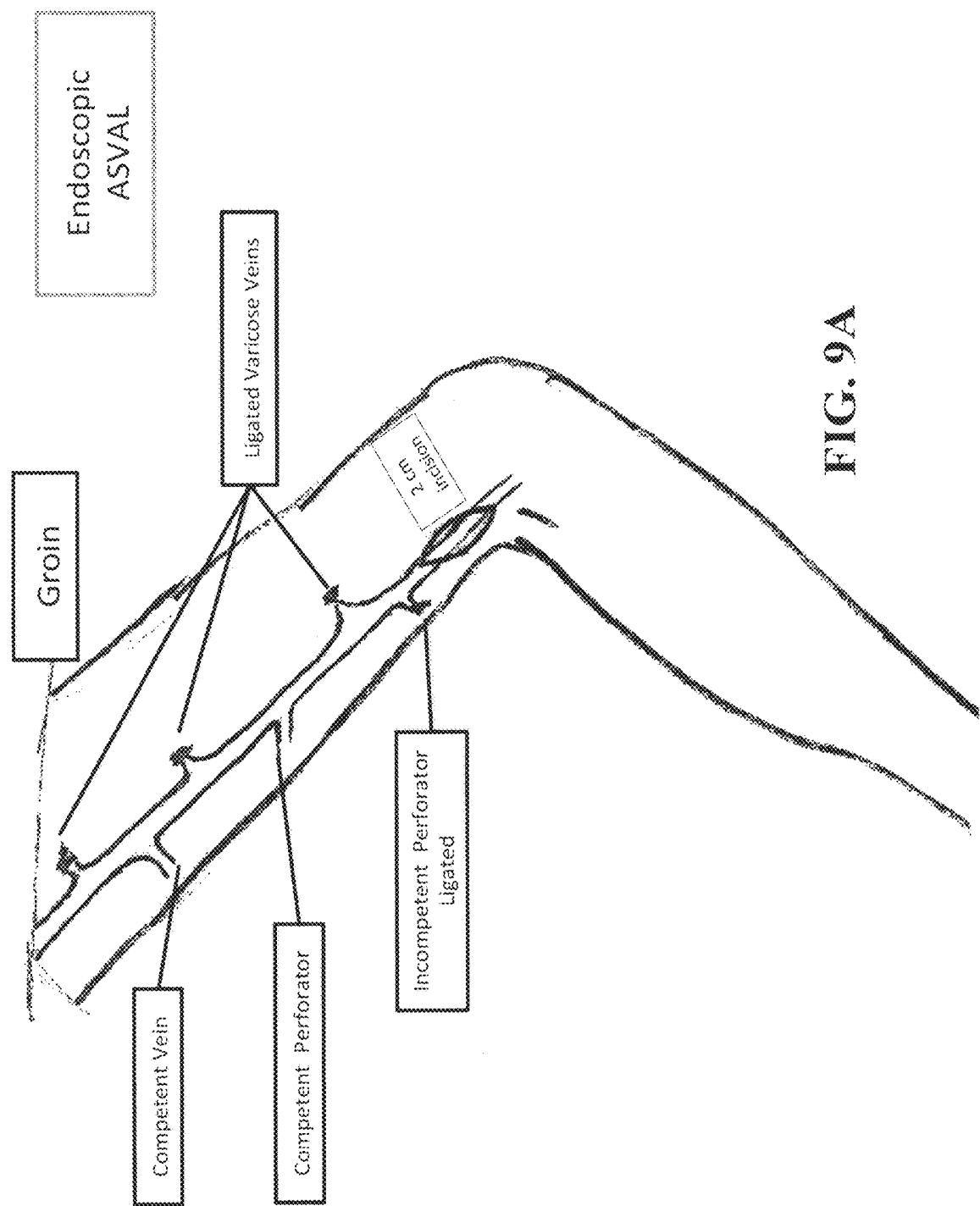


FIG. 8B





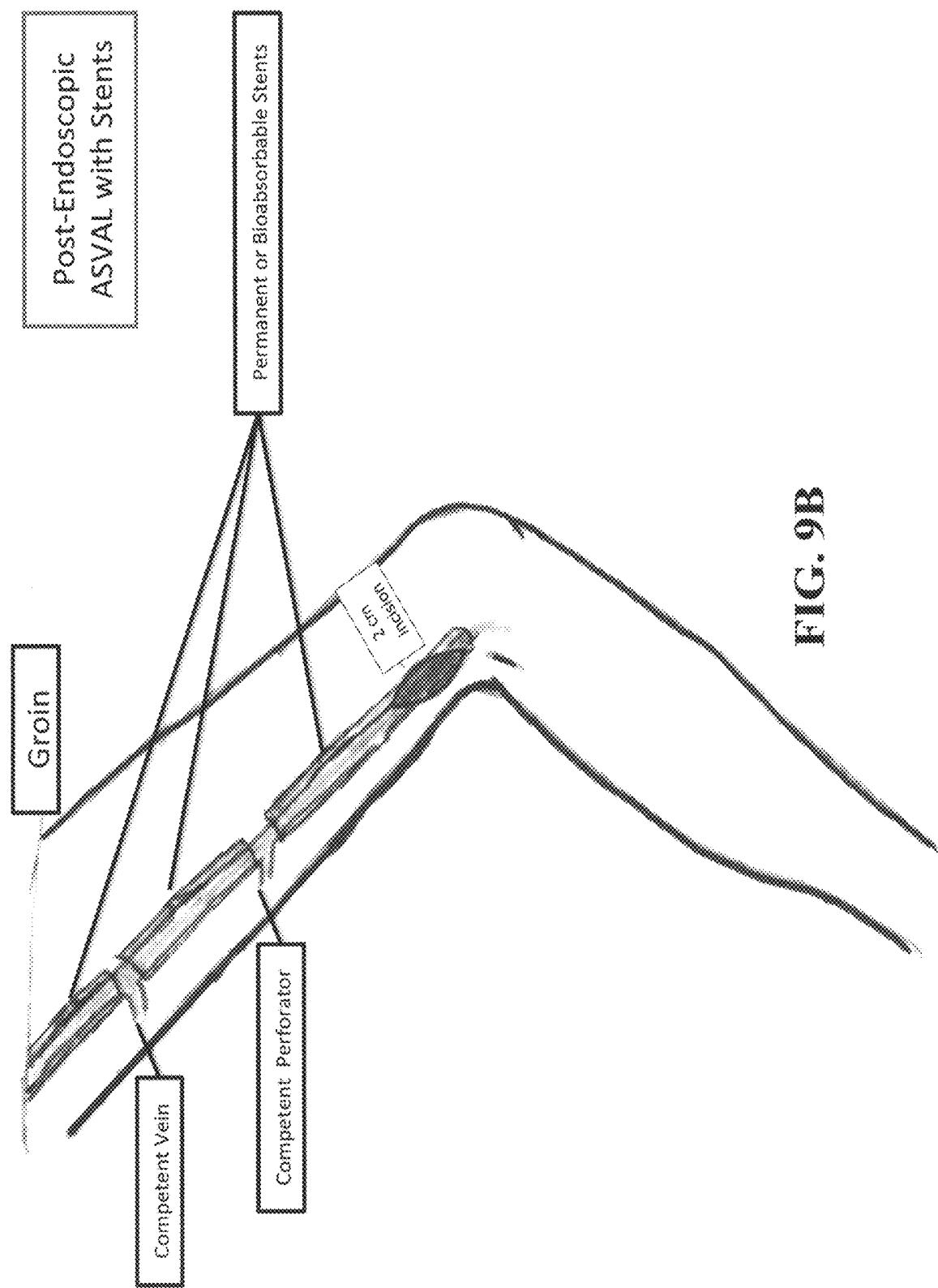
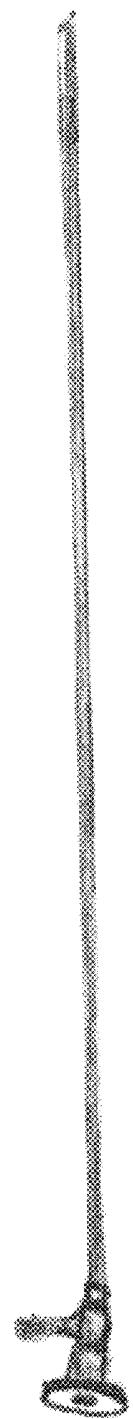


FIG. 9B



**FIG. 10**

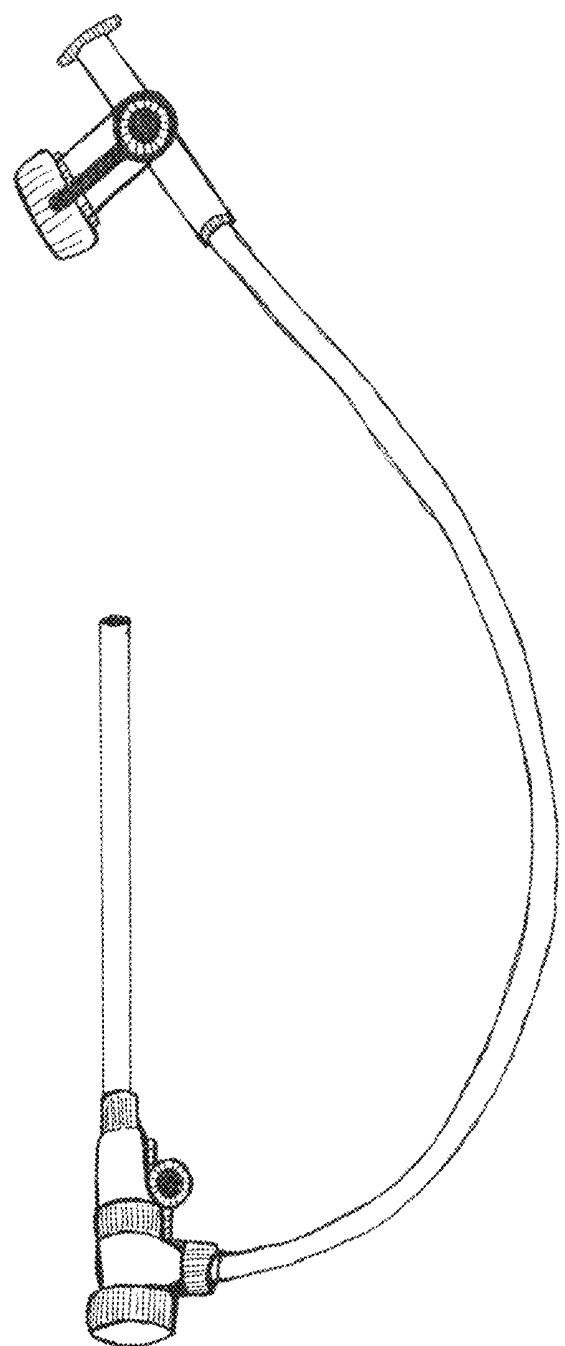


FIG. 11

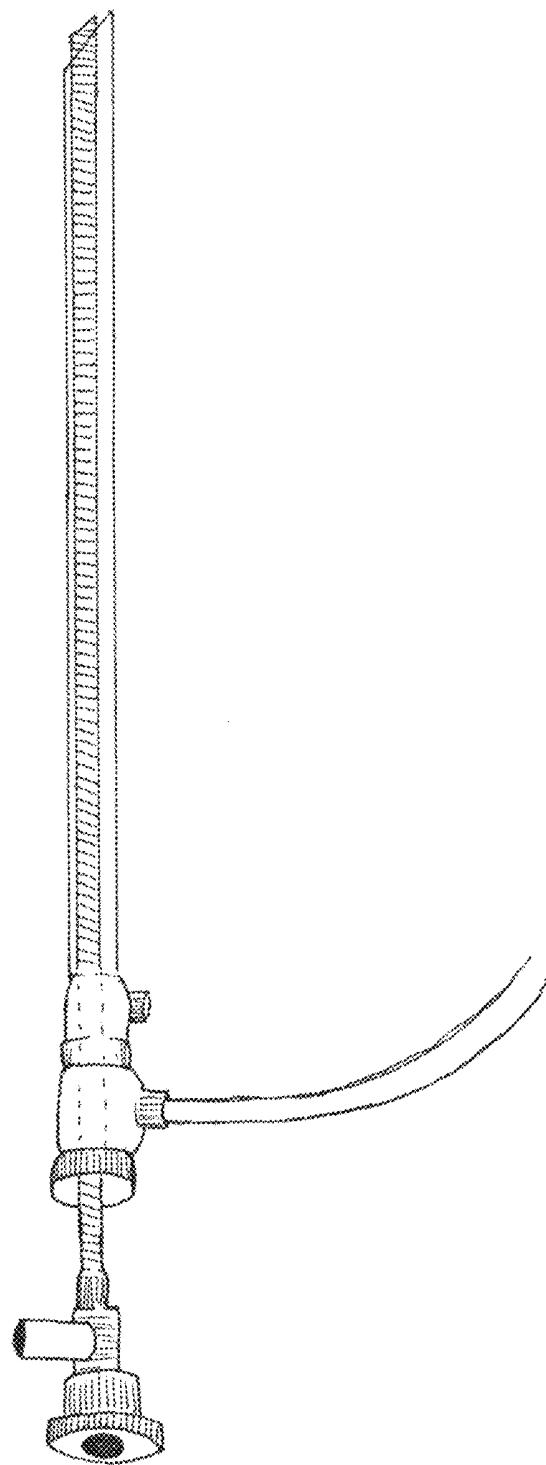


FIG. 12



FIG. 13

Tumescent fluid being injected inside introducer sheath and around cystoscope and exiting as a jet spray for hydrodissection

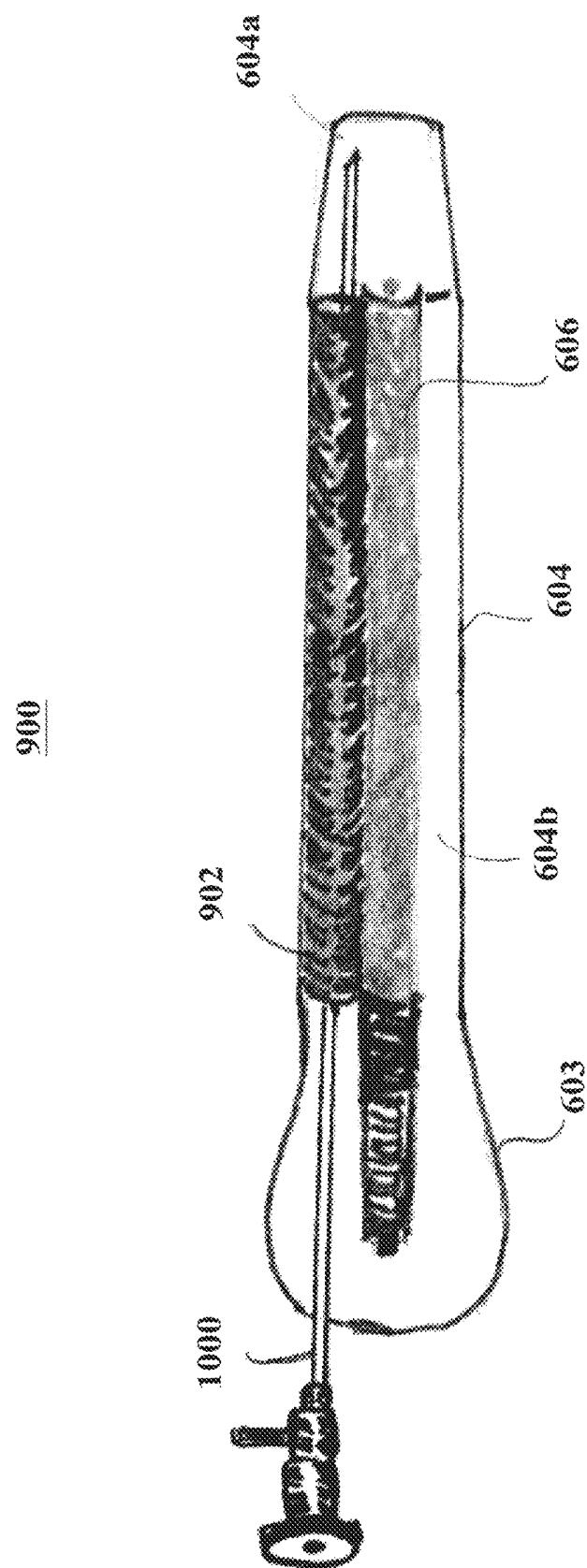
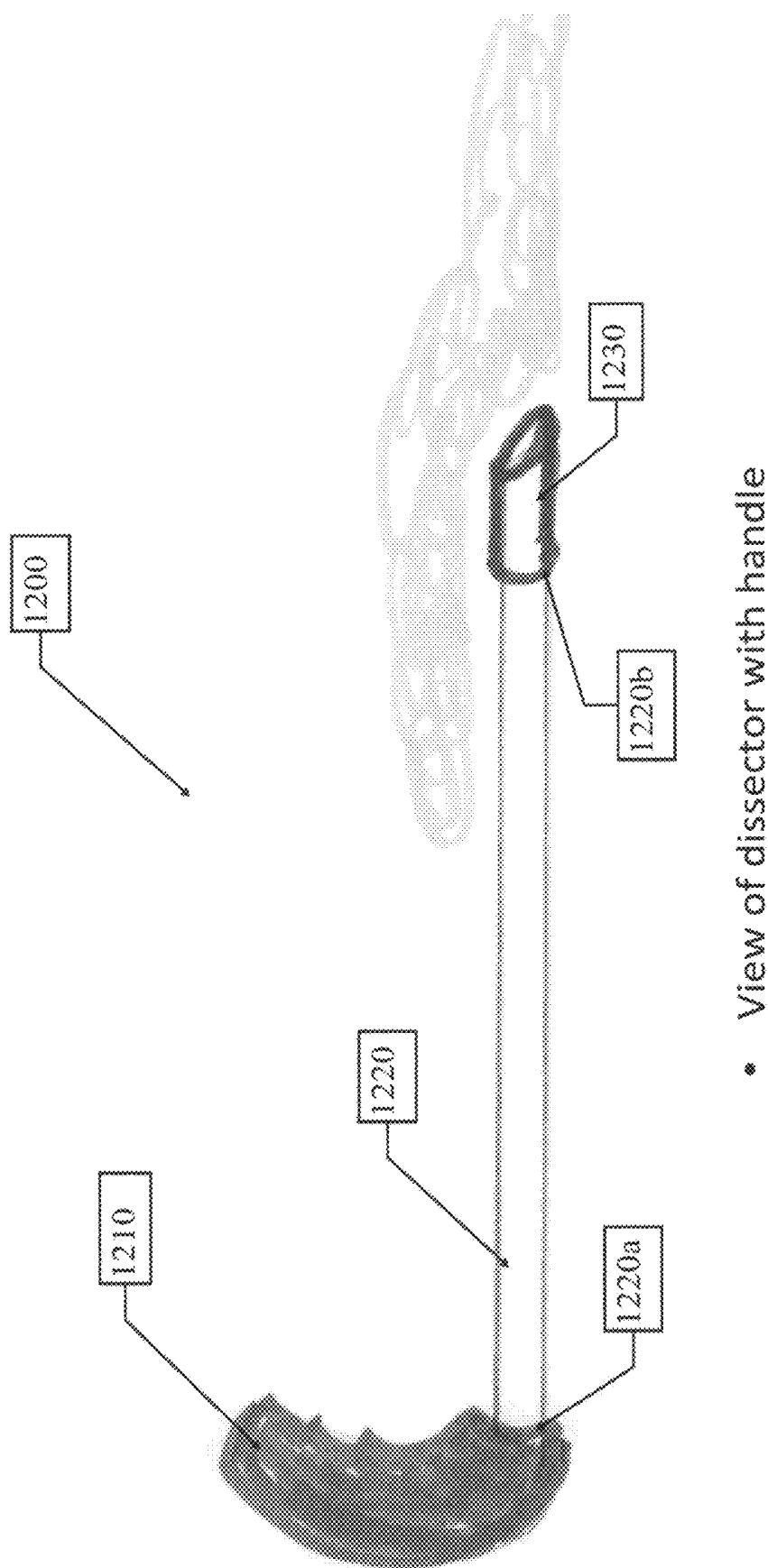
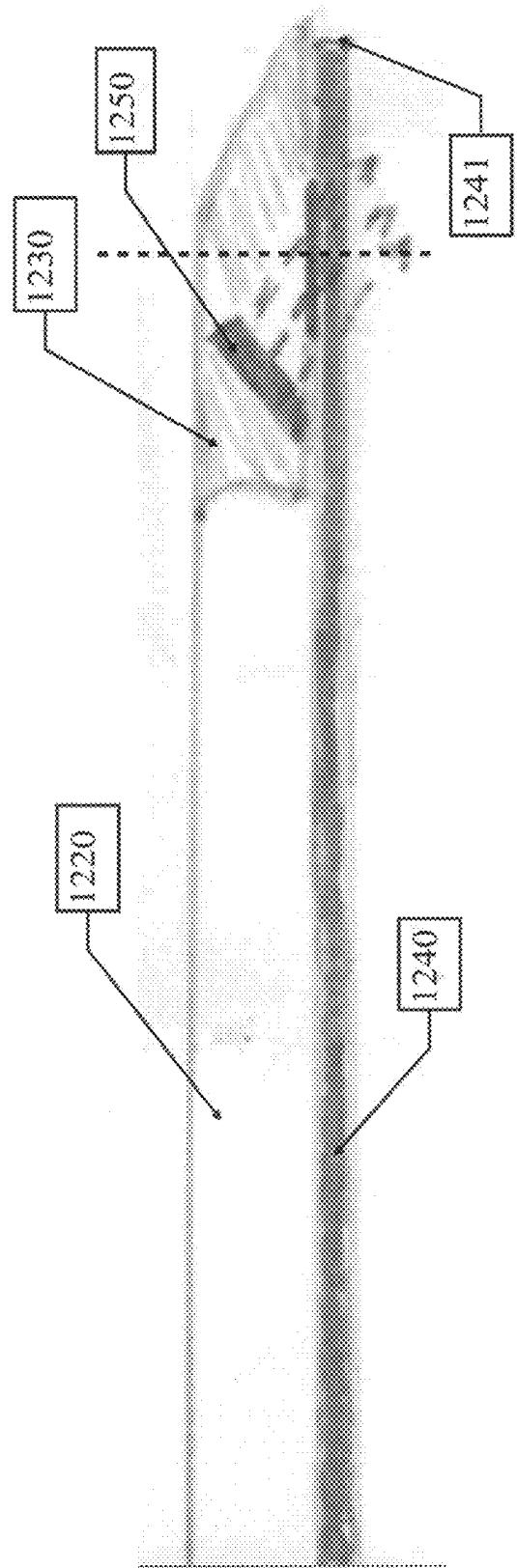


FIG. 14



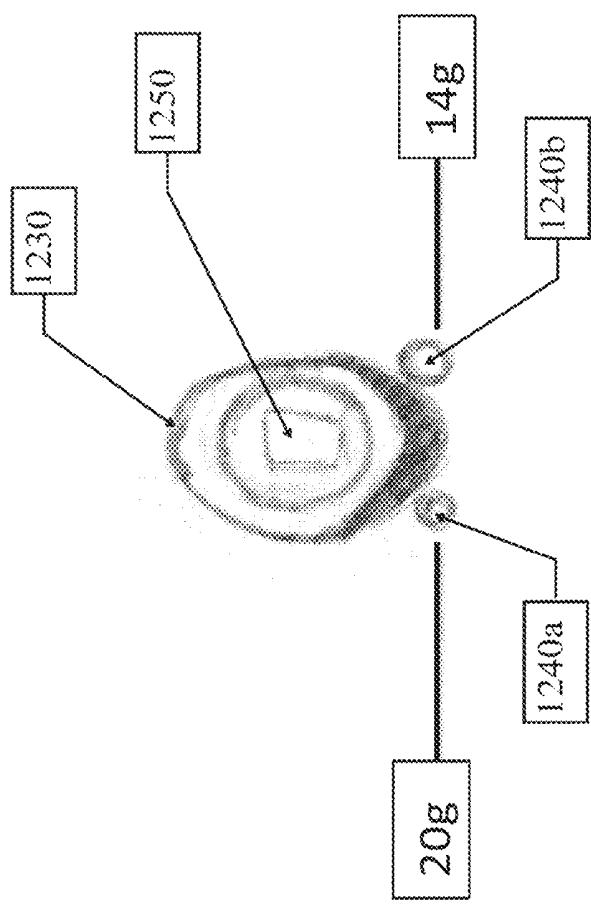
\* View of dissector with handle

**FIG. 15**



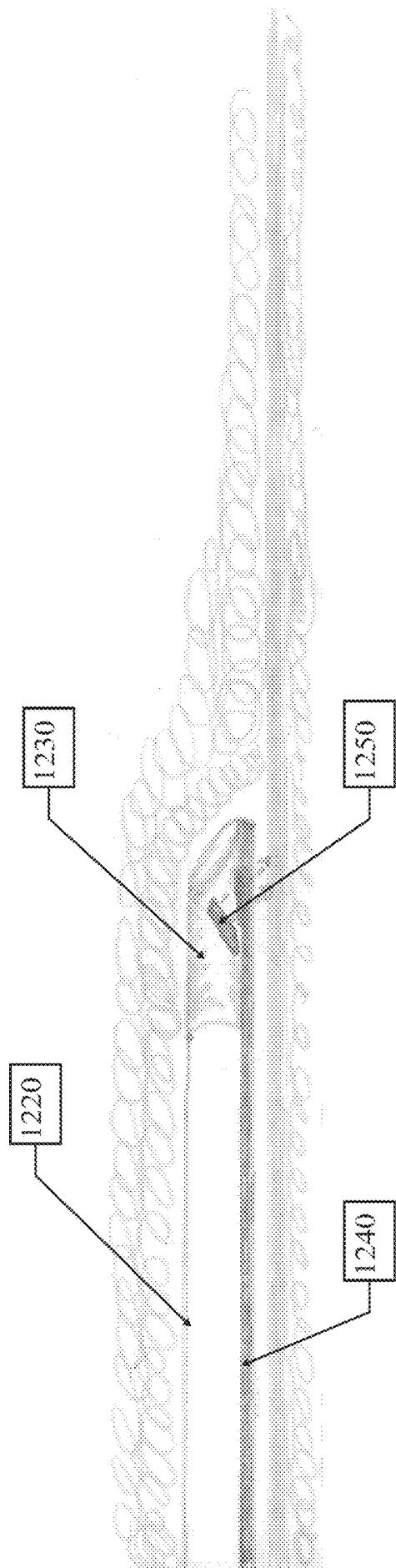
Side view of the dissector showing a camera with 30 degree line of sight to underlying GSV

FIG. 16



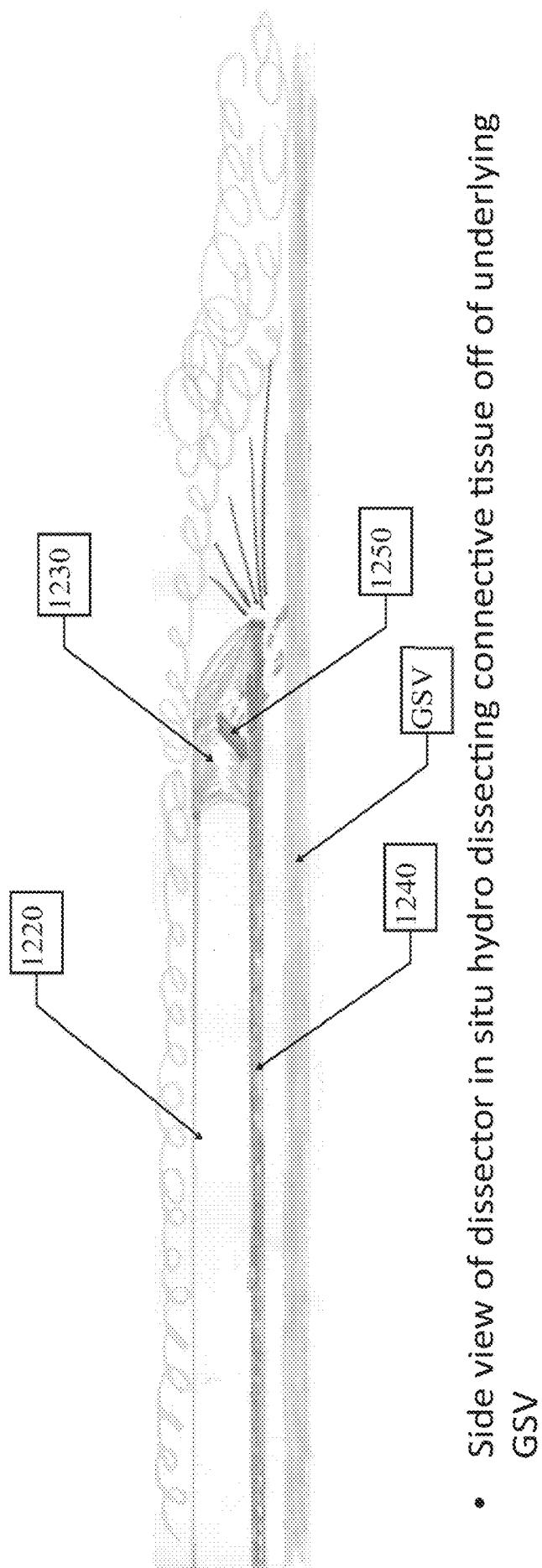
- Head on view of dissector showing smaller 20g port for suction of tumescent fluid and larger 14g port for hydrodissection

FIG. 17



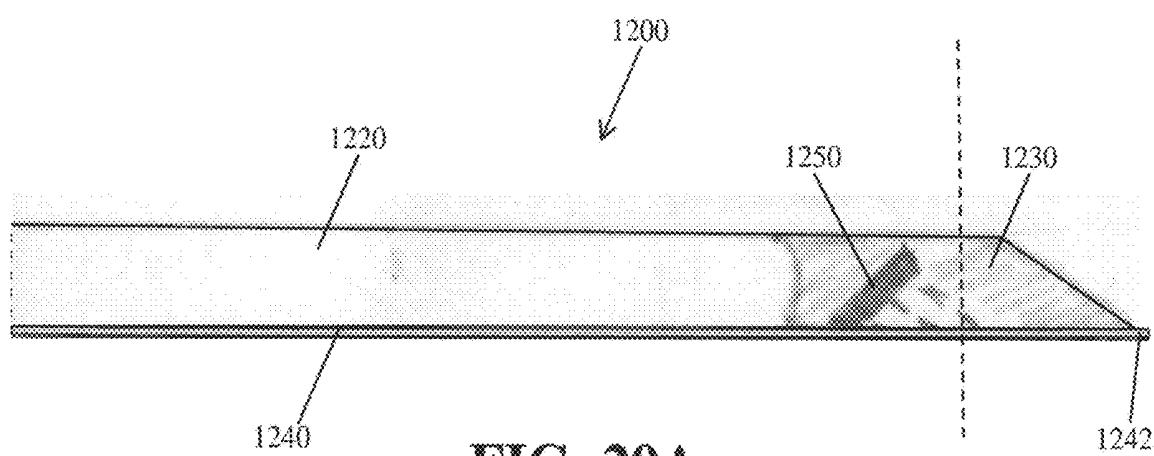
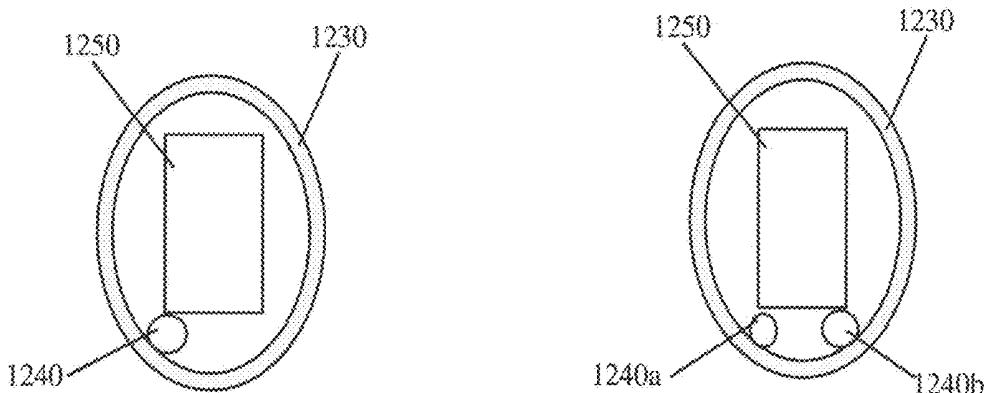
- Same view of dissector in situ, surrounded by connective tissue (represented in yellow) just above GSV (represented in blue)

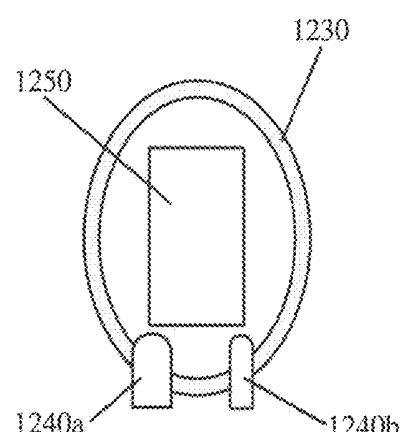
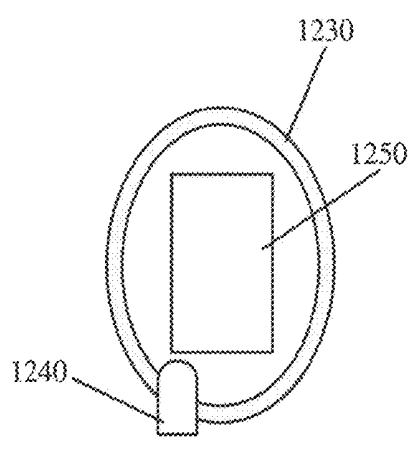
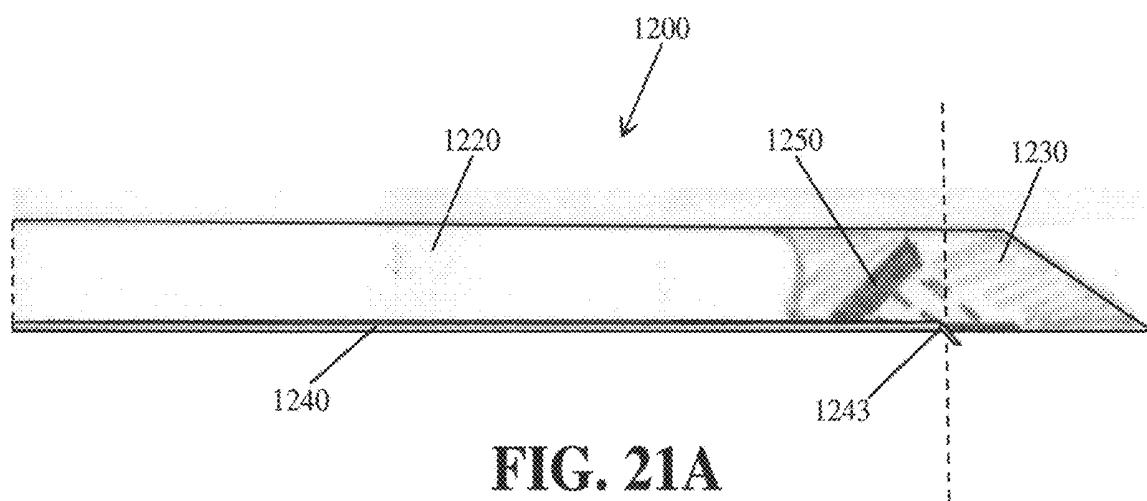
FIG. 18



• Side view of dissector in situ hydro dissecting connective tissue off of underlying  
GSV

FIG. 19

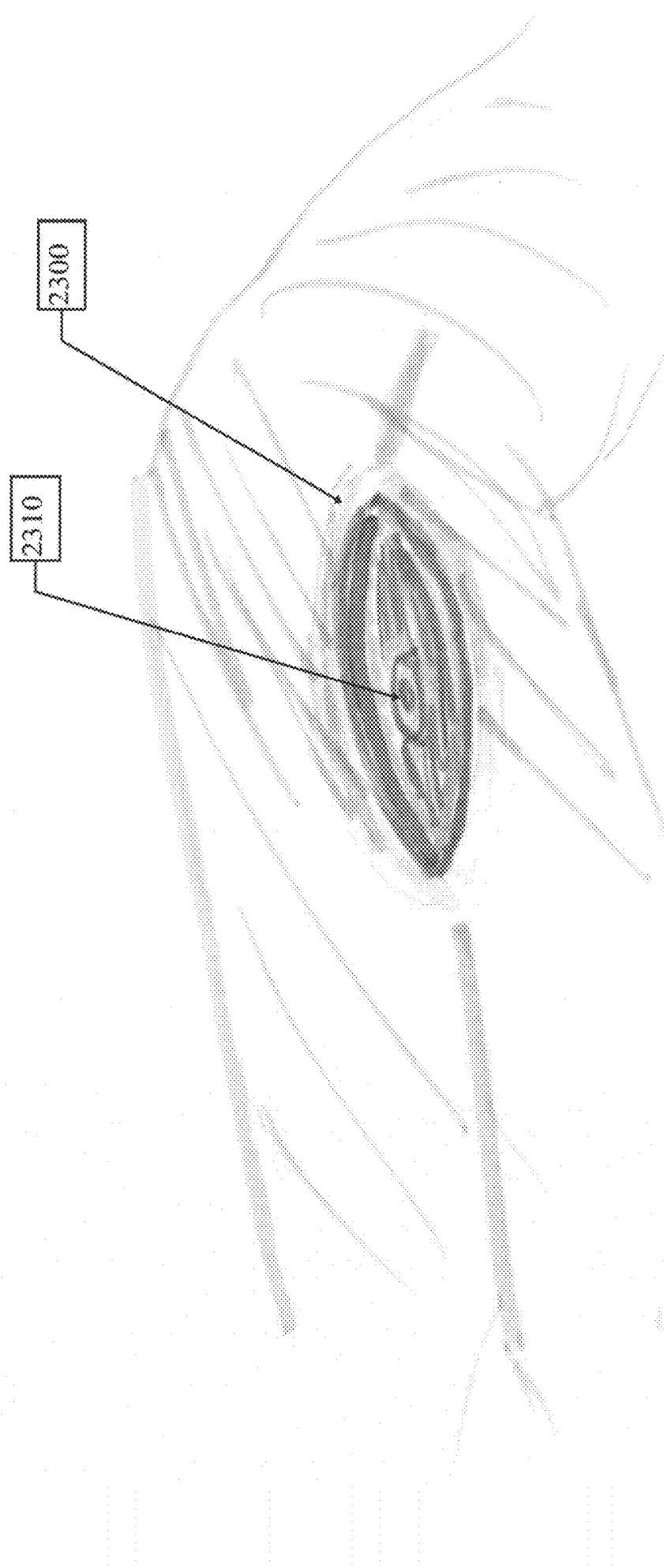
**FIG. 20A****FIG. 20B****FIG. 20C**





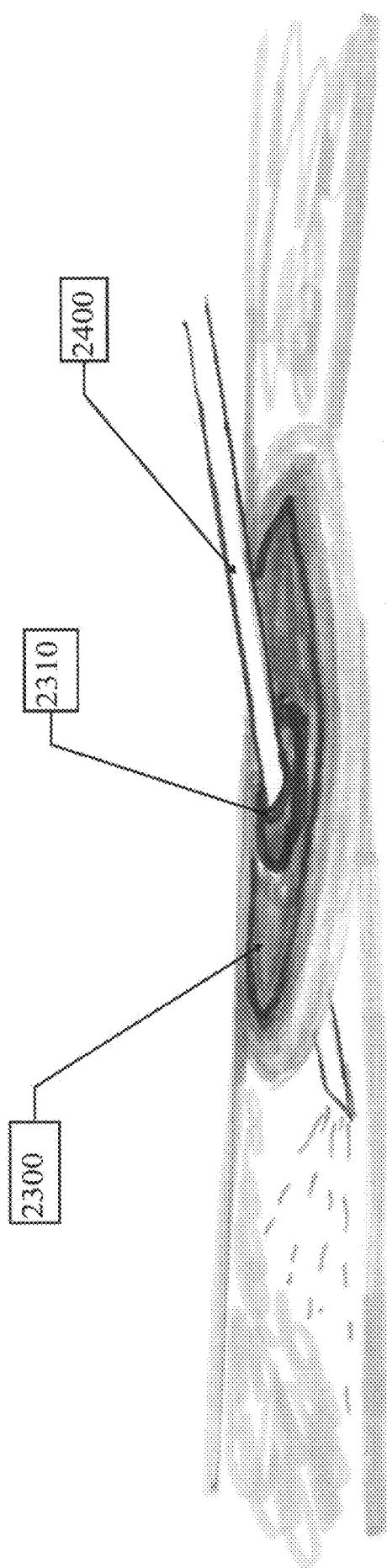
**3 cm incision at knee**

**FIG. 22**



Diaphragm with access port covering incision

**FIG. 23**



OBP Smart Dissector placed through access port

**FIG. 24**

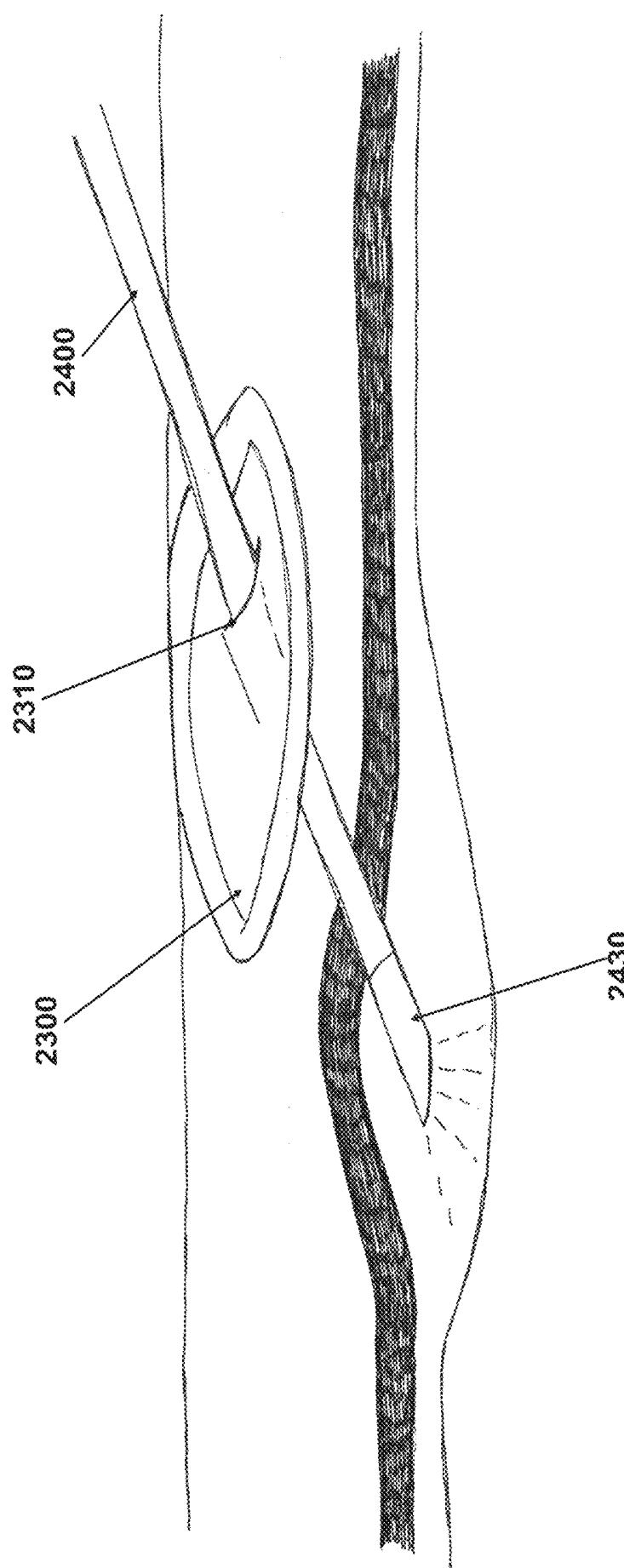
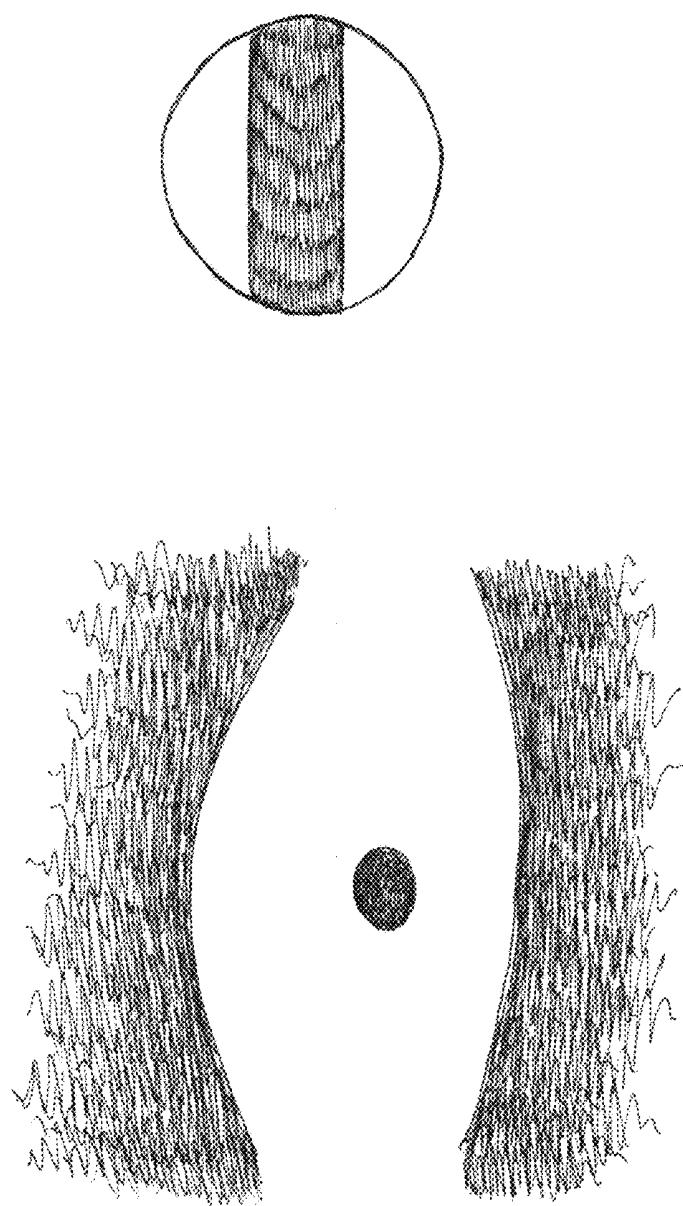


FIG. 25

**FIG. 26**

Terason monitor with split screen



LEFT:  
Ultrasound view of hydrodissection

RIGHT:  
GSV under direct vision via OBP  
Smart Dissector

**MINIMALLY INVASIVE NO TOUCH (MINT)  
PROCEDURE FOR HARVESTING THE  
GREAT SAPHENOUS VEIN (GSV) AND  
VENOUS HYDRODISSECTOR AND  
RETRACTOR FOR USE DURING THE MINT  
PROCEDURE**

**INTRODUCTION**

There are currently two vascular epidemics present in the population of the United States. Atherosclerosis directly leads to coronary artery disease (CAD), which is the leading cause of death in the United States today. Coronary artery bypass grafting (CABG) may be described simply as a procedure for bypassing severely damaged or non-functional coronary arteries using a grafted portion of a healthy vein or artery harvested from the patient under treatment, such as the great saphenous vein (GSV), explained in greater detail below. Atherosclerosis also is the cause of peripheral arterial disease (PAD), which leads to significant disability, increased amputation rates, and death. A second epidemic which is present in the United States is a very high incidence of significant varicose veins.

**SUMMARY OF THE INVENTION**

This patent application discloses an improvement over the known endoscopic vein harvest (EVH) methods presently used to harvest the GSV for use in CABG procedures in a way that increases long term patency of the grafted portions as well as an improvement in the treatment of varicose veins that preserves the GSV in the body of the patient under treatment so that it will be available in an optimized state for harvesting in the future, if required.

In certain embodiments of the invention, a minimally invasive method for dissecting a greater saphenous vein (GSV) from surrounding tissues is provided. The method comprises inserting one of a needle and a hydrodissector into a patient's body so that a tip of the one of the needle and the hydrodissector is placed in a predetermined position adjacent to the GSV to be dissected from surrounding tissues, and injecting fluid at a substantially constant volumetric flow rate from the one of the needle and the hydrodissector while moving the one of the needle and the hydrodissector along a predetermined length of the GSV to cause dissection of the GSV from the surrounding tissues, wherein hydrodissected GSV is suitable for subsequent harvesting for use in surgical bypass procedures. In certain embodiments, the predetermined position adjacent the GSV is 1-2 mm away from an upper surface of the GSV closest to the patient's skin or 1-2 mm away from a lower surface of the GSV furthest from the patient's skin.

In certain embodiments, the fluid injected in the injecting step comprises tumescent fluid including one or more of: isotonic sodium bicarbonate solution, Balanced Salt Solution with a pH of 7.4, isotonic saline solution, Plasma Lyte A solution, and an endothelial damage inhibitor solution comprising glutathione, ascorbic acid and L-arginine. In certain embodiments, the tumescent fluid further comprises one or more medications including one or more of: aspirin, low-molecular weight heparin, one or more vasodilators, nitroglycerine, Endothelin A receptor antagonist, folic acid, angiotensin II receptor antagonist, Spermine/NO, Losartan, Perillyl alcohol, Superoxide dismutase, Antitissue factor antibody, Verapamil, Ursolic acid, Rapamycin, Azathioprin, Paclitaxel, C-type natriuretic peptide, Leoligin, Papaverine,

platelet rich plasma and stem cells. In some embodiments, these medications may be applied to the GSV after performing the hydrodissection.

In some embodiments, the GSV is hydrodissected from the surrounding tissues using one or more needles, and the inserting and injection steps are successively performed for each of a plurality of portions of a length of the GSV to cause dissection the respective portion of the length of the GSV from the surrounding tissues. In some embodiments, a plurality of needles are used, and each respective portion of the length of the GSV is hydrodissected from the surrounding tissues using a respective one of the plurality of needles.

In certain embodiments, the steps of inserting and injecting are performed under one or more of: (1) ultrasound guidance for visualizing the one of the needle and the hydrodissector and (2) direct vision of the one of the needle and the hydrodissector using an image capturing device provided on or in proximity with the one of the needle and the hydrodissector. The ultrasound guidance for visualizing one of the needle and hydrodissector may be performed using a portable ultrasound device. When direct vision is used, the direct vision may be obtained by capturing live images using the image capturing device provided at the tip of the hydrodissector.

In certain embodiments, the minimally invasive method further comprises, before performing the inserting and injecting steps, making an incision in a patient's extremity; and positioning a barrier with an access port through the incision so as to cover and seal the incision, wherein the inserting step comprises inserting the one of the needle and the hydrodissector through the access port into the predetermined position adjacent the GSV to be dissected from the surrounding tissues. In some embodiments, the barrier is formed from fluid-tight material and comprises one of a diaphragm and a tissue occluder, and the access port comprises a fluid-tight one way valve.

The present invention is also directed to a surgical bypass method that includes the above minimally invasive method, and further includes harvesting the hydrodissected GSV by exposing the hydrodissected GSV, dividing side branches of the hydrodissected GSV and dividing proximal and distal ends of the hydrodissected GSV, and using harvested GSV for bypass surgery. In some embodiments, the harvesting step further comprises lifting the hydrodissected GSV after exposing the hydrodissected GSV and prior to dividing the side branches.

The present invention is also directed to an ambulatory selective varicose vein ablation method comprising the above minimally invasive method and further including exposing the hydrodissected GSV; and ligating incompetent perforator and varicosed vein side branches. The ambulatory selective varicose vein ablation method may further include applying drug eluting stents to the hydrodissected GSV and ligated vein side branches for delivering one or more of drug therapy, stem cell therapy and gene therapy to the GSV.

The present invention is further directed to harvesters and hydrodissectors used for the above methods. In some embodiments, the invention provides a harvester for harvesting a vein, the harvester comprising a handle, a blade extending at an angle from the handle, and one or more hook-shaped attachments configured to couple with the blade so as to protrude from a surface of the blade, the one or more hook-shaped attachments being configured for lifting of a vein during a vein harvesting procedure. The hook-shaped attachment may be a C-shaped attachment or a U-shaped attachment, and may be detachable from the blade. In certain embodiments, the blade includes a plurality

of coupling mechanisms along a length of the blade, each of the coupling mechanisms being configured to selectively couple with one of the hook-shaped attachments. In some embodiments, the blade has a first surface facing away from the handle and an opposing second surface, and the one or more hook-shaped attachments are configured to couple to the first surface of the blade. In other embodiments, the blade comprises a tubular shaft and a spoon-shaped tip at a distal end of the tubular shaft and the one or more hook-shaped attachments are configured to couple to one or more of the tubular shaft and the spoon-shaped tip.

The harvester of the present invention may also include one or more ports provided at the distal end of the tubular shaft, each of the one or more ports is configured to be coupled to one of a fluid supply, a gas supply and a vacuum. In some embodiments, the harvester further includes an image capturing assembly for capturing images of an operating field, with the image capturing assembly including an image capturing device provided at a tip of the blade. The tip of the blade may be spoon-shaped including a concave surface and an opposing convex surface, and the image capturing device may be provided on the concave surface of the spoon-shaped tip.

In another embodiment, the present invention provides a harvester for harvesting a vein, the harvester comprising a handle, a blade extending at an angle from the handle and having a spoon-shaped tip at a distal end of the blade, the spoon-shaped tip including a concave surface and a convex surface, and an image capturing assembly for capturing images of an operating field, the image capturing assembly including an image capturing device provided on the concave surface of the spoon-shaped tip.

In yet another embodiment, the present invention provides a harvesting retractor for harvesting a vein, which includes a handle, a blade extending at an angle from the handle and having a first surface facing away from the handle and an opposing second surface, and a tunnel formed on the first surface of the blade and extending along a portion of the blade configured for accommodating a direct visualization device therein. The harvesting retractor may also include a channel along the first surface of the blade and a channel cover covering the channel, wherein the channel is configured for one or more of: removal of fluids from operating field, removal of debris from the operating field, removal of smoke from the operating field, injecting fluid into the operating field and infusing gas into the operating field, and wherein the channel and the tunnel extend along the first surface of the blade and are parallel to one another.

The present invention also provides a hydrodissector for hydrodissecting a vein, the hydrodissector comprising a handle, a shaft extending from the handle at an angle and including a tip at a distal end thereof, at least one port configured to be coupled to a fluid supply for supplying fluid at a substantially constant pressure, and provided at the distal end of the shaft, and an image capturing assembly configured to provide direct visualization of the vein during hydrodissection. In certain embodiments, the image capturing assembly comprises an image capture device encased by the tip of the shaft. The image capture device includes a lens, an image sensor and/or one or more light sources. The image capturing assembly may also include a power source for powering the image capture device, said power source being provided in one of the tip, the shaft and the handle.

In certain embodiments, the tip of the shaft is transparent and the image capture device is positioned inside the tip so that an optical axis of the image capture device is angled relative to a lengthwise axis of the tip so as to allow direct

viewing of the vein to be hydrodissected. In some embodiments, the tip has a substantially cylindrical shape and an angled end so that a first surface of the tip is longer than an opposing second surface of the tip.

In certain embodiments, the at least one port is external and adjacent to the first surface of the tip, while in other embodiments, the at least one port is provided in the tip and is configured to be coupled the fluid supply via one of the shaft and a conduit extending inside the shaft. The at least one port may include a first port configured to be coupled to a fluid supply and having a size between 14 and 22 gauge, and in some embodiments, a second port may be provided for coupling to a vacuum.

In certain embodiments, the tip is configured to rotate relative to the shaft. In some embodiments, the shaft is configured to rotate relative to the handle. In some embodiments, the tip of the shaft is removable from a body of the shaft and interchangeable with one or more second tips, while in other embodiments the shaft is removable from the handle and interchangeable with one or more second shafts. The second tip may be a spoon-shaped tip configured for retracting tissues and for harvesting the vein, and a second image capturing device may be provided on the spoon-shaped tip. The second shaft may include a second tip, such as a spoon-shaped tip, and may be configured to releasably couple with the handle and to convert the hydrodissector into a harvester for harvesting the vein, and may have a second image capturing device is provided on the second tip.

The above features of the invention as well as the features recited in the claims are interchangeable and may be combined and used in any configuration with one another. Further features and advantages will be apparent to those skilled in the art after reviewing the drawings and detailed description provided herein.

#### BRIEF DESCRIPTION OF THE DRAWINGS

FIGS. 1-A-1B show a process of hydrodissecting the GSV using one needle to hydrodissect multiple sections of the GSV;

FIGS. 2A-2B show another process of hydrodissecting the GSV using one needle to hydrodissect multiple sections of the GSV;

FIGS. 3A-3B show another process of hydrodissecting the GSV using multiple needles to hydrodissect respective sections of the GSV;

FIG. 4 shows another process of hydrodissecting the GSV using a venous hydrodissector;

FIGS. 5A-5C show an exemplary venous hydrodissector for use in the process of FIG. 4;

FIG. 6 shows a retractor for use during harvesting the GSV;

FIG. 7 shows another version of a retractor for use during the harvesting of the GSV;

FIGS. 8A and 8B show a front view of different versions of the retractor of FIG. 7;

FIG. 9A shows a GSV after undergoing an endoscopic ASVAL procedure;

FIG. 9B shows a GSV after undergoing the Endoscopic ASVAL procedure and having bioabsorbable drug eluting stents applied thereto;

FIG. 10 shows an exemplary visualization device that uses a pediatric cystoscope;

FIG. 11 shows a 7F introducer sheath suitable for use with the visualization device of FIG. 10;

FIG. 12 shows the visualization device used with the introducer sheath;

FIG. 13 shows an end portion of the visualization device extending through an end of the introducer sheath and fluid being pumped through the introducer sheath around the visualization device;

FIG. 14 shows a retractor of the present invention used with the visualization device of FIG. 10;

FIG. 15 shows a side view of another exemplary hydrodissector for use with the procedure shown in FIG. 4;

FIG. 16 shows a close-up of the side view of the hydrodissector of FIG. 15 at its distal end;

FIG. 17 shows a cross-sectional view of the hydrodissector's tip, taken along a dashed line in FIG. 16;

FIG. 18 shows an end view of the hydrodissector of FIG. 15 in situ, surrounded by connective tissue above the GSV;

FIG. 19 shows an end view of the hydrodissector of FIG. 15 in situ while dissecting connective tissue off the underlying GSV;

FIGS. 20A-20C show another exemplary version of the hydrodissector for use with the procedure shown in FIG. 4;

FIGS. 21A-21C show another exemplary version of the hydrodissector for use with the procedure shown in FIG. 4;

FIGS. 22-25 show another version of the procedure for hydrodissecting the GSV; and

FIG. 26 shows an exemplary split screen visualization which includes an ultrasound view of hydrodissection and a direct visualization view.

## DETAILED DESCRIPTION

### Minimally Invasive No Touch (Mint) Procedure for CABG and Lower Extremity Bypass

Since its introduction in 1967 by Renee Favalaro, coronary artery bypass surgery (CABG) has saved the lives of millions of patients with coronary artery disease (CAD). As originally described, CABG was performed by harvesting the great saphenous vein (GSV) via a longitudinal incision over the entire length of the GSV, referred to as the open vein (OVH) technique. The OVH technique, however, resulted in a significant incidence of leg wound complications, including bleeding, hematoma, infection, amputation and death. In the mid-1990's, a minimally invasive harvesting technique was developed to reduce leg wound complications called endoscopic vein harvest (EVH). EVH employs the techniques of minimally invasive surgery to harvest the GSV. Specifically, the EVH technique employs a 2 cm incision at the level of the knee. The GSV is exposed through this incision and bluntly dissected from its surrounding connective tissue, including a well-developed laminar ligament which attaches the GSV to the underlying muscular fascia. This laminar ligament has been anatomically well defined and arises from the adventitia of the GSV. While EVH has greatly reduced the incidence of leg wound complications, several recent articles have suggested that the patency rates of the GSV harvested by EVH are inferior to those harvested by the open vein technique (OVH).

Concurrent with the development of EVH, Dr. Domingos R Souza, Department of Cardiovascular and Thoracic Surgery, Örebro University Hospital, Örebro, Sweden, has developed a so called "No Touch" technique for harvesting the GSV. In this technique, the GSV is harvested with a cuff of surrounding tissue so that the GSV itself is never touched during the harvesting procedure. This technique has resulted in five year patency rates of 90% for this vascular conduit, which is equivalent to the results obtained when utilizing the internal thoracic artery (ITA), which is considered to be the gold standard of vascular conduits for CABG. Unfortu-

nately, this technique is technically demanding and results in local leg wound complications as high as 50%. As a result, this technique has not been widely adopted.

Therefore, a need exists for a venous harvesting technique that improves patency rates of the harvested GSVs without wound complications and without requiring extensive training in adopting the technique. The minimally invasive no touch (MINT) procedure of the present invention provides these advantages by effectively improving the patency rates of harvested GSVs without the local leg wound complications associated with the known "No Touch" harvesting technique. The MINT procedure also provides for visualization of the vein during dissection and harvesting, thereby reducing or eliminating a risk of damaging the harvested GSV and making it easy for physicians to acquire the skill of harvesting the GSV.

The MINT procedure utilizes the technique of hydrodissection to facilitate the harvesting of the GSV. It should be noted that the MINT procedure, including the hydrodissection and the harvesting of the GSV, can be readily applied to harvesting the GSV for CABG and for lower extremity bypass procedures.

Hydrodissection is a technique that has been used in microsurgical procedures such as DIEP flaps, robotic prostatectomy and dissection of ITA for CABG. It has been established that hydrodissection facilitates microvascular dissection while not affecting the patency of the microvascular pedicle itself. One difficulty in using hydrodissection for harvesting the GSV is the laminar ligament which attaches the GSV to the underlying muscular fascia and which typically requires a blunt force to divide it. For example, the blunt force necessary to divide this ligament during the EVH procedure likely contributes to endothelial damage to the GSV, which can result in reduced patency rates. In order to minimize or eliminate any endothelial damage done to the GSV, the MINT procedure contemplates performing hydrodissection several hours and preferably, several days, prior to harvesting the GSV at the time of CABG. Doing so allows for recovery of any endothelial damage done at the time of the hydrodissection. However, in those patients with a need for an emergency bypass, hydrodissection can be performed immediately before harvesting and excess fluid remaining after hydrodissection can be milked or suctioned from the tunnel along the GSV before harvesting the GSV.

In greater detail, the inventive improved MINT procedure includes bringing the candidate for CABG surgery to the catheterization lab (or an associated venous treatment facility) several hours and preferably, several days prior to the actual harvesting of the GSV. The candidate is placed with the lower extremity in a frog leg position and then subjected to duplex scanning of the GSV to be hydrodissected and utilized. Ultrasonic equipment may be used for evaluating the GSV and to trace its course using a marker, e.g., Sharpie® marking pen. After confirming that the GSV is of significant caliber and quality to be utilized, the lower extremity is prepped and sterilized with Chlorhexidine prep. Hydrodissection of the GSV is then carried out under sonographic control, such as by ultrasound guidance, using a needle, such as a 20 gauge or 22 gauge echogenic spinal needle and an infusion pump, or using a venous hydrodissector with a blunt tip or a pencil tip and an opening at the end, or a venous hydrodissector as described below and shown in FIGS. 10-13 and 15-21. After the GSV is hydrodissected, the GSV is exposed using a harvester (or retractor) described in more detail herein below, and is harvested

by exposing and dividing side branches of the GSV and by dividing proximal and distal ends of the GSV.

During hydrodissection, needle visualization or venous hydrodissector visualization using ultrasound is used in order to insert the needle into a “sweet spot” in the extremity near the GSV without making contact with the GSV. The “sweet spot” is a predetermined position into which a tip of the needle or hydrodissector is inserted and is preferably about 1-2 mm distance away from the wall of the GSV. In other embodiments, the distance from the GSV may be smaller or greater than 1-2 mm. In certain embodiments, the “sweet spot” is located at or near the upper surface of the GSV, i.e., surface closest to the patient’s skin, i.e., at a 12 o’clock location, while in other embodiments, the “sweet spot” is located to the side of the upper surface of the GSV, i.e., at about 20-90 degrees away from a plane connecting the center of the GSV and the top surface of the GSV in either direction (or between 9 o’clock and 12 o’clock or between 12 o’clock and 3 o’clock), and preferably at an angle of around 30-60 degrees from the plane connecting the center and the top surface of the GSV. Although the “sweet spot” may include other surfaces of the GSV, the top and side surfaces of the vein are the preferred locations because the GSV is held tightly to the fascia by a ligament. Since the GSV is surrounded by the fascia, needle or venous hydrodissector localization and placement of the needle or venous hydrodissector in the “sweet spot” is important so that fluid to be injected flows only into desired areas around the GSV. When multiple hydrodissection passes are performed along the length of the GSV, a second or subsequent hydrodissection pass may be performed with a second “sweet spot” being adjacent to the lower surface of the GSV, i.e., at or around a 6 o’clock location, which is opposite to the upper or top surface of the GSV. Alternatively, the first pass may be performed with the “sweet spot” being adjacent to the lower surface of the GSV and the second or subsequent pass may be performed with the second “sweet spot” being adjacent to the upper surface of the GSV. In certain embodiments, the second “sweet spot” may be to the side of the lower surface of the GSV (between 6 o’clock and 9 o’clock or between 6 o’clock and 3 o’clock).

Fluid used during hydrodissection is tumescent fluid, such as isotonic sodium bicarbonate with or without lidocaine, Balanced Salt Solution with a pH of around 7.4, such as Hank’s Balanced Salt Solution manufactured by Thermo Fisher Scientific Isolyte Solution, or isotonic saline solution and/or any other suitable tumescent fluid solution. In some embodiments, the tumescent fluid is DuraGraft (GALA Solution named after Glutathione, Ascorbic acid, L-Arginine) endothelial damage inhibitor solution manufactured by Somahltion, Inc. based in Jupiter, Fla. DuraGraft is used for tissue preservation in the GSV specifically for CABG, and is a preferred solution for performing the hydrodissection in order to reduce endothelial damage during this procedure. Examples of a GALA solution and a Hank’s Balanced Salt Solution suitable for use as tumescent fluid during hydrodissection are disclosed in U.S. Pat. No. 7,981,596. In certain embodiments, tumescent fluid includes one or more medications for protecting the GSV and assisting in healing of the GSV. These one or more medications include one or more of aspirin, which protects the endothelium, heparin, such as local low-molecular weight heparin, and one or more vasodilators, such as venous vasodilators or combination dilators. Other medications that can be included in the tumescent fluid include but are not limited to one or more of the following: Nitroglycerine, Endothelin A receptor antagonist, Folic Acid, Angiotensin II receptor antagonist. Sper-

mine/NO, Losartan, Perillyl alcohol, Superoxide dismutase, Antitissue factor antibody, Verapamil, Heparin, Ursolic acid, Local Aspirin, Rapamycin, Azathioprin, Paclitaxel, C-type natriuretic peptide, Leoligin and Papaverine. In some embodiments, tumescent fluid may include platelet rich plasma or stem cells for strengthening the wall of the GSV, and in certain embodiments, gene therapy may be used as part of the tumescent fluid.

When used for performing hydrodissection of the GSV, the use of the above-mentioned solutions should greatly reduce the initial learning curve for inexperienced Physicians Assistants, as well as improve the patency of the GSV when grafted. That is, even in experienced hands, this inventive MINT procedure should greatly eliminate the amount of blunt trauma resulting in endothelial dysfunction at the time of harvesting.

In some embodiments, the GSV is hydrodissected completely from the surrounding fascia. Complete hydrodissection may be necessary when the harvesting of the vein is performed immediately or shortly after the hydrodissection. In order to completely hydrodissect the GSV from the surrounding fascia, it may be necessary to perform multiple passes of hydrodissection along the length of the GSV, e.g., two passes of hydrodissection. For example, in a first hydrodissection pass, the needle or the hydrodissector is inserted into the “sweet spot” at or around the upper surface of the GSV (at or around 12 o’clock) and the GSV is hydrodissected by moving the needle or the hydrodissector along the upper surface of the GSV. The first hydrodissection pass will hydrodissect at least the upper half of the GSV (from 9 o’clock to 3 o’clock). In order to ensure that the GSV is completely hydrodissected around the lower half of the GSV, the second hydrodissection pass may be performed by placing the needle or hydrodissector in the second “sweet spot” at or around the lower surface of the GSV (at or around 6 o’clock), which is opposite to the “sweet spot” at the upper surface so that the needle and the dissector is between the GSV and the muscular fascia. The second hydrodissection pass proceeds by moving the needle or the hydrodissector along the lower surface of the GSV until the GSV is lifted off the muscular fascia. As discussed above, the locations of the “sweet spot” and the second “sweet spot” may be reversed or may be provided at different locations relative to the GSV.

However, in other embodiments, the GSV is partially hydrodissected so that all surrounding fascia is dissected from the vein except the laminar ligament, which can be dissected at a later time, under direct vision. In certain embodiments, the partially hydrodissected GSV remains tethered to some of the surrounding tissues. Partial hydrodissection of the GSV may result in less damage to the vein, thus extending the utility of the GSV and reducing its failure rate. Any remaining tissue can be hydrodissected under direct vision with either a spinal needle or venous hydrodissector.

As mentioned above, ultrasound guidance is used for needle or venous hydrodissector localization and during hydrodissection. After the needle or venous hydrodissector is inserted and fluid is injected, the fluid makes a pocket around the GSV and the GSV may move during the hydrodissection. Ultrasound guidance allows the user to see the pocket forming around the vein and to see the tip of the needle or venous hydrodissector to ensure that the needle or venous hydrodissector does not damage the GSV. In some embodiments of the invention, portable ultrasound equipment is used for the ultrasound guidance. For example, Terason® t3200 or t3300 Ultrasound System with Enhanced

Needle Visualization (ENV) may be used for ultrasound guidance and for needle localization during the hydrodissection. The ENV helps the user to insert the needle or venous hydrodissector close to the GSV without coming into contact with the GSV.

When hydrodissection is performed using one or more needles, a needle is inserted into the lower extremity and the needle tip is visualized using ultrasound guidance. In the present illustrative embodiment, the “sweet spot” for hydrodissection using one or more needles is at the top of the GSV and about 1 mm away from the wall of the GSV. However, in other embodiments, the “sweet spot” may be off to the side of the GSV.

Once the needle tip is visualized in the “sweet spot”, fluid is injected at high pressure to hydrodissect the GSV from the surrounding connective tissue. In this illustrative embodiment, a predetermined length of the GSV, e.g., about 10 cm of the GSV, is hydrodissected, after which the needle is removed, inserted at the next section of the GSV to be hydrodissected, the needle tip is visualized under ultrasound guidance, and after the needle tip is visualized in the “sweet spot,” fluid is again injected at high pressure to hydrodissect another predetermined length of the GSV. This process is repeated until the entire length of the GSV is hydrodissected. In hydrodissecting each section of the GSV, the amount of fluid may be determined based on time of performing the hydrodissection, wherein the fluid is pumped at a constant volumetric flow rate (e.g., ml/m or ml/s). In the illustrative embodiment of the invention, about 100 ml of fluid is injected for about every 10 cm of the GSV being hydrodissected. In such embodiments, typically hydrodissection is performed 3 or 4 times along the length of the GSV, injecting between about 300 ml and 400 ml of fluid. Hydrodissection using one or more needles may be performed using one needle, such as an 18 gauge needle, a 20 gauge needle or a 22 gauge needle, e.g. 22 gauge echogenic spinal needle or an introducer needle with a  $\frac{1}{50}$  inch opening, or using multiple needles of similar size, wherein each needle is used for hydrodissecting a separate predetermined length of the GSV. The size of the needle is not limited to 18, 20 or 22 gauge sizes and other sizes may be used as long as sufficient fluid pressure is provided for hydrodissection. For example, the size of the needle may be between 14 gauge and 22 gauge.

The process of hydrodissecting the GSV using one or more needles is illustrated in FIGS. 1A-1B, 2A-2B and 3A-3B. As shown in FIGS. 1A-1B, one needle 104 is used for hydrodissection to hydrodissect four consecutive sections of the GSV 102. In FIGS. 1A-1B, the needle 104 is inserted into each consecutive section of the GSV 102 in accordance with the circled numbers 1-4, from the knee area and up to the groin area. FIG. 1B illustrates insertion of the needle 104 into the “sweet spot” adjacent to the GSV 102 prior to injecting the fluid to dissect the GSV from surrounding connective tissue. In FIGS. 2A-2B, the order of insertion of the needle 104 into each consecutive section of the GSV 102 is opposite of FIG. 1A, starting from the groin area to the knee area. The insertion of the needle 104 into the “sweet spot” adjacent the GSV 102 in FIG. 2B is similar to that of FIG. 1B. In FIGS. 3A-3B, four needles are used for hydrodissection of four consecutive sections of the GSV 102. As shown in FIG. 3A, all four needles 104 are inserted into the “sweet spot” as shown in FIG. 3B, after which the fluid is injected through each needle to hydrodissect the corresponding section of the GSV from the surrounding connective tissue. Although FIGS. 1A-3B show hydrodissection being performed on the GSV between the knee area and the groin area, it is understood that the same hydrodissection proce-

dure may also be performed between the knee area and the ankle of the lower extremity, and may be performed along the entire length of the GSV. It is also understood that the number of sections of the GSV is not limited to 3 or 4 and may be greater depending on the length of the GSV being hydrodissected. Moreover, as described above, multiple hydrodissection passes may be made where needed in order to achieve sufficient dissection of the GSV.

Alternatively, hydrodissection may be performed by passing a narrow pencil-tip or a blunt-tipped venous hydrodissector under ultrasound guidance in the “sweet spot” through a small incision in the lower extremity and by pumping fluid, e.g., tumescent fluid, at high pressure through an opening at the tip of the venous hydrodissector to hydrodissect the GSV from surrounding connective tissues. In certain embodiments, the incision for inserting the venous hydrodissector is formed around the knee area. In this way, the hydrodissection procedure requires only one incision for hydrodissecting the entire length of the GSV, including a portion between the knee area and the groin area and a portion between the knee area and the ankle area. In some embodiments, the “sweet spot” for inserting the venous hydrodissector is about 1 mm away from the GSV wall and at a location off to the side of the GSV, such as about 20-90 degrees in either direction from a plane connecting the top surface of the GSV and the center of the GSV. This way, the venous hydrodissector is introduced along the side of the vein transversely, reducing possibility of damage to the GSV.

In some embodiments, the venous hydrodissector is introduced into the incision and after the venous hydrodissector tip is visualized in the “sweet spot,” fluid is injected at high pressure through the opening in the venous hydrodissector to hydrodissect the GSV from the surrounding connective tissue. During hydrodissection, the venous hydrodissector is slid up along the GSV while injecting the fluid until the venous hydrodissector is fully inserted into the lower extremity along the GSV. After performing hydrodissection on one of the portions of the GSV, i.e., either the portion between the knee and the groin area or the portion between the knee and the ankle, the venous hydrodissector is removed and the same hydrodissection process may be performed on the other portion of the GSV through the same incision until the whole length of the GSV has been hydrodissected. In other embodiments, the venous hydrodissector may be introduced into the incision and fully inserted along the GSV to the other end of the GSV before visualizing the venous hydrodissector tip in the “sweet spot” and thereafter injecting fluid. In such embodiments, after the fluid is injected, the GSV is hydrodissected by pulling the venous hydrodissector back along the GSV. Similarly, both portions of the GSV may be hydrodissected through the same incision made in the knee area. As in the hydrodissection using one or more needles, the amount of fluid may be determined based on the amount of time of performing the hydrodissection, wherein the fluid is pumped at a constant volumetric flow rate (e.g., ml/m or ml/s). In the illustrative embodiment of the invention, about 100 ml of fluid is injected for about every 10 cm of the GSV being hydrodissected, with around 300-400 ml of fluid injected for each portion of the GSV that is hydrodissected.

The process of hydrodissecting the GSV using a venous hydrodissector is illustrated in FIG. 4. As shown, a blunt tipped venous hydrodissector 204 is used for hydrodissection to hydrodissect the one of two sections of the GSV 202. The venous hydrodissector 204 is inserted into a small incision, which is preferably formed in the knee area, and

slid along the GSV 202 before placing the tip of the venous hydrodissector in the “sweet spot” and pumping tumescent fluid to hydrodissect the GSV from the surrounding tissue. In this case, the venous hydrodissector 204 is slowly pulled out through the incision while hydrodissecting the GSV. Alternatively, the venous hydrodissector 204 may be inserted into the incision and once the venous hydrodissector 204 tip is visualized in the “sweet spot”, the fluid is pumped to hydrodissect the GSV while sliding the venous hydrodissector 204 further along the GSV. Although FIG. 4 shows the venous hydrodissector being inserted at the top of the GSV, in other embodiments, the venous hydrodissector is inserted along the side of the GSV, at an angle between 20 and 90 degrees from the plane connecting the center and the top of the GSV. As described above, multiple hydrodissection passes may be made where needed in order to achieve sufficient dissection of the GSV, and in a second hydrodissection pass, the hydrodissector is visualized in the second “sweet spot” which is on the opposite side of the GSV from the “sweet spot” during the first hydrodissection pass (e.g., around 180 degrees relative to the “sweet spot” during the first hydrodissection pass).

An example of a pencil tip venous hydrodissector suitable for hydrodissecting the GSV is shown in FIGS. 5A-5B. The venous hydrodissector may be disposable or may be reusable. The venous hydrodissector 204 has an elongated hollow substantially cylindrical body 206 and a pencil tip with a small opening 206a therein. The length of the venous hydrodissector body 206 can be between 10 and 30 cm long, and preferably between 15-25 cm long. The body of the venous hydrodissector may be made from metallic materials, such as stainless steel or titanium, or from polymers and/or plastics with sufficient strength. The venous hydrodissector 206 also includes a port 208 at the other end to which an infusion pump for pumping the fluid can be connected. The port 208 can be a standard port, e.g., a Luer Lock port, to which any standard infusion pump may be coupled, or can be any other type of port. FIG. 5B shows a close-up of the tip of the venous hydrodissector, showing a small opening 206a formed at the tip. The opening 206a should be small enough to create sufficient pressure when the fluid is pumped therethrough. For example an opening sized between about 0.01 and 0.1 inches in diameter is suitable, and preferably between 0.01625 and 0.06 inches in diameter (14-22 gauge in size). In one illustrative embodiment, the opening 206a is about 0.02 inches to about 0.04 inches in diameter. In another illustrative embodiment, the opening is between 0.01625 and 0.024 inches in diameter. FIG. 5C shows a close-up view of another venous hydrodissector tip which has a cone-shaped blunt tip. Like in FIG. 5B, the venous hydrodissector tip in FIG. 5C includes a small opening formed at the tip which is sized to create sufficient fluid pressure when fluid is pumped therethrough.

In certain embodiments, a venous hydrodissector with a wider body and a larger opening at tip may be used in combination with a needle. In such embodiments, the needle is inserted into the venous hydrodissector so that the tip of the needle is covered by the tip of the venous hydrodissector. The needle may be 14 gauge to 22 gauge in size, similar to the needle size used for the hydrodissection with a needle or a different size (gauge) needle. The infusion pump is connected to the needle and pumps the fluid through the needle and out of the tip of the venous hydrodissector. This arrangement provides for sufficient fluid pressure to hydrodissect the GSV from the surrounding tissue while protecting the GSV from inadvertent damage by using the venous hydrodissector near the wall of the GSV.

The inventive hydrodissection techniques are optimized by use of the above-described venous hydrodissector. The venous hydrodissector is configured with a pencil tip shaped or a cone-shaped tip and only one outflow port in the center of the tip in order to ensure that the hydrodissection implemented by use of the venous hydrodissector occurs in parallel to the GSV.

Using the above-described venous hydrodissector minimizes force vectors that might result off-angle from the axial center of the linear extent of the GSV, for example, at 90° or less which is likely in conventional or standard infusion cannulas, which are known to have one or more outflow ports arranged in the cannula shaft, which create fluid paths substantially perpendicular to the cannula longitudinal axis. Fluid typically exits from these conventional ports creating force vectors perpendicular or slightly less than perpendicular to the longitudinal axis. The venous hydrodissector, therefore, reduces trauma that the hydrodissection procedure might impose on or to the GSV.

Although the hydrodissection procedure described above is performed under ultrasound guidance, it is also possible to perform the above-described hydrodissection of the GSV under direct vision instead of using ultrasound guidance. Direct vision of the hydrodissection procedure can be achieved by using a visualization device comprising a thin tube with a camera and a light source provided at one end and capable of connecting to a display panel (e.g., a tablet, a TV, a monitor, etc.) either using a wire or wirelessly. In certain embodiments, the diameter of the tube is about 2 mm or smaller. In some embodiments, a port for infusion of liquid may be included in the visualization device, which is used as a hydrodissector, while in other embodiments, no such port is included in order to reduce the diameter of the tube. In certain embodiments, a pediatric cystoscope, an angioscope or an endoscope may be used as the visualization device. It is desired for the visualization device to be capable of capturing and transmitting clear images when exposed to liquids. An example of a suitable visualization device, which is a pediatric cystoscope, is shown in FIG. 10, or a hydrodissector shown in FIGS. 15-19. An example of a suitable angioscope is an Olympus 2 mm angioscope. In this way, the MINT procedure can be performed utilizing currently available urologic or vascular equipment.

In the embodiments that use direct vision when performing hydrodissection, the patient is first prepped and draped in the usual fashion with the donor lower extremity in the frog leg position. First, about 30 ml of tumescent fluid is injected inside the fascial envelope. In some embodiments, the tumescent fluid is injected just above the GSV, i.e., at 12 o’clock position, while in other embodiments, the tumescent fluid may be injected to the side of the GSV. This injection of the tumescent fluid can be performed either percutaneously with ultrasound guidance, such as by using a portable ultrasound device, or under direct vision via a small incision, e.g., about 2 cm incision, that exposes the GSV. If a percutaneous injection is performed, the GSV is then exposed via a small incision, e.g., standard 2-3 cm incision, just below the tumescent fluid collection.

Using a syringe with a needle, such as a 10 mL syringe with a 21 gauge spinal needle, the fluid collection is entered while keeping the needle and syringe parallel to and just above the exposed GSV. After the fluid is aspirated, a guide wire is passed into the fluid space and an introducer sheath, such as a 7F introducer sheath, is placed into the fluid space. FIG. 11 shows a 7F introducer sheath suitable for use in this procedure. As shown, the introducer sheath includes a side

port which can be used for pumping fluid through the introducer sheath, as described in more detail below.

After the introducer sheath is placed, the visualization device, such as a 2 mm pediatric cystoscope shown in FIG. 10 or a 2 mm angioscope, is passed into the fluid space via the introducer sheath. FIG. 12 shows a 2 mm cystoscope inserted into the 7F introducer sheath and demonstrates the positioning of the cystoscope relative to the 7F introducer sheath. When the visualization device, e.g., cystoscope or angioscope, is connected to a display device, either by a wire or wirelessly, the GSV is visualized directly on the monitor using the visualization device, e.g., cystoscope or angioscope. This technique allows the hydrodissection of the GSV to be performed under direct vision in real time. After the introducer sheath and the visualization device, e.g., cystoscope or angioscope, are positioned, hydrodissection can be performed using one of the following techniques.

In a first technique, the side port of the introducer sheath is attached to an infusion pump and fluid is infused via the introducer sheath at a sufficiently high rate to hydrodissect the GSV. Hydrodissection is performed by moving the assembly of the visualization device with the introducer sheath, while pumping fluid along the length of the GSV or a portion of the GSV. FIG. 13 shows an end portion of the visualization device extending through an end of the introducer sheath, and fluid being pumped through the introducer sheath around the visualization device. The visualization device allows the hydrodissection to be performed under direct vision in real time and eliminates the need for ultrasound guidance.

In one example, a 7F introducer sheath like the one shown in FIG. 11 and a 2 mm cystoscope as shown in FIG. 10 or a 2 mm angioscope are used for performing hydrodissection of the GSV. The size match of the 7F introducer and the 2 mm cystoscope/angioscope diameter allows just enough room for the fluid to travel in the sheath and around the cystoscope/angioscope and to exit the sheath as a jet of fluid with sufficient pressure to hydrodissect the GSV. In addition, there is no back up or leaking of fluid. In this technique, the hydrodissection of the GSV is performed using a single assembly of the visualization device with the introducer sheath, with the assembly being advanced together as a unit along the GSV. In certain embodiments, the hydrodissection is performed by advancing the cystoscope/angioscope and introducer sheath assembly proximally toward the groin. However, in other embodiments, the direction in which the hydrodissection is performed may be changed.

In a second technique of performing hydrodissection, the hydrodissection of the GSV is performed using a needle or the venous hydrodissector, as described above, with the fluid being pumped through the needle or the venous hydrodissector, and using the visualization device with the introducer sheath for direct visualization of the GSV and of the needle or the venous hydrodissector. The configuration of the needle or venous hydrodissector used in this variation of the hydrodissection procedure is the same as described above. For example, the hydrodissection may be performed percutaneously using a needle, such as a 22 gauge spinal needle, under direct vision using the visualization device with the introducer sheath. This hydrodissection technique is similar to the hydrodissection technique described above using one or more needles or using the venous hydrodissector, but instead of ultrasound guidance, this procedure is performed under direct vision.

In a third technique, a needle or a venous hydrodissector is attached to the visualization device lengthwise, so that the visualization device and the needle or the venous hydrodis-

sector extend side by side within the introducer sheath. The configuration of the needle or venous hydrodissector used in this variation of the hydrodissection procedure is the same as described above. The needle or the venous hydrodissector is attached to an infusion pump so as to pump fluid therethrough. For example, a 20 or 22 gauge blunt tipped spinal needle can be attached lengthwise to a 2 mm cystoscope. The hydrodissection of the GSV in this technique is performed by advancing the visualization device with the attached needle or venous hydrodissector along the GSV as the fluid is being pumped, while leaving the introducer sheath in place. As in the first and second techniques, the hydrodissection of the GSV is performed under direct vision via the venous hydrodissector in real time.

Other types of hydrodissectors 1200 (or dissectors) that can be used for hydrodissection of the GSV are shown in FIGS. 15-21. The hydrodissectors of FIGS. 15-21 provide direct visualization of the GSV during hydrodissection by capturing and transmitting live images of the GSV and surrounding areas during the procedure.

FIG. 15 shows a general side view of the hydrodissector 1200 with a handle 1210. As shown, the hydrodissector 1200 includes an elongated tubular-shaped body 1220 having a proximal end 1220a to which the handle 1210 is coupled and a distal end 1220b to which an angled tip 1230 is coupled. The angled tip 1230 is preferably formed from plastic, polymer material, glass, acrylic glass, e.g., poly(methylmethacrylate), Plexiglass, etc., or other suitable materials, and is transparent or translucent. The body 1220 can be formed from a metallic material, e.g., stainless steel, aluminum, titanium, etc., or from a suitable plastic or polymer material. Similarly, the handle 1210 can be formed from plastic or polymer material or may be formed from metal or any other suitable material.

The angled tip 1230 has a substantially cylindrical shape and has an angled end so that a lower surface (first surface) of the tip 1230 is longer than an upper surface (second surface) of the tip 1230. The angled end of the tip 1230 is preferably sealed or closed so as to prevent fluids and debris from entering the angled tip 1230 through the angled end. However, in other embodiments, the angled end of the tip 1230 may be partially sealed/closed or may be open. In the illustrative embodiment shown in FIGS. 15-19, the lower surface of the tip 1230 would be positioned closer to the GSV than the upper surface during the hydrodissection procedure.

In order to allow the lower surface of the angled tip 1230 (longer surface of the angled tip) to be positioned closer to the GSV than the opposing upper surface during the hydrodissection procedure, the orientation of the angled tip 1230 relative to the orientation of the handle 1210 may be adjustable. In certain embodiments, the handle 1210 can be rotated around the tubular-shaped body 1220 and can be locked in one or more orientations, or the tubular-shaped body 1220 can be rotated relative to the handle 1210. The locking orientations of the handle 1210 may be flexible to allow an operator to select any suitable orientation, or the locking orientations of the handle 1210 may be predetermined so as to limit the number of orientations of the handle 1210 relative to the tubular-shaped body 1220. For example, in the hydrodissector of FIG. 15, one locking orientation may be as shown in FIG. 15 where the handle is oriented in the same direction as the upper surface of the angled tip 1230, and another locking orientation may be 180 degrees around the tubular-shaped body so that the handle 1210 is oriented in the same direction as the lower surface of the angled tip 1230. Additional locking orientations may be

provided in the hydrodissector. In certain embodiments, the angled tip 1230 may be rotated relative to the tubular-shaped body 1220 and may be locked in one or more orientations, which may be predetermined or may be flexible so as to be selectable by the operator. Rotating the handle 1210 and/or the angled tip 1230 around the tubular-shaped body 1220 allows the hydrodissector 1200 to be used to hydrodissect the GSV along the upper surface of the GSV, i.e., along the surface closest to the patient's skin, and to hydrodissect the GSV along the lower surface of the GSV, i.e., along the surface adjacent the muscular fascia.

FIG. 16 shows a close-up of the side view of the hydrodissector 1200 at its distal end and FIG. 17 shows a cross-sectional view of the hydrodissector's angled tip 1230 taken along a dashed line in FIG. 16. As shown in FIGS. 16 and 17, the hydrodissector 1200 includes at least one fluid port 1240 for injecting fluid therethrough to hydrodissect the GSV as described above. The at least one fluid port 1240 includes a conduit that extends along the tubular-shaped body 1220 and is coupled to a fluid supply at a proximal end thereof (not shown) and has an injection opening 1241 at a distal end thereof. The proximal end of the conduit of the fluid port 1240 may have a Luer Lock fitting or any other suitable fitting at its end to allow the fluid port 1240 to be connected to the fluid supply, e.g., tumescent fluid supply, gas supply, e.g., CO<sub>2</sub> supply, and/or vacuum source. The injection opening 1241 is preferably located at or near the angled end of the angled tip 1230.

In some embodiments, as shown in FIG. 17, the hydrodissector 1200 includes two fluid ports 1240a, 1240b including conduits that extend substantially parallel to one another along the tubular-shaped body 1220. The conduit of each port may have a Luer Lock fitting or any other suitable fitting at its proximal end for connection to fluid supply, gas supply and/or vacuum source. The fluid ports 1240a, 1240b may have the same size or may have different sizes from one another, and the sizes of the ports may vary between 14 and 22 gauge. In the illustrative embodiment shown in FIG. 17, the fluid port 1240a is smaller than the fluid port 1240b, with the fluid port 1240a having a 20 gauge size opening and the fluid port 1240b having a 14 gauge size opening. In this illustrative embodiment, the fluid port 1240a is used for injecting tumescent fluid for hydrodissecting the GSV, as described above, and the fluid port 1240b is used for suction of tumescent fluid after hydrodissection of the GSV. However, in other embodiments, the smaller sized port may be used for suction of fluid while the larger sized port is used for injection of fluid, or the ports may have the same size. In the embodiment of FIG. 17, the conduits of the ports 1240a, 1240b are provided along a lower outer surface of the tubular-shaped body 1220 and along the outer lower surface of the angular tip 1230. Specifically, the ports 1240a, 1240b are spaced from one another so that each port 1240a, 1240b is provided along a different side of the lower outer surface of the tubular-shaped body 1220 and along a different side of the lower surface of the angled tip 1230. In other embodiments, the ports 1240a, 1240b may be provided along the same side of the lower outer surface of the tubular-shaped body 1220 and the lower surface of the angled tip 1230. In certain embodiments, one or both of the ports may include a sealing or closing mechanism to close the port opening when not in use. In this way, when one of the ports is being used to inject fluid to hydrodissect the GSV, the fluid is prevented from escaping through the other port.

Certain embodiments may include only one port 1240, instead of two ports, for supplying fluid for hydrodissection

of the GSV. In such cases, the conduit of the single port may extend along the lower outer surface of the tubular-shaped body 1220 and along the lower surface of the angled tip 1230 and may be centered or may be shifted to one of the sides relative to the tubular-shaped body and the tip. The positioning of the port depends on the position of an image capture device 1250 and is made such that the port does not block the field of view of the image capture device.

As also shown in FIGS. 16 and 17, the hydrodissector 1200 includes the image capture apparatus 1250, such as a video camera or the like, disposed inside the angled tip 1230. By placing the image capture apparatus 1250 inside the angled tip 1230, the image capture apparatus 1250 is protected from fluids and debris during the hydrodissection of the GSV. As mentioned above, in certain embodiments, the angled end of the angled tip 1230 is closed or sealed, and thus, in such embodiments, the image capture apparatus 1250 is encapsulated or encased in the angled tip and protected from fluids and debris. The image capture apparatus 1250 is configured to capture live images so as to visualize the GSV during the hydrodissection procedure. The live images may be transmitted wirelessly from the image capture apparatus 1250 to a computer, a tablet or a suitable display, or may be transmitted through a wire, e.g., by a USB connection.

The image capture apparatus is preferably an miniature camera so that it can be fitted within the angled tip 1230. The image capture apparatus may be a waterproof or non-waterproof, CMOS-based video camera with encapsulated lighting. In one example, the camera is a HD waterproof endoscope video camera probe with a small diameter of less than 1 inch, e.g., about 0.1-0.5 inch diameter, that includes a Hi-Vision or Super Hi-Vision CMOS sensor and has a resolution of 2.0 MP or higher. The camera preferably has a focal distance between 0.5 and 4 inches. However, the focal distance of the camera may vary depending on its configuration and desired position within the angled tip 1230. The camera of this example includes one or more of a USB-C connection, a Micro USB connection, a Bluetooth® connection and/or a Wi-Fi connection for connecting with an external display, computer or tablet. In other examples, the camera may be a miniature cystoscope, angioscope or laparoscope camera. In certain examples, the camera may be compatible with any operating system, such as Windows 7/8/10, Mac OS, Android system, etc. and may support a USB On-The-Go (USB OTG or OTG) and USB video device class (UVC) functions. In certain embodiments, the camera uses a lens carrier housing for enclosing the lens, and image sensor chip and/or lighting, such as the endoscope video cameras, and the lens carrier housing is attached to a surface of the angled tip of the hydrodissector or positioned within the angled tip. In other embodiments, the camera may be a one-piece assembly that incorporates the lens, the image sensor chip and/or the lighting, which can be molded into the angled tip or received in a cavity formed in the angled tip of the hydrodissector.

As shown, the image capture apparatus 1250 is positioned at an angle with respect to the lower surface of the angled tip 1230, i.e., an optical axis of the camera is at an angle with respect to the lower surface of the angled tip 1230, so that a camera lens and a camera sensor are provided at an angle with respect to the line of sight to the GSV which underlies the lower surface of the angled tip during hydrodissection. The angle of the image capture apparatus 1250 may be between 15 and 60 degrees relative to the lower surface of the angled tip 1230. In the illustrative embodiment of FIG. 16, the image capture apparatus 1250 is positioned at about

a 30 degree angle relative to the lower surface of the angled tip **1230**. This angled positioning of the image capture apparatus **1250** allows for direct viewing of the GSV to be hydrodissected and during the hydrodissection procedure. The angle of the image capture apparatus **1250** relative to the lower surface of the angled tip **1230** will depend on the distance of the image capture device **1250** from the injection opening **1241** of the fluid input port **1240a** and the field of view of the image capture apparatus **1250**. Although not shown in FIGS. 16 and 17, the angled tip **1230** may also have one or more light sources, e.g., one or more LEDs, disposed therein. For example, a plurality of LEDs may be disposed around the image capture apparatus **1250**, or at least one LED may be disposed adjacent to the image capture apparatus **1250**. In some embodiments, the LEDs are angled relative to the lower surface of the angled tip **1230** similarly to the image capture apparatus **1250** so as to direct light emitted from the LEDs in the same direction as the object being captured by the image capture apparatus **1250**. Also not shown in FIGS. 15-17 are one or more power sources for powering the image capture apparatus **1250** and/or the light source(s) and any connections or wiring necessary for connecting the power source(s) to the image capture apparatus **1250** and/or the light source(s) and for connecting the image capture apparatus **1250** with a display, a computer or tablet, if needed. In some embodiments, the image capture apparatus **1250** may include an internal power source, while in other embodiments, the power source may be disposed within the tubular-shaped body **1220** or within the handle **1210**. The connections or wiring to the power source and/or to the display, computer or tablet may be provided through the tubular-shaped body **1220** and/or through the handle **1210**.

FIGS. 18 and 19 show the hydrodissector of FIGS. 15-17 being used during hydrodissection of the GSV along the top surface of the GSV. As shown in FIG. 18, the hydrodissector is surrounded by the connective tissue just above the GSV. As discussed above, to hydrodissect the GSV, the hydrodissector is placed in the “sweet spot”, with the angled tip **1230** being preferably just above the top surface of the GSV, e.g., a few millimeters above the GSV, and the image capture apparatus **1250** is used for directly visualizing the hydrodissector **1200** in the “sweet spot” and for directly visualizing the GSV and the surrounding area. After the hydrodissector of FIGS. 15-17 is placed in the “sweet spot,” fluid is injected through one of the fluid ports **1240a** or **1240b** as shown in FIG. 19 so as to dissect the connective tissue off the GSV. The hydrodissector **1200** is moved along the length of the GSV while dissecting the connective tissue off the GSV in order to hydrodissect the entire length of the GSV. As mentioned above, the GSV may be hydrodissected using multiple hydrodissection passes, so that during the second hydrodissection pass, the hydrodissector **1200** is visualized adjacent the lower surface of the GSV, which is opposite to the upper surface of the GSV shown in FIGS. 18 and 19, and then fluid is injected through one of the fluid ports of the hydrodissector, while moving the hydrodissector along the lower surface of the GSV to dissect the muscular fascia from the GSV. Before using the hydrodissector **1200** for the second hydrodissection pass, the handle **1210** or the angled tip **1230** of the hydrodissector is rotated about 180 degrees relative to the tubular body so that during the second hydrodissection pass, the lower (longer) surface of the angular tip **1230** faces the GSV.

FIGS. 20A-20C and 21A-21C show other versions of the hydrodissector **1200** that can be used for hydrodissecting the GSV. The hydrodissector **1200** in FIGS. 20A-20C and

21A-21C is modified by providing the one or more ports **1240** that include conduits inside the tubular-shaped body **1220**. FIGS. 20A and 21A show a close-up side view of the hydrodissector **1200** near its distal end, and in each of these embodiments, the hydrodissector **1200** includes the tubular-shaped body **1220**, the angled tip **1230** attached to the distal end of the tubular-shaped body **1220**, the image capture apparatus **1250** provided inside and enclosed by the angled tip **1230** and one or more ports **1240** for fluid supply, gas supply and/or vacuum. As in the embodiment of FIGS. 15-19, the image capture apparatus **1250** is provided at an angle between 15 and 60 degrees relative to the lower surface of the angled tip **1230**. The conduits of the one or more ports **1240** are provided within the tubular-shaped body **1220** and the difference between the embodiment of FIGS. 20A-C and FIG. 21A-C is the configuration of the one or more ports **1240**.

As shown in FIG. 20A, the conduits of the one or more ports **1240** extend along the lower inner surface of the body **1220** and along the inner lower surface of the angled tip **1230**. An opening **1242** is provided for each port at the end of the angled tip **1230**. FIGS. 20B and 20C show cross-sectional views of the hydrodissector **1200** in FIG. 20A taken along the dashed line in FIG. 20A. FIG. 20B shows a cross-sectional view of a hydrodissector with one port **1240**, and FIG. 20C shows a cross-sectional view of a hydrodissector with two ports **1240a** and **1240b**. The ports **1240**, **1240a**, **1240b** preferably have an opening of 14-22 gauge in size. In FIG. 20B, the port **1240** is preferably a fluid port for supplying tumescent fluid for hydrodissection of the GSV and has a size between 14 and 22 gauge, and preferably, 20 or 22 gauge. In FIG. 20C, the ports **1240a**, **1240b** may have the same size or may have different sizes. For example, port **1240a** may be used as a fluid port for supplying tumescent fluid for hydrodissection of the GSV and may have a size between 14 and 22 gauge, and preferably, 20 or 22 gauge. The port **1240b** may be used as a suction port and may have a larger size between 14 and 22 gauge, and preferably between 14 and 18 gauge. In certain embodiments, the port **1240a** may be used for suction and the port **1240b** may be used for fluid supply and may be sized as needed for these functions. In certain embodiments, one or both of the ports **1240a**, **1240b** may be closed or sealed when not in use in order to prevent fluid from entering the unused port during the hydrodissection procedure.

As shown in FIGS. 20B and 20C, the port **1240** or the ports **1240a**, **1240b** are disposed on the inner lower surface of the angled tip **1230** and are shifted to the side away from the center. In FIG. 20C, both ports may be provided on the same side instead of being on different sides of the angled tip **1230**. In any case, the ports **1240**, **1240a**, **1240b** are positioned so as not to block the field of view of the image capture apparatus **1250** through the lower surface of the angled tip **1230**.

In FIGS. 21A-21C, the hydrodissector **1200** has one or more ports **1240** including conduits which extend along the lower inner surface of the tubular-shaped body **1220** and along a portion of the angled tip **1230**. Each port **1240** is then directed through an opening **1243** in the lower surface of the angled tip **1230** to outside of the hydrodissector **1200**. The end of the port **1240** may extend downwardly from the opening or may be angled toward the distal end of the hydrodissector, as shown in FIG. 21A. Although FIG. 21A shows the port **1240** extending through the opening **1243** in the lower surface of the angled tip **1230**, in other embodiments, the opening may be provided in the lower surface of the tubular body **1220** and the port **1240** would extend

through the opening in the tubular body 1220. The position of the opening would depend on the desired position of fluid injection from the hydrodissector 1200 during the hydrodissection procedure.

FIGS. 21B and 21C show cross-sectional views of the hydrodissector 1200 in FIG. 21A taken along the dashed line in FIG. 21A. FIG. 21B shows a configuration of the hydrodissector 1200 with one port 1240, while FIG. 21C shows a configuration of the hydrodissector 1200 with two ports 1240a, 1240b. As in FIGS. 20B and C, the ports 1240, 1240a, 1240b are shifted to the side away from the center so as not to block the view of the image capture apparatus 1250 through the angled tip 1230. In FIGS. 21B and 21C, port sizes and uses are similar to those of FIGS. 20B and 20C and thus, detailed description thereof is omitted.

Although the embodiments of FIGS. 20A-21C show at least one port 1240 extending along the lower surface of the body 1220 and the angled tip 1230, in other embodiments, fluid may be supplied directly to the tubular-shaped body 1220, without using a separate structure for the port, and a small opening may be provided in the angular tip for fluid injection therefrom. The opening size should be such that fluid is injected from the opening with sufficient fluid pressure for hydrodissection of the GSV. The opening size may be between 14 and 22 gauge and preferably, 20 or 22 gauge. The opening may be provided at the end of the angled tip, similar to FIG. 20A or may be provided in the lower surface of the angled tip, similar to FIG. 21A.

Although FIGS. 15-17 and 20A-21C show the hydrodissector that uses the angled tip 1230, in other embodiments, the angled tip 1230 may be removable from the body 1220 and may be interchangeable with other types of tips attachable to the body 1220. Different tips may be used for different phases of the procedure, e.g., angled tip 1230 for hydrodissection of the GSV and other types of tips for harvesting of the GSV. In certain embodiments, the angled tip 1230 may be removable from the body 1220 and may be replaced with a shovel-shaped or spoon-shaped tip. An example of a shovel-shaped or spoon-shaped tip is shown in FIGS. 7, 8A and 8B, which show the shovel-shaped or spoon-shaped tip being used on a harvesting retractor. In such cases, the camera and/or any light sources are held in the shovel-shaped or spoon-shaped tip, e.g., on the concave surface of the shovel-shaped or spoon-shaped tip, which provides partial protection for the camera and/or light source(s) from fluids and debris. The camera and/or light source(s) may be positioned so as to face in a direction away from the handle and toward a distal end of the dissector (e.g., at about 90 degrees relative to the lower surface of the tip) or may be angled to face away from the concave surface of the shovel-shaped or spoon-shaped tip (e.g., at an angle between 90 and 180 degrees relative to the lower surface of the tip). In such embodiments, the camera may use a lens carrier housing that encloses the lens, the image sensor chip and/or lighting (e.g., LEDs) and the lens carrier is attached, either permanently or detachably, to the concave surface of the spoon-shaped tip. In yet other embodiments, the camera may be a one-piece assembly that incorporates the lens, the image sensor chip and/or the lighting, which can be molded into the spoon-shaped tip or received in a cavity formed in the spoon-shaped tip.

As in the embodiment of FIGS. 15-17, the port(s) in this embodiment are provided along the lower surface of the shovel-shaped or spoon-shaped tip (along the convex surface thereof) and any wiring or connections and power source(s) are provided within the body 1220 and/or the handle 1210. Alternatively, the fluid port(s) may be provided

along the inside surface of the body 1220, similar to the embodiments of FIGS. 20A and 21A, and may be passed to the outside through an opening in the body 1220.

In certain embodiments, instead of interchangeable tips which can be removed from the body 1220 and changed as needed, the body 1220 of the hydrodissector is releasable and removable from the handle, and can be replaced with a different body having a different tip. For example, the body 1220, i.e., shaft, of the hydrodissector of FIGS. 15-17 that includes the angled tip, may be removable from the handle and interchangeable with a second body, i.e., shaft, with a different tip, such as a shovel-shaped or spoon-shaped tip, to be attached to the handle. This configuration of the hydrodissector, where the body together with the tip, is interchangeable, avoids removal and changing of small parts on the hydrodissector during or in between surgical procedures.

The dissector with the shovel-shaped or spoon-shaped tip thereon, or with the second body having the shovel-shaped or spoon-shaped tip, may be used as a retractor or harvester during the harvesting of the GSV, as described in more detail below. Similar to the retractor shown in FIGS. 6 and 7, and described below, one or more C-shaped and/or U-shaped attachments may be releasably attached to the shovel-shaped or spoon-shaped tip or to the body 1220 of the dissector. In addition, as in the retractor of FIGS. 6 and 7, the tip and/or the body 1220 may have multiple coupling positions for selectively coupling or clipping on the C-shaped and/or U-shaped attachments at different locations.

When the venous hydrodissector of FIGS. 5A-5C, the visualization device of FIGS. 10-13 or the hydrodissectors of FIGS. 15-19, 20A-C and 21A-C are used for hydrodissecting the GSV, the above-described hydrodissection procedure may be modified as shown in FIGS. 22-26 in order to provide a fluid-tight insertion access site to the GSV through an incision. The modified hydrodissection procedure of FIGS. 22-26 may also be used when the tumescent fluid is injected using one or more needles. As shown in FIG. 22, a 3 cm or similar size incision is made at the knee of the patient, and as shown in FIG. 23, a small circular or elliptical diaphragm 2300 or a suitable tissue occluder with a one-way valve 2310 or access port is placed through the incision to cover and seal the incision made in FIG. 22. The diaphragm may be made of rubber or similar fluid-tight and malleable material. The one-way valve 2310 is water-tight so as to prevent leakage of tumescent fluid injected into the incision during hydrodissection. As shown in FIG. 24, the hydrodissector 2400, such as the visualization device of FIGS. 10-13 or the hydrodissector of FIG. 5A-5C, 15-19, 20A-C or 21A-C, is placed through the access port 2310 and thereafter directed to the "sweet spot" adjacent the top surface of the GSV. The hydrodissection procedure is then performed as described above by injecting tumescent fluid to hydrodissect the GSV from the surrounding fascia and moving the hydrodissector along the top surface of the GSV to accomplish hydrodissection of the entire length of the GSV.

As discussed above, in certain embodiments, multiple hydrodissection passes may be needed to achieve sufficient hydrodissection of the GSV from the surrounding fascia. In certain cases, when hydrodissection of the GSV is performed as shown in FIGS. 22-24, at least the upper half of the GSV from about 9 o'clock to about 3 o'clock is hydrodissected from the surrounding fascia. In order to ensure that the lower half of the GSV is completely hydrodissected from 3 o'clock to 9 o'clock, the second hydrodissection pass may be performed along the lower surface of the GSV. Prior to performing the second hydrodissection pass, the handle 1210 or the angled tip 1230 of the hydro-

dissector shown in FIGS. 15-21C is rotated about 180 degrees and locked in this orientation so that when the hydrodissector is used for the second hydrodissection pass, the image capture apparatus in the angled tip 1230 faces the GSV to provide direct visualization of the GSV. As shown in FIG. 25, the hydrodissector 2400 is placed through the access port 2310 in the diaphragm and directed to the second “sweet spot” adjacent the lower surface of the GSV (at or around the 6 o’clock position). In this position, the angled tip 2430 of the hydrodissector 2400 is positioned between the GSV and the muscular fascia to which the GSV is attached. The second hydrodissection pass then proceeds in a controlled fashion by injecting tumescent fluid from the hydrodissector and with the image capture apparatus facing the GSV, i.e., looking up at the GSV at 6 o’clock, as the GSV is being lifted off the muscular fascia. The second hydrodissection pass ensures complete hydrodissection of the GSV from the surrounding fascia and eliminates the need for use of a needle to touch up the hydrodissection.

In certain embodiments, in addition to the direct visualization provided by the hydrodissector using a camera, ultrasound guidance may be used in order to place the tip of the hydrodissector in the “sweet spot” and to advance the hydrodissector along the GSV. In such cases, an ultrasound probe used for ultrasound guidance is connected to the same or different display unit, computer or tablet as the camera of the hydrodissector. When the ultrasound probe and the camera of the hydrodissector are connected to the same display unit, computer or tablet, a split screen is displayed showing live images from the camera and ultrasound images from the ultrasound probe. In this way, the operator can control the dissection of the GSV by keeping the hydrodissector right over the GSV and also watching the fluid form a halo around the GSV using the ultrasound probe. As mentioned above, portable Terason® ultrasound devices may be used for ultrasound guidance during hydrodissection. FIG. 26 shows an exemplary split screen visualization which includes an ultrasound view of hydrodissection on a left screen portion and direct visualization on a right screen portion. After the hydrodissection of the GSV is complete, the hydrodissector is removed and the fluid is evacuated. Alternatively, prior to removing the hydrodissector, fluid supply is turned off and suction is turned on via a suction port of the hydrodissector in order to evacuate the fluid. In this case, the hydrodissector is removed after evacuating the fluid.

The above described hydrodissection of the GSV procedures allow the GSV to be dissected from the surrounding fascia without damaging the GSV. Moreover, the saphenous nerve runs along the GSV and is often damaged by conventional techniques, resulting in loss of a sensory function. Hydrodissection of the GSV completely dissects the saphenous nerve from the GSV, without damaging the nerve, and as a result, sensory function of the extremity is not affected. In experienced hands, the GSV hydrodissection procedure takes less than 10 minutes to perform. In this technique, a catheter in the GSV is not required to render the GSV echogenic and thus easy to visualize during hydrodissection. Therefore, the above-described hydrodissection is performed without a catheter present in the GSV.

As discussed above, the hydrodissection procedure also requires that a sufficient amount of tumescent fluid is injected around the GSV so that the vein is surrounded by a dark halo of fluid (when viewed using u/s or under direct vision) without any echogenic connective tissue. This ensures that at the time of GSV harvest for CABG, the only attachments of the GSV will be its branches which have also

been hydrodissected from the surrounding connective tissue. This is possible because in a closed space such as the fascial envelope surrounding the GSV, the force vector of the fluid creating the hydrodissection travels along the path of least resistance which is the interface between the adventitia of the GSV and its branches and the surrounding connective tissue.

Moreover, by hydrodissecting the GSV, the hydrodissected GSV may be used as a drug-delivery system by applying one or more medications or solutions to the adventitia or the outer wall of the GSV. The one or more medications or solutions may be applied to the GSV during hydrodissection by including one or more medications in the tumescent fluid, as described above, or by separately applying the one or more medications to the hydrodissected GSV after performing the hydrodissection. As discussed above, in some embodiments, medications to protect the GSV and to heal the GSV may be applied to the hydrodissected GSV, and in particular, to the adventitia of the hydrodissected GSV, including aspirin, which protects the endothelium, heparin, such as local low-molecular weight heparin, and one or more vasodilators, such as venous vasodilators or combination dilators. Other medications may include but are not limited to one or more of the following: Nitroglycerine, Endothelin A receptor antagonist, Folic Acid, Angiotensin II receptor antagonist, Spermine/NO, Losartan, Perillyl alcohol, Superoxide dismutase, Antitissue factor antibody, Verapamil, Heparin, Ursolic acid, Local Aspirin, Rapamycin, Azathioprin, Paclitaxel, C-type natriuretic peptide, Leoligin and Papaverine. Characteristics and use of these medications is described in more detail in “*Perivascular administration of drugs and genes as a means of reducing vein graft failure*” by Wiedemann, et al., published by Current Opinion in Pharmacology 2012, 12:203-216. In some embodiments, platelet rich plasma or stem cells may be used to strengthen the wall of the GSV. In certain embodiments, gene therapy may be used on the GSV.

As discussed above, ideally, hydrodissection of the GSV is performed several hours or one or two days prior to the harvesting of the GSV and the actual bypass surgery. For harvesting of the GSV and the bypass surgery, the patient is prepped and draped in a standard fashion, and the hydrodissected GSV is exposed through an incision in the knee area. A retractor (also referred to as a “harvester”) described below can be used to expose the GSV so as to allow for visualization of the GSV in order to allow harvesting of the GSV. Alternatively, as discussed above, the hydrodissector described above with respect to FIGS. 15-17 and with the shovel-shaped or spoon-shaped tip may be used for harvesting the GSV. During the harvesting procedure, the retractor or harvester is used to expose the GSV and to lift the GSV so that exposed side branches of the GSV can be divided. Specifically, the side branches of the GSV are divided with a bipolar cautery device or using hemoclips or scissors. Thereafter, proximal and distal ends of the GSV are also divided so as to allow the harvested GSV to be used for bypass surgery.

FIGS. 6, 7, 8A and 8B illustrate a retractor or harvester which may be used during the GSV harvesting procedure. The retractor is preferably a disposable retractor. However, in some embodiments, the retractor may be reusable. FIG. 6 shows one embodiment of the retractor or harvester, while FIGS. 7 and 8A-8B show another variation of the retractor of FIG. 6, which has a different blade and tip configuration. Both retractors of FIG. 6 and of FIGS. 7 and 8A-8B may be used for harvesting as shown in FIG. 7.

As shown in FIG. 6, the retractor 600 includes a handle 602 and a blade 604 extending at an angle from the handle 602. The retractor 600 may include a curved section 603 connecting the handle 602 to the blade 604.

The blade 604 of the retractor 600 is of sufficient length to be inserted along the dissected GSV so as to expose the GSV and its branches. For example, the length of the blade 604 may be between 10 and 30 cm. In one example, the length of the blade is around 25 cm, while in another example, the blade is 15 cm in length. The width of the blade can be between 1 and 5 cm, and preferably between 2 and 4 cm. In one example, the width of the blade 604 is 2 cm, while in another example, the width of the blade is 4 cm. As shown in FIG. 6, the blade 604 also includes a tip 604a, which in FIG. 6 is shown as a substantially rectangular tip angled relative to the rest of the blade 604. The configuration of the tip 604a of the blade 604 may be varied and is not limited to the one shown in FIG. 6. For example, the tip 604a may have a rounded shape or may have a triangular shape with the sidewalls converging to a narrower tip or to a point. In another example, the tip may be shovel-shaped or spoon-shaped, as shown in FIGS. 7 and 8A-8B. In some examples, the tip 604a may include a lip at its end, or projections or an in-molded pattern to assist in holding back the tissue. In other variations, the end of the tip 604a may be smooth. In yet other examples, the tip 604a may be aligned with the rest of the blade 604 instead of being angled.

The blade 604 has a first surface 604b which faces an inside of the patient when in use and a second surface 604c which faces the outside of the patient when in use. The retractor 600 also includes a channel formed along the first surface 604b of the blade 604 and extending through the handle 602 of the retractor to a port 608. The channel includes a channel cover 606 that covers at least a portion of the channel extending along the first surface 604b of the blade 604 and which is coupled with the handle and/or may extend into the handle. The configuration of the channel and the channel cover 606 may be similar to the smoke evacuation channel used in a retractor described in U.S. Pub. Nos. US 2016/0354072 and 2017/0245849 and U.S. application Ser. No. 15/869,994, all of which are assigned to the same assignee herein and are incorporated herein by reference. In the retractor of the present invention, the channel can be used for removal of fluid, debris and/or smoke as well as for providing fluid into the incision and the open cavity. For example, the channel may be used for washing the GSV with fluid, such as the sodium bicarbonate solution or a solution of one or more medications mentioned above, and/or for providing a CO<sub>2</sub> infusion to the GSV.

In certain embodiments, particularly those that use the channel for conducting liquids and for supplying liquids to the patient cavity, the construction of the channel is made airtight and/or watertight so as to prevent the fluids from leaking into and possibly damaging other components of the retractor, e.g. electrical components. For example, in order to ensure watertight construction, the channel may include a tube, a conduit or a similar fluid conveying member extending from the port 608 in the handle and through the length of the handle 602. The tube may also extend under the cover 606 along at least a portion of the length of the blade 604. In other embodiments, the cover may engage with the blade 604 in an airtight manner and extend into the handle to fluidly couple with the tube or similar device passing through the handle to the port 608. As can be appreciated, the port 608 can be connected to a fluid supply and/or an infusion pump for supplying the fluid, e.g., CO<sub>2</sub>, sodium bicarbonate solution, medication solution, etc. Additionally,

the port 608 can be connected to a vacuum source when suction from the cavity is needed.

As shown in FIG. 6, the retractor also includes one or more U-shaped attachments 610 which are releasably attached to the blade 604 so as to protrude from the first surface 604b of the blade. In the illustrative embodiment of FIG. 6, a single U-shaped attachment is provided near the distal end of the blade 604. However, it is understood that the position of the U-shaped attachment may be varied, and may be changed from one position to another depending on the needs of the user. In some embodiments, multiple U-shaped attachments may be used if desired.

Multiple coupling mechanisms may be provided along the length of the blade 604 so as to allow desired positioning of the U-shaped attachment(s) along the length of the blade. As shown in FIG. 7, the U-shaped attachment is used to gently lift and hold the hydrodissected GSV. This allows for holding and exposing the perivenous space with one hand. As can be seen in FIG. 7, the tip 604a of the blade 604 is inserted into the incision to expose the hydrodissected GSV. After inserting the tip of the blade 604 into the incision and exposing the GSV, the U-shaped attachment can be snapped or clipped onto the blade and around the GSV so as to allow the retractor to gently raise the GSV to separate it from the surrounding tissues. When the GSV is exposed and held by the retractor 600 of the present invention, the branches are easily visible to the user and can be divided using bipolar cautery, hemoclips or scissors.

In the present invention, it is desired for the U-shaped attachment(s) to be completely releasable from the retractor blade. This configuration avoids having any branches of the GSV being torn or damaged. The U-shaped attachment may be clipped onto the blade 604 such as by inserting the ends of the U-shaped attachment into corresponding slots in the blade and engaging the ends of the U-shaped attachment with the corresponding slots. In some embodiments, the ends of the U-shaped attachment may include outward protrusions, which are inserted into corresponding slots in the blade while squeezing the legs of the U-shaped attachment toward each other and which engage with the corresponding slots in the blade by releasing the legs of the U-shaped attachment. The slots in the blade may have a horizontal, vertical or angled orientation relative to the length of the blade. Other mechanisms of releasable coupling of the U-shaped attachment, such as use of cantilever joints and other types snap-fit mechanisms, are contemplated by the invention. In other embodiments, the U-shaped attachment may have only one leg permanently fixed to the retractor and the other leg releasably attached so as to allow opening and closing of the U-shaped attachment.

In yet other embodiments, one or more C-shaped attachments may be used instead of the U-shaped attachment(s), wherein one of the ends of the C-shaped attachment is attached to or engaged with the first surface of the blade, while the other end is not attached to the blade and is positioned at a distance from the first surface of the blade. This configuration allows the GSV to be slipped into the C-shaped attachment through the space between the unattached end and the first surface of the blade. The C-shaped attachment(s) may be releasable from the retractor blade, or in some embodiments, the C-shaped attachment(s) may be permanently attached to the retractor blade.

Although FIG. 6 shows the U-shaped attachment being coupled to the first surface of the blade, in other embodiments, the span of the U-shaped attachment or C-shaped attachment may be smaller and the coupling of one or both legs of the attachment may be to the channel cover 606. In

yet other embodiments, one or more coupling mechanisms for the attachment may be provided at or near the tip **604a** of the blade. It is also understood that the particular shape of the attachment is not limited to the U or C shape and that other shapes may be suitable for lifting the GSV.

In accordance with the present invention, the retractor **600** of FIG. 6 may be a “smart” retractor which is provided with an illumination assembly for illuminating the operating field and/or with an image capturing assembly for capturing still and/or video images of the operating field in order to allow for observation of the GSV during the harvesting procedure. In some embodiments, the illumination assembly is provided separately from the image capturing assembly. In other embodiments, the illumination assembly is integrated into the image capturing assembly, wherein the image capturing assembly includes one or more light sources for illuminating the operating field and for illuminating an area to be captured in one or more still or video images.

FIGS. 8A and 8B show schematic exemplary embodiments of the “smart” retractor when viewed from the tip **604a** of the retractor blade **604** of FIG. 7. The “smart” retractor of FIGS. 8A and 8B includes an illumination assembly with at least one light source **812** and/or an image capturing assembly with a camera **814**. The light source **812** may be an LED or any other suitable light source, and in some embodiments, the light source may be used in combination with an optical guide (a waveguide) for conducting light from the light source. In some embodiments, the camera **814** is an endoscope camera which is miniature in size so that it can be attached to the retractor blade **604** without interfering with the tissues and the GSV. The camera **814** may be a waterproof, CMOS-based video camera with encapsulated lighting. In one example, the camera **814** is a HD waterproof endoscope video camera probe with a small diameter of less than 1 inch, e.g., about 0.1-0.5 inch diameter, that includes a Hi-Vision or Super Hi-Vision CMOS sensor and has a resolution of 2.0 MP or higher. The camera preferably has a focal distance between 0.5 and 4 inches, and in this example has a focal distance between 1.2 and 2.4 inches. However, the focal distance of the camera may vary depending on its configuration and desired position on the retractor blade. The camera may include adjustable light sources, e.g., LEDs, at the camera tip. The camera in this example may have 6-8 LEDs disposed at the tip of the camera and spaced around the periphery of the tip. The number of LEDs may be varied depending on the size of the camera and the size and brightness of the LEDs. The brightness and/or color of the LEDs may be adjustable. The camera **814** of this example includes one or more of a USB-C connection, a Micro USB connection, a Bluetooth® connection and/or a Wi-Fi connection for connecting with an external display. In certain examples, the camera may be compatible with any operating system, such as Windows 7/8/10, Mac OS, Android system, etc. and may support a USB On-The-Go (USB OTG or OTG) and USB video device class (UVC) functions. More specific examples of the camera **814** include endoscope cameras manufactured by Depstech® including NTC85S 2-In-1 Endoscope, WiFi 10 WIFI Endoscope or WIFI Borescope. Other waterproof miniature cameras are suitable for use in the retractor of the present invention.

Although not shown, in certain embodiments, the illumination assembly further includes at least one energy source, e.g., a battery, an activation device, e.g., a removable tab, a switch, a button or the like, and electrical connections among the activation device, the energy source and the light source(s). The construction of the illumination assembly

may be similar to the illumination assemblies disclosed in U.S. Pub. Nos. US 2016/0354072 and 2017/0245849 and U.S. application Ser. No. 15/869,994, which are incorporated herein by reference.

The image capturing assembly includes an image capture apparatus, i.e., a camera **814**, which is capable of taking still and/or video images. The image capturing assembly may also include a storage device, e.g., a memory card, flash storage, or the like, for storing captured images/videos and/or a communication interface for communicating captured images/videos and/or live view images/videos to one or more outside devices. The communication interface may be a wired communication interface, such as USB or HDMI, or a wireless communication interface, such as Bluetooth®, Wi-Fi or Near Field Communication. In certain embodiments, the camera may be capable of both wired and wireless communication, including but not limited to USB, HDMI, Bluetooth®, Wi-Fi, Near Field Communication, etc. For example, the image capture assembly may be connected, by a wire or wirelessly, to a video screen, so as to transmit images during the procedure and to allow the user to view the images on the video screen. The image capture apparatus, the storage device and/or the communication interface are preferably housed within the same housing. In certain embodiments, the image capturing assembly also includes one or more energy sources, e.g., batteries, or may be electrically coupled with the one or more energy sources of the illumination assembly. In yet other embodiments, the image capturing assembly may not include any energy sources therein and may require external power supply, e.g., via a USB connection. For example, during use, the image capturing assembly may be connected via the USB connection with a display screen so that power is supplied to the image capturing assembly from the display screen via the USB connection and captured or live images are transmitted from the image capturing assembly to the display screen via the same USB connection.

In certain embodiments, the camera uses a lens carrier housing for enclosing the lens, and image sensor chip and/or lighting, such as the endoscope video camera described above, and the lens carrier housing is permanently or releasably attached to the surface of the retractor or to the tip of the retractor. In other embodiments, the camera may be a one-piece assembly that incorporates the lens, the image sensor chip and/or the lighting, which can be molded into the retractor blade or into the tip of the retractor blade, or may be received in a cavity formed in the retractor blade or the tip of the blade.

In the embodiments of FIGS. 7, 8A and 8B, the retractor is modified from the retractor of FIG. 6, wherein the blade includes a channel passing therethrough, the channel cover **606** is formed on the concave surface of the tip **604a** and is coupled with the channel passing through the blade **604**. In other embodiments, the blade may include a channel along the surface of the blade with a channel cover provided on the surface of the blade **604**, similar to the configuration of FIG. 6, and the channel cover **606** formed on the surface of the tip **604a** may be coupled with the channel and the corresponding channel cover provided on the blade **604**. In the embodiment of FIG. 8A, the light source **812** (or a waveguide when used in combination with the light source) of the illumination assembly is positioned at or near the open end of the channel cover **606** and is configured to illuminate the operating area around the tip **604a** of the retractor blade. In FIG. 8A, the camera **814** is provided outside of the channel cover **606** and is attached to the concave surface of the retractor tip **604a**, the surface of the retractor blade and/or to

the external surface of the channel cover 606. In some cases, the camera 814 is releasably attached to or clipped or snapped onto the retractor blade, the retractor tip or the channel cover. In other embodiments, the camera is permanently attached to the retractor. Although FIG. 8A shows the camera 814 being provided outside the channel cover 606 while the light source 812 is provided inside, or partially enclosed by, the channel cover 606, in other embodiments, the positions of the camera 814 and the light source 812 may be switched so that the camera 814 is provided inside or partially enclosed by the channel cover 606 and the light source 812 is provided outside the channel cover 606.

In the embodiment of FIG. 8A, wiring connecting the light source 812 to the at least one energy source (not shown) can be provided between the channel cover 606 and the concave surface of the tip 604a and extend along or inside the blade and into the handle of the retractor. Exemplary positioning of the wiring between the light source and the energy source is described in U.S. Pub. Nos. US 2016/0354072 and 2017/0245849. Wiring, if any, for connecting the camera 814 to an energy source (external or within the handle of the retractor) and/or to any external device (e.g., display screen) may be provided along the surface of the retractor blade 604 outside of the channel in the retractor blade or may be provided in the channel in the retractor blade and may extend from the proximal end of the blade or through the retractor handle.

In the embodiment of FIG. 8B, the light source 812 of the illumination assembly and the camera 814 of the image capturing assembly are positioned adjacently at or near the open end of the channel cover 606. In this case, wiring connecting the light source 812 and the camera 814 are provided between the channel cover 606 and the concave surface of the tip 604a, along the channel in the blade 604 or along the outer surface of the blade, and may extend into and through the handle of the retractor and/or from the proximal end of the blade.

In certain embodiments of FIGS. 8A and 8B, the positioning of the light source 812 and/or the camera 814 may be varied relative to the end of the channel cover 606. For example, either the light source 812 or the camera 814, or both, may be positioned closer to a distal end of the tip 604a of the retractor blade. For example, in some embodiments, the camera 814 may be positioned at the end of the tip of the retractor blade, and in other embodiments, the camera may be positioned about 1-2 cm away from the end of the blade tip. In yet other embodiments, the camera 814 may be positioned further away from the blade tip. The positioning of the camera 814 relative to the tip of the retractor blade is dependent on the depth of field, the color of the illumination and the amount of light provided by the illumination assembly. The camera 814 should be positioned so as to allow clear visualization of the GSV being harvested while avoiding debris and fluids from the operating region blocking the view of the camera 814. In certain embodiments, the position of the camera 814 relative to the tip of the blade may be changeable, such as by sliding by a sliding mechanism along the blade or by detaching the camera 814 from one position and reattaching the camera 814 at another position relative to the tip. In some embodiments, the camera may be a self-cleaning camera that is capable of clearing any debris or fluids accumulating on the camera lens. In certain embodiments, the camera may be water proof or liquid proof and/or may be coated with a waterproof coating, such as a silicone coating.

As mentioned above, in some embodiments, the illumination assembly may be integrated with the image capturing

assembly. For example, one or more light sources may be provided as part of the image capturing assembly on the camera 814 or may surround the camera 814 or the camera lens so as to provide a single integrated assembly. In such embodiments, power for the integrated image capturing and illumination assembly may be provided from an external source, e.g., via a USB cable. Alternatively, the retractor may include one or more energy sources provided in the handle or near the proximal end of the blade for powering the one or more light sources and/or the camera. In some embodiments, the integrated image capturing and illumination assembly may selectively use power supplied by one or more energy sources in the retractor, e.g., in the handle or on the blade, for the light sources and/or the camera when external power is not available and use external power supplied from an external power source when available.

As discussed above, the “smart” retractor or harvester of the present invention can be used during the GSV harvesting procedure to enable direct visualization of the GSV being harvested and to provide illumination during the harvesting procedure. In one specific example, the camera 814 of the retractor is connected wirelessly or by a sterile USB cord to a portable ultrasound machine, such as Terason® t3200 or t3300, so that the display screen of the portable ultrasound machine acts as a monitor or display for the camera. In addition, when the camera is connected to the ultrasound machine or any other display screen using the USB cord, power may be supplied to the camera via the USB cord so that additional wires or batteries are not required for operation of the camera. The retractor of this invention exposes the GSV and allows for better visualization of the GSV and its branches during the harvesting procedure.

In another embodiment, another version of a retractor 900 is shown in FIG. 14. The configuration of the retractor 900 is similar to that of FIGS. 6 and 7, and similar features are shown using similar reference numbers. However, instead of including a camera in the retractor 900, the retractor of FIG. 14 includes a tunnel 902 formed on or connected to the blade 604 for loading a visualization device 1000, such as a cystoscope, an angioscope or an endoscope. The visualization device may be the same visualization device used for hydrodissecting the GSV under direct vision.

As shown in FIG. 14, the tunnel 902 is formed on the first surface 604b of the blade 604 and extends adjacent to the channel cover 606 used for smoke evacuation or fluid/gas delivery. The size and shape of the tunnel 902 is not limited to the shape shown in FIG. 4 and may be smaller in width, shorter or longer in length and/or may be formed using a solid tunnel cover permanently or releasably attached to the first surface 604b of the blade or using a plurality of C or U shaped attachments permanently or releasably attached to the first surface of the blade along the channel cover 606. In other embodiments, the tunnel may be integrally formed with the blade, instead of using a separate cover or attachments. In some embodiments, the position of the tunnel 902 may be varied. For example, the tunnel 902 may be provided on top of the channel cover 606 instead of to the side of the channel cover 606.

As shown in FIG. 14, the tunnel 902 is used for loading and holding the visualization device 1000 adjacent to the retractor blade 604. In the illustrative embodiment of FIG. 14, when the visualization device is loaded into the tunnel, the tip of the visualization device is placed near the tip 604a of the retractor for optimal visualization of the GSV during harvesting. However, in other embodiments the positioning of the tip of the visualization device may be adjusted so as to provide desired visualization of the GSV. Although not

shown, in some embodiments, a locking mechanism may be used to lock in place the position of the visualization device in the tunnel 902 or relative to the retractor blade 604. The locking mechanism would prevent movement of the visualization device relative to the retractor during the GSV harvesting procedure.

Although the tunnel 902 in the retractor of FIG. 14 is used for loading the visualization device, in other embodiments, the tunnel can be used for holding other devices, as needed. In the retractor of FIG. 14, since a camera is not required to be part of the retractor, a smaller size of the retractor and lower manufacturing cost can be maintained. However, in some embodiments, the configuration of the retractor of FIG. 6 may be modified to include the tunnel for loading the visualization device. In such embodiments, the retractor would include a camera, as shown in FIGS. 8A and 8B, and would also be capable of loading a visualization device, or other devices, as needed.

In certain embodiments, instead of using the retractor of FIGS. 8A-B and 14, the hydrodissector 1200 of FIGS. 15-21 or the hydrodissector with the shovel-shaped or spatula-shaped tip described above may be used during the harvesting procedure. In these embodiments, the camera of the hydrodissector provides direct visualization and illumination of the GSV being harvested. One or more of the fluid ports 1240, 1240a, 1240b of the hydrodissector may be used for washing the GSV with fluid, such as the sodium bicarbonate solution or a solution of one or more medications mentioned above, and/or for providing a CO<sub>2</sub> infusion to the GSV. Furthermore, if needed, suction may be provided to the GSV using one of the fluid ports 1240a, 1240b to remove any excess fluids.

As discussed above, in some embodiments, the hydrodissector of FIGS. 15-21 has interchangeable tips or interchangeable bodies with different tips, so that the angled tip 1230 or the body with the angled tip of the hydrodissector in FIGS. 15-21 may be removed and replaced with another tip, such as a shovel-shaped or spoon-shaped tip, or another body with a different tip, in order to convert the hydrodissector into a retractor/harvester. As also discussed above, the shovel-shaped or spoon-shaped tip includes a camera provided on its concave surface and directed so as to provide direct visualization of the GSV when the tip is used to retract tissue around the GSV. In certain embodiments, the camera is angled between 90 and 180 degrees relative to the surface of the shovel-shaped or spoon-shaped tip. In addition, as in the embodiments of the retractor in FIGS. 6 and 7, one or more C-shaped or U-shaped attachment(s) may be removably attached to the shovel-shaped or spoon-shaped tip or to the tubular-shaped body so that the C-shaped or U-shaped attachment(s) is used for lifting the GSV. For example, one or more C-shaped or U-shaped attachments may be removably attached on the concave side of the shovel-shaped or spoon-shaped tip. The one or more C-shaped or U-shaped attachments may be attached at other locations on this convertible hydrodissector so as to optimize lifting of the hydrodissected GSV without causing damage thereto.

In certain embodiments, other devices that prevent trauma to the GSV and preserve the GSV may be utilized for vein harvesting in addition to the above-described retractor and/or hydrodissector. For example, a Vein Preparation Kit manufactured and sold by VasoPrep Surgical ([vasoprep.com](http://vasoprep.com)) may be used during harvesting the GSV. VasoPrep's Vein Preparation Kit includes a non-toxic surgical marking pen that preserves endothelial function, a pressure relief assembly that automatically limits distention pressure during preparation of the vein, a bulldog clamp foratraumatic

vein occlusion, a vein cannula and cannula introducer assembly and other components such as syringes and temporary vein storage cup. Either some or all of the components of this kit may be used during GSV harvesting. Other techniques and devices which preserve the vein during harvesting are described in U.S. Pat. No. 8,691,556, assigned to Vanderbilt University, which may be used during GSV harvesting. The entire disclosure of the '556 patent is incorporated herein by reference.

In accordance with the present invention, a kit for performing the MINT procedure may be provided in order to supply the devices needed for performing the MINT procedure. In certain embodiments, the kit includes one or more of the following items: one or more needles for use in hydrodissecting the GSV, one or more disposable venous hydrodissectors having a pencil tip and/or the cone-shaped blunt tip, at least one disposable "smart" retractor/harvester with one or more U-shaped and/or C-shaped adapters, disposable clip applicators, such as clip applicators manufactured by Microline Surgical, clips, such as hemoclips, disposable scissors, disposable hook(s), disposable cauteries, disposable electrode(s) and tumescent fluid for use in hydrodissection. The kit may also include medication solutions for use after hydrodissection and other solutions and/or devices for use during the MINT procedure. The kit may also include the hydrodissector and sheath introducer shown in FIGS. 10-13, and/or the hydrodissector of FIGS. 15-19 and/or FIGS. 20A-C and/or FIGS. 21A-C as well as interchangeable tips or interchangeable bodies with different tips for the hydrodissector of FIGS. 15-19, 20A-C and/or 21A-C to enable conversion between hydrodissecting functions and harvesting functions. Moreover, the kit may also include a vein preservation kit, such as a Vein Preparation Kit manufactured by VasoPrep ([www.vasoprep.com](http://www.vasoprep.com)) that includes a surgical marking pen, a pressure relief assembly, a bulldog clamp foratraumatic vein occlusion, a vein cannula and cannula introducer assembly and other components such as syringes, temporary vein storage cup, etc.

Using Endoscopic Asval, a Modification of the Mint Procedure to Treat Varicose Veins

The most popular method for treating varicose veins involves the removal or destruction of the Great Saphenous Vein (GSV). This technique is based on the "descending theory" of the etiology of varicose veins, which was first posited by Trendelenburg in 1894, when patients presenting for treatment had far advance disease. Today, the majority of patients treated for varicose veins have far milder disease with GSVs that do not have to be sacrificed for the treatment to be effective. This more modern treatment is based on the "ascending theory" of the etiology of varicose veins. The "ascending theory" posits that varicose veins start in the more superficial, thin wall veins and the GSV only becomes pathologic once a large venous reservoir develops. This allows the majority of patients to be treated by meticulous, ultrasound guided, phlebectomy such as the ASVAL technique, which can prevent the loss of the GSV. According to the CEAP Classification System, there are six levels of venous disease. The ASVAL method works well for C-2 level venous disease and for some C-3 level venous disease. However, for patients with more far advanced disease, the ASVAL method alone will not save the GSV, and this patient group would be an ideal group of candidates for Endoscopic ASVAL of the present invention.

The Endoscopic ASVAL procedure starts exactly as the MINT procedure described above, with ultrasound guided hydrodissection of the GSV from just below the knee at Boyd's perforator to the groin. A small incision is made at

the knee and the hydrodissection is started as in the MINT procedure. The position of the incision and hydrodissection may be adjusted as needed for the procedure. The Endoscopic ASVAL procedure differs from the above-described MINT procedure in that the side branches which are varicosed and incompetent perforators are divided, while branches which are normal, healthy and competent perforators are left alone and are not divided. In this way, the varicosed branches of the GSV are divided while leaving the healthy branches that are competent perforators intact to ensure long-term patency of the GSV.

The abnormal branches to be divided can be identified by ultrasound preoperatively with the patient in a standing position. Once the abnormal vessels have been divided, the Endoscopic ASVAL procedure is finished with the GSV left in situ. The knee incision is closed and the patient is placed in a thigh length compression stocking. Compression therapy is continued for several weeks post-op to ensure that the GSV remains undilated while the cicatrix around the vein forms. The cicatrix formed around the GSV should act as an exoskeleton at the time it is harvested for bypass. The use of exoskeletons around venous bypasses in animal and human studies have resulted in improved hemodynamics and reduced Vein Graft Failure (VGF). At the time of bypass, the GSV and its surrounding cicatrix can be harvested using the principles developed by Dr. Keith Delman in performing minimally invasive lymph node groin dissection in patients with metastatic malignant melanoma.

The Endoscopic ASVAL procedure and any future harvesting of the GSV can be performed using the same equipment as the above-described MINT procedure, namely the echogenic needle and/or venous hydrodissector, the portable ultrasound, such as Terason t3200 or t3300, and/or the visualization device, and the "smart" retractor, all of which are described above. These procedures can all be done under local tumescent anesthesia in an outpatient setting, thus reducing the complexity and cost of the procedures and reducing patient recovery time.

As with the above-described MINT procedure, the Endoscopic ASVAL allows the adventitia of the GSV to be treated with drugs such as platelet rich plasma or stem cells to strengthen the wall of the GSV, since weakness of the vein wall is thought to be a primary cause of varicose veins. These and other drugs, as well as gene therapy, can be delivered to the GSV over several days, weeks or months, using existing technology. For example, drug therapy, stem cell therapy and/or gene therapy can be delivered to the GSV on a permanent or a bioabsorbable drug eluting stents. Other drugs, such as the ones mentioned herein above used in the MINT procedure, may be applied to the GSV to promote strengthening of the venous wall, preventing thrombosis and preventing damage to the GSV.

FIG. 9A shows a GSV after undergoing the Endoscopic ASVAL procedure described above. As shown in FIG. 9A, the procedure is performed through a 2-cm incision preferably in the knee region to hydrodissect the GSV between the knee and the groin. As also shown in FIG. 9A, incompetent perforator and varicosed vein branches are ligated while competent perforator branches are left intact. In other embodiments, the position of the incision and the size thereof may be different, and in some embodiments, the portion of the GSV treated may be between the knee and the ankle, or may be the full length of the GSV. The procedure of FIG. 9A may be modified to use a diaphragm with a one-way access port, as described above with respect to FIGS. 22-26, and to perform multiple hydrodissection passes.

FIG. 9B shows a GSV after undergoing the Endoscopic ASVAL procedure and having bioabsorbable drug eluting stents applied thereto. As shown, the stents are applied to the hydrodissected GSV and the ligated branches in order to deliver drug therapy, stem cell therapy and/or gene therapy to the GSV. In the embodiment shown in FIG. 9B, the stents are not applied to the competent perforator branches, which are not ligated. In other embodiments, however, the stents may be applied to all branches, including the competent perforator branches and the ligated branches, or to selected branches of the GSV, as needed.

The above-described MINT procedure and the Endoscopic ASVAL procedure can also address a concern that thrombus might develop in the GSV at the time of hydrodissection. This may be prevented by giving the patient one dose of therapeutic Lovenox two hours prior to the hydrodissection. This would protect against the possibility of any intraluminal clots developing during the hydrodissection and the effect of the Lovenox would be completely neutralized by the time GSV harvesting is carried out at the time of the CABG. In certain cases, standard EVH procedure as well as the MINT procedure described above can cause intra and postoperative bleeding at the saphenectomy site leading to hematoma formation and increased leg wound complications. This complication can be avoided by infusing tumescent fluid containing isotonic sodium bicarbonate with Lidocaine and epinephrine into the potential space created by the saphenectomy at the time of the harvesting. This would also eliminate any possibility of intra or postoperative bleeding necessitating the use of drains in the leg.

While the above descriptions of the MINT procedure and the Endoscopic ASVAL procedure direct the use of a needle, such as an echogenic spinal needle, or venous hydrodissector to perform the hydrodissection under ultrasound guidance or under direct vision to make this procedure as minimally invasive as possible, other effective imaging techniques are available. For example, if the sonographic skills of the average Physician Assistant performing this procedure do not allow them to safely use an echogenic needle, a rigid 2 mm cannula can be easily placed in the saphenous space with a 7-French introducer sheath. This blunt tipped 2 mm infusion cannula completely eliminates any potential damage to the GSV at the time of hydrodissection secondary to a sharp tipped echogenic spinal needle. Alternatively, the venous hydrodissectors described above can be used instead of the needle.

The above-described MINT procedure and the Endoscopic ASVAL procedure solve a number of problems typically associated with vein dissection and harvesting procedures. First, the MINT procedure and the Endoscopic ASVAL procedure solve a problem of leg wound complications that occur with open vein harvest techniques by using a minimally invasive technique performed through a 3 cm incision. Second, the MINT procedure and the Endoscopic ASVAL procedure solve a problem of blunt trauma to the GSV that occurs during harvesting because hydrodissection of the GSV eliminates all blunt trauma during harvesting.

Another common problem occurring in conventional procedures is thrombus, both macro and micro, which occurs in about 67% of GSVs harvested with standard EVH procedures. In the present invention, addition of low molecular heparin to the perivascular space has been demonstrated to penetrate the vessel wall down to the endothelium. Also, addition of aspirin to the perivascular space has a direct protective effect on the endothelium which reduces endothelial denudation and thrombosis. The MINT procedure and

the Endoscopic ASVAL procedure also solve a problem of spasms of the GSV. Specifically, addition of anti-spasmodic agents such as Papaverine or nitroglycerine-verapamil solutions, to the tumescent fluid prevents spasms of the GSV.

When the hydrodissection of the GSV is performed about 24 hours before performing a lower extremity bypass, the fascial space surrounding the GSV has to be gently re-expanded with the tumescent fluid solution containing the above-described medications, i.e., aspirin, low molecular weight heparin, Papaverine, etc. This is necessary to ensure the perivascular delivery of the aspirin, low molecular weight heparin and anti-spasmodic agents at the moment the harvesting of the GSV is started. This prevents the initiation of thrombosis, which is known to be the first step leading to intimal hyperplasia and the chief cause of vein graft failure. Therefore, at the time of vein harvest for either CABG or the lower extremity bypass, the hydrodissector and/or retractor described above used for harvesting is required.

The present invention also solves a problem of a toxic environment surrounding the GSV. In the present invention, Plasma Lyte A, which is a major component of the tumescent fluid, has a pH of 7.4 compared to Normal Saline with a pH of 5.6, which is known to be toxic to the GSV. Thus, the tumescent fluid used during the MINT procedure and the Endoscopic ASVAL procedure avoids a toxic environment surrounding the GSV. In addition, the present invention solves the problem of a toxic effect of CO<sub>2</sub>, which is a further cause of acidosis leading to endothelial damage. Specifically, the MINT procedure and the Endoscopic ASVAL procedure use an open CO<sub>2</sub> system and the Plasma Lyte A solution is a buffered salt solution which would neutralize the effect of CO<sub>2</sub>.

The MINT procedure and the Endoscopic ASVAL procedure of the present invention solve a problem of inexperienced physician assistants (PAs) damaging the GSV during harvesting, thus leading to inferior GSV patency rates. In the present invention, for lower extremity bypass procedures, where hydrodissection is performed 24 hours pre-op with an ultrasound guided spinal needle or with an ultrasound and/or direct vision guided hydrodissector, the PA can perfect the hydrodissection technique on venous patients that are having their GSVs ablated. PAs would be allowed in a cardiac suite after video confirmation of mastery of this technique on venous patients. Moreover, for CABG patients, where the MINT procedure takes place immediately prior to bypass, the hydrodissectors described above feature real-time visualization of the GSV and ultrasound monitoring of the hydrodissection will ensure complete andatraumatic dissection of the GSV. As a result, this process eliminates the learning curve needed for the standard EVH procedures.

Moreover, the MINT procedure and the Endoscopic ASVAL procedure of the present invention solve a problem of post-operative hematomas at harvest site. In the present invention, once the GSV is harvested, the site is infiltrated with tumescent fluid consisting of isotonic sodium bicarbonate with xylocaine and epinephrine added. During this procedure, no drain is used and a water tight closure is performed. Thigh length stocking and Ace wrap is applied to the patient's extremity prior to leaving the operating room.

Finally, performing hydrodissection of the GSV, as described above, about 24 hours prior to a lower extremity bypass allows the surgeon to perform this complex vascular reconstruction under straight local anesthesia since all of the dissection has already been completed the day before. As a result, the present invention substantially reduces the occurrence of surgical trauma, and the surgical trauma for this reconstruction is the same as for a simple embolectomy.

Therefore, the procedures of the present invention reduce post-operative morbidity and mortality rates.

In all cases, it is understood that the above-described arrangements are merely illustrative of the many possible specific embodiments which represent applications of the present invention. Numerous and varied other arrangements, including use of different materials and various configurations of components of the retractor, can be readily devised without departing from the spirit and scope of the invention.

#### INCORPORATION BY REFERENCE

The present application claims priority to U.S. Provisional Patent Application Nos. 62/533,714 filed on Jul. 18, 2017, 62/640,892 filed on Mar. 9, 2018 and 62/683,376 filed Jun. 11, 2018, the disclosures of which are incorporated herein by reference.

We claim:

1. A hydrodissector for hydrodissecting a vascular target, the hydrodissector comprising:  
a handle;  
a shaft extending from the handle at an angle and including a tapered tip at a distal end thereof;  
at least one port provided at the tapered tip and configured to be coupled to a fluid supply and to eject fluid from the tapered tip into the space between the vascular target and surrounding tissues to dissect the vascular target from the surrounding tissues, said at least one port being sized to provide sufficient pressure and velocity to dissect the vascular target from the surrounding tissues; and  
an image capturing assembly configured to provide direct visualization of the vascular target during hydrodissection,  
wherein the length of the shaft is configured for insertion into an incision to atraumatically hydrodissect the vascular target from the surrounding tissues; and  
wherein the image capturing assembly is provided inside the tapered tip.
2. The hydrodissector of claim 1, wherein the image capturing assembly comprises an image capture device encased by the tapered tip of the shaft.
3. The hydrodissector of claim 2, wherein the image capture device includes a lens, an image sensor and one or more light sources.
4. The hydrodissector of claim 3, wherein the image capturing assembly further comprises a power source for powering the image capture device, said power source being provided in one of the tapered tip, the shaft and the handle.
5. The hydrodissector of claim 2, wherein the tapered tip of the shaft is transparent and wherein the image capture device is positioned inside the tapered tip so that an optical axis of the image capture device is angled relative to a lengthwise axis of the tapered tip so as to allow direct viewing of the vascular target to be hydrodissected.
6. The hydrodissector of claim 1, wherein the tapered tip has a substantially cylindrical shape and an angled end, and wherein a first surface of the tapered tip is longer than an opposing second surface of the tapered tip.
7. The hydrodissector of claim 6, wherein the at least one port is one of:  
(a) external and adjacent to the first surface of the tapered tip and is configured to be coupled to the fluid supply via a conduit extending along an outer surface of the shaft; and

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(b) provided in the tapered tip and is configured to be coupled the fluid supply via one of the shaft and a conduit extending inside the shaft.

**8.** The hydrodissector of claim **6**, wherein the at least one port is provided in the tapered tip and extends from one of (a) the first surface of the tapered tip and (b) an angled end of the tapered tip adjacent to the first surface of the tapered tip.

**9.** The hydrodissector of claim **1**, wherein the at least one port includes a first port configured to be coupled to a fluid supply and a second port configured to be coupled to a vacuum.

**10.** The hydrodissector of claim **6**, wherein one of (a) the tapered tip is configured to rotate relative to the shaft and (b) the shaft is configured to rotate relative to the handle.

**11.** The hydrodissector of claim **2**, wherein the tapered tip of the shaft is removable from a body of the shaft and interchangeable with one or more second tips.

**12.** The hydrodissector of claim **11**, wherein the second tip is a spoon-shaped tip configured for retracting tissues and for harvesting the vascular target, and wherein a second image capturing device is provided on the spoon-shaped tip.

**13.** The hydrodissector of claim **2**, wherein the shaft is removable from the handle and interchangeable with one or more second shafts.

**14.** The hydrodissector of claim **13**, wherein the second shaft includes a second tip and is configured to releasably couple with the handle and to convert the hydrodissector into a harvester for harvesting the vascular target, and wherein a second image capturing device is provided on the second tip.

**15.** The hydrodissector of claim **1**, wherein the shaft is configured to hydrodissect the vascular target from the surrounding tissues without blunt dissection of the vascular target or of the surrounding tissues.

**16.** The hydrodissector of claim **1**, wherein the shaft comprises a tubular shaft with an opening at a distal end thereof, and the tapered tip covering the opening.

**17.** A minimally invasive method for dissecting a vascular target from surrounding tissues, the method comprising:

inserting one of a needle and a hydrodissector into a patient's body so that a tip of the one of the needle and the hydrodissector is placed in a predetermined position adjacent to the vascular target to be dissected from surrounding tissues; and

injecting fluid at a pressure and velocity sufficient to dissect the vascular target from the surrounding tissues from the one of the needle and the hydrodissector while moving the one of the needle and the hydrodissector along a predetermined length of the vascular target to causeatraumatic dissection of the vascular target from the surrounding tissues,

wherein hydrodissected vascular target is suitable for subsequent harvesting for use in surgical bypass procedures, and

wherein the inserting and injecting steps are performed without requiring a large incision along the entire portion of the vascular target being dissected.

**18.** The minimally invasive method of claim **17**, wherein the predetermined position adjacent to the vascular target is one of: about 1 to 2 mm away from an upper surface of the vascular target closest to the patient's skin, and about 1 to 2 mm away from a lower surface of the vascular target furthest from the patient's skin.

**19.** The minimally invasive method of claim **17**, wherein the fluid injected in the injecting step comprises tumescent fluid including one or more of: isotonic sodium bicarbonate

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solution, Balanced Salt Solution with a pH of about 7.4, isotonic saline solution, Plasma Lyte A solution, and an endothelial damage inhibitor solution comprising glutathione, ascorbic acid and L-arginine.

**20.** The minimally invasive method in accordance with claim **19**, wherein the tumescent fluid further comprises one or more medications including one or more of: aspirin, low-molecular weight heparin, one or more vasodilators, nitroglycerine, Endothelin A receptor antagonist, folic acid, angiotensin II receptor antagonist, Spermine/NO, Losartan, Perilyl alcohol, Superoxide dismutase, Antitissue factor antibody, Verapamil, Ursolic acid, Rapamycin, Azathioprin, Paclitaxel, C-type natriuretic peptide, Leoligin, Papaverine, platelet rich plasma and stem cells.

**21.** The minimally invasive method of claim **17**, wherein the vascular target is hydrodissected from the surrounding tissues using one or more needles, and wherein the inserting and injection steps are successively performed for each of a plurality of portions of a length of the vascular target to cause dissection the respective portion of the length of the vascular target from the surrounding tissues.

**22.** The minimally invasive method of claim **17**, wherein the inserting and injecting steps are performed under one or more of: (1) ultrasound guidance for visualizing the one of the needle and the hydrodissector and (2) direct vision of the one of the needle and the hydrodissector using an image capturing device provided on or in proximity with the one of the needle and the hydrodissector.

**23.** The minimally invasive method of claim **22**, wherein the vascular target is hydrodissected using the hydrodissector and the direct vision of the hydrodissector is obtained by capturing live images using the image capturing device provided at the tip of the hydrodissector.

**24.** The minimally invasive method of claim **17**, further comprising, before performing the inserting and injecting steps:

making an incision in a patient's extremity; and positioning a barrier with an access port through the incision so as to cover and seal the incision, wherein the inserting step comprises inserting the one of the needle and the hydrodissector through the access port into the predetermined position adjacent the vascular target to be dissected from the surrounding tissues.

**25.** The minimally invasive method of claim **24**, wherein: the barrier is formed from fluid-tight material and comprises one of a diaphragm and a tissue occluder, and the access port comprises a fluid-tight one way valve.

**26.** A surgical bypass method comprising:

the minimally invasive method of claim **17**; harvesting the hydrodissected vascular target by exposing the hydrodissected vascular target, dividing side branches of the hydrodissected vascular target and dividing proximal and distal ends of the hydrodissected vascular target; and

using harvested vascular target for bypass surgery.

**27.** The bypass surgical method of claim **26**, wherein the harvesting step further comprises lifting the hydrodissected vascular target after exposing the hydrodissected vascular target and prior to dividing the side branches.

**28.** An ambulatory selective varicose vein ablation method, wherein the vascular target is a great saphenous vein (GSV), the method comprising:

the minimally invasive method of claim **17**; exposing the hydrodissected GSV; and ligating incompetent perforator and varicosed vein side branches.

**29.** The ambulatory selective varicose vein ablation method of claim **28**, further comprising applying drug eluting stents to the hydrodissected GSV and ligated vein side branches for delivering one or more of drug therapy, stem cell therapy and gene therapy to the GSV. 5

**30.** A hydrodissector for hydrodissecting a vascular target, the hydrodissector comprising:

a handle;

a shaft extending from the handle at an angle and including a tapered tip at a distal end thereof; 10

at least one port provided at the tapered tip and configured to be coupled to a fluid supply and to eject fluid from the tapered tip into the space between the vascular target and surrounding tissues to dissect the vascular target from the surrounding tissues, the at least one port being sized to provide sufficient pressure and velocity 15

to dissect the vascular target from the surrounding tissues,

wherein the length of the shaft is configured for insertion 20

into an incision to atraumatically hydrodissect the

vascular target from the surrounding tissues, and

wherein the shaft is configured to accommodate an image capturing assembly adjacent the tapered tip to provide direct visualization of the vascular target during hydrodissection. 25

**31.** The hydrodissector in accordance with claim **30**, wherein the tapered tip of the shaft is transparent so as to allow direct viewing therethrough.

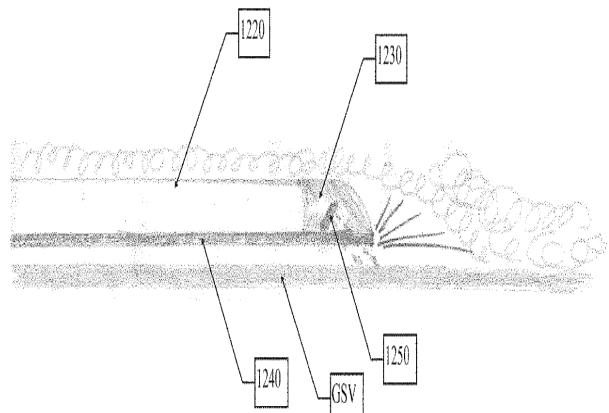
**32.** The hydrodissector in accordance with claim **30**, wherein the size of an opening in the port is between 30 0.01625 inches and 0.06 inches in diameter.

\* \* \* \* \*

专利名称(译)	微创无接触 ( MINT ) 程序 , 用于收集大隐静脉 ( GSV ) 以及静脉水解剖器和牵开器 , 以在MINT程序中使用		
公开(公告)号	<a href="#">US10687793</a>	公开(公告)日	2020-06-23
申请号	US16/039115	申请日	2018-07-18
[标]申请(专利权)人(译)	OBP 医学公司		
申请(专利权)人(译)	OBP医疗法人		
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发明人	GALLAGHER, JOHN SWIFT, JEFFREY RALPH MCCONNELL, DOUGLAS SWIFT, JASON		
IPC分类号	A61B17/00 A61B17/3203 A61B17/02 A61B90/30 A61B17/32 A61B90/00		
CPC分类号	A61B17/00008 A61B17/02 A61B90/30 A61B17/0218 A61B17/320016 A61B17/3203 A61B2217/007 A61B2017/320056 A61B2017/320044 A61B90/361 A61B2017/32035 A61B2017/320024 A61B2090 /306 A61B2090/309		
优先权	62/533714 2017-07-18 US 62/640892 2018-03-09 US 62/683376 2018-06-11 US		
其他公开文献	<a href="#">US20190021709A1</a>		
外部链接	<a href="#">Espacenet</a>		

### 摘要(译)

一种用于解剖静脉的水解剖器 , 该水解剖器包括手柄 , 从手柄以一定角度延伸并在其远端包括尖端的轴 , 至少一个端口构造为联接至用于在大致上供给流体的流体源。固定在轴的远端的恒定压力 , 以及图像捕获组件 , 该组件可在水解剖时直接显示静脉。还介绍了使用水解剖仪从周围组织解剖大隐静脉 ( GSV ) 的微创方法。



• Side view of dissector in situ hydrodissecting connective tissue off of underlying GSV