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CONTROL METHOD OF ULTRASOUND
ENDOSCOPE SYSTEM****Publication Classification**(51) **Int. Cl.**
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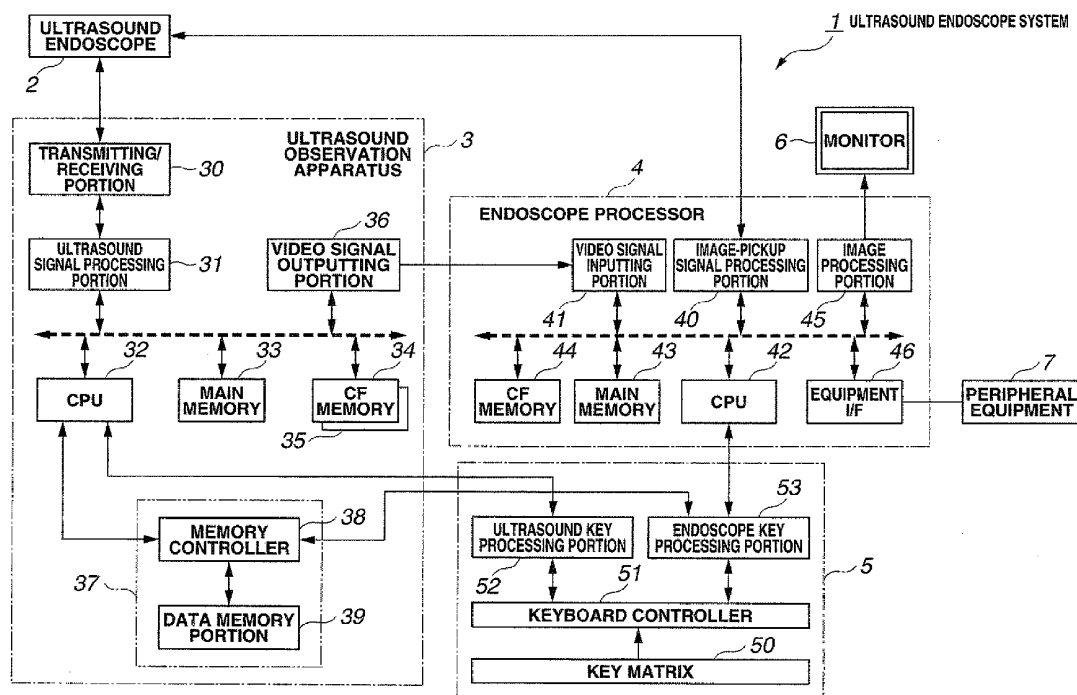
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(57) **ABSTRACT**

In the present invention, an ultrasound observation apparatus includes an information reposition portion; the information reposition portion is a storage portion for storing various state information in an endoscope processor inputted from a keyboard and is configured to include a memory controller and a data memory portion. Moreover, the keyboard is configured to include a key matrix, a keyboard controller, an ultrasound key processing portion and an endoscope key processing portion. This configuration allows the ultrasound observation apparatus to easily share various state information of a plurality of apparatuses making up the system.



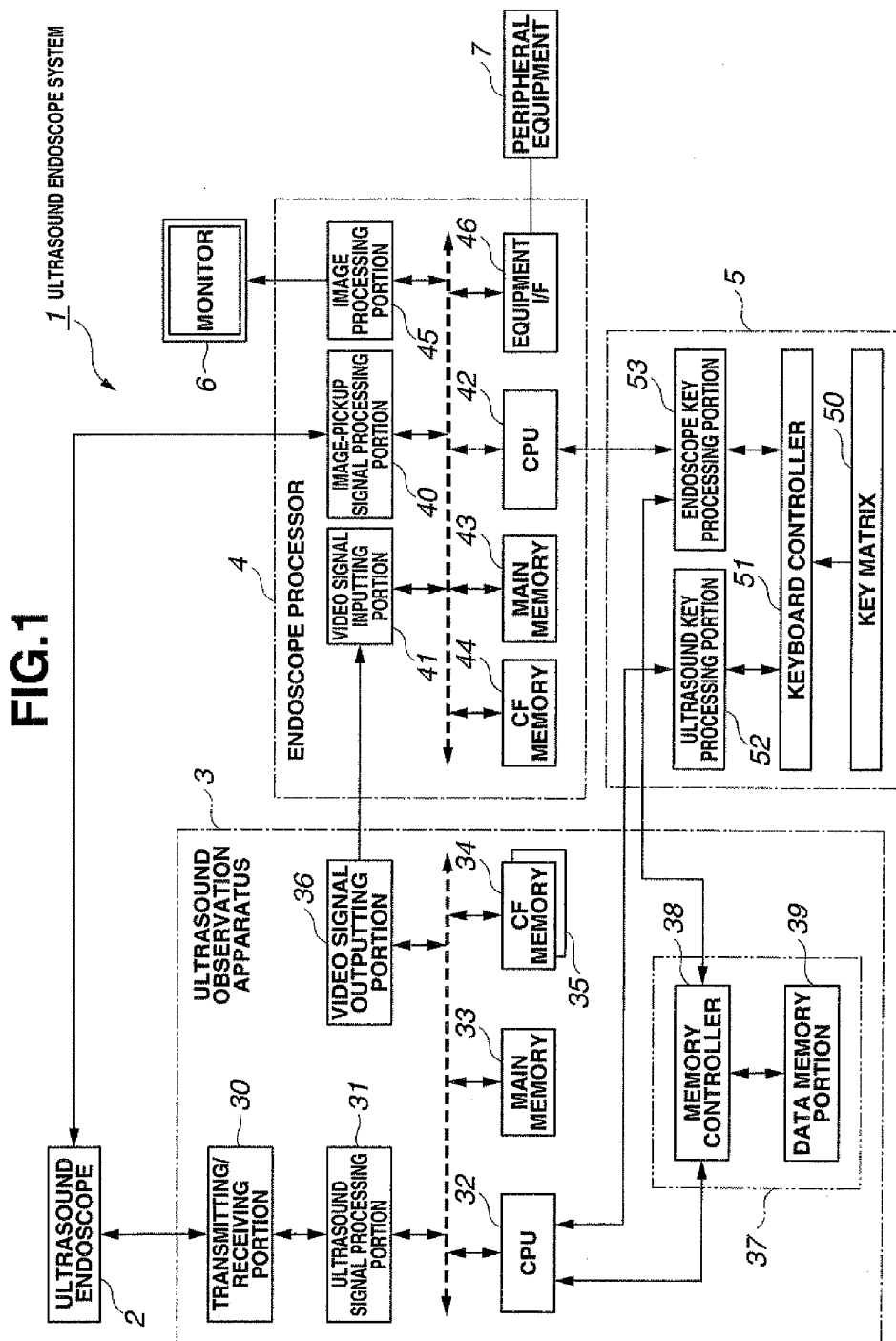


FIG.2

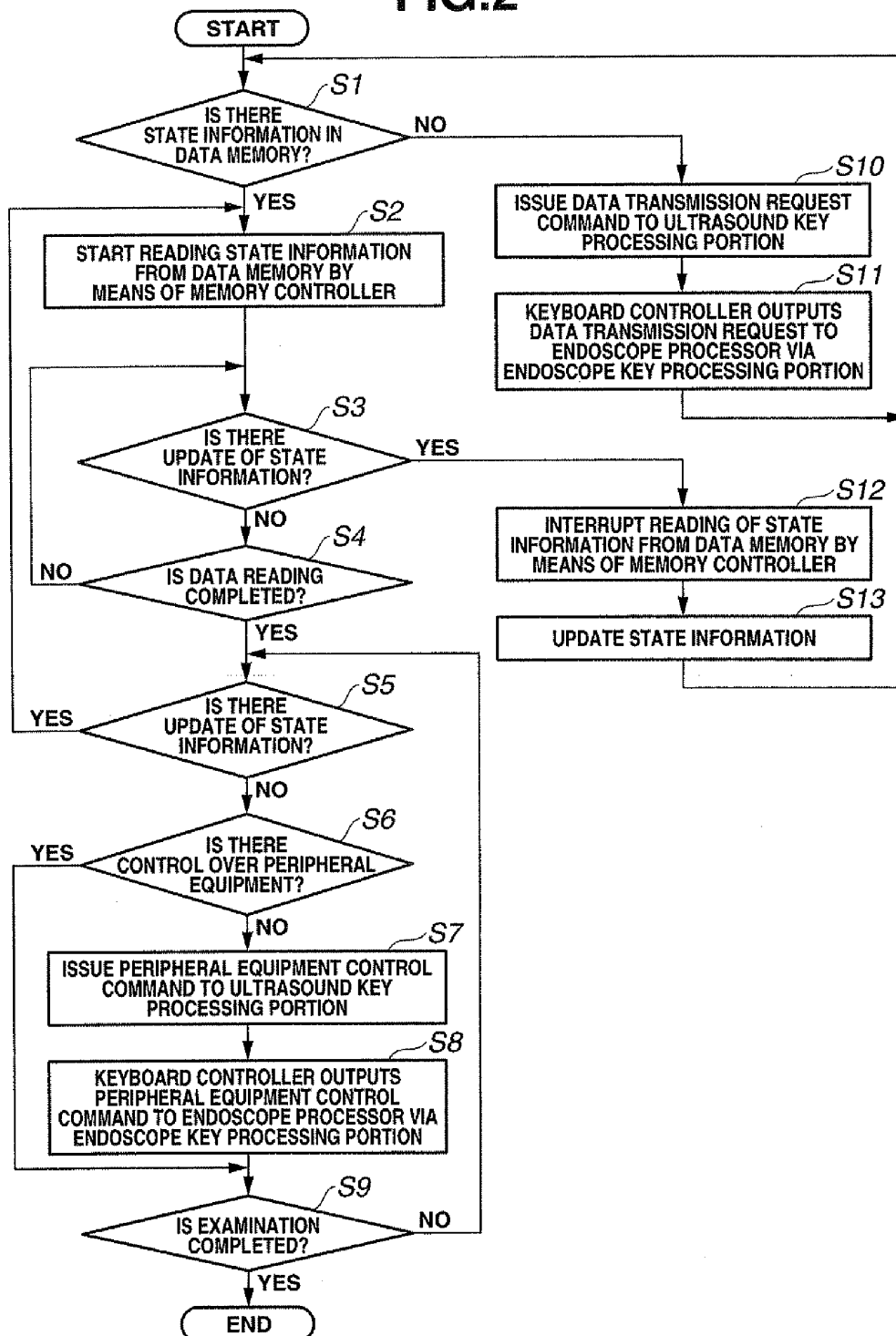


FIG.3

	BEFORE-READING	AFTER-READING
SETTING STATE INFORMATION READ-IN FLAG: Flag 1	ON	OFF
OPERATION STATE INFORMATION READ-IN FLAG: Flag 2	ON	OFF

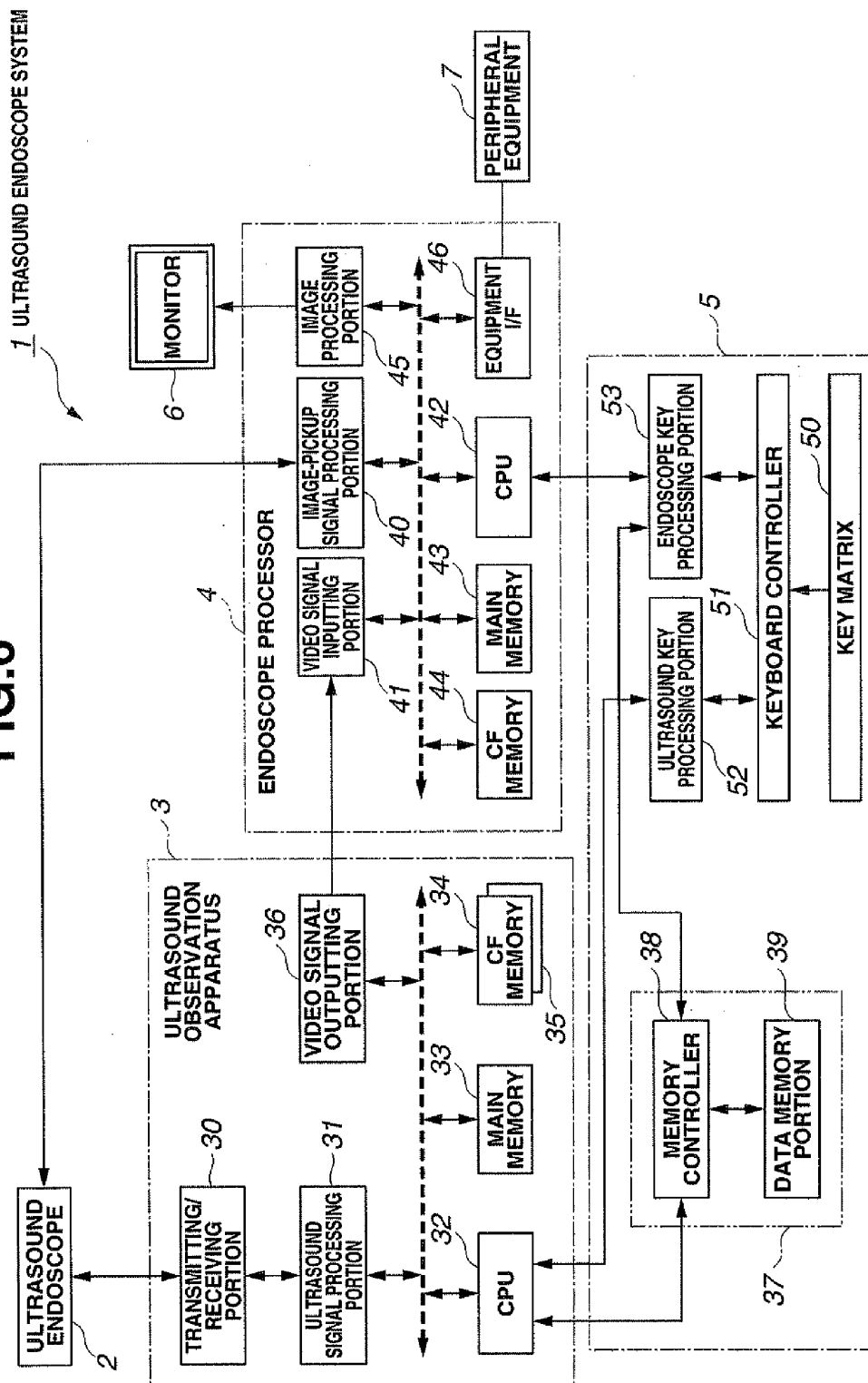
FIG.4

	ULTRASOUND ENDOSCOPE OPERATION PORTION SWITCH			
	SWITCH 1	SWITCH 2	SWITCH 3	SWITCH 4
ULTRASOUND CONTROL MODE	ULTRASOUND FUNCTION 1	ULTRASOUND FUNCTION 2	ULTRASOUND FUNCTION 3	ULTRASOUND FUNCTION 4
ENDOSCOPE CONTROL MODE	ENDOSCOPE FUNCTION 1	ENDOSCOPE FUNCTION 2	ENDOSCOPE FUNCTION 3	ENDOSCOPE FUNCTION 4

FIG.5

ADDRESS	DATA	CONTENT OF DATA
00	01234	PATIENT ID
01	Ichiro Suzuki	PATIENT NAME
02	28/Feb./1950	DATE OF BIRTH
03	male	SEX
04	2605L-1	NAME OF ENDOSCOPE PROCESSOR
05~	:	IMAGE DATA

FIG. 6



ULTRASOUND ENDOSCOPE SYSTEM AND CONTROL METHOD OF ULTRASOUND ENDOSCOPE SYSTEM

CROSS REFERENCE TO RELATED APPLICATION

[0001] This application claims benefit of Japanese Patent Application No. 2007-098853 filed on Apr. 4, 2007, the contents of which are incorporated by this reference.

BACKGROUND OF THE INVENTION

[0002] 1. Field of the Invention

[0003] The present invention relates to an ultrasound endoscope system and a control method of the ultrasound endoscope system, and more particularly to an ultrasound endoscope system made up of an ultrasound observation apparatus, an endoscope processor, and a keyboard connected to both the foregoing equipment, and a control method of the ultrasound endoscope system.

[0004] 2. Description of the Related Art

[0005] In recent years, ultrasound endoscope systems which are made up of an ultrasound observation apparatus for endoscope (hereinafter abbreviated as an ultrasound observation apparatus), an endoscope processor, and a plurality of peripheral equipment connected to both the foregoing equipment are proposed in, for example, Japanese Patent Application Laid-Open No. 2005-143582, and Japanese Patent Application Laid-Open No. 2005-177348.

[0006] The ultrasound observation apparatus is configured to include a control circuit which causes an ultrasound tomography image (hereinafter, simply referred to as an ultrasound image) to be displayed on a display portion, the ultrasound image being obtained from a signal generated by performing a predetermined signal processing based on an ultrasound signal obtained by inserting an ultrasound endoscope, which is provided in the distal end portion with an ultrasound transducer, into a body cavity and driving the ultrasound transducer to transmit/receive an ultrasound, as well as controls the entire system.

[0007] The ultrasound endoscope is provided at the distal end of its insertion portion with an image pickup device etc.; the endoscope processor receives an image signal obtained by the ultrasound endoscope and subjects it to a predetermined signal processing to generate a signal, by which an endoscope image is displayed on the display portion.

[0008] Ultrasound diagnostic apparatus systems (or ultrasound endoscope systems), in which the above described two equipment are electrically connected with a plurality of peripheral equipment, for example, a printer (a video printer etc.), an information recording apparatus (an image file system etc.), an information inputting apparatus (a card reader etc.), and an operation instruction inputting apparatus (a keyboard etc.), have been commercialized and in widespread use.

[0009] Conventionally, after an ultrasound endoscope system is constructed by electrically connecting the ultrasound observation apparatus and the endoscope processor with respective peripheral equipment by using a connection cable; the setting etc. of the ultrasound observation apparatus and the endoscope processor, and the peripheral equipment connected thereto are all manually performed by a user or equipment administrator (hereinafter referred to as a user etc.) based on technical data (hereinafter simply referred to as an

instruction manual etc.) such as an instruction manual, a sales manual, and a connection wiring diagram corresponding to each equipment.

[0010] On the other hand, some of conventional ultrasound endoscope systems are configured to include an operation instruction inputting apparatus such as a keyboard (hereinafter simply referred to as a keyboard) in order to convey an instruction signal etc. to the ultrasound observation apparatus and the endoscope processor. In some cases, the keyboard is electrically connected to the both equipment respectively: the ultrasound observation apparatus and the endoscope processor, so that one keyboard can be used in common for both the equipment.

[0011] The system of Japanese Patent Application Laid-Open No. 2005-143582 is an ultrasound diagnostic apparatus system made up of an ultrasound observation apparatus, an endoscope processor, and a plurality of peripheral equipment connected to both the foregoing equipment, the system being configured to include a system setting portion provided in any one of the ultrasound observation apparatus and the endoscope processor, a communication portion for transferring the information set by the system setting portion to the other of the ultrasound observation apparatus and the endoscope processor, and an operation setting modification portion for performing its own setting based on the system setting information transferred from the communication portion.

[0012] Further, the system of Japanese Patent Application Laid-Open No. 2005-177348 is an ultrasound diagnostic apparatus system made up of an ultrasound observation apparatus, an endoscope processor, and a plurality of peripheral equipment including an operation portion connected to both the foregoing equipment, wherein the ultrasound observation apparatus comprises a control circuit which comprises: a first storage portion for prestoring one or both of online manual information and help information relating to the system; a second storage portion for storing a usage situation of the system whenever necessary; and a selection portion for displaying information selected based on each information stored in the first storage portion and the second storage portion, on a display apparatus; and wherein the selection portion reads usage situation information stored in the second storage portion upon receiving an instruction signal from the operation portion, and reads information corresponding to the usage situation information from the first storage portion to transfer it to the display apparatus.

SUMMARY OF THE INVENTION

[0013] The ultrasound endoscope system of the present invention comprises:

[0014] an ultrasound endoscope which is inserted into a body cavity to acquire ultrasound data in the body cavity and optical image data in the body cavity;

[0015] an ultrasound observation apparatus for applying data processing to the ultrasound data to generate an ultrasound image;

[0016] an endoscope processor for applying data processing to the optical image data to generate an endoscope image;

[0017] an information inputting portion for inputting information to the ultrasound observation apparatus and the endoscope processor;

[0018] an information reposition portion which allows setting state information provided by the information inputting portion for one of the ultrasound observation apparatus and the endoscope processor to be written therein via the infor-

mation inputting portion, as well as allows the written setting state information to be read therefrom at the other of the ultrasound observation apparatus and the endoscope processor; and

[0019] an information reposition control portion for controlling the writing/reading of the information of the information reposition portion.

[0020] Other features and benefits of the present invention will be made clear by the following description.

BRIEF DESCRIPTION OF THE DRAWINGS

[0021] FIGS. 1 to 6 relate to embodiment 1 of the present invention, in which

[0022] FIG. 1 is a configuration diagram to show the configuration of an ultrasound endoscope system;

[0023] FIG. 2 is a flowchart to show the flow of processing in the ultrasound observation apparatus of FIG. 1;

[0024] FIG. 3 illustrates the flag of a memory controller in the processing of FIG. 2;

[0025] FIG. 4 illustrates the function of an operation switch provided in the ultrasound endoscope in the processing of FIG. 2;

[0026] FIG. 5 shows an example of the data format of the data file repositioned in the information reposition portion of FIG. 1; and

[0027] FIG. 6 is a configuration diagram to show the configuration of a variation of the ultrasound endoscope system of FIG. 1.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

Embodiment 1

[0028] As shown in FIG. 1, an ultrasound endoscope system 1 is configured to include: an ultrasound endoscope 2 which is inserted into a body cavity to pick up an ultrasound echo signal and an image within the body cavity; an ultrasound observation apparatus 3 for driving an ultrasound device (not shown) of the ultrasound endoscope 2 and applying signal processing to the ultrasound echo signal to generate an ultrasound image; an endoscope processor 4 for driving an image pickup device (such as a CCD and a CMOS, not shown) of the ultrasound endoscope 2 and applying signal processing to an image pickup signal to generate an endoscope image; and a keyboard 5 for inputting various instruction signals to the ultrasound observation apparatus 3 and the endoscope processor 4.

[0029] The ultrasound observation apparatus 3 is configured to include a transmitting/receiving portion 30, an ultrasound signal processing portion 31, a CPU 32, a main memory 33, two Compact Flash (™) memories (CF memories) 34, 35, a video signal outputting portion 36, and an information reposition portion 37.

[0030] The transmitting/receiving portion 30 transmits a drive signal to the ultrasound device of the ultrasound endoscope 2 and receives an ultrasound echo signal from the ultrasound device.

[0031] The ultrasound signal processing portion 31 is a processing portion for generating the above described drive signal and generating various ultrasound images (such as a B mode image and a doppler image) from the ultrasound echo signal. Details thereof will be omitted because they are known.

[0032] The CPU 32 is a control portion for controlling the entire ultrasound observation apparatus 3 and is operated by a system program stored in the main memory 33.

[0033] The CF memory 34 is a storage portion for storing an application program activated by the CPU 32; and the CF memory 35 is a storage portion for storing an ultrasound image generated at the ultrasound signal processing portion 31.

[0034] The video signal outputting portion 36 outputs the ultrasound image generated at the ultrasound signal processing portion 31 or the ultrasound image stored in the CF memory 35, to the endoscope processor 4.

[0035] The information reposition portion 37 is a storage portion for storing various state information in the endoscope processor 4 inputted by the keyboard 5, and is configured to include a memory controller 38 as the information reposition control portion and a data memory portion 39 as the information reposition portion. The memory controller 38 manages the writing and reading at the data memory portion 39 and transmits/receives data to/from the CPU 32 and a later-described endoscope key processing portion 53 of the keyboard 5.

[0036] The endoscope processor 4 is configured to include an image-pickup signal processing portion 40, a video signal inputting portion 41, a CPU 42, a main memory 43, a CF memory 44, an image processing portion 45, and an equipment I/F portion 46.

[0037] The image-pickup signal processing portion 40 transmits a drive signal to the image pickup device of the ultrasound endoscope 2, receives an image pickup signal from the image pickup device, performs a predetermined signal processing on the received image pickup signal, and generates an endoscope image. Details thereof will be omitted because they are known.

[0038] The video signal inputting portion 41 is an inputting portion for inputting an ultrasound image from the video signal outputting portion 36 of the ultrasound observation apparatus 3.

[0039] The CPU 42 is a control portion for controlling the entire endoscope processor 4, and is operated by a system program stored in the main memory 43.

[0040] The CF memory 44 is a storage portion for storing endoscope images generated at the image-pickup signal processing portion 40 and ultrasound images inputted from the video signal inputting portion 41.

[0041] Moreover, ultrasound image data in real time is stored in the main memory 43. Further, the CF memory 44 is a memory for data saving connected via a card slot (not shown).

[0042] The image processing portion 45 is a processing portion for generating a display image in order to display the endoscope image and the ultrasound image stored in the CF memory 44 on a monitor 6.

[0043] The equipment I/F portion 46 is an interface for transmitting/receiving data to/from various peripheral equipment 7 such as a printer apparatus (a video printer) and an information recording apparatus (image filing apparatus).

[0044] The keyboard 5 is configured to include a key matrix 50, a keyboard controller 51, an ultrasound key processing portion 52 and an endoscope key processing portion 53.

[0045] The key matrix 50 is configured to include a group of switches made up of a plurality of switches for inputting data.

[0046] The keyboard controller **51** is a control portion for managing the operational state of the plurality of switches of the key matrix **50** and controlling the entire keyboard **5**.

[0047] The ultrasound key processing portion **52** outputs the data inputted at the key matrix **50** to the CPU **32** of the ultrasound observation apparatus **3** based on the control by the keyboard controller **51** and outputs a control command from the CPU **32** of the ultrasound observation apparatus **3** to the keyboard controller **51**. Here, the control command from the CPU **32** of the ultrasound observation apparatus **3**, which is, for example, a command to perform recording to the peripheral equipment **7** as a recording target of ultrasound images, is transmitted to the CPU **42** of the endoscope processor **4** via the keyboard controller **51** and the endoscope key processing portion **53**.

[0048] The endoscope key processing portion **53** outputs the data inputted at the key matrix **50** based on the control by the keyboard controller **51** to the CPU **42** of the endoscope processor **4** and the memory controller **38** of the ultrasound observation apparatus **3**, as well as outputs the control command from the CPU **32** of the ultrasound observation apparatus **3** to the CPU **42** of the endoscope processor **4** through the keyboard controller **51**.

[0049] Next, description will be made on the action of the present embodiment configured as so far described. When the ultrasound endoscope system **1** made up of the ultrasound observation apparatus **3** and the endoscope processor **4** is constructed, the keyboard controller **51** of the keyboard **5** controls the endoscope key processing portion **53**. Then the endoscope key processing portion **53** outputs the data inputted at the key matrix **50** to the CPU **42** of the endoscope processor **4** and the memory controller **38** of the ultrasound observation apparatus **3** based on the control by the keyboard controller **51**.

[0050] By this operation, the CPU **42** of the endoscope processor **4** recognizes patient information (information such as patient ID, patient name, patient age, and patient sex) as setting state information from the keyboard **5** and reposit the recognized patient information in the CF memory **44**.

[0051] Simultaneously, the memory controller **38** of the ultrasound observation apparatus **3** inputs the patient information from the endoscope key processing portion **53** and reposit it in the data memory portion **39**. Then, the memory controller **38** sets a setting state information read-in flag, Flag **1**, which is a flag for the CPU **32** of the ultrasound observation apparatus **3**, into an ON state which indicates a "before-reading" state (see FIG. 3).

[0052] Then, as shown in FIG. 2, the CPU **32** of the ultrasound observation apparatus **3** judges if there is before-reading state information (which has not been read) in the data memory portion **39** of the information reposition portion **37** through the setting state information read-in flag, Flag **1**, at step **S1**.

[0053] The CPU **32** of the ultrasound observation apparatus **3** performs this judgment through the flags (Flag **1**, Flag **2**) as shown in FIG. 3, which are managed by the memory controller **38** of the information reposition portion **37**. Flag **1** is a flag for managing the setting state information, and Flag **2** is a flag for managing the operation state information of the endoscope processor **4**.

[0054] Specifically, the setting state information, which is patient information (patient's ID, name, age, sex, etc.) or state information of setting value information (image processing setting values such as luminance, contrast, etc.) inputted from

the keyboard **5** to the endoscope processor **4**, is inputted into the memory controller **38** via the endoscope key processing portion **53** to be reposit in the data memory portion **39**. The above described Flag **1** is a flag for managing the reading of the reposit setting state information in the data memory portion **39**.

[0055] Further, the operation state information, which is state information to show the control state at the endoscope processor **4** (for example, an allocation state of the operation switches of the ultrasound endoscope **2** as shown in FIG. 4, a connection state of peripheral equipment connected to the endoscope processor **4**, and the like) is inputted into the memory controller **38** and reposit in the data memory portion **39**. The above described Flag **2** is a flag for managing the reading of the reposit operation state information at the data memory portion **39**.

[0056] If the CPU **32** of the ultrasound observation apparatus **3** judges that there is before-reading state information (which has not been read) in the data memory portion **39** of the information reposition portion **37** through the flag of the memory controller **38** (Flag **1**, Flag **2**; see FIG. 3), the CPU **32** of the ultrasound observation apparatus **3** starts the read processing of the before-reading state information from the data memory portion **39** by means of the memory controller **38** at step **S2**.

[0057] Then, the CPU **32** of the ultrasound observation apparatus **3** judges if there is an update of state information to the data memory portion **39** (an update of setting information at the keyboard **5** or an update of operation state at the endoscope processor **4**) through the flag of the memory controller **38** (Flag **1**, Flag **2**; see FIG. 3) at step **S3**.

[0058] Then, when judging that there is no update of state information, the CPU **32** of the ultrasound observation apparatus **3** judges if the reading of data is completed at step **S4**, and repeats step **S3** and step **S4** until the reading of data is completed.

[0059] Upon completion of the reading of data, the CPU **32** of the ultrasound observation apparatus **3** again judges if there is an update of state information to the data memory portion **39** (an update of setting information at the keyboard **5** or an update of operation state at the endoscope processor **4**) at step **S5** through the flag of the memory controller **38** (Flag **1**, Flag **2**; see FIG. 3). When there is a data update, the process returns to step **S3**, and when there is no data update, advances to step **S6**.

[0060] The CPU **32** of the ultrasound observation apparatus **3** judges if there is control over the peripheral equipment **7** (for example, data recording control of ultrasound image etc. to an information recording apparatus (an image filing apparatus), which is the peripheral equipment **7**) at the ultrasound observation apparatus **3** at step **S6**. When there is control over the peripheral equipment **7**, the process advances to step **S7**, and when there is no control over the peripheral equipment **7**, advances to step **S9**.

[0061] At step **S7**, the CPU **32** of the ultrasound observation apparatus **3** issues a control command for the peripheral equipment to the ultrasound key processing portion **52**. Then, at step **S8**, the keyboard controller **51** inputs the control command through the ultrasound key processing portion **52**, and farther outputs the control command to the CPU **42** of the endoscope processor **4** via the endoscope key processing portion **53**.

[0062] Then, at step **S9**, until the examination at the ultrasound endoscope system **1** is completed, the CPU **32** of the

ultrasound observation apparatus 3 repeats the processing of the above described step S5 to step S9.

[0063] Further, at step S1, when judging that there is no before-reading state information (which has not been read) in the data memory portion 39 of the information reposition portion 37, through the flag, Flag 1, the CPU 32 of the ultrasound observation apparatus 3 issues a data-transmission request command to the ultrasound key processing portion 52 at step S10.

[0064] Then, at step S11, the keyboard controller 51 inputs the data-transmission request command via the ultrasound key processing portion 52, and further outputs the data-transmission request command to the CPU 42 of the endoscope processor 4 via the endoscope key processing portion 53.

[0065] The data-transmission request command causes the CPU 42 of the endoscope processor 4 to output the state information, which has been requested via the endoscope key processing portion 53, to the CPU 32 of the ultrasound observation apparatus 3.

[0066] Further when the CPU 32 of the ultrasound observation apparatus 3 judges that there is an update of the state information (an update of setting information at the keyboard 5 or an update of operation state at the endoscope processor 4) for the data memory portion 39, through the flag (Flag 1, Flag 2: see FIG. 3) of the memory controller 38 at step S3, the process advances to step S11.

[0067] At step S11, the CPU 32 of the ultrasound observation apparatus 3 controls the memory controller 38 to interrupt the reading of the data memory portion. Then, the CPU 32 of the ultrasound observation apparatus 3 waits for an update of the state information, and the process returns to step S1.

[0068] As so far described, according to the present embodiment, since when setting state information including the patient information is inputted into the endoscope processor 4 with the keyboard 5, the setting state information is automatically repositioned in the data memory portion 39 of the ultrasound observation apparatus 3, the CPU 32 of the ultrasound observation apparatus 3 can recognize the setting state information of the endoscope processor 4 repositioned in the data memory portion 39 via the memory controller 38. That is, the ultrasound observation apparatus 3 can easily share the setting state information with the endoscope processor 4 without need of any operation.

[0069] The CPU 32 of the ultrasound observation apparatus 3 can recognize the operation state information of the endoscope processor 4 repositioned in the data memory portion 39, and can transmit for example a control command for the peripheral equipment 7 to the CPU 42 of the endoscope processor 4 successively via the ultrasound key processing portion 52, the keyboard controller 51, and the endoscope key processing portion 53 of the keyboard 5, to control the peripheral equipment 7.

[0070] Since the CPU 32 of the ultrasound observation apparatus 3 can transmit such a control command to the CPU 42 of the endoscope processor 4 not through a predetermined protocol communication, but via the keyboard 5 based on the operation state information repositioned in the data memory portion 39, the ultrasound observation apparatus 3 can easily control the peripheral equipment 7 without needing any communication sequence.

[0071] Moreover, the ultrasound endoscope 2 has a plurality of operation portion switches in the operation portion and

as shown in FIG. 4, the functions of the plurality of operation portion switches are set by the operation mode of the ultrasound endoscope system 1.

[0072] Specifically, the functions of the plurality of operation portion switches are set by an endoscope control mode by the endoscope processor 4 and an ultrasound control mode by the ultrasound endoscope 2 based on the operation state information of the endoscope processor 4 and are stored in the data memory portion 39.

[0073] Then, in the endoscope control mode, the plurality of operation portion switches provide switches for each actuating endoscope function (such as a release function and a freeze function of endoscope image) under the control by the endoscope processor 4. Further, in the ultrasound control mode, the plurality of operation portion switches provide switches for each actuating the ultrasound function (such as a release function and a freeze function of ultrasound image) under the control by the endoscope processor 4. For example, a freeze operation of ultrasound image is enabled by a switch in the endoscope.

[0074] Here, the data format of the data file stored in the information reposition portion 37 is shown in FIG. 5. Since, as shown by the data format of FIG. 5, there is a unique name (for example, "2605L-1") of the endoscope processor 4 in the data file, even if the version of the data format is changed and the number and length of the shared data are changed corresponding to the connected endoscope processor, it is possible to cope with those changes while maintaining the compatibility of the data file.

[0075] Moreover, as shown in FIG. 1, the information reposition portion 37 is supposed to be provided in the ultrasound observation apparatus 3, but without being limited to that, the information reposition portion 37 may be provided in the keyboard 5 as shown in FIG. 6.

[0076] Furthermore, though not shown, configuration may be such that the information reposition portion 37 is provided in the endoscope processor 4, and the function of the ultrasound key processing portion 52 is replaced by the function of the endoscope key processing portion 53; for example, configuration may be such that various state information set in the ultrasound observation apparatus 3 via the ultrasound key processing portion 52 is shared by the endoscope processor 4 and the ultrasound observation apparatus 3 by means of the information reposition portion 37.

[0077] In the present invention, it is obvious that different embodiments in a wide range may be configured based on the present invention without being deviated from the spirit and scope of the present invention. The present invention will not be limited by particular embodiments thereof other than being limited by the appended claims.

What is claimed is:

1. An ultrasound endoscope system, comprising:
 - an ultrasound endoscope which is inserted into a body cavity to acquire ultrasound data in the body cavity and optical image data in the body cavity;
 - an ultrasound observation apparatus for applying data processing to the ultrasound data to generate an ultrasound image;
 - an endoscope processor for applying data processing to the optical image data to generate an endoscope image;
 - an information inputting portion for inputting information to the ultrasound observation apparatus and the endoscope processor;

- an information reposition portion which allows setting state information provided by the information inputting portion for one of the ultrasound observation apparatus and the endoscope processor to be written via the information inputting portion, as well as allows the written setting state information to be read at the other of the ultrasound observation apparatus and the endoscope processor; and
- an information reposition control portion for controlling the writing/reading of the information of the information reposition portion.
2. The ultrasound endoscope system according to claim 1, wherein the setting state information stored by the information reposition portion is patient information, and setting value information for one of the ultrasound observation apparatus and the endoscope processor.
3. The ultrasound endoscope system according to claim 1, wherein the information reposition control portion controls the writing/reading of operation state information in one of the ultrasound observation apparatus and the endoscope processor into/from the information reposition portion.
4. The ultrasound endoscope system according to claim 2, wherein the information reposition control portion controls the writing/reading of operation state information in one of the ultrasound observation apparatus and the endoscope processor into/from the information reposition portion.
5. The ultrasound endoscope system according to claim 1, wherein the information reposition control portion outputs a control command for controlling one of the ultrasound observation apparatus and the endoscope processor from the other of the ultrasound observation apparatus and the endoscope processor to the one of the ultrasound observation apparatus and the endoscope processor.
6. The ultrasound endoscope system according to claim 2, wherein the information reposition control portion outputs a control command for controlling one of the ultrasound observation apparatus and the endoscope processor from the other of the ultrasound observation apparatus and the endoscope processor to the one of the ultrasound observation apparatus and the endoscope processor.
7. The ultrasound endoscope system according to claim 3, wherein the information reposition control portion outputs a control command for controlling one of the ultrasound observation apparatus and the endoscope processor from the other of the ultrasound observation apparatus and the endoscope processor to the one of the ultrasound observation apparatus and the endoscope processor.
8. The ultrasound endoscope system according to claim 4, wherein the information reposition control portion outputs a control command for controlling one of the ultrasound observation apparatus and the endoscope processor from the other of the ultrasound observation apparatus and the endoscope processor to the one of the ultrasound observation apparatus and the endoscope processor.
9. The ultrasound endoscope system according to claim 1, wherein the information inputting portion is a keyboard.
10. The ultrasound endoscope system according to claim 2, wherein the information inputting portion is a keyboard.
11. A control method of an ultrasound endoscope system, wherein the ultrasound endoscope system comprises:
- an ultrasound endoscope which is inserted into a body cavity to acquire ultrasound data within the body cavity and optical image data within the body cavity,
- an ultrasound observation apparatus for applying data processing to the ultrasound data to generate an ultrasound image;
- an endoscope processor for applying data processing to the optical image data to generate an endoscope image; and
- an information inputting portion for inputting information to the ultrasound observation apparatus and the endoscope processor, and wherein the control method comprises:
- an information reposition step for writing setting state information provided by the information inputting portion for one of the ultrasound observation apparatus and the endoscope processor via the information inputting portion, as well as reading the written setting state information at the other of the ultrasound observation apparatus and the endoscope processor; and
- an information reposition control step for controlling the writing/reading of information in the information reposition step.
12. The control method of an ultrasound endoscope system according to claim 11, wherein
- the setting state information stored in the information reposition step is patient information, and setting value information for one of the ultrasound observation apparatus and the endoscope processor.
13. The control method of an ultrasound endoscope system according to claim 11, wherein
- the information reposition control step comprises controlling the writing/reading of operation state information for one of the ultrasound observation apparatus and the endoscope processor in the information reposition step.
14. The control method of an ultrasound endoscope system according to claim 12, wherein
- the information reposition control step comprises controlling the writing/reading of operation state information for one of the ultrasound observation apparatus and the endoscope processor in the information reposition step.
15. The control method of an ultrasound endoscope system according to claim 11, wherein
- the information reposition control step comprises outputting a control command for controlling one of the ultrasound observation apparatus and the endoscope processor from the other of the ultrasound observation apparatus and the endoscope processor to the one of the ultrasound observation apparatus and the endoscope processor.
16. The control method of an ultrasound endoscope system according to claim 12, wherein
- the information reposition control step comprises outputting a control command for controlling one of the ultrasound observation apparatus and the endoscope processor from the other of the ultrasound observation apparatus and the endoscope processor to the one of the ultrasound observation apparatus and the endoscope processor.
17. The control method of an ultrasound endoscope system according to claim 13, wherein
- the information reposition control step comprises outputting a control command for controlling one of the ultrasound observation apparatus and the endoscope processor from the other of the ultrasound observation apparatus and the endoscope processor to the one of the ultrasound observation apparatus and the endoscope processor.

18. The control method of an ultrasound endoscope system according to claim **14**, wherein

the information reposition control step comprises outputting a control command for controlling one of the ultrasound observation apparatus and the endoscope proces-

sor from the other of the ultrasound observation apparatus and the endoscope processor to the one of the ultrasound observation apparatus and the endoscope processor.

* * * * *

专利名称(译)	超声内窥镜系统及超声内窥镜系统的控制方法		
公开(公告)号	US20080249361A1	公开(公告)日	2008-10-09
申请号	US12/050318	申请日	2008-03-18
[标]申请(专利权)人(译)	奥林巴斯医疗株式会社		
申请(专利权)人(译)	奥林巴斯医疗系统股份有限公司.		
当前申请(专利权)人(译)	OLYMPUS CORPORATION		
[标]发明人	OKUNO YOSHIYUKI		
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摘要(译)

在本发明中，超声波观测装置包括信息再现部分;信息再定位部分是用在于从键盘输入的内窥镜处理器中存储各种状态信息的存储部分，并且被配置为包括存储器控制器和数据存储器部分。此外，键盘被配置为包括键矩阵，键盘控制器，超声键处理部分和内窥镜键处理部分。该配置允许超声波观察设备容易地共享构成系统的多个设备的各种状态信息。

