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106 - 1201

309 - 303

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10

, , , , ,

1

2

3 2

(108)

4

5

6

7

.

8

(PRF)

9 ,

10 ,

<

103 :

301 :

302 : FFT

304 :

1 (transducer array; 103) (101) (101) (101) (101) v 1
 , t=t₀ , 2N

1

$$v = \frac{\Delta_\theta \lambda_0}{2\pi T_{PRF}}$$

0 , T_{PRF} (Pulse Repitition Frequency, PRF) 1
 v

2 (transducer array; 103) (103)
 (pre - amp, 104) TGC (105) (104) TGC (105)
 (gain) (107) (quadrature demodulator, 106)
 5) A/D (108) (108) 2N (109)
 (2N)

(103) 가 가 (108)
 (spectral Doppler) — (109) —

3 2 (108) (301)
 (301) (high - pass filter) FFT (Fast Fourier Trans
 forming part, 302) 2N , 2N
 n; 303 (post - processing portio
 (base line shifting) (108) (log compression)
 (109) (304)
 2N (109)

4
y
4

4 x
가
4
가

(401) (402)
(noise threshold)
(403) (f_p)

가
가
가
가
가

가
가
(Pulse Repetition frequency, PRF)가

가 (aliasing)

5
 5 , M
 f_i $x(i, t_M)$ $2N$ t_M $x(i, t_M)$ $2N$ t_M , M
 5
 5 가
 5
 , 5
 ,
 - N N - 1 N f_i i가 $2N$, ,가
 , 5

6
 6
 x 가 , 가 6
 가 , 6

(PRF, Pulse Repetition Frequency)가 7

(PRF)

8 (PRF) , x
 , y 8 5 8
 가
 가 가
 , 가 가 가
 , 가 가 가
 , 가 가 가

, 8 j 80 . j
 . i 가
 , -80 . i -80
 가

8 , 2N N 128 . 가
 , 8 가 , j
 i 가 , 가 가
 가 2

3

$$N_{new} = N_{old} + (N_{old} - \text{abs}(\text{peak_index})) = 2N_{old} - \text{abs}(\text{peak_index})$$

2 N_{new} 8 N_{old} 128 , i , N_{old} , N_{new} 176가
 N_{new} 176 가

3

4

$$PRF_{new} = PRF_{old} \times \frac{N_{new}}{N_{old}}$$

3 2 ,
4 .

5

$$PRF_{new} = PRF_{old} \times \left(2 - \frac{\text{abs}(\text{peak_index})}{N_{old}} \right)$$

PRF_{new} , peak_index , N_{old} , PRF_{old}

9 , x[i] i . 9 i N-1 ,
-N . 1210 가 , 0 N-1 , -
N -1 . 가 , 1220 x[i]가
(Noise_Threshold) . x[i]가 1225
(peak_index) i . 1230 i가 -1 . i가 -1
1231 N-1
, 1232 i -N .

8 j , i가 0 80 , 1220 x[i]가
, peak_index가 . i가 81 N-1 , -N -1
1220 x[i]가 , peak_index가
N-1 , -N -80 peak_index 80 . i , i가 0
, peak_index -80 .

9 1210 가 . , i가 0 1 -N , N-1
1 .

10 , ,
 1310 9 , 1320 ,
 1330 가 , 가 ,
 1330 가 , (N_{new}) , 1360 3 , 1350 2
 (PRF_{new}) ,
 10 , 2 3 1350 4 2 , 1360 3
 , 가 가 가

(57)

1.

2.

1 ,
가 ,

$$PRF_{new} = PRF_{old} \times \left(2 - \frac{abs(peak_index)}{N_{old}} \right)$$

PRF_{new} , N_{old} , PRF_{old} , peak_index

3.

1 , 가 ,

4.

5.

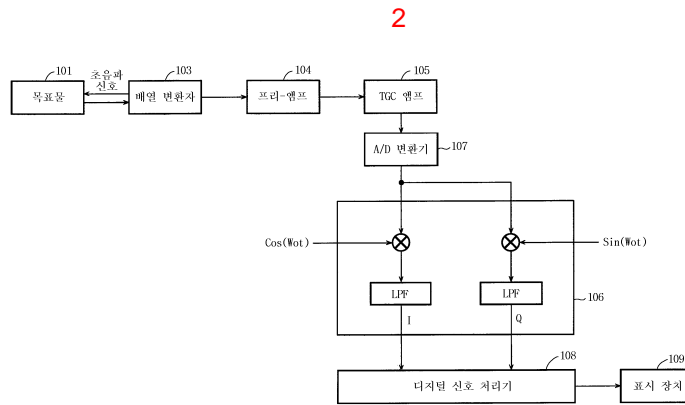
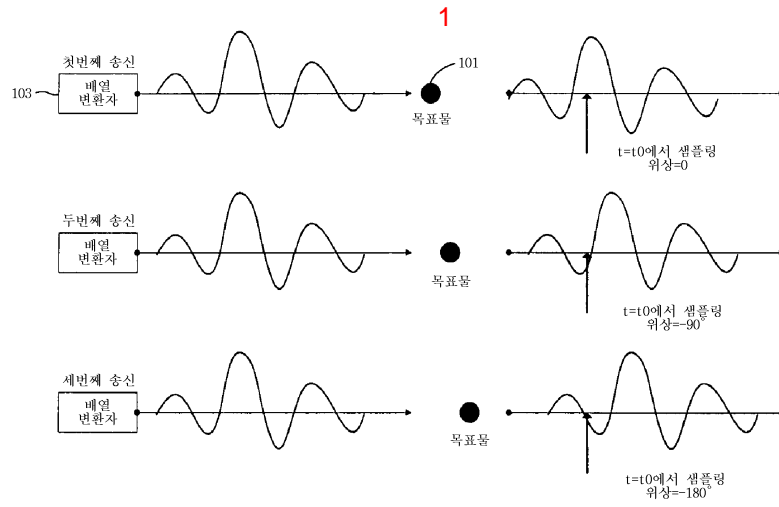
4 , 가 ,

$$PRF_{new} = PRF_{old} \times \left(2 - \frac{abs(peak_index)}{N_{old}} \right)$$

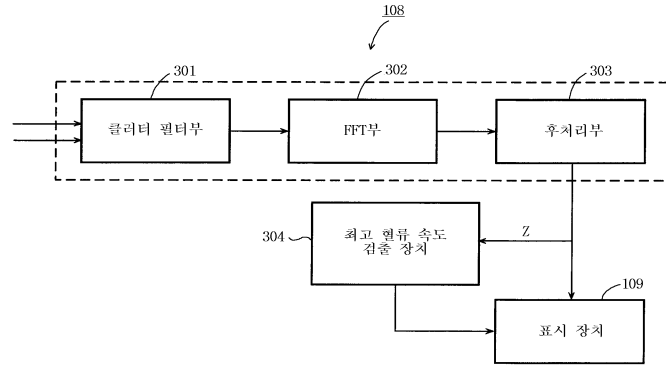
PRF_{new} , N_{old} , PRF_{old} , peak_index

6.

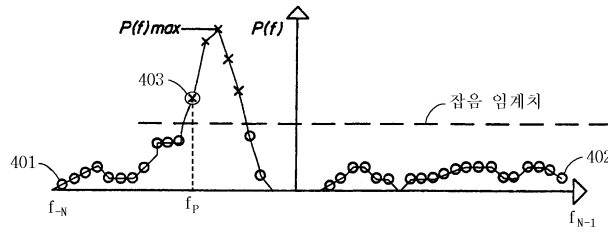
4 가 ,



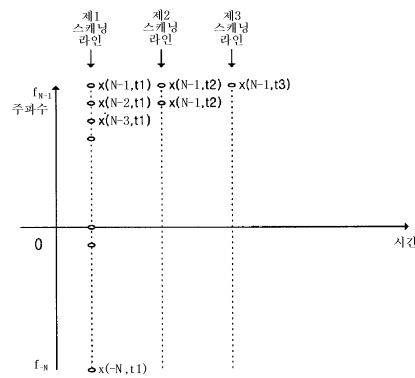
3



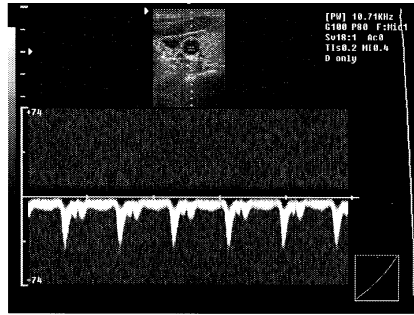
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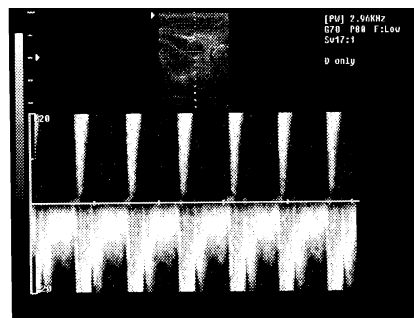
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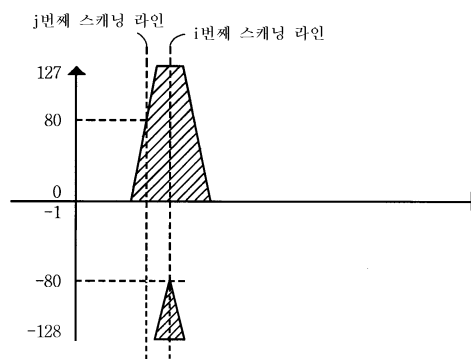
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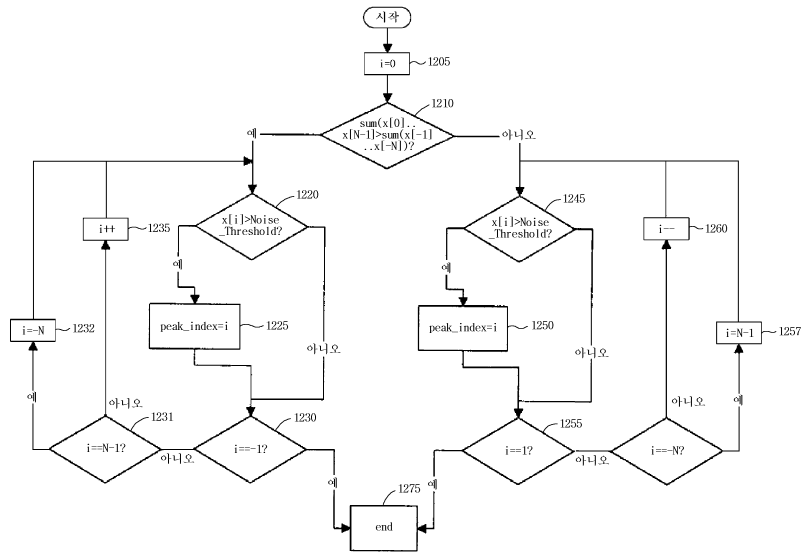


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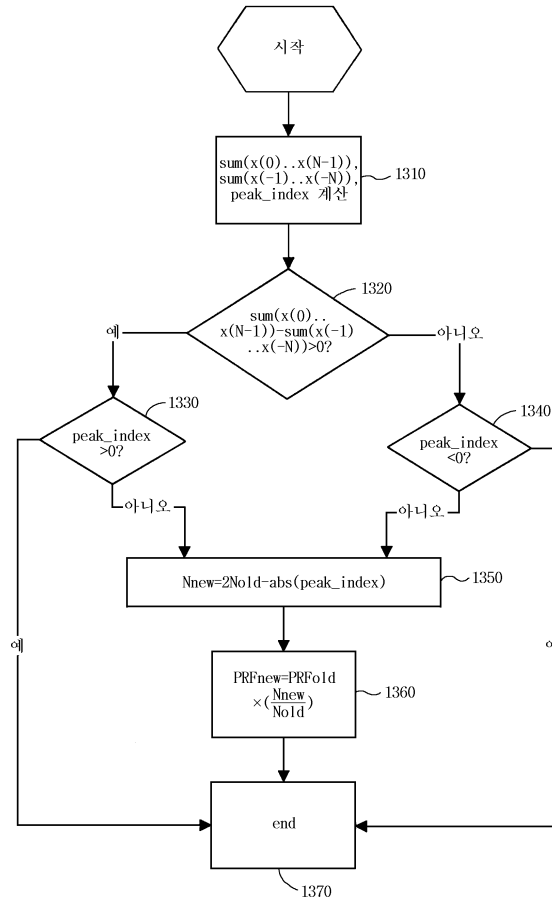


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专利名称(译)	使用多普勒效应测量血流速度的超声诊断设备和方法		
公开(公告)号	KR100381874B1	公开(公告)日	2003-04-26
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代理人(译)	CHU,晟敏 CHANG, SOO KIL		
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摘要(译)

本发明涉及超声诊断设备和使用多普勒效应测量血流速率的方法。根据本发明的血流速度测量方法包括产生其样本的样本数据的步骤，检测包括产生的步骤的步骤，以及来自频率分布数据的血流速率，多个频率分量处理样本数据并具有各自对应于功率电平，而频率分布数据 - 样本数据的频率分布数据显示多个血流速率分量，以及感测是否在频率分布数据中产生混叠的步骤和在感知情况下的脉冲重现频率更新阶段来自混叠感测阶段的混叠更新预定的脉冲重现频率，以便产生混叠。超声诊断装置，血流速率测量，多普勒效应，噪声阈值，混叠，脉冲重现频率。

