



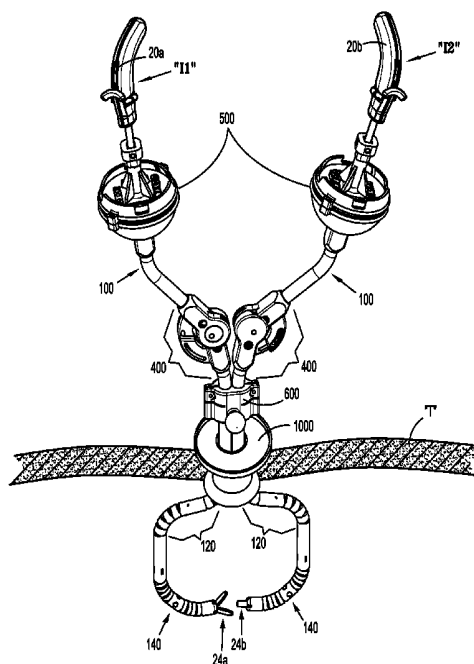
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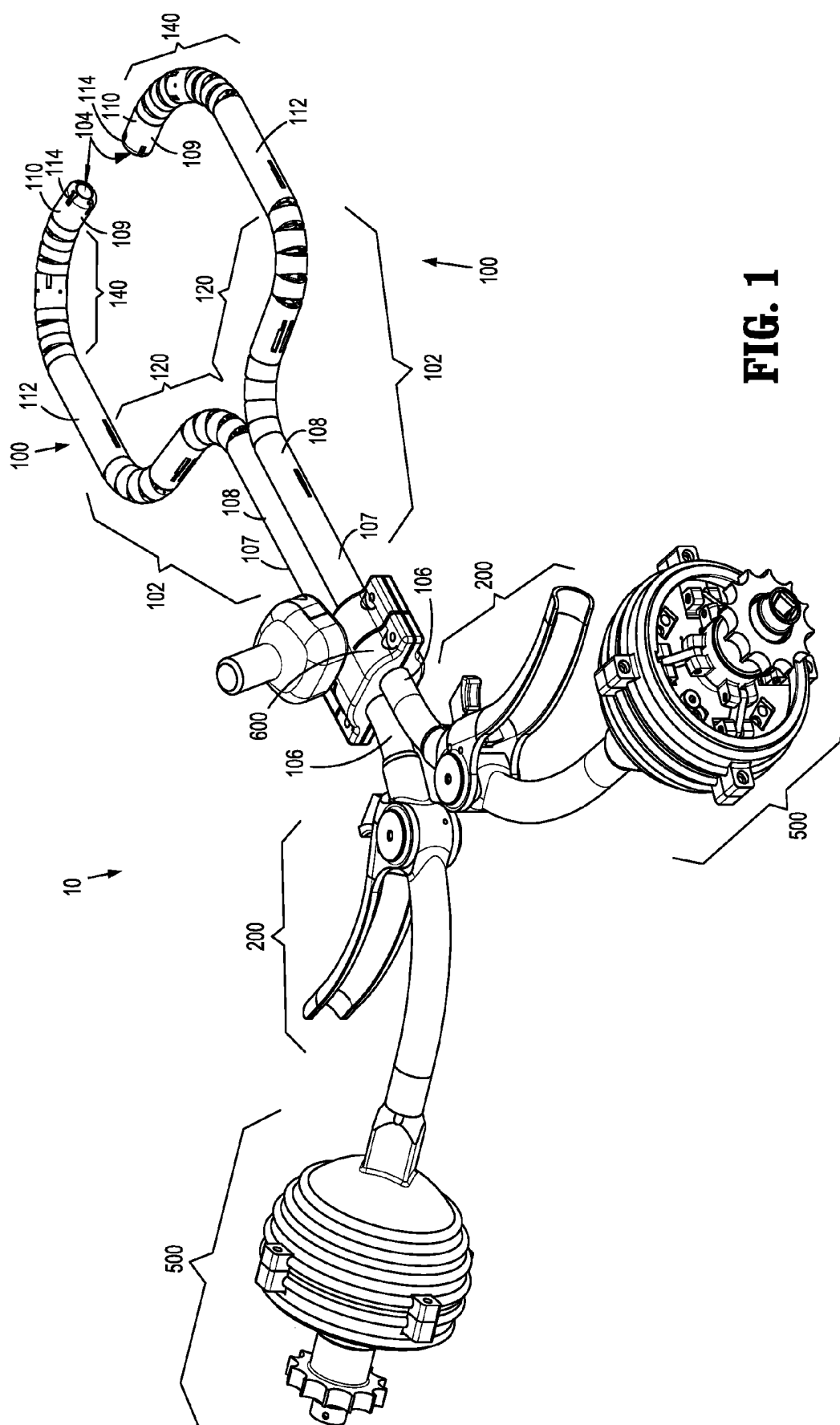
(19) **United States**(12) **Patent Application Publication**  
**Malkowski et al.**(10) **Pub. No.: US 2017/0296279 A1**(43) **Pub. Date: Oct. 19, 2017**(54) **ARTICULATING SURGICAL ACCESS  
SYSTEM FOR LAPAROSCOPIC SURGERY***A61B 17/34* (2006.01)*A61B 17/34* (2006.01)*A61B 17/34* (2006.01)*A61B 17/00* (2006.01)(71) Applicant: **Covidien LP**, Mansfield, MA (US)(72) Inventors: **Jaroslav T. Malkowski**, Trumbull, CT  
(US); **Eric Taylor**, East Hampton, CT  
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NY (US)(52) **U.S. Cl.**CPC ..... *A61B 34/71* (2016.02); *A61B 17/3423*(2013.01); *A61B 34/30* (2016.02); *A61B**17/0218* (2013.01); *A61B 17/3421* (2013.01);*A61B 2017/2906* (2013.01); *A61B 2017/00327*(2013.01); *A61B 17/3431* (2013.01); *A61B**2034/306* (2016.02); *A61B 2034/302*(2016.02); *A61B 2017/2908* (2013.01); *A61B**2017/3445* (2013.01); *A61B 2017/3447*(2013.01); *A61B 2017/347* (2013.01); *A61B**2017/00314* (2013.01)(21) Appl. No.: **15/640,811**(22) Filed: **Jul. 3, 2017****Related U.S. Application Data**(60) Continuation of application No. 15/005,048, filed on  
Jan. 25, 2016, now Pat. No. 9,707,046, which is a  
division of application No. 13/412,079, filed on Mar.  
5, 2012, now Pat. No. 9,259,240.(60) Provisional application No. 61/469,001, filed on Mar.  
29, 2011.**Publication Classification**(51) **Int. Cl.***A61B 34/00* (2006.01)*A61B 34/30* (2006.01)*A61B 17/02* (2006.01)*A61B 17/34* (2006.01)*A61B 17/34* (2006.01)*A61B 17/29* (2006.01)*A61B 17/00* (2006.01)*A61B 17/34* (2006.01)*A61B 34/30* (2006.01)*A61B 34/30* (2006.01)*A61B 17/29* (2006.01)

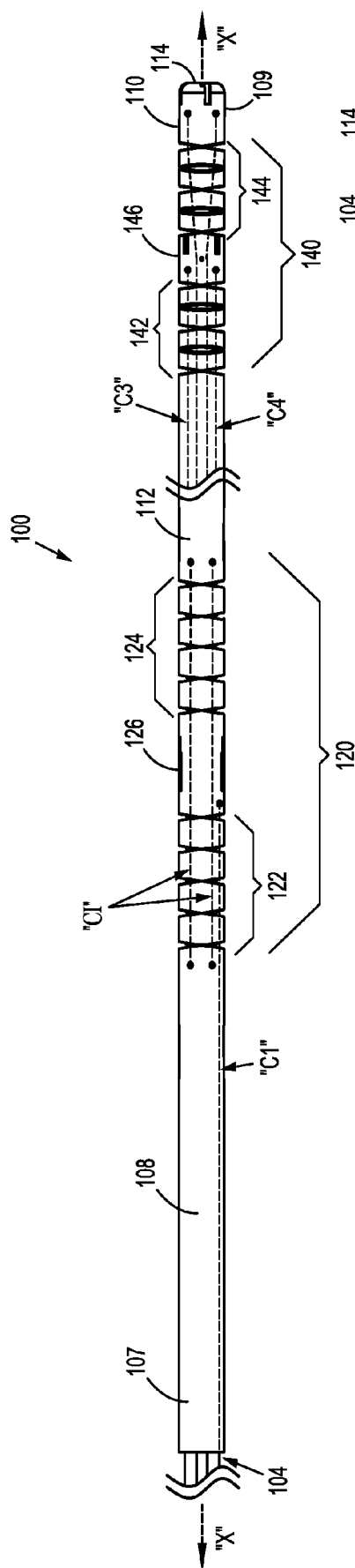
(57)

**ABSTRACT**

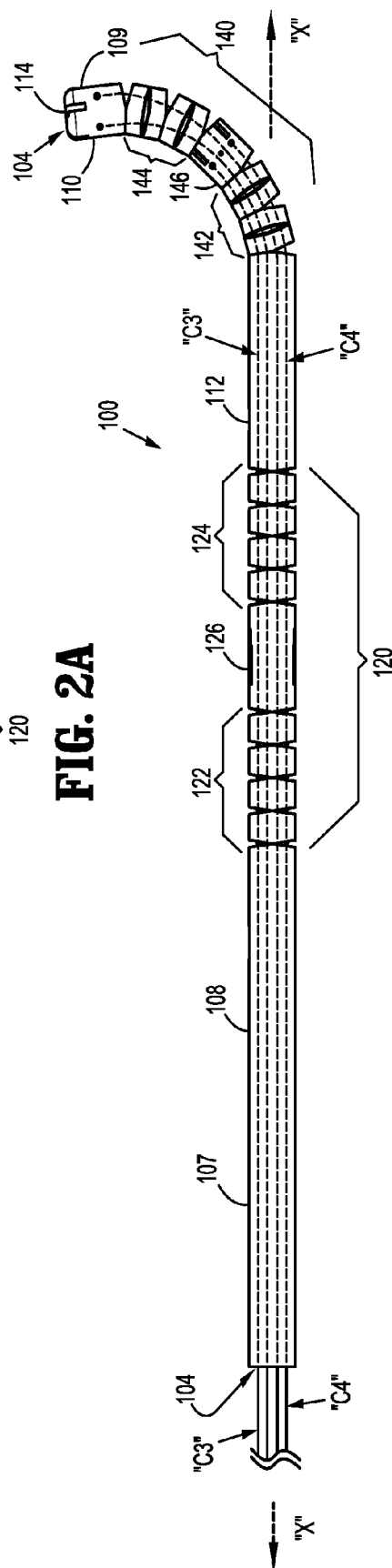
A surgical system includes one or more arms defining a passageway therethrough. The arm includes a proximal portion configured for positioning externally of a patient's body and a distal portion configured for positioning within an internal body cavity. The distal portion includes first and second articulatable segments spaced apart from one another and capable of independent articulation between a substantially straight configuration and an articulated configuration. A first articulation assembly is coupled to the proximal portion of the one arm and is transitionable between a first state and a second state for articulating the first articulatable segment between the substantially straight configuration and the articulated configuration. A second articulation assembly is coupled to the proximal portion of the arm and is configured to move between a plurality of positions for articulating the second articulatable segment between the substantially straight configuration and the articulated configuration.



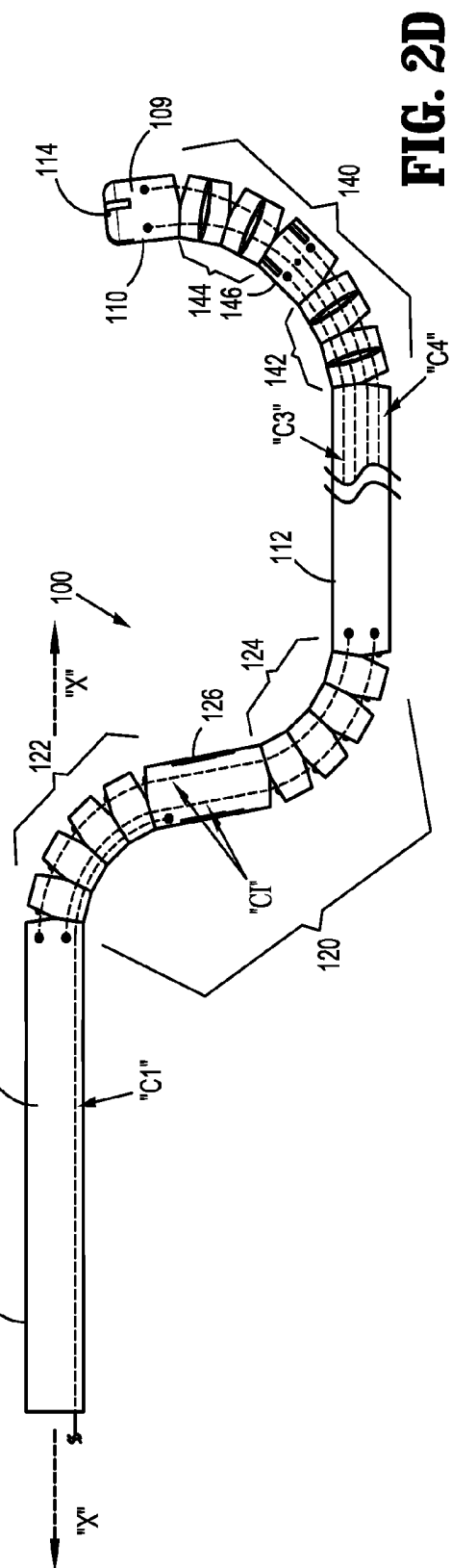
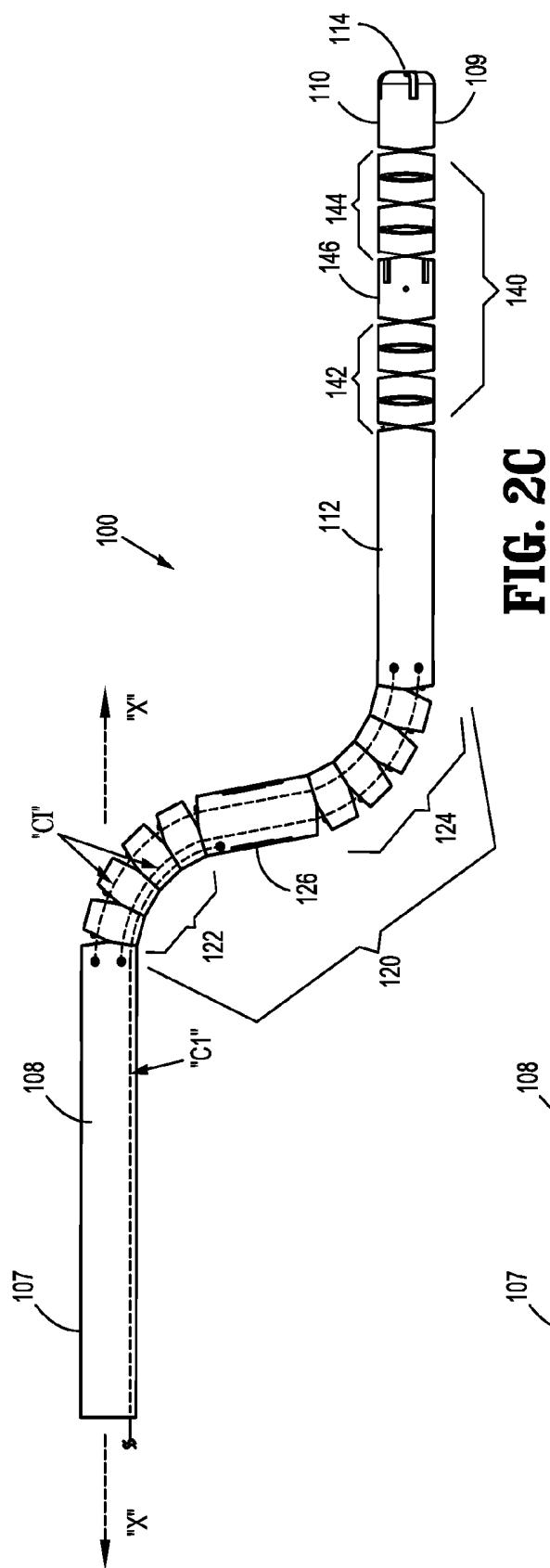


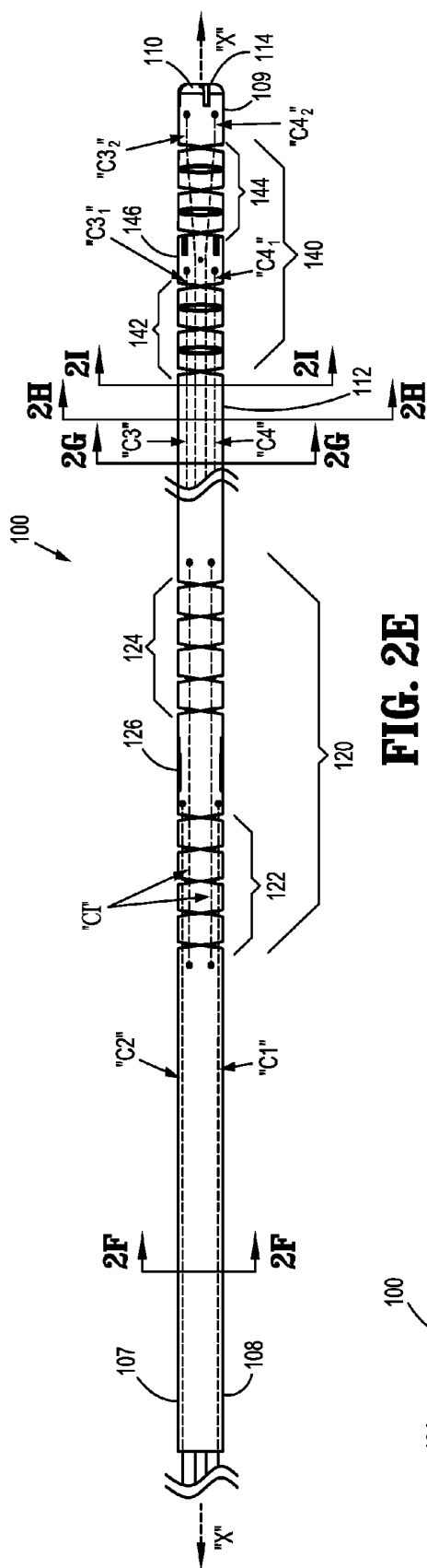


**FIG. 2A**

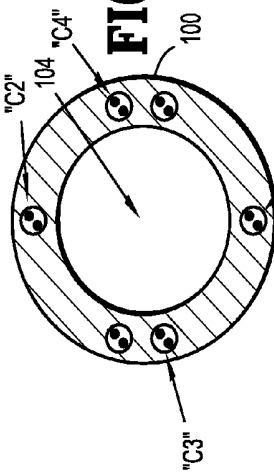


**FIG. 2B**

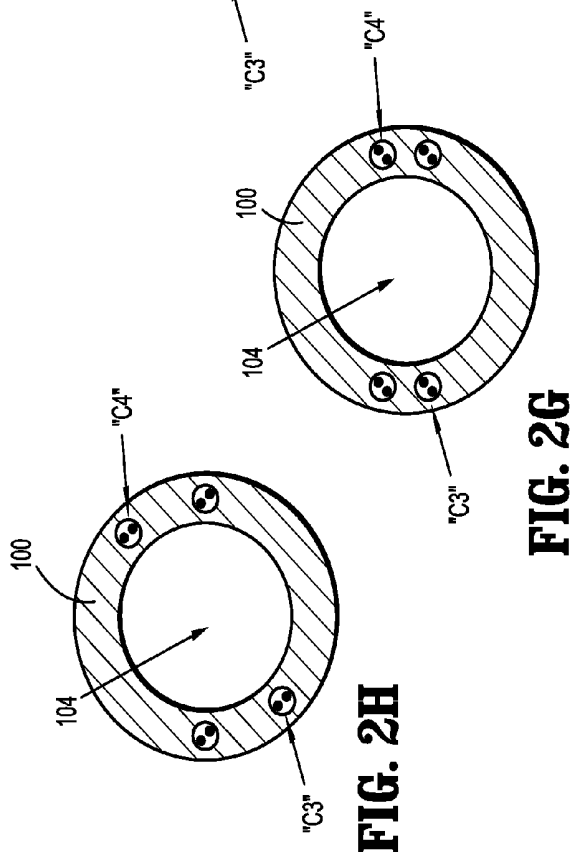




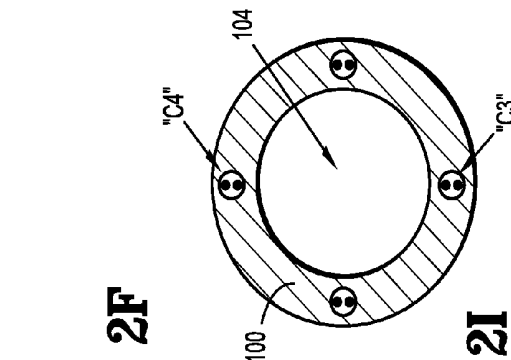
**FIG. 2E**



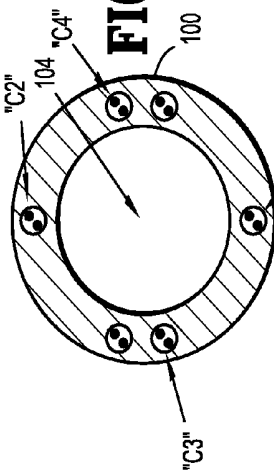
**FIG. 2F**



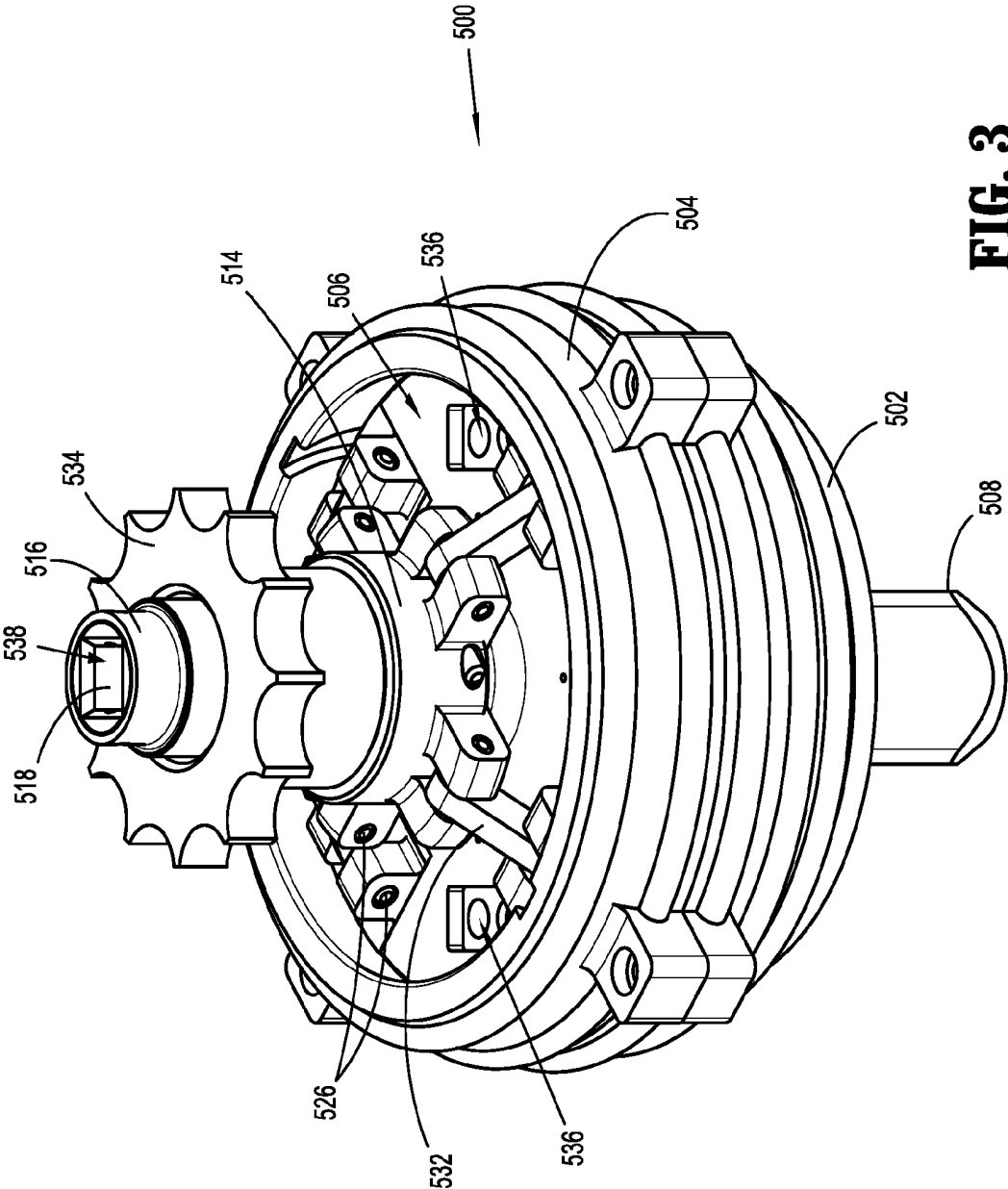
**FIG. 2G**



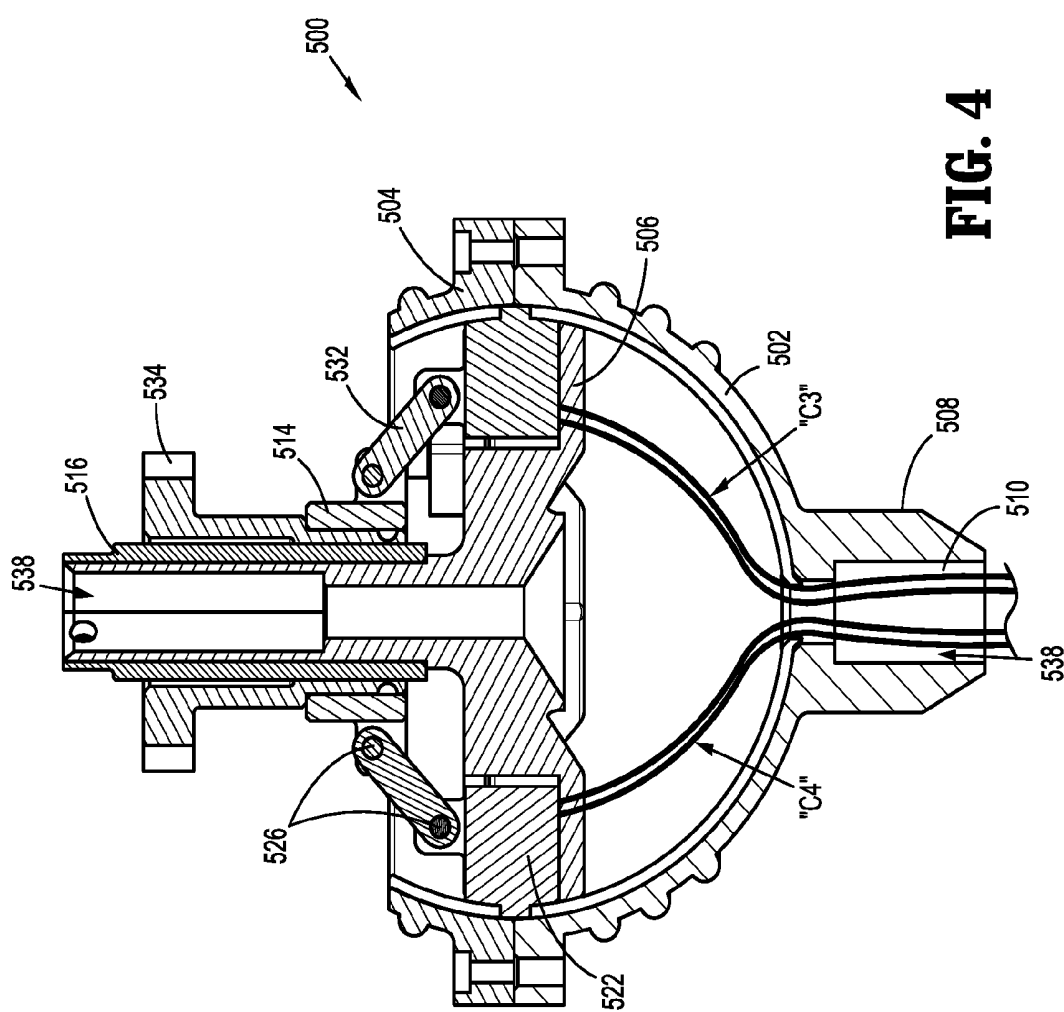
**FIG. 2H**



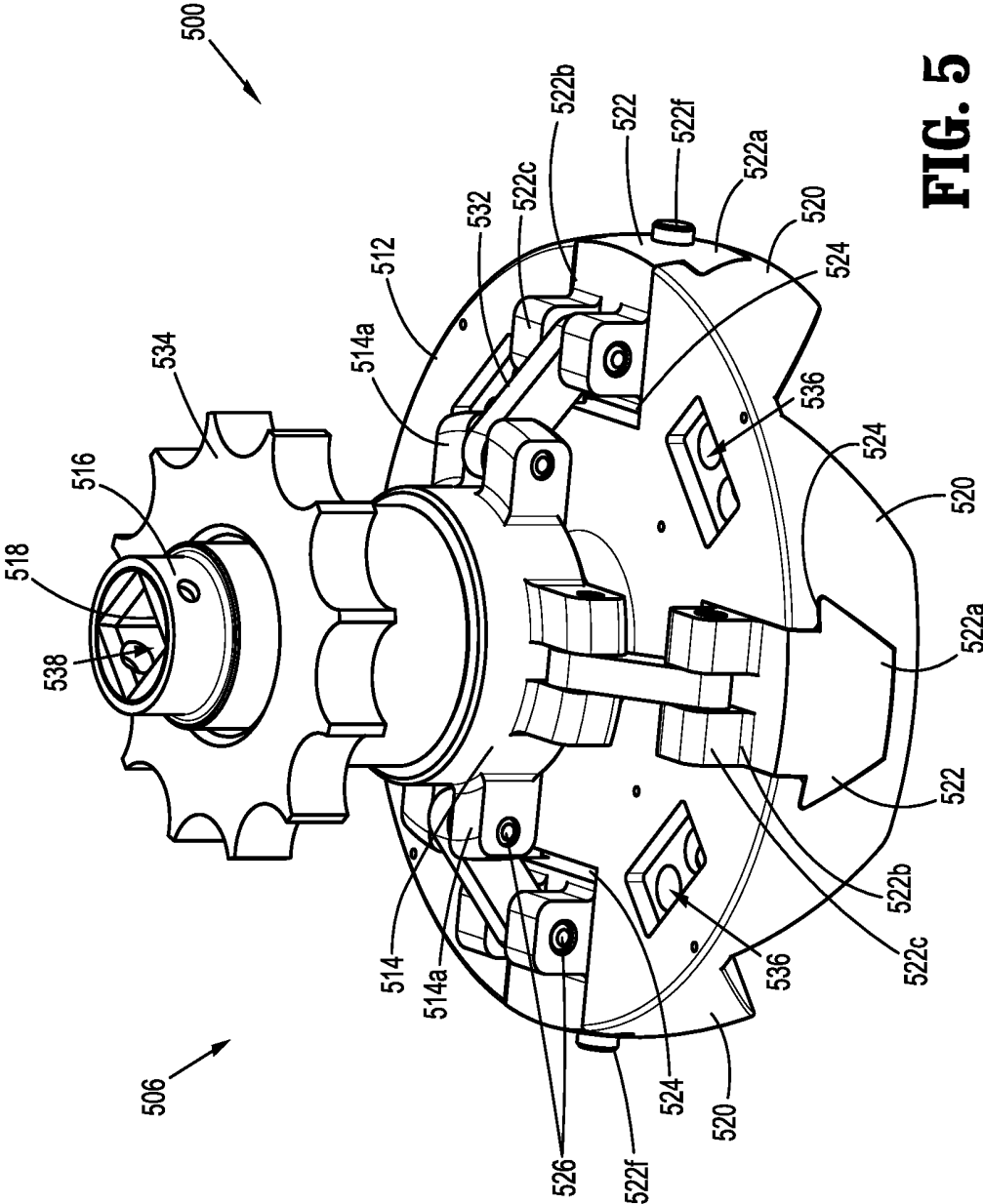
**FIG. 2I**



**FIG. 3**

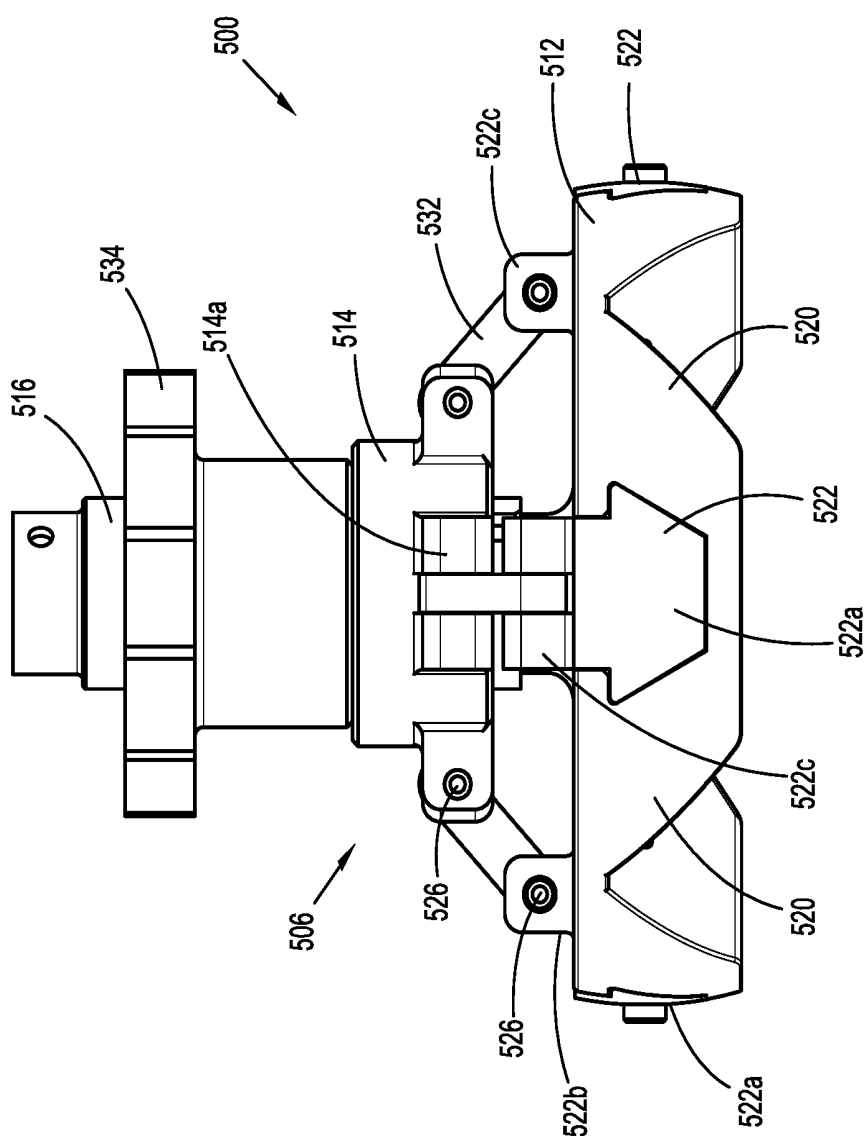


**FIG. 4**

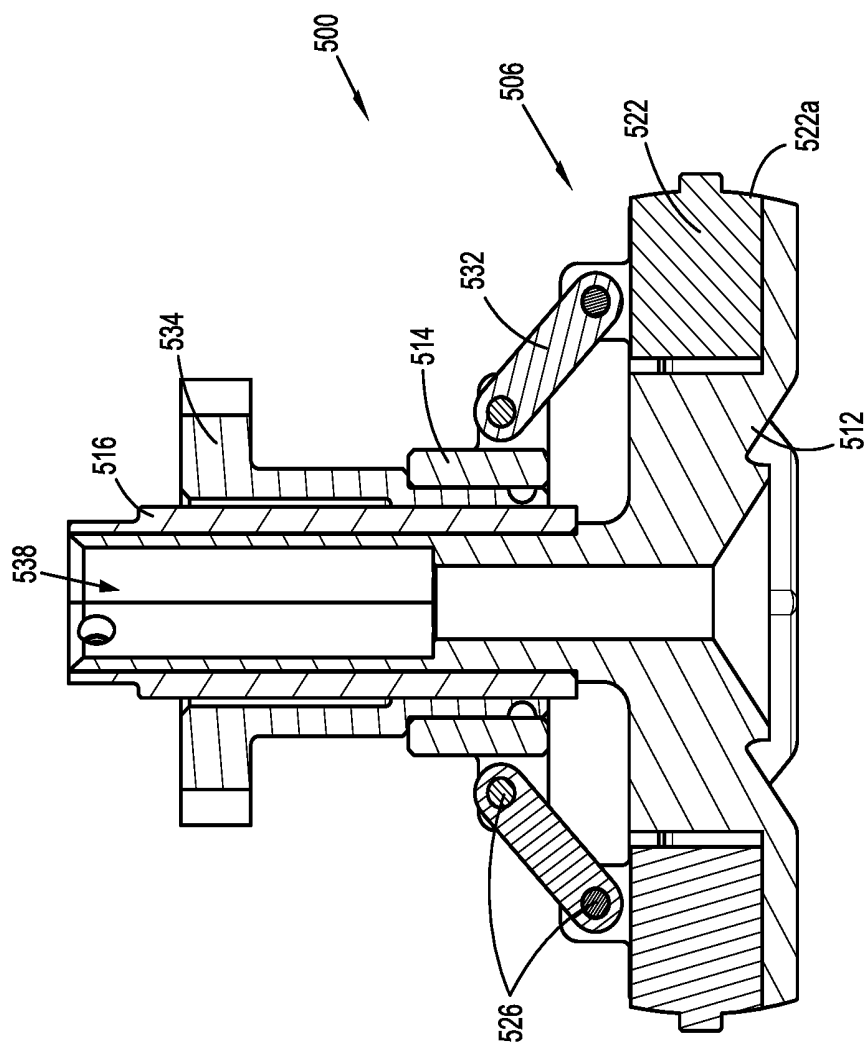


**FIG. 5**

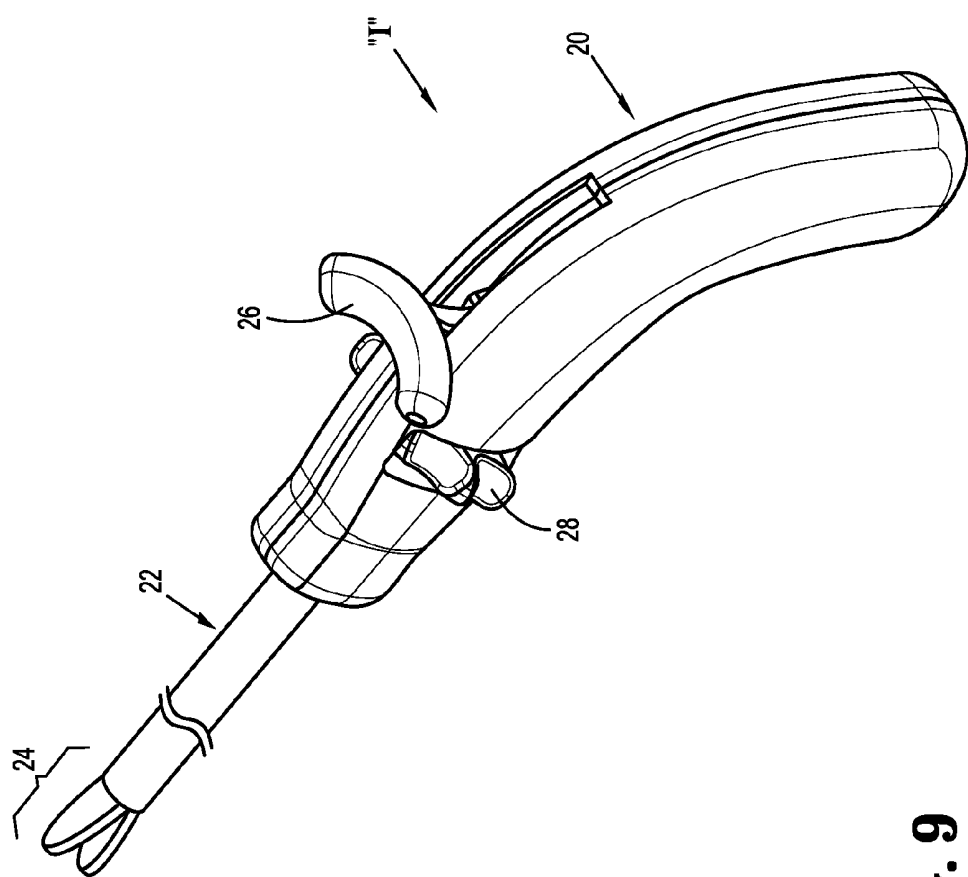




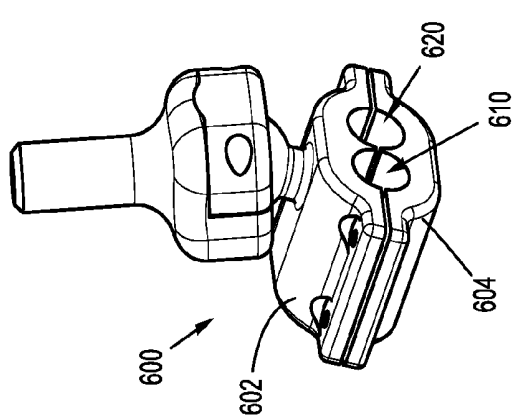
**FIG. 6**



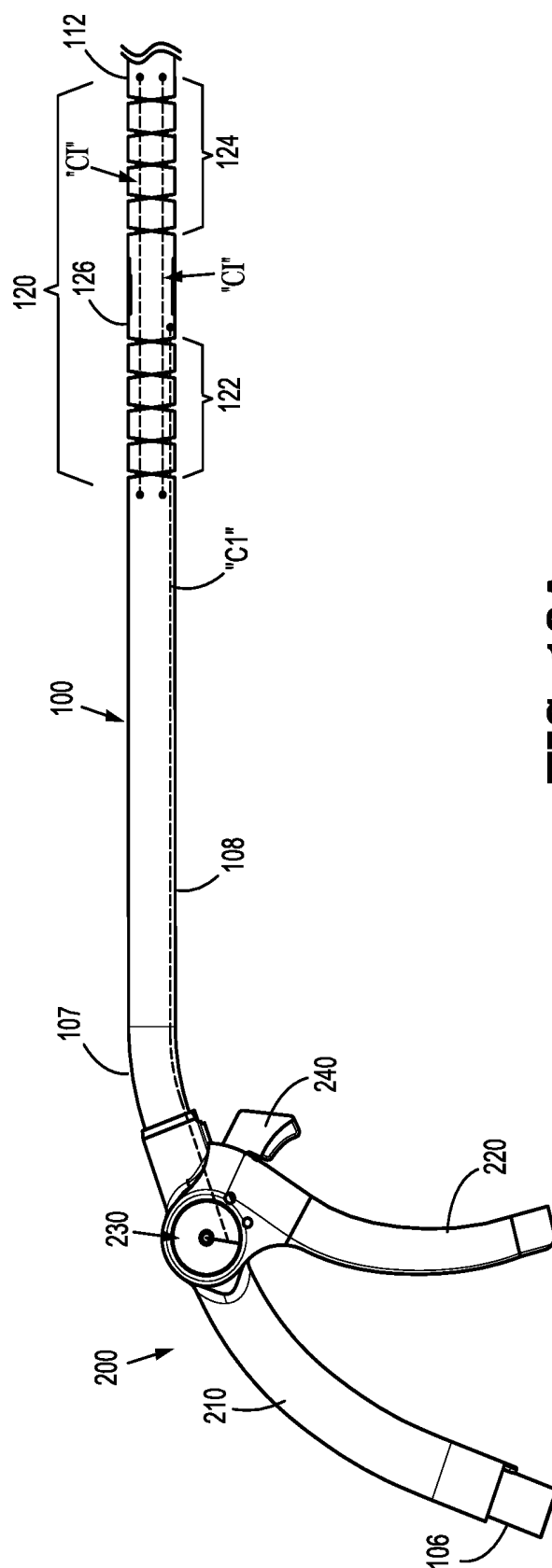
**FIG. 7**

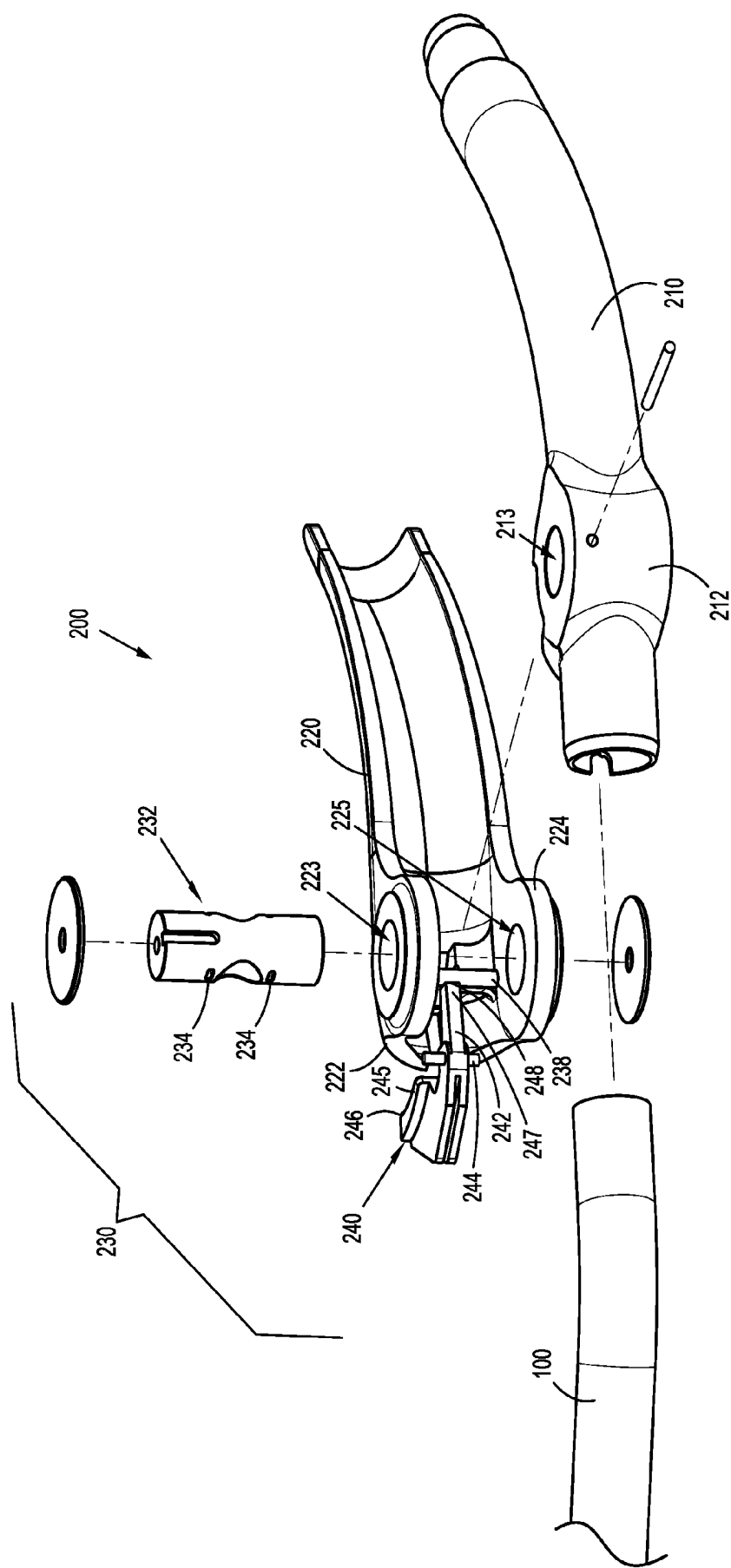


**FIG. 8**

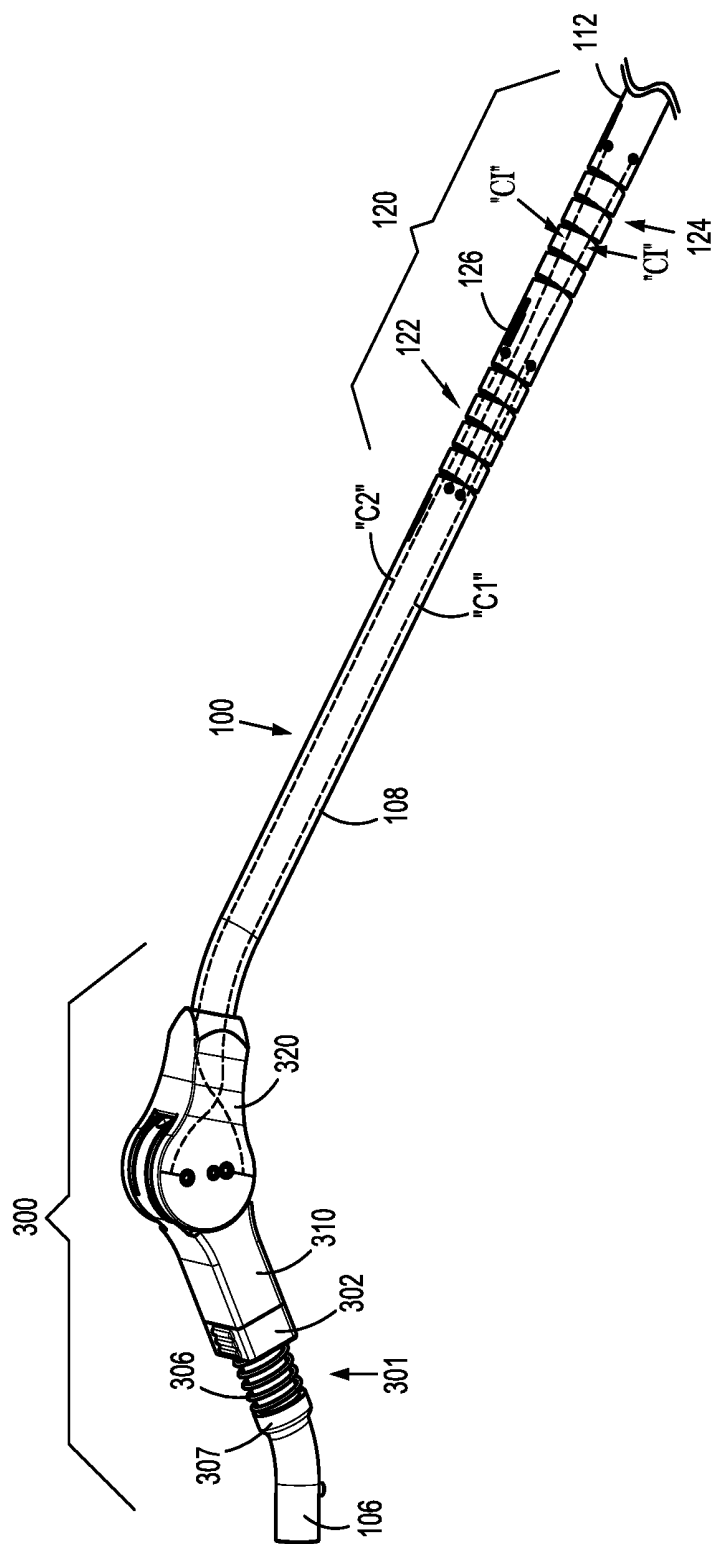


**FIG. 9**

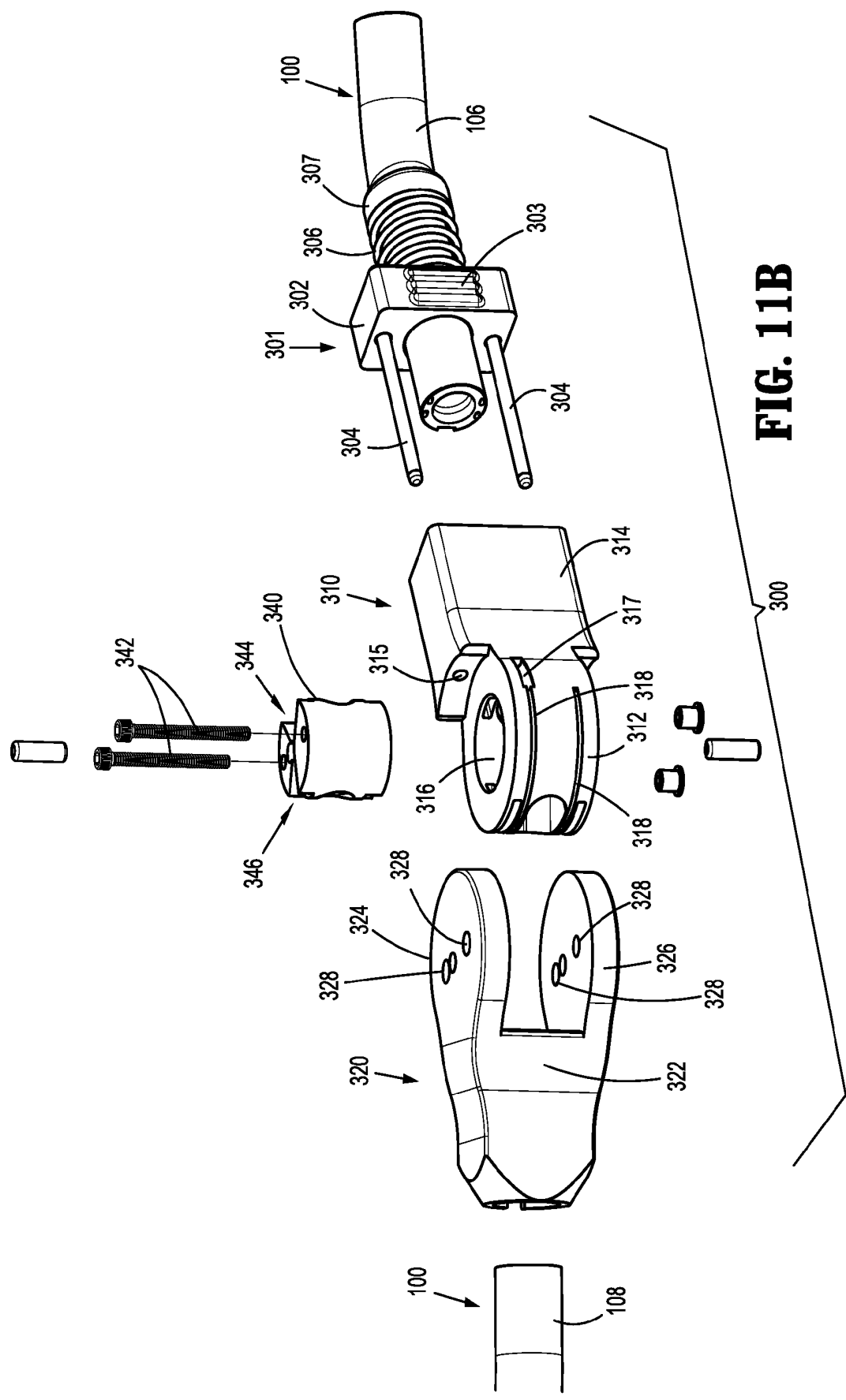




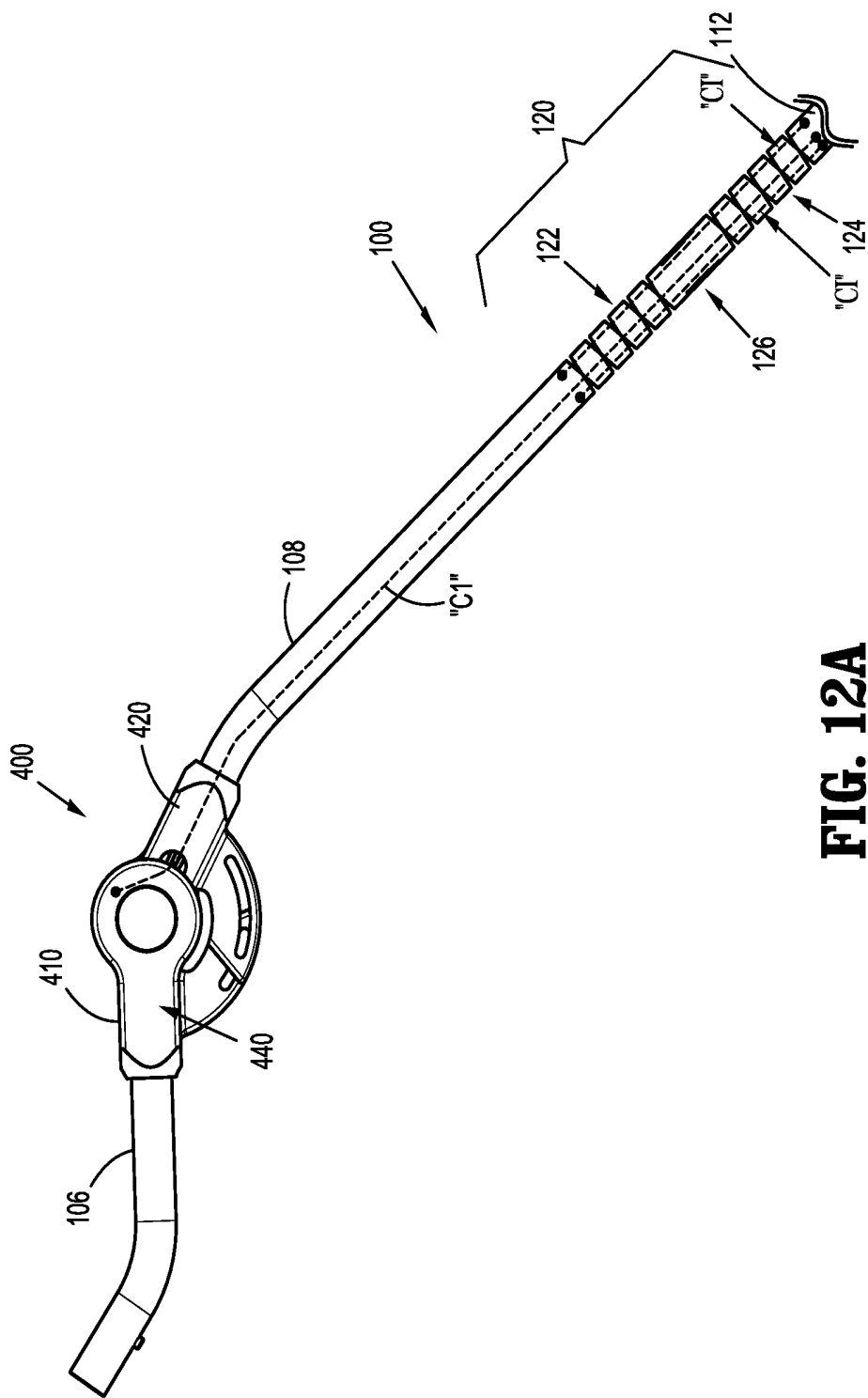
**FIG. 10B**



**FIG. 11A**

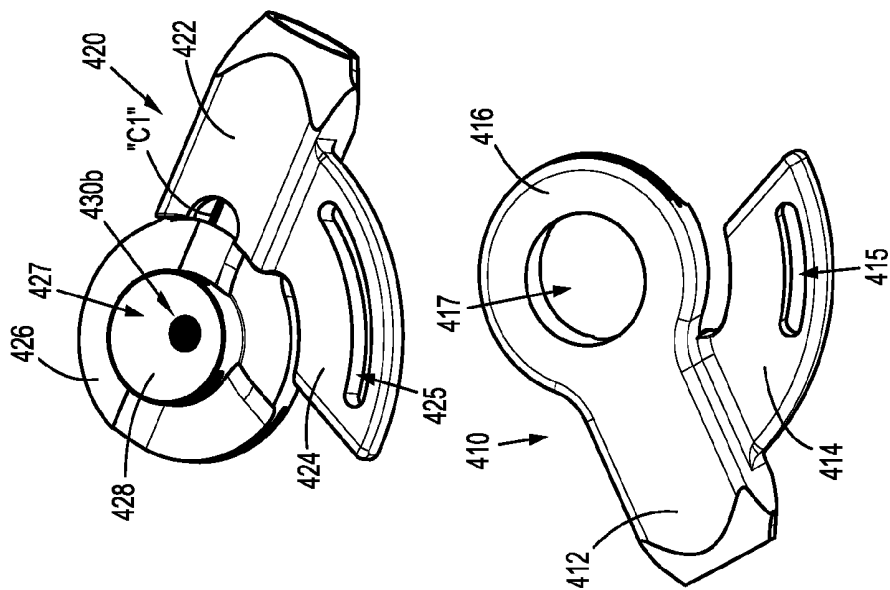


**FIG. 11B**

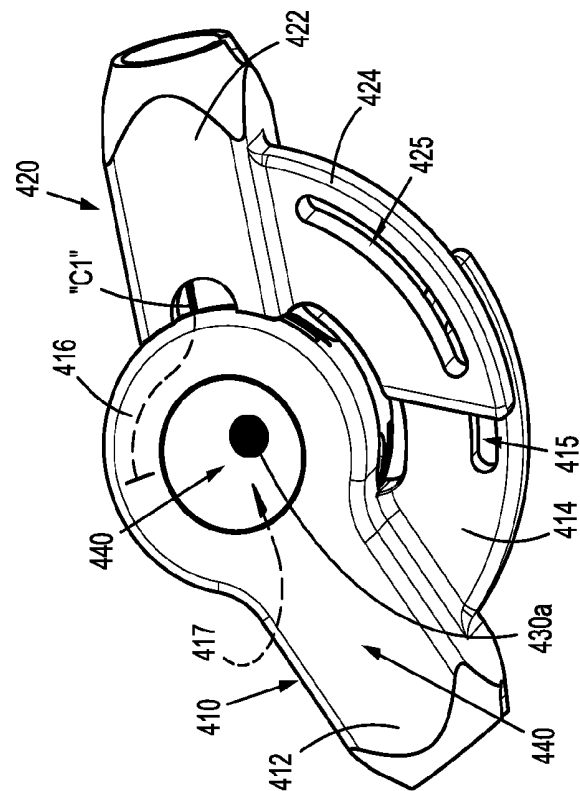


**FIG. 12A**

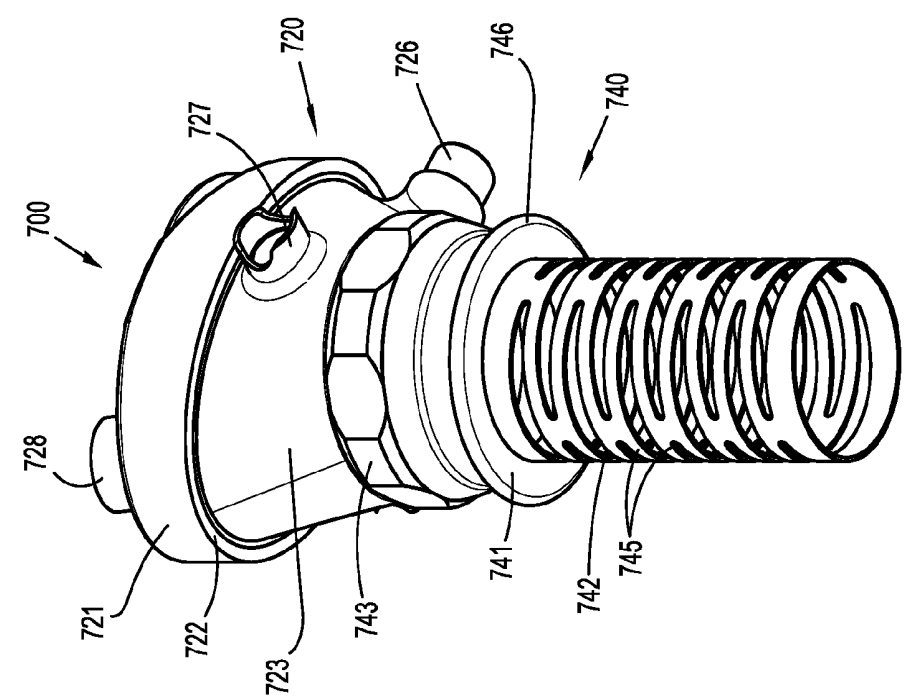




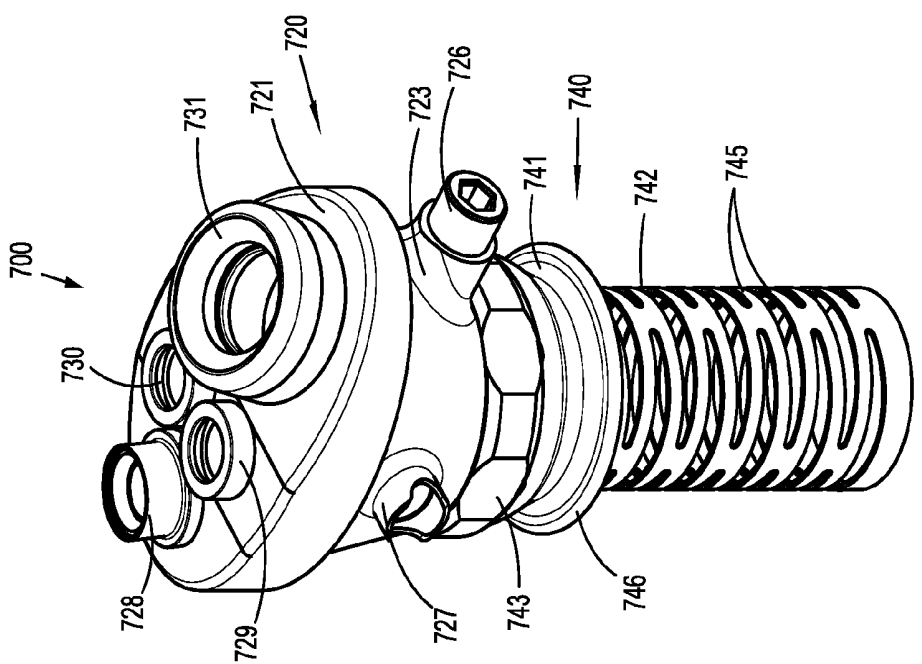
**FIG. 12C**



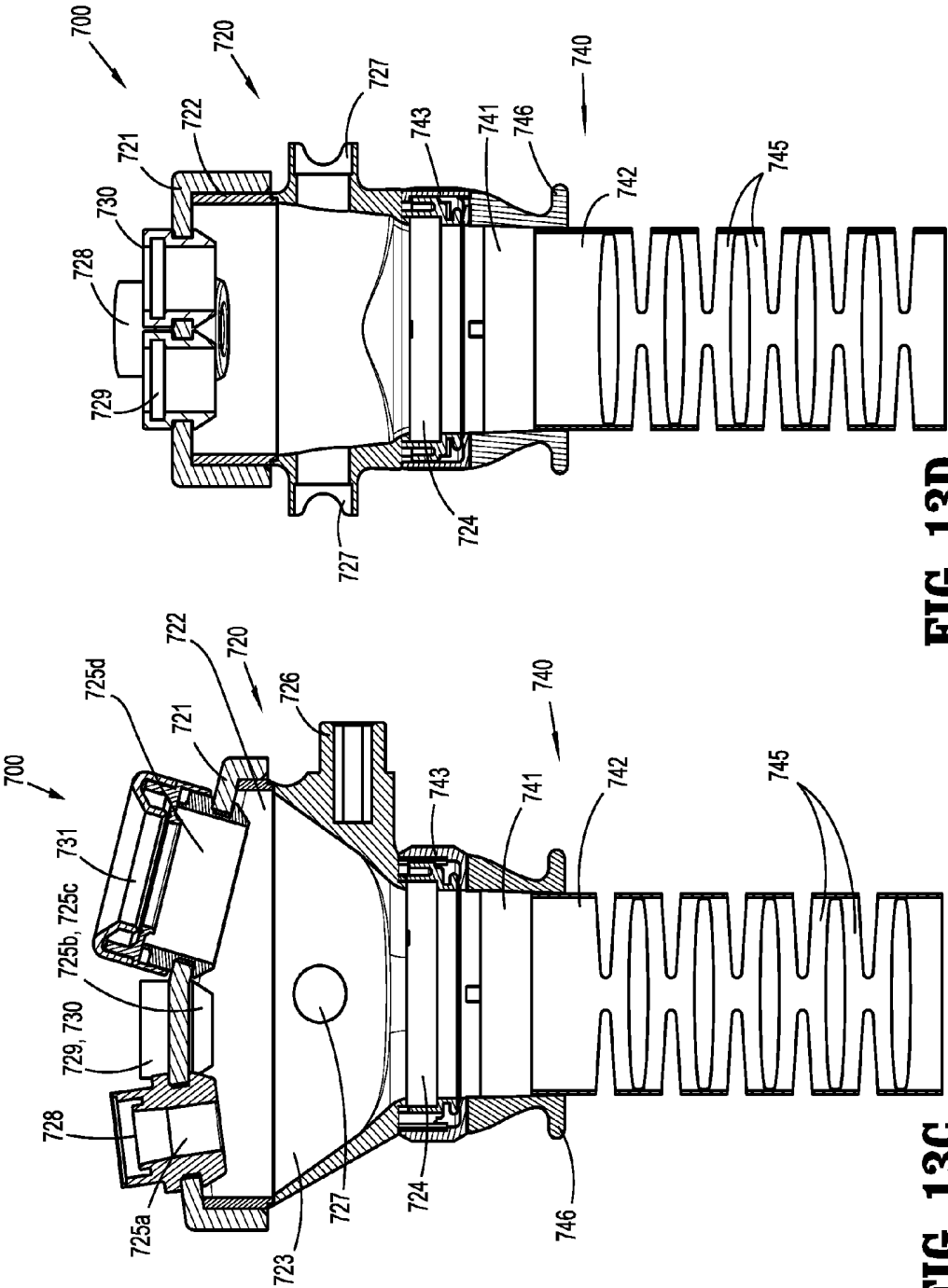
**FIG. 12B**



**FIG. 13A**

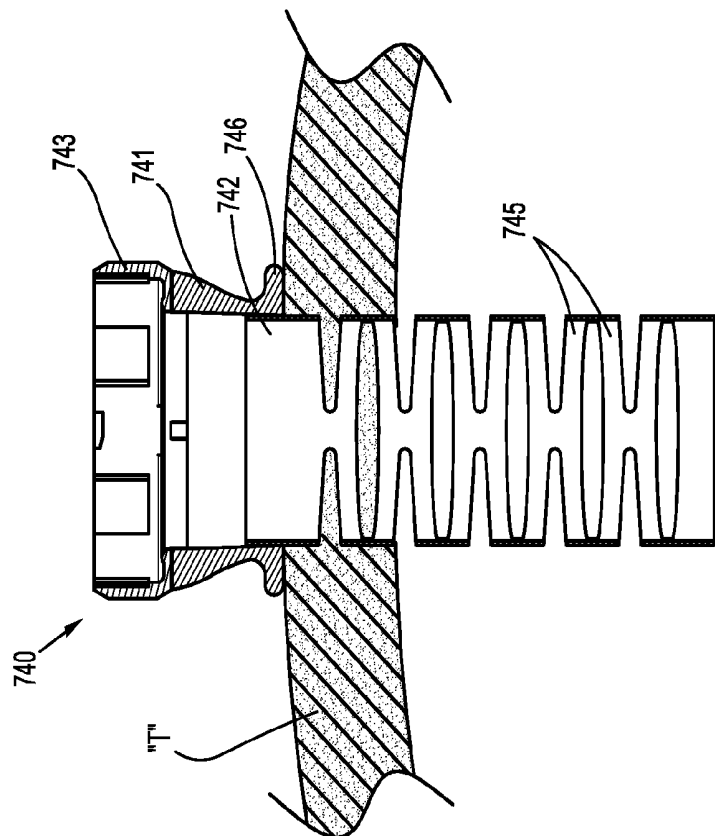


**FIG. 13B**

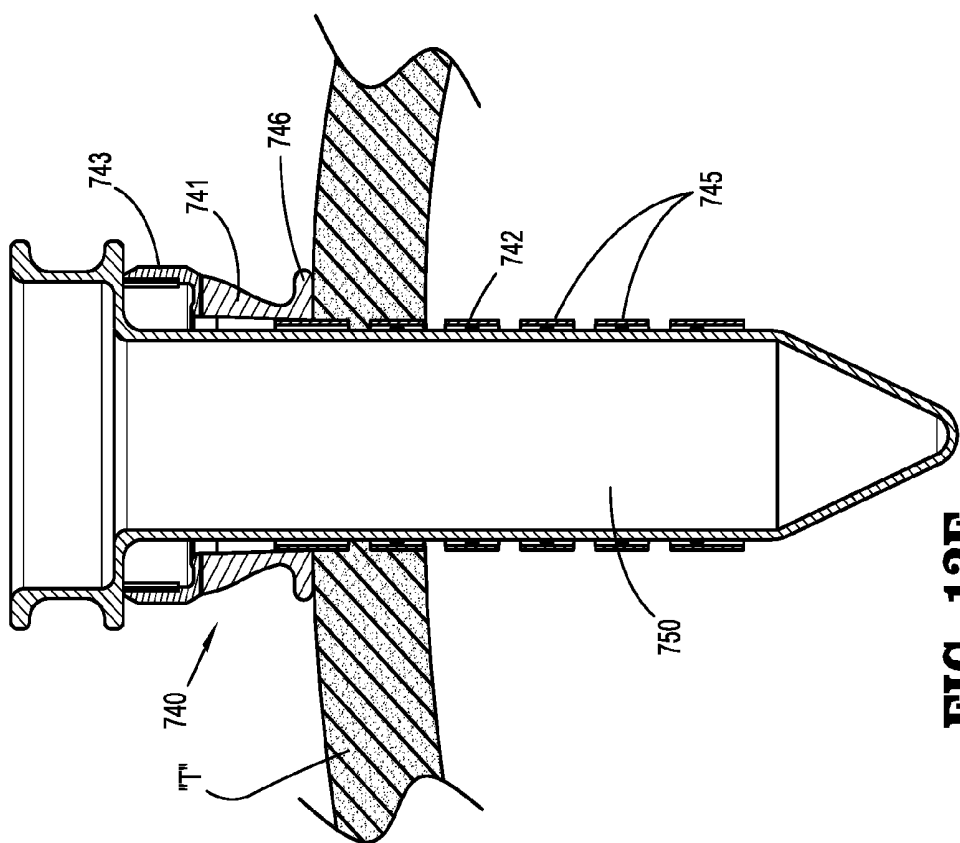


**FIG. 13D**

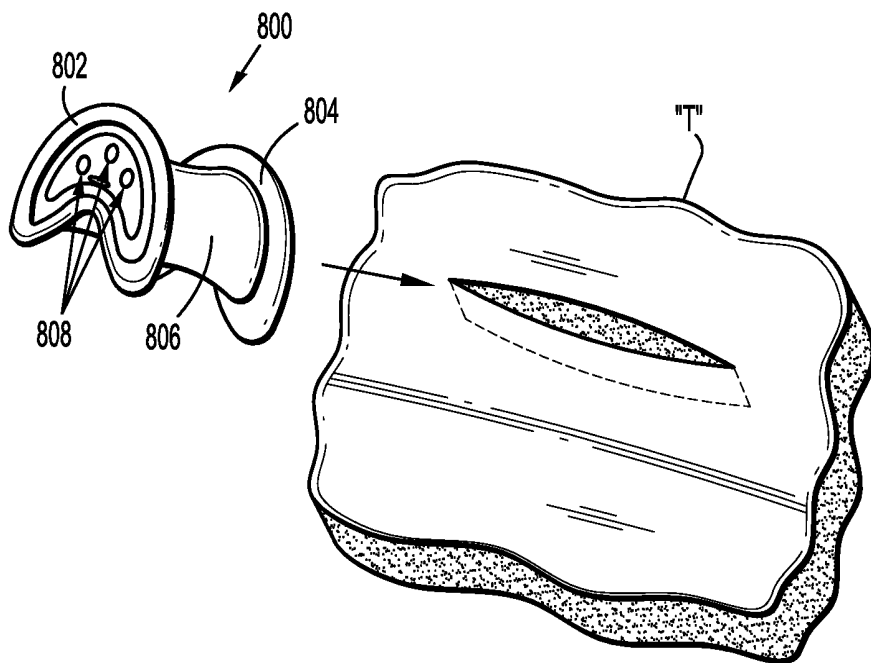
**FIG. 13C**



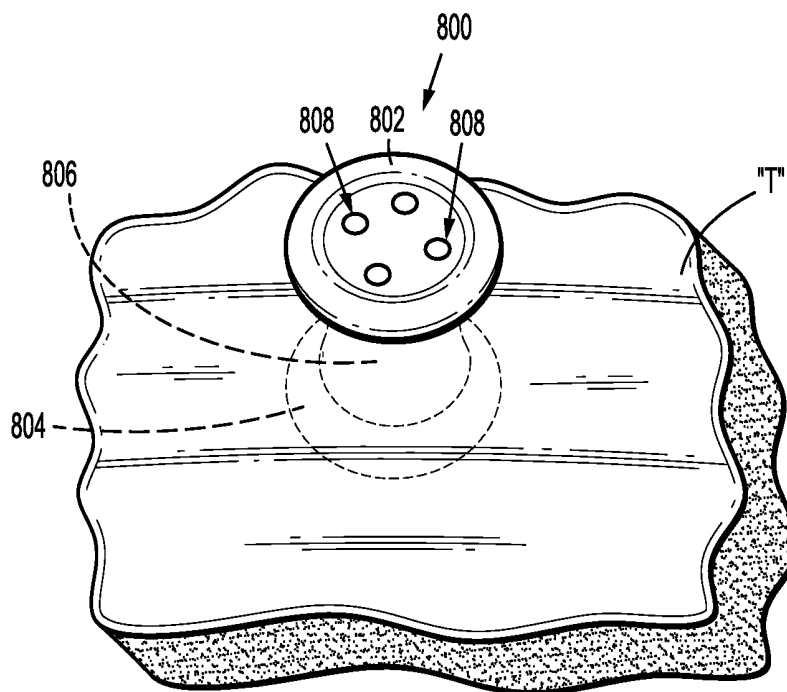
**FIG. 13F**



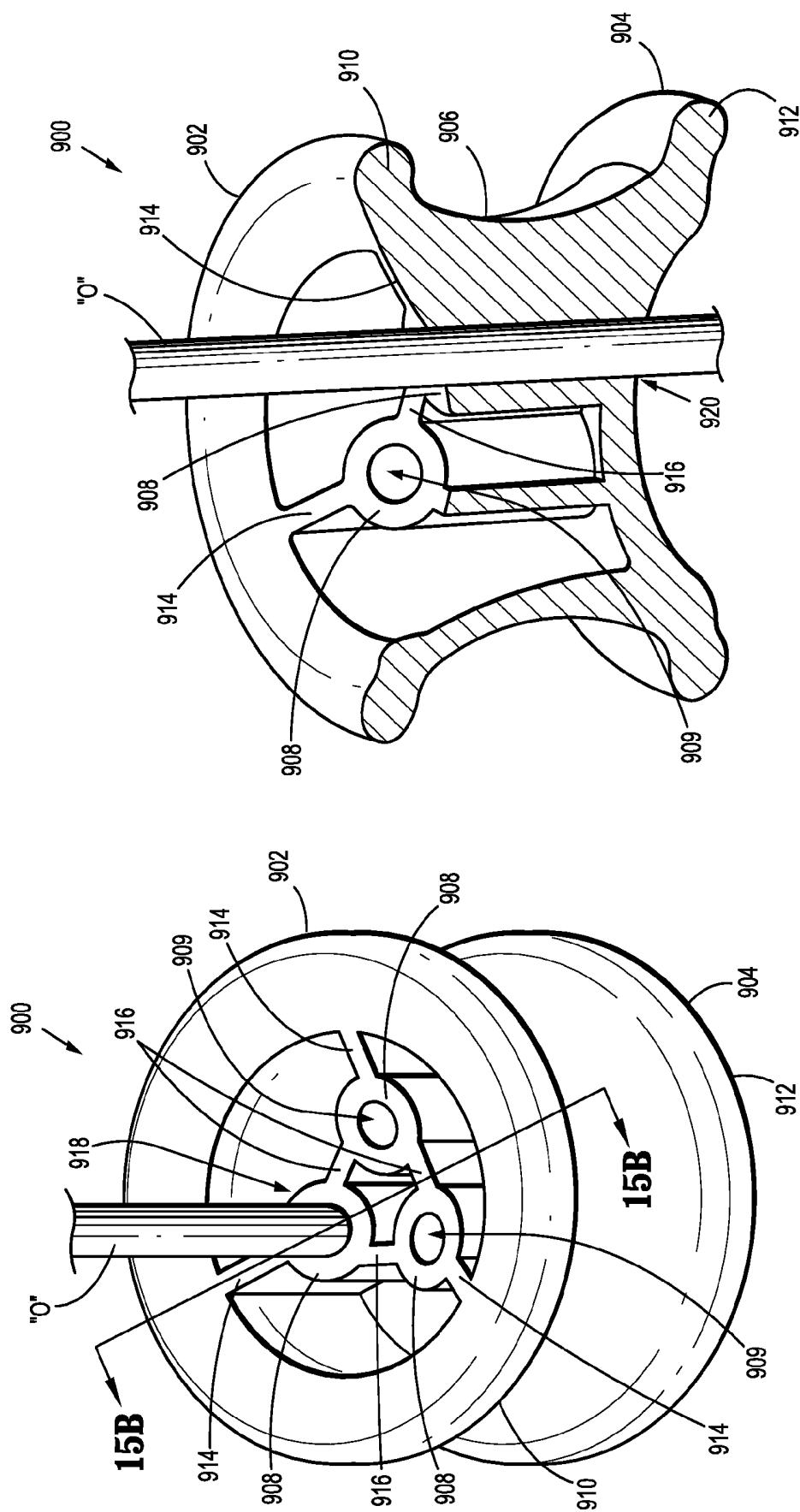
**FIG. 13E**



**FIG. 14A**

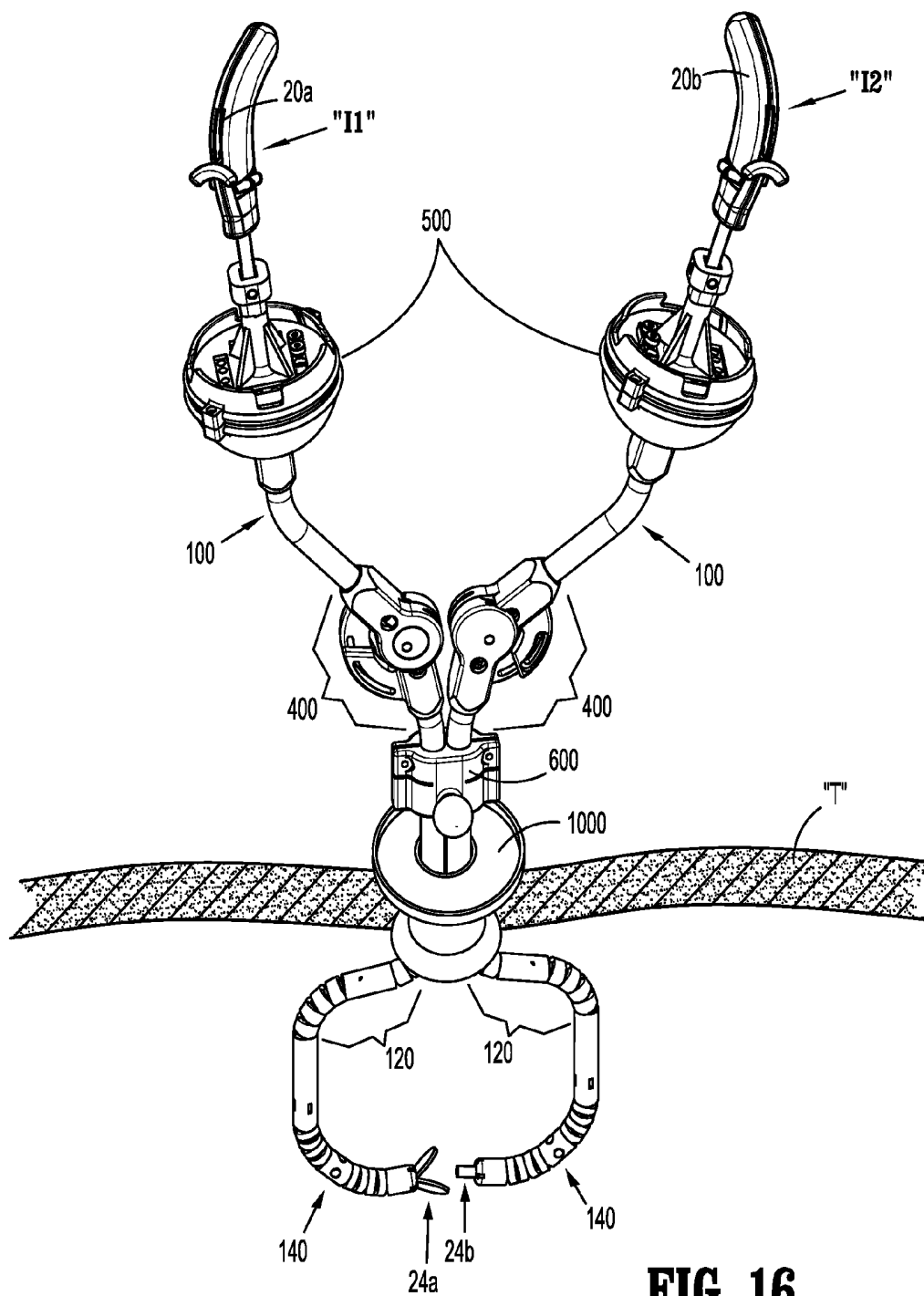


**FIG. 14B**



**FIG. 15B**

**FIG. 15A**



**FIG. 16**

## ARTICULATING SURGICAL ACCESS SYSTEM FOR LAPAROSCOPIC SURGERY

### CROSS-REFERENCE TO RELATED APPLICATIONS

[0001] This application is a Continuation of U.S. patent application Ser. No. 15/005,048 filed Jan. 25, 2016, which is a divisional of U.S. patent application Ser. No. 13/412,079 filed Mar. 5, 2012, now U.S. Pat. No. 9,259,240, which claims the benefit of and priority to U.S. Provisional Patent Application No. 61/469,001 filed on Mar. 29, 2011, the entire disclosure of which is incorporated by reference herein.

### BACKGROUND

#### Technical Field

[0002] The present disclosure relates to a surgical access device, and more particularly, to an articulating surgical access system for use in laparoscopic surgical procedures.

#### Background of Related Art

[0003] In laparoscopic and endoscopic surgical procedures, a small incision or puncture is made in a patient's body, e.g., in the abdomen, to provide an entry point for a surgical access device which is inserted into the incision and facilitates the insertion of instruments used in performing surgical procedures within an internal surgical site. Laparoscopic surgical procedures are advantageous in that, as compared to traditional open surgical procedures, both trauma to the patient and recovery time are reduced due to the relatively small incisions formed through the patient's body. However, since these access incisions are small, only elongated, small diametered instrumentation may be used to access the internal body cavities and organs.

[0004] During such procedures, surgical objects such as surgical access devices, e.g., trocar and cannula assemblies, are inserted into the patient's body through the incision in tissue. In general, prior to the introduction of the surgical object into the patient's body, insufflation gases are used to enlarge the area surrounding the target surgical site to create a larger, more accessible work area. The surgeon is then able to perform the procedure within the abdominal cavity by manipulating the instruments that have been extended through the access devices. The manipulation of such instruments within the internal body is similarly limited by both spatial constraints and the need to maintain the body cavity in an insufflated state.

### SUMMARY

[0005] In accordance with one embodiment of the present disclosure, a surgical system is provided. The surgical system includes one or more arms defining a longitudinal passageway extending therethrough that is configured to receive a surgical instrument therein. The arm(s) includes a proximal portion configured for positioning externally of a patient's body and a distal portion configured for positioning within an internal body cavity. The distal portion includes first and second articlatable segments spaced-apart from one another and capable of independent articulation between a substantially straight configuration and an articulated configuration. A first articulation assembly is coupled to the proximal portion of the arm and is transitionable between a

first state and a second state for articulating the first articlatable segment between the substantially straight configuration and the articulated configuration. A second articulation assembly (different from the first articulation assembly) is coupled to the proximal portion of the arm and is configured to move through a plurality of positions for articulating the second articlatable segment between the substantially straight configuration and the articulated configuration.

[0006] In one embodiment, one or more sets of articulation cables extend from each of the first and second articlatable segments to the first and second articulation assemblies, respectively. The articulation cables are selectively tensionable for articulating the respective articlatable segment from which they extend.

[0007] In another embodiment, the first articulation assembly includes a lever and a base. The lever is movable relative to the base between a spaced-apart position and an approximated position for articulating the first articlatable segment between the substantially straight configuration and the articulated configuration. A locking assembly may also be provided to fix the lever in position relative to the base, thereby fixing the position of the first articlatable segment. Further, the locking assembly may be automatically engaged to lock the lever in position when the lever is moved to the approximated position such that the first articlatable segment is automatically locked in the articulated position.

[0008] In still another embodiment, the first articulation assembly includes first and second components pivotable relative to one another between a substantially aligned position and a substantially transverse position for articulating the first articlatable segment between the substantially straight configuration and the articulated configuration. Further, a locking assembly may be provided. The locking assembly is configured to fix the first and second components in position relative to one another upon pivotable movement of the first and second components to one or more pre-determined positions relative to one another. More specifically, the locking assembly may include a slide block selectively translatable to release the first and second components from fixed position relative to one another.

[0009] In yet another embodiment, an access portal is provided. The access portal is configured for positioning within an incision in tissue and to receive the arm therethrough such that the distal portion of the arm is positioned within the internal body cavity.

[0010] In still yet another embodiment, the second articulation assembly includes a base defining a cavity and a rotatable member movably disposed in the cavity of the base. The rotatable member is movable relative to the base to articulate the second articlatable segment between the substantially straight and articulated configurations. The rotatable member is further transitionable between an unlocked state, wherein the rotatable member is movable within the cavity of the base relative to the base, and a locked state, wherein an orientation of the rotatable member is fixed relative to the base.

[0011] In another embodiment, the rotatable member includes a port extending therethrough in communication with the longitudinal passageway of the arm. The port is configured to receive the surgical instrument therein. In such an embodiment, movement of the surgical instrument disposed within the port of the rotatable member relative to the



base articulates the second articulatable segment between the substantially straight and articulated configurations.

#### BRIEF DESCRIPTION OF THE DRAWINGS

[0012] Various embodiments of the present disclosure are described hereinbelow with reference to the drawings, wherein:

[0013] FIG. 1 is a top, perspective view of a surgical access system provided in accordance with one embodiment of the present disclosure;

[0014] FIG. 2A is a side view of a cannula arm configured for use with the surgical access system of FIG. 1 disposed in a first configuration;

[0015] FIG. 2B is a side view of the cannula arm of FIG. 2A disposed in a second configuration;

[0016] FIG. 2C is a side view of the cannula arm of FIG. 2A disposed in a third configuration;

[0017] FIG. 2D is a side view of the cannula arm of FIG. 2A disposed in a fourth configuration;

[0018] FIG. 2E is a side view of another embodiment of a cannula arm configured for use with the surgical access system of FIG. 1;

[0019] FIG. 2F is a transverse, cross-sectional view of the cannula arm of FIG. 2E taken across section line 2F-2F;

[0020] FIG. 2G is a transverse, cross-sectional view of the cannula arm of FIG. 2E taken across section line 2G-2G;

[0021] FIG. 2H is a transverse, cross-sectional view of the cannula arm of FIG. 2E taken across section line 2H-2H;

[0022] FIG. 2I is a transverse, cross-sectional view of the cannula arm of FIG. 2E taken across section line 2I-2I;

[0023] FIG. 3 is a perspective view of one embodiment of a gimbal assembly configured for use with the surgical access system of FIG. 1;

[0024] FIG. 4 is a side, cross-sectional view of the gimbal assembly of FIG. 3;

[0025] FIG. 5 is a perspective view of a rotatable member of the gimbal assembly of FIG. 3;

[0026] FIG. 6 is a side view of the rotatable member of FIG. 5;

[0027] FIG. 7 is a side, cross-sectional view of the rotatable member of FIG. 5;

[0028] FIG. 8 is rear, perspective view of a surgical instrument configured for use with the surgical access system of FIG. 1;

[0029] FIG. 9 is front, perspective view of a retainer clip configured for use with the surgical access system of FIG. 1;

[0030] FIG. 10A is a side view of one embodiment of a lever-actuated articulation assembly configured for use with the surgical access system of FIG. 1;

[0031] FIG. 10B is a side, exploded view of the lever-actuated articulation assembly of FIG. 10A;

[0032] FIG. 11A is a perspective view of another embodiment of an articulation assembly configured for use with the surgical access system of FIG. 1;

[0033] FIG. 11B is side, exploded view of the articulation assembly of FIG. 11A;

[0034] FIG. 12A is a perspective view of yet another embodiment of an articulation assembly configured for use with the surgical access system of FIG. 1;

[0035] FIG. 12B is an enlarged, perspective view of the articulation assembly of FIG. 12B;

[0036] FIG. 12C is an enlarged, exploded view of the articulation assembly of FIG. 12A;

[0037] FIG. 13A is a top, perspective view of one embodiment of a surgical portal apparatus configured for use with the surgical access system of FIG. 1;

[0038] FIG. 13B is a bottom, perspective view of the surgical portal apparatus of FIG. 13A;

[0039] FIG. 13C is a side, cross-sectional view of the surgical portal apparatus of FIG. 13A;

[0040] FIG. 13D is a front, cross-sectional view of the surgical portal apparatus of FIG. 13A;

[0041] FIG. 13E is a side, cross-sectional view of the surgical portal apparatus of FIG. 13A inserted into an incision in tissue with an obturator inserted therethrough;

[0042] FIG. 13F is a side, cross-sectional view of the surgical portal apparatus of FIG. 13A inserted into an incision in tissue with the obturator removed therefrom;

[0043] FIG. 14A is top, perspective view of another embodiment of a surgical access port configured for use with surgical access system of FIG. 1 in position for insertion into an incision in tissue;

[0044] FIG. 14B is top, perspective view of the surgical access port of FIG. 14A inserted into an incision in tissue;

[0045] FIG. 15A is top, perspective view of yet another embodiment of a surgical access port configured for use with surgical access system of FIG. 1;

[0046] FIG. 15B is longitudinal, cross-sectional view of the access port of FIG. 15A; and

[0047] FIG. 16 is a top, perspective view of a surgical access system in accordance with the present disclosure inserted through an access port and into an internal surgical site.

#### DETAILED DESCRIPTION OF EMBODIMENTS

[0048] Embodiments of the present disclosure will now be described in detail with reference to the drawings, in which like reference numerals designate identical or corresponding elements in each of the several views. As used herein, the term “distal,” as is conventional, will refer to that portion of the instrument, apparatus, device or component thereof which is farther from the user, while the term “proximal” will refer to that portion of the instrument, apparatus, device or component thereof which is closer to the user. In the following description, well-known functions or constructions are not described in detail to avoid obscuring the present disclosure in unnecessary detail.

[0049] Turning to FIG. 1, an articulatable surgical access system is shown generally identified by reference numeral 10. Surgical access system 10 is configured for insertion through an access port, e.g., access port 700 (FIGS. 13A-13F), positioned within an incision in tissue or a naturally occurring orifice (e.g., anus or vagina) to facilitate performing one or more minimally-invasive or laparoscopic surgical tasks within an internal surgical site. Surgical access system 10 generally includes a pair of articulatable cannula arms 100, each of which includes a first articulatable segment 120 and a second articulatable segment 140, both of which are disposed toward the distal portions 102 of cannula arms 100. Each cannula arm 100 defines a longitudinal passageway 104 extending therethrough that is configured to receive a surgical instrument “I” (FIGS. 8 and 16) therein. Cannula arms 100 each further include a proximal articulation assembly, e.g., a lever assembly 200, coupled thereto and configured for controlling articulation of one of the articulatable segments, e.g., first articulatable segment 120, and a gimbal assembly 500 mounted to the proximal end 106 thereof for

controlling articulation of the other articulatable segment, e.g., second articulatable segment **140**, as will be described in greater detail below. Cannula arms **100** are independently articulatable relative to one another and may be joined by a retaining clip **600**, or other suitable structure.

**[0050]** Each of the cannula arms **100**, gimbal assemblies **500**, and the components thereof are substantially similar to one another and, thus, reference herein will be made to only one of the cannula arms **100**, gimbal assemblies **500**, and corresponding components thereof to avoid unnecessary repetition. However, it is also envisioned that the various embodiments of cannula arms **100** and the components thereof described herein may be interchanged with one another to define different configurations and/or to provide a surgical access system **10** having two different cannula arms **100**, depending on the surgical purpose to be achieved.

**[0051]** Turning now to FIGS. 2A-2D, the various articulated configurations of cannula arm **100** will be described. Although four (4) particular configurations of cannula arm **100** are shown in FIGS. 2A-2D, it is envisioned that various other configurations may be provided, e.g., cannula arm **100** may be configured to articulate off of longitudinal axis “X-X” in any direction (i.e., 360 degree articulation). Further, as will be described below, the first and second articulatable segments **120**, **140**, respectively, are controllable, e.g., movable between the four (4) configurations, via manipulation of proximal articulation assembly **200** and gimbal assembly **500**, respectively. In particular, cannula arm **100** includes a plurality of sets of tension wires, or cables “C1” and “C3”-“C4” extending proximally from the first and second articulatable segments **120**, **140**, respectively, to the respective articulation control assemblies thereof, e.g., proximal articulation assembly **200** and gimbal assembly **500**, for controlling the articulation of cannula arm **100** between the various configurations. While reference is made herein to cable sets “C1” and “C3”-“C4” for articulating articulatable segments **120** and **140**, it is envisioned that different numbers and/or configurations of cable sets may be provided to achieve different degrees or configurations of articulation of cannula arm **100**. For example, four sets of cables may be used in conjunction with each of the articulatable segments **120**, **140**, to facilitate 360 degree articulation of cannula arm **100**. However, to facilitate understanding, only cable sets “C1” and “C3”-“C4” will be described with reference to FIGS. 2A-2D and with respect to the articulation of cannula arm **100** through four different configurations, keeping in mind that the articulation of cannula arm **100** need not be limited to certain degrees of articulation or specific configurations, i.e., cannula arm **100** may be capable of 360 degree articulation relative to longitudinal axis “X-X” and may be articulated to various configurations between the unarticulated and fully articulated configurations thereof. The specific components and features of each of the embodiments of the articulation control assemblies for use with cannula arm **100** will be described in greater detail hereinbelow with reference to those various embodiments.

**[0052]** Continuing with reference to FIGS. 2A-2D, and as mentioned above, the distal portion **102** of cannula arm **100** includes first and second articulatable segments **120**, **140**, respectively that are independently articulatable relative to one another. More specifically, distal portion **102** of cannula arm **100** includes a substantially rigid tubular member **108** disposed at a proximal end **107** thereof and a distal cap **110**

disposed at a distal end **109** thereof. First articulatable segment **120** is positioned distally of and adjacent to tubular member **108**, while second articulatable segment **140** is positioned proximally of and adjacent to distal cap **110**, with a substantially rigid intermediate tubular member **112** disposed therebetween. First articulatable segment **120** further includes first and second sections of articulating linkages **122**, **124**, respectively, interconnected by an elongated linkage **126**. Similarly, second articulatable segment **140** includes first and second sections of articulating linkages **142**, **144**, respectively, interconnected by an elongated linkage **146**. As can be appreciated, and as will be described in greater detail below, the various sections of linkages **122**, **124**, **142** and **144** permit articulation of cannula arm **100** to form various different configurations thereof, e.g., via selectively tensioning one or more of the sets of cables “C1” and “C3”-“C4.”

**[0053]** More specifically, as best shown in FIG. 2A, cable set “C1” extends distally through tubular member **108**, first linkage section **122**, elongated linkage **126**, and second linkage section **124**, ultimately anchoring within intermediate tubular member **112**. Although only one cable set “C1” is shown, it is envisioned that a pair of cable sets “C1” extend similarly through cannula arm **100** on one side thereof. Internal cable sets “C1” on the other hand, extend through first articulation segment **120**, anchoring on either side thereof, but do not extend proximally (or distally) substantially beyond first articulation segment **120**. In other words, internal cable sets “C1” are internal to first articulation segment **120**, except for the anchoring thereof within elongated tubular member **108** and intermediate tubular member **112** at the ends thereof. Further, although only two opposed internal cable sets “C1” are shown, it is envisioned that four cable sets “C1” disposed at radially-spaced positions about cannula arm **100** be provided. As will be described below, cable set “C1” is selectively tensionable, e.g., via proximal articulation assembly **200** (FIG. 1), to articulate first articulatable segment **120**.

**[0054]** With continued reference to FIG. 2A, opposed cable sets “C3” and “C4” each include a pair of cables. One of the cables of each of cable sets “C3” and “C4” extends distally through tubular member **108**, first articulatable segment **120**, intermediate tubular member **112**, and first section **142** of second articulatable segment **140**, ultimately anchoring in elongated linkage **146**. The other cable of each cable set “C3” and “C4” extends distally through tubular member **108**, first articulatable segment **120**, intermediate tubular member **112**, and second articulatable segment **140**, ultimately anchoring in distal cap **110**. However, although cable sets “C3” and “C4” extend through first articulatable segment **120**, the tension on cable sets “C3” and “C4” is unaffected by the articulation or configuration of first articulatable segment **120**, i.e., such that independence between first and second articulatable segments **120**, **140**, respectively, is maintained. The routing of cable sets “C3” and “C4” through first articulatable segment **120** to second articulatable segment **140** to maintain the independence between first and second articulatable segments **120**, **140**, respectively, will be described in detail below with reference to FIGS. 2E-2I, although this configuration applies similarly to the embodiment of FIGS. 2A-2D.

**[0055]** FIG. 2A shows cannula arm **100** disposed in a substantially straight configuration, wherein cannula arm **100** is substantially aligned with longitudinal axis “X-X.”

More particularly, both the first and second articulatable segments **120**, **140**, respectively, (and the first and second sections **122**, **124** and **142**, **144**, respectively, thereof) are disposed in a substantially straight configuration. In this configuration, cable set “C1” is substantially un-tensioned such that the opposed cable sets “C1” are similarly tensioned to maintain first articulatable segment **120** in a straight configuration, i.e., such that first articulatable segment **120** does not curve, or bend off of longitudinal axis “X-X.” Likewise, cable set “C3” and cable set “C4” are similarly tensioned relative to one another to achieve the same result, i.e., a straight configuration. As can be appreciated, this substantially straight configuration facilitates insertion of cannula arm **100** through an access port, e.g., access port **700** (FIGS. **13A-13F**), disposed within an incision in tissue and into an internal surgical site.

[0056] Further, the links forming the first and second articulatable segments **120**, **140**, respectively, may be engaged to one another via springs (not explicitly shown) such that cannula arm **100** is biased toward this substantially straight position shown in FIG. **2A**. As can be appreciated, due to this configuration, first articulatable segment **120** is returned to the substantially straight configuration when cable set “C1” is substantially un-tensioned.

[0057] FIG. **2B** shows a second configuration of cannula arm **100**, wherein both the first and second sections **142**, **144**, respectively, of second articulatable segment **140** are disposed in a fully articulated configuration such that the distal end **109** of cannula arm **100** is articulated, or curved off of longitudinal axis “X-X” and such that a distal surface **114** of cannula arm **100** faces generally perpendicularly to longitudinal axis “X-X.” This configuration is achieved by applying greater tension to cable set “C3” as compared to cable set “C4” such that second articulatable segment **140** is curved off longitudinal axis “X-X” in the direction of cable set “C3.” In this configuration, first articulatable segment **120**, on the other hand, remains in the substantially straight configuration.

[0058] FIG. **2C** shows a third configuration of cannula arm **100**, wherein both the first and second sections **122**, **124**, respectively, of first articulatable segment **120** are disposed in a fully articulated configuration such that intermediate tubular member **112** is radially displaced from, but remains substantially parallel to, longitudinal axis “X-X” of cannula arm **100**. This configuration is achieved by applying tension to cable set “C1” to articulate first linkage section **122** of first articulatable segment **120**, as shown in FIG. **2C**. As a result of this tension, the neutrality of tension between opposed internal cables “C1” is lost such that second linkage section **124** of first articulatable segment **120** is articulated in a substantially opposite direction relative to first linkage section **122**, i.e., to form an S-like shaped configuration. In this configuration, second articulatable segment **140** remains in the substantially straight configuration, e.g., cable sets “C3” and “C4” are similarly tensioned, but is radially displaced from longitudinal axis “X-X” due to the articulation of first articulatable segment **120**.

[0059] FIG. **2D** shows a fourth configuration, wherein both the first and second articulatable segments **120**, **140**, respectively, are disposed in their respective fully articulated configurations, e.g., wherein cable set “C1” is tensioned and wherein cable set “C3” is more greatly tensioned as compared to cable set “C4.” Similarly as in the previous configuration, in this fourth configuration, intermediate tubular

member **112** is radially displaced from, but remains parallel to, longitudinal axis “X-X” of cannula arm **100**. As can be appreciated, in this fourth configuration, cannula arm **100** defines a generally C-shaped configuration.

[0060] Turning now to FIGS. **2E-2F**, another configuration for the cables extending through cannula arm **100** is shown. In the embodiment of FIGS. **2E-2F**, a second cable set “C2” is added to oppose cable set “C1” such that, rather than tensioning and un-tensioning cable set “C1” to articulate and return first articulatable segment **120**, first articulatable segment **120** is articulated or returned by applying greater or less tension, respectively, to cable set “C1” as compared to cable set “C2.” In other words, cable set “C1” is tensioned to articulate first articulatable segment **120**, while cable set “C2” is tensioned to return first articulatable segment **120** to the substantially straight configuration.

[0061] The configuration of cable sets “C3” and “C4” in FIGS. **2E-2F** is substantially similar to that of the embodiment of cannula arm **100** described above with reference to FIGS. **2A-2D**. In particular, one of the cables “C3<sub>1</sub>,” “C4<sub>1</sub>” of each of cable sets “C3” and “C4,” respectively, extends distally through tubular member **108**, first articulatable segment **120**, intermediate tubular member **112**, and first section **142** of second articulatable segment **140**, ultimately anchoring in elongated linkage **146**, while the other cable “C3<sub>2</sub>,” “C4<sub>2</sub>” of each cable set “C3” and “C4,” respectively, extends distally through tubular member **108**, first articulatable segment **120**, intermediate tubular member **112**, and second articulatable segment **140**, ultimately anchoring in distal cap **110**.

[0062] Turning now to FIGS. **2E-2I**, as mentioned above, cable sets “C3” and “C4” are routed through first articulatable segment **120** such that the tension on cable sets “C3” and “C4” is unaffected by the articulation or configuration of first articulatable segment **120**. More specifically, as shown in FIG. **2F**, cable sets “C3” and “C4” are disposed at radially opposed positions about cannula arm **100** and are about 90 degrees offset from cable sets “C1” and “C2,” respectively. An additional cable set is paired with each of cable sets “C3” and “C4” at the radially opposed positions thereof and extend through cannula arm **100** to second articulatable segment **140**, e.g., such that four cable sets may be provided to permit 360 degree articulation of second articulatable segment **140**. Due to this configuration, wherein cable sets “C3” and “C4” and the additional cable sets are offset 90 degrees relative to cable sets “C1” and “C2,” the tension on cable sets “C3” and “C4” and the additional cable sets is not altered as cable sets “C1” and “C2” are selectively tensioned relative to one another to articulate first articulatable segment **120**.

[0063] Referring now to FIGS. **2G-2I**, once cable sets “C3” and “C4” and the additional cable sets extend through first articulatable segment **120** and into intermediate tubular member **112**, cable sets “C3” and “C4” begin to rotate from the paired, opposed positions of FIGS. **2F** and **2G**, toward the position shown in FIG. **2I**, wherein cable sets “C3,” “C4,” and the additional cable sets are equally-spaced radially about cannula arm **100** such that the four cable sets, cable sets “C3,” “C4,” and the additional cable sets, may be selectively tensioned to articulate second articulatable segment **140** through 360 degrees of articulation. In other words, the cable sets are bunched in pairs at opposed positions and are offset 90 degrees relative to cable sets “C1” and “C2” during passage through first articulatable segment

**120** such that the tension on cable sets “C3” and “C4” is unaffected by the articulation or configuration of first articulatable segment **120**, and cable sets “C3” and “C4” are rotated 90 degrees from this position as the cables extend from first articulatable segment **120** toward second articulatable segment **140** such that cable sets “C3” and “C4” and the additional cable sets are equally-spaced about cannula arm **100** to permit 360 degree articulation of second articulatable segment **140** via selective tensioning of one or more of the cable sets.

[0064] With reference now to FIGS. 3 and 4, one embodiment of a gimbal assembly configured for use with surgical access system **10** is shown generally identified by reference numeral **500**. As will be described in detail below, gimbal assembly **500** is selectively manipulatable to articulate one of the articulatable segments of cannula arm **100**, e.g., second articulatable segment **140**, between the substantially straight configuration (see FIGS. 2A and 2C) and the curved, or articulated configuration (see FIGS. 2B and 2D).

[0065] Continuing with reference to FIGS. 3-4, gimbal assembly **500** includes a base member **502**, a cover **504**, and a rotatable member **506**. Base member **502** has a semicircular or hemispherical configuration defining an internal cavity therein, although other configurations are contemplated. Base member **502** further includes a port **508** defining a passage **510** (FIG. 4) in communication with the cavity. Rotatable member **506** is disposed in the cavity. Rotatable member **506** is adapted to swivel or rotate within the cavity in multiple dimensions or along multiple axes with respect to base member **502** and cover **504**. Cover **504** is attached to base member **502** to retain rotatable member **506** within the cavity of base member **502**. Cover **504** may be attached to base member **502** through any conventional means including adhesives, bayonet coupling, or screws (as shown in FIG. 3).

[0066] With reference now to FIG. 5, rotatable member **506** includes a base unit **512**, a collar **514**, and a neck **516**. In particular, neck **516** extends proximally from base unit **512**. Collar **514** is slidably mounted on neck **516** and is coupled to base unit **512**. Neck **516** defines a channel **518** therethrough. Channel **518** is in communication with the cavity defined in base member **502** (FIGS. 3-4), which in turn is in communication with passage **510** (FIG. 4) of port **508** (FIG. 4).

[0067] With continued reference to FIG. 5, in conjunction with FIGS. 3-4, base unit **512** of rotatable member **506** includes lateral walls **520** and locking fingers **522** circumferentially arranged about base unit **512**. Lateral walls **520** conform to the contour of an inner surface of the semicircular or hemispherical-shaped base member **502**. Specifically, lateral walls **520** extend radially inward to facilitate swivel or rotation thereof against the inner surface of base member **502**. In addition, base unit **512** defines circumferentially arranged recesses **524**, each of which at least partially extends along respective lateral wall **520**. In particular, each recess **524** is adapted to accommodate therein at least a portion of locking finger **522**. Each locking finger **522** includes a contact portion **522a** and a head portion **522b**. Head portion **522b** includes a pair of protrusion members **522c** defining a gap therebetween. Each protrusion member **522c** defines a bore to accommodate a pin **526** therein.

[0068] Each locking finger **522** is movable between an unlocking state and a locking state. In the unlocking state, contact portion **522a** of locking finger **522** is disposed in

recess **524** defined in lateral wall **520** and is substantially flush with lateral wall **520** to enable swivel or rotation of rotatable member **506** with respect to base member **502** and cover **504**. In the locking state, contact portion **522a** of locking finger **522** extends radially outwardly from recess **524** defined in lateral wall **520** and contacts the inner surface of base member **502**, such that pressure is applied against the inner surface of base member **502** by contacting portion **522a**, thereby securing rotatable member **506** in a particular orientation with respect to base member **502** and cover **504**. In addition, contact portion **522a** may further include a gripping portion **522f** to improve contact with and reduce slippage against the inner surface of base member **502**, i.e., to facilitate the locking of rotatable member **506** in position relative to base member **502**.

[0069] With reference to FIGS. 5 and 6, in conjunction with FIGS. 3-4, collar **514** is translationally mounted on neck **516** of rotatable member **506**. In particular, collar **514** includes a plurality of circumferentially arranged protruding parts **514a**. Each pair of protruding parts **514a** is aligned with a corresponding pair of protrusion members **522c** of locking finger **522**. Each locking finger **522** is coupled with collar **514** by a linkage member **532**. Specifically, one end of linkage member **532** is received in the gap defined by the pair of protruding parts **514a** of collar **514** and is pivotally connected to the pair of protruding parts **514a** by a pin **526**. The other end of linkage member **532** is pivotally disposed in the gap defined in head portion **522b** of locking finger **522** and is pivotally connected to protrusion members **522c** of locking finger **522** by pin **526**. In this manner, the axial position of collar **514** along neck **516** determines the state of locking finger **522**. For example, positioning locking collar **514** to the distal-most position along neck **516** causes linkage member **532** to urge head portion **522b** of locking finger **522** such that locking finger **522** slides radially outwardly to urge contact portion **522a** of locking finger **522** into contact with the inner surface of base member **502**. In other words, positioning locking collar **514** in the distal-most position extends contact portion **522a** of locking finger **522** radially outwardly to transition rotatable member **506** to the locking state.

[0070] With continued reference to FIGS. 5 and 6, in order to facilitate axial movement of collar **514** along neck **516** of rotatable member **506**, rotatable member **506** further includes a lock wheel **534** threadedly mounted on neck **516**. Neck **516** includes a corresponding threaded portion (not shown). Lock wheel **534** is coupled with collar **514**, whereby rotation of lock wheel **534** about neck **516** moves lock wheel **534** and collar **514** axially along neck **516**. In this manner, locking fingers **522** may be moved between the locking state and the unlocking state through rotation of lock wheel **534**.

[0071] With reference to FIGS. 6 and 7, rotation of lock wheel **534** in a first direction moves collar **514** axially in the distal direction. Such movement transfers force to locking finger **522** through linkage member **532** which causes locking finger **522** to slide radially outwardly, enabling contact portion **522a** to extend radially outwardly from recess **524** defined in base unit **512** such that locking fingers **522** are urged into contact with the inner surface of base member **502** (FIG. 4). In this manner, rotatable member **506** may be securely fixed in a desired orientation with respect to base member **502** and cover **504** (see FIGS. 3-4). Rotation of lock wheel **534** in a second direction (opposite of the first

direction), on the other hand, moves collar **514** axially in the proximal direction. Such movement causes locking finger **522** to slide radially inwardly, returning contact portion **522a** to within recess **524** defined in lateral wall **520**, wherein contact portion **522a** is substantially flush with lateral wall **520**. In this manner, rotatable member **506** is able to freely rotate or swivel about various axes relative to base member **502** and cover **504** (see FIGS. 3-4).

[0072] Referring now to FIGS. 3-7, in conjunction with FIGS. 2A-2D, rotatable member **506** includes a plurality of engagement apertures **536** defined therethrough. Engagement apertures **536** are radially disposed about a center of rotatable member **506** and are configured to secure third and fourth cable sets "C3" and "C4," respectively, therein (although more engagement apertures **536** and cable sets may be provided to achieve greater degrees of articulation). In particular, third set of cables "C3" is engaged within one of the engagement apertures **536** and extends distally therefrom through cannula arm **100** and through second articulating segment **140** on a first side thereof, ultimately anchoring in distal cap **110** of cannula arm **100**. Fourth set of cables "C4" is similarly engaged within another one of the engagement apertures **536** and extends distally therefrom through cannula arm **100** and through second articulating segment **140** on a second, opposed side thereof, ultimately anchoring in distal cap **110**. Accordingly, in this configuration, as rotatable member **506** is swiveled or rotated within the cavity of base member **502**, as described above, the opposed third and fourth sets of cables "C3," "C4," respectively, are selectively tensioned (or un-tensioned) relative to one another to articulate second articulatable segment **140** of cannula arm **100** between the substantially straight configuration (FIGS. 2A and 2C) and the articulated, or curved configuration (FIGS. 2B and 2D). Further, it is envisioned that engagement apertures **536** and the third and fourth sets of cables "C3," "C4," respectively, be oriented to translate rotation or movement of rotatable member **506** into similar articulation of second articulatable segment **140** of cannula arm **100**. In other words, it is envisioned that moving rotatable member **506** in a first direction effects corresponding articulation of second articulatable segment **140** in that first direction.

[0073] Gimbal assembly **500** may further be transitioned between the locking state and the unlocking state, as described above, to retain rotatable member **506** in a desired orientation, thus retaining second articulatable segment **140**, i.e., maintaining the relative tension between cable sets "C3" and "C4," of cannula arm **100** in a desired configuration, e.g., the substantially straight configuration, the articulated configuration, or any configuration therebetween.

[0074] Turning now to FIG. 8, in conjunction with FIGS. 1-4, an example of a surgical instrument configured for use with surgical access system **10** is shown as surgical instrument "I," although it is envisioned that any other suitable surgical instrument may be used in conjunction with surgical access system **10**, depending on the surgical task to be completed. In particular, surgical instrument "I" includes a handle assembly **20**, a flexible, elongated tubular member **22** extending distally from handle assembly **20** and an end effector assembly **24** (e.g., a pair of jaw members for grasping and/or manipulating tissue, or any other suitable end effector assembly for performing a surgical task within an internal surgical site) disposed at a distal end of the flexible, elongated tubular member **22**. End effector assembly **24** of surgical instrument "I" is configured for insertion

through longitudinal passageway **538** of gimbal assembly **500** and longitudinal passageway **104** of cannula arm **100** (which is in communication with longitudinal passageway **538** of gimbal assembly **500**) such that end effector assembly **24** extends distally from distal cap **110** of cannula arm **100** within the internal surgical site. In this configuration, flexible elongated tubular member **22** of surgical instrument "I" is disposed within longitudinal passageway **104**. Due to the flexible nature of elongated tubular member **22**, elongated tubular member **22** is flexed, or curved in accordance with the articulation of cannula arm **100** to position end effector assembly **24** in a desired position and/or orientation. Further, surgical instrument "I" may be releasably engageable, i.e., lockable, with collar **514** of gimbal assembly **500** to retain surgical instrument "I" in substantially fixed position relative to rotatable member **506** thereof.

[0075] With continued reference to FIGS. 1-4 and 8, in conjunction with FIG. 16, once surgical instrument "I" has been inserted into passageway **538** of gimbal assembly **500** and through passageway **104** of cannula arm **100** (and, optionally, locked to gimbal assembly **500**), surgical instrument "I" may be manipulated to manipulate gimbal assembly **500** and, thus, to articulate second segment **140** of cannula arm **100**, as desired. More specifically, manipulating handle assembly **20** of surgical instrument "I" urges rotatable member **506** to swivel or rotate within the cavity of base member **502**, as described above, which, in turn, tensions (or un-tensions) cable sets "C3," "C4" to articulate second articulatable segment **140** of cannula arm **100**. In other words, the surgeon may manipulate handle assembly **20** of surgical instrument "I" to effect corresponding articulation of cannula arm **100** and, thus, end effector assembly **24** which extends distally therefrom. As can be appreciated, handle assembly **20** remains disposed proximally and externally of surgical system **10**, allowing the surgeon to grasp and manipulate surgical instrument "I" to articulate cannula arm **100** and also allowing the surgeon to manipulate trigger **26** and/or wheel **28** for further operating end effector assembly **24**.

[0076] Turning to FIG. 9, in conjunction with FIG. 1, a retaining clip **600** configured for use with surgical system **10** is shown. More specifically, retaining clip **600** is configured for positioning about first and second cannula arms **100** for retaining the substantially rigid tubular members **108** of the cannula arms **100** in fixed position relative to one another, e.g., such that the rigid tubular members **108** of cannula arms **100** are fixed in position adjacent to and substantially parallel relative to one another, although other configurations are contemplated. However, although retaining clip **600** couples the cannula arms **100** to one another, each of the cannula arms **100** remains independently articulatable.

[0077] With continued reference to FIG. 9, retaining clip **600** includes a pair of lumens **610**, **620** extending there-through. As can be appreciated, each lumen **610**, **620** is configured to retain one of the cannula arms **100** therein. More specifically, retaining clip **600** includes first and second components **602**, **604** that cooperate with one another to form lumens **610**, **620**. First and second components **602**, **604** may be releasably engaged to one another via any suitable mechanism, e.g., screws, latching, etc., and may be adjustable relative to one another for increasing or decreasing the diameters of lumens **610**, **620** to secure retaining clip **600** about cannula arms **100** or to permit retaining clip **600** to be slid longitudinally along cannula arms **100**. In use,

retaining clip 600 remains externally disposed of the body during a minimally-invasive surgical procedure.

**[0078]** Turning now to FIGS. 10A-10B, lever assembly 200 will be described. As mentioned above with reference to FIG. 1, lever assembly 200 is configured to selectively control the articulation of first articulatable segment 120 of cannula arm 100 between the substantially straight configuration (FIGS. 2A and 2B) and the articulated, or curved configuration (FIGS. 2C and 2D). More specifically, lever assembly 200 is disposed towards proximal end 106 of cannula arm 100 and includes a base portion 210 disposed about cannula arm 100, a lever arm 220 rotatable about a pivot assembly 230 relative to cannula arm 100 between a spaced-apart position and an approximated position, and a locking assembly 240. As shown in FIG. 10A, lever 220 may initially be disposed in the spaced-apart position such that first articulatable segment 120 of cannula arm 100 is initially disposed, or biased, toward the substantially straight configuration (also shown in FIGS. 2A and 2B), due to the lack of tension on cable set "C1" and the spring-biased configuration of the linkages of first articulatable segment 120. However, other configurations are also contemplated, e.g., wherein first articulatable segment 120 of cannula arm 100 is biased toward the articulated configuration (see FIGS. 2C and 2D). As will be described in greater detail below, moving lever 220 from the spaced-apart position toward the approximated position tensions cable set "C1" to articulate first section 122 thereof, which, in turn, unevenly tensions internal cable sets "C1" to articulate second section 124 thereof. In other words, moving lever 220 from the spaced-apart position toward the approximated position articulates first articulatable segment 120 of cannula arm 100 from the substantially straight configuration toward an articulated configuration (FIGS. 2C and 2D).

**[0079]** With continued reference to FIGS. 10A-10B, and to FIG. 10B in particular, lever 220 defines a cross-sectional configuration complementary to base portion 210 and defines a diameter slightly larger than that of base portion 210 such that, in the approximated position, lever 220 is disposed about base portion 210. Lever 220 further includes a pair of spaced-apart flanges 222, 224, each defining an aperture 223, 225, respectively, extending therethrough. Flanges 222, 224 are configured for positioned on either side of hub 212 of base portion 210, which includes a lumen 213 extending therethrough. During assembly, a pivot pin 232 is disposed through aperture 223 of flange 222, lumen 213 of hub 212, and aperture 225 of flange 224 to pivotably engage lever 220 and base portion 210 to one another. More specifically, pivot pin 232 is secured to flanges 222 and 224 such that movement of lever 220 between the spaced-apart and approximated positions rotates lever 220 relative to base portion 210 and rotates pivot pin 232 within and relative to hub 212 of base portion 210.

**[0080]** Pivot pin 232 further includes a pair of recesses 234 defined therein for securing the proximal ends of each of the cables of cable set "C1" thereto. The cables of cable set "C1" are secured within recesses 234 such that, upon rotation of pivot pin 232 relative to hub 212, the proximal ends of the cables of cable set "C1" are rotated about the pivot axis of pivot pin 232 to tension the cables of cable set "C1." Accordingly, as lever 220 is moved from the spaced-apart position to the approximated position to rotate pivot pin 232 relative to hub 212 of base portion 210, cable set "C1" is "wound-up" about pivot pin 232, thus pulling cable

set "C1" proximally and tensioning cable set "C1." Due to this configuration, as lever 220 is moved toward the approximated position, first articulatable segment 120 of cannula arm is bent, or articulated from the substantially straight configuration (FIGS. 2A, 2B and 10A) to the curved, or articulated configuration (FIGS. 2C and 2D).

**[0081]** Referring momentarily to FIG. 1, and as mentioned above, cable sets "C3" and "C4" (FIGS. 2A-2D) are configured to extend from second articulatable segment 140 proximally through cannula arm 100, ultimately engaging gimbal assembly 500, which is manipulatable for selectively tensioning cable sets "C3" and "C3" (FIGS. 2A-2D) for articulating second articulatable segment 140. As such, cable sets "C3" and "C4" (FIGS. 2A-2D) pass through lever assembly 200. However, lever assembly 200 and pivot pin 232 thereof are configured such that cables "C3" and "C4" are uninterrupted, i.e., the tension on cables "C3" and "C4" is maintained, regardless of the position of lever 220 and/or locking assembly 240. This configuration maintains the independence of articulation between first and second articulatable segments 120, 140, respectively.

**[0082]** Referring again to FIGS. 10A-10B, locking assembly 240 includes a locking arm 242 pivotable about a pivot pin 244 secured within hub 212 of base portion 210 between an unlocked position and a locked position. Locking arm 242 includes a trigger 246 disposed at first end 245 thereof and a locking finger 248 disposed at second end 247 thereof. In use, upon movement of lever 220 to the approximated position relative to body portion 210 of lever assembly 200, i.e., to articulate first articulatable segment 120 of cannula arm 100 from the substantially straight configuration to the articulated configuration, locking finger 248 engages locking pin 238 of lever 220 to inhibit return of lever 220 to the spaced-apart position, thereby retaining pivot pin 232 in position and fixing the tension on cable set "C1." In other words, locking finger 248 engages locking pin 238 as lever 220 is approximated relative to base portion 210 such that lever 220 is locked in the approximated position, thereby locking first articulatable segment 120 of cannula arm 100 in the articulated position. Locking arm 242 may be biased by a spring (not shown) or other suitable biasing member such that locking finger 248 is biased into engagement with, i.e., automatically engages, locking pin 238 upon movement of lever 220 to the approximated position. Alternatively, locking arm 242 may be selectively actuatable, e.g., via depressing lock trigger 246, to lock lever 220 in position once lever 220 has reached the approximated position. As can be appreciated, in either configuration, lever 220 is freely movable from the spaced-apart position to just prior to the approximated position for moving first articulatable segment 120 of cannula arm 100 between the substantially straight and various partially-articulated positions. However, it is also envisioned that locking assembly 240 be configured to lock lever 220 in various positions between the spaced-apart and approximated positions for correspondingly locking first articulatable segment 120 of cannula arm 100 at various positions between the substantially straight configuration and the articulated configuration.

**[0083]** With continued reference to FIGS. 10A-10B, in order to unlock lever 220 from the approximated position (or any other position), trigger 246 of locking assembly 240 is depressed, thereby disengaging locking finger 248 and locking pin 238 and allowing lever 220 to return under bias back to the approximated position and, accordingly, rotating pivot

pin 232 back to its initial position to substantially un-tension cable set “C1,” thus returning first articulating segment 120 of cannula arm 100 to the substantially straight configuration under the spring-bias of the linkages of first articulating segment 120.

[0084] Referring to FIGS. 11A-11B, another embodiment of an articulation assembly for selectively controlling the articulation of first articulating segment 120 of cannula arm 100 between the substantially straight configuration (FIG. 2E) and the articulated, or curved configuration (see e.g., FIGS. 2C and 2D), is shown designated as articulation assembly 300. Articulation assembly 300 incorporates the cable configuration shown in FIGS. 2E-2I, although other configuration, e.g., the configuration of FIGS. 2A-2D is also contemplated. Articulation assembly 300 is interdisposed between tubular member 108 of cannula arm 100 and proximal end 106 of cannula arm 100 and generally includes an inner member 310 and an outer member 320 pivotably coupled to inner member 310 such that inner member 310 is movable relative to outer member 320 between a substantially aligned position (see FIG. 11A), wherein the inner and outer members 310, 320, respectively, are substantially aligned with one another, and a substantially transverse position, wherein the inner and outer members 310, 320, respectively, are disposed in a substantially transverse relation relative to one another. As will be described in greater detail below, moving inner member 310 relative to outer member 320 from the substantially aligned position (FIG. 11A) to the substantially transverse position articulates first articulating segment 120 of cannula arm 100 from the substantially straight configuration (FIGS. 2A, 2B and 11A) to the articulated configuration (FIGS. 2C and 2D).

[0085] Inner member 310 of articulation assembly 300, as best shown in FIG. 11B, includes a rotatable member 312 and a base 314 extending proximally therefrom. Rotatable member 312 is configured for positioning between flanges 322, 324 of outer member 320, as will be described below, and includes a central aperture 316 extending therethrough. Rotatable member 312 further includes a pair of recesses 317 defined within an outer periphery thereof and a channel 318 defined therein and extending circumferentially about rotatable member 312 from each of the recesses 317. The proximal end of each of cable sets “C1” and “C2” is secured within one of the recesses 317 of rotatable member 312 in opposite directions such that cable set “C1” extends from one of recesses 317 through corresponding channel 318 circumferentially about rotatable member 312 in a first direction, while cable set “C2” extends from the other recess 317 through the other channel 318 circumferentially about rotatable member 312 in a second, opposite direction. Due to this configuration, as will be described in greater detail below, rotation of inner member 310 relative to outer member 320 selectively tensions one of the cable sets, e.g., cable set “C1,” while un-tensioning the other, opposed cable set, e.g., cable set “C2,” thereby articulating first articulating segment 120 of cannula arm 100 from the substantially straight configuration (FIGS. 2E and 10A) to the curved, or articulated configuration (see, e.g., FIGS. 2C and 2D).

[0086] Continuing with reference to FIGS. 11A-11B, outer member 320 of articulation assembly 300 includes a distal base 322 configured to engage tubular member 108 of cannula arm 100, and a pair of flanges 324, 326 extending proximally from distal base 322. Flanges 324, 326 are spaced-apart sufficiently to receive rotatable member 312 of

inner member 310 therebetween. Flanges 324, 326 each include a plurality of apertures 328 defined therethrough. Apertures 328 are configured to receive bolts 342 therethrough. During assembly, boss 340 is positioned within central aperture 316 of rotatable member 312 of inner member 310 and outer member 320 is positioned about inner member 310 such that flanges 324, 326 are positioned on opposed ends of rotatable member 312 and boss 340. Thereafter, bolts 342 are inserted through apertures 328 and are secured within boss 340 to fixedly engage boss 340 between flanges 324, 326 of outer member 320. In this configuration, wherein boss 340 and outer member 320 are fixed in position relative to one another, inner member 310 is rotatable about boss 340 and, thus, relative to outer member 320 between the substantially aligned and substantially transverse positions. Boss 340 further includes a pair of detents 344, 346 defined therein, the importance of which will be described in greater detail below. Boss 340 also includes a passageway extending therethrough to permit insertion of a surgical instrument, e.g., surgical instrument “I” (FIG. 8), completely through cannula arm 100.

[0087] In use, as proximal end 106 of cannula arm 100 is moved radially, i.e., off-axis, relative to tubular member 108 of cannula arm 100, inner member 310 is rotated about boss 340 and relative to outer member 320 to permit such movement of proximal end 106 of cannula arm 100. This relative rotation of inner member 310 rotates rotatable member 312 such that cable set “C1” is wound-up about rotatable member 312, causing cable set “C1” to be pulled proximally, thereby tensioning cable set “C1.” At the same time, cable set “C2” is un-wound about rotatable member 312, thereby slackening cable set “C2” to reduce the tension on cable set “C2.” As a result, with a greater relative tension on first cable set “C1” as compared to second cable set “C2,” first articulating segment 120 of cannula arm 100 is articulated from the substantially straight configuration (FIGS. 2E and 11A) toward the articulated configuration (see, e.g., FIGS. 2C and 2D).

[0088] Referring still to FIGS. 11A-11B, articulation assembly 300 further includes a locking mechanism 301 for selectively locking inner and outer members 310, 320, respectively, in one of a plurality of fixed positions relative to one another. Locking mechanism 301 includes a block 302 having a pair of rods 304 extending distally therefrom. Rods 304 are configured to extend through lumens 315 defined within base 314 of inner member 310 and to protrude distally at least partially therefrom. More specifically, a spring 306 interdisposed between collar 307 and block 302 biases block 302 distally such that rods 304 are biased distally to protrude from lumens 315 of base 314 toward boss 340, which is disposed within central lumen 316 of rotatable member 312 of inner member 310.

[0089] In use, as inner member 310 is rotated relative to boss 340 and outer member 320 from the substantially aligned position toward the substantially transverse position to articulate first articulating segment 120 of cannula arm 100, rods 304 are eventually positioned adjacent to first detent 344 defined within boss 340. With rods 304 positioned adjacent first detent 344, boss no longer inhibits further distal biasing of rods 304 and, as such, spring 306 urges block 302 and rods 304 distally such that rods 304 extend into first detent 344, thereby inhibiting rotation of boss 340 and inner member 310 relative to one another. In other words, the engagement between rods 304 and first



detent 344 locks inner member 310 and outer member 320 in a first pre-determined position relative to one another and, thus, locks first articulatable segment 120 in a first articulated configuration.

[0090] In order to release inner and outer members 310, 320, respectively, from this locked position, block 302 is translated proximally to remove rods 304 from detents 344. In other words, block 302 serves as a release slide for locking mechanism 301. As such, block 302 may include a gripping portion 303 (or gripping portions) configured to facilitate grasping and translating (i.e., sliding) block 302 against the bias of spring 306 to release locking mechanism 301. With rods 304 removed from detents 344, i.e., with block 302 in the release position, inner member 310 may be rotated relative to outer member 320, e.g., to a second pre-determined position, wherein rods 304 are positioned adjacent to second detent 346. Similarly as described above, once rods 304 are positioned adjacent to second detent 346, spring 306 urges rods 304 distally into second detent 346, thereby locking inner member 310 in the second predetermined position relative to outer member 320 and, accordingly, locking first articulatable segment 120 in a second articulated configuration.

[0091] As can be appreciated, the number and positioning of detents 344, 346 defined within boss 340 determine the number and position of pre-determined locking positions of inner and outer members 310, 320, respectively, and, thus, the locking configurations of first articulatable segment 120 of cannula arm 100. For example, inner and outer members 310, 320, respectively, may be initially biased towards the substantially aligned position such that first articulatable segment 120 of cannula arm 100 is biased toward the substantially straight configuration; detent 344 may be positioned to define an intermediate locking position of inner and outer members 310, 320, respectively, and, thus, an intermediate articulated configuration for first articulatable segment 120 of cannula arm 100; and detent 346 may be positioned at the substantially transverse position of inner and outer members 310, 320, respectively, such that the second locking position of inner and outer members 310, 320, respectively, locks first articulatable segment 120 of cannula arm 100 in the fully articulated configuration. However, it is envisioned that the number and position of detents 344, 346 may be altered to achieve other desired locking configurations for first articulatable segment 120 of cannula arm 100.

[0092] Referring briefly to FIG. 1, in order to maintain the independence of articulation between first and second articulatable segments 120, 140, respectively, cable sets “C3” and “C4” (FIGS. 2A-2D) are configured to extend through the passageway defined through boss 340 such that, similarly as discussed above with respect to articulation assembly 200, cables “C3” and “C4” are uninterrupted, i.e., the tension on cables “C3” and “C4” is maintained, regardless of the position inner and outer members 310, 320, respectively, relative to one another.

[0093] With reference to FIGS. 12A-12C, yet another embodiment of an articulation mechanism 400 provided in accordance with the present disclosure and configured for use with surgical access system 10 (FIG. 1) is shown. Similar to the articulation mechanisms described above, articulation mechanism 400 is configured for selectively controlling the articulation of first articulatable segment 120 of cannula arm 100 between the substantially straight con-

figuration (FIGS. 2A and 2B) and the articulated, or curved configuration (FIGS. 2C and 2D). More specifically, articulation mechanism 400 includes proximal and distal members 410, 420, respectively, that are pivotably movable relative to one another between a substantially aligned position (see FIG. 12A), wherein the proximal and distal members 410, 420, respectively, are substantially aligned with one another, and a substantially transverse position, wherein the proximal and distal members 410, 420, respectively, are disposed in a substantially transverse relation relative to one another, in order to articulate first articulatable segment 120 of cannula arm 100 between the substantially straight configuration (FIGS. 2A and 2B) and the articulated configuration (FIGS. 2C and 2D).

[0094] Proximal member 410 of articulation assembly 400 includes a connector 412 configured for engagement with proximal end 106 of cannula arm 100, a semi-disc-shaped flange 414 extending from connector 412, and an annular central member 416 extending distally from connector 412. The curvature of semi-disc-shaped flange 414 is similar to that of central member 416 such that semi-disc-shaped flange 414 is co-axially positioned relative to central member 416 along the length of semi-disc-shaped flange 414. Further, semi-disc-shaped flange 414 includes an arcuate slot 415 defined therethrough that defines a similar arc-angle as compared to semi-disc-shaped flange 414. Central member 416, on the other hand, includes a central aperture 417 defined therethrough. As best shown in FIGS. 12A and 12B, the proximal ends of the cables of cable set “C1” are anchored within central member 416 at a radially-spaced position, i.e., off-center, relative to central aperture 417. Proximal member 410 may further include a cap 440 disposed thereon that includes a knob 430a extending into central aperture 417. Knob 430a is centered relative to cannula arm 100, the importance of which will be described in greater detail below.

[0095] Distal member 420 is similar to proximal member 410 and includes a connector 422 configured for engagement with tubular member 108 of cannula arm 100, a semi-disc-shaped flange 424 extending from connector 422, and an annular central member 426 extending proximally from connector 422. As with proximal member 410, semi-disc-shaped flange 424 is co-axially positioned relative to central member 426 along the length of semi-disc-shaped flange 424. Semi-disc-shaped flange 424 also includes an arcuate slot 425 defined therethrough that defines a similar arc-angle as compared to semi-disc-shaped flange 424. Central member 426 of distal member 420 includes a central recess 427 defined therein that is configured for positioning about and in alignment with central aperture 417 of central member 416 of proximal member 410. Recess 427 includes a recessed floor 428 that includes a knob 430b extending therefrom that opposes knob 430a of cover 440 of proximal member 410, but is sufficiently spaced therefrom to permit passage of a surgical instrument therebetween. Further, cable set “C1” is configured to extend through connector 422 of distal member 420 and into anchored engagement within central member 416 of proximal member 410 at a radial position thereof, as best shown in FIG. 12B.

[0096] In the assembled condition, as shown in FIG. 12B, proximal member 410 is positioned substantially atop distal member 420, although flange 424 of distal member 420 is disposed atop flange 414 of proximal member 410, and such that central members 416, 426, respectively, thereof are



aligned with one another. Proximal and distal members **410**, **420**, respectively, are coupled to one another in any suitable fashion that permits relative rotation of proximal and distal members **410**, **420** between the substantially aligned position and the substantially transverse position, e.g., via a pin (not explicitly shown) engaged within slots **415**, **425** of flanges **414**, **424**, respectively, of proximal and distal members **410**, **420**, respectively.

[0097] In use, as proximal end **106** of cannula arm **100** is moved radially, i.e., off-axis, relative to tubular member **108** of cannula arm **100**, proximal member **410** is rotated relative to distal member **420**. As proximal member **410** is rotated relative to distal member **420**, central member **416** of proximal member **410** is rotated relative to central member **426** of distal member **420** such that cable set “C1” is pulled proximally (due to its anchoring within central member **416** of proximal member **410** and the rotation of central member **416**), causing cable set “C1” to be tensioned. As a result, with cable set “C1” tensioned, first articulatable segment **120** of cannula arm **100** is articulated from the substantially straight configuration (FIGS. 2A and 2B) toward the articulated configuration (FIGS. 2C and 2D), similarly as described above with respect to lever assembly **200** (FIGS. 10A-10B).

[0098] As mentioned above, knobs **430a**, **430b** extend into the passageway defined through articulation assembly **400**. More specifically, knobs **430a**, **430b** are configured to route cable sets “C3” and “C4” (FIGS. 2A-2D), respectively, therearound. Since knobs **430a**, **430b** are centrally disposed relative to cannula arm **100**, the tension on cable sets “C3” and “C4” (FIGS. 2A-2D) is not altered as proximal and distal members **410**, **410** are rotated relative to one another between the substantially aligned and substantially transverse positions. In other words, knobs **430a**, **430b** help maintain the independence between the articulation of first and second articulatable segments **120**, **140**, respectively (see FIG. 1).

[0099] Referring now to FIGS. 13A-13F and initially to FIGS. 13A-13B, one embodiment of a surgical portal apparatus **700** configured for use with surgical access system **10** is shown. Surgical portal apparatus **700** generally includes a housing **720** and a tubular member **740**. Surgical portal apparatus **700** is adapted for insertion within an incision in tissue, e.g., through the abdominal or peritoneal lining, in connection with a laparoscopic or endoscopic surgical procedure and is dimensioned to receive surgical objects therethrough to provide access to an internal surgical site. Housing **720** is configured to be releasably attached to tubular member **740**, although housing **720** and tubular member **740** may alternatively be permanently attached or affixed to one another in any suitable manner. Housing **720** and tubular member **740** may also be utilized independently with other surgical objects such as, for example, an obturator, as will be discussed below.

[0100] Referring now to FIGS. 13C-13D, housing **720** includes a cover **721**, a cap piece **722**, a central portion **723**, and a locking connector **724**. Cover **721** is disposed at the proximal end of housing **720** and defines a plurality of passageways **725a-725d** for the reception of surgical objects. Cover **721** may be formed from any foam, rubber or gel like material which is adapted to flex or move upon manipulation of a surgical object so as to allow a surgeon a greater range of motion. Passageways **725a-725d** are configured and dimensioned to accommodate a variety of dif-

ferently sized surgical objects and may include sealing ports **728-731** to allow for the maintenance of a fluid-tight sealed surgical space. Sealing ports **728-731** may be formed monolithically or may be formed of separate parts. Sealing port **731** may include a mounting ring **731a**, a valve ring **731b**, and a valve member **731c**. Mounting ring **731a** is adapted to form a sealed relationship with cover **721** and dimensioned to receive valve ring **731b** in a substantially fluid sealed manner. Valve ring **731b** is adapted to receive valve member **731c** in a fluid sealed manner. Sealing ports **728-731** may include sealing valves for maintenance of a fluid tight seal such as flapper valves, duck-bill valves, or other suitable valves. Although four passageways **725a-725d** and sealing ports **728-731** are shown it is envisioned that cover **721** may include alternate configurations containing larger or smaller numbers and sizes of passageways **725a-725d** and sealing ports **728-731** depending on the needs of the surgeon. In one particular example, each of the cannula arms **100** of surgical access system **10** is inserted through one of sealing ports **729**, **730** (which define similar configurations), while the remaining ports **728**, **731** may be used for other instrumentation or may simply be left vacant.

[0101] Cap piece **722** is dimensioned to receive cover **721** in a fluid sealed manner and to attach cover **721** to central portion **723**. Central portion **723** may include a connector **726** and a fluid conducting conduit **727**. Connector **726** is adapted to releasably couple housing **720** to a surgical support system (not shown) for maintaining surgical portal apparatus **700** securely in position, while fluid conducting conduit **727** provides fluid access to and from the internal surgical site. Fluid conduit **727** may include a valve (not shown) in fluid communication therewith for controlling the rate and/or direction of fluid flow therethrough. Fluid conducting conduit **727**, for example, may be used to introduce insufflation gasses into the internal body cavity. Locking connector **724** is attached at the distal end of central portion **723** and is adapted for releasable attachment to tubular member **740** via snap fit, bayonet coupling, screw fit or other suitable mechanism. It is also envisioned that at least some of the components of housing **720** may be monolithically formed, including but not limited to cap piece **722**, central portion **723** and locking connector **724**.

[0102] Tubular member **740** includes a body connector **741**, a flexible portion **742**, and a locking collar **743**. Tubular member **740** defines a passageway therethrough and may also include a sealing valve to maintain insufflation when housing **720** is removed. Body connector **741** is disposed at the proximal end of flexible portion **742** and locking collar **743** is disposed at the proximal end of body connector **741**. Body connector **741** and locking collar **743** may also be monolithically formed. Locking collar **743** is dimensioned to releasably receive locking connector **724** of housing **720** via a bayonet coupling in a substantially fluid sealed manner. Locking collar **743** may alternatively receive locking connector **724** in snap fit, screw fit or any other suitable arrangement. Locking connector **724** may include a sealing mechanism **733** such as, for example, an o-ring, to facilitate attachment to locking collar **743** in a substantially fluid sealed manner.

[0103] Flexible portion **742** is dimensioned and configured for insertion into an incision whereby flexible portion **742** creates a substantially sealed relationship with the incision. Flexible portion **742** is adapted to allow surgical objects access through the incision and into the surgical

space. Flexible portion **742** is formed of a flexible material that is capable of deforming during manipulation of surgical objects while still maintaining seal integrity in the surgical space and may be made from suitable biocompatible polymers. Flexible portion **742** may include a plurality of ribs **745** which facilitate the flexing of flexible portion **742** while providing additional structural strength. Ribs **745** may be formed of the same material as flexible portion **742** or may be formed of a different material. Flexible portion **742** may also include a tubular segment (not shown) internal or external to the ribs which facilitates the sealed reception of flexible portion **742** in the tissue. The tubular segment (not shown) and ribs **745** may also be formed monolithically. Further, flexible portion **742** may be capable of deforming upon insertion into an incision in tissue to substantially conform to the shape of the incision and thereby provide a better seal.

[0104] Referring now to FIGS. 13E-13F, body connector **741** may include a flange **746** disposed at the distal end of body connector **741**. Flange **746** may be used to indicate to a surgeon or physician that tubular member **740** is fully inserted into the incision and may also be adapted to provide a sealing relationship with an outer wall of tissue “T.” Flange **746** may be formed of the same material as body connector **741** or may be formed of a foam like or other material suitable for creating a fluid tight seal with tissue “T.” Optionally flange **746** may include a separate material attached thereto to facilitate the creation of the sealed relationship with tissue “T.”

[0105] During use, referring now to FIGS. 13A-13F, with housing **720** detached from tubular member **740**, obturator **750** is inserted into tubular member **740**. Tubular member **740** is then inserted into an incision in tissue “T” until flange **746** rests against the outer wall of tissue “T.” Once tubular member **740** is fully inserted, obturator **750** is removed and housing **720** is attached. Alternatively, tubular member **740** may be inserted into the incision in tissue “T” without obturator **750**. In this case housing **720** may be attached either prior to insertion or after insertion. After housing **720** is attached to tubular member **740** by inserting locking connector **724** into locking collar **744** a surgical object may be introduced through one of the passageways **725a-725d** and into the surgical space. For example, each of the cannula arms **100** of surgical access system **10** (FIG. 1) may be inserted through one of the sealing ports **729**, **730**.

[0106] Turning now to FIGS. 14A-14B, another embodiment of an access port, or seal anchor member **800** is shown. Seal anchor member **800**, along with other embodiments of access ports that may be used in conjunction with surgical access system **10**, are disclosed in commonly-owned, co-pending U.S. patent application Ser. No. 12/244,024 to Richard et al., filed Oct. 2, 2008, the entire contents of which are hereby incorporated by reference herein. Accordingly, seal anchor member **800** will only be summarily described herein.

[0107] Seal anchor member **800** includes respective proximal and distal rims **802**, **804** and an intermediate portion **806** extending longitudinally between the proximal and distal rims **802**, **804**, respectively. Seal anchor member **800** further includes one or more ports **808** that extend longitudinally between proximal and distal rims **802**, **804**, respectively, and through seal anchor member **800**.

[0108] Seal anchor member **800** is formed of a biocompatible compressible material that facilitates the resilient,

reciprocal transitioning of seal anchor member **800** between an expanded condition (FIG. 14B) and a compressed condition (FIG. 14A). Seal anchor member **800** is preferably formed from a suitable foam material having sufficient compliance to form a seal about one or more surgical objects inserted through one or more of ports **808** and to establish a sealing relation with tissue “T.” The foam is preferably sufficiently compliant to accommodate off axis motion of the surgical object when inserted therethrough. In one embodiment, the foam includes a polyisoprene material. The foam may also be a “memory” foam such that seal anchor member **800** is resiliently transitionable between the expanded condition (FIG. 14B) and the compressed condition (FIG. 14A). [0109] With continued reference to FIGS. 14A-14B, proximal and distal rims **802**, **804**, respectively, of seal anchor member **800** extend radially outwardly from seal anchor member **800**, while intermediate portion **806** defines a reduced diameter such that seal anchor member **800** defines an “hour-glass” shape or configuration to assist in anchoring seal anchor member **800** within tissue. However, other configurations of seal anchor member **800** are also contemplated.

[0110] Each port **808** of seal anchor member **800** is configured to removably receive one or more surgical objects therethrough in sealing relation therewith. Prior to the insertion of a surgical object, ports **808** are disposed in a first state wherein each port **808** defines a closed configuration such that the escape of insufflation gas (not shown) through ports **808** of seal anchor member **800** is substantially inhibited. Upon the introduction of a surgical object, the port **808** transitions to a second state wherein port **808** expands in diameter to substantially approximate the diameter of the surgical object, creating a seal therearound.

[0111] As mentioned above, seal anchor member **800** is adapted to transition from an expanded condition (FIG. 14B) to a compressed condition (FIG. 14A) so as to facilitate the insertion and securement thereof within an incision in tissue “T.” More particularly, once an incision has been formed through body tissue “T,” seal anchor member **800** is squeezed or compressed to reduce seal anchor member **800** from the expanded condition to the compressed condition, as shown in FIG. 14A. Seal anchor member **800** may be compressed into any suitable configuration prior to being inserted into an incision, not merely the configuration shown in FIG. 14A.

[0112] Referring now to FIG. 14B, once seal anchor member **800** has been inserted through the incision in tissue “T,” the pressure, e.g., the squeezing or compression force, applied to seal anchor member **800** is released, allowing seal anchor member **800** to return towards the expanded, or uncompressed condition. Typically, the incision is formed having a size that is slightly smaller than the diameter of the seal anchor member **800** in the expanded state such that, once placed within the incision in tissue “T,” seal anchor member **800** is sealingly engaged therein. Once positioned as described above, one or more surgical objects, e.g., surgical access system **10** (FIG. 1), may be inserted through ports **808** to perform a surgical task within the internal surgical site.

[0113] Referring now to FIGS. 15A-15B, another embodiment of an access port, or seal anchor member **900** is disclosed. Seal anchor member **900** is similar to seal anchor member **800** (FIGS. 14A-14B) and, accordingly, similar features will be summarized hereinbelow while the differ-

ences thereof will be described in greater detail. Seal anchor member 900, similar to seal anchor member 800 includes respective proximal and distal ends 902, 904, an intermediate portion 906 disposed between the proximal and distal ends 902, 904, and one or more generally tubular port segments 908 defining ports 909 that extend longitudinally through seal anchor member 900 and between the proximal and distal ends 902, 904. Proximal and distal ends 902, 904 each define a rim 910, 912, respectively, of seal anchor member 900 that facilitates the anchoring of seal anchor member 900 within tissue "T."

[0114] With continued reference to FIGS. 15A-15B, tubular port segments 908 are secured to seal anchor member 900 by a plurality of connective members 914 such that the longitudinal position of the port segments 908 remain substantially constant with respect to the respective proximal and distal rims 910, 912 during insertion and removal of a surgical object therefrom. As shown, each of the connective members 914 extends inwardly from the seal anchor member 900 and is attached to one of the ports 908. Further, several interconnective members 916 are disposed between the port segments 908 to interconnect the port segments 908 to one another. Connective members 914 (and/or the interconnective members 916) may be composed of the same material comprising seal anchor member 900 or, alternatively, may be composed of a material that is substantially more rigid, to inhibit off-axis movement of the surgical object "O" following its insertion into one of the ports 908, or substantially less rigid, to facilitate off-axis movement of the surgical object "O."

[0115] Continuing with reference to FIGS. 15A-15B, ports 908 extend longitudinally through seal anchor member 900 such that the proximal ends 918 of the ports 908 are substantially coplanar with the proximal rim 910 of seal anchor member 900 and such that the distal ends 920 of the ports 908 are substantially coplanar with the distal rim 912 of seal anchor member 900. However, it is also envisioned that the proximal and distal ends 918, 920 of ports 908 extend beyond the proximal and distal rims 902, 904, or that the proximal and distal ends 916, 918 of ports 908 are defined entirely within the intermediate portion 906 thereof. The insertion and operation of seal anchor member 900 is similar to that of seal anchor member 800 (see FIGS. 14A-14B), discussed above, and, thus, will not be repeated here.

[0116] Referring now to FIG. 16, the use and operation of surgical access system 10, as described in detail with reference to the various embodiments thereof, will be summarized in order to interrelate and provide appreciation for the various components and features of surgical access system 10. In FIG. 16, surgical access system 10 is shown including a pair of cannula arms 100 each having an articulation assembly 400 coupled thereto and a gimbal assembly 500 disposed at a proximal end thereof.

[0117] Initially, an access port 1000 (or any other suitable access port, such as those described above) is positioned within an incision in tissue "T" or a naturally occurring orifice (e.g., anus or vagina). Thereafter, cannula arms 100 are each inserted distally through the access portion 1000 in the substantially straight configuration such that the distal ends 109 thereof are positioned adjacent the internal surgical site. Prior or subsequent to insertion, cannula arms 100 may be secured to one another via retaining clip 600, as described above. Next, a surgical instrument "I1," "I2" is inserted

through each of the cannula arms 100 such that the end effector assemblies 24a, 24b, respectively, thereof extend distally from cannula arms 100 and such that the handle assemblies 20a, 20b, respectively, thereof extend proximally from gimbal assemblies 500. With surgical instruments "I1" and "I2" in position within surgical access device 10, the proximal portions of cannula arms 100 may be selectively manipulated such that articulation mechanism 400 translates motion thereof to articulate first articulatable segments 120 of cannula arm 100 to a desired position and/or handle assemblies 20a, 20b may be selectively manipulated to swivel the corresponding gimbal assemblies 500 such that second articulatable segments 140 are articulated to a desired configuration. As can be appreciated, the independent articulation of each of the cannula arms 100 and of the first and second articulatable segments 120, 140, respectively, thereof facilitates positioning of end effector assemblies 24a, 24b in various different positions relative to one another to perform a surgical task within the internal surgical site. For example, as shown in FIG. 16, both cannula arms 100 are disposed in the fourth configuration (see FIG. 2D), defining opposed C-shaped configurations such that end effector assemblies 24a, 24b extend toward one another. This configuration is advantageous in that the effector assemblies 24a, 24b are opposed, i.e., facing, one another, rather than adjacent to, i.e., side-by-side, one another, thus facilitating performing a surgical task within the internal surgical site that requires cooperation of instruments "I1" and "I2."

[0118] FIG. 16 shows one embodiment of surgical access system 10 wherein an articulation mechanism 400 is coupled to each of the cannula arms 100 for selectively articulating first articulatable segments 120 of cannula arms 100. However, it is envisioned that any of the other articulation mechanisms, e.g., articulation mechanisms 200 and 300, may be used in conjunction with either or both of the cannula arms 100 as part of surgical access system 10. The use of surgical access system 10 in conjunction with these embodiments, i.e., with articulation mechanisms 200 or 300, is substantially similar to that as described above with reference to FIG. 16, except for the specific operation of the particular articulation mechanism 200, 300 (which are described in detail above with reference to FIGS. 10A-10B and 11A-11B, respectively), and, thus, will not be repeated herein for purposes of brevity.

[0119] Although the illustrative embodiments of the present disclosure have been described herein with reference to the accompanying drawings, the above description, disclosure, and figures should not be construed as limiting, but merely as exemplifications of particular embodiments. It is to be understood, therefore, that the disclosure is not limited to those precise embodiments, and that various other changes and modifications may be effected therein by one skilled in the art without departing from the scope or spirit of the disclosure.

1. (canceled)
2. A method of accessing a surgical site, comprising:
  - inserting a distal portion of a first arm through a first lumen of an access port such that a proximal portion of the first arm is positioned on an external side of the access port and the distal portion of the first arm is positioned on an internal side of the access port, the first arm defining a first passageway therethrough;

inserting a first surgical instrument through the first passageway such that a first end effector of the first surgical instrument extends distally from the distal portion of the first arm and a handle of the first surgical instrument extends proximally from the proximal portion of the first arm; and

manipulating a first control interface operably coupled to a first articulation assembly of the first arm to articulate a first articable segment of the distal portion of the first arm independent of a second articable segment of the first arm to position the first end effector within the surgical site.

3. The method according to claim 2, further including positioning the access port within an opening in tissue.

4. The method according to claim 2, further including inserting a second arm through a second lumen of access port such that a proximal portion of the second arm is positioned on the external side of the access port and a distal portion of the second arm is positioned on the internal inside of the access port.

5. The method according to claim 4, further including inserting a second surgical instrument through a second passageway defined through the second arm such that a second end effector of the second surgical instrument extends distally from the distal portion of the second arm and a handle of the second surgical instrument extends proximally from the proximal portion of the second arm.

6. The method according to claim 5, further including manipulating a second control interface operably coupled to a second articulation assembly of the second arm to articulate a first articable segment of the distal portion of the second arm independent of a second articable segment of the second arm to position the end effector of the first surgical instrument within the surgical site.

7. The method according to claim 6, wherein manipulating the first and second control interfaces includes independently articulating each the first and second articable

segments of each of the first and second arms between a substantially straight configuration and an articulated configuration.

8. The method according to claim 7, wherein independently articulating the first and second articable segments includes disposing each of the first and second articable segments of the first and second arms in the articulated configuration such that the first end effector opposes the second end effector.

9. The method according to claim 8, wherein disposing each of the first and second articable segments of the first and second arms in the articulated configuration includes aligning a longitudinal axis of the first end effector with a longitudinal axis of the second end effector.

10. The method according to claim 2, wherein manipulating the first control interface includes independently articulating the first and second articable segments of the first arm between a substantially straight configuration and an articulated configuration.

11. The method according to claim 10, wherein independently articulating the first and second articable segments of the first arm includes disposing each of the first and second articable segments of the first arm in the articulated configuration such that the first end effector is disposed orthogonal to a longitudinal axis of the proximal portion of the first arm.

12. The method according to claim 2, wherein manipulating the first control interface includes pivoting a lever pivotally coupled to the proximal portion of the first arm.

13. The method according to claim 2, wherein manipulating the first control interface includes rotating a first member about a longitudinal axis of the proximal portion of the first arm.

14. The method according to claim 2, wherein manipulating the first control interface includes rotating a first flange relative to a second flange, the first and second flanges movably secured to the proximal portion of the first arm.

\* \* \* \* \*

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#### 摘要(译)

手术系统包括一个或多个臂，所述臂限定穿过其中的通道。臂包括近侧部分和远侧部分，近侧部分构造成用于定位在患者身体外部，远侧部分构造成用于定位在体内腔体内。远端部分包括彼此间隔开的第一和第二可铰接段，并且能够在基本直的构造和铰接构造之间独立铰接。第一铰接组件联接到一个臂的近侧部分，并且可在第一状态和第二状态之间转换，以使第一可铰接区段在基本直的构型和铰接构型之间铰接。第二铰接组件联接到一个臂的近侧部分并且构造成在多个位置之间移动，用于在基本直的构型和铰接构型之间铰接第二可铰接段。

