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(54) **ULTRASONIC DIAGNOSTIC APPARATUS**

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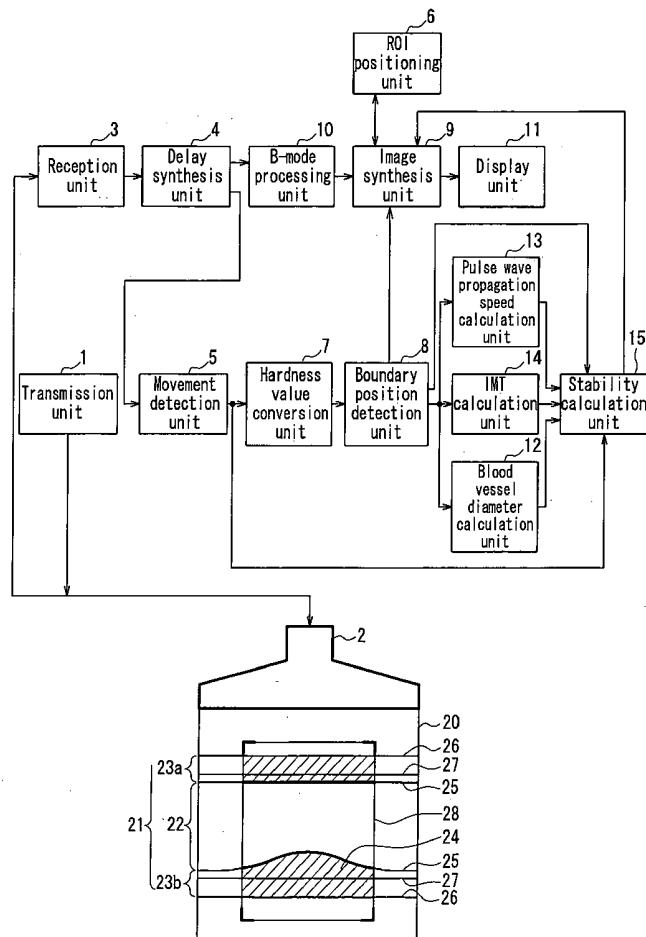
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(57) ABSTRACT

There are provided transmission means (1) for transmitting an ultrasonic signal from a surface of a skin of a subject toward a blood vessel (21) of the subject, reception means (3) for receiving a reflected ultrasonic echo and converting the ultrasonic echo into an electric signal to obtain the ultrasonic echo signal in a depth direction from the surface of the skin, movement detection means (5) for analyzing a phase of the ultrasonic echo signal in a direction traversing the blood vessel to calculate a movement amount in each of a plurality of regions including a blood vessel wall and a vicinity of the blood vessel wall, analysis means (7) for analyzing a state of the blood vessel based on a variation in the calculated movement amount in each of the regions, boundary position detection means (8) for detecting a boundary position between the blood vessel wall and a blood flow region of the blood vessel based on a result of the analysis by the analysis means, and stability judgment means (15) for comparing the detected boundary position with a detection result in a previous cycle.



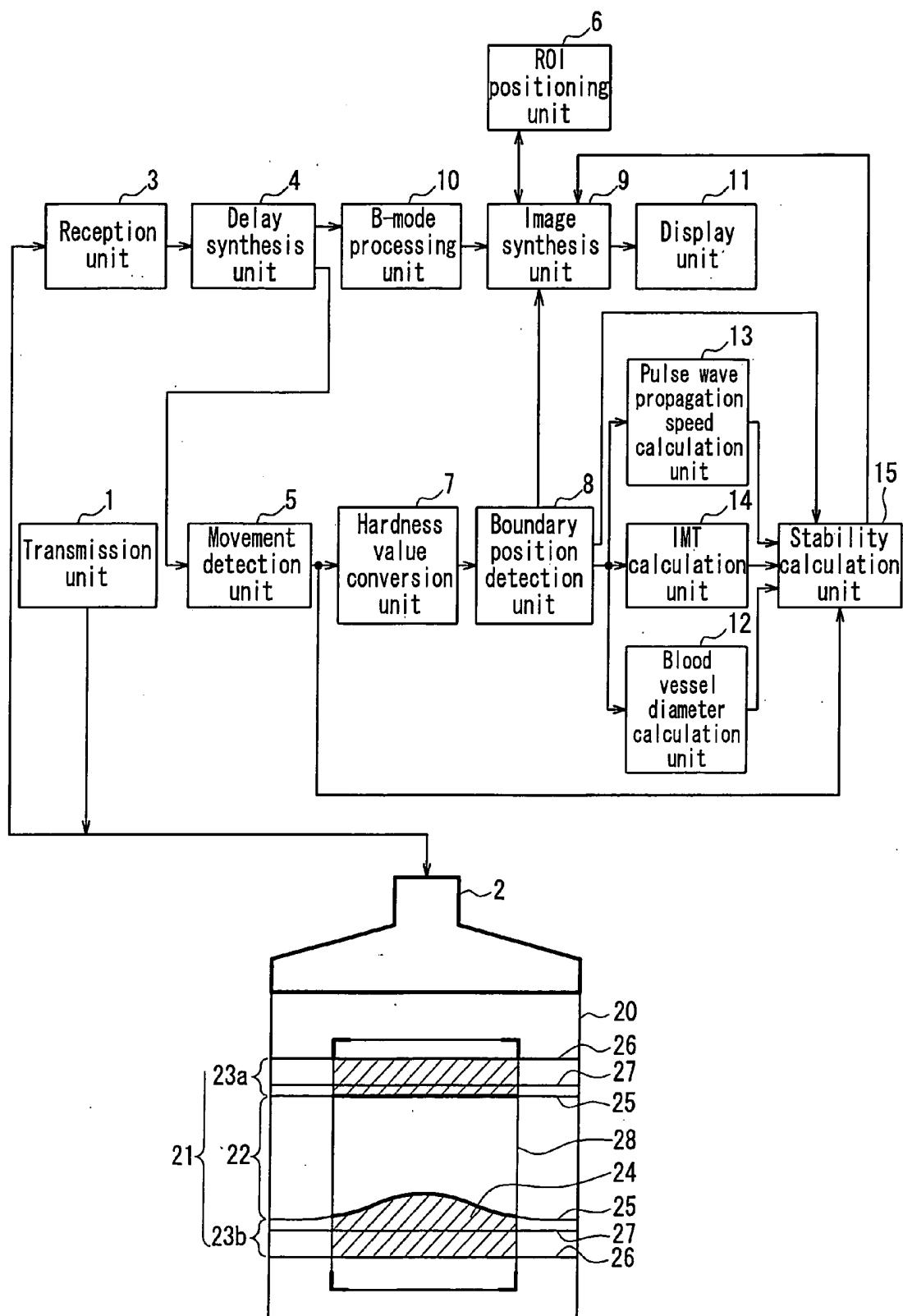


FIG. 1

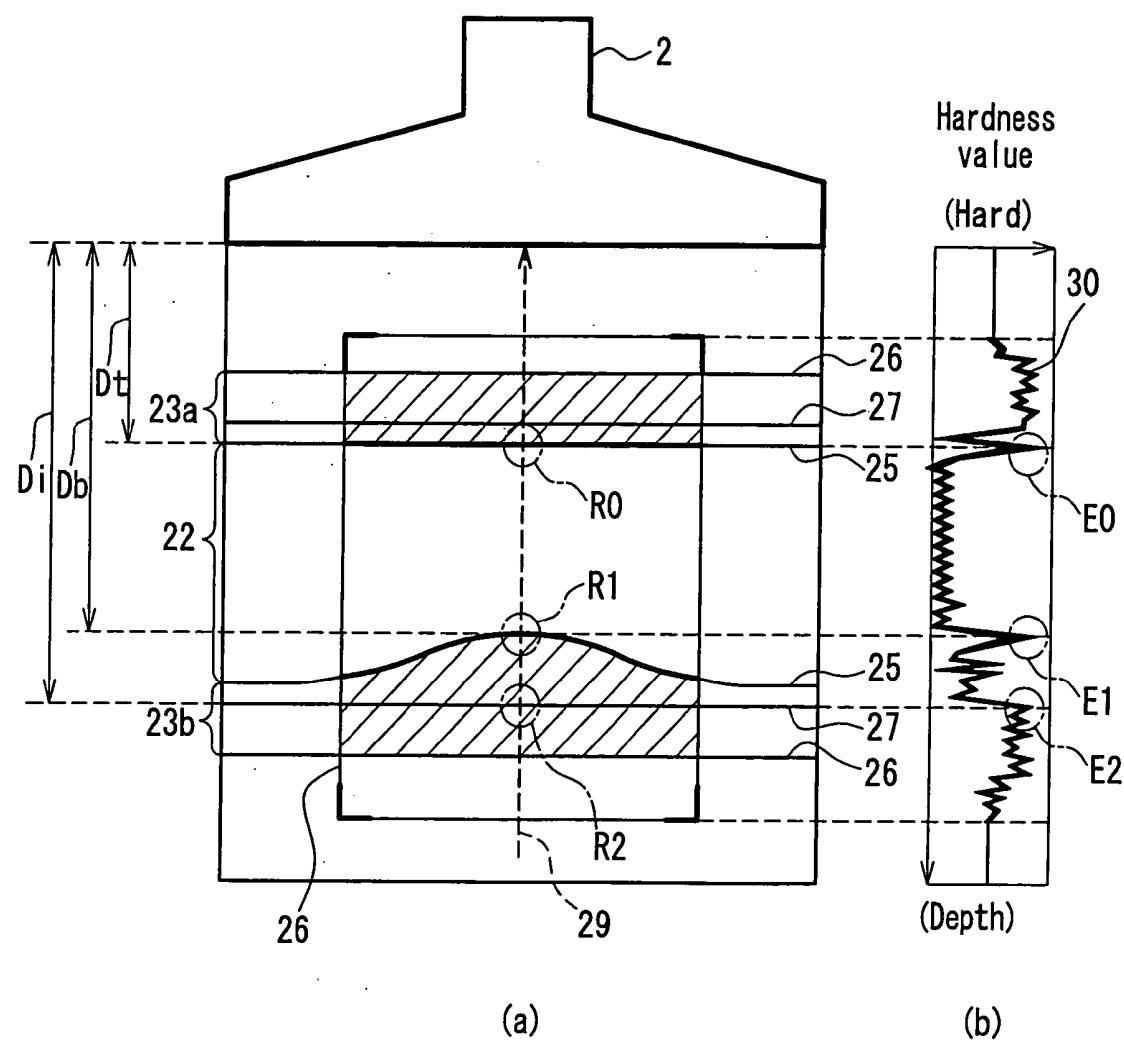


FIG. 2

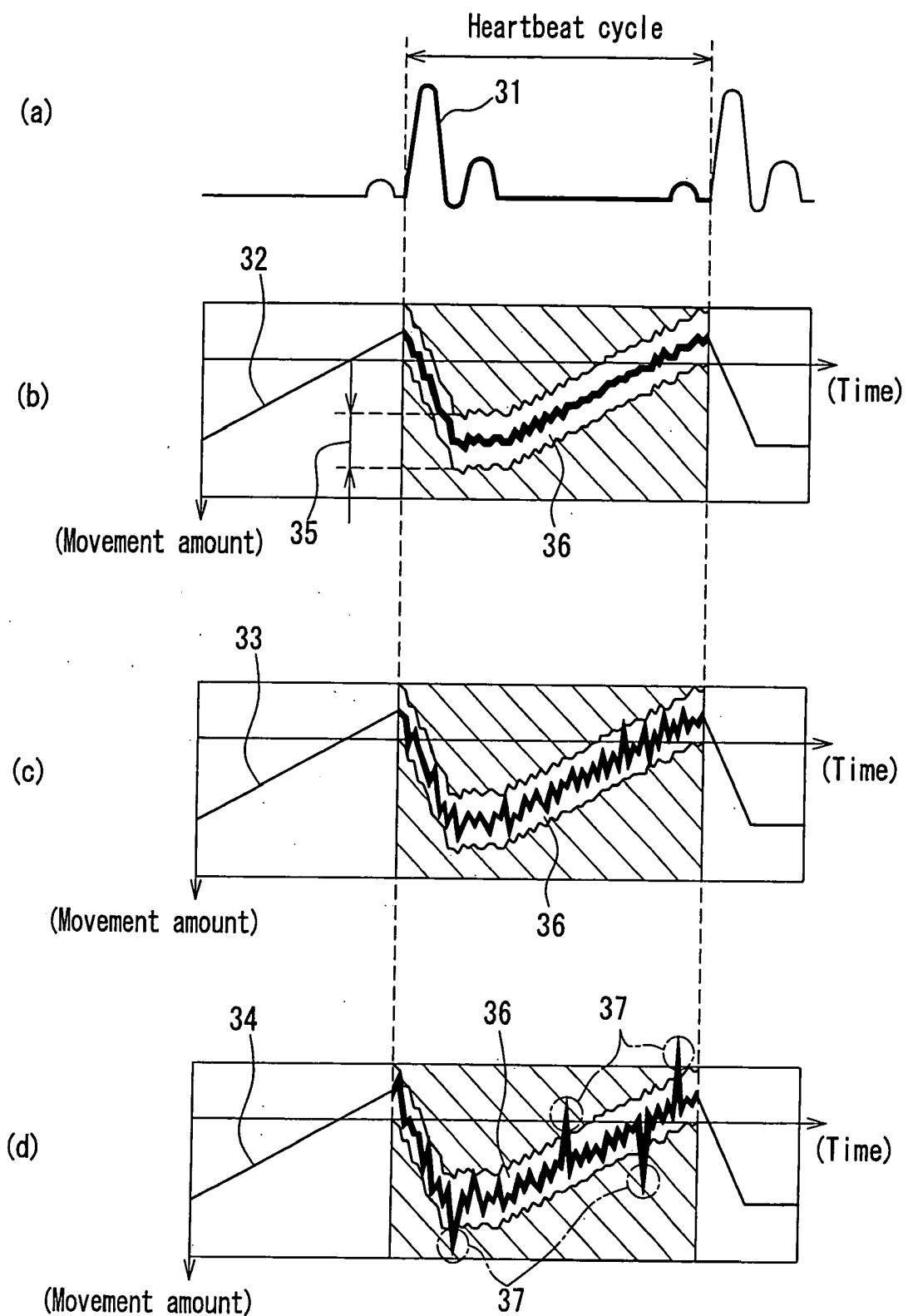


FIG. 3

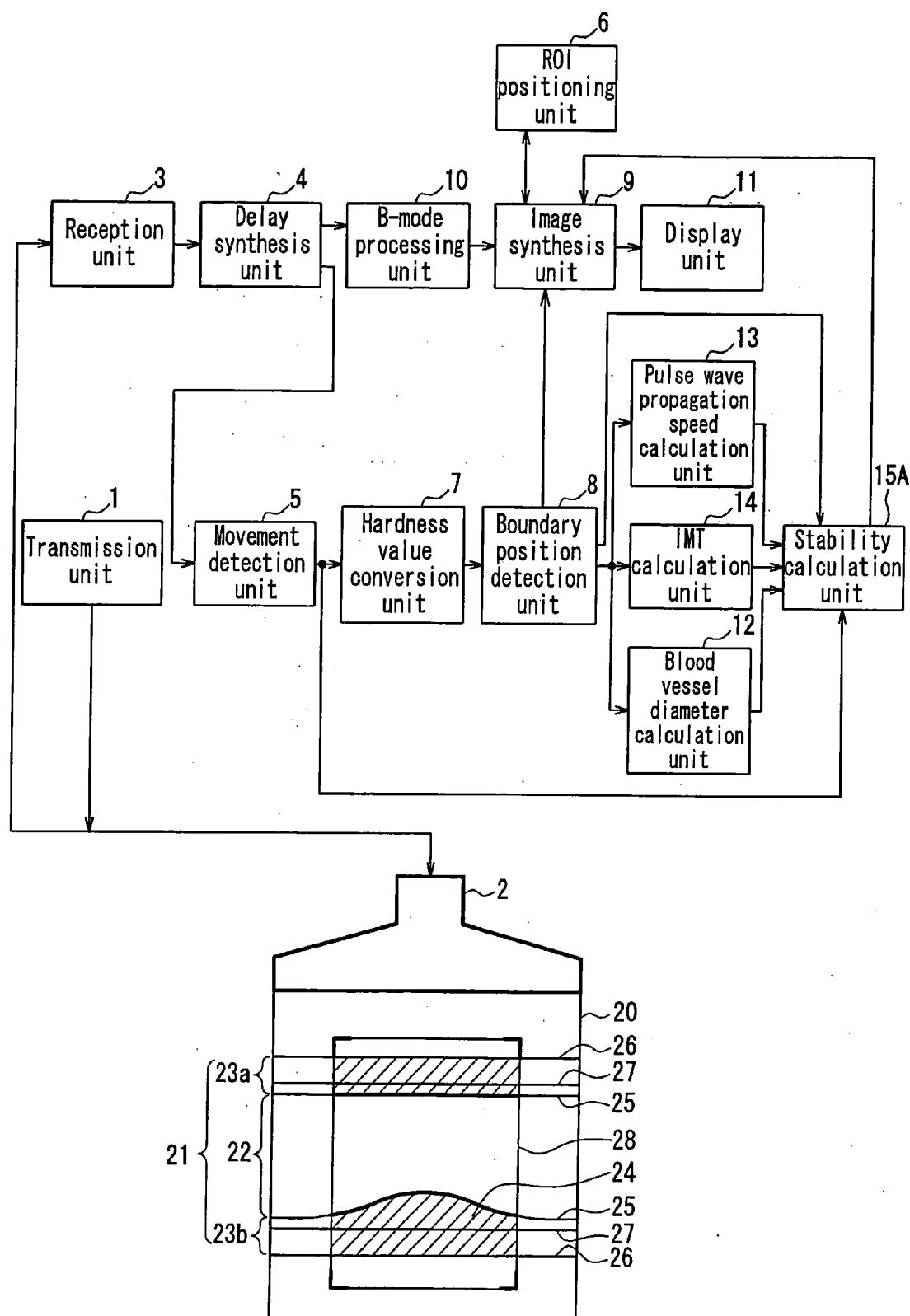


FIG. 4

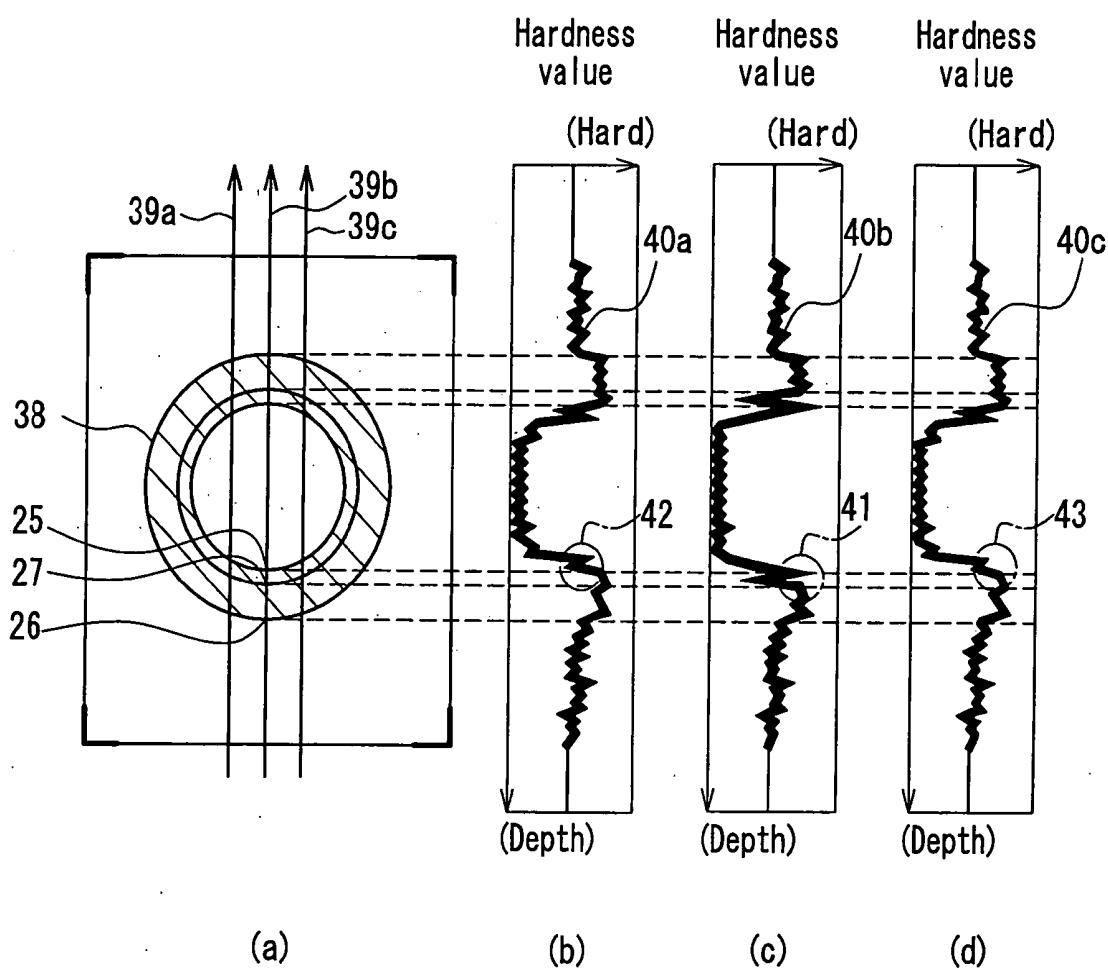


FIG. 5

ULTRASONIC DIAGNOSTIC APPARATUS

TECHNICAL FIELD

[0001] The present invention relates to an ultrasonic diagnostic apparatus having a function of determining a state of a blood vessel by ultrasonic waves.

BACKGROUND ART

[0002] It is known as a function of ultrasonic diagnostic apparatuses that ultrasonic pulses are transmitted from a surface of a skin of a subject toward a blood vessel of the subject, so as to carry out a measurement on various states of the blood vessel based on ultrasonic echo signals reflected by the blood vessel.

[0003] For example, a method of detecting the boundary of a blood vessel wall by ultrasonic waves is disclosed in JP 2000-271117 A. According to this method, assuming that a blood vessel has a standard structure, the displacement and diameter of a blood vessel, the thickness of a blood vessel wall, and the like are measured based on a maximum peak value and a second peak value of a luminance signal in image data obtained based on ultrasonic waves reflected by the blood vessel.

[0004] Further, a method of calculating a propagation speed of pulse waves in a blood vessel is disclosed in JP 11(1999)-76233 A. According to this method, a propagation speed of pulse waves is determined based on a variation with time in the cross-sectional shape of a blood vessel in a plurality of regions in a longitudinal direction of the blood vessel.

[0005] Further, Japanese Patent No. 2889568 discloses a method of detecting an IMT (Intima-Media Thickness) value of a blood vessel wall (carotid artery) by ultrasonic waves. According to this method, assuming that a blood vessel has a standard structure, an IMT value of a blood vessel wall (carotid artery) is measured based on a maximum peak value and a second peak value of a luminance signal in image data obtained based on ultrasonic waves reflected by the blood vessel.

[0006] However, in an actual medical diagnosis of a blood vessel, it is difficult in many cases to carry out a measurement in a stable state due to a variety of factors such as a state in which an ultrasonic probe is fixed, a stationary and respiratory state of a subject, and the like.

[0007] On this account, in an actual measurement, a large-scale device is used to fix a probe and a subject and the subject is requested to stop his/her breathing during the measurement, so that a measurement is more likely to be carried out stably. Further, the measurement is carried out a plurality of times and data that can be measured with accuracy are selected. Consequently, the measurement takes a long diagnosis time, and a constant measurement accuracy cannot be obtained by different operators. Also, for future use in the area of a diagnosis targeted for a large number of people, such as a medical examination, means for judging a state of stability of a measurement is being demanded.

DISCLOSURE OF INVENTION

[0008] An object of the present invention is to provide an ultrasonic diagnostic apparatus that is capable of judging a state of stability of a measurement.

[0009] An ultrasonic diagnostic apparatus according to the present invention includes: transmission means for transmitting at least one ultrasonic signal from a surface of a skin of a

subject toward a blood vessel of the subject; reception means for receiving an ultrasonic echo reflected by the blood vessel and converting the ultrasonic echo into an electric signal to obtain the ultrasonic echo signal in a depth direction from the surface of the skin; movement detection means for analyzing a phase of the ultrasonic echo signal in a direction traversing the blood vessel to calculate a movement amount in each of a plurality of regions including a blood vessel wall composing the blood vessel and a vicinity of the blood vessel wall; analysis means for analyzing a state of the blood vessel based on a variation in the calculated movement amount in each of the regions; boundary position detection means for detecting a boundary position between a blood flow region and the blood vessel wall of the blood vessel based on a result of the analysis by the analysis means; and stability judgment means for comparing the boundary position detected by the boundary position detection means with a detection result in a previous cycle.

[0010] This configuration makes it possible to judge the stability of the detection of the boundary position based on a result of comparing the detected boundary position between the blood flow region and the blood vessel wall with a detection result in a previous cycle. Consequently, an operator easily and promptly can be notified whether measured data are appropriate or not during a measurement.

[0011] Preferably, the above-mentioned configuration further includes an ROI (Region of Interest) positioning means for positioning an ROI where the boundary position in the depth direction from the surface of the skin is to be detected by the boundary position detection means, and the ROI positioning means positions the ROI so that the ROI lies astride at least one of an anterior wall of the blood vessel wall on a side closer to the transmission means and a posterior wall of the blood vessel wall on a side farther from the transmission means. This configuration allows reliable detection of the boundary position between the blood vessel wall and the blood flow region.

[0012] Preferably, the transmission means transmits a plurality of ultrasonic signals toward a plurality of regions in a longitudinal direction of the blood vessel, the boundary position detection means detects the plurality of boundary positions in the longitudinal direction of the blood vessel, and the stability judgment means compares the plurality of boundary positions detected by the boundary position detection means, thereby judging the stability of a result of the detection of the boundary positions. This configuration allows the judgment accuracy to be increased.

[0013] In the above-mentioned configuration, the boundary position detection means can detect the plurality of boundary positions in the depth direction from the surface of the skin, and a blood vessel diameter calculation means for calculating a diameter of the blood vessel based on the plurality of detected boundary positions further can be included. This configuration allows multifaceted detection of a state of the blood vessel.

[0014] The stability judgment means can compare the diameter of the blood vessel calculated by the blood vessel diameter calculation means with a calculation result in a previous cycle, thereby judging the stability of a result of the detection of the boundary positions. This configuration allows stable detection of a state of the blood vessel.

[0015] The boundary position detection means can detect the boundary positions in the plurality of regions in the longitudinal direction of the blood vessel, and a pulse wave

propagation speed calculation means for calculating a pulse wave propagation speed indicating a speed at which a pulse wave propagates, based on a variation with time in the plurality of boundary positions detected by the boundary position detection means further can be included. This configuration allows multifaceted detection of a state of the blood vessel.

[0016] The stability judgment means can compare the pulse wave propagation speed calculated by the pulse wave propagation speed calculation means with the pulse wave propagation speed calculated in a previous cycle, thereby judging the stability of a result of the calculation of the pulse wave propagation speed. This configuration allows stable detection of the pulse wave propagation speed.

[0017] The pulse wave propagation speed calculation means can calculate pulse wave propagation speeds in a plurality of adjacent regions in the longitudinal direction of the blood vessel, and the stability judgment means can compare the pulse wave propagation speeds in the plurality of adjacent regions, thereby judging the stability of the calculation of the pulse wave propagation speeds by the pulse wave propagation speed calculation means. This configuration allows the judgment accuracy to be increased.

[0018] The boundary position detection means can detect a boundary position between a tunica intima and the blood flow region of the blood vessel and a position of a tunica media of the blood vessel based on a hardness value of tissue in the depth direction, and the stability judgment means can compare the boundary position and the position of the tunica media detected by the boundary position detection means with the boundary position and the position of the tunica media calculated a predetermined number or more of cycles prior to the present cycle, thereby judging the stability of a result of the detection of the boundary position and the position of the tunica media. This configuration allows stable detection of the boundary position and the position of the tunica media.

[0019] The transmission means can transmit a plurality of ultrasonic signals toward a plurality of regions in the longitudinal direction of the blood vessel, the boundary position detection means can detect the boundary positions between the tunica intima and the blood flow region of the blood vessel and the positions of the tunica media of the blood vessel in a plurality of regions adjacent to each other in the longitudinal direction of the blood vessel, and the stability judgment means can compare the boundary positions and the positions of the tunica media adjacent to each other that are detected by the boundary position detection means, thereby judging the stability of the detection of the boundary positions and the positions of the tunica media by the boundary position detection means. This configuration allows stable detection of the boundary position and the position of the tunica media.

[0020] An IMT (Intima-Media Thickness) calculation means for measuring an IMT, which is a thickness from the tunica intima to the tunica media, based on a variation with time in the boundary position between the tunica intima and the blood flow region of the blood vessel and a variation with time in the position of the tunica media of the blood vessel further can be included, and the stability judgment means can judge the stability of a result of the detection of the boundary position by the boundary position detection means based on the IMT measured by the calculation means. This configuration allows stable detection of the boundary position.

[0021] The IMT calculation means can calculate the IMT values in a plurality of regions adjacent to each other in the longitudinal direction of the blood vessel, and the stability judgment means can compare the IMT values in the plurality of regions, thereby judging the stability of a result of the detection of the boundary position by the boundary position detection means. This configuration allows stable detection of the boundary position.

[0022] Display means for displaying the stability judged by the stability judgment means further can be included. This configuration allows visual recognition of the stability.

BRIEF DESCRIPTION OF DRAWINGS

[0023] FIG. 1 is a block diagram showing a configuration of an ultrasonic diagnostic apparatus according to a first embodiment of the present invention.

[0024] FIG. 2 is a schematic view for explaining an operation of the ultrasonic diagnostic apparatus shown in FIG. 1.

[0025] FIG. 3 is a schematic view for explaining another operation of the ultrasonic diagnostic apparatus shown in FIG. 1.

[0026] FIG. 4 is a block diagram showing a configuration of an ultrasonic diagnostic apparatus according to a second embodiment of the present invention.

[0027] FIG. 5 is a schematic view for explaining an operation of the ultrasonic diagnostic apparatus shown in FIG. 4.

DESCRIPTION OF THE INVENTION

[0028] Hereinafter, embodiments of the present invention will be described with reference to the drawings.

First Embodiment

[0029] FIG. 1 is a block diagram schematically showing a configuration of an ultrasonic diagnostic apparatus according to a first embodiment of the present invention. Note here that FIG. 1 also shows a B-mode image 20 received by the ultrasonic diagnostic apparatus. A transmission unit 1 generates an ultrasonic pulse and supplies it to an ultrasonic probe 2. The ultrasonic probe 2 transmits the ultrasonic pulse supplied from the transmission unit 1 from a surface of a skin of a living body toward the inside thereof. The B-mode image 20 is an image obtained when the ultrasonic pulse is transmitted toward a blood vessel 21.

[0030] In this image, the blood vessel 21 extends in a direction tilted with respect to the surface of the skin and is indicated by an anterior wall 23a and a posterior wall 23b that surround a blood flow region 22 in the lumen in which blood flows. The anterior wall 23a is a blood vessel wall on a side closer to the ultrasonic probe 2, and the posterior wall 23b is a blood vessel wall on a side farther from the ultrasonic probe 2. In this example, the blood vessel 21 has an atheroma 24 as a local disease that is developed on an inner surface of the posterior wall 23b.

[0031] The blood vessel wall shown as the anterior wall 23a and the posterior wall 23b includes a tunica intima 25 that is formed on an inner surface of the blood vessel wall and faces the blood flow region 22, a tunica adventitia 26 formed on an outer surface of the blood vessel wall, and a tunica media 27 formed between the tunica intima 25 and the tunica adventitia 26. In FIG. 8, the atheroma 24 as a local disease is developed between the tunica intima 25 and the tunica media 27.

[0032] An ultrasonic echo reflected by the blood vessel 21 is converted into an electric signal by the ultrasonic probe 2,

and the obtained ultrasonic echo signal is supplied to a movement detection unit **5** on one hand via a reception unit **3** and a delay synthesis unit **4**. The movement detection unit **5** detects a movement amount in each region in a depth direction from the surface of the skin based on the received ultrasonic echo signal. The detection of a movement amount in each region by the movement detection unit **5** can be carried out by a well-known method based on a phase change of the received signal, and thus a specific description will be omitted.

[0033] In the B-mode image **20**, an ROI (Region of Interest) **25** is shown that is provided for detecting a boundary position in the depth direction from the surface of the skin. The positioning of the ROI **28** in a tomographic image is set by an ROI positioning unit **6**. In order to achieve the object of the present embodiment, the ROI **28** is set so as to lie astride at least one of the anterior wall **23a** and the posterior wall **23b**. In the example shown in FIG. 1, the ROI **28** is positioned so as to lie astride both the anterior wall **23a** and the posterior wall **23b**. [0034] The movement amount detected by the movement detection unit **5** is supplied to a hardness value conversion unit **7**. The hardness value conversion unit **2** converts the movement amount detected by the movement detection unit **5** into a hardness value of tissue in the depth direction from the surface of the skin. For example, when a difference in the movement amount (thickness variation) between neighboring regions is analyzed from a variation in the movement amount in respective regions of the blood vessel wall, a large thickness variation is obtained in a soft region, while a small thickness variation is obtained in a hard region. Thus, based on this, the hardness value in each region can be detected. The hardness value of the tissue obtained by the hardness value conversion unit **7** is supplied to a boundary position detection unit **8**.

[0035] The boundary position detection unit **8** detects a boundary position between the tunica intima **25** and the blood flow region **22** of the blood vessel **21** and a position of the tunica media **27** based on the hardness value. Since the detection is carried out based on the hardness value of the tissue in the depth direction, by which a variation state of the tissue is clarified, the boundary position can be recognized automatically with a simple algorithm. Further, the boundary position detection unit **8** generates a two-dimensionally mapped color display image showing a cross section of the blood vessel **21**, and supplies it to an image synthesis unit **9**.

[0036] Instead of the hardness value conversion unit **7**, a method of analyzing another state of the blood vessel based on the movement amount detected by the movement detection unit **5** may be used, so that the boundary position detection unit **8** can detect the boundary position based on a result of that analysis. For example, when attention is given to a variation state (track) of the movement amount of the blood vessel in one heartbeat, the track has different characteristics such as a movement direction reversed between the blood flow region **22** and the posterior wall **23b**. Thus, by analyzing this, a middle point at which the track is reversed can be judged as the boundary position **25**.

[0037] The received signal that has passed through the reception unit **3** and the delay synthesis unit **4** is supplied also to a B-mode processing unit **10** on the other hand. The B-mode processing unit **10** generates image information showing the cross section of the blood vessel **21** based on the received signal, and supplies it to the image synthesis unit **9**. The image synthesis unit **9** synthesizes the image information supplied from the B-mode processing unit **10** and the bound-

ary information recognized automatically by the boundary position detection unit **8**, and displays the synthesis on a monitor of a display unit **11**.

[0038] The detection signal from the boundary position detection unit **8** is supplied also to a blood vessel diameter calculation unit **12**, a pulse wave propagation speed calculation unit **13**, an IMT calculation unit **14**, and a stability judgment unit **15**.

[0039] The blood vessel diameter calculation unit **12** calculates a diameter of the lumen of the blood vessel **21** based on a plurality of boundary positions recognized automatically by the boundary position detection unit **8**. The pulse wave propagation speed calculation unit **13** calculates a pulse wave propagation speed indicating a speed at which a pulse wave propagates, based on a variation with time in the plurality of boundary positions recognized automatically by the boundary position detection unit **8**. More specifically, the boundary position detection unit **8** detects the boundary positions in a plurality of regions in a longitudinal direction of the blood vessel, and supplies them to the pulse wave propagation speed calculation unit **13**. The pulse wave propagation speed calculation unit **13** calculates a pulse wave propagation speed based on a variation with time in the plurality of boundary positions. A specific method of the calculation is disclosed in JP 11(1999)-76233 A.

[0040] The IMT calculation unit **14** uses the detection signal output from the boundary position detection unit **8** to measure the thickness of the tunica media **27** as an IMT value based on a variation with time in the boundary position between the tunica intima **25** and the blood flow region **22** and a variation with time in the position of the tunica media **27** in one heartbeat cycle. The IMT calculation unit **14** calculates at least one of a maximum value, a minimum value, and an average value of the IMT value in one heartbeat cycle.

[0041] The outputs from the blood vessel diameter calculation unit **12**, the pulse wave propagation speed calculation unit **13**, and the IMT calculation unit **14** are supplied to a stability judgment unit **15**. The stability judgment unit **15** has a function of judging the stability of a measurement. The stability judgment unit **15** is supplied with the detection signals from the movement detection unit **5** and the boundary position detection unit **8** and judges the stability based on those signals. For example, the stability judgment unit **15** compares the movement amount of the blood vessel wall calculated by the movement detection unit **5** with the movement amount of the blood vessel wall calculated a predetermined number or more of cycles prior to the present cycle, thereby judging the stability of the result of the detection of the movement amount of the blood vessel wall by the movement detection unit **5**. A detailed operation thereof will be described later.

[0042] FIG. 2 is a schematic view for explaining an operation of the ultrasonic diagnostic apparatus according to the present embodiment. In FIG. 2, (a) shows an image that is the same as the B-mode image **20** shown in FIG. 1. Reference numeral **29** denotes a single scanning line indicating a track of an ultrasonic wave transmitted from the ultrasonic probe **2**. In the figure, (b) shows a hardness value **27** of the tissue that is obtained by the hardness value conversion unit **7** for each portion on the scanning line **29**.

[0043] Herein, attention is given to a point R0 on the tunica intima **25** of the anterior wall **23a** on a side closer to the surface of the skin, a point R1 on the tunica intima **25** of the posterior wall **23b** on a side farther from the surface of the

skin, and a point R2 on the tunica media 27 of the posterior wall 23b on the scanning line 29. The point R0 is located at a position at a depth Dt from the surface of the skin, the point R1 is located at a position at a depth Db from the surface of the skin, and the point R2 is located at a position at a depth Di from the surface of the skin. The hardness value at the points R0, R1, and R2 is represented by E0, E1, and E2, respectively, in (b).

[0044] The hardness value 30 in the depth direction from the surface of the skin is far lower in the blood flow region 22 than on the blood vessel wall. On this account, based on the hardness value 30, the boundary position between the blood flow region 22 and the tunica intima 25 easily can be recognized automatically with a simple algorithm.

[0045] In addition, the inner diameter of the blood vessel can be calculated by the following Formula (1), and the IMT value can be calculated automatically by incorporating the following Formula (2) into an algorithm.

$$\text{Inner diameter of blood vessel} = Db - Dt \quad (1)$$

$$IMT = Di - Db \quad (2)$$

[0046] Herein, Di-Db corresponds to the thickness from the tunica intima to the tunica media.

[0047] Further, when the transmission unit 3 transmits a plurality of ultrasonic signals toward a plurality of regions in the longitudinal direction of the blood vessel 21, and the same processing as above is performed with respect to a plurality of scanning lines 29 corresponding to a plurality of ultrasonic echo signals, it is possible to obtain distributions of the propagation speed of a pulse wave, the hardness value, and the like in the longitudinal direction of the blood vessel 21.

[0048] Next, the operation of the stability judgment unit 15 will be described with reference to FIG. 3. As mentioned above, in an actual medical diagnosis of a blood vessel, it is difficult to carry out a measurement in a stable state due to a variety of factors such as a state in which the ultrasonic probe 2 is fixed, a stationary and respiratory state of a subject, and the like. Consequently, in reality a large-scale device is used to fix the probe 2 and a subject and the subject is requested to stop his/her breathing during a measurement, so that a measurement is more likely to be carried out stably. Further, the measurement is carried out a plurality of times and data that can be measured with accuracy are selected. As a result, the measurement takes a long diagnosis time, and moreover a constant measurement accuracy cannot be obtained by different operators.

[0049] When ideal measured data are obtained in a state in which the positional relationship between a subject and the ultrasonic probe 2 is constant or a state in which the subject is in a stable state by stopping his/her breathing, the blood vessel wall has a closely analogous movement track during each heartbeat. Based on this, the stability of the measurement for detecting the IMT value itself is judged.

[0050] FIG. 3 is a schematic view for explaining the operation of the stability judgment unit 15. In the figure, (a) shows an ECG (Electrocardiograph) waveform 28. Waveforms shown in (b) to (d) indicate movement tracks 32, 33, and 34, respectively, of the blood vessel wall in respective measuring cycles synchronized with a heartbeat cycle of the ECG waveform 31 shown in (a). The movement track 32 shown in (b) is measured in a cycle immediately preceding the cycles in which the movement tracks 33 and 34 shown in (c) and (d) are measured.

[0051] In (b) of FIG. 3, a tolerance 33 is shown that allows for a permissible error 35 with respect to the movement track 32 in the immediately preceding cycle. The tolerance 36 is compared with a movement track in the subsequent measuring cycle. For example, in the case of the movement track 30 shown in (c) that is within the tolerance 36 at any points, it is judged that a stable measurement has been carried out. In the case of the movement track 31 shown in (d) that has improper points 37 out of the tolerance 36, it is judged that a measurement has been carried out unstably.

[0052] When an operator is notified of information indicating whether a measurement has been carried out stably or unstably in real time, the operator can judge during the measurement whether the present measurement result is reliable or not. Consequently, a measuring time can be made shorter.

[0053] Further, the stability judgment unit 15 can compare the boundary position between the blood flow region 22 and the tunica intima 25 and the position of the tunica media 27 that are detected by the boundary position detection unit 8 with the boundary position and the position of the tunica media 27 calculated a predetermined number or more of cycles prior to the present cycle, thereby judging the stability of the result of the detection of the boundary position and the position of the tunica media 27.

[0054] Further, the stability judgment unit 15 may judge whether a measurement has been carried out stably or unstably based on a difference between the measurement result in the present cycle and that in the immediately preceding cycle. Alternatively, the stability judgment unit 15 may judge whether a measurement has been carried out stably or unstably based on a comparison with stable movement tracks measured not only in the immediately preceding cycle but also in a plurality of past cycles. Further, the threshold value (permissible error 35) for the judgment as to whether a measurement has been carried out stably or unstably may be changed.

[0055] Further, the boundary position detection unit 8 can detect a plurality of boundary positions in the longitudinal direction of the blood vessel 21, and the stability judgment unit 15 can compare the plurality of boundary positions detected by the boundary position detection unit 8, thereby judging the stability of the result of the detection of the boundary positions.

[0056] In the present embodiment, the stability judgment unit 15 also can judge the stability of a measurement based on the output from the blood vessel diameter calculation unit 12, the pulse wave propagation speed calculation unit 13, or the IMT calculation unit 14 in the following manner. For example, the stability judgment unit 15 compares the diameter of the blood vessel calculated by the blood vessel diameter calculation unit 12 with a calculation result in a previous cycle, thereby judging the stability of the result of the detection of the boundary position between the blood flow region 22 and the tunica intima 25. Alternatively, the stability judgment unit 15 compares the pulse wave propagation speed calculated by the pulse wave propagation speed calculation unit 13 with that calculated in a previous cycle, thereby judging the stability of the result of the calculation of the pulse wave propagation speed. Alternatively, the pulse wave propagation speed calculation unit 13 calculates pulse wave propagation speeds in a plurality of adjacent regions in the longitudinal direction of the blood vessel, and the stability judgment unit 15 compares the pulse wave propagation speeds in the plurality of adjacent regions, thereby judging the stability of the result of the calculation of the pulse wave

propagation speeds. Alternatively, the IMT calculation unit **14** calculates IMT values in a plurality of regions adjacent to each other in the longitudinal direction of the blood vessel **21**, and the stability judgment unit **15** compares the IMT values in the plurality of regions, thereby judging the stability of the result of the detection of the boundary position by the boundary position detection unit **6**.

[0057] Further, the stability judgment unit **15** may compare a value of, for example, pseudo boundary judgment position, which is obtained from an echo brightness value unsuitable for judging a boundary, in the present cycle with that in the immediately preceding cycle. By combining a plurality of such functions of judging the measurement stability, the reliability of a measurement result can be increased further.

Second Embodiment

[0058] FIG. 4 is a block diagram showing a configuration of an ultrasonic diagnostic apparatus according to a second embodiment. Components common to those of the ultrasonic diagnostic apparatus according to the first embodiment shown in FIG. 1 are denoted with the same reference numerals, and repeated descriptions will be omitted.

[0059] In the present embodiment, a stability judgment unit **15A** has a different configuration from that of the stability judgment unit **15** in FIG. 1. The stability judgment unit **15A** compares boundary positions and positions of the tunica media adjacent to each other in a direction traversing the blood vessel **21**, the positions being detected by the boundary position detection unit **8**, thereby judging the stability of the detection of the boundary positions and the positions of the tunica media by the boundary position detection unit **8**.

[0060] FIG. 5 is a schematic view for explaining an operation of the ultrasonic diagnostic apparatus according to the present embodiment. In FIG. 5, (a) shows a cross section **38** of the blood vessel. A measurement is performed such that three scanning lines **39a**, **39b**, and **39c** pass through the cross section **38** of the blood vessel. In the Figure, (b) to (d) show hardness values **40a**, **40b**, and **40c** measured by the scanning lines **39a**, **39b**, and **39c**, respectively.

[0061] With respect to the hardness value **40b** corresponding to the scanning line **39b** that passes exactly through the center of the blood vessel, an ultrasonic echo signal has a clearer intensity difference because an ultrasonic signal impinges upon a wall surface and a film surface almost vertically. Thus, a clear peak waveform **41** for separating the tunica intima **25** and the tunica media **27** is obtained. On the other hand, with respect to the hardness values **40a** and **40c** corresponding to the scanning lines **39a** and **39c**, respectively, that do not pass exactly through the center of the blood vessel, the ultrasonic echo signal has an unclear intensity difference on the wall surface and the film surface, and waveforms **42** and **43** do not have their peaks. Consequently, it is difficult to separate the tunica intima **25** and the tunica media **27**, and the IMT value cannot be obtained.

[0062] With the use of such characteristics of the hardness value, when the IMT value can be measured stably, it is possible to judge whether a path of the ultrasonic wave indicated by the scanning line is exactly through the center of the cross section of the blood vessel. Thus, the stability of a measurement itself by the ultrasonic diagnostic apparatus can be judged.

[0063] Further, the stability of the measurement can be judged by simultaneously referring to the results of the measurement of the IMT values in a plurality of regions in the

direction traversing the blood vessel. Further, in combination with a comparison with the IMT value in the immediately preceding cycle or the like, the reliability of the measurement can be increased further.

[0064] As described above, the stability (constancy) of a measurement itself can be judged based on the fact that the center of the cross section of the blood vessel has to be captured at all times when the IMT value is measured.

[0065] Further, when an operator is notified of information indicating the stability (constancy) of a measurement itself in real time, the operator can judge during the measurement whether the present measurement result is reliable or not. Consequently, a measuring time can be made shorter.

INDUSTRIAL APPLICABILITY

[0066] According to the present invention, it is possible to provide the ultrasonic diagnostic apparatus that is capable of judging a state of stability of a measurement.

1. An ultrasonic diagnostic apparatus, comprising:
transmission means for transmitting at least one ultrasonic signal from a surface of a skin of a subject toward a blood vessel of the subject;
reception means for receiving an ultrasonic echo reflected by the blood vessel and converting the ultrasonic echo into an electric signal to obtain the ultrasonic echo signal in a depth direction from the surface of the skin;
movement detection means for analyzing a phase of the ultrasonic echo signal in a direction traversing the blood vessel to calculate a movement amount in each of a plurality of regions including a blood vessel wall composing the blood vessel and a vicinity of the blood vessel wall;
analysis means for analyzing a state of the blood vessel based on a variation in the calculated movement amount in each of the regions;
boundary position detection means for detecting a boundary position between a blood flow region and the blood vessel wall of the blood vessel based on a result of the analysis by the analysis means; and
stability judgment means for comparing the boundary position detected by the boundary position detection means with a detection result in a previous cycle.

2. The ultrasonic diagnostic apparatus according to claim 1, further comprising an ROI (Region of Interest) positioning means for positioning an ROI where the boundary position in the depth direction from the surface of the skin is to be detected by the boundary position detection means,

wherein the ROI positioning means positions the ROI so that the ROI lies astride at least one of an anterior wall of the blood vessel wall on a side closer to the transmission means and a posterior wall of the blood vessel wall on a side farther from the transmission means.

3. The ultrasonic diagnostic apparatus according to claim 1, wherein the transmission means transmits a plurality of ultrasonic signals toward a plurality of regions in a longitudinal direction of the blood vessel, the boundary position detection means detects the plurality of boundary positions in the longitudinal direction of the blood vessel, and the stability judgment means compares the plurality of boundary positions detected by the boundary position detection means, thereby judging stability of a result of the detection of the boundary positions.

4. The ultrasonic diagnostic apparatus according to claim 1, wherein the boundary position detection means detects the plurality of boundary positions in the depth direction from the surface of the skin,

the apparatus further comprising a blood vessel diameter calculation means for calculating a diameter of the blood vessel based on the plurality of detected boundary positions.

5. The ultrasonic diagnostic apparatus according to claim 4, wherein the stability judgment means compares the diameter of the blood vessel calculated by the blood vessel diameter calculation means with a calculation result in a previous cycle, thereby judging stability of a result of the detection of the boundary positions.

6. The ultrasonic diagnostic apparatus according to claim 1, wherein the boundary position detection means detects the boundary positions in the plurality of regions in the longitudinal direction of the blood vessel,

the apparatus further comprising a pulse wave propagation speed calculation means for calculating a pulse wave propagation speed indicating a speed at which a pulse wave propagates, based on a variation with time in the plurality of boundary positions detected by the boundary position detection means.

7. The ultrasonic diagnostic apparatus according to claim 6, wherein the stability judgment means compares the pulse wave propagation speed calculated by the pulse wave propagation speed calculation means with the pulse wave propagation speed calculated in a previous cycle, thereby judging stability of a result of the calculation of the pulse wave propagation speed.

8. The ultrasonic diagnostic apparatus according to claim 6, wherein the pulse wave propagation speed calculation means calculates pulse wave propagation speeds in a plurality of adjacent regions in the longitudinal direction of the blood vessel, and the stability judgment means compares the pulse wave propagation speeds in the plurality of adjacent regions, thereby judging stability of a result of the calculation of the pulse wave propagation speeds.

9. The ultrasonic diagnostic apparatus according to claim 1, wherein the boundary position detection means detects a boundary position between a tunica intima and the blood flow region of the blood vessel and a position of a tunica media of the blood vessel based on a hardness value of tissue in the depth direction, and the stability judgment means compares the boundary position and the position of the tunica media

detected by the boundary position detection means with the boundary position and the position of the tunica media calculated a predetermined number or more of cycles prior to the present cycle, thereby judging stability of a result of the detection of the boundary position and the position of the tunica media.

10. The ultrasonic diagnostic apparatus according to claim 1, wherein the transmission means transmits a plurality of ultrasonic signals toward a plurality of regions in the longitudinal direction of the blood vessel, the boundary position detection means detects the boundary positions between the tunica intima and the blood flow region of the blood vessel and the positions of the tunica media of the blood vessel in a plurality of regions adjacent to each other in the longitudinal direction of the blood vessel, and the stability judgment means compares the boundary positions and the positions of the tunica media adjacent to each other that are detected by the boundary position detection means, thereby judging stability of the detection of the boundary positions and the positions of the tunica media by the boundary position detection means.

11. The ultrasonic diagnostic apparatus according to claim 1, further comprising an IMT (Intima-Media Thickness) calculation means for measuring an IMT, which is a thickness from the tunica intima to the tunica media, based on a variation with time in the boundary position between the tunica intima and the blood flow region of the blood vessel and a variation with time in the position of the tunica media of the blood vessel,

wherein the stability judgment means judges stability of a result of the detection of the boundary position by the boundary position detection means based on the IMT measured by the IMT calculation means.

12. The ultrasonic diagnostic apparatus according to claim 11, wherein the IMT calculation means calculates the IMT values in a plurality of regions adjacent to each other in the longitudinal direction of the blood vessel, and the stability judgment means compares the IMT values in the plurality of regions, thereby judging stability of a result of the detection of the boundary position by the boundary position detection means.

13. The ultrasonic diagnostic apparatus according to claim 1, further comprising display means for displaying the stability judged by the stability judgment means.

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摘要(译)

提供了传输装置(1)，用于将来自受试者皮肤表面的超声信号传输到受试者的血管(21)，接收装置(3)，用于接收反射的超声回波并将超声回波转换成用于从皮肤表面沿深度方向获得超声回波信号的电信号，用于分析超声回波信号在穿过血管的方向上的相位的运动检测装置(5)，以计算每个中的移动量。包括血管壁和血管壁附近的多个区域，用于基于每个区域中计算的移动量的变化分析血管状态的分析装置(7)，边界位置检测装置(8)用于根据分析装置的分析结果检测血管壁和血管的血流区域之间的边界位置，并且稳定性判断意味着s(15)，用于将检测到的边界位置与前一周期中的检测结果进行比较。

