



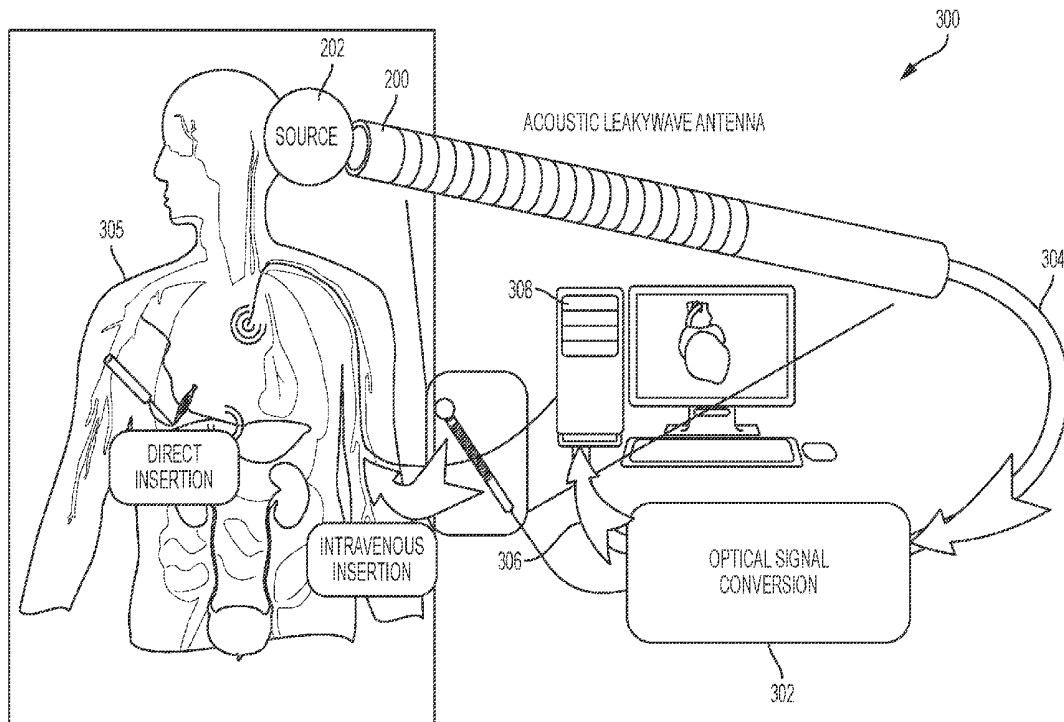
US 20170059707A1

(19) **United States**(12) **Patent Application Publication**
Rohde et al.(10) **Pub. No.: US 2017/0059707 A1**(43) **Pub. Date: Mar. 2, 2017**(54) **MINIATURE ACOUSTIC LEAKY-WAVE
ANTENNA FOR ULTRASONIC IMAGING***A61B 8/00* (2006.01)*A61B 8/12* (2006.01)(71) Applicant: **The Government of the United States
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(US)**(52) **U.S. CL.**CPC *G01S 15/899* (2013.01); *A61B 8/12*
(2013.01); *A61B 8/0891* (2013.01); *A61B*
8/445 (2013.01); *A61B 8/4494* (2013.01);
A61B 8/0841 (2013.01); *A61B 2017/3413*
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(57)

ABSTRACT(21) Appl. No.: **15/246,798**(22) Filed: **Aug. 25, 2016****Related U.S. Application Data**(60) Provisional application No. 62/212,654, filed on Sep.
1, 2015.**Publication Classification**(51) **Int. Cl.***G01S 15/89* (2006.01)*A61B 8/08* (2006.01)

An ultrasonic imaging system includes a micro-acoustic source configured to generate a broadband ultrasonic pulse. The ultrasonic imaging system further includes an acoustic leaky-wave antenna configured to use a frequency dependent angular dispersion to simultaneously collect reflected signals from multiple angles of the broadband ultrasonic pulse, wherein the reflected signals contain information about a surrounding medium. The ultrasonic imaging system further includes a sensor operationally coupled to the acoustic leaky-wave antenna, the sensor configured to detect the reflected signals collected by the acoustic leaky-wave antenna.



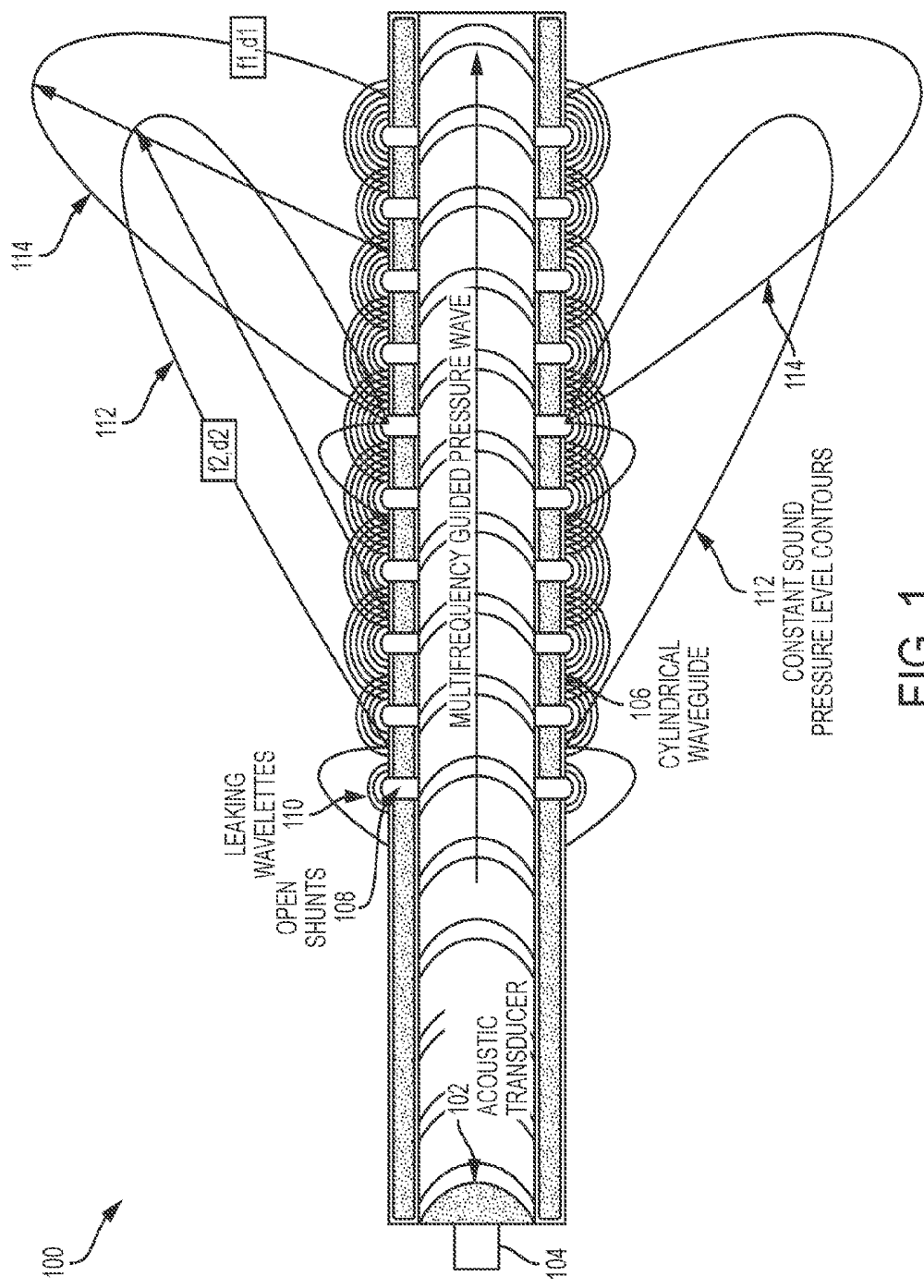


FIG. 1

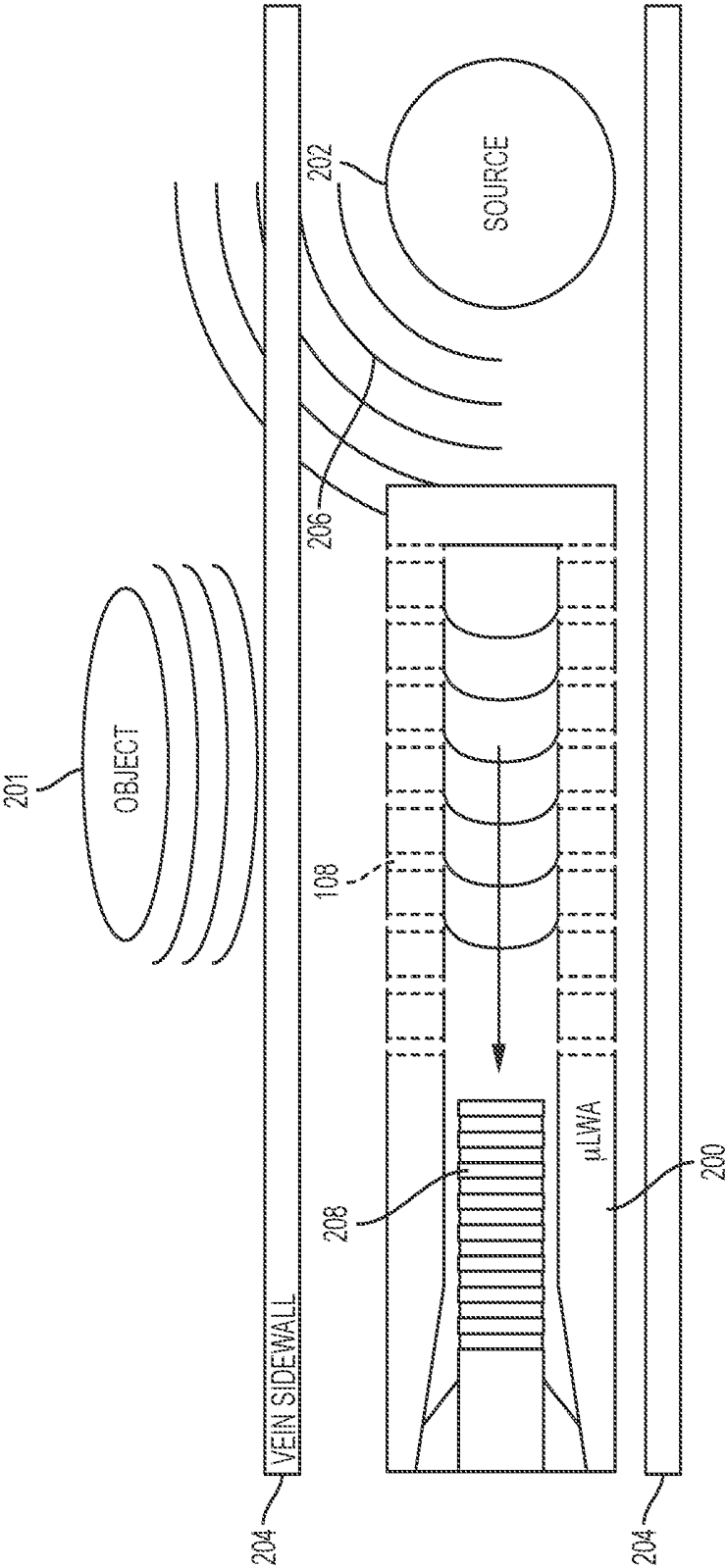


FIG. 2A

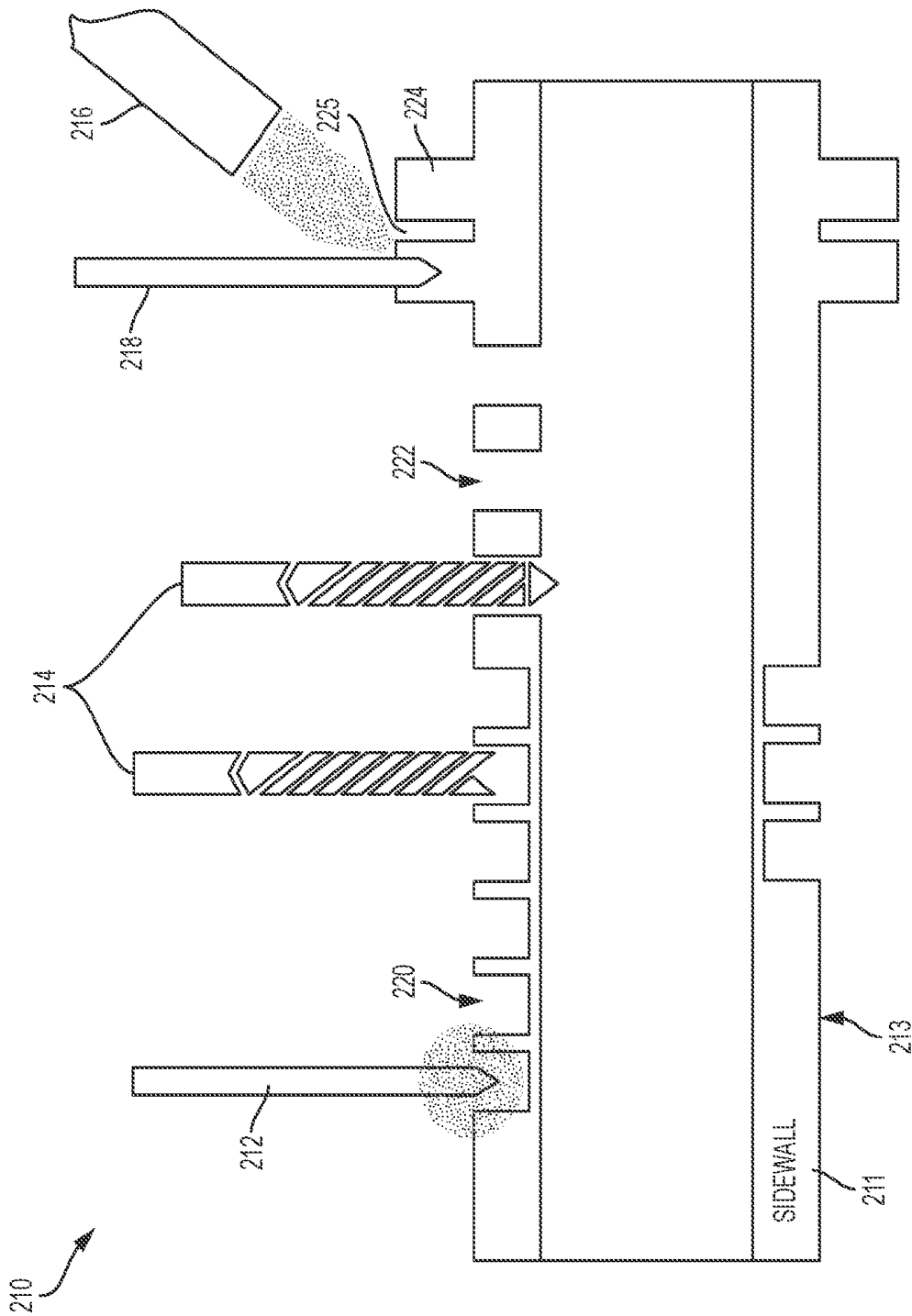
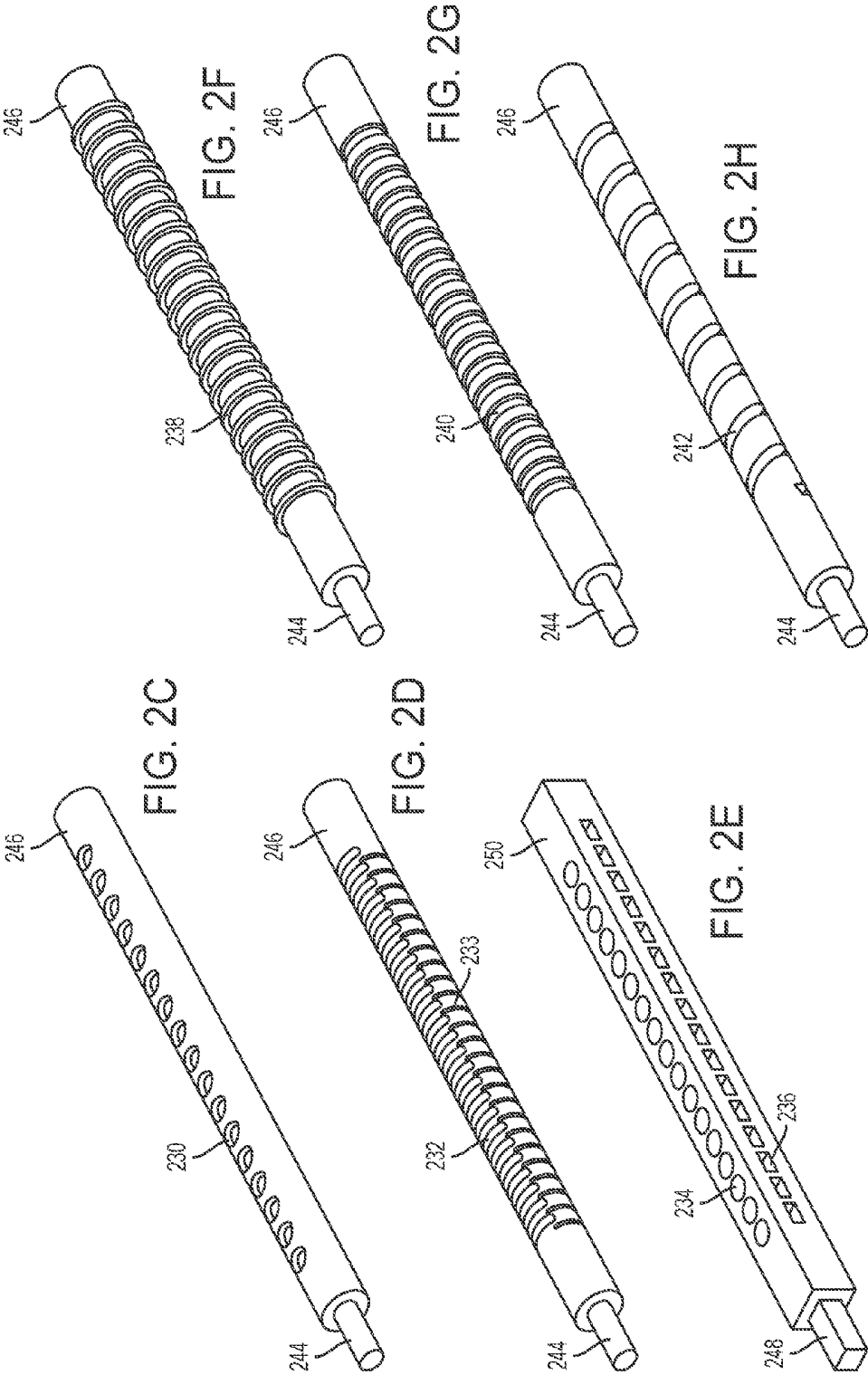


FIG. 2B



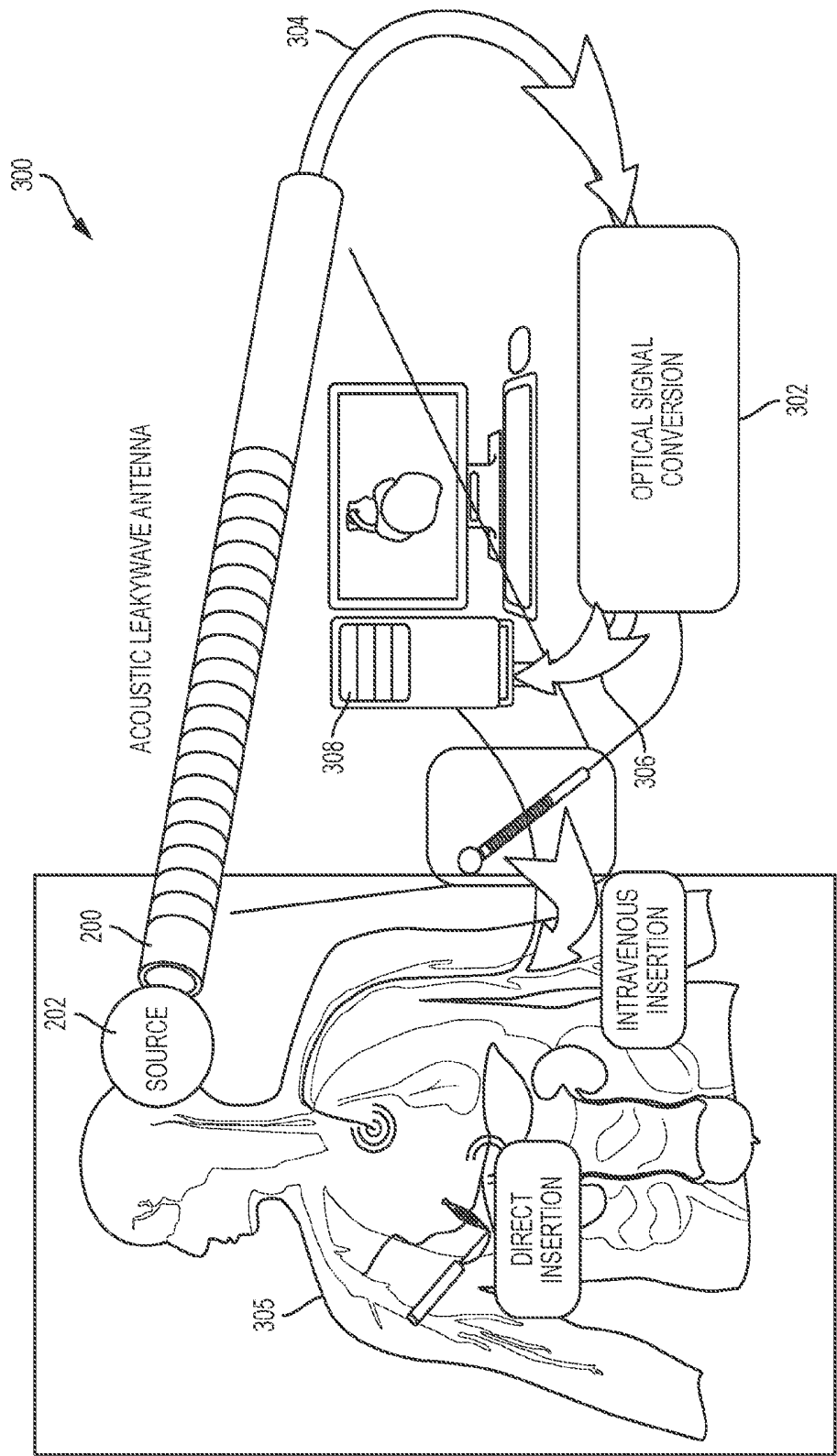


FIG. 3

MINIATURE ACOUSTIC LEAKY-WAVE ANTENNA FOR ULTRASONIC IMAGING

CROSS-REFERENCE TO RELATED APPLICATIONS

[0001] This application claims priority to U.S. Provisional Patent Application No. 62/212,654 filed on Sep. 1, 2015, the complete disclosure of which, in its entirety, is herein incorporated by reference.

GOVERNMENT INTEREST

[0002] The embodiments described herein may be manufactured, used, and/or licensed by or for the United States Government without the payment of royalties thereon.

BACKGROUND

[0003] Technical Field

[0004] The embodiments herein generally relate to diagnostic detecting tools, and more particularly to ultrasonic imaging tools.

[0005] Description of the Related Art

[0006] Ultrasonic imaging is a heavily leveraged diagnostic tool in the medical industry, particularly in the fields of cardiology, obstetrics, surgery, and neurology. However, the current state of the art has several complications that limit the use of ultrasonic imaging as a point-of-care diagnostic tool. The complexity and power requirements and external (e.g., outside the body) nature of current systems limit their portability and penetration depth. Typical penetration depths for external ultrasonic imaging techniques limit their useful frequency range, and hence, their resolution. It is desirable to increase the range and versatility of the ultrasonic imaging devices.

SUMMARY

[0007] In view of the foregoing, an embodiment herein provides an ultrasonic imaging system comprising a micro-acoustic source configured to generate a broadband ultrasonic pulse; an acoustic leaky-wave antenna configured to use a frequency dependent angular dispersion to simultaneously collect reflected signals from multiple angles of the broadband ultrasonic pulse, wherein the reflected signals contain information about a surrounding medium; and a sensor operationally coupled to the acoustic leaky-wave antenna, the sensor configured to detect the reflected signals collected by the acoustic leaky-wave antenna.

[0008] The ultrasonic pulse generated by the micro-acoustic source may be in the 1-20 MHz ultrasound range. The micro-acoustic source may be communicatively coupled to the leaky-wave antenna. The acoustic leaky-wave antenna, the micro-acoustic source, and the sensor may be configured to be placed inside a vein, and wherein the reflected signals collected by the leaky-wave antenna may be reflected from any of a sidewall of the vein and an object outside the vein. The sensor may comprise a fiber Bragg grating configured to sense pressure fields. The fiber Bragg grating may be configured to generate an optical signal in response to detecting the reflected signals collected by the leaky-wave antenna.

[0009] The ultrasonic imaging system may further comprise an optical signal converter optically coupled to the sensor, wherein the optical signal converter may be configured to convert the optical signal generated by the sensor to

an electric signal. The ultrasonic imaging system may further comprise a computing device electronically coupled to the optical converter, wherein the computing device may be configured to process and display the information about the surrounding medium in the reflected signals. The sensor may comprise a capacitive micromachined ultrasonic transducer configured to generate an electric signal in response to detecting the reflected signals collected by the acoustic leaky-wave antenna.

[0010] Another embodiment herein provides a method comprising a micro-acoustic source configured to generate a broadband ultrasonic pulse; an acoustic leaky-wave antenna comprising a waveguide; and a plurality of periodically structured sub-wavelength acoustic ports on the waveguide configured to coherently interact with the broadband ultrasonic pulse, resulting in frequency dependent leakage of the energy of the broadband ultrasonic pulse through a plurality of leaking wavelettes with a fixed, programmed phase relationship into a surrounding medium, wherein the acoustic leaky-wave antenna is configured to use a frequency dependent angular dispersion to simultaneously collect reflected signals from multiple angles of the broadband ultrasonic pulse, wherein the reflected signals contain information about the surrounding medium; and a sensor operationally coupled to the acoustic leaky wave antenna, the sensor configured to detect the reflected signals collected by the acoustic leaky-wave antenna.

[0011] The waveguide may comprise a bio-compatible soft polymer stent. The plurality of acoustic ports may be created using femtosecond laser machining to make any of periodic patterned grooves and open cuts. The plurality of acoustic ports may be created using femtosecond laser machining to make periodic holes. The waveguide may comprise a hypodermic needle. The hypodermic needle may comprise a 28 gauge metal needle. The plurality of acoustic ports may comprise holes each having an approximately 100 μm diameter.

[0012] Another embodiment herein provides a probe comprising a micro-acoustic source configured to generate a broadband ultrasonic pulse; an acoustic leaky-wave antenna comprising: a waveguide; a plurality of periodically structured sub-wavelength acoustic ports having a shape of any of patterned grooves and holes; and a sensor operationally coupled to the acoustic leaky wave antenna, the sensor configured to detect reflected signals collected by the acoustic leaky-wave antenna.

[0013] The sensor may comprise a fiber Bragg grating configured to sense pressure fields. The fiber Bragg grating may be configured to generate an optical signal in response to detecting the reflected signals. The sensor may comprise a capacitive micromachined ultrasonic transducer configured to generate an electric signal in response to detecting the reflected signals collected by the acoustic leaky-wave antenna.

[0014] These and other aspects of the embodiments herein will be better appreciated and understood when considered in conjunction with the following description and the accompanying drawings. It should be understood, however, that the following descriptions, while indicating preferred embodiments and numerous specific details thereof, are given by way of illustration and not of limitation. Many changes and modifications may be made within the scope of

the embodiments herein without departing from the spirit thereof, and the embodiments herein include all such modifications.

BRIEF DESCRIPTION OF THE DRAWINGS

[0015] The embodiments herein will be better understood from the following detailed description with reference to the drawings, in which:

[0016] FIG. 1 is a schematic diagram illustrating a Leaky Wave Antenna (LWA) according to an embodiment herein;

[0017] FIG. 2A is a schematic diagram illustrating a micro-leaky-wave antenna (μ LWA) according to an embodiment herein;

[0018] FIG. 2B is a schematic diagram illustrating manufacturing periodic structure of a leaky-wave antenna according to an embodiment herein;

[0019] FIG. 2C is a schematic diagram illustrating a first type of periodic sidewall pattern of the antenna according to an embodiment herein;

[0020] FIG. 2D is a schematic diagram illustrating a second type of periodic sidewall pattern of the antenna according to an embodiment herein;

[0021] FIG. 2E is a schematic diagram illustrating a third type of periodic sidewall pattern of the antenna according to an embodiment herein;

[0022] FIG. 2F is a schematic diagram illustrating a fourth type of periodic sidewall pattern of the antenna according to an embodiment herein;

[0023] FIG. 2G is a schematic diagram illustrating a fifth type of periodic sidewall pattern of the antenna according to an embodiment herein;

[0024] FIG. 2H is a schematic diagram illustrating a sixth type of periodic sidewall pattern of the antenna according to an embodiment herein; and

[0025] FIG. 3 illustrates an acoustic leaky-wave antenna system according to an embodiment herein.

DETAILED DESCRIPTION

[0026] The embodiments herein and the various features and advantageous details thereof are explained more fully with reference to the non-limiting embodiments that are illustrated in the accompanying drawings and detailed in the following description. Descriptions of well-known components and processing techniques are omitted so as to not unnecessarily obscure the embodiments herein. The examples used herein are intended merely to facilitate an understanding of ways in which the embodiments herein may be practiced and to further enable those of skill in the art to practice the embodiments herein. Accordingly, the examples should not be construed as limiting the scope of the embodiments herein.

[0027] Ultrasonic images may be formed in one of several modalities or an overlaid combination of discrete modalities. Examples of these imaging types are pulse-echo, Doppler flow imaging elastography, and 4D imaging. Pulse-echo imaging returns structural information, and Doppler imaging returns fluid flow velocities. Elastography is an extension of Doppler imaging where a strong incident pulse induces motion at a tissue interface, and the elastic properties of the moving tissue can be evaluated. Similarly, 4D imaging is an extension of the pulse-echo technique to retrieve time-resolved 3D images of tissue structures.

[0028] In the pulse-echo mode, an ultrasonic pulse (typically in the 1-10 MHz frequency range) is sent from an external piezoelectric source into a tissue zone to be imaged. Scattered return pulses (echoes) can be detected due to differences in acoustic impedance between tissue types. These pulse reflections are detected by the same (or similar) external piezoelectric transducer, and the time delay between pulse and echo determines the distance to the various tissue type interfaces. In Doppler flow imaging, changes in reflected frequency content map onto the flow-velocity of particulate laden fluids such as blood.

[0029] Imaging may occur when the pulse source has directivity (a “beam”) and that directivity is scanned in space. The beam forming and scanning may be performed mechanically, with a single specially shaped source, or may be performed with a coherently phased array of multiple piezoelectric transducers. Phased arrays may allow for a nearly arbitrary beam shape and direction. Phased arrays, however, may be limited by the number and size of the array elements. The speed of phased array sensing also allows for fast imaging, and the use of multiple arrays allows real-time imaging of 3D structures (i.e., 4D imaging).

[0030] Multi-element linear or phased arrays of transducer elements in an ultrasonic imaging device may lead to very high processing bandwidth (typically greater than 100 GHz) requirements, but may require high power and complex processing capabilities. This may decrease the portability and ease-of-use of the imaging device. Also, arrays of elements may generally be limited in size and external coupling complexity when internal imaging is the goal, such as in intravenous ultrasonic imaging.

[0031] An embodiment herein provides a device that utilizes a geometrically scaled version of an acoustic imaging leaky wave antenna in the 1-20 MHz ultrasound range. In an embodiment, the acoustic imaging leaky wave antenna may be integrated with an output transduction mechanism. In an exemplary embodiment, the output transduction mechanism may be a fiber-optic transducer based on distributed Bragg gratings. To produce a waveguide structure for the high frequency ultrasound aqueous environments, femtosecond laser machining or other micro-machining techniques may be used to engineer optimized, fast-wave-coupling acoustic ports into the surface of a millimeter scale metallic or glass capillary tubes. The probe provided by the embodiments herein may produce 3D ultrasonic images of biological tissue using a single, non-directional source and a single non-directional detector, all in a package sufficiently small to be inserted intravenously, resulting in a robust, arthroscopically enabled tool for interior assessment, surgical monitoring, or structural monitoring in non-biological confined spaces. Referring now to the drawings, and more particularly to FIGS. 1 through 3, where similar reference characters denote corresponding features consistently throughout the figures, there are shown preferred embodiments.

[0032] FIG. 1 is a schematic diagram illustrating an acoustic leaky-wave antenna (ALWA) 100. The ALWA 100 uses a frequency dependent angular dispersion relation to simultaneously collect data from multiple angles with a single transducer 102 via a broadband source pulse 104. The ALWA 100 includes a waveguide 106 with periodically structured sub-wavelength output acoustic ports or shunts 108. Acoustic ports 108 may be configured as any of grooves and open cuts. These acoustic ports 108 coherently interact

with the guided wave and result in frequency dependent leakage of the guided energy through leaking wavelettes **110** into the surrounding medium. The coherent addition of leaking radiation results in a propagating wave with a frequency dependent direction, for example the propagating wave **112** and the propagating wave **114**.

[0033] An embodiment herein applies the ideas of leaky wave antenna technology to acoustic analogs. An embodiment herein reduces the size of acoustic leaky-wave antennas, and increases the operational frequency to the ultrasonic imaging range of 1-20 MHz. Accommodating the MHz scale frequencies of ultrasonic imaging reduces the size of the acoustic antenna to the (sub) millimeter scale.

[0034] FIG. 2A, with reference to FIG. 1, is a schematic diagram illustrating a micro-leaky-wave antenna (μ LWA) **200** according to an embodiment herein. In an embodiment, a micro-acoustic source **202** outputs a high bandwidth ultrasonic pulse **206**. In an embodiment, the source **202** may generate ultrasonic pulse in the 1-20 MHz ultrasound range. The micro-acoustic source **202** is communicatively coupled to the μ LWA **200**. In an embodiment, the micro-acoustic source **202** may be physically attached to the μ LWA **200**. In an embodiment, the source **202** may be a high powered, broadband source located externally and used to insonify a target volume where the μ LWA **200** is located. The pulse **206** may illuminate and reflect from the various tissue boundaries, for example vein sidewall **204**, or an object **201** located outside the vein and is collected by the micro-acoustic wave antenna **200**. In an embodiment, sensor **208** is operationally coupled to the μ LWA **200**. The sensor **208** may be an acoustic sensor for pressure fields coupled into the μ LWA **200**. In an embodiment, the sensor **208** is a fiber Bragg grating (FBG). An FBG may be operationally coupled to the μ LWA **200**, and act as an acoustic sensor for pressure fields coupled into the μ LWA **200** through appropriately configured ports.

[0035] To efficiently convert the collected acoustic signals, fiber optic sensing techniques may be utilized. In an embodiment, by placing the FBG based sensor **208** inside the μ LWA **200**, interior pressure changes can be monitored and transmitted to an external analysis system (such as computing device **308** shown in FIG. 3). Using an optical signal transport has the advantages of well-developed systems for biological use, very low power consumption, compact design, and high frequency response. The FBG based sensor **208** may be configured based on the homodyne detection of optical phase shifts between a sensing and non-sensing optical path. Detection and 3D imaging of hard or soft object **201** may be conducted by time-resolved (pulse-echo) broadband illumination, short pulse illumination.

[0036] In an embodiment, sensor **208** comprises a micro-acoustic sensor such as a capacitive micromachined ultrasonic transducer (CMUT). A CMUT sensor may be used to convert ultrasonic signals into electrical signals. A CMUT could also be used as a micro-acoustic source replacing the source **202**.

[0037] In an embodiment, CMUTs include a suspended, conductive membrane material above a conductive substrate. Flexure modes of the membrane result in electrical signals through capacitive coupling between the membrane and substrate. CMUTs may be created with a micromechanical machining approach compatible with current 2D photolithography techniques. As such they can be small (microm-

eter scale), and densely arrayed using current semiconductor processing techniques. Although CMUT elements have no intrinsic directionality, arrays of sensors can be arranged to be directionally sensitive.

[0038] FIG. 2B, with reference to FIG. 1 to FIG. 2A, is a schematic diagram illustrating manufacturing periodic structures of a leaky-wave antenna, according to an embodiment herein. In an embodiment, the acoustic ports **108** are manufactured on a sidewall **211** of a longitudinal structure **213**. In an embodiment the longitudinal structure **213** may be a cylindrical structure or a rectangular longitudinal structure. In another embodiment the longitudinal structure **213** is a hypodermic needle.

[0039] To create the acoustic ports **108** on the μ LWA **200**, an embodiment utilizes micromachining techniques such as femtosecond laser ablation, using laser beam **212**, to create periodic grooves **220** or open holes **222**. An embodiment utilizes computer controlled micromachining techniques, using micro mills **214** to create the periodic grooves **220** or the open holes **222**. An embodiment uses advanced additive manufacturing techniques, using nozzle **216** and laser beam **218**, to make protrusions **224** and periodic grooves **225**. In an embodiment, periodic grooves **220**, **225** or open holes **222** function as the acoustic ports **108**.

[0040] In an embodiment, femtosecond laser ablation, using laser beam **212**, may be used for the high precision removal of material from surface of the structure **213**, without heat deposition. This provides the opportunity to machine any material from soft polymers to transparent glasses to metals. Combined with the use of high precision computer numeric control (CNC) multi-axis abrading micro-milling, using micro mills **214** (micro-lathing), femtosecond laser **212**, or machining and/or additive welding techniques, using nozzle **216**, allow the nearly arbitrary removal/buildup of design material. In an embodiment, the open hole **222** is approximately 100 μ m in diameter, bored through metal, 28 gauge hypodermic needle **213**. In an embodiment, each of the periodic grooves **220** are approximately 100 μ m in diameter.

[0041] FIGS. 2C-2H, with reference to FIG. 1 to FIG. 2B, are schematic diagrams illustrating periodic sidewall patterns as the acoustic ports **108** on the μ LWA **200**, according to exemplary embodiments herein. Any of the manufacturing methods illustrated in FIG. 2B, for example, the laser ablation method, controlled micromachining technique, or the additive manufacturing technique may be used in manufacturing any of the acoustic ports illustrated in FIGS. 2C-2H.

[0042] FIG. 2C illustrates periodic holes **230** as the acoustic ports **108**. FIG. 2D illustrates multiple slot geometries **232**, **233** as the acoustic ports **108**. FIG. 2E illustrates periodic slots **234** and divots **236** as the acoustic ports **108**. FIG. 2F illustrates periodic extruded ridges **238** as the acoustic ports **108**. FIG. 2G illustrates periodic tapered cuts **240** as the acoustic ports **108**. FIG. 2H illustrates periodic spiral grooves **242** as the acoustic ports **108**.

[0043] In the embodiments herein, acoustic ports **230**, **232**, **234**, **236**, **238**, **240**, and **242** are created in a stiff, fluid-filled, hollow material structure **246** having a round cross section, or similar structure **250** having a square cross section. Structures **246**, **250** each may have their corresponding transducers **244**, **248**.

[0044] Different patterns shown in exemplary embodiments of FIGS. 2C-2H may have different functionalities.

For example, creating slot geometries **232**, **233** of FIG. 2D, or periodic slots **234** and divots **236** of FIG. 2E, or continuously varying spiral groove **242** of FIG. 2H, into difference angular regions of the μ LWA **200**, may produce additional directivity by mapping additional, programmed, frequencies onto the azimuthal quadrants of the μ LWA **200**.

[0045] In some exemplary embodiments, a restricted collection angular field of view is built into the μ LWA **200** by only placing acoustic ports in one region of the antenna surface. In an embodiment herein, uniform patterning about the antenna azimuthal surface, such as extruded ridges **238** of FIG. 2F, or periodic tapered cuts **240** of FIG. 2G, may result in a full angular field of view, but no azimuthal signal discrimination. The geometry, size, spacing, depth, sidewall taper of the acoustic ports **108** may depend on the frequency band used by the source **202**. In an embodiment the grooves or holes are sub-millimeter in size.

[0046] FIG. 3, with reference to FIGS. 1 through 2H, illustrates an acoustic leaky-wave antenna system **300** according to an embodiment herein. In an embodiment, the μ LWA **200** and the source **202** may be communicatively connected to an optical signal conversion device **302**. The optical signal conversion device **302** is configured to convert an optical signal **304** generated by the μ LWA **200** to an electrical signal **306**. The electrical signal **306** may be used by a computing device **308** to process and display information detected by the μ LWA **200**.

[0047] In an embodiment, the computing device **308** may map acoustic reflections from soft targets illuminated with an additional non-directional source via their frequency response to an angular position and range. Using external data processing of the optically transduced signal, the computing device **308** may map all objects within the field of view of the μ LWA **200**. Such a configuration could be operated in any of the currently utilized ultrasonic imaging modalities as discussed above.

[0048] In an embodiment, low scale μ LWA **200** and source **202** may be inserted intravenously in a body of interest **305** and guided to areas of interest for high-resolution (high-frequency) imaging. The μ LWA **200** and source **202** may also be inserted in other tissues or in an organ. Additionally, insertion through small incisions could aid the diagnostic tools available in minimally invasive surgical techniques such as the Da Vinci® robotic surgery available from Intuitive Surgical, Inc., approach or insertion of the device into a traumatic wound entry point could yield a rapid, real time, assessment of interior structure damage near the time of injury. As a non-biological sensor, the μ LWA **200** could be used to monitor structural properties of highly confined spaces.

[0049] Using the μ LWA **200** allows for the use of a single, high bandwidth transducer to acquire signals simultaneously from multiple directions. This single sensor arrangement greatly reduces the complexity and processing needs of an ultrasonic imaging system. In turn, this opens the possibility of creating highly portable diagnostic tools for 3D imaging of organic tissues. Metamaterial techniques also produce LWA designs that make use of negative (left-handed) dispersion relations to extend the field of view of standard LWAs from less than 90° in the forward direction to a full 180°. The use of this additional design parameter space could lead to an even more powerful imaging tool.

[0050] The foregoing description of the specific embodiments will so fully reveal the general nature of the embodi-

ments herein that others can, by applying current knowledge, readily modify and/or adapt for various applications such specific embodiments without departing from the generic concept, and, therefore, such adaptations and modifications should and are intended to be comprehended within the meaning and range of equivalents of the disclosed embodiments. It is to be understood that the phraseology or terminology employed herein is for the purpose of description and not of limitation. Therefore, while the embodiments herein have been described in terms of preferred embodiments, those skilled in the art will recognize that the embodiments herein can be practiced with modification within the spirit and scope of the appended claims.

What is claimed is:

1. An ultrasonic imaging system comprising:

a micro-acoustic source configured to generate a broadband ultrasonic pulse;

an acoustic leaky-wave antenna configured to use a frequency dependent angular dispersion to simultaneously collect reflected signals from multiple angles of said broadband ultrasonic pulse, wherein said reflected signals contain information about a surrounding medium; and

a sensor operationally coupled to said acoustic leaky-wave antenna, said sensor configured to detect said reflected signals collected by said acoustic leaky-wave antenna.

2. The system of claim 1, wherein said ultrasonic pulse generated by said micro-acoustic source is in a 1-20 MHz ultrasound range.

3. The system of claim 1, wherein said micro-acoustic source is communicatively coupled to said leaky-wave antenna.

4. The system of claim 1, wherein said acoustic leaky-wave antenna, said micro-acoustic source, and said sensor are configured to be placed inside a vein, and wherein said reflected signals collected by said leaky-wave antenna is reflected from any of a sidewall of said vein and an object outside said vein.

5. The system of claim 1, wherein said sensor comprises a fiber Bragg grating configured to sense pressure fields.

6. The system of claim 5, wherein said fiber Bragg grating is configured to generate an optical signal in response to detecting said reflected signals collected by said leaky-wave antenna.

7. The system of claim 1, further comprising an optical signal converter optically coupled to said sensor, wherein said optical signal converter is configured to convert said optical signal generated by said sensor to an electric signal.

8. The system of claim 1, further comprising a computing device electronically coupled to said optical converter, wherein said computing device is configured to process and display said information about said surrounding medium in said reflected signals.

9. The system of claim 1, wherein said sensor comprises a capacitive micromachined ultrasonic transducer configured to generate an electric signal in response to detecting said reflected signals collected by said acoustic leaky-wave antenna.

10. A probe comprising:

a micro-acoustic source configured to generate a broadband ultrasonic pulse;

an acoustic leaky-wave antenna comprising:

a waveguide; and

- a plurality of periodically structured sub-wavelength acoustic ports on said waveguide configured to coherently interact with said broadband ultrasonic pulse, resulting in frequency dependent leakage of the energy of said broadband ultrasonic pulse through a plurality of leaking wavelettes with a fixed, programmed phase relationship into a surrounding medium,
- wherein said acoustic leaky-wave antenna is configured to use a frequency dependent angular dispersion to simultaneously collect reflected signals from multiple angles of said broadband ultrasonic pulse, wherein said reflected signals contain information about said surrounding medium; and
- a sensor operationally coupled to said acoustic leaky wave antenna, said sensor configured to detect said reflected signals collected by said acoustic leaky-wave antenna.
11. The probe of claim 10, wherein said waveguide comprises a bio-compatible soft polymer stent.
12. The probe of claim 10, wherein said plurality of acoustic ports are created using femtosecond laser machining to make any of periodic patterned grooves and open cuts.
13. The probe of claim 10, wherein said plurality of acoustic ports are created using femtosecond laser machining to make periodic holes.
14. The probe of claim 10, wherein said waveguide comprises a hypodermic needle.
15. The probe of claim 14, wherein said hypodermic needle comprises a 28 gauge metal needle.
16. The probe of claim 14, wherein said plurality of acoustic ports comprises holes each having an approximately 100 μm diameter.
17. A probe comprising:
- a micro-acoustic source configured to generate a broadband ultrasonic pulse;
 - an acoustic leaky-wave antenna comprising:
 - a waveguide;
 - a plurality of periodically structured sub-wavelength acoustic ports having a shape of any of patterned grooves and holes; and
 - a sensor operationally coupled to said acoustic leaky wave antenna, said sensor configured to detect reflected signals collected by said acoustic leaky-wave antenna.
18. The probe of claim 17, wherein said sensor comprises a fiber Bragg grating configured to sense pressure fields.
19. The probe of claim 18, wherein said fiber Bragg grating is configured to generate an optical signal in response to detecting said reflected signals.
20. The probe of claim 17, wherein said sensor comprises a capacitive micromachined ultrasonic transducer configured to generate an electric signal in response to detecting said reflected signals collected by said acoustic leaky-wave antenna.
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专利名称(译)	用于超声成像的微型声学泄漏波天线		
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申请号	US15/246798	申请日	2016-08-25
申请(专利权)人(译)	美利坚合众国政府作为代表由海军部长		
当前申请(专利权)人(译)	美利坚合众国政府作为代表由海军部长		
[标]发明人	ROHDE CHARLES ALAN		
发明人	ROHDE, CHARLES ALAN GUILD, MATTHEW DAVID NAIFY, CHRISTINA JEANNE		
IPC分类号	G01S15/89 A61B8/08 A61B8/00 A61B8/12		
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优先权	62/212654 2015-09-01 US		
外部链接	Espacenet USPTO		

摘要(译)

一种超声成像系统包括被配置为产生宽带超声波脉冲的微声源。超声成像系统还包括声泄漏波天线，其被配置为使用频率相关的角色散来同时收集来自宽带超声脉冲的多个角度的反射信号，其中反射信号包含关于周围介质的信息。超声成像系统还包括可操作地耦合到声泄漏波天线的传感器，传感器配置成检测由声泄漏波天线收集的反射信号。

