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(54) ULTRASOUND IMAGE RECONSTRUCTION
WITH RECEIVE APERTURE CONTROL

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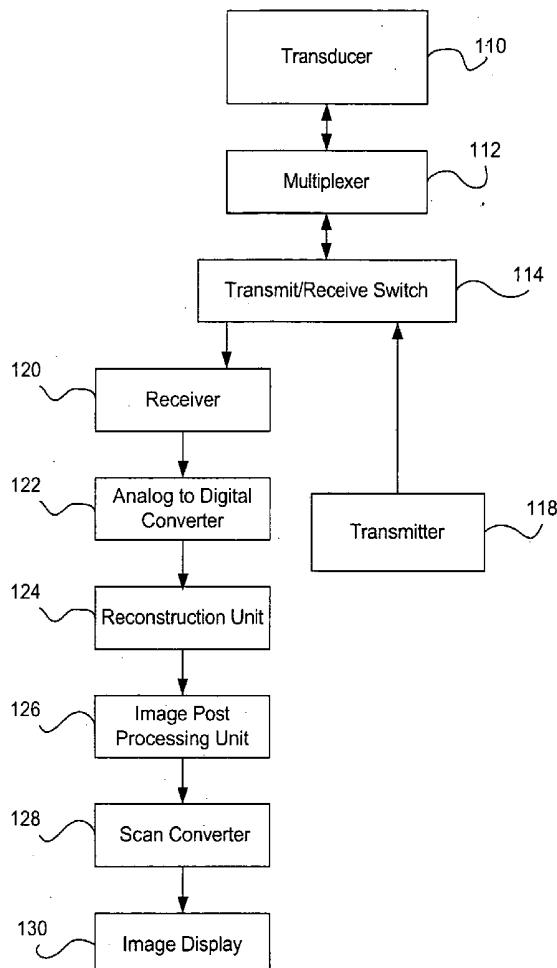
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(57) **ABSTRACT**

Methods for processing ultrasound signals are provided. Processing of ultrasound signals comprises identifying qualified reconstruction channels in a receive aperture, grouping qualified reconstruction channels in the aperture, and preprocessing of selected echo signals using the grouped qualified reconstruction channels to produce reconstruction signals. Additional methodologies comprise comparing a number of channels in a receive aperture with a number of reconstruction channels to determine a number of reconstruction signals and grouping qualified channels in the receive aperture such that the number of reconstruction data signals is not less than the number of reconstruction channels. An ultrasound reconstruction unit comprising a receive aperture control engine configured to use selected echo signals to adaptively determine a set of reconstruction signals is also provided.



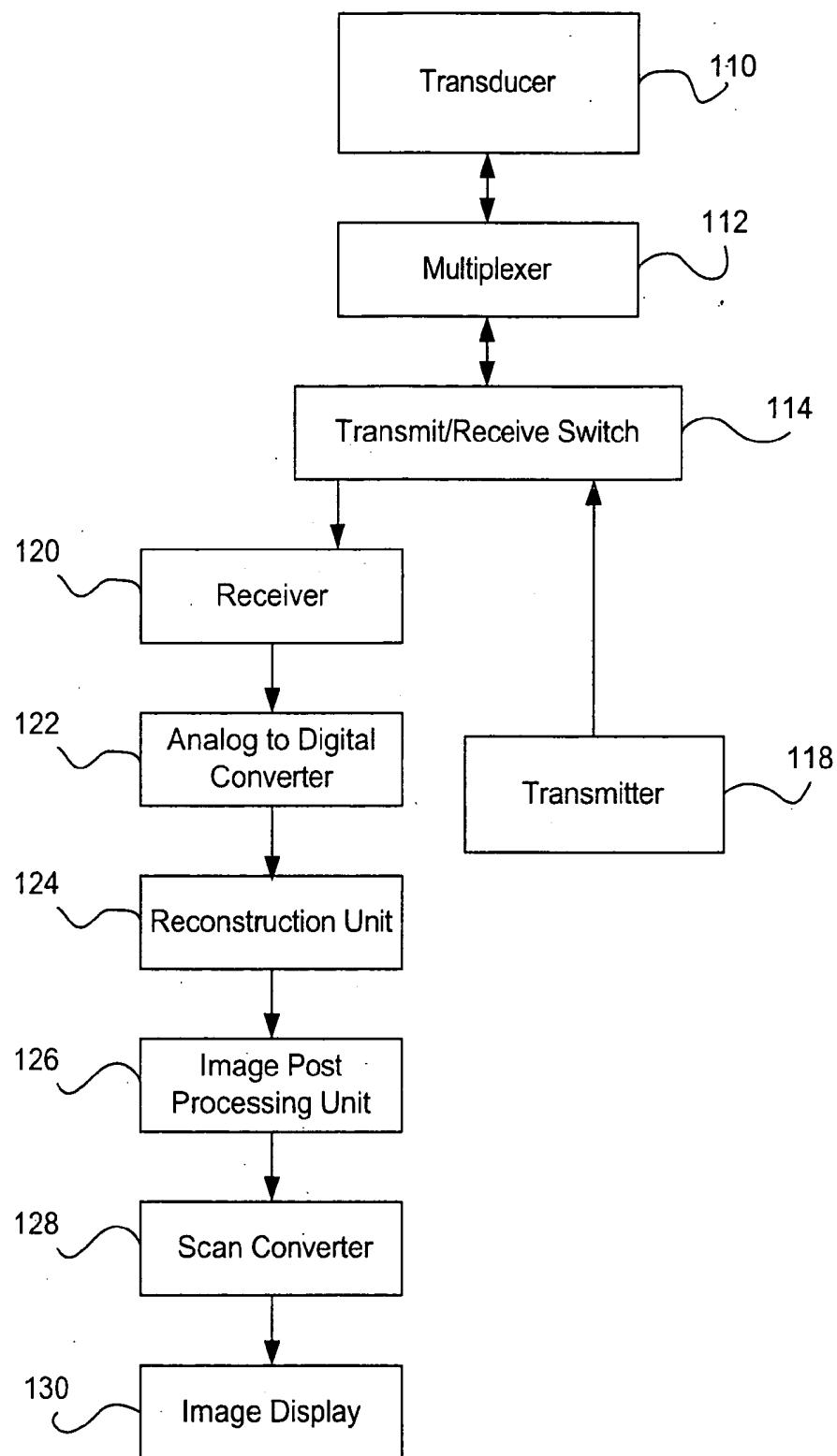


FIG. 1

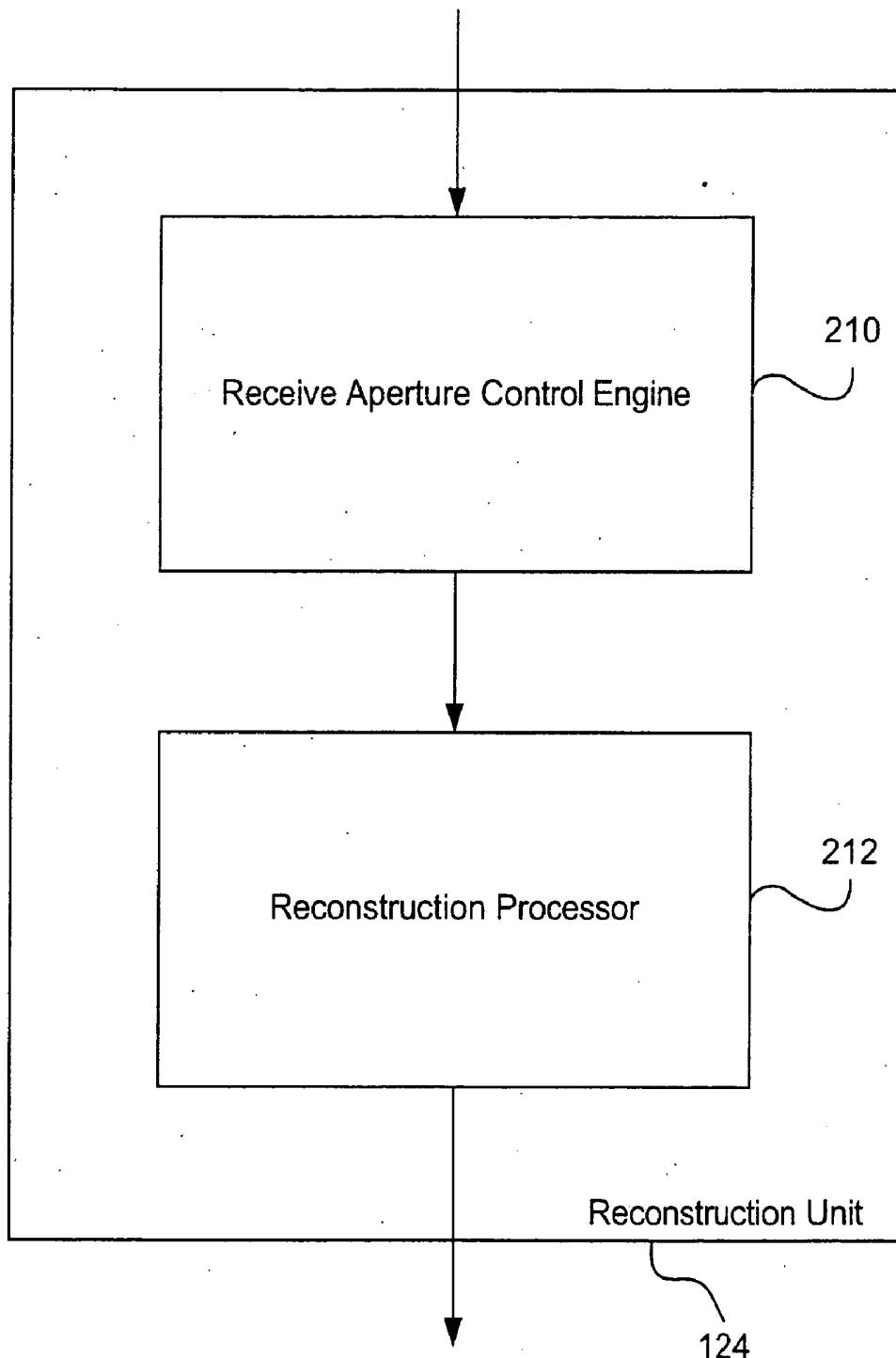


FIG. 2

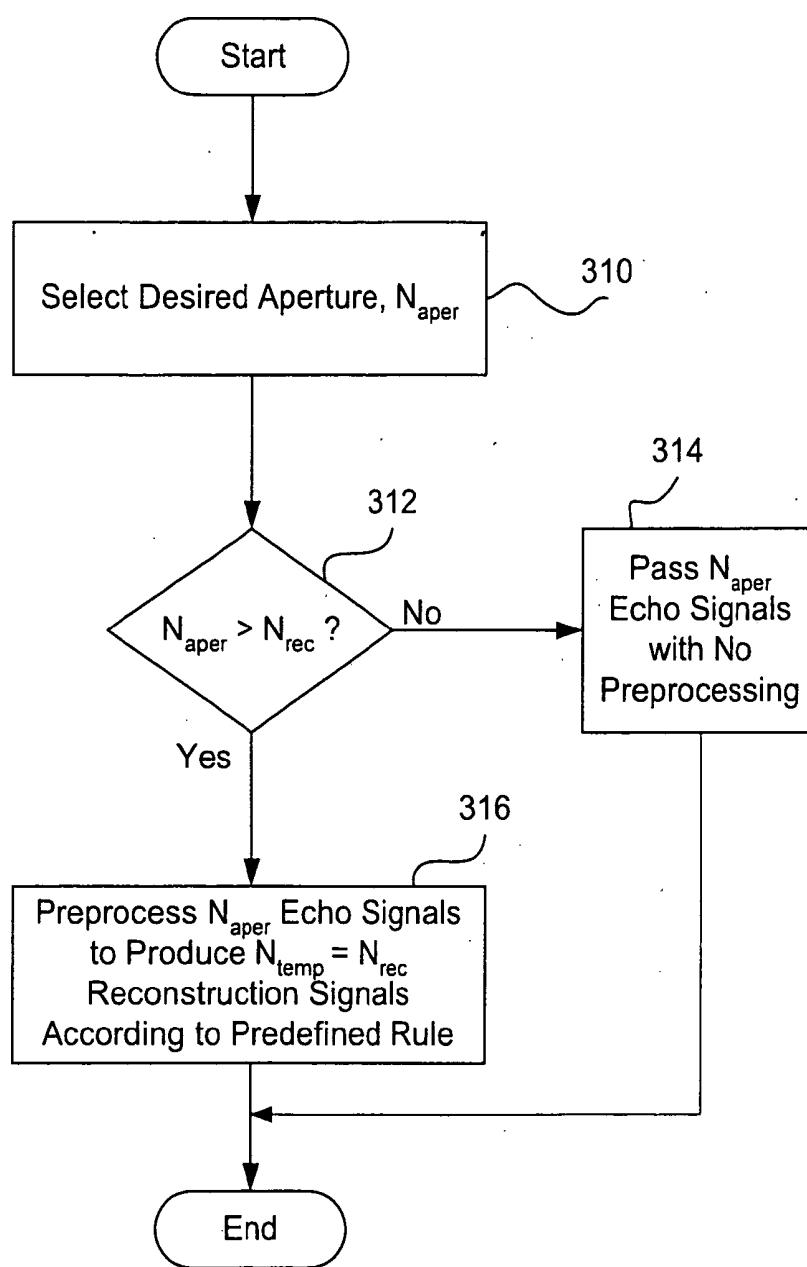


FIG. 3

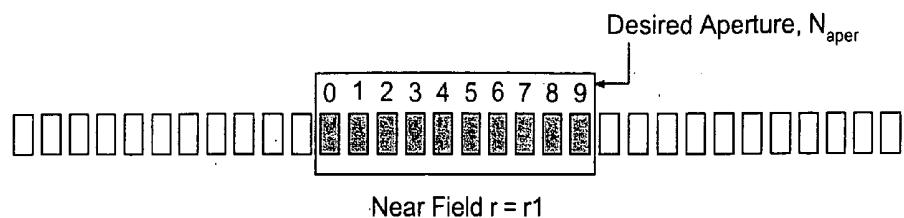


FIG. 4A

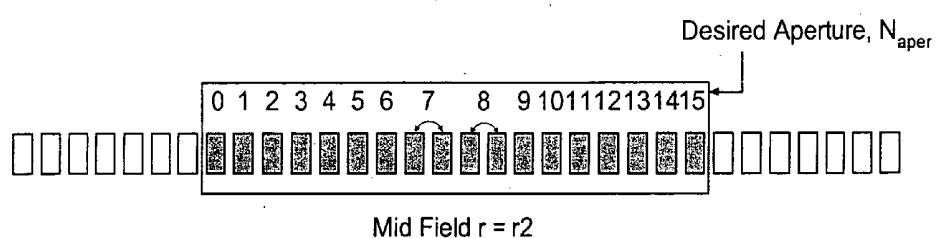


FIG. 4B

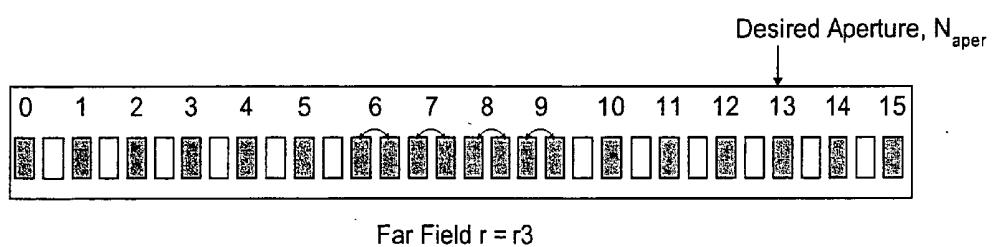


FIG. 4C

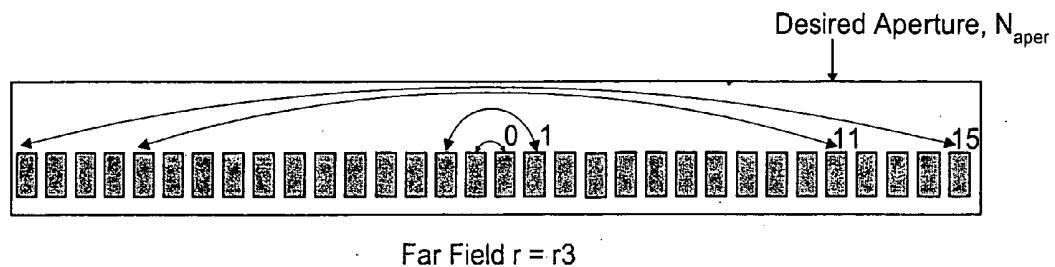


FIG. 4D

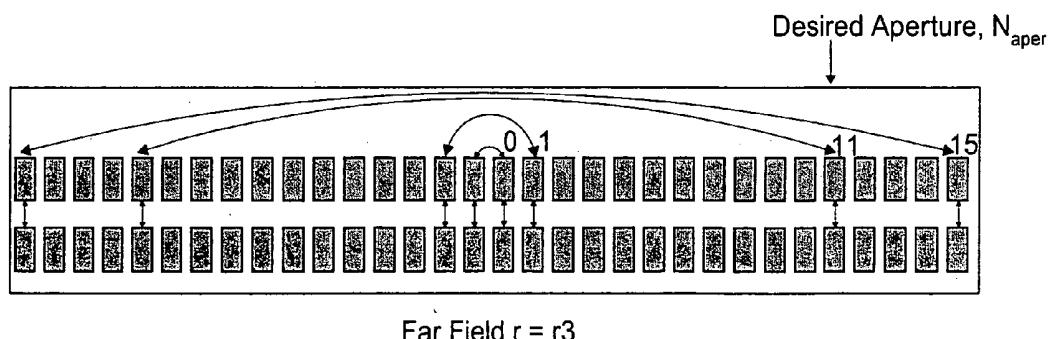


FIG. 4E

ULTRASOUND IMAGE RECONSTRUCTION WITH RECEIVE APERTURE CONTROL

CROSS REFERENCE TO RELATED APPLICATIONS

[0001] This application is a continuation application and claims the priority benefit of U.S. patent application Ser. No. 10/246,854 filed Sep. 18, 2002, now U.S. Pat. No. _____, and titled "Adaptive Receive Aperture for Ultrasound Image Reconstruction." The disclosure of this commonly owned application is incorporated herein by reference.

BACKGROUND OF THE INVENTION

[0002] 1. Field of the Invention

[0003] This invention relates generally to ultrasound imaging systems and relates more particularly to ultrasound image reconstruction.

[0004] 2. Description of the Background Art

[0005] Ultrasonic imaging is a frequently used method of analysis for examining a wide range of materials. Ultrasonic imaging is especially common in medicine because of its relatively non-invasive nature, low cost, and fast response times. Typically, ultrasonic imaging is accomplished by generating and directing ultrasonic signals into a medium under investigation using a set of ultrasound generating transducers and then observing reflections or scatterings generated at the boundaries of dissimilar materials, such as tissues within a patient, using a set of ultrasound receiving transducers. The receiving and generating transducers may be arranged in arrays and are typically different sets of transducers, but may differ only in the circuitry to which they are connected. The reflections are converted to electrical signals by the receiving transducers and then processed, using techniques known in the art, to determine the locations of echo sources. The resulting data is displayed using a display device, such as a monitor.

[0006] Typically, the ultrasonic signal transmitted into the medium under investigation is generated by applying continuous or pulsed electronic signals to an ultrasound generating transducer. The transmitted ultrasound is most commonly in the range of 1 MHz to 15 MHz. The ultrasound propagates through the medium under investigation and reflects off interfaces, such as boundaries, between adjacent tissue layers. Scattering of the ultrasonic signal is the deflection of the ultrasonic signal in random directions. Attenuation of the ultrasonic signal is the loss of ultrasonic signal as the signal travels. Reflection of the ultrasonic signal is the bouncing off of the ultrasonic signal from an object and changing its direction of travel. A reflector is an object that reflects ultrasonic signals. Transmission of the ultrasonic signal is the passing of the ultrasonic signal through a medium. As it travels, the ultrasonic energy is scattered, attenuated, reflected, and/or transmitted. The portion of the reflected or scattered signal that returns to the transducers is detected as echoes by detecting transducers. The detecting transducers convert the ultrasound echoes to electronic echo signals and, after amplification and digitization, furnishes these signals to a reconstruction unit. The reconstruction unit in turn calculates locations of echo sources. After reconstructing, the calculated positional information is used to generate two-dimensional data that can be presented as an image.

[0007] Oscillations in ultrasonic signal intensity are often called "side lobes." Side lobes occur when the ultrasonic signal's intensity oscillates as a function of position rather than falls off monotonically as a function of distance from the center of the medium under investigation. The term "apodization" refers to the process of affecting the distribution of ultrasonic signal intensity of transducer elements to reduce side lobes.

[0008] Ultrasound imaging systems typically use a transducer array having a fixed number of transducer elements. The number of transmit and/or receive channels used by the system may be less than the number of transducer elements to lower costs and increase portability. Multiplexers typically control the size and location of active transmit and receive apertures in hardware by selecting which transducer elements are coupled to the transmit and/or receive channels. For the purposes of this application, the size of an aperture is expressed as a number of active transducer elements.

[0009] Lateral resolution is the minimum separation between two point reflectors in a medium under investigation that can produce two separate echoes with an ultrasound system. Lateral resolution may be poor if the image of a point target is too wide, and two or more closely spaced reflectors are detected as a single reflector. Sensitivity is the ability of an ultrasound system to detect weak echoes. Contrast resolution is the ability of an ultrasound system to distinguish differences in strength of adjacent echoes. Improving lateral resolution, sensitivity, and contrast resolution improves the overall performance of an ultrasound system.

[0010] There are various known methodologies for improving the lateral resolution, sensitivity, and contrast resolution in an ultrasound imaging system having a limited number of transmit and/or receive channels. For example, a synthetic transmit aperture or receive aperture improves lateral resolution, sensitivity, and contrast resolution, but results in a reduced frame rate. A synthetic receive aperture can be implemented by making two or more transmit firings in the same image area (or line) and using different receive channels for each firing using multiplexer control. The receive aperture is synthesized from all of the firings to form a larger effective receive aperture. A synthetic transmit aperture or receive aperture can also be implemented by utilizing the symmetry of some scan formats, such as linear and curved linear formats. For example, the symmetry of some scan formats results in symmetric element pairs. Shorting symmetric element pairs together in hardware increases the effective aperture during transmission or reception. However, such an implementation in hardware only extracts a single line of information per firing.

[0011] Another known methodology for improving lateral resolution, sensitivity, and contrast resolution in an ultrasound imaging system with a limited number of transmit and/or receive channels is using adaptive element pitch control through various multiplexer connections. Adaptive element pitch control is implemented in hardware through multiplexer connections and includes element skipping, element shorting, and a combination of both. Adaptive element pitch selection can be changed for different operating modes, for example B-mode or color flow imaging, or for different operating frequencies. Since adaptive element pitch control is implemented in hardware, the transmit

and/or receive aperture cannot be adaptively varied as a function of the depth of the imaging point.

SUMMARY OF THE INVENTION

[0012] In accordance with the present invention, a system and method are disclosed to implement an adaptive receive aperture for ultrasound image reconstruction. In one embodiment, the method of the invention includes determining a size of a desired receive aperture at each imaging point, comparing the size of the desired receive aperture with a predetermined number of reconstruction channels, if the size of the desired receive aperture is not greater than the number of reconstruction channels, processing echo signals for the desired receive aperture to produce an ultrasound image, and if the size of the desired receive aperture is greater than the number of reconstruction channels, preprocessing the echo signals for the desired receive aperture to produce reconstruction signals that are equal in number to the number of reconstruction channels, and then processing the reconstruction signals to produce an ultrasound image. The size of the desired receive aperture may be based on the line and the depth of an imaging point in a region of interest in a medium under investigation. Reconstruction channels are the processing channels of the reconstruction processor determined by the processing power and the frame rate requirement of the ultrasound system.

[0013] In one embodiment, the system of the invention includes a transducer array having a plurality of transducer elements. Each of the transducer elements is configured to receive ultrasonic signals and convert them into electronic echo signals. The system also includes a multiplexer for selectively coupling transducer elements in the transducer array, and passing the selected echo signals from the selected receive channels. A reconstruction unit is configured to receive the selected echo signals from the multiplexer. The reconstruction unit includes a receive aperture control engine configured to use the selected echo signals to adaptively determine a set of reconstruction signals. The receive aperture control engine compares the size of the receive aperture with a predetermined number of reconstruction channels at each imaging point. If the size of the receive aperture is not greater than the number of reconstruction channels, the receive aperture control engine passes all of the selected echo signals for further processing by a reconstruction processor. If the size of the receive aperture is greater than the number of reconstruction channels, the receive aperture control engine preprocesses the echo signals to produce reconstruction signals that are equal in number to the number of reconstruction channels, and outputs the reconstruction signals for further processing by the reconstruction processor.

[0014] In one embodiment, preprocessing the echo signals includes grouping qualified channels in the receive aperture by taking a weighted sum of each group. A group of qualified channels may be a pair of adjacent channels or channels with symmetry with respect to the imaging point. In one embodiment, the receive aperture control engine identifies groups of qualified channels by determining whether the phase difference between echo signals for a group of channels is less than a specified value. Preprocessing may also include skipping (ignoring) echo signals for certain channels in the receive aperture.

BRIEF DESCRIPTION OF THE DRAWINGS

[0015] FIG. 1 is a block diagram of one embodiment for an ultrasound imaging system, in accordance with the present invention;

[0016] FIG. 2 is a block diagram of one embodiment of the reconstruction unit of FIG. 1, in accordance with the invention;

[0017] FIG. 3 is a flowchart of method steps for adaptively determining a set of reconstruction signals, in accordance with one embodiment of the invention; and

[0018] FIGS. 4A-4E illustrate determining reconstruction signals in accordance with one embodiment of the invention.

DETAILED DESCRIPTION OF THE INVENTION

[0019] FIG. 1 is a block diagram of one embodiment of an ultrasound imaging system that includes, but is not limited to, a transducer 110, a multiplexer 112, a transmit/receive switch 114, a transmitter 118, a receiver 120, an analog to digital converter 122, a reconstruction unit 124, an image post processing unit 126, a scan converter 128, and an image display 130. Transducer 110 includes an array of transducer elements that may be arranged in various configurations, such as linear, sector, and curved linear. Each of the transducer elements is configured to produce and receive ultrasonic signals. Transducer 110 converts electronic signals into ultrasonic signals while transmitting, and converts received ultrasonic signals into electronic echo signals while receiving. Multiplexer 112 controls which transducer elements in transducer 110 are coupled to transmit and/or receive channels for transmitting and/or receiving ultrasonic signals. Multiplexer 112 controls the size and location of a receive aperture by coupling certain transducer elements to transmit/receive switch 114. Transmitter 118 produces electronic signals for driving transducer 110 to produce, focus or defocus, and steer an ultrasound beam. Transmit/receive switch 114 allows signals from transmitter 118 to pass to multiplexer 112, and allows echo signals from multiplexer 112 to pass to receiver 120.

[0020] Receiver 120 receives echo signals via transmit/receive switch 114 and multiplexer 112 from transducer 110, and outputs the echo signals to analog to digital converter 122. Reconstruction unit 124 processes the digital echo signals from analog to digital converter 122 to produce reconstructed in-phase (I) and quadrature (Q) signals for each imaging point that are output to image post processing unit 126. The contents and functionality of reconstruction unit 124 are further discussed below in conjunction with FIG. 2. Image post processing unit 126 processes the I and Q signals, and scan converter 128 processes the output of image post processing unit 126 to produce image data that is output to image display 130. Image post processing unit 126 and scan converter 128 may process the I and Q signals to produce, for example, B-mode (gray-scale) image data, color image data, color Doppler image data, or any other type of image data appropriate for producing an ultrasound image.

[0021] FIG. 2 is a block diagram of one embodiment of reconstruction unit 124 of FIG. 1, in accordance with the invention. Reconstruction unit 124 includes, but is not limited to, a receive aperture control engine 210 and a

reconstruction processor 212. The input to receive aperture control engine 210 is the digitized signals from all receive channels within the receive aperture in the format of I and Q signals. Receive aperture control engine 210 adaptively determines a set of reconstruction signals and sends the reconstruction signals, and their corresponding phase alignment and apodization information, to reconstruction processor 212. The functionality of receive aperture control engine 210 is further discussed below in conjunction with FIG. 3.

[0022] Reconstruction processor 212 combines the reconstruction signals and their corresponding phase alignment and apodization information into a single digital signal at every imaging point in the format of I and Q signals. The reconstructed I and Q signals are output to image post processing unit 126 (FIG. 1).

[0023] FIG. 3 is a flowchart of method steps for adaptively determining a set of reconstruction signals, according to one embodiment of the invention. An ultrasound system may transmit ultrasonic signals into a medium under investigation, for example a human patient, to produce an image of a region of interest, for example the abdomen. In general, increasing the depth of an imaging point requires increasing the number of reconstruction channels, which corresponds to slower reconstruction or a need for greater computational power, and decreasing the depth of an imaging point requires decreasing the number of reconstruction channels, which corresponds to faster reconstruction or a need for lower computational power. Practically, the ultrasound system may not be able to support the number of reconstruction channels required. A number of reconstruction channels, N_{rec} , is set by the ultrasound system for each imaging point at a line m and a depth r . N_{rec} may be set according to various criteria, for example cost and desired frame rate. N_{rec} indicates a number of available reconstruction channels, but does not indicate a particular set of reconstruction channels or receive channels in the system.

[0024] In step 310, receive aperture control engine 210 selects a desired receive aperture, N_{aper} , which is a function of the imaging point at line m and depth r , and is expressed as a number of channels. Typically, an imaging point at a shallower depth requires a smaller receive aperture and an imaging point at a deeper depth requires a larger receive aperture for a given resolution. Then, in step 312, receive aperture control engine 210 determines whether N_{aper} is greater than N_{rec} . If N_{aper} is not greater than N_{rec} , then a number of reconstruction signals N_{temp} is set equal to N_{aper} , and in step 314 receive aperture control engine 210 passes the received echo signals, and their corresponding phase alignment and apodization information, for the N_{aper} channels to reconstruction processor 212 with no preprocessing. When N_{aper} is not greater than N_{rec} , the echo signals are the reconstruction signals used by reconstruction processor 212 to produce the I and Q signals.

[0025] If N_{aper} is greater than N_{rec} , then the method continues with step 316, where receive aperture control engine 210 preprocesses the received echo signals to produce N_{temp} reconstruction signals according to a predefined rule, where the number of reconstruction signals N_{temp} is set equal to N_{rec} . In one embodiment, the predefined rule is to group qualified channels and, if necessary, skip channels in the receive aperture such that the number of reconstruction signals (N_{temp}) is equal to N_{rec} . In one embodiment, a set of

adjacent (two or more) channels is qualified if the phase difference between echo signals corresponding to the adjacent channels is smaller than a specified value (e.g., forty-five degrees). In another embodiment, a set of channels that are symmetric with respect to the imaging point is qualified because the phases of the symmetric channels are equal. In another embodiment, both qualified adjacent channels and qualified symmetric channels are grouped if they are all qualified according to the predefined rule. Receive aperture control engine 210 groups qualified channels by taking a weighted sum of the received echo signals from the channels in each group. The weights for grouped channels may be equal, or may be set based on a receive aperture apodization function. The corresponding phase alignment and apodization information of the reconstruction signal for a channel group represents the phase alignment and apodization information of that group.

[0026] If all qualified channels are grouped and the resulting number of reconstruction signals is greater than N_{rec} , then receive aperture control engine 210 skips selected channels in the receive aperture (i.e., ignores the echo signals on selected channels) to reduce the number of reconstruction signals to be equal to N_{rec} .

[0027] FIGS. 4A-4E illustrate selection of reconstruction signals in accordance with one embodiment of the invention. For the purpose of illustration, the maximum number of receive channels shown in FIGS. 4A-4D is thirty-two and in FIG. 4E is sixty-four, and the number of available reconstruction channels N_{rec} is sixteen; however, any maximum number of receive channels and any value of N_{rec} are within the scope of the invention. In FIG. 4A, the imaging point to be reconstructed is in a near field at depth $r1$, and the size of the desired aperture, N_{aper} , is ten channels. Since N_{aper} is not greater than N_{rec} (i.e., $10 < 16$), the number of reconstruction signals N_{temp} is set equal to N_{aper} , and receive aperture control engine 210 passes the received echo signals as the reconstruction signals, and their phase alignment and apodization information, for all N_{aper} channels to reconstruction processor 212. The reconstruction signals and their phase alignment and apodization information are further processed by reconstruction processor 212 to produce I and Q signals of the imaging point.

[0028] In FIG. 4B, the imaging point is in a mid field at depth $r2$, and the desired aperture, N_{aper} , is eighteen channels. The imaging point is at a greater depth than that of FIG. 4A, and thus the desired aperture is larger. Since N_{aper} is greater than N_{rec} (i.e., $18 > 16$), receive aperture control engine 210 sets N_{temp} equal to N_{rec} and preprocesses the received echo signals to produce N_{temp} reconstruction signals according to the predefined rule described above in conjunction with FIG. 3. In FIG. 4B, receive aperture control engine 210 determines that there are four qualified pairs of adjacent channels, but since there are only two extra data points ($N_{aper} - N_{rec} = 18 - 16 = 2$), receive aperture control engine 210 groups two pairs of channels (indicated by arrow connectors in FIG. 4B) by taking a weighted sum of the echo signals of the adjacent channels, resulting in reconstruction signals for the reconstruction channels labeled seven and eight in FIG. 4B. The corresponding phase alignment and apodization information of the reconstruction signal for a grouped pair of channels represents the phase alignment and apodization information of that pair.

[0029] In FIG. 4C, the imaging point is in a far field at depth r_3 , and the desired aperture, N_{aper} , is thirty-two channels. The imaging point is at a deeper depth than those of FIGS. 4A and 4B, and thus the desired aperture is larger. Since N_{aper} is greater than N_{rec} (i.e., $32 > 16$), receive aperture control engine 210 sets N_{temp} equal to N_{rec} and preprocesses the received echo signals to produce N_{temp} reconstruction signals according to the predefined rule described above in conjunction with FIG. 3. In the FIG. 4C embodiment, receive aperture control engine 210 determines that there are four qualified pairs of adjacent channels, and groups the four pairs of channels (indicated by arrow connectors in FIG. 4C) by taking a weighted sum of each pair of adjacent channels, resulting in reconstruction signals for the reconstruction channels labeled six through nine in FIG. 4C. The corresponding phase alignment and apodization information of the reconstruction signal for a grouped pair of channels represents the phase alignment and apodization information of that pair.

[0030] After grouping all of the available qualified pairs of adjacent channels, receive aperture control engine 210 still needs to reduce the number of channels by twelve. Since there are no remaining qualified pairs of adjacent channels, receive aperture control engine 210 discards twelve channels by skipping alternate channels from each side of the grouped channels. Receive aperture control engine 210 ignores the echo signals that correspond to the skipped channels by not passing them to reconstruction processor 212. Receive aperture control engine 210 then outputs the N_{temp} reconstruction signals and their corresponding phase alignment and apodization information to reconstruction processor 212.

[0031] In FIG. 4D, the imaging point is in a far field at depth r_3 as in FIG. 4C, and the desired aperture, N_{aper} , is thirty-two channels. In the FIG. 4D embodiment, the scan format of the ultrasound system is linear, curved linear, or any other scan format that applies symmetric delay profiles with respect to reconstruction line origin. Receive aperture control engine 210 determines that there are sixteen pairs of channels that are symmetric about the imaging point, and qualify for grouping. Receive aperture control engine 210 groups all sixteen pairs of symmetric channels (indicated by arrow connectors in FIG. 4D) by taking a weighted sum of each pair of symmetric channels, resulting in reconstruction signals for the reconstruction channels labeled zero through fifteen in FIG. 4D. After grouping, the number of reconstruction signals is equal to N_{rec} , so no channels need to be skipped.

[0032] In FIG. 4E, the maximum number of receive channels is sixty-four, and the receive channels are arranged as a two-dimensional array. Only two channels in the elevation direction are shown for ease of illustration; however, any number of receive channels in the elevation and any type of symmetry of transducer 110 is within the scope of the invention. The imaging point is in a far field at depth r_3 and the desired aperture, N_{aper} , is sixty-four channels. In the FIG. 4E embodiment, the scan format of the ultrasound system is linear, curved linear, or any other scan format that applies symmetric delay profiles with respect to reconstruction line origin. Receive aperture control engine 210 determines that there are sixteen sets of four channels that are symmetric about the imaging point and qualify for grouping. Receive aperture control engine 210 groups all sixteen sets of four qualified channels (indicated by arrow connectors in

FIG. 4E) by taking a weighted sum of each set of four channels, resulting in reconstruction signals for the reconstruction channels labeled zero through fifteen in FIG. 4E. After grouping, the number of reconstruction signals is equal to N_{rec} , so no channels need to be skipped.

[0033] Receive aperture control engine 210 determines whether to preprocess the received echo signals at each imaging point and determines how to preprocess the received echo signals at each imaging point. Channels are discarded or grouped within the desired receive aperture only when necessary. Preprocessing the received echo signals according to the invention optimizes the use of the reconstruction processing power of the ultrasonic imaging system of FIG. 1. According to the invention, the effective receive aperture can be adaptively varied as a function of the location of the imaging point. The ultrasonic imaging system is able to optimally use the limited number of reconstruction channels to provide improved lateral resolution, sensitivity, and contrast resolution at each imaging point in a region of interest in a medium under investigation.

[0034] The invention has been described above with reference to specific embodiments. It will, however, be evident that various modifications and changes may be made thereto without departing from the broader spirit and scope of the invention as set forth in the appended claims. The foregoing description and drawings are, accordingly, to be regarded in an illustrative rather than a restrictive sense.

1. A method of processing ultrasound signals, comprising:
receiving ultrasound signals from a medium of interest;
converting the received ultrasound signals into echo signals;
identifying qualified reconstruction channels in a receive aperture;
grouping the qualified reconstruction channels in the receive aperture; and
preprocessing the selected echo signals.

2. The method of claim 1, wherein preprocessing the echo selected signals comprises use of the grouped qualified reconstruction channels to produce reconstruction signals.

3. The method of claim 1, wherein preprocessing the selected echo signals comprises skipping echo signals for certain reconstruction channels.

4. The method of claim 1, wherein identifying qualified reconstruction channels in a receive aperture comprises determining whether a phase difference between the echo signals for a qualified reconstruction channel is less than a specified value.

5. The method of claim 1, wherein a group of qualified reconstruction channels comprises a pair of adjacent channels.

6. The method of claim 1, wherein a group of qualified reconstruction channels comprises channels with symmetry with respect to an imaging point.

7. The method of claim 1, wherein grouping the qualified reconstruction channels comprises taking a weighted sum of echo signals corresponding to the qualified reconstruction channels.

8. The method of claim 7, wherein each channel in the qualified group of reconstruction channels has a weight equal to a weight of other channels in the qualified group of channels.

9. The method of claim 7, wherein each channel in the qualified group of reconstruction channels has a weight based on a receive aperture apodization function for a current image point.

10. A method of adaptively determining a set of reconstruction signals, comprising:

selectively passing echo signals to a reconstruction unit;
comparing a number of channels in a receive aperture with a number of reconstruction channels to determine a number of reconstruction signals, wherein comparing comprises using the selected echo signals to determine the number of reconstruction signals to be equal to the number of reconstruction channels if the number of channels in the receive aperture is greater than the number of reconstruction channels; and

grouping qualified channels in the receive aperture such that the number of reconstruction signals is not less than the number of reconstruction channels.

11. The method of claim 10, wherein grouping qualified channels in the receive aperture comprises taking a weighted sum of echo signals corresponding to the qualified channels.

12. The method of claim 11, wherein each channel in a group of qualified channels has a weight equal to a weight of other channels in the group of qualified channels.

13. The method of claim 11, wherein each channel in a group of qualified channels has a weight based on a receive aperture apodization function for a current image point.

14. The method of claim 10, wherein a group of channels in the receive aperture is qualified if the channels in the group are symmetric about an imaging point.

15. The method of claim 10, wherein a group of channels in the receive aperture are qualified if the group of channels is an adjacent pair of channels and a phase difference between echo signals for the channels of the pair is less than a specified value.

16. The method of claim 10, further comprising skipping channels in the receive aperture such that the number of reconstruction signals equals the number of reconstruction channels.

17. The method of claim 16, wherein skipping channels in the receive aperture comprises ignoring signals on the skipped channels.

18. An ultrasound reconstruction unit configured to receive selected echo signals from a plurality of transducer elements, the ultrasound reconstruction unit comprising a receive aperture control engine configured to use selected echo signals to adaptively determine a set of reconstruction signals.

19. The ultrasound reconstruction unit of claim 18, wherein the ultrasound reconstruction unit is further configured to process the set of reconstruction signals to produce in-phase and quadrature signals.

20. The ultrasound reconstruction unit of claim 18, wherein the receive aperture control engine is further configured to adaptively determine a number of reconstruction signals by comparing a number of channels of a receive aperture with a number of reconstruction channels.

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专利名称(译)	接收孔径控制的超声图像重建		
公开(公告)号	US20050131296A1	公开(公告)日	2005-06-16
申请号	US11/048288	申请日	2005-01-31
[标]申请(专利权)人(译)	周清华 MCLAUGHLIN GLENW MO LARRY Y 姬廷局域网		
申请(专利权)人(译)	CHOU李庆华 MCLAUGHLIN GLEN W. MO LARRY Y. 姬廷-LAN		
当前申请(专利权)人(译)	深圳迈瑞生物医疗电子股份有限公司.		
[标]发明人	CHOU CHING HUA MCLAUGHLIN GLEN W MO LARRY Y L JI TING LAN		
发明人	CHOU, CHING-HUA MCLAUGHLIN, GLEN W. MO, LARRY Y.L. JI, TING-LAN		
IPC分类号	G01S7/52 G01S15/89 A61B8/00		
CPC分类号	G01S7/52047 G01S15/8915 Y10S128/916		
其他公开文献	US7087020		
外部链接	Espacenet USPTO		

摘要(译)

提供了用于处理超声信号的方法。超声信号的处理包括识别接收孔径中的合格重建信道，在孔径中对合格的重建信道进行分组，以及使用分组的合格重建信道预处理所选择的回波信号以产生重建信号。附加方法包括将接收孔径中的多个信道与多个重建信道进行比较，以确定多个重建信号，并在接收孔径中对合格信道进行分组，使得重建数据信号的数量不小于重建信道的数量。。还提供了一种超声重建单元，包括：接收孔径控制引擎，被配置为使用所选择的回波信号来自适应地确定一组重建信号。

