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(54) **ULTRASONIC INTRACAVITY PROBE FOR 3D IMAGING**

ULTRASCHALL-SONDE FÜR DIE 3D-DARSTELLUNG IN KÖRPERHÖHLEN

SONDE ECHOGRAPHIQUE ENDOCAVITAIRE POUR IMAGERIE 3D

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Description

[0001] This invention relates to medical diagnostic imaging systems and, in particular, to intracavity probes for three dimensional imaging for ultrasonic diagnostic imaging systems.

[0002] Intracavity ultrasound probes have been in use for many years for imaging the body from within the body. By imaging from within the body internal organs can be imaged more directly without the need to transmit ultrasound waves through intervening tissue and body structure. For example, transesophageal probes can image the heart and abdominal organs from the esophagus or stomach and avoid the need to send and receive ultrasound through or around the ribs. The present invention relates to intracavity probes inserted in the vagina (IVT probes) or rectum (ICT probes) to image the cervix, uterus, or prostate.

[0003] In the past, IVT and ICT probes have scanned a two dimensional image region from within the body. This could be done with an array transducer or oscillating single crystal transducer which would scan a sector-shaped area of the body. By curving the elements of an array transducer completely around the distal tip region of the probe, sectors approximating 180° could be scanned. A typical IVT intracavity probe 10 is shown in FIGURE 1. This probe includes a shaft portion 12 of about 16,7 cm (6.6 inches) in length and 2,54 cm (one inch) in diameter which is inserted into a body cavity. The ultrasound transducer is located in the distal tip 14 of the shaft. The probe is grasped and manipulated by a handle 16 during use. At the end of the handle is a strain relief 18 for a cable 20 which extend about 91,4 cm - 213,4 cm (3-7 feet) and terminates at a connector 22 which couples the probe to an ultrasound system. A typical IVT probe may have a shaft and handle which is 30,5 cm (12 inches) in length and weigh about 1361 grams (48 ounces) including the cable 20 and the connector 22.

[0004] In recent years ultrasound systems have been introduced with three dimensional (3D) imaging capability and intracavity probes have been designed to perform 3D imaging. Generally this is done by replacing the array transducer which is statically affixed in the distal tip with an array transducer which can be oscillated rapidly in the elevation direction. This oscillation will sweep the image plane being scanned through a volumetric region, acquiring multiple adjacent planar images which can be rendered into a three dimensional image. However, as was the case with earlier oscillating single crystal or annular array transducers, the oscillating array transducer of the 3D probe must be contained within a fluid through which it can oscillate and which is highly transmissive of ultrasound. Generally this fluid will be a water or oil-based solution such as a mineral oil. The fluid is preferably biocompatible so as not to injure or irritate the tissues of the patient in the event of leakage.

[0005] These mechanically oscillating 3D array probes will generally house the motor for the oscillation drive

within the handle of the probe, thereby keeping it outside the body of the patient. This motor location then mandates a fluid compartment for the oscillating mechanism and transducer which extends through most of or all of the shaft and distal tip of the probe. The fluid will comprise a large portion of the weight of the probe which is located in the shaft of the probe, causing the center of gravity of the probe to be forward of the handle and in the shaft of the probe. This imbalance makes the intracavity probe unwieldy and difficult to manipulate easily.

[0006] US 5,762,066 describes an intracavity probe with a rotatable transducer member in the distal end of a housing. A window is closed with a membrane. A fluid reservoir extending from the distal end throughout the handle is enclosed in the probe housing, provided with a pressurizing piston at the proximal end of the handle system to adjust pressure of the coupling fluid in the reservoir against the membrane.

[0007] It would be desirable to reduce the forward weight and balance of the probe so that the 3D intracavity probe is easier to manipulate during a diagnostic procedure.

[0008] The invention is defined by claim 1.

[0009] In accordance with the principles of the present invention a 3D intracavity probe includes an array transducer in the distal tip which is swept to scan a volumetric region. The array transducer is swept by motor which is located in the handle of the probe. The array transducer is contained within a fluid chamber located at the distal tip of the probe and requiring less than 10 cm³ (cc) of fluid. As a result, the center of gravity of the shaft and handle is located in the handle and not the shaft, making the probe easier and more comfortable to hold and manipulate during use.

[0010] In accordance with further aspects of the present invention, the array transducer is mounted on an array mount made of a low mass material and displacing space within the chamber which otherwise would be filled with fluid, thereby reducing the fluid volume of the chamber. The shaft and shaft components, except for critical wear surfaces of the array drive mechanism, are also made of low mass materials such as plastics and aluminum. Accordingly, the weight of the probe is less than two-thirds of the weight of prior art 3D intracavity probes.

[0011] In the drawings:

FIGURE 1 illustrates a typical intracavity ultrasound probe of the prior art.

FIGURE 2 illustrates a side view of an intracavity probe for three dimensional imaging of the present invention.

FIGURE 3 is a side cross-sectional view of a 3D intracavity probe of the present invention.

FIGURE 4 is a perspective view of the tip assembly of a 3D intracavity probe of the present invention.

[0012] Referring now to FIGURE 2, an intracavity ultrasound probe 30 of the present invention is shown. The

probe 30 includes a handle section 36 by which the user holds the handle for manipulation during use. At the rear of the handle is a strain relief 18 for the probe cable (not shown). Extending from the forward end of the handle 36 is the shaft 32 of the probe which terminates in a dome-shaped acoustic window 34 at the distal end through which ultrasound is transmitted and received during imaging. Contained within the distal end of the shaft is a transducer mount assembly 40 which is also shown in the cross-sectional view of the shaft of FIGURE 3 and in the uncovered view of FIGURE 4. A convex curved array transducer 46 is attached to a transducer cradle 48 at the distal end of the assembly 40. The transducer cradle 48 is pivotally mounted by its pivot axis 49 to be rocked back and forth in the distal end of the probe and thereby sweep an image plane through a volumetric region in front of the probe. The transducer cradle 48 is rocked by an oscillating drive shaft 50 which extends from a motor and position sensor 60 in the handle 36 to the transducer mount assembly 40. The drive shaft 50 extends through an isolation tube 52 in the shaft which serves to isolate the moving drive shaft from the electrical conductors and volume compensation balloon 44 located in the shaft proximal the transducer mount assembly 40. The drive shaft 50 rocks the cradle by means of two mating bevel gears 54, one at the end of the drive shaft 50 and another on the transducer cradle 48. The motor alternately drives the drive shaft 50 in one direction of rotation and then the other, which alternately rocks the transducer cradle 48 in one direction and then the other, which sweeps the image plane of the transducer array 46 back and forth through the volumetric region in front of the distal end of the probe. The echo signals acquired by the transducer array 46 are beamformed, detected, and rendered by the ultrasound system to form a three dimensional image of the volumetric region scanned by the probe.

[0013] Because ultrasonic energy does not efficiently pass through air, the array transducer 46 is surrounded by a liquid which is transmissive of ultrasound and closely matches the acoustic impedance of the body which is approximately that of water. Water-based, oil-based, and synthetic polymeric liquids may be used. In a constructed embodiment silicone oil is used. In accordance with the principles of the present invention, only a small amount of liquid is required in the shaft 32 because the weight of the liquid can contribute significantly to the overall weight of the shaft. In some prior art probes the entire shaft is filled with liquid, adding substantial weight to the shaft and causing the center of gravity of the handle and shaft to be located in the shaft. Other prior art probes have used sizeable elastomeric bags of liquid for the liquid bath of the transducer array. These embodiments also locate the center of gravity of the probe in the shaft, which makes the probe ungainly and difficult to maneuver easily. The liquid used in such embodiments can approach 50 cm³ (cc), for instance, adding its weight to the probe shaft at the distal end.

[0014] In accordance with the principles of the present

invention the majority of the liquid bath for the transducer array is contained within the transducer mount assembly 40. The only liquid located to the rear of the back surface 42 of the transducer mount assembly 40 (see FIGURE 2) is the small amount of the volume compensation balloon 44. In a constructed embodiment the total amount of liquid in the shaft of the probe is 6.3 cm³ (cc), of which 95% is contained within the transducer mount assembly 40. Only 0.3 cm³ (cc) of liquid is contained within the volume compensation balloon 44, which can be kept to a small volume of liquid due to the low overall volume of liquid. In the constructed embodiment the length of the shaft 32 was 19,1 cm (7.5 inches) from the handle to the distal tip (dimension A in FIGURE 2). The transducer mount assembly 40 is contained within the distal 3,8 cm (1.5 inches) of that length (dimension B in FIGURE 2). Thus, there is only 6 cm³ (cc) of liquid in the forward half of the probe shaft 32, and only 6.3 cm³ (cc) of liquid in the entire shaft. Ninety-five percent of the liquid is in close proximity to the transducer array, located as it is in the distal 20% of the probe shaft. With so little liquid in the shaft and so little liquid in the forward half of the probe shaft, and the motor located in the handle, the center of gravity 62 of the probe handle and shaft is located in the handle, 2,54 cm (a full inch) behind the handle/shaft interface (dimension C in FIGURE 2). With the center of gravity located in the handle the probe is much easier and more comfortable to manipulate during use.

[0015] In addition to the small amount of fluid needed in the forward section of the shaft, the embodiment of FIGURES 3 and 4 employ additional measures to reduce the amount of liquid and the weight of the probe shaft 32. Only critical wear surfaces within the shaft 32, such as the drive shaft 50, the gears 54, and pivot points for the transducer cradle are made of stainless steel. Selected fasteners and fittings are also made of stainless steel. Other components within the shaft are made of lighter materials with a density lighter than that of stainless steel. The transducer cradle 48 is made of three pieces of aluminum and is tapered on the sides which are the leading edges as the cradle travels through the liquid. The tapering on either side causes the cradle to move more easily through the liquid with less resistance. The space behind the transducer array and backing is not hollow but is filled so as to displace volume that would otherwise be occupied by liquid, further reducing the liquid needed in the distal end of the probe. The main body of the transducer mount assembly 40 is also made of aluminum, as is the isolation tube 52. The volume compensation balloon 44 is made of a thin plastic. The transducer array and its backing are made of material customarily used for those purposes such as piezoelectric ceramic and epoxy. This use of lightweight materials enables a constructed embodiment of the present invention including the probe shaft and handle to weigh only 250 grams, compared to the 400 gram weights of prior art probes.

Claims

1. An ultrasonic intracavity probe (30) for scanning a volumetric region from within the body comprising:
 - a handle section (36) to be held during use of the probe (30); and
 - a shaft section (32) having a distal end which is to be inserted into a body cavity during use of the probe (30);
 - a pivotally mounted array transducer (46) located in the distal end of the shaft section (32);
 - a motor (60) located in the handle section (36);
 - a drive mechanism coupled to the motor (60) and the array transducer (46) which acts to move the array transducer (46) during scanning; and
 - a liquid bath located in the distal end of the shaft section (32), a portion of which is located between the array transducer (46) and the distal end of the shaft section (32) during scanning, wherein the center of gravity of the probe (30) is located in the handle section (36); wherein a transducer mount assembly (40) is located in the distal end of the shaft section (38), the array transducer (46) being pivotally mounted to the transducer mount assembly (40);
 - wherein the liquid bath is located within the transducer mount assembly (40);
 - wherein the majority of the liquid bath is contained within the transducer mount assembly (40).
2. The ultrasonic intracavity probe of Claim 1, wherein the transducer mount assembly (40) has a proximal termination within 7,62 cm (3 inches) of the distal end of the shaft section (32), wherein 75% of the liquid bath is contained within the transducer mount assembly (40).
3. The ultrasonic intracavity probe of Claim 2, wherein the transducer mount assembly (40) has a proximal termination within 3,8 cm (1.5 inches) of the distal end of the shaft section (32).
4. The ultrasonic intracavity probe of Claim 3, wherein 90% of the liquid bath is contained within the transducer mount assembly (40).
5. The ultrasonic intracavity probe of Claim 1, wherein the liquid bath has a volume of less than 25 cm³ (cc) of liquid.
6. The ultrasonic intracavity probe of Claim 5, wherein the liquid bath has a volume of less than 10 cm³ (cc) of liquid.
7. The ultrasonic intracavity probe of Claim 6, wherein the liquid bath has a volume of approximately 6 cm³ (cc) of liquid.
8. The ultrasonic intracavity probe of Claim 1, wherein 90% of the liquid bath is located in the most distal 25% of the length of the shaft section (32).
9. The ultrasonic intracavity probe of Claim 8, wherein the liquid bath has a volume of less than 10 cm³ (cc) of liquid.
10. The ultrasonic intracavity probe of Claim 1, wherein the transducer mount assembly (40) has a main body formed of a material which is lighter than stainless steel.
11. The ultrasonic intracavity probe of Claim 10, wherein the array transducer (46) is pivotally mounted to the transducer mount assembly (40) by a transducer cradle (48), wherein the transducer cradle (48) is made of a material which is lighter than stainless steel.
12. The ultrasonic intracavity probe of Claim 11, wherein the transducer cradle (48) includes a solid body located behind the array transducer (46) which displaces volume in the transducer mount assembly (40) that would otherwise be occupied by liquid.
13. The ultrasonic intracavity probe of Claim 11, wherein the transducer cradle (48) is tapered so as to pass more easily through the liquid bath.
14. The ultrasonic intracavity probe of Claim 10, wherein the transducer mount assembly (40) includes wear surfaces made of stainless steel.
15. The ultrasonic intracavity probe of Claim 14, wherein the wear surfaces are part of the drive mechanism.
16. The ultrasonic intracavity probe of Claim 10, wherein the weight of the probe (30) is less than 400 grams.
17. The ultrasonic intracavity probe of Claim 16, wherein the weight of the probe (30) is less than 300 grams.
18. The ultrasonic intracavity probe of Claim 17, wherein the weight of the probe (30) is approximately 250 grams.
19. The ultrasonic intracavity probe of Claim 17, wherein the only components of the shaft section (32) which are made of a material at least equal to the density of stainless steel are components of the drive mechanism.

Patentansprüche

1. Ultraschallsonde (30) für den intrakavitären Einsatz zum Abtasten einer volumetrischen Region innerhalb des Körpers, die Folgendes umfasst:
 - einen Griffabschnitt (36) zum Halten während des Einsatzes der Sonde (30);
 - einen Schaftabschnitt (32) mit einem distalen Ende, das während des Einsatzes der Sonde (30) in eine Körperhöhle einzuführen ist;
 - einen schwenkbar montierten Array-Wandler (46), der sich im distalen Ende des Schaftabschnitts (32) befindet;
 - einen Motor (60), der sich im Griffabschnitt (36) befindet;
 - einen Antriebsmechanismus, der mit dem Motor (60) und dem Array-Wandler (46) gekoppelt ist und so funktioniert, dass er den Array-Wandler (46) während der Abtastung bewegt; und
 - ein Flüssigkeitsbad, das sich im distalen Ende des Schaftabschnitts (32) befindet und von dem sich während der Abtastung ein Teil zwischen dem Array-Wandler (46) und dem distalen Ende des Schaftabschnitts (32) befindet, wobei sich der Schwerpunkt der Sonde (30) in dem Griffabschnitt (36) befindet, wobei sich eine Wandlerträgereinheit (40) in dem distalen Ende des Schaftabschnitts (32) befindet, wobei der Array-Wandler (46) schwenkbar an die Wandlerträgereinheit (40) montiert ist;
 - wobei sich das Flüssigkeitsbad innerhalb der Wandlerträgereinheit (40) befindet;
 - wobei der größte Teil des Flüssigkeitsbades in der Wandlerträgereinheit (40) enthalten ist.
 2. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 1, wobei die Wandlerträgereinheit (40) einen proximalen Abschluss in einer Entfernung von höchstens 7,62 cm (3 Zoll) vom distalen Ende des Schaftabschnitts (32) aufweist, wobei 75% des Flüssigkeitsbades in der Wandlerträgereinheit (40) enthalten sind.
 3. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 2, wobei die Wandlerträgereinheit (40) einen proximalen Abschluss in einer Entfernung von höchstens 3,8 cm (1,5 Zoll) vom distalen Ende des Schaftabschnitts (32) aufweist.
 4. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 3, wobei 90% des Flüssigkeitsbades in der Wandlerträgereinheit (40) enthalten sind.
 5. Ultraschallsonde für den intrakavitären Einsatz nach
- Anspruch 1, wobei das Flüssigkeitsbad ein Volumen von weniger als 25 cm³ Flüssigkeit hat.
 6. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 5, wobei das Flüssigkeitsbad ein Volumen von weniger als 10 cm³ Flüssigkeit hat.
 7. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 6, wobei das Flüssigkeitsbad ein Volumen von ungefähr 6 cm³ Flüssigkeit hat.
 8. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 1, wobei sich 90% des Flüssigkeitsbades in den distalen 25% der Länge des Schaftabschnitts (32) befinden.
 9. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 8, wobei das Flüssigkeitsbad ein Volumen von weniger als 10 cm³ Flüssigkeit hat.
 10. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 1, wobei die Wandlerträgereinheit (40) einen Hauptkörper aufweist, der aus einem Material besteht, das leichter als Edelstahl ist.
 11. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 10, wobei der Array-Wandler (46) durch eine Wandlerwippe (48) schwenkbar an die Wandlerträgereinheit (40) montiert ist, wobei die Wandlerwippe (48) aus einem Material besteht, das leichter als Edelstahl ist.
 12. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 11, wobei die Wandlerwippe (48) einen Festkörper umfasst, der sich hinter dem Array-Wandler (46) befindet und Volumen in der Wandlerträgereinheit (40) verdrängt, das sonst von der Flüssigkeit eingenommen würde.
 13. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 11, wobei die Wandlerwippe (48) angeschrägt ist, damit sie leichter durch das Flüssigkeitsbad gleitet.
 14. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 10, wobei die Wandlerträgereinheit (40) Verschleißflächen aus Edelstahl umfasst.
 15. Ultraschallsonde für den intrakavitären Einsatz nach

Anspruch 14,
wobei die Verschleiß flächen Teil des Antriebsmechanismus sind.

16. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 10, wobei das Gewicht der Sonde (30) weniger als 400 g beträgt. 5
17. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 16, wobei das Gewicht der Sonde (30) weniger als 300 g beträgt. 10
18. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 17, wobei das Gewicht der Sonde (30) ungefähr 250 g beträgt. 15
19. Ultraschallsonde für den intrakavitären Einsatz nach Anspruch 17, wobei die einzigen Komponenten des Schaftabschnitts (32), die aus einem Material bestehen, dessen Dichte mindestens gleich der Dichte von Edelstahl ist, Komponenten des Antriebsmechanismus sind. 20 25

Revendications

1. Sonde intracavité ultrasonique (30) pour balayer une région volumétrique à l'intérieur du corps, comprenant :
- une section de manche (36) à tenir au cours de l'utilisation de la sonde (30) ;
- une section d'arbre (32) ayant une extrémité distale qui doit être insérée dans une cavité de corps au cours de l'utilisation de la sonde (30) ;
- un transducteur de réseau monté de manière à pouvoir pivoter (46) situé à l'extrémité distale de la section d'arbre (32) ;
- un moteur (60) situé dans la section de manche (36) ;
- un mécanisme d'entraînement couplé au moteur (60) et au transducteur de réseau (46) qui sert à déplacer le transducteur de réseau (46) au cours du balayage ; et
- un bain de liquide situé à l'extrémité distale de la section d'arbre (32), dont une portion est située entre le transducteur de réseau (46) et l'extrémité distale de la section d'arbre (32) au cours du balayage, dans laquelle le centre de gravité de la sonde (30) est situé dans la section de manche (36) ; dans laquelle un ensemble de montage de transducteur (40) est situé à l'extrémité distale de la section d'arbre (32), le transducteur de réseau (46) étant monté de manière
- 30 35 40 45 50 55

à pouvoir pivoter sur l'ensemble de montage de transducteur (40) ;

dans laquelle le bain de liquide est situé à l'intérieur de l'ensemble de montage de transducteur (40) ;

dans laquelle la majorité du bain de liquide est contenue à l'intérieur de l'ensemble de montage de transducteur (40).

2. Sonde intracavité ultrasonique selon la revendication 1, dans laquelle l'ensemble de montage de transducteur (40) a une terminaison proximale à 7,62 cm (3 pouces) au maximum de l'extrémité distale de la section d'arbre (32), dans laquelle 75 % du bain de liquide est contenu à l'intérieur de l'ensemble de montage de transducteur (40).
3. Sonde intracavité ultrasonique selon la revendication 2, dans laquelle l'ensemble de montage de transducteur (40) a une terminaison proximale à 3,8 cm (1,5 pouce) au maximum de l'extrémité distale de la section d'arbre (32).
4. Sonde intracavité ultrasonique selon la revendication 3, dans laquelle 90 % du bain de liquide est contenu à l'intérieur de l'ensemble de montage de transducteur (40).
5. Sonde intracavité ultrasonique selon la revendication 1, dans laquelle le bain de liquide a un volume inférieur à 25 cm³ de liquide.
6. Sonde intracavité ultrasonique selon la revendication 5, dans laquelle le bain de liquide a un volume inférieur à 10 cm³ de liquide.
7. Sonde intracavité ultrasonique selon la revendication 6, dans laquelle le bain de liquide a un volume d'approximativement 6 cm³ de liquide.
8. Sonde intracavité ultrasonique selon la revendication 6, dans laquelle 90 % du bain de liquide se trouve dans les 25 % les plus distaux de la longueur de la section d'arbre (32).
9. Sonde intracavité ultrasonique selon la revendication 8, dans laquelle le bain de liquide a un volume inférieur à 10 cm³ de liquide.

10. Sonde intracavité ultrasonique selon la revendication 1,
dans laquelle l'ensemble de montage de transducteur (40) a un corps principal constitué d'un matériau plus léger que l'acier inoxydable. 5
11. Sonde intracavité ultrasonique selon la revendication 10,
dans laquelle le transducteur de réseau (46) est monté de manière à pouvoir pivoter sur l'ensemble de montage de transducteur (40) par un arceau de transducteur (48), 10
dans lequel l'arceau de transducteur (48) est constitué d'un matériau plus léger que l'acier inoxydable. 15
12. Sonde intracavité ultrasonique selon la revendication 11,
dans laquelle l'arceau de transducteur (48) comprend un corps plein situé derrière le transducteur de réseau (46) qui déplace un volume dans l'ensemble de montage de transducteur (40) qui serait autrement occupé par du liquide. 20
13. Sonde intracavité ultrasonique selon la revendication 11, 25
dans laquelle l'arceau de transducteur (48) est effilé pour passer plus facilement à travers le bain de liquide.
14. Sonde intracavité ultrasonique selon la revendication 10, 30
dans laquelle l'ensemble de montage de transducteur (40) comprend des surfaces d'usure constituées d'acier inoxydable. 35
15. Sonde intracavité ultrasonique selon la revendication 14,
dans laquelle les surfaces d'usure font partie du mécanisme d'entraînement. 40
16. Sonde intracavité ultrasonique selon la revendication 10,
dans laquelle le poids de la sonde (30) est inférieur à 400 g. 45
17. Sonde intracavité ultrasonique selon la revendication 16,
dans laquelle le poids de la sonde (30) est inférieur à 300 g. 50
18. Sonde intracavité ultrasonique selon la revendication 17,
dans laquelle le poids de la sonde (30) est d'environ 250 g. 55
19. Sonde intracavité ultrasonique selon la revendication 17,
dans laquelle les seuls composants de la section

d'arbre (32) qui sont constitués d'un matériau de densité au moins égale à la densité de l'acier inoxydable sont des composants du mécanisme d'entraînement.

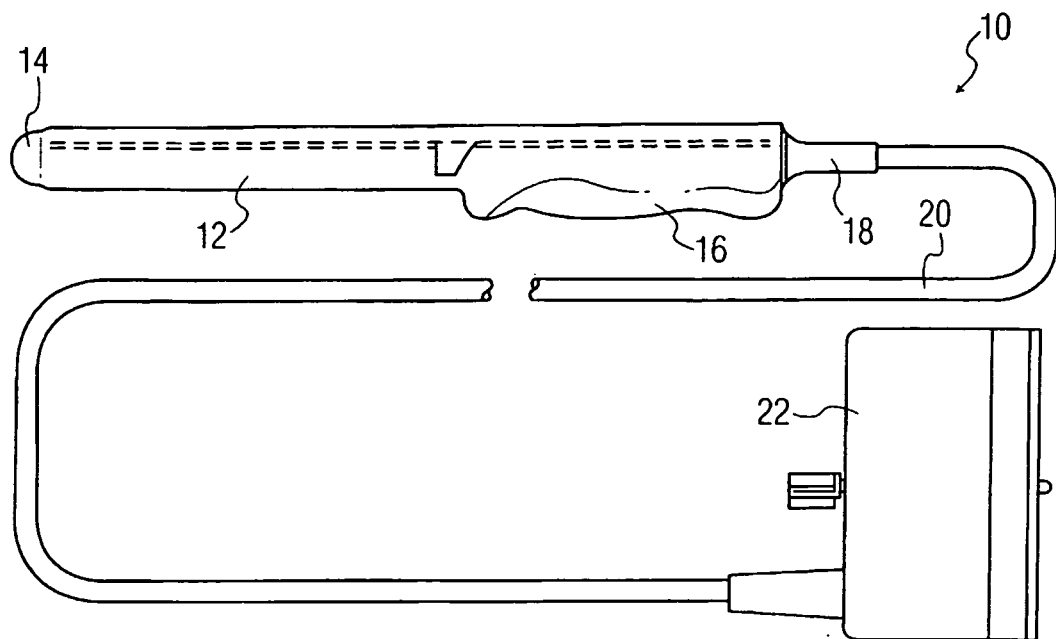


FIG. 1

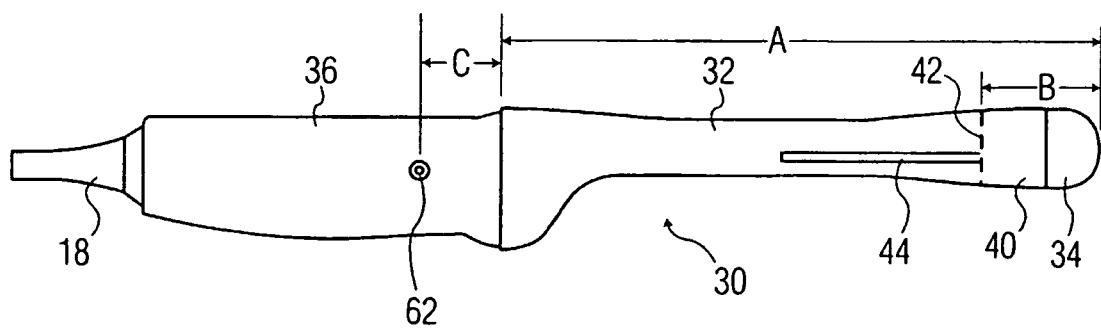


FIG. 2

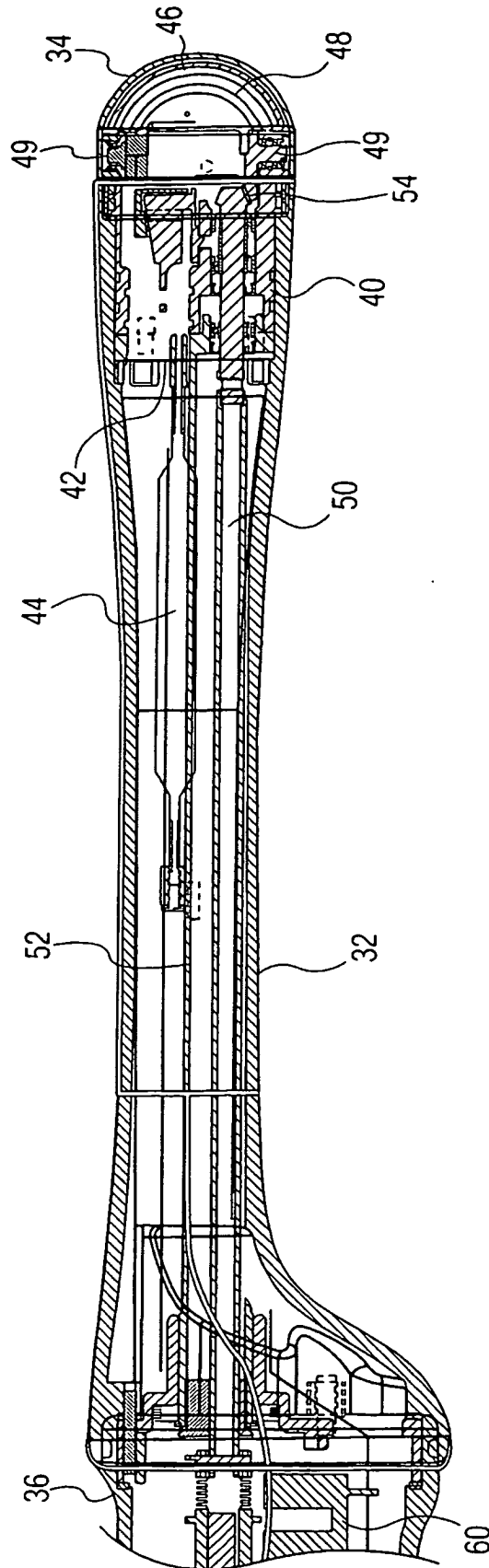


FIG. 3

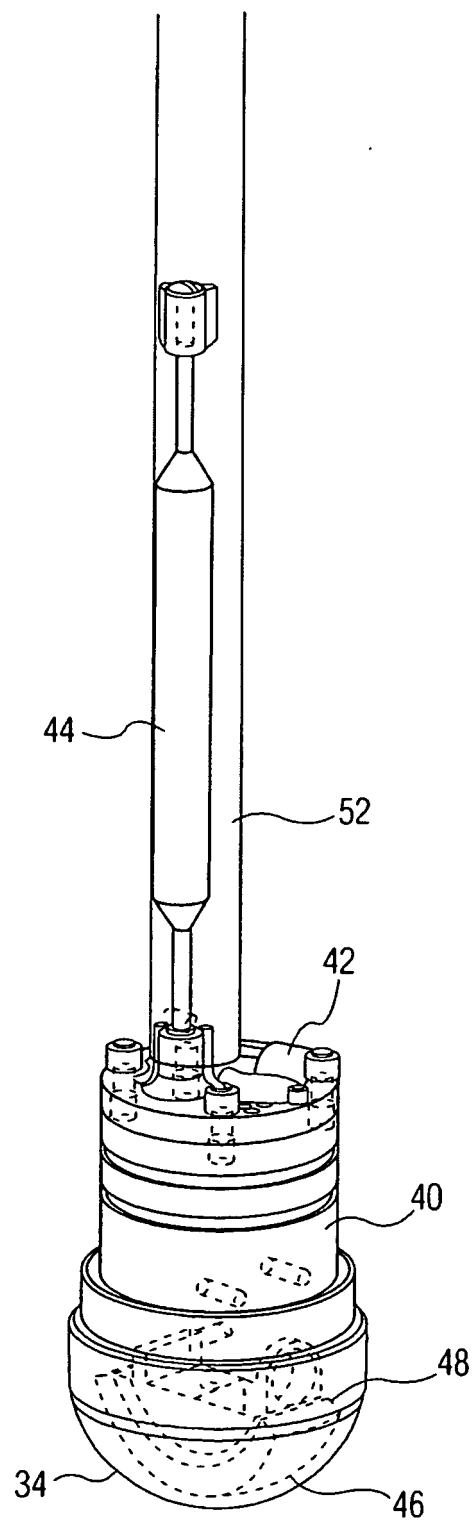


FIG. 4

REFERENCES CITED IN THE DESCRIPTION

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- US 5762066 A [0006]

专利名称(译)	超声腔内探头用于三维成像		
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摘要(译)

腔内超声探头包括枢转安装的阵列换能器，其被振荡以从身体内扫描体积区域。换能器由位于探头手柄中的电机振荡。阵列换能器浸没在液体中，该液体在换能器的元件和主体之间声学地耦合超声能量。声耦合液体位于探针轴的远端尖端，其中仅需要6cc的液体。少量液体减少了探头轴的重量，使得探头的重心位于手柄中，使探头舒适且易于操作。探头轴中的大部分部件由铝或其他低密度材料制成，使探头的总重量保持在约250克。

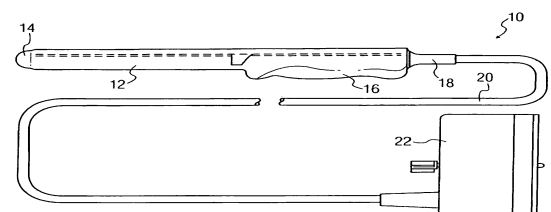


FIG. 1

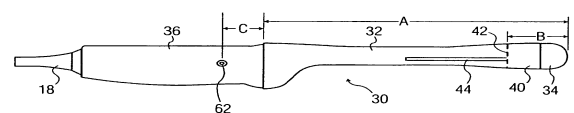


FIG. 2