



(11) **EP 3 143 938 B1**

(12) **EUROPEAN PATENT SPECIFICATION**

(45) Date of publication and mention of the grant of the patent:  
**04.09.2019 Bulletin 2019/36**

(51) Int Cl.:  
**A61B 8/00** <sup>(2006.01)</sup> **H04W 84/12** <sup>(2009.01)</sup>

(21) Application number: **16196182.6**

(22) Date of filing: **25.07.2012**

(54) **WIRELESS COMMUNICATION METHOD OF PROBE FOR ULTRASOUND DIAGNOSIS AND APPARATUS THEREFOR**

**DRAHTLOSKOMMUNIKATIONSVERFAHREN EINER SONDE ZUR ULTRASCHALLDIAGNOSE UND VORRICHTUNG DAFÜR**

**PROCÉDÉ DE COMMUNICATION SANS FIL DE SONDE DE DIAGNOSTIC ULTRASON ET APPAREIL CORRESPONDANT**

(84) Designated Contracting States:  
**AL AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HR HU IE IS IT LI LT LU LV MC MK MT NL NO PL PT RO RS SE SI SK SM TR**

(30) Priority: **25.07.2011 KR 20110073773**

(43) Date of publication of application:  
**22.03.2017 Bulletin 2017/12**

(62) Document number(s) of the earlier application(s) in accordance with Art. 76 EPC:  
**12817598.1 / 2 736 417**

(73) Proprietor: **Samsung Electronics Co., Ltd.**  
**Gyeonggi-do 16677 (KR)**

(72) Inventors:  
• **KIM, Kang-sik**  
**Gyeonggi-do (KR)**

- **KIM, Jung-jun**  
**Seoul (KR)**
- **HAN, Ho-san**  
**Seoul (KR)**
- **HONG, Soon-jae**  
**Gyeonggi-do (KR)**

(74) Representative: **Grootscholten, Johannes A.M. et al**  
**Arnold & Siedsma**  
**Bezuidenhoutseweg 57**  
**2594 AC The Hague (NL)**

(56) References cited:  
**WO-A2-2008/115312 US-A1- 2010 191 121**  
**US-A1- 2010 286 527 US-A1- 2011 105 904**

**EP 3 143 938 B1**

Note: Within nine months of the publication of the mention of the grant of the European patent in the European Patent Bulletin, any person may give notice to the European Patent Office of opposition to that patent, in accordance with the Implementing Regulations. Notice of opposition shall not be deemed to have been filed until the opposition fee has been paid. (Art. 99(1) European Patent Convention).

## Description

**[0001]** The present invention relates to a method in which a probe apparatus for ultrasound diagnosis transmits an echo signal to an ultrasonic imaging apparatus, and an apparatus for performing the method.

**[0002]** Ultrasound diagnostic imaging systems transmit ultrasonic signals from the surface of a human body toward a predetermined region inside the human body and acquire tomographic images of soft-tissue or blood flow by using information obtained from an ultrasonic signal reflected by liquids or tissue inside the human body. Advantages of an ultrasound system are its relatively small size, low cost, real-time display, and the fact that the subject is not exposed to ionizing radiation (e.g., X-rays). Therefore, ultrasound imaging systems are widely used along with other types of image diagnostic devices, such as an X-ray diagnostic device, a computerized tomography (CT) scanner, a magnetic resonance imaging (MRI) device, a nuclear medicine (gamma camera) diagnostic device, etc.

**[0003]** FIG. 1 illustrates a typical ultrasound diagnostic imaging system 150 as currently in use today, which diagnostic includes a probe 110 for transceiving ultrasonic signals, and an ultrasound diagnostic imaging system body 100, namely, an ultrasonic imaging apparatus 100, to which the probe 110 is connected via a cable 120.

**[0004]** In a conventional ultrasound diagnostic imaging system illustrated in Fig. 1, the cable 120 causes much inconvenience to a person using the ultrasound imaging system 150 to perform an ultrasound test, due to the length (usually 1-2m), thickness and weight of the cable 120.

**[0005]** The present invention provides a method and apparatus for wirelessly transmitting an echo signal to an ultrasonic imaging apparatus without loss.

**[0006]** The present disclosure is distinguished over the following acknowledged prior art according to US-2011/105904, US-2010/286527, WO-2008/115312 and US-2010/191121, relative to which it is novel and inventive to achieve, using the features of the appended independent claims, that pairing between an ultrasonic imaging apparatus and a probe is performed by a user simply pressing buttons included in an ultrasonic imaging apparatus and a probe. Thus the probe portion of an ultrasound imaging system may be simply and easily replaced, if necessary, while the existing ultrasonic imaging apparatus is being used.

**[0007]** According to the present invention, operator inconvenience is greatly reduced.

**[0008]** According to an aspect of the present invention, there is provided a probe apparatus for ultrasound diagnostic imaging, the probe apparatus comprising: a beacon monitoring unit which monitors for the reception of a mmWave beacon from an ultrasonic imaging apparatus of a Personal Basic Service Set (PBSS) with which the probe apparatus is not yet associated, when a user command for making a pairing request is received; a peer

determination unit which detects an ultrasonic imaging apparatus which is to be paired with the probe apparatus by using first pairing information included in a received mmWave beacon; an association performing unit which performs a procedure for associating the probe apparatus with a PBSS of the ultrasonic imaging apparatus by using a basic service set ID (BSSID) included in the received mmWave beacon; and a pairing request unit which transmits second pairing information to the ultrasonic imaging apparatus via the PBSS, wherein the first pairing information represents that the ultrasonic imaging apparatus has been requested by a user to perform pairing, and the second pairing information represents that the probe apparatus has been requested by the user to perform pairing. Associated with this probe, a corresponding communication method and ultrasound diagnostic system are provided.

**[0009]** Herein below, the invention will be elucidated by reference to embodiments in the appended drawings.

FIG. 1 illustrates a prior art ultrasound diagnostic imaging system;

FIG. 2 illustrates an ultrasound diagnostic imaging system according to an embodiment of the present invention;

FIG. 3 is a flowchart illustrating a communication process of a probe, according to an embodiment of the present invention;

FIG. 4 is a flowchart illustrating a process in which the probe performs pairing with an ultrasonic imaging apparatus, according to an embodiment of the present invention;

FIG. 5 is a flowchart illustrating a pairing process according to an embodiment of the present invention;

FIG. 6 is a flowchart illustrating a pairing process according to another embodiment of the present invention;

FIG. 7 is a flowchart illustrating a pairing process according to another embodiment of the present invention;

FIG. 8 is a flowchart illustrating a pairing process according to another embodiment of the present invention;

FIG. 9 is a flowchart illustrating a pairing process according to another embodiment of the present invention;

FIG. 10 is a flowchart illustrating a process of controlling a link margin, according to an embodiment of the present invention;

FIG. 11 illustrates a format illustrating a link margin response frame according to an embodiment of the present invention; and

FIG. 12 is a block diagram illustrating a structure of a probe apparatus according to an embodiment of the present invention.

**[0010]** The following description, with reference to the

accompanying drawings, is provided to assist a person of ordinary skill in the art with a comprehensive understanding of exemplary embodiments of the invention. The description includes various specific details to assist in that understanding but these details are to be regarded as merely exemplary. Accordingly, those of ordinary skill in the art will recognize that various changes and modifications of the exemplary embodiments described herein can be made without departing from the scope of the appended claims. Also, descriptions of well-known functions and constructions may be omitted for clarity and simplicity so as not to obscure appreciation of the present invention by a person of ordinary skill with such well-known functions and constructions.

**[0011]** The terms and words used in the following description and claims are not limited to the bibliographical meanings, but, are merely used by the inventor to enable a clear and consistent understanding of the invention. Accordingly, it should be apparent to those skilled in the art that the following description of exemplary embodiments of the present invention are provided for illustration purposes only and not for the purpose of limiting the invention as defined by the appended claims.

**[0012]** Expressions such as "at least one of", when preceding a list of elements, refers to at least one of the entire list of elements and is not intended to be limited individual elements of the list.

**[0013]** It is to be understood that the singular forms "a", "an", and "the" include plural references unless the context clearly dictates otherwise. Thus, for example, reference to "a component surface" typically includes reference to one or more of such surfaces.

**[0014]** Finally, the term "substantially" typically means that the recited characteristic, parameter, or value need not be achieved exactly, but that deviations or variations, including for example, tolerances, measurement error, measurement accuracy limitations and other factors known to those skilled in the art, may occur in amounts that do not preclude the effect the characteristic was intended to provide.

**[0015]** FIG. 2 illustrates an ultrasound diagnostic imaging system 200 according to an embodiment of the present invention, which diagnostic includes an ultrasonic imaging apparatus 210 and a probe 220 including an ultrasonic wave transducer.

**[0016]** The probe 220 and the ultrasonic imaging apparatus 210 are associated with a same mmWave (millimeter Wave) -based wireless network, and the probe 220 transmits an echo signal received via the transducer portion of the probe, to the ultrasonic imaging apparatus 210 using one or more signal channels in the 60 GHz frequency band. The ultrasonic imaging apparatus 210 generates ultrasonic images in various modes, such as B-mode, color flow, and Doppler, by using the ultrasound echo signal transmitted thereto using the 60 GHz frequency band signal channel, and displays the ultrasonic images.

**[0017]** The probe 220 generates an ultrasonic signal

by applying one or more pulses to an ultrasonic oscillator of a transducer. Once generated, the ultrasonic signal is reflected by a target (such as structures in a human body) and is received as an echo signal by the transducer. The transducer converts the echo signal into an electrical signal, and then requires a high bandwidth communication channel on the order of multiple gigabytes, to wirelessly transmit the electrical signal, and also so as to not interfere with other wireless electronic apparatuses during wireless transmission of the echo signal.

**[0018]** To this end, according to embodiments of the present invention, an echo signal is wirelessly transmitted via a wireless network that uses millimeter waves. For example, a wireless communication technique based on the WiGig standard of the Wireless Gigabit Alliance (WGA) may be used.

**[0019]** The WiGig standard is sufficient to transmit an echo signal that has been converted into digital data because the WiGig standard supports data transmission rates up to 7 Gbps, and may steer a signal direction by using the directionality of beams to minimize interference with other systems. The WiGig standard as a local-distance wireless communication standard is also generally suitable for ultrasonic test environments where a probe and an ultrasonic imaging apparatus are close to each other, and using the WiGig standard consumes less power than other wireless communication standards and thus may minimize the weight and size of battery which is to be built into the probe. The dashed line circle in FIG 2 enclosing probe 220 and the ultrasonic imaging apparatus 210 denotes a wireless communication network with which the probe and imaging apparatus communicate with each other, and may be a personal basic service set (PBSS) of the WiGig standard, as explained in more detail below.

**[0020]** \*43FIG. 3 is a flowchart of a communication process performed by a probe, according to an embodiment of the present invention.

**[0021]** In operation 301, the probe performs a procedure in order to become associated with a PBSS mmWave-based wireless network. In the PBSS, at least one station needs to operate as a PBSS control point (PCP) that manages the PBSS. However, the probe is limited in its size and weight, and thus it may be preferred that the ultrasonic imaging apparatus 210 may operate as the PCP. Alternatively, both the ultrasonic imaging apparatus and the probe may operate as a station, and another device may operate as the PCP in the PBSS.

**[0022]** In operation 302, the probe generates a data frame with a format suitable for the mmWave-based wireless network, by using an echo signal received via the transducer.

**[0023]** In operation 303, the probe transmits the data frame to the ultrasonic imaging apparatus using a signal in a 60 GHz frequency band. The ultrasonic imaging apparatus (such as 210 of FIG 2) receives the data frame, generates therefrom an ultrasonic image via signal processing, and displays the ultrasonic image.

**[0024]** FIG. 4 is a flowchart of a process in which the probe performs pairing with the ultrasonic imaging apparatus, according to an embodiment of the present invention.

**[0025]** The PBSS is an ad-hoc structure that performs direct communication between stations without passing through a PCP. Accordingly, the probe and the ultrasonic imaging apparatus need to be subjected to a process of recognizing themselves as peer devices and setting a communication protocol to perform mutual communication. This process is referred to as pairing. A push button configuration (PBC) method may be used to perform pairing between the probe and the ultrasonic imaging apparatus. In other words, when a user pushes pairing buttons included in the probe and the ultrasonic imaging apparatus simultaneously (or within a short time interval thereafter), the probe and the ultrasonic imaging apparatus are paired.

**[0026]** In operation 401, when a user command for making a pairing request is input, that is, when a pairing button is pressed, the probe receives a mmWave beacon frame (hereinafter, referred to as a beacon frame) of the PBSS not yet associated. Before the user command for making a pairing request is input, the probe is not associated with the PBSS of the ultrasonic imaging apparatus, and thus does not parse a beacon frame broadcast from the PBSS to which the ultrasonic imaging apparatus belongs, but discards it. However, when a user presses the pairing buttons, the probe starts monitoring an externally received beacon frame.

**[0027]** In operation 402, the probe detects the ultrasonic imaging apparatus which is to be paired with the probe by using first pairing information included in the beacon frame. It is assumed that the ultrasonic imaging apparatus has already belonged to the PBSS, and the ultrasonic imaging apparatus may operate as a PCP or a general station rather than the PCP in the PBSS. When a user presses the pairing button included in the ultrasonic imaging apparatus to perform pairing, the PCP of the PBSS broadcasts the first pairing information, representing that the ultrasonic imaging apparatus has requested pairing, via a beacon frame. The first pairing information may include PBC information representing that the pairing button of the ultrasonic imaging apparatus has been pressed, and a medium access control (MAC) address of the ultrasonic imaging apparatus.

**[0028]** In operation 403, the probe is associated with the PBSS of the ultrasonic imaging apparatus by using Basic Service Set ID (BSSID) included in the beacon frame. Although the probe is associated with the PBSS after determining a peer device (operation 402) in the present embodiment, operation 403 may be performed before operation 402.

**[0029]** In operation 404, the probe transmits second pairing information to the ultrasonic imaging apparatus. The second pairing information represents that the probe has requested pairing, and may include PBC information representing that the pairing button of the probe has been

pressed, and a MAC address of the probe.

**[0030]** FIG. 5 is a flowchart of a pairing process according to another embodiment of the present invention where it is assumed that both an ultrasonic imaging apparatus 510 and a probe 520 are initially driven, that is, the ultrasonic imaging apparatus 510 did not yet generate any PBSSs and the probe 520 is not yet associated with any PBSSs.

**[0031]** In a first operation, a pairing button included in the ultrasonic imaging apparatus 510 is pressed by a user.

**[0032]** In a second operation, the ultrasonic imaging apparatus 510, in response to the user pressing the pairing button, generates a PBSS and becomes operational so as to serve as a PCP of the PBSS.

**[0033]** In a third operation, the ultrasonic imaging apparatus 510 broadcasts a beacon frame including first pairing information  $PI_1$ . The first pairing information  $PI_1$  may include PBC information representing that the pairing button included in the ultrasonic imaging apparatus 510 has been pressed, and a MAC address of the ultrasonic imaging apparatus 510.

**[0034]** At this time, even when the probe 520 is turned on and is physically located at a distance capable of receiving a beacon of the ultrasonic imaging apparatus 510, the probe 520 does not parse the beacon frame but discards it because the probe 520 is not yet associated with the PBSS of the ultrasonic imaging apparatus 510. Accordingly, the probe 520 does not react to the beacon frame received in the third operation.

**[0035]** Although the first pairing information  $PI_1$  is broadcast via the beacon frame in a beacon section in the present embodiment, the ultrasonic imaging apparatus 510 may broadcast the first pairing information  $PI_1$  in a time section other than the beacon section.

**[0036]** In a fourth operation, a pairing button included in the probe 520 is pressed by the user. Accordingly, the probe 520 starts monitoring externally received beacon frames without discarding them.

**[0037]** In a fifth operation, the ultrasonic imaging apparatus 510 re-broadcasts the beacon frame including the first pairing information  $PI_1$ .

**[0038]** In a sixth operation, the probe 520 recognizes the ultrasonic imaging apparatus 510 as a peer device.

**[0039]** In a seventh operation, the probe 520 transmits an association request frame requesting association with the PBSS to the ultrasonic imaging apparatus 510.

**[0040]** In an eighth operation, the ultrasonic imaging apparatus 510 transmits to the probe 520 an association response frame approving the association request of the probe 520.

**[0041]** In a ninth operation, the probe 520 transmits the first pairing information  $PI_1$  and second pairing information  $PI_2$  to the ultrasonic imaging apparatus 510. The second pairing information  $PI_2$  may include PBC information representing that the pairing button included in the probe 520 has been pressed, and a MAC address of the probe 520.

**[0042]** In a tenth operation, the ultrasonic imaging apparatus 510 recognizes the probe 520 as a peer device by analyzing the second pairing information  $PI_2$ .

**[0043]** FIG. 6 is a flowchart of a pairing process according to another embodiment of the present invention where, as in the embodiment of FIG. 5, it is assumed that both an ultrasonic imaging apparatus 610 and a probe 620 are initially driven.

**[0044]** In a first operation, a pairing button included in the ultrasonic imaging apparatus 610 is pressed by a user.

**[0045]** In a second operation, the ultrasonic imaging apparatus 610 generates a PBSS and serves as a PCP of the PBSS.

**[0046]** In a third operation, the ultrasonic imaging apparatus 610 broadcasts a beacon frame including first pairing information  $PI_1$ . The first pairing information  $PI_1$  may include PBC information representing that the pairing button included in the ultrasonic imaging apparatus 610 has been pressed, and a MAC address of the ultrasonic imaging apparatus 610.

**[0047]** At this time, even when the probe 620 is turned on and is physically located at a distance capable of receiving a beacon of the ultrasonic imaging apparatus 610, the probe 620 does not parse the beacon frame but discards it because the probe 620 is not yet associated with the PBSS of the ultrasonic imaging apparatus 610. Accordingly, the probe 620 does not react to the beacon frame received in the third operation.

**[0048]** In a fourth operation, a pairing button included in the probe 620 is pressed by the user. Accordingly, the probe 620 starts monitoring externally received beacon frames without discarding them.

**[0049]** In a fifth operation, the ultrasonic imaging apparatus 610 re-broadcasts the beacon frame including the first pairing information  $PI_1$ .

**[0050]** In a sixth operation, the probe 620 recognizes the ultrasonic imaging apparatus 610 as a peer device.

**[0051]** In a seventh operation, the probe 620 transmits the first pairing information  $PI_1$  and second pairing information  $PI_2$  to the ultrasonic imaging apparatus 610. The second pairing information  $PI_2$  may include PBC information representing that the pairing button included in the probe 620 has been pressed, and a MAC address of the probe 620.

**[0052]** In an eighth operation, the ultrasonic imaging apparatus 610 recognizes the probe 620 as a peer device by analyzing the second pairing information  $PI_2$ .

**[0053]** In a ninth operation, the probe 620 transmits an association request frame requesting association with the PBSS to the ultrasonic imaging apparatus 610.

**[0054]** In a tenth operation, the ultrasonic imaging apparatus 610 transmits to the probe 620 an association response frame approving the association request of the probe 620.

**[0055]** As such, in the embodiment of FIG. 6, in contrast with the embodiment of FIG. 5, the probe 620 is associated with the PBSS after transmitting the second pairing

information  $PI_2$  to the ultrasonic imaging apparatus 610.

**[0056]** FIG. 7 is a flowchart of a pairing process according to another embodiment of the present invention where it is assumed that, while an ultrasonic imaging apparatus 710 is operating as a PCP of a PBSS, a probe 720 is initially driven.

**[0057]** In a first operation, a pairing button included in the ultrasonic imaging apparatus 710 is pressed by a user.

**[0058]** In a second operation, the ultrasonic imaging apparatus 710 broadcasts a beacon frame including first pairing information  $PI_1$ . The first pairing information  $PI_1$  may include PBC information representing that the pairing button included in the ultrasonic imaging apparatus 710 has been pressed, and a MAC address of the ultrasonic imaging apparatus 710.

**[0059]** At this time, even when the probe 720 is turned on and is physically located at a distance capable of receiving a beacon frame of the ultrasonic imaging apparatus 710, the probe 720 does not parse the beacon frame but discards it because the probe 620 is not yet associated with the PBSS of the ultrasonic imaging apparatus 710. Accordingly, the probe 720 does not react to the beacon frame received in the second operation.

**[0060]** In a third operation, a pairing button included in the probe 720 is pressed by the user. Accordingly, the probe 720 starts monitoring externally received beacon frames without discarding them.

**[0061]** In a fourth operation, the ultrasonic imaging apparatus 710 re-broadcasts the beacon frame including the first pairing information  $PI_1$ .

**[0062]** In a fifth operation, the probe 720 recognizes the ultrasonic imaging apparatus 710 as a peer device.

**[0063]** In a sixth operation, the probe 520 is associated with the PBSS of the ultrasonic imaging apparatus 710.

**[0064]** In a seventh operation, the probe 520 transmits second pairing information  $PI_2$  to the ultrasonic imaging apparatus 710. The second pairing information  $PI_2$  may include PBC information representing that the pairing button included in the probe 720 has been pressed, and a MAC address of the probe 720.

**[0065]** In an eighth operation, the ultrasonic imaging apparatus 710 recognizes the probe 720 as a peer device by analyzing the second pairing information  $PI_2$ .

**[0066]** FIG. 8 is a flowchart of a pairing process according to another embodiment of the present invention where, similar to the embodiment of FIG. 7, it is assumed that while an ultrasonic imaging apparatus 810 is already operating as a PCP of a PBSS, a probe 820 is initially driven.

**[0067]** In a first operation, a pairing button included in the ultrasonic imaging apparatus 810 is pressed by a user.

**[0068]** In a second operation, the ultrasonic imaging apparatus 810 broadcasts a beacon frame including first pairing information  $PI_1$ . The first pairing information  $PI_1$  may include PBC information representing that the pairing button included in the ultrasonic imaging apparatus

810 has been pressed, and a MAC address of the ultrasonic imaging apparatus 810.

**[0069]** At this time, even when the probe 820 is turned on and is physically located at a distance capable of receiving a beacon frame of the ultrasonic imaging apparatus 810, the probe 820 does not parse the beacon frame but discards it because the probe 820 is not yet associated with the PBSS of the ultrasonic imaging apparatus 810. Accordingly, the probe 820 does not react to the beacon frame received in the second operation.

**[0070]** In a third operation, a pairing button included in the probe 820 is pressed by the user. Accordingly, the probe 820 starts monitoring externally received beacon frames without discarding them.

**[0071]** In a fourth operation, the ultrasonic imaging apparatus 810 re-broadcasts the beacon frame including the first pairing information  $PI_1$ .

**[0072]** \*95 In a fifth operation, the probe 820 recognizes the ultrasonic imaging apparatus 810 as a peer device.

**[0073]** In a sixth operation, the probe 820 is associated with the PBSS of the ultrasonic imaging apparatus 810 and at the same time transmits second pairing information  $PI_2$  to the ultrasonic imaging apparatus 810. In other words, the probe 820 carries the second pairing information  $PI_2$  in an association request frame and transmits the association request frame including the second pairing information  $PI_2$  to the ultrasonic imaging apparatus 810.

**[0074]** In a seventh operation, the ultrasonic imaging apparatus 810 recognizes the probe 820 as a peer device by analyzing the second pairing information  $PI_2$ .

**[0075]** FIG. 9 is a flowchart of a pairing process according to another embodiment of the present invention. In the embodiment of FIG. 9, it is assumed that an ultrasonic imaging apparatus 910 is operating as a general station rather than a PCP 920 of a PBSS even when the ultrasonic imaging apparatus 910 already belongs to the PBSS, and that a probe 930 is initially driven.

**[0076]** In a first operation, a pairing button included in the ultrasonic imaging apparatus 910 is pressed by a user.

**[0077]** In a second operation, the ultrasonic imaging apparatus 910 transmits to a PCP 920 first pairing information  $PI_1$  representing that the ultrasonic imaging apparatus 910 needs to perform pairing. The first pairing information  $PI_1$  may include PBC information representing that the pairing button included in the ultrasonic imaging apparatus 910 has been pressed, and a MAC address of the ultrasonic imaging apparatus 910.

**[0078]** In a third operation, the PCP 920 broadcasts a beacon frame including the first pairing information  $PI_1$ . Since the probe 930 is not yet associated with the PBSS, the probe 930 does not parse the beacon frame but discards the same. As described above, the PCP 920 may broadcast the first pairing information  $PI_1$  in a time section other than the beacon section.

**[0079]** In a fourth operation, a pairing button included in the probe 930 is pressed by the user. Accordingly, the

probe 930 starts monitoring externally received beacon frames.

**[0080]** In a fifth operation, the PCP 920 re-broadcasts the beacon frame including the first pairing information  $PI_1$ .

**[0081]** In a sixth operation, the probe 930 recognizes the ultrasonic imaging apparatus 910 as a peer device of the probe 930 by referring to the first pairing information  $PI_1$ .

**[0082]** In a seventh operation, the probe 930 is associated with the PBSS of the PCP 920.

**[0083]** In an eighth operation, the probe 930 transmits to the PCP 920 second pairing information  $PI_2$  representing that the probe 930 itself is requested by the user to perform pairing. The second pairing information  $PI_2$  may be included in an association request frame that the probe 930 transmits to the PCP 920 while the probe 930 is being associated with the PBSS.

**[0084]** In a ninth operation, the PCP 920 broadcasts a beacon frame including the first pairing information  $PI_1$  and the second pairing information  $PI_2$ .

**[0085]** In a tenth operation, in response to the beacon frame including the first pairing information  $PI_1$  and the second pairing information  $PI_2$ , the ultrasonic imaging apparatus 910 recognizes the probe 930 as a peer device of the ultrasonic imaging apparatus 910.

**[0086]** As such, according to the embodiments of the present invention, pairing between an ultrasonic imaging apparatus and a probe is performed by a user simply pressing buttons included in an ultrasonic imaging apparatus and a probe. Thus the probe portion of an ultrasound imaging system may be simply and easily replaced, if necessary, while the existing ultrasonic imaging apparatus is being used.

**[0087]** FIG. 10 is a flowchart of a process of controlling a link margin, according to an embodiment of the present invention.

**[0088]** The link margin is information used to determine a status of the communication link, and denotes a power level of a reception signal that is required by a current modulation technique. When the value of the link margin is positive, the power of the reception signal is more than necessary. When the value of the link margin is negative, the power of the reception signal is insufficient.

**[0089]** In operation 1010, a probe forms a communication link with an ultrasonic imaging apparatus via a PBSS. The formation of the communication link denotes completion of preparations for a communication with a peer device, including pairing.

**[0090]** In operation 1020, the probe receives a link margin response frame including information about the link margin (hereinafter, also referred to as link margin information) from the ultrasonic imaging apparatus, and extracts the link margin information from the link margin response frame. A format of the link margin response frame will be described later with reference to FIG. 11.

**[0091]** The ultrasonic imaging apparatus calculates the link margin information based on a data frame that

the probe transmits in the 60 GHz band, and then informs the probe of the calculated link margin. The link margin response frame may be received every time the probe requests the link margin response frame, or may be transmitted by the ultrasonic imaging apparatus periodically without special requests or whenever the state of a link degrades.

**[0092]** In operation 1030, the probe adjusts the link margin based on the link margin information. To adjust the link margin, the probe may perform at least one of a change in transmission power, a change in a modulation and coding scheme (MCS), a change in beam forming, and a change in channel frequency within the 60 GHz band.

**[0093]** FIG. 11 illustrates a format of a link margin response frame 1100 according to an embodiment of the present invention.

**[0094]** As illustrated in FIG. 11, the link margin response frame 1100 includes a category field 1101, an action field 1102, a transmission number field 1103, a preferred action field 1104, a link margin element field 1105, an unsolicited field 1106, and a data frame ID field 1107.

**[0095]** The category field 1101 represents what kind of frame the link margin response frame 1100 belongs to. According to the present embodiment, the category field 1101 may indicate that the link margin response frame 1100 is a control frame.

**[0096]** The action field 1102 indicates that the link margin response frame 1100 is a link margin response frame categorized into a control frame which is the frame type determined by the category field 1101.

**[0097]** The transmission number field 1103 indicates the number of times the link margin response frame 1100 is transmitted from an ultrasonic imaging apparatus to a probe.

**[0098]** The preferred action field 1104 indicates one operation that the ultrasonic imaging apparatus requests from among a change in transmission power, a change in MCS, beam forming, and a channel frequency change. When the link margin response frame 1100 including the preferred action field 1104 is received, the probe may perform the operation indicated by the preferred action field 1104 or may perform an operation for margin adjustment independently without respect to the preferred action field 1104. Although the preferred action field 1104 is illustrated as an independent field of the link margin response frame 1100 in FIG. 11, the preferred action field 1104 may be a subfield of the link margin element field 1105.

**[0099]** The link margin element field 1105 includes the link margin information and is divided into an element ID field 1108, a length field 1109, a MCS field 1110, and a link margin field 1111.

**[0100]** The element ID field 1108 indicates that the link margin element field 1105 is a field including the link margin information.

**[0101]** The length field 1109 indicates a length of the

link margin element field 1105.

**[0102]** The MCS field 1110 indicates an index representing an MCS which is to be changed, when the preferred action field 1104 indicates that the ultrasonic imaging apparatus requests a change in the MCS.

**[0103]** The link margin field 1111 records information about the link margin calculated by the ultrasonic imaging apparatus.

**[0104]** The unsolicited field 1106 represents whether the link margin response frame 1100 is received in response to a request frame of the probe. For example, when the link margin response frame 1100 is received in response to a request of the probe, the unsolicited field 1106 may record 0, and otherwise, the unsolicited field 1106 may record a value other than 0. If the probe transmits a link margin request frame (not shown) to the ultrasonic imaging apparatus to request the link margin response frame 1100, the link margin request frame may include at least one of a category field indicating the kind of frame, an action field indicating that the link margin response frame 1100 is a link margin request frame from among frames categorized into the kind of frame indicated by the category field, and a transmission number field representing the number of times the link margin request frame is transmitted.

**[0105]** The data frame ID field 1107 includes a sequence number of a data frame used when the ultrasonic imaging apparatus calculates the link margin. Through these pieces of information, the probe can recognize a time for calculating the link margin, and thus may adequately control the state of a communication link.

**[0106]** FIG. 12 is a block diagram of a structure of a probe apparatus 1200 according to another embodiment of the present invention.

**[0107]** As illustrated in FIG. 12, the probe apparatus 1200 includes a transducer 1201, a receiver beam former 1202, a user interface 1203, and a wireless transceiver module 1250.

**[0108]** The wireless transceiver module 1250 includes an association performing unit 1251, a frame generation unit 1252, a margin information processing unit 1253, a margin control unit 1254, a beam forming unit 1255, a wireless communication unit 1256, and a link formation unit 1260. The link formation unit 1260 includes a pairing request unit 1261, a peer determination unit 1262, and a beacon monitoring unit 1263. The wireless transceiver module 1250 may further include other various components such as a battery, an analog to digital converter (ADC), and a low noise amplifier (LNA). This will be apparent to one of ordinary skill in the art, thus no further descriptions thereof are provided.

**[0109]** The transducer 1201 converts an ultrasonic echo signal received from a test target into an electrical signal, and the receiver beam former 1202 gathers multiple channels of echo signals (more specifically, digital data into which the echo signals are converted) received from oscillators arranged in an array or matrix form in the transducer 1201.

**[0110]** The wireless transceiver module 1250 performs procedures necessary for transmitting an echo signal to an ultrasonic imaging apparatus 1280 in the 60 GHz frequency band. The association performing unit 1251 performs a procedure for associating the probe apparatus 1200 using a mmWave-based wireless network. As described above, the mmWave-based wireless network may be a PBSS that follows the WiGig standard of WGA. When the probe 1200 and the ultrasonic imaging apparatus 1280 perform communications via the PBSS, the ultrasonic imaging apparatus 1280 may operate as a PCP instead of the probe 1200, in order that the size and weight of the probe 1200 can be kept low by not including the components therein which would be necessary to allow the probe to be a PCP .

**[0111]** The frame generation unit 1252 generates a data frame with a format suitable for the mmWave-based wireless network, by using the echo signal received via the transducer 1201.

**[0112]** The wireless communication unit 1256 transmits the data frame generated by the frame generation unit 1252 to the ultrasonic imaging apparatus 1280 via the 60 GHz frequency band.

**[0113]** The beam forming unit 1255 performs mmWave beamforming together with the ultrasonic imaging apparatus 1280. In other words, the beam forming unit 1255 performs procedures necessary for efficiently transmitting and receiving data to and from the ultrasonic imaging apparatus 1280 by using mmWaves, such as by using sector level sweeping and beam refinement techniques, well known to those of ordinary skill in the art.

**[0114]** The link formation unit 1260 forms a link with the ultrasonic imaging apparatus 1280. When a user command for making a pairing request is received via the user interface 1203, the beacon monitoring unit 1263 receives a mmWave beacon of the PBSS to which the ultrasonic imaging apparatus 1280 belongs. The reception of the user command for making a pairing request denotes not only physical reception but also requests an operation of parsing and analyzing a received beacon frame.

**[0115]** Accordingly, the peer determination unit 1262 detects the ultrasonic imaging apparatus 1280 which is to be paired with the probe 1200 by using first pairing information included in the mmWave beacon. The first pairing information represents that the ultrasonic imaging apparatus 1280 has been requested by a user to perform pairing, and may include the MAC address of the ultrasonic imaging apparatus 1280 and PBC information representing that a PBC-type pairing button included in the ultrasonic imaging apparatus 1280 has been pressed.

**[0116]** The pairing request unit 1261 transmits second pairing information representing that the probe 1200 requests pairing, to the ultrasonic imaging apparatus 1280 via the PBSS. The second pairing information may include the MAC address of the probe 1200 and PBC information representing that a PBC-type pairing button included in the probe 1200 has been pressed.

**[0117]** The margin information processing unit 1253 extracts information about a link margin of a communication link from the ultrasonic imaging apparatus 1280. The link margin information may be included in a link margin response frame that the ultrasonic imaging apparatus 1280 transmits to the probe 1200 in response to a request of the probe 1200 or periodically without requests or when the state of the communication link degrades.

**[0118]** The margin control unit 1254 controls the link margin based on the link margin response frame. More specifically, the margin control unit 1254 may adjust the link margin by performing at least one of a change in transmission power, a change in a MCS, a change in beam forming, and a change in a channel frequency within the 60 GHz frequency band.

**[0119]** The above-described method and apparatus embodiments of the present invention can be realized in hardware or as software or computer code that can be stored in a recording medium such as a CD ROM, an RAM, a floppy disk, a hard disk, a DVD or a magneto-optical disk or downloaded over a network, so that the methods described herein can be rendered in such software using a general purpose computer, or a special processor or in programmable or dedicated hardware, such as an ASIC or FPGA. As would be understood in the art, the computer, the processor or the programmable hardware include memory components, e.g., RAM, ROM, Flash, etc. that may store or receive software or computer code that when accessed and executed by the computer, processor or hardware implement the processing methods described herein.

**[0120]** While the present invention has been particularly shown and described with reference to exemplary embodiments thereof, it will be understood by those of ordinary skill in the art that various changes in form and details may be made therein without departing from the scope of the present invention as defined by the following claims.

## Claims

1. A probe apparatus (1200) for ultrasound diagnostic imaging, the probe apparatus comprising:

an ultrasound transducer (1201), which is arranged to generate at least an echo signal;  
 a frame generation unit (1252), which is arranged to generate a data frame to include in the data frame the echo signal received from the ultrasound transducer;  
 a wireless communication unit (1256), which is arranged to transmit the data frame to an ultrasonic imaging apparatus (1280) over a signal channel,

### CHARACTERISED IN THAT

the wireless communication unit is arranged to

transmit the data frame to the ultrasonic imaging apparatus (1280) over the signal channel in a 60 GHz frequency band via a mmWave-based wireless network; and by

a beacon monitoring unit (1263), which receives a mmWave beacon of a PBSS Control Point "PCP" which includes first pairing information transmitted from a Personal Basic Service Set "PBSS" with which the probe apparatus is not associated, when a pairing request is received by pressing a pairing button of the probe;

a peer determination unit (1262), which detects an ultrasonic imaging apparatus which is to be paired with the probe apparatus by using the first pairing information included in the mmWave beacon;

an association performing unit (1251), which performs a procedure for associating the probe apparatus with a PBSS of the ultrasonic imaging apparatus (1280) by using a basic service set ID "BSSID" included in the mmWave beacon; and

a pairing request unit (1261), which transmits second pairing information to the PCP which transmits a mmWave beacon which includes the second pairing information to the ultrasonic imaging apparatus via the PBSS,

wherein the first pairing information represents that the ultrasonic imaging apparatus (1280) has been requested by a user to perform pairing, and the second pairing information represents that the probe apparatus (1200) has been requested by the user to perform pairing.

2. The probe apparatus of claim 1, wherein the frame generation unit (1252) is arranged to generate a data frame with a format suitable for mmWave-based wireless network, and the mmWave-based wireless network comprises a Personal Basic Service Set "PBSS" and a PBSS control point "PCP" of the PBSS that follow the WiGig standard of the Wireless Gigabit Alliance "WGA".

3. The probe apparatus of claim 1 or 2, further comprising a beam forming unit (1255), which is arranged to perform mmWave beamforming of the signal in the 60 GHz frequency band to transmit the data frame to the ultrasonic imaging apparatus (1280).

4. The probe apparatus of any preceding claim, further comprising:

a link formation unit which is arranged to form a communication link with the ultrasonic imaging apparatus in a Personal Basic Service Set "PBSS" that uses mmWaves;

a margin information processing unit (1253), which is arranged to extract information about a

link margin of the communication link from a link margin response frame received from the ultrasonic imaging apparatus (1280); and a margin control unit (1254), which is arranged to control the probe apparatus to perform at least one of a change in transmission power of an echo signal, a change in a modulation and coding scheme "MCS" to be applied to the echo signal, a change in beam forming with the ultrasonic imaging apparatus, and a change in channel frequency within a 60 GHz frequency band based on the extracted information received from the margin information processing unit (1253).

5. The probe apparatus of claim 4, wherein the margin information processing unit (1253) is arranged to transmit a link margin request frame requesting information about the link margin to the ultrasonic imaging apparatus (1280), and to receive and process the link margin response frame received from the ultrasonic imaging apparatus in response to the link margin request frame.

6. A communication method of a probe apparatus (930) for ultrasound diagnostic imaging, the communication method comprising:

receiving (401) a mmWave beacon of a PBSS Control Point "PCP" (920) which includes first pairing information transmitted from a Personal Basic Service Set "PBSS" with which the probe apparatus (930) is not associated, when a pairing request is received by pressing a pairing button of the probe;

detecting (402) an ultrasonic imaging apparatus (910) which is to be paired with the probe apparatus (930) by using the first pairing information included in the mmWave beacon;

performing (403) a procedure for associating the probe apparatus (930) with a PBSS of the ultrasonic imaging apparatus (910) by using a basic service set ID "BSSID" included in the mmWave beacon;

transmitting (404) second pairing information to the PCP (920) which transmits a mmWave beacon which includes the second pairing information to the ultrasonic imaging apparatus (910) via the PBSS;

generating an echo signal using an ultrasound transducer;

generating (302) a data frame to include in the data frame the echo signal received from the ultrasound transducer of the probe apparatus; and

transmitting (303) the data frame to an ultrasonic imaging apparatus over a signal channel in a 60 GHz frequency band via a mmWave-based

wireless network;  
 wherein the first pairing information represents that the ultrasonic imaging apparatus (910) has been requested by a user to perform pairing, and the second pairing information represents that the probe apparatus (930) has been requested by the user to perform pairing.

7. The communication method of claim 6, wherein the generating the data frame comprises generating a data frame with a format suitable for mmWave-based wireless network, and the mmWave-based wireless network is a Personal Basic Service Set "PBSS" and a PBSS control point "PCP" (920) of the PBSS that follows the WiGig standard of the Wireless Gigabit Alliance "WGA".

8. The communication method of claim 6 or 7, further including:

using the mmWave-based wireless network to form a communication link with the ultrasonic imaging apparatus (910) in a Personal Basic Service Set "PBSS" that uses mmWaves for signal transmission;

extracting information about a link margin of the communication link from a link margin response frame received from the ultrasonic imaging apparatus (910) via the communication link; and performing at least one of a change in transmission power of an echo signal, a change in a modulation and coding scheme "MCS" to be applied to the echo signal, a change in beam forming with the ultrasonic imaging apparatus (910), and a change in channel frequency within a 60 GHz frequency band, based on the extracted information about link margin.

9. The communication method of claim 8, further comprising including the link margin information in a link margin response frame that the ultrasonic imaging apparatus (910) transmits to the probe (930) via the communication link in response to a request of the probe (930) or periodically without requests or when the state of the communication link degrades.

10. An ultrasound diagnostic system comprising: a probe apparatus (1200), having an ultrasound transducer (1201); and an ultrasound imaging apparatus (1280), wherein:

the probe apparatus (1200) is arranged to wirelessly transmit an echo signal received from the ultrasound transducer of the probe apparatus to the ultrasonic imaging apparatus (1280); and the ultrasonic imaging apparatus (1280) is arranged to generate an ultrasonic image based on the echo signal received from the probe ap-

paratus (1200),

#### CHARACTERISED IN THAT

the probe apparatus (1200) is arranged to use a signal channel in a 60 GHz frequency band via a mmWave-based wireless communication network and to receive a mmWave beacon of a PBSS Control Point "PCP" which includes first pairing information transmitted from a Personal Basic Service Set "PBSS" with which the probe apparatus (1200) is not associated, when a pairing request is received by pressing a pairing button of the probe, to detect an ultrasonic imaging apparatus (1280) which is to be paired with the probe apparatus (1200) by using the first pairing information included in the mmWave beacon, perform a procedure for associating the probe apparatus with a PBSS of the ultrasonic imaging apparatus (1280) by using a basic service set ID "BSSID" included in the mmWave beacon, and transmit second pairing information to the PCP which transmits a mmWave beacon which includes the second pairing information to the ultrasonic imaging apparatus (1280) via the PBSS, and

wherein the first pairing information represents that the ultrasonic imaging apparatus (1280) has been requested by a user to perform pairing, and the second pairing information represents that the probe apparatus (1200) has been requested by the user to perform pairing.

11. The ultrasound diagnostic system of claim 10, wherein the ultrasonic imaging apparatus (1280) is arranged to generate a data frame with a format suitable for mmWave-based wireless network, and the mmWave-based wireless network is a Personal Basic Service Set "PBSS" and a PBSS control point "PCP" of the PBSS that follows the WiGig standard of the Wireless Gigabit Alliance "WGA".

12. The ultrasound diagnostic system of claim 10 or 11, wherein the probe apparatus (1200) comprises:

a link formation unit, which is arranged to form a communication link with the ultrasonic imaging apparatus in a Personal Basic Service Set "PBSS" that uses mmWaves;

a margin information processing unit (1253), which is arranged to extract information about a link margin of the communication link from a link margin response frame received from the ultrasonic imaging apparatus (1280); and a margin control unit (1254), which is arranged to control the probe apparatus to perform at least one of a change in transmission power of an echo signal, a change in a modulation and coding scheme "MCS" to be applied to the echo signal, a change in beam forming with the ultra-

sonic imaging apparatus, and a change in channel frequency within a 60 GHz frequency band based on the extracted information received from the margin information processing unit (1253).

13. The ultrasound diagnostic system of claim 12, wherein the margin information processing unit (1253) is arranged to transmit a link margin request frame requesting information about the link margin to the ultrasonic imaging apparatus (1280), and to receive and process a link margin response frame received from the ultrasonic imaging apparatus (1280) in response to the transmitted link margin request frame.
14. A computer-readable recording medium having embodied thereon a computer program causing an ultrasound diagnostic system according to at least one of claims 10 - 13 to execute the method according to at least one of claims 6 - 9.

#### Patentansprüche

1. Schallkopfvorrichtung (1200) für Ultraschalldiagnosebildgebung, wobei die Vorrichtung Folgendes umfasst:

einen Ultraschallwandler (1201), der dazu ausgerichtet ist, wenigstens ein Echosignal zu erzeugen;

eine Rahmenerzeugungseinheit (1252), die dazu ausgerichtet ist, einen Datenrahmen zu erzeugen und das von dem Ultraschallwandler gesendete Echosignal in den Datenrahmen einzufügen;

eine drahtlose Kommunikationseinheit (1256), die dazu ausgerichtet ist, den Datenrahmen durch einen Signalkanal an eine Ultraschallbildgebungsvorrichtung (1280) zu übertragen,

**DADURCH GEKENNZEICHNET, DASS**

die drahtlose Kommunikationseinheit dazu ausgerichtet ist, den Datenrahmen über den Signalkanal in einem 60 GHz Frequenzband über das auf Millimeterwellen basierende drahtlose Netzwerk an die Ultraschallbildgebungsvorrichtung (1280) zu übertragen; und **gekennzeichnet durch**

eine Beacon-Überwachungseinheit (1263), die einen Millimeterwellen-Beacon eines PBSS-Kontrollpunkts (PCP) empfängt, welcher erste Paarungsinformationen enthält, die von einem Personal Basic Service Set (PBSS) übertragen werden, mit dem die Schallkopfvorrichtung nicht verknüpft ist, wenn eine Paarungsanforderung empfangen wird **durch** Drücken einer Paarungstaste der Sonde;

eine Peer-Bestimmungseinheit (1262), die eine Ultraschallbildgebungsvorrichtung erfasst, welche unter Verwendung der in dem Millimeterwellen-Beacon enthaltenen ersten Paarungsinformationen mit der Schallkopfvorrichtung gepaart werden soll;

eine Verknüpfungsausführungseinheit (1251), die einen Vorgang zum Verknüpfen der Schallkopfvorrichtung mit einem PBSS der Ultraschallbildgebungsvorrichtung (1280) **durch** Verwenden einer in dem Millimeterwellen-Beacon enthaltenen Basisdienstsatz-ID (BSSID) ausführt; und

eine Paarungsanforderungseinheit (1261), die zweite Paarungsinformationen an den PCP überträgt, welcher einen der zweiten Paarungsinformationen enthaltenden Millimeterwellen-Beacon über das PBSS an die Ultraschallbildgebungsvorrichtung überträgt,

wobei die ersten Paarungsinformationen darstellen, dass eine von einem Benutzer stammende Anforderung zur Durchführung einer Paarung **durch** die Ultraschallbildgebungsvorrichtung (1280) empfangen wurde, und wobei die zweiten Paarungsinformationen darstellen, dass eine von einem Benutzer stammende Anforderung zur Durchführung einer Paarung **durch** die Schallkopfvorrichtung (1200) empfangen wurde.

2. Schallkopfvorrichtung nach Anspruch 1, wobei die Rahmenerzeugungseinheit (1252) dazu ausgerichtet ist, einen Datenrahmen mit einem für ein auf Millimeterwellen basierendes drahtloses Netzwerk geeigneten Format zu erzeugen, und wobei das auf Millimeterwellen basierende drahtlose Netzwerk ein Personal Basic Service Set (PBSS) und einen PBSS-Kontrollpunkt (PCP) des PBSS, die dem Wi-Gig-Standard der Wireless Gigabit Alliance (WGA) entsprechen, umfasst.

3. Schallkopfvorrichtung nach Anspruch 1 oder 2, weiterhin umfassend eine Strahlformungseinheit (1255), die dazu ausgerichtet ist, eine Millimeterwellen-Strahlformung des Signals in dem 60 GHz Frequenzband durchzuführen, um den Datenrahmen an die Ultraschallbildgebungsvorrichtung (1280) zu übertragen.

4. Schallkopfvorrichtung nach einem der vorangegangenen Ansprüche, die weiterhin Folgendes umfasst:

eine Verbindungsbildungseinheit, die dazu ausgerichtet ist, eine Kommunikationsverbindung mit der Ultraschallbildgebungsvorrichtung in einem Millimeterwellen verwendenden Personal Basic Service Set (PBSS) zu bilden;

eine Reserveinformationsverarbeitungseinheit

- (1253), die dazu ausgerichtet ist, Informationen über eine Verbindungsreserve der Kommunikationsverbindung aus einem von der Ultraschallbildgebungsvorrichtung (1280) gesendeten Verbindungsreserveantwortrahmen zu extrahieren; und
- eine Reservesteuerungseinheit (1254), die dazu ausgerichtet ist, die Schallkopfvorrichtung derart zu steuern, dass diese wenigstens eine der folgenden ausführt: eine Veränderung in der Übertragungsleistung eines Echosignals, eine Veränderung in einem Modulations- und Codierungsschema (MCS), das auf das Echosignal angewendet werden soll, eine Veränderung in der Strahlformung mit der Ultraschallbildgebungsvorrichtung und eine Veränderung in der Kanalfrequenz innerhalb eines 60 GHz Frequenzbands, basierend auf den von der Reserveinformationsverarbeitungseinheit (1253) gesendeten extrahierten Informationen.
- 5
- 10
- 15
- 20
- 25
- 30
- 35
- 40
- 45
- 50
- 55
- 60
- 65
- 70
- 75
- 80
- 85
- 90
- 95
- 100
- 105
- 110
- 115
- 120
- 125
- 130
- 135
- 140
- 145
- 150
- 155
- 160
- 165
- 170
- 175
- 180
- 185
- 190
- 195
- 200
- 205
- 210
- 215
- 220
- 225
- 230
- 235
- 240
- 245
- 250
- 255
- 260
- 265
- 270
- 275
- 280
- 285
- 290
- 295
- 300
- 305
- 310
- 315
- 320
- 325
- 330
- 335
- 340
- 345
- 350
- 355
- 360
- 365
- 370
- 375
- 380
- 385
- 390
- 395
- 400
- 405
- 410
- 415
- 420
- 425
- 430
- 435
- 440
- 445
- 450
- 455
- 460
- 465
- 470
- 475
- 480
- 485
- 490
- 495
- 500
- 505
- 510
- 515
- 520
- 525
- 530
- 535
- 540
- 545
- 550
- 555
- 560
- 565
- 570
- 575
- 580
- 585
- 590
- 595
- 600
- 605
- 610
- 615
- 620
- 625
- 630
- 635
- 640
- 645
- 650
- 655
- 660
- 665
- 670
- 675
- 680
- 685
- 690
- 695
- 700
- 705
- 710
- 715
- 720
- 725
- 730
- 735
- 740
- 745
- 750
- 755
- 760
- 765
- 770
- 775
- 780
- 785
- 790
- 795
- 800
- 805
- 810
- 815
- 820
- 825
- 830
- 835
- 840
- 845
- 850
- 855
- 860
- 865
- 870
- 875
- 880
- 885
- 890
- 895
- 900
- 905
- 910
- 915
- 920
- 925
- 930
- 935
- 940
- 945
- 950
- 955
- 960
- 965
- 970
- 975
- 980
- 985
- 990
- 995
- 1000

mung mit der Ultraschallbildgebungsvorrichtung (910) und einer Veränderung in der Kanalfrequenz innerhalb eines 60 GHz Frequenzbands, basierend auf den extrahierten Informationen über die Verbindungsreserve.

9. Kommunikationsverfahren nach Anspruch 8, weiterhin umfassend das Einfügen der Verbindungsreserveinformationen in einen Verbindungsreserveantwortrahmen, der von der Ultraschallbildgebungsvorrichtung (910) über die Kommunikationsverbindung an den Schallkopf (930) übertragen wird, als Reaktion auf eine Anforderung des Schallkopfs (930) oder periodisch ohne Anforderungen oder wenn der Zustand der Kommunikationsverbindung sich verschlechtert.

10. Ultraschalldiagnosesystem, welches eine einen Ultraschallwandler (1201) aufweisende Schallkopfvorrichtung (1200) und eine Ultraschallbildgebungsvorrichtung (1280) umfasst, wobei:

die Schallkopfvorrichtung (1200) dazu ausgerichtet ist, ein von dem Ultraschallwandler der Schallkopfvorrichtung gesendetes Echosignal drahtlos an die Ultraschallbildgebungsvorrichtung (1280) zu übertragen; und

die Ultraschallbildgebungsvorrichtung (1280) dazu ausgerichtet ist, ein Ultraschallbild basierend auf dem von der Schallkopfvorrichtung (1200) gesendeten Echosignal zu erzeugen,

**DADURCH GEKENNZEICHNET, DASS**

die Schallkopfvorrichtung (1200) dazu ausgerichtet ist, einen Signalkanal in einem 60 GHz Frequenzband über ein auf Millimeterwellen basierendes drahtloses Kommunikationsnetzwerk zu verwenden und einen Millimeterwellen-Beacon eines PBBS-Kontrollpunkts (PCP) zu empfangen, welcher erste Paarungsinformationen enthält, die von einem Personal Basic Service Set (PBSS) übertragen werden, mit dem die Schallkopfvorrichtung (1200) nicht verknüpft ist, wenn eine Paarungsanforderung empfangen wird durch Drücken einer Paarungstaste der Sonde; eine Ultraschallbildgebungsvorrichtung (1280) zu erfassen, welche unter Verwendung der in dem Millimeterwellen-Beacon enthaltenen ersten Paarungsinformationen mit der Schallkopfvorrichtung (1200) gepaart werden soll, einen Vorgang zum Verknüpfen der Schallkopfvorrichtung mit einem PBSS der Ultraschallbildgebungsvorrichtung (1280) durch Verwenden einer in dem Millimeterwellen-Beacon enthaltenen Basisdienstsatz-ID (BSSID) durchzuführen; und zweite Paarungsinformationen an den PCP zu übertragen, welcher einen Millimeterwellen-Beacon, der die zweiten Paarungsinformationen enthält, über das PBSS an

die Ultraschallbildgebungsvorrichtung (1280) überträgt;

wobei die ersten Paarungsinformationen darstellen, dass eine von einem Benutzer stammende Anforderung zur Durchführung einer Paarung durch die Ultraschallbildgebungsvorrichtung (1280) empfangen wurde, und wobei die zweiten Paarungsinformationen darstellen, dass eine von einem Benutzer stammende Anforderung zur Durchführung einer Paarung durch die Schallkopfvorrichtung (1200) empfangen wurde.

11. Ultraschalldiagnosesystem nach Anspruch 10, wobei die Ultraschallbildgebungsvorrichtung (1280) dazu ausgerichtet ist, einen Datenrahmen mit einem für ein auf Millimeterwellen basierendes drahtloses Netzwerk geeigneten Format zu erzeugen, und wobei es sich bei dem auf Millimeterwellen basierenden drahtlosen Netzwerk um ein Personal Basic Service Set (PBSS) und ein PBSS-Kontrollpunkt (PCP) des PBSS, der dem WiGig-Standard der Wireless Gigabit Alliance (WGA) entspricht, handelt.

12. Ultraschalldiagnosesystem nach Anspruch 10 oder 11, wobei die Schallkopfvorrichtung (1200) Folgendes umfasst:

eine Verbindungsbildungseinheit, die dazu ausgerichtet ist, eine Kommunikationsverbindung mit der Ultraschallbildgebungsvorrichtung in einem Millimeterwellen verwendenden Personal Basic Service Set (PBSS) zu bilden;

eine Reserveinformationsverarbeitungseinheit (1253), die dazu ausgerichtet ist, Informationen über eine Verbindungsreserve der Kommunikationsverbindung aus einem von der Ultraschallbildgebungsvorrichtung (1280) gesendeten Verbindungsreserveantwortrahmen zu extrahieren; und

eine Reservesteuerungseinheit (1254), die dazu ausgerichtet ist, die Schallkopfvorrichtung derart zu steuern, dass diese wenigstens eine der folgenden ausführt: eine Veränderung in der Übertragungsleistung eines Echosignals, eine Veränderung in einem Modulations- und Codierungsschema (MCS), das auf das Echosignal angewendet werden soll, eine Veränderung in der Strahlformung mit der Ultraschallbildgebungsvorrichtung und eine Veränderung in der Kanalfrequenz innerhalb eines 60 GHz Frequenzbands, basierend auf den von der Reserveinformationsverarbeitungseinheit (1253) gesendeten extrahierten Informationen.

13. Ultraschalldiagnosesystem nach Anspruch 12, wobei die Reserveinformationsverarbeitungseinheit (1253) dazu ausgerichtet ist, einen Anforderungs-

rahmen für eine Verbindungsreserve, in dem Informationen über die Verbindungsreserve angefragt werden, an die Ultraschallbildgebungsvorrichtung (1280) zu übertragen, und einen von der Ultraschallbildgebungsvorrichtung (1280) als Reaktion auf den Anforderungsrahmen für eine Verbindungsreserve gesendeten Verbindungsreserveantwortrahmen zu empfangen und zu verarbeiten.

14. Computerlesbares Speichermedium, auf dem ein Computerprogramm eingebettet ist, das ein Ultraschalldiagnosesystem nach wenigstens einem der Ansprüche 10 bis 13 veranlasst, das Verfahren nach wenigstens einem der Ansprüche 6 bis 9 auszuführen.

### Revendications

1. Appareil à sonde (1200) pour échographie de diagnostic, l'appareil à sonde comprenant :

un transducteur à ultrasons (1201) agencé pour produire au moins un signal échographique ;  
une unité génératrice de trame (1252) agencée pour produire une trame de données en incluant dans la trame de données le signal échographique reçu en provenance du transducteur à ultrasons ;

une unité de communication sans fil (1256) agencée pour transmettre la trame de données à un appareil échographique (1280) sur une voie de traitement,

#### CARACTÉRISÉ EN CE QUE

l'unité de communication sans fil est agencée pour transmettre la trame de données à l'appareil échographique (1280) sur la voie de traitement dans une bande de fréquence de 60 GHz par l'intermédiaire du réseau sans fil reposant sur les ondes millimétriques ; et **caractérisé par** une unité de surveillance de balise (1263), qui reçoit une balise à ondes millimétriques d'un point de contrôle PBSS (PCP) contenant des premières informations de pairage transmises par un réseau PBSS (Personal Basic Service Set) avec lequel l'appareil à sonde n'est pas associé, lors de la réception d'une demande de pairage suite à une pression exercée sur un bouton de pairage de la sonde ;

une unité de détermination de pair (1262), qui détecte un appareil échographique destiné à être apparié avec l'appareil à sonde à l'aide des premières informations de pairage contenues dans la balise à ondes millimétriques ;

une unité d'association (1251), qui effectue une procédure d'association de l'appareil à sonde avec un réseau PBSS de l'appareil échographique (1280) au moyen d'un identifiant BSSID

(Basic Service Set ID) contenu dans la balise à ondes millimétriques ; et

une unité de demande de pairage (1261), qui transmet des deuxièmes informations de pairage au PCP qui transmet une balise à ondes millimétriques, contenant les deuxièmes informations de pairage, à l'appareil échographique par le biais du réseau PBSS,

lesdites premières informations de pairage représentant le fait que l'utilisateur a fait une demande de pairage auprès de l'appareil échographique (1280), et lesdites deuxièmes informations de pairage représentant le fait que l'utilisateur a fait une demande de pairage auprès de l'appareil à sonde (1200).

2. Appareil à sonde selon la revendication 1, dans lequel l'unité génératrice de trame (1252) est agencée pour produire une trame de données dont le format est adapté à un réseau sans fil reposant sur les ondes millimétriques, et le réseau sans fil reposant sur les ondes millimétriques comprend un réseau PBSS (Personal Basic Service Set) et un point de contrôle PBSS (PCP) du réseau PBSS qui suivent la norme WiGig de la Wireless Gigabit Alliance (WGA).

3. Appareil à sonde selon la revendication 1 ou 2, comprenant en outre une unité de formation de faisceau (1255) agencée pour réaliser une formation de faisceau d'ondes millimétriques du signal dans la bande de fréquence de 60 GHz pour transmettre la trame de données à l'appareil échographique (1280).

4. Appareil à sonde selon l'une quelconque des revendications précédentes, comprenant en outre :

une unité formatrice de liaison agencée pour former une liaison de communication avec l'appareil échographique dans un réseau PBSS (Personal Basic Service Set) utilisant les ondes millimétriques ;

une unité de traitement d'informations de marge (1253) agencée pour extraire des informations concernant une marge de liaison propre à la liaison de communication à partir d'une trame de réponse concernant la marge de liaison reçue en provenance de l'appareil échographique (1280) ; et

une unité de commande de marge (1254) agencée pour commander l'appareil à sonde afin de réaliser au moins une opération parmi une modification de puissance d'émission d'un signal échographique, une modification d'un programme de modulation et de codage (MCS, Modulation and Coding Scheme) destiné à être appliqué au signal échographique, une modification de la formation de faisceau avec l'appareil échographique, et une modification de la fréquence

de voie dans une bande de fréquence de 60 GHz en fonction des informations extraites reçues en provenance de l'unité de traitement d'informations de marge (1253).

5. Appareil à sonde selon la revendication 4, dans lequel l'unité de traitement d'informations de marge (1253) est agencée pour transmettre à l'appareil échographique (1280) une trame de requête concernant la marge de liaison demandant des informations concernant la marge de liaison, et pour recevoir et traiter la trame de réponse concernant la marge de liaison reçue en provenance de l'appareil échographique en réponse à la trame de requête concernant la marge de liaison.

6. Procédé de communication pour un appareil à sonde (930) pour échographie de diagnostic, le procédé de communication comprenant :

la réception (401) d'une balise à ondes millimétriques d'un point de contrôle PBSS (PCP) (920) contenant des premières informations de pairage transmises par un réseau PBSS (Personal Basic Service Set) avec lequel l'appareil à sonde (930) n'est pas associé, lors de la réception d'une demande de pairage suite à une pression exercée sur un bouton de pairage de la sonde ; la détection (402) d'un appareil échographique (910) destiné à être apparié avec l'appareil à sonde (930) à l'aide des premières informations de pairage contenues dans la balise à ondes millimétriques ;

la réalisation (403) d'une procédure d'association de l'appareil à sonde (930) avec un réseau PBSS de l'appareil échographique (910) au moyen d'un identifiant BSSID (Basic Service Set ID) contenu dans la balise à ondes millimétriques ;

la transmission (403) de deuxièmes informations de pairage au PCP (920) qui transmet une balise à ondes millimétriques, contenant les deuxièmes informations de pairage, à l'appareil échographique (910) par le biais du réseau PBSS ;

la production d'un signal échographique au moyen d'un transducteur à ultrasons ;

la production (302) d'une trame de données en incluant dans la trame de données le signal échographique reçu en provenance du transducteur à ultrasons de l'appareil à sonde ; et la transmission (303) de la trame de données à un appareil échographique sur une voie de traitement dans une bande de fréquence de 60 GHz par l'intermédiaire du réseau sans fil reposant sur les ondes millimétriques ;

lesdites premières informations de pairage représentant le fait que l'utilisateur a fait une de-

mande de pairage auprès de l'appareil échographique (910), et lesdites deuxièmes informations de pairage représentant le fait que l'utilisateur a fait une demande de pairage auprès de l'appareil à sonde (930).

7. Procédé de communication selon la revendication 6, dans lequel la production de la trame de données comprend la production d'une trame de données dont le format est adapté à un réseau sans fil reposant sur les ondes millimétriques, et le réseau sans fil reposant sur les ondes millimétriques consiste en un réseau PBSS (Personal Basic Service Set) et un point de contrôle PBSS (PCP) (920) du réseau PBSS qui suit la norme WiGig de la Wireless Gigabit Alliance (WGA).

8. Procédé de communication selon la revendication 6 ou 7, comprenant en outre :

l'utilisation du réseau sans fil reposant sur les ondes millimétriques pour former une liaison de communication avec l'appareil échographique (910) dans un réseau PBSS (Personal Basic Service Set) utilisant les ondes millimétriques pour la transmission des signaux ; l'extraction d'informations concernant une marge de liaison propre à la liaison de communication à partir d'une trame de réponse concernant la marge de liaison reçue en provenance de l'appareil échographique (910) par l'intermédiaire de la liaison de communication ; et la réalisation d'au moins une opération parmi une modification de puissance d'émission d'un signal échographique, une modification d'un programme de modulation et de codage (MCS, Modulation and Coding Scheme) destiné à être appliqué au signal échographique, une modification de la formation de faisceau avec l'appareil échographique (910), et une modification de la fréquence de voie dans une bande de fréquence de 60 GHz, en fonction des informations extraites concernant la marge de liaison.

9. Procédé de communication selon la revendication 8, comprenant en outre l'inclusion des informations concernant la marge de liaison dans une trame de réponse concernant la marge de liaison que l'appareil échographique (910) transmet à la sonde (930) par l'intermédiaire de la liaison de communication en réponse à une requête de la sonde (930) ou périodiquement sans requête ou lorsque l'état de la liaison de communication se dégrade.

10. Système échographique de diagnostic comprenant : un appareil à sonde (1200), présentant un transducteur à ultrasons (1201), et un appareil échographique (1280), dans lequel :

l'appareil à sonde (1200) est agencé pour transmettre sans fil un signal échographique reçu en provenance du transducteur à ultrasons de l'appareil à sonde à l'appareil échographique (1280), et

l'appareil échographique (1280) est agencé pour produire une image échographique fondée sur le signal échographique reçu en provenance de l'appareil à sonde (1200),

**CARACTÉRISÉ EN CE QUE**

l'appareil à sonde (1200) est agencé pour utiliser une voie de traitement dans une bande de fréquence de 60 GHz par l'intermédiaire d'un réseau de communication sans fil reposant sur les ondes millimétriques et pour recevoir une balise à ondes millimétriques d'un point de contrôle PBSS (PCP) contenant des premières informations de pairage transmises par un réseau PBSS (Personal Basic Service Set) avec lequel l'appareil à sonde (1200) n'est pas associé, lors de la réception d'une demande de pairage suite à une pression exercée sur un bouton de pairage de la sonde, pour détecter un appareil échographique (1280) destiné à être apparié avec l'appareil à sonde (1200) à l'aide des premières informations de pairage contenues dans la balise à ondes millimétriques, pour réaliser une procédure d'association de l'appareil à sonde avec un réseau PBSS de l'appareil échographique (1280) au moyen d'un identifiant BSSID (Basic Service Set ID) contenu dans la balise à ondes millimétriques ; et pour transmettre des deuxièmes informations de pairage au PCP qui transmet une balise à ondes millimétriques, contenant les deuxièmes informations de pairage, à l'appareil échographique (1280) par le biais du réseau PBSS, et

lesdites premières informations de pairage représentant le fait que l'utilisateur a fait une demande de pairage auprès de l'appareil échographique (1280), et lesdites deuxièmes informations de pairage représentant le fait que l'utilisateur a fait une demande de pairage auprès de l'appareil à sonde (1200).

11. Système échographique de diagnostic selon la revendication 10, dans lequel l'appareil échographique (1280) est agencé pour produire une trame de données dont le format est adapté à un réseau sans fil reposant sur les ondes millimétriques, et le réseau sans fil reposant sur les ondes millimétriques consiste en un réseau PBSS (Personal Basic Service Set) et un point de contrôle PBSS (PCP) du réseau PBSS qui suit la norme WiGig de la Wireless Gigabit Alliance (WGA).

12. Système échographique de diagnostic selon la revendication 10 ou 11, dans lequel l'appareil à sonde

(1200) comprend :

une unité formatrice de liaison agencée pour former une liaison de communication avec l'appareil échographique dans un réseau PBSS (Personal Basic Service Set) utilisant les ondes millimétriques ;

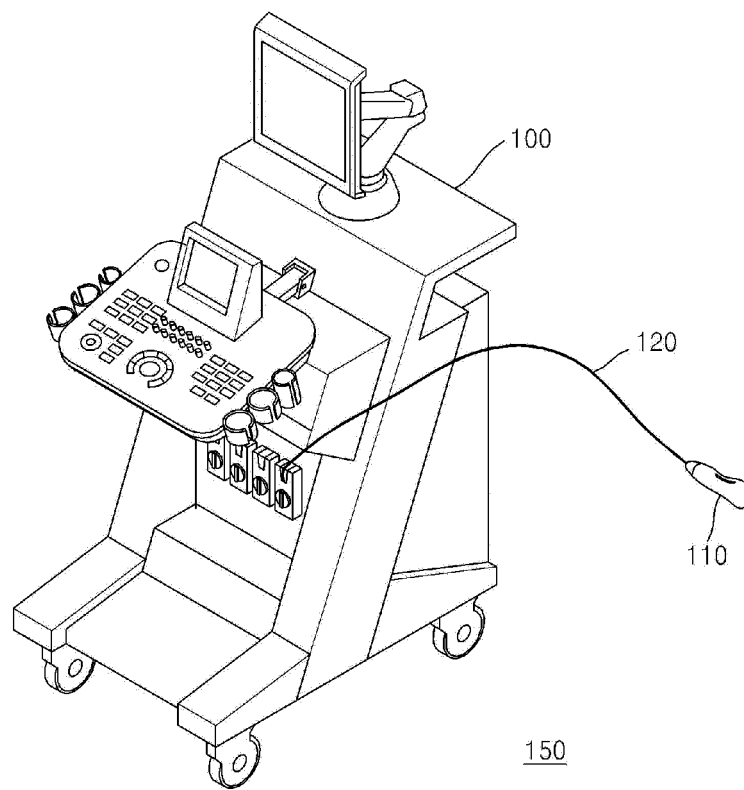
une unité de traitement d'informations de marge (1253) agencée pour extraire des informations concernant une marge de liaison propre à la liaison de communication à partir d'une trame de réponse concernant la marge de liaison reçue en provenance de l'appareil échographique (1280) ; et

une unité de commande de marge (1254) agencée pour commander l'appareil à sonde afin de réaliser au moins une opération parmi une modification de puissance d'émission d'un signal échographique, une modification d'un programme de modulation et de codage (MCS, Modulation and Coding Scheme) destiné à être appliqué au signal échographique, une modification de la formation de faisceau avec l'appareil échographique, et une modification de la fréquence de voie dans une bande de fréquence de 60 GHz en fonction des informations extraites reçues en provenance de l'unité de traitement d'informations de marge (1253).

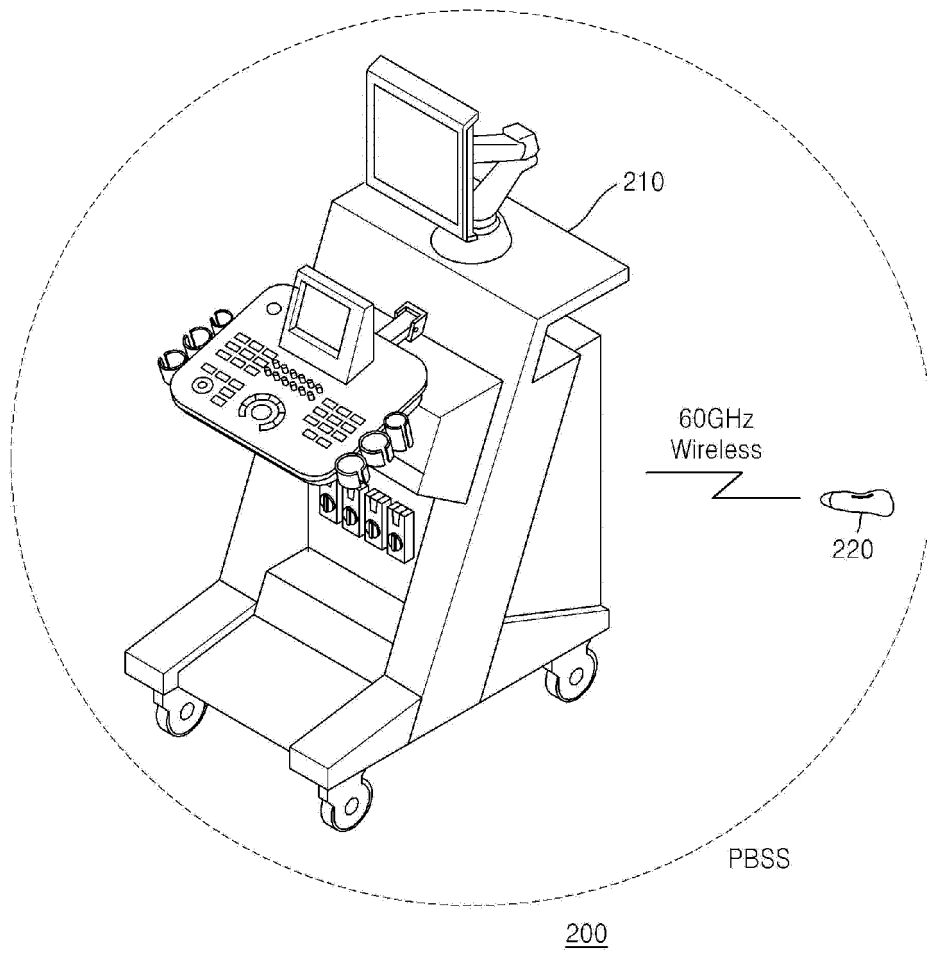
13. Système échographique de diagnostic selon la revendication 12, dans lequel l'unité de traitement d'informations de marge (1253) est agencée pour transmettre à l'appareil échographique (1280) une trame de requête concernant la marge de liaison demandant des informations concernant la marge de liaison, et pour recevoir et traiter une trame de réponse concernant la marge de liaison reçue en provenance de l'appareil échographique (1280) en réponse à la trame de requête concernant la marge de liaison transmise.

14. Support d'enregistrement lisible par ordinateur dans lequel est incorporé un programme informatique amenant un système échographique de diagnostic conforme à au moins une des revendications 10 à 13 à exécuter le procédé conforme à au moins une des revendications 6 à 9.

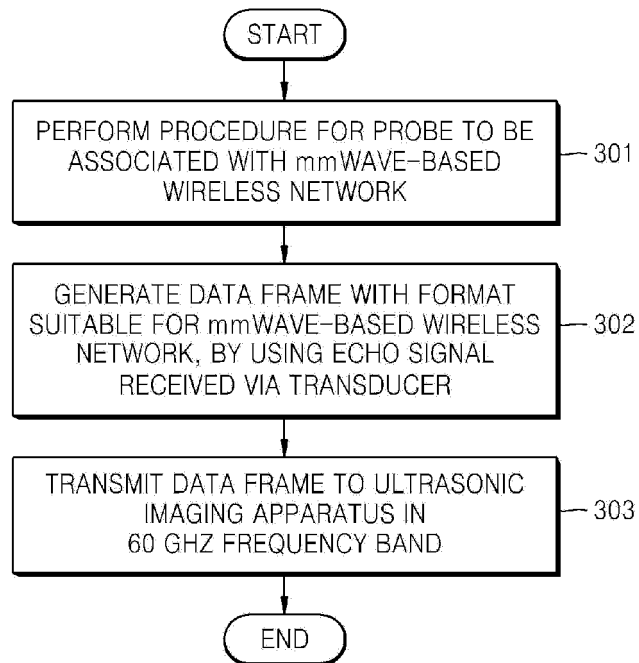
【Figure 1】



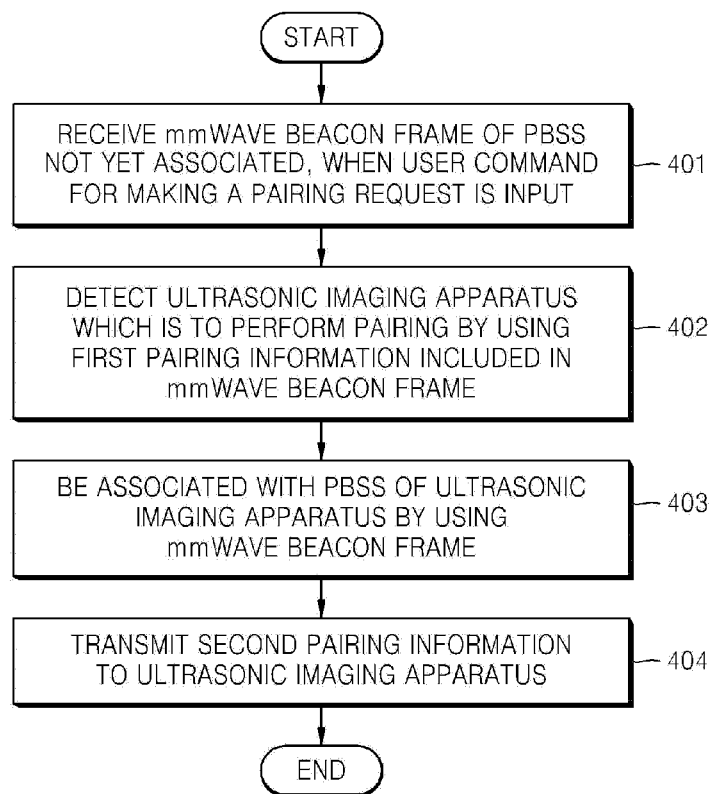
【Figure 2】



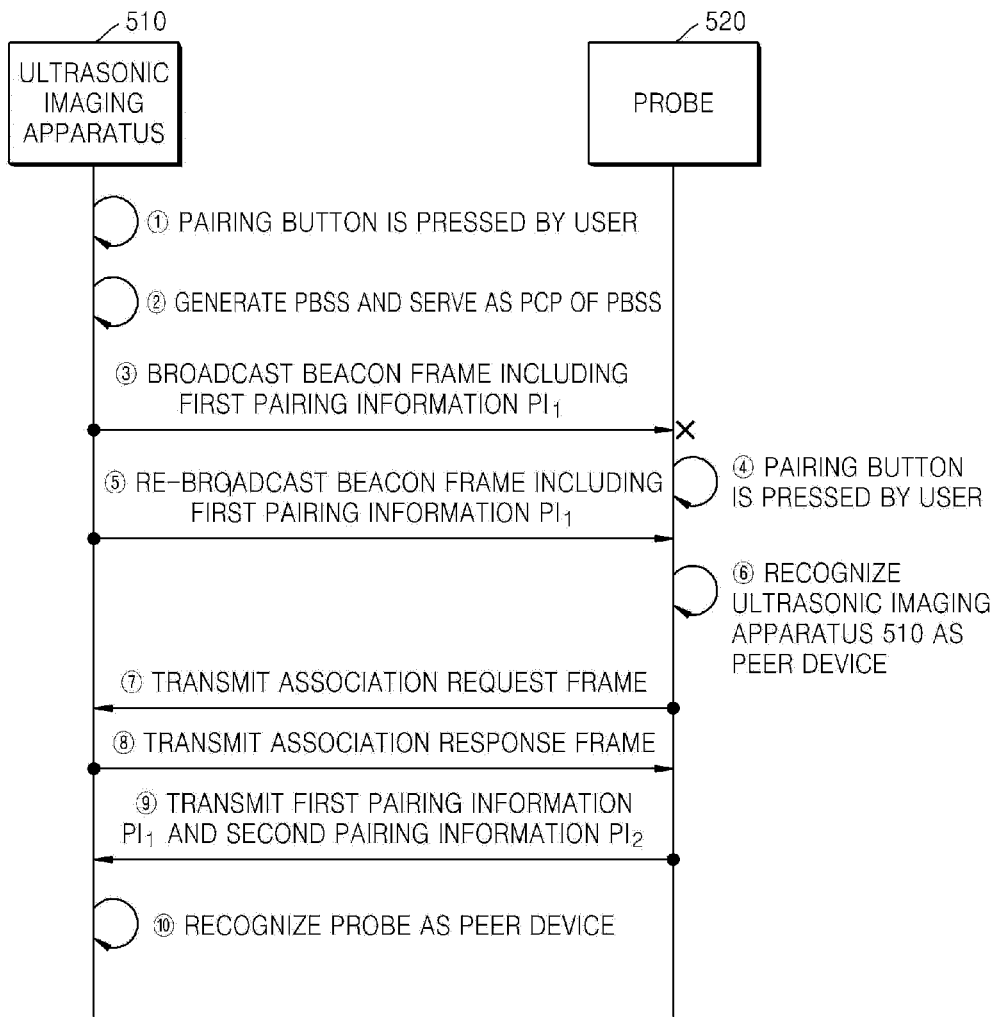
【Figure 3】



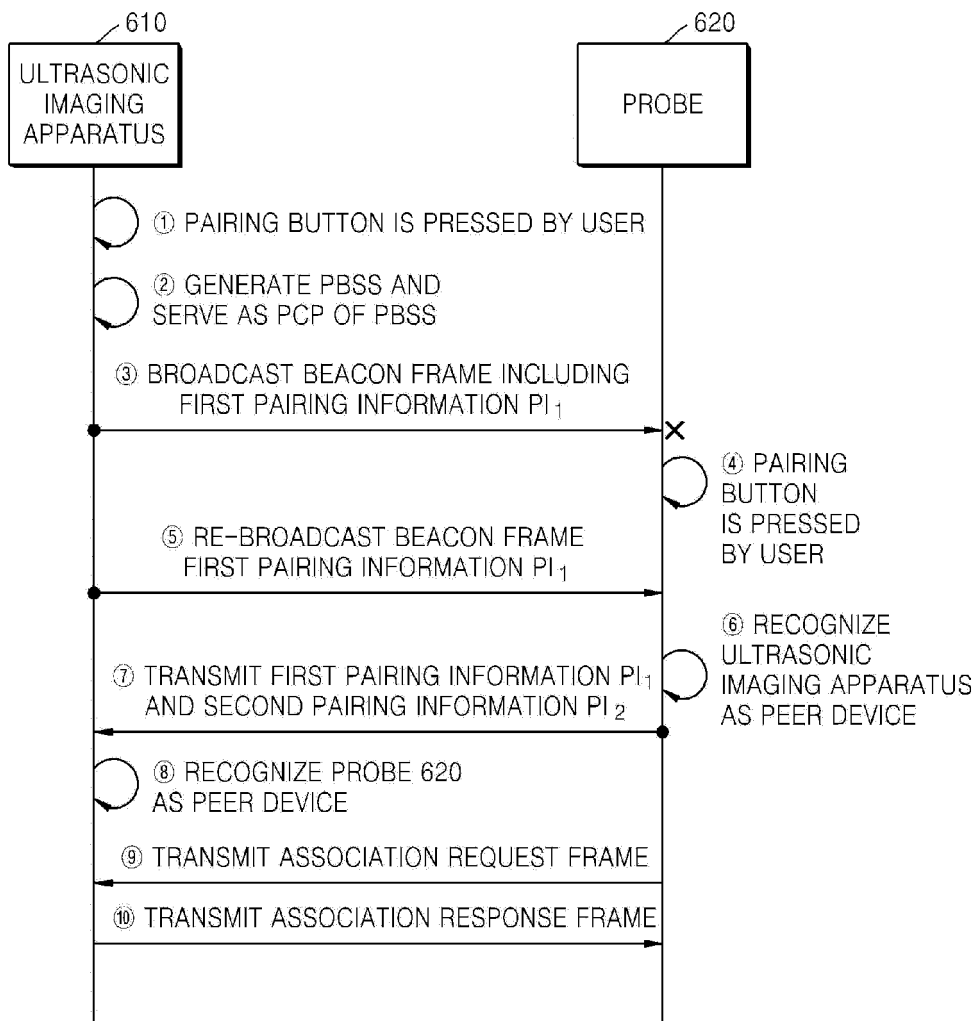
【Figure 4】



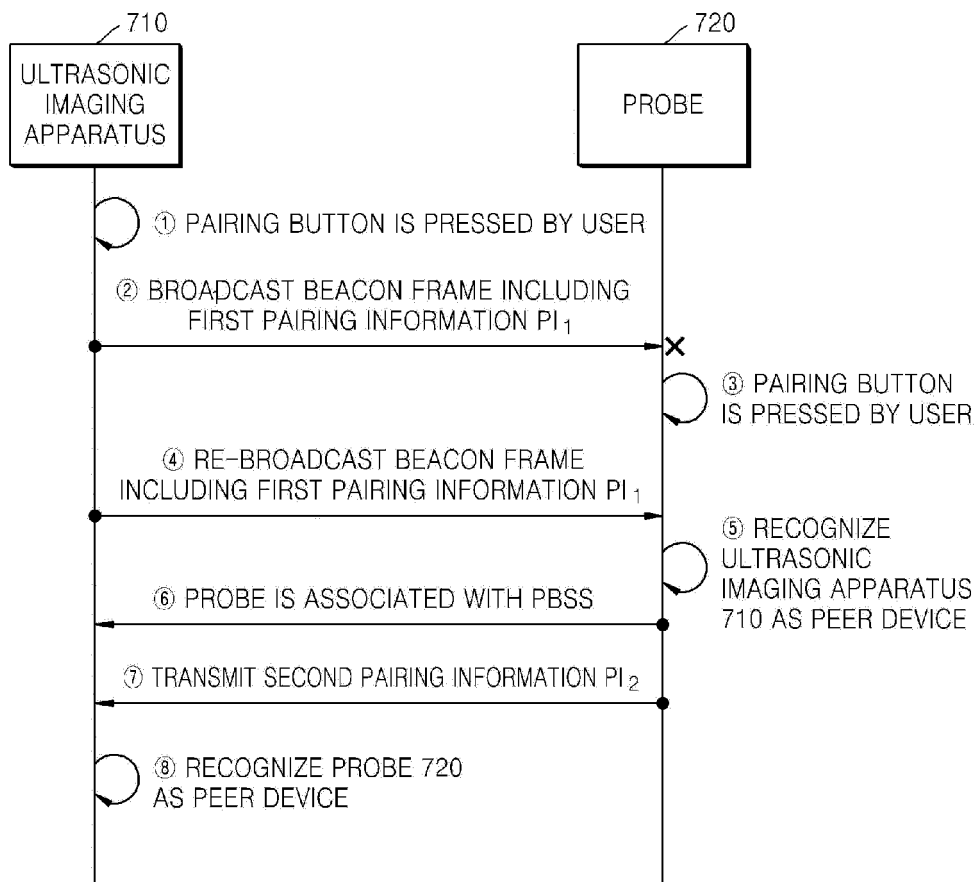
【Figure 5】



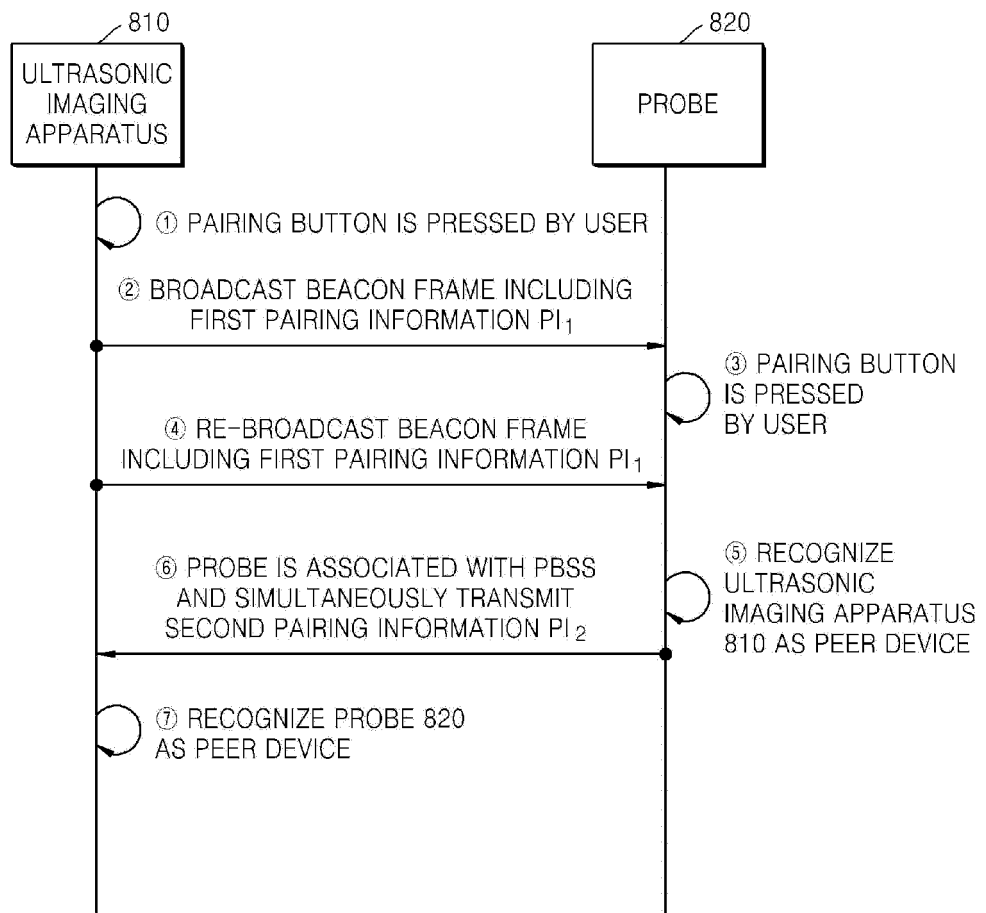
【Figure 6】



【Figure 7】

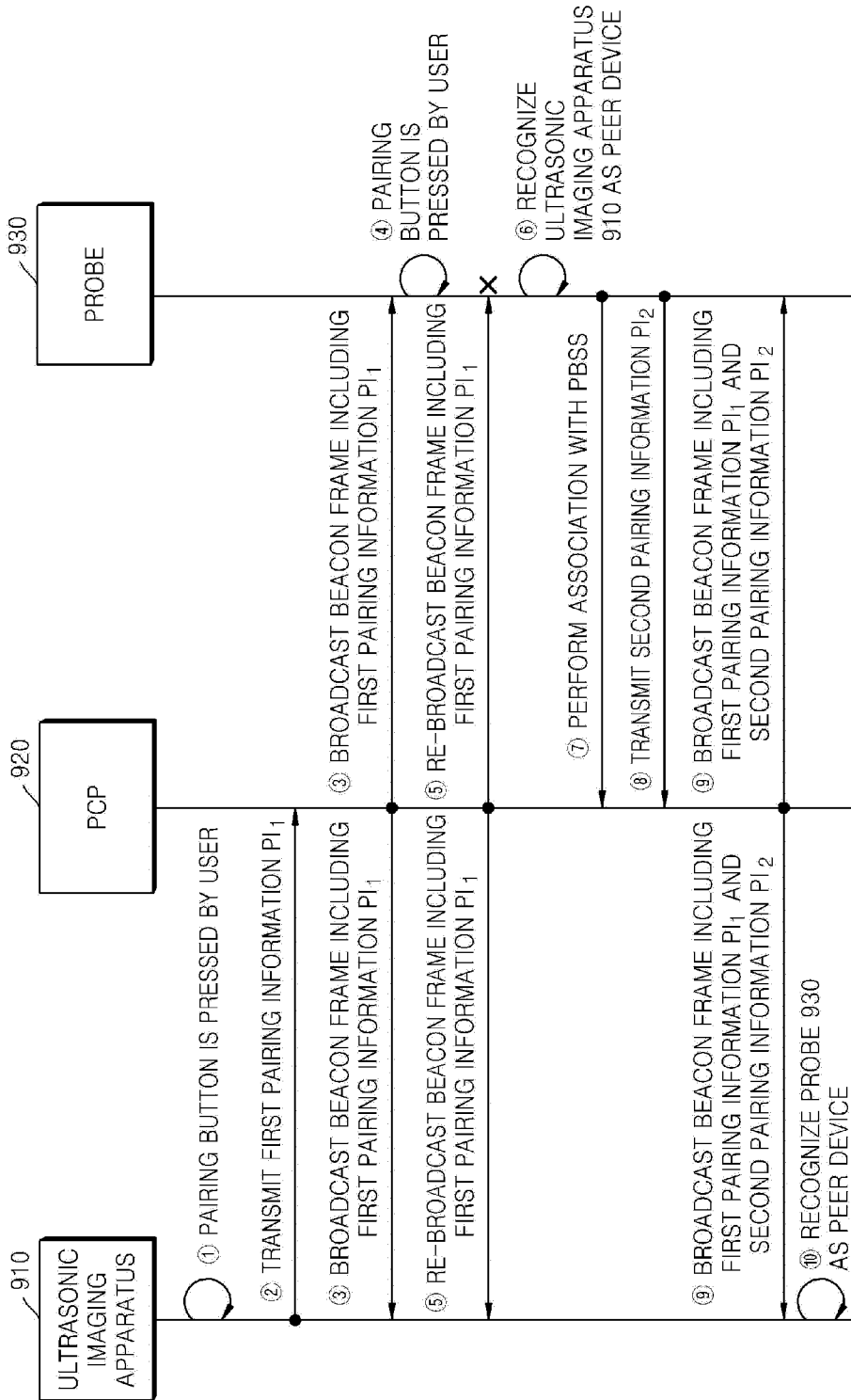


【Figure 8】

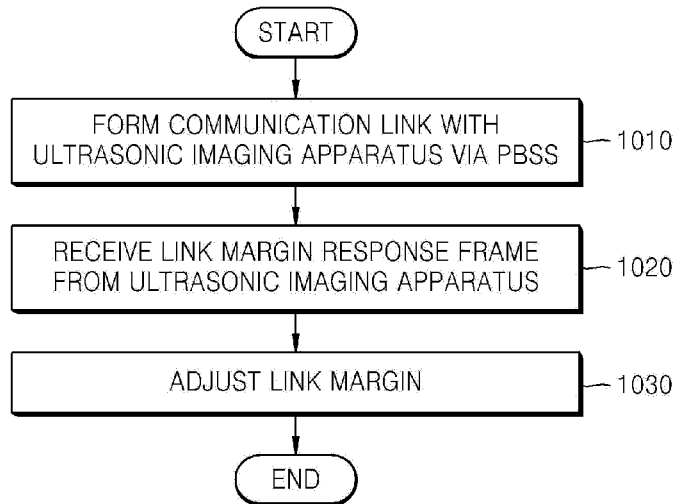


\*190

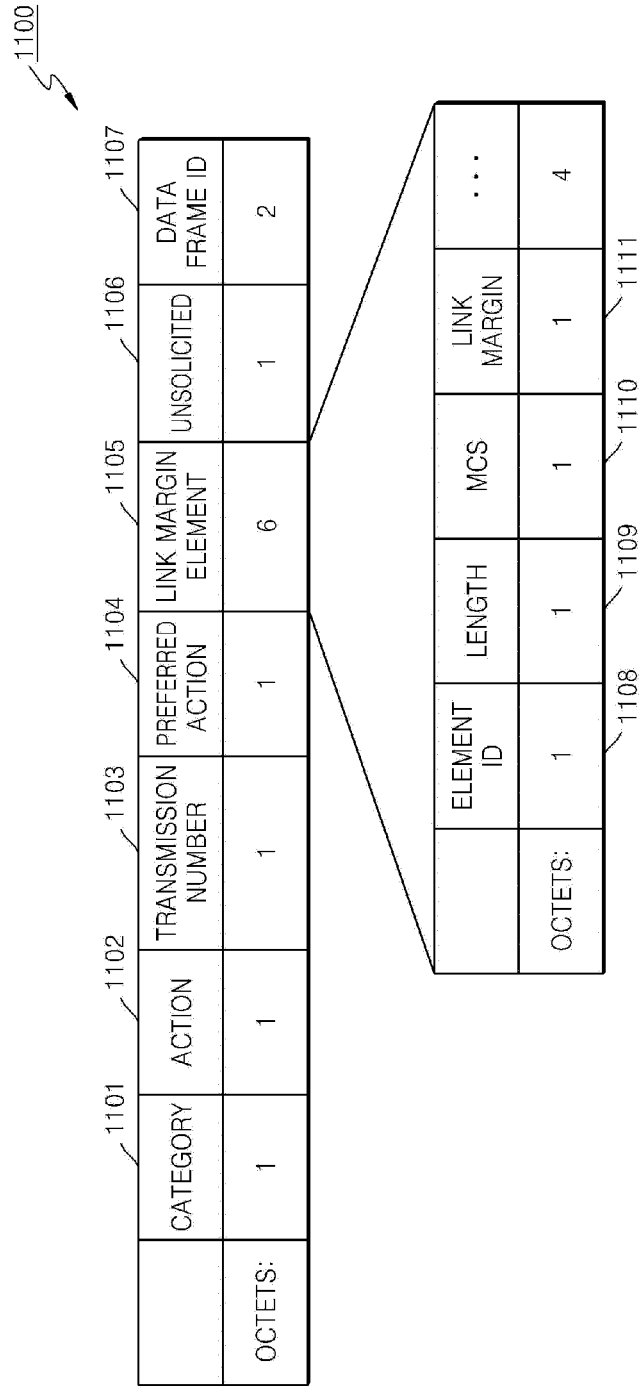
【Figure 9】



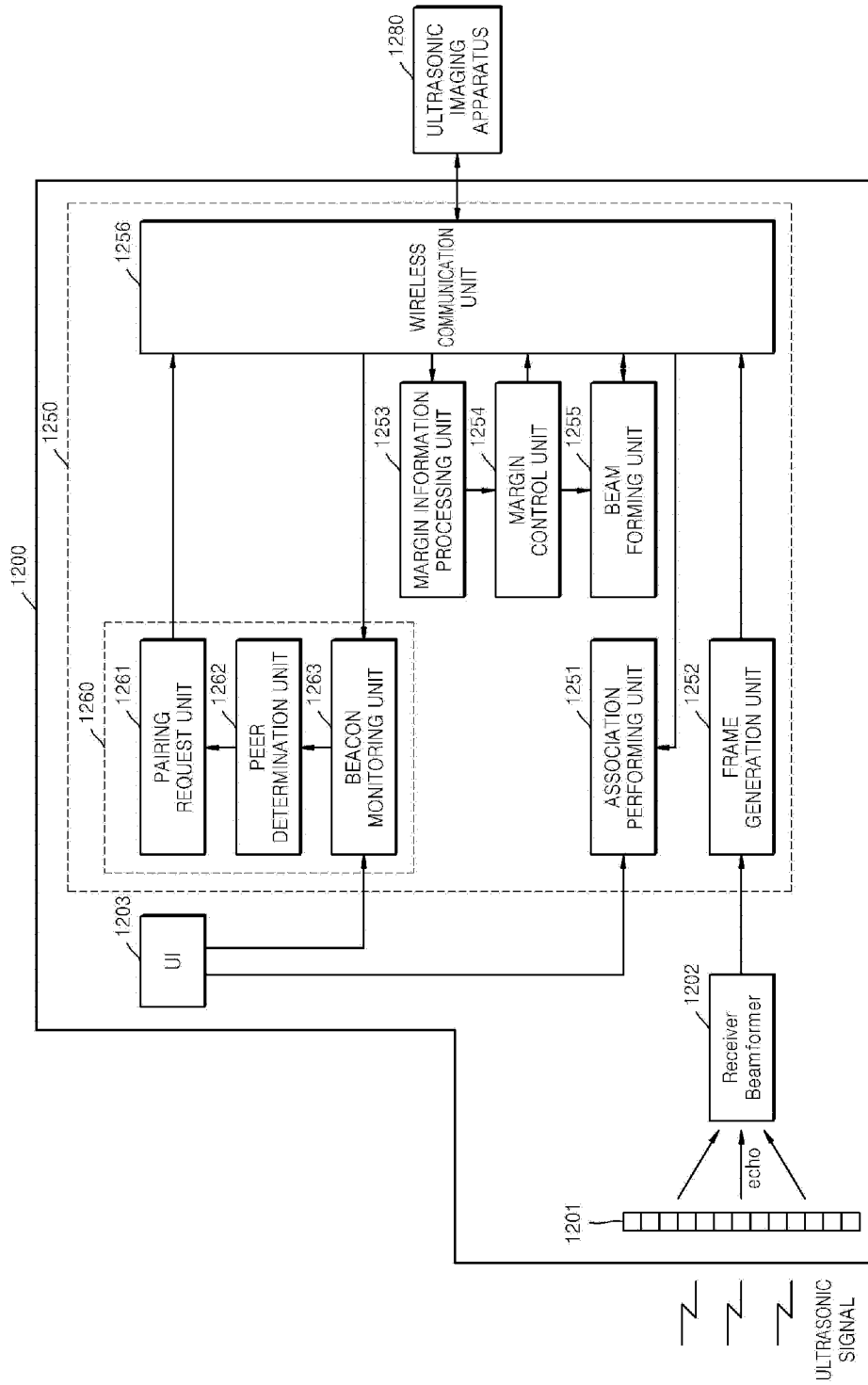
【Figure 10】



【Figure 11】



【Figure 12】



**REFERENCES CITED IN THE DESCRIPTION**

*This list of references cited by the applicant is for the reader's convenience only. It does not form part of the European patent document. Even though great care has been taken in compiling the references, errors or omissions cannot be excluded and the EPO disclaims all liability in this regard.*

**Patent documents cited in the description**

- US 2011105904 A [0006]
- US 2010286527 A [0006]
- WO 2008115312 A [0006]
- US 2010191121 A [0006]

专利名称(译)	超声诊断探头的无线通信方法及其装置		
公开(公告)号	<a href="#">EP3143938B1</a>	公开(公告)日	2019-09-04
申请号	EP2016196182	申请日	2012-07-25
[标]申请(专利权)人(译)	三星电子株式会社		
申请(专利权)人(译)	SAMSUNG ELECTRONICS CO. , LTD.		
当前申请(专利权)人(译)	SAMSUNG ELECTRONICS CO. , LTD.		
[标]发明人	KIM KANG SIK KIM JUNG JUN HAN HO SAN HONG SOON JAE		
发明人	KIM, KANG-SIK KIM, JUNG-JUN HAN, HO-SAN HONG, SOON-JAE		
IPC分类号	A61B8/00 H04W84/12		
CPC分类号	A61B8/4405 A61B8/4472 H04W84/12		
优先权	1020110073773 2011-07-25 KR PCT/KR2012/005910 2012-07-25 WO		
其他公开文献	EP3143938A1		
外部链接	<a href="#">Espacenet</a>		

摘要(译)

用于超声诊断成像的探头设备与基于mmWave的个人基本服务集 (PBSS) 关联, 与超声成像设备进行配对, 并将通过探头的换能器部分接收到的回波信号发送到超声成像设备。60 GHz频带中的信号通道, 从而消除了对数据传输电缆的需求, 并大大减少了操作员的不便。

【Figure 1】

