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(22) 2002 07 23

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101-1302

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2 1 1

3(a)

3(b) 3(a)

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5 4

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8(a)

8(b) 8(a)

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3 : 1

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8 : amp;

9 :

, (depth), (contrast), (focusing), (gain), (edge enhancement),
(frame average) 가 가 가 ,

$$I_N(m,n) = \mu_d + \frac{(I(m,n)-\mu)}{\sigma} \times \sigma_d$$

$$, (m,n) \quad \text{가} \quad , I_N(m,n) \\ , I(m,n) \quad . \quad 5 \quad . \quad (4) \\ . \quad 1 \quad . \quad 1 \quad . \quad 6 \quad . \quad , \quad (50) \\ 1 \quad . \quad (4) \quad 1 \quad (3) \quad , \quad 6 \\ (60) \quad . \quad .$$

(Log Power Spectrum)

, (50) ()
가 .

$F(u,v)$ 2

$$F(u,v) = \log |\Im \{ I_N(m,n) \}|$$

, (m,n) 1 , $I_N(m,n)$, \tilde{f}
 (Discrete Fourier Transform), (u,v)
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 symmetry) ,
 . .
 . .
 . .

(60) (50)

가

$$F(u,v) \quad . \quad (\textbf{J}) \quad 3$$

$$f = \{F(0,0), F(0,1), \dots, F(U,V)\}$$

, (U,V) (f)

$$\begin{array}{ccccccccc} & & (\overline{\mathbf{f}_k}) & & (\sigma_k) & & 4 & & 5 \\ (\overline{F}_k(u, v)) & & (\sigma_k(u, v)) & & & & & 6 & \\ & & & & & & & & 7 \\ & & & & & & & & k \end{array}$$

$$\overline{\mathbf{f}}_k = \left\{ \overline{F}_k(0,0), \overline{F}_k(0,1), \dots, \overline{F}_k(U,V) \right\}, \quad k = 1, 2, \dots, K$$

$$\sigma_k = \{ \sigma_k(0,0), \sigma_k(0,1), \dots, \sigma_k(U,V) \}, \quad k = 1, 2, \dots, K$$

$$\text{amp}; \quad (8)$$

$$\begin{array}{ccccccccc} (9) & 1 & (4) & & (\mathbf{f}) & & \text{amp}; \\ & (8) & & & (5) & & (5) \\ , & , & & & (10) & & \\ , & , & & & & & \\ \uparrow & & & & & & \\ & & (5) & & & & \\ & & & & & & \\ & & 8 & & & & \\ & & & & & & \text{(Mahalanobis)} \end{array}$$

$$d(\mathbf{f}, \overline{\mathbf{f}}_k) = \left\| \frac{\mathbf{f} - \overline{\mathbf{f}}_k}{\sigma_k} \right\|, \quad k = 1, 2, \dots, K$$

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(\mathcal{F}) $f = \{F(0,0), F(0,1), \dots, F(U,V)\}$

$$\begin{aligned} F(u,v) & \text{, } \log |\mathcal{J}\{I_N(m,n)\}| \text{, } (m,n) \\ \text{, } I_N(m,n) & \text{, } (u,v) \text{, } \mathcal{J} \text{, } , \text{, } (U,V) \end{aligned}$$

8.

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 $(\overline{F}_k(u,v))$

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$$\overline{F}_k(u,v) = \frac{1}{M} \sum_{i=1}^M F_k^i(u,v), \quad k = 1, 2, \dots, K$$

 $F_k^i(u,v)$ $(u,v) \text{, } M \text{, } k$ k

i

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$$\sigma_k(u, v) = \left\{ \frac{1}{M} \sum_{i=1}^M \{ F_k^i(u, v) - \bar{F}_k(u, v) \}^2 \right\}^{1/2}, \quad k = 1, 2, \dots, K$$

$$\begin{aligned} & F_k^i(u, v) \\ & (u, v) \\ & , \quad \bar{F}_k(u, v) \\ & , \quad M \quad k \\ & , \quad k \\ & , \quad i \\ & , \quad K \end{aligned}$$

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$$d(f, \bar{f}_k) = \left\| \frac{f - \bar{f}_k}{\sigma_k} \right\|, \quad k = 1, 2, \dots, K$$

$$\begin{aligned} & f \\ & , \quad \bar{f}_k \\ & \sigma_k \end{aligned}$$

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(\mathcal{F})

$$f = \{F(0,0), F(0,1), \dots, F(U,V)\}$$

$$\text{F(u,v)} \quad \nmid \quad , \quad \log |\mathcal{J}\{I_N(m,n)\}| \quad , \quad (m,n) \\ , \quad I_N(m,n) \quad , \quad (u,v) \quad \mathcal{J} \quad , \quad (U,V)$$

17.

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k

($\overline{F}_k(u, v)$)

$$\overline{F}_k(u, v) = \frac{1}{M} \sum_{i=1}^M F_k^i(u, v), \quad k = 1, 2, \dots, K$$

$$\begin{matrix} F_k^i(u, v) \\ (u, v) \\ K \end{matrix}, \quad M - k$$

18.

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k

($\sigma_k(u, v)$)

$$\sigma_k(u, v) = \left\{ \frac{1}{M} \sum_{i=1}^M \{ F_k^i(u, v) - \overline{F}_k(u, v) \}^2 \right\}^{1/2}, \quad k = 1, 2, \dots, K$$

$$\begin{matrix} F_k^i(u, v) \\ (u, v) \\ \overline{F}_k(u, v) \\ , \quad M - k \end{matrix}, \quad k - i$$

19.

14

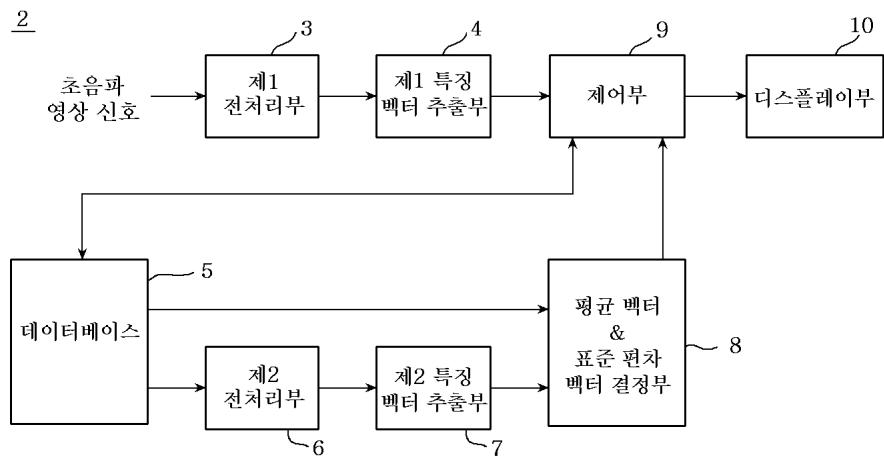
,

$$d(f, \overline{f}_k) = \left\| \frac{f - \overline{f}_k}{\sigma_k} \right\|, \quad k = 1, 2, \dots, K$$

f

 \overline{f}_k σ_k

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2



3a



3b



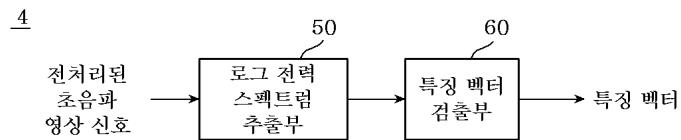
4



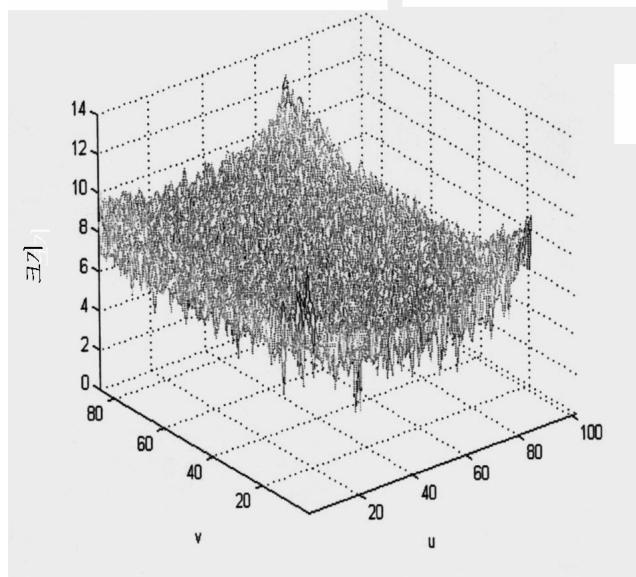
5



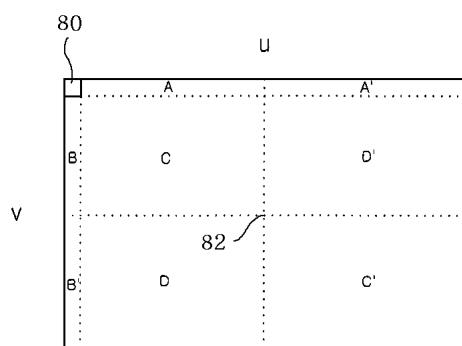
6



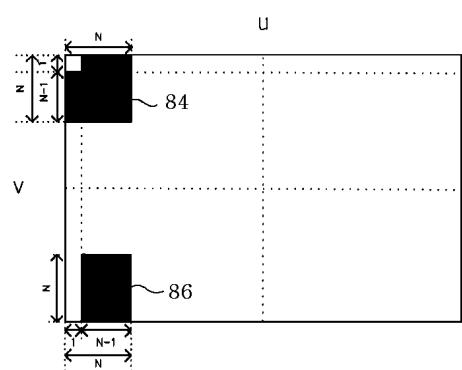
7



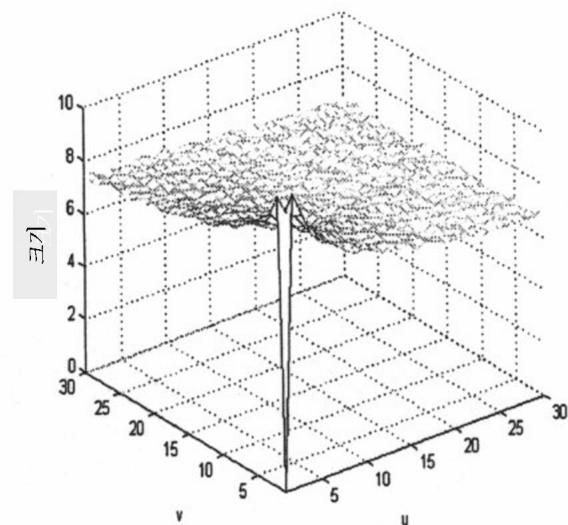
8a



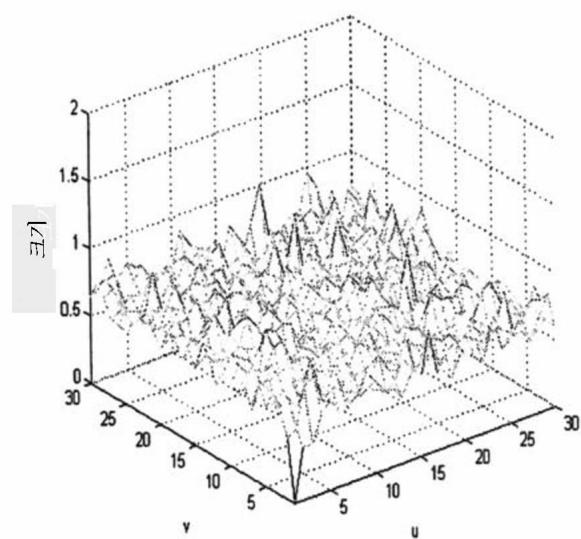
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专利名称(译)	用于从超声图像信号识别器官的装置和方法		
公开(公告)号	KR1020040009255A	公开(公告)日	2004-01-31
申请号	KR1020020043132	申请日	2002-07-23
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IPC分类号	G06K9/52 A61B8/08 G06K9/00 G06T7/00 A61B8/00 G06T1/00		
CPC分类号	A61B8/08 G06K9/00127 Y10S128/916 G06K9/52 G06T7/0012		
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其他公开文献	KR100490564B1		
外部链接	Espacenet		

摘要(译)

本发明提供了使用存储在特征向量中的长期类超声图像信号的平均向量和标准偏差向量来计算数据库长期类超声图像信号与输入超声图像信号之间的距离的装置和方法。输入超声图像信号的数据库并且以这种方式用于关于作为输入超声图像信号的长期的数据库超声图像信号中的最小距离下的超声图像信号的长期。超声图像信号，数据库，长期，距离，识别。

