



US 20120101378A1

(19) **United States**

(12) **Patent Application Publication**
LEE

(10) **Pub. No.: US 2012/0101378 A1**
(43) **Pub. Date: Apr. 26, 2012**

(54) **PROVIDING AN ULTRASOUND SPATIAL COMPOUND IMAGE BASED ON A PHASED ARRAY PROBE IN AN ULTRASOUND SYSTEM**

(52) **U.S. Cl. 600/437**

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(57) **ABSTRACT**

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Embodiments for providing an ultrasound spatial compound image are disclosed. In one embodiment, by way of non-limiting example, an ultrasound system comprises: an ultrasound data acquisition unit configured to acquire ultrasound data based on a phased array probe having a plurality of elements; and a processing unit in communication with the ultrasound data acquisition unit, the processing unit being configured to set a virtual common point corresponding to predetermined scan-lines, move the virtual common point in a longitudinal direction of the elements to set a plurality of scan-lines, form a plurality of ultrasound images based on the ultrasound data, and perform spatial compounding upon the ultrasound images to form an ultrasound spatial compound image, wherein the ultrasound data acquisition unit is configured to acquire the ultrasound data based on the plurality of scan-lines corresponding to each of the ultrasound images.

(21) Appl. No.: **13/209,833**

(22) Filed: **Aug. 15, 2011**

(30) **Foreign Application Priority Data**

Oct. 20, 2010 (KR) 10-2010-0102629

Publication Classification

(51) **Int. Cl.**
A61B 8/00 (2006.01)

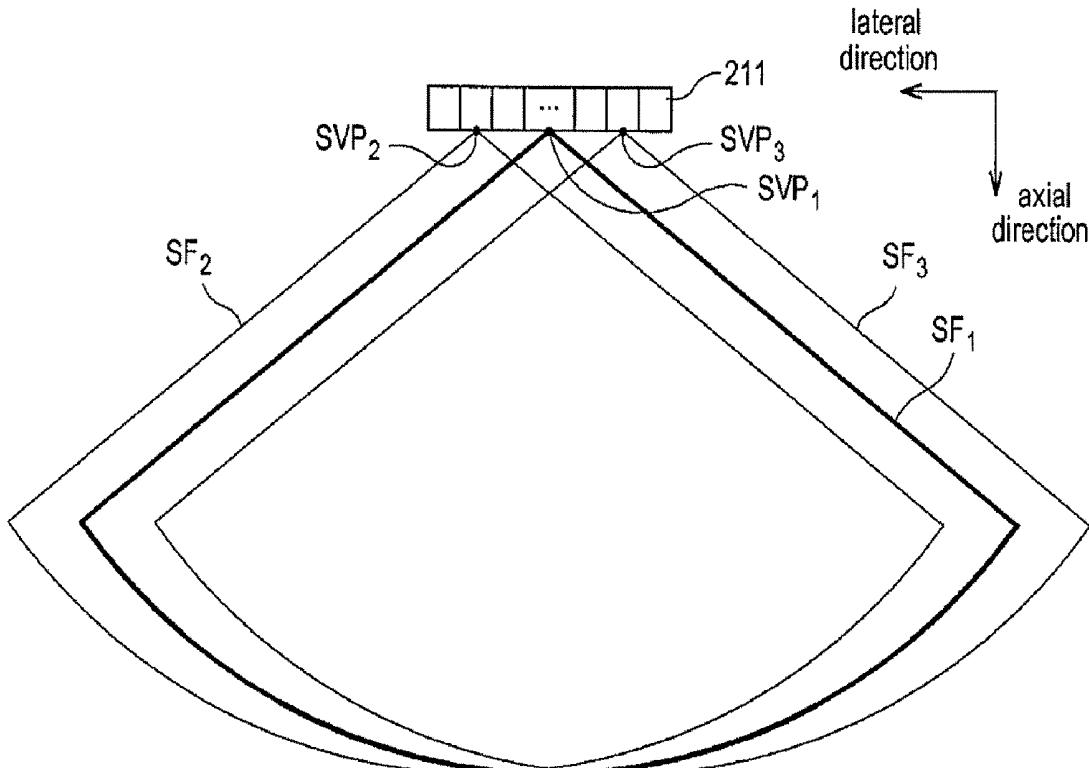


FIG. 1

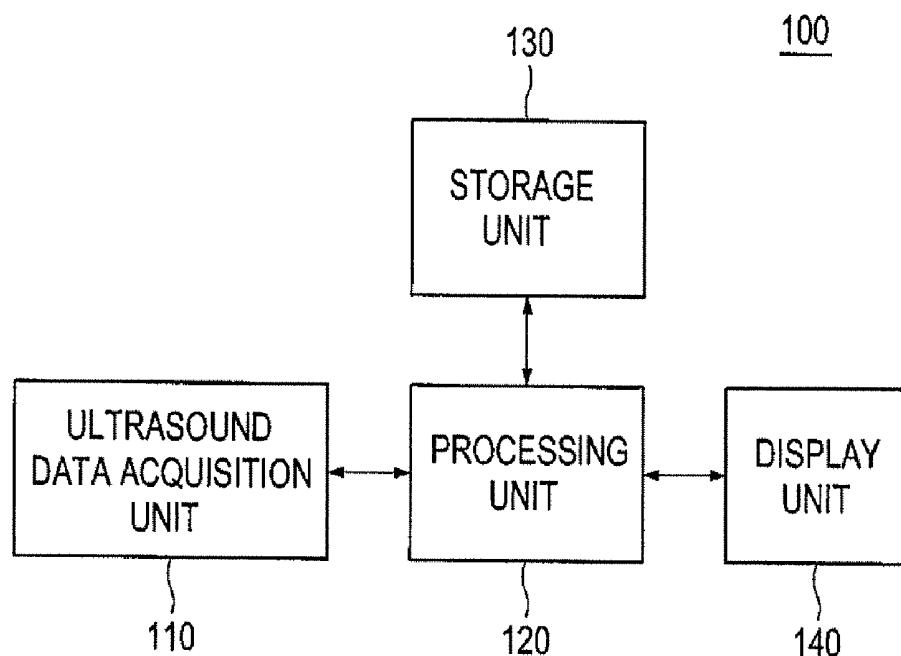


FIG. 2

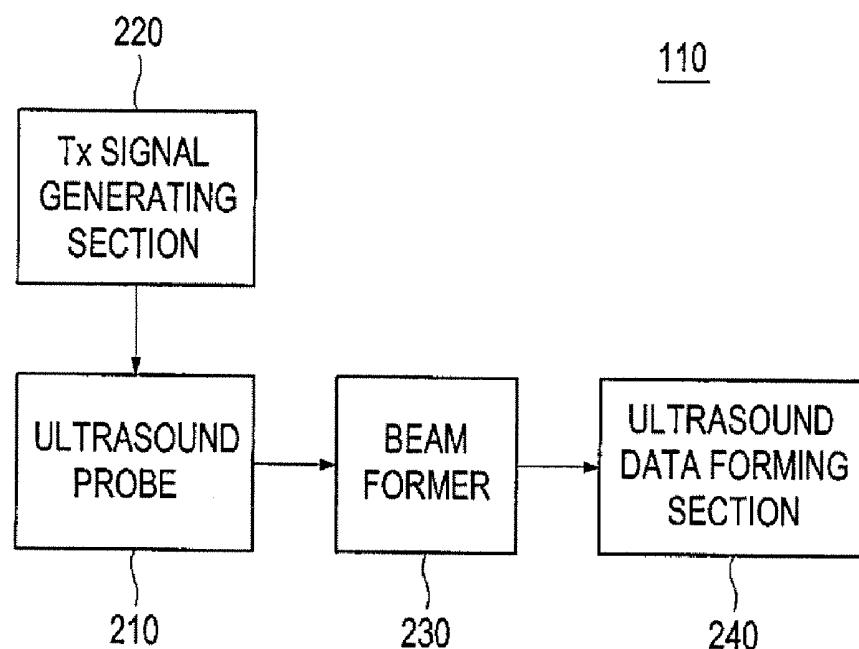


FIG. 3

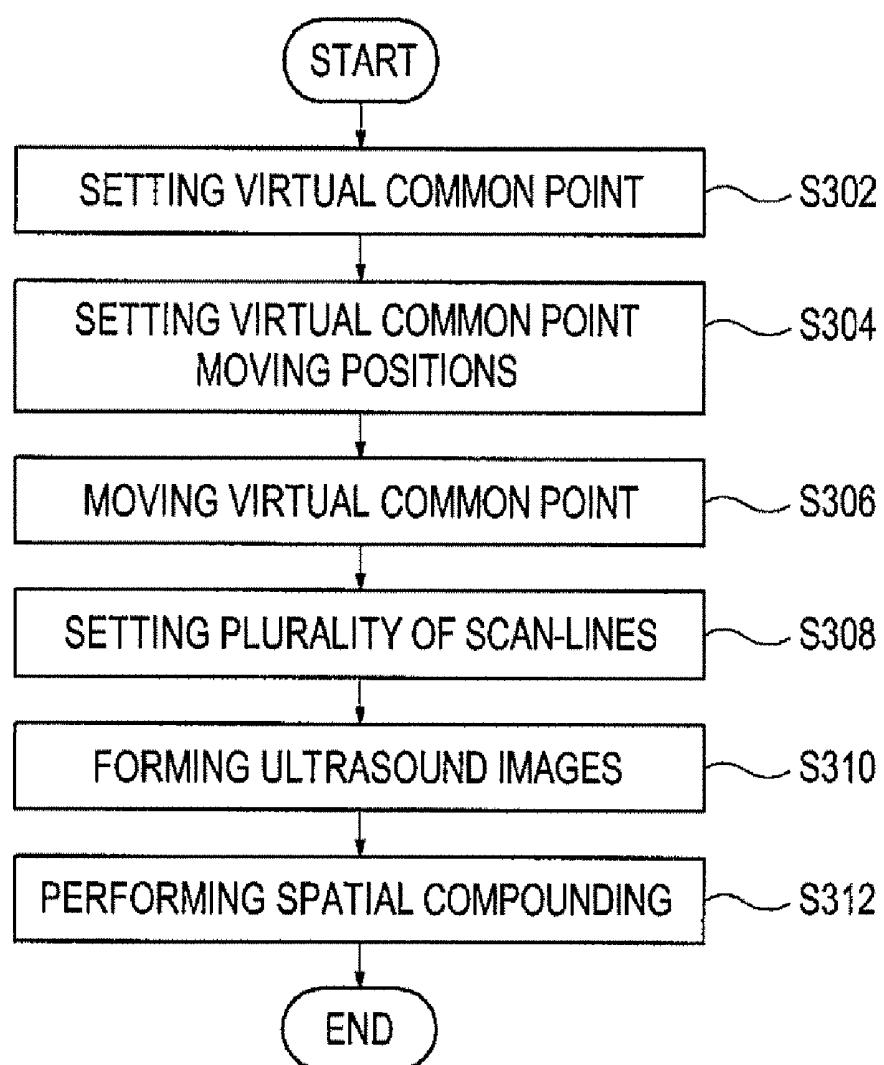


FIG. 4

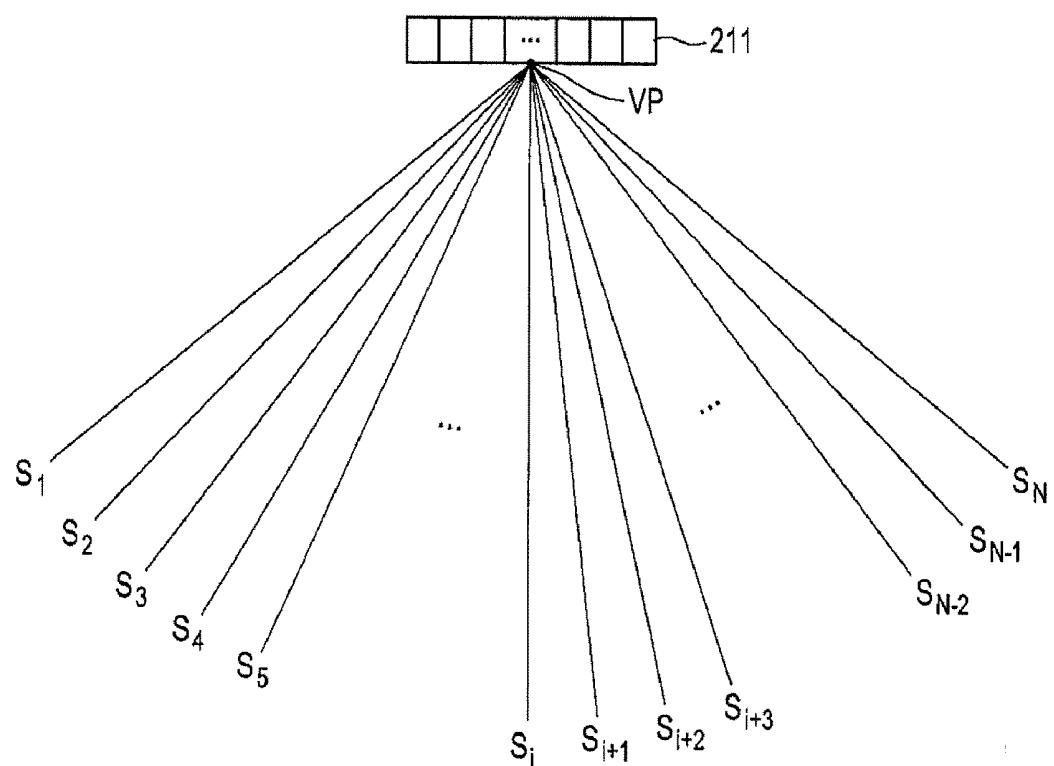


FIG. 5

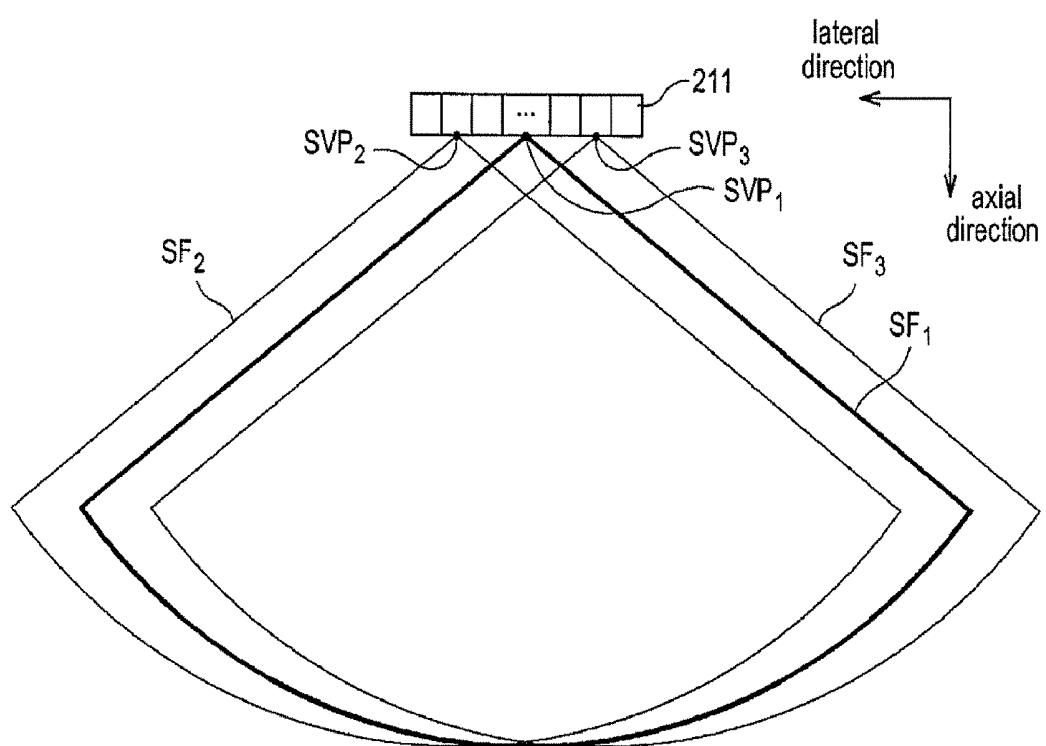
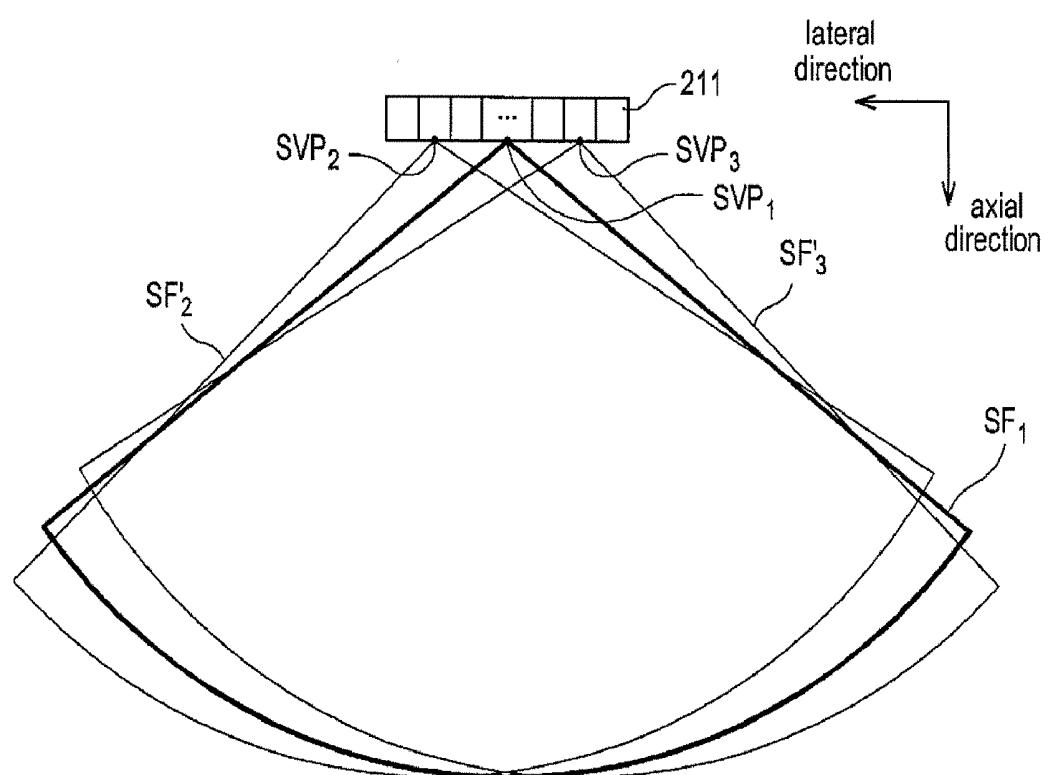


FIG. 6



PROVIDING AN ULTRASOUND SPATIAL COMPOUND IMAGE BASED ON A PHASED ARRAY PROBE IN AN ULTRASOUND SYSTEM

CROSS-REFERENCE TO RELATED APPLICATION

[0001] The present application claims priority from Korean Patent Application No. 10-2010-0102629 filed on Oct. 20, 2010, the entire subject matter of which is incorporated herein by reference.

TECHNICAL FIELD

[0002] The present disclosure generally relates to ultrasound systems, and more particularly to providing an ultrasound spatial compound image based on a phased array probe in an ultrasound system.

BACKGROUND

[0003] An ultrasound system has become an important and popular diagnostic tool since it has a wide range of applications. Specifically, due to its non-invasive and non-destructive nature, the ultrasound system has been extensively used in the medical profession. Modern high-performance ultrasound systems and techniques are commonly used to produce two-dimensional or three-dimensional ultrasound images of internal features of a target object (e.g., human organs).

[0004] The ultrasound system may transmit and receive ultrasound signals to and from a living body to thereby form a 2D (two-dimensional) ultrasound image or a 3D (three-dimensional) ultrasound image. Various techniques have been studied to enhance resolution of the ultrasound image. Spatial compounding is known as one of such techniques.

[0005] Spatial compounding is an imaging technique for forming a compound image by combining ultrasound images. That is, the ultrasound system forms a plurality of ultrasound images and performs the spatial compounding upon the ultrasound images to form an ultrasound spatial compound image.

[0006] The ultrasound system sets a virtual common point, at which scan-lines intersect by extending the scan-lines to back of elements of a convex probe, and moves the virtual common point to particular positions to thereby set a plurality of scan-lines corresponding to each of the ultrasound images. However, there is a problem since the ultrasound spatial compound image cannot be formed by using a phased array probe.

SUMMARY

[0007] Embodiments for providing an ultrasound spatial compound image in an ultrasound system are disclosed herein. In one embodiment, by way of non-limiting example, an ultrasound system comprises: an ultrasound data acquisition unit configured to acquire ultrasound data based on a phased array probe having a plurality of elements; and a processing unit in communication with the ultrasound data acquisition unit, the processing unit being configured to set a virtual common point corresponding to predetermined scan-lines, move the virtual common point in a longitudinal direction of the elements to set a plurality of scan-lines, form a plurality of ultrasound images based on the ultrasound data, and perform spatial compounding upon the ultrasound images to form an ultrasound spatial compound image, wherein the ultrasound data acquisition unit is configured to

acquire the ultrasound data based on the plurality of scan-lines corresponding to each of the ultrasound images.

[0008] In another embodiment, there is a method of providing an ultrasound spatial compound image based on a phased array probe having a plurality of elements, comprising: a) setting a virtual common point corresponding to predetermined scan-lines; b) moving the virtual common point in a longitudinal direction of the elements to set a plurality of scan-lines; c) acquiring ultrasound data by transmitting and receiving ultrasound signals based on the plurality of scan-lines; d) forming a plurality of ultrasound images based on the ultrasound data; and e) performing spatial compounding upon the ultrasound images to form an ultrasound spatial compound image.

[0009] This summary is provided to introduce a selection of concepts in a simplified form that are further described below in the Detailed Description. This Summary is not intended to identify key or essential features of the claimed subject matter, nor is it intended to be used in determining the scope of the claimed subject matter.

BRIEF DESCRIPTION OF THE DRAWINGS

[0010] FIG. 1 is a block diagram showing an illustrative embodiment of an ultrasound system.

[0011] FIG. 2 is a block diagram showing an illustrative embodiment of an ultrasound data acquisition unit.

[0012] FIG. 3 is a flow chart showing a process of forming an ultrasound spatial compound image.

[0013] FIG. 4 is a schematic diagram showing an example of a plurality of scan-lines and a virtual common point.

[0014] FIG. 5 is a schematic diagram showing an example of ultrasound images and sub-virtual common points.

[0015] FIG. 6 is a schematic diagram showing another example of the ultrasound images and the sub-virtual common points.

DETAILED DESCRIPTION

[0016] A detailed description may be provided with reference to the accompanying drawings. One of ordinary skill in the art may realize that the following description is illustrative only and is not in any way limiting. Other embodiments of the present invention may readily suggest themselves to such skilled persons having the benefit of this disclosure.

[0017] Referring to FIG. 1, an ultrasound system 100 in accordance with an illustrative embodiment is shown. As depicted therein, the ultrasound system 100 may include an ultrasound data acquisition unit 110. The ultrasound data acquisition unit 110 may be configured to transmit and receive ultrasound signals to and from a living body to acquire ultrasound data. The living body may include a plurality of target objects (e.g., blood vessels, a heart, etc.).

[0018] FIG. 2 is a block diagram showing an illustrative embodiment of the ultrasound data acquisition unit 110. Referring to FIG. 2, the ultrasound data acquisition unit 110 may include an ultrasound probe 210. The ultrasound probe 210 may include a plurality of elements 211 (see FIG. 4) for reciprocally converting between ultrasound signals and electrical signals. The ultrasound probe 210 may be configured to transmit ultrasound signals to the living body along each of a plurality of scan-lines. The ultrasound probe 210 may be further configured to receive ultrasound signals (i.e., ultrasound echo signals) from the living body to output received

signals. The received signals may be analog signals. The ultrasound probe **210** may include a phased array probe.

[0019] The ultrasound data acquisition unit **110** may further include a transmit (Tx) signal generating section **220**. The Tx signal generating section **220** may be configured to control the transmission of the ultrasound signals. The Tx signal generating section **220** may be further configured to generate electrical signals (“Tx signals”) for obtaining at least one ultrasound image in consideration of the elements and focal points. The ultrasound image may include a brightness mode image. However, it should be noted herein that the ultrasound image may not be limited thereto.

[0020] In one embodiment, the Tx signal generating section **220** may be configured to generate first Tx signals for obtaining a first ultrasound image SF_1 as shown in FIG. 5 or FIG. 6. Thus, the ultrasound probe **210** may be configured to convert the first Tx signals provided from the Tx signal generating section **220** into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output first received signals. The Tx signal generating section **220** may be further configured to generate second Tx signals for obtaining a second ultrasound image SF_2 as shown in FIG. 5 or FIG. 6. As such, the ultrasound probe **210** may be configured to convert the second Tx signals provided from the Tx signal generating section **220** into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output second received signals. The Tx signal generating section **220** may be further configured to generate third TX signals for obtaining a third ultrasound image SF_3 as shown in FIG. 5 or FIG. 6. Accordingly, the ultrasound probe **210** may be configured to convert the third Tx signals provided from the Tx signal generating section **220** into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output third received signals.

[0021] The number of ultrasound images may be determined depending on the number of the ultrasound images, which are needed to form an ultrasound spatial compound image.

[0022] The ultrasound data acquisition unit **110** may further include a beam former **230**. The beam former **230** may be configured to convert the received signals provided from the ultrasound probe **210** into digital signals. The beam former **230** may be further configured to apply delays to the digital signals in consideration of the elements and the focal points to thereby output digital receive-focused signals.

[0023] In one embodiment, the beam former **230** may be configured to convert the first received signals provided from the ultrasound probe **210** into first digital signals. The beam former **230** may be further configured to apply delays to the first digital signals in consideration of the elements and the focal points to thereby output first digital receive-focused signals. The beam former **230** may be also configured to convert the second received signals provided from the ultrasound probe **210** into second digital signals. The beam former **230** may be additionally configured to apply delays to the second digital signals in consideration of the elements and the focal points to thereby output second digital receive-focused signals. The beam former **230** may be further configured to convert the third received signals provided from the ultrasound probe **210** into third digital signals. The beam former **230** may be configured to apply delays to the third digital

signals in consideration of the elements and the focal points to thereby output third digital receive-focused signals.

[0024] The ultrasound data acquisition unit **110** may further include an ultrasound data forming section **240**. The ultrasound data forming section **240** may be configured to form ultrasound data corresponding to the ultrasound image based on the digital receive-focused signals. The ultrasound data may include radio frequency data. However, it should be noted herein that the ultrasound data may not be limited thereto. The ultrasound data forming section **240** may be also configured to perform signal processing (e.g., gain control, etc) upon the digital receive-focused signals.

[0025] In one embodiment, the ultrasound data forming section **240** may be configured to form first ultrasound data corresponding to the first ultrasound image SF_1 based on the first digital receive-focused signals provided from the beam former **230**. The ultrasound data forming section **240** may be further configured to form second ultrasound data corresponding to the second ultrasound image SF_2 based on the second digital receive-focused signals provided from the beam former **230**. The ultrasound data forming section **240** may be also configured to form third ultrasound data corresponding to the third ultrasound image SF_3 based on the third digital receive-focused signals provided from the beam former **230**.

[0026] Referring back to FIG. 1, the ultrasound system **100** may further include a processing unit **120** in communication with the ultrasound data acquisition unit **110**. The processing unit **120** may include a central processing unit, a microprocessor or a graphic processing unit. However, it should be noted herein that the processing unit **120** may not be limited thereto.

[0027] FIG. 3 is a flow chart showing a process of forming an ultrasound spatial compound image. The processing unit **120** may be configured to set a virtual common point VP corresponding to scan-lines S_1 to S_N in consideration of positions of the elements **211** as shown in FIG. 4, at step S302 in FIG. 3. The virtual common point VP may be a point, at which the scan-lines S_1 to S_N intersect.

[0028] The processing unit **120** may be configured to set virtual common point moving positions for moving the virtual common point VP in a lateral direction based on the virtual common point VP, at step S304 in FIG. 3. The lateral direction may be a longitudinal direction of the elements **211** as shown in FIG. 5. In FIG. 5, the axial direction may be a Tx direction of the ultrasound signals.

[0029] The processing unit **120** may be configured to move the virtual common point VP to the virtual common point moving positions to set sub-virtual common points corresponding to the ultrasound images, at step S306 in FIG. 3.

[0030] In one embodiment, the processing unit **120** may be configured to set a first virtual common point moving position corresponding to the first ultrasound image SF_1 based on the virtual common point VP. That is, the processing unit **120** may set a position of the virtual common point VP as the first virtual common point moving position. The processing unit **120** may be further configured to set a first sub-virtual common point SVP_1 corresponding to the first ultrasound image SF_1 based on the first virtual common point moving position, as shown in FIG. 5. The processing unit **120** may be also configured to set a second virtual common point moving position for moving the virtual common point VP in the lateral direction by a predetermined distance based on the virtual common point VP. The processing unit **120** may be

further configured to move the virtual common point VP to the second virtual common point moving position to set a second virtual common point SVP_2 corresponding to the second ultrasound image SF_2 , as shown in FIG. 5. The processing unit 120 may be also configured to set a third virtual common point moving position for moving the virtual common point VP in the lateral direction by a predetermined distance based on the virtual common point VP. The processing unit 120 may be further configured to move the virtual common point VP to the third virtual common point moving position to set a third virtual common point SVP_3 corresponding to the third ultrasound image SF_3 , as shown in FIG. 5. A distance between the virtual common point VP and the second sub-virtual common point SVP_2 and a distance between the virtual common point VP and the third sub-virtual common point SVP_3 are either same or different.

[0031] The processing unit 120 may be configured to set a plurality of scan-lines corresponding to each of the ultrasound images based on the virtual common point and the sub-virtual common points, at step S308 in FIG. 3. Thus, the ultrasound data acquisition unit 110 may be configured to transmit the ultrasound signals to the living body along the set scan-lines and receive the ultrasound echo signals from the living body to acquire the ultrasound data corresponding to each of the ultrasound images.

[0032] In one embodiment, the processing unit 120 may be configured to set a reference ultrasound image from the ultrasound images SF_1 to SF_3 . The processing unit 120 may set the first ultrasound image SF_1 , which does not move the virtual common point VP, as the reference ultrasound image. The processing unit 120 may be further configured to set a plurality of scan-lines corresponding to the reference ultrasound image (i.e., first ultrasound image SF_1). That is, the processing unit 120 may set the scan-lines S_1 to S_N shown in FIG. 4 as the plurality of scan-lines corresponding to the reference ultrasound image. The processing unit 120 may be further configured to move the first sub-virtual common point SVP_1 (i.e., virtual common point VP) to the second virtual common point SVP_2 to set a plurality of scan-lines (i.e., steering angles corresponding to the scan-lines) corresponding to the second ultrasound images SF_2 . That is, the processing unit 120 may set the plurality of scan-lines corresponding to the reference ultrasound image as the plurality of scan-lines corresponding to the second ultrasound image SF_2 . The processing unit 120 may be further configured to move the first sub-virtual common point SVP_1 (i.e., virtual common point VP) to the third sub-virtual common point SVP_3 to set a plurality of scan-lines (i.e., steering angles corresponding to the scan-lines) corresponding to the third ultrasound image SF_3 . That is, the processing unit 120 may set the plurality of scan-lines corresponding to the reference ultrasound image as the plurality of scan-lines corresponding to the third ultrasound image SF_3 .

[0033] Optionally, the processing unit 120 may be configured to rotate the second ultrasound image SF_2 toward the first ultrasound image SF_1 at a predetermined rotating angle on a basis of the second sub-virtual common point SVP_2 . The processing unit 120 may be further configured to reset a plurality of scan-lines corresponding to the rotated second ultrasound image SF_2 based on the predetermined rotating angle, as shown in FIG. 6. The processing unit 120 may be also configured to rotate the third ultrasound image SF_3 toward the first ultrasound image SF_1 at a predetermined rotating angle on a basis of the third sub-virtual common point SVP_3 . The processing unit 120 may be further config-

ured to reset a plurality of scan-lines corresponding to the rotated third ultrasound image SF_3 based on the predetermined rotating angle, as shown in FIG. 6.

[0034] The processing unit 120 may be configured to form the ultrasound images based on the ultrasound data provided from the ultrasound data acquisition unit 110, at step S310 in FIG. 3.

[0035] In one embodiment, the processing unit 120 may be configured to form the first ultrasound image SF_1 based on the first ultrasound data provided from the ultrasound data acquisition unit 110. The processing unit 120 may be further configured to form the second ultrasound image SF_2 based on the second ultrasound data provided from the ultrasound data acquisition unit 110. The processing unit 120 may be also configured to form the third ultrasound image SF_3 based on the third ultrasound data provided from the ultrasound data acquisition unit 110.

[0036] The processing unit 120 may be configured to perform spatial compounding upon the ultrasound images to form an ultrasound spatial compound image, at step S312 in FIG. 3. The methods of performing the spatial compounding are well known in the art. Thus, they have not been described in detail so as not to unnecessarily obscure the present invention. For example, the processing unit 120 may perform the spatial compounding by calculating a mean brightness value corresponding to each of the pixels of the ultrasound images.

[0037] Referring back to FIG. 1, the ultrasound system 100 may further include a storage unit 130. The storage unit 130 may store the ultrasound data acquired by the ultrasound data acquisition unit 110. The storage unit 130 may also store the ultrasound images formed by the processing unit 120.

[0038] The ultrasound system 100 may further include a display unit 140. The display unit 140 may be configured to display the ultrasound spatial compound image. The display unit 140 may be also configured to display the ultrasound images.

[0039] Although embodiments have been described with reference to a number of illustrative embodiments thereof, it should be understood that numerous other modifications and embodiments can be devised by those skilled in the art that will fall within the spirit and scope of the principles of this disclosure. More particularly, numerous variations and modifications are possible in the component parts and/or arrangements of the subject combination arrangement within the scope of the disclosure, the drawings and the appended claims. In addition to variations and modifications in the component parts and/or arrangements, alternative uses will also be apparent to those skilled in the art.

What is claimed is:

1. An ultrasound system, comprising:
 - an ultrasound data acquisition unit configured to acquire ultrasound data based on a phased array probe having a plurality of elements; and
 - a processing unit in communication with the ultrasound data acquisition unit, the processing unit being configured to set a virtual common point corresponding to predetermined scan-lines, move the virtual common point in a longitudinal direction of the elements to set a plurality of scan-lines, form a plurality of ultrasound images based on the ultrasound data, and perform spatial compounding upon the ultrasound images to form an ultrasound spatial compound image,

wherein the ultrasound data acquisition unit is configured to acquire the ultrasound data based on the plurality of scan-lines corresponding to each of the ultrasound images.

2. The ultrasound system of claim 1, wherein the processing unit is configured to:

set virtual common point moving positions for moving the virtual common point in the longitudinal direction on a basis of the virtual common point;

move the virtual common point to the virtual common point moving positions to set sub-virtual common points corresponding to the ultrasound images; and

set the plurality of scan-lines corresponding to each of the ultrasound images based on the virtual common point and the sub-virtual common points.

3. The ultrasound system of claim 2, wherein the processing unit is configured to:

set a reference ultrasound image from the ultrasound images;

set a position of the virtual common point as the virtual common point moving position corresponding to the reference ultrasound image; and

set remaining virtual common point moving positions corresponding to remaining ultrasound images based on the virtual common point moving position corresponding to the reference ultrasound image.

4. The ultrasound system of claim 3, wherein the processing unit is configured to:

set the predetermined scan-lines as the plurality of scan-lines corresponding to reference ultrasound image; and set the plurality of scan-lines corresponding to each of the remaining ultrasound images based on the plurality of the scan-lines corresponding to the reference ultrasound image.

5. The ultrasound system of claim 3, wherein the processing unit is further configured to:

rotate the remaining ultrasound images toward the reference ultrasound image at predetermined rotating angles based on the sub-virtual common points corresponding to the remaining ultrasound images; and

reset the plurality of scan-lines corresponding to the remaining ultrasound images.

6. A method of providing an ultrasound spatial compound image based on a phased array probe having a plurality of elements, comprising:

a) setting a virtual common point corresponding to predetermined scan-lines;

b) moving the virtual common point in a longitudinal direction of the elements to set a plurality of scan-lines;

c) acquiring ultrasound data by transmitting and receiving ultrasound signals based on the plurality of scan-lines;

d) forming a plurality of ultrasound images based on the ultrasound data; and

e) performing spatial compounding upon the ultrasound images to form an ultrasound spatial compound image.

7. The method of claim 6, wherein the step b) comprises:

b1) setting virtual common point moving positions for moving the virtual common point in the longitudinal direction on a basis of the virtual common point;

b2) moving the virtual common point to the virtual common point moving positions to set sub-virtual common points corresponding to the ultrasound images; and

b3) setting the plurality of scan-lines corresponding to each of the ultrasound images based on the virtual common point and the sub-virtual common points.

8. The method of claim 7, wherein the step b1) comprises:

setting a reference ultrasound image from the ultrasound images;

setting a position of the virtual common point as the virtual common point moving position corresponding to the reference ultrasound image; and

setting remaining virtual common point moving positions corresponding to remaining ultrasound images based on the virtual common point moving position corresponding to the reference ultrasound image.

9. The method of claim 8, wherein the step b3) comprises:

setting the predetermined scan-lines as the plurality of scan-lines corresponding to reference ultrasound image; and

setting the plurality of scan-lines corresponding to each of the remaining ultrasound images based on the plurality of the scan-lines corresponding to the reference ultrasound image.

10. The method of claim 7, wherein the step b) further comprises:

rotating the remaining ultrasound images toward the reference ultrasound image at predetermined rotating angles based on the sub-virtual common points corresponding to the remaining ultrasound images; and

resetting the plurality of scan-lines corresponding to the remaining ultrasound images.

* * * * *

专利名称(译)	基于超声系统中的相控阵探头提供超声空间复合图像		
公开(公告)号	US20120101378A1	公开(公告)日	2012-04-26
申请号	US13/209833	申请日	2011-08-15
[标]申请(专利权)人(译)	三星麦迪森株式会社		
申请(专利权)人(译)	三星MEDISON CO. , LTD.		
当前申请(专利权)人(译)	三星MEDISON CO. , LTD.		
[标]发明人	LEE KWANG JU		
发明人	LEE, KWANG JU		
IPC分类号	A61B8/00		
CPC分类号	A61B8/0833 A61B8/4488 G01S15/8915 G01S7/52085 G01S15/8995 A61B8/5253		
优先权	1020100102629 2010-10-20 KR		
外部链接	Espacenet USPTO		

摘要(译)

公开了用于提供超声空间复合图像的实施例。在一个实施例中，作为非限制性示例，超声系统包括：超声数据获取单元，被配置为基于具有多个元件的相控阵探头来获取超声数据；处理单元，用于与超声数据获取单元通信的处理单元，用于设置与预定扫描线对应的虚拟公共点，沿元素的纵向移动虚拟公共点，以连接多个扫描线，基于超声数据形成多个超声图像，并对超声图像执行空间复合以形成超声空间复合图像，其中，超声数据获取单元被配置为基于多个扫描线获取超声数据对应于每个超声图像。

