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(54) Method for providing ultrasound images and ultrasound apparatus

Verfahren zur Bereitstellung von Ultraschallbildern und Ultraschallvorrichtung

Procédé pour fournir des images ultrasonores et appareil à ultrasons

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Description

BACKGROUND OF THE INVENTION

1. Field of the Invention

[0001] The present invention relates to a method and apparatus for providing ultrasound images that a user wants to view by using a probe including a sensor.

2. Description of the Related Art

[0002] Ultrasound diagnosis apparatuses transmit ultrasound signals from a surface of a human body to be diagnosed toward a part *in vivo* and obtain images related to a cross-section of soft tissue or blood flow by using information regarding ultrasound signals reflected from the part.

[0003] Ultrasound diagnosis apparatuses have various advantages, including a compact size, low cost, and real-time display. Also, ultrasound diagnosis apparatuses have excellent stability because there is no fear of X-ray exposure, and thus, the ultrasound diagnosis apparatuses are commonly used together with other diagnosis apparatuses, such as computerized tomography (CT) scanners, magnetic resonance imaging (MRI) apparatuses, nuclear medicine diagnosis apparatuses, or the like.

[0004] However, it is difficult for a user to obtain a 2-dimensional ultrasound image that he or she wants to view at once by using an ultrasound diagnosis apparatus. This is because various 2-dimensional ultrasound images may be obtained according to the location of a probe or an angle between the probe and a subject to be diagnosed.

[0005] Also, when a typical ultrasound diagnosis apparatus is used, a user manipulates a probe by using one of his or her hands and manipulates a control panel of the ultrasound diagnosis apparatus by using the other hand to obtain an ultrasound image, and the obtained ultrasound image is displayed on a display unit. Also, the user manipulates a track ball and various buttons of the control panel to rotate the displayed ultrasound image in a particular orientation or at a particular angle. In this regard, if the obtained ultrasound image is not what the user wants to view, the user places the probe on the subject to be diagnosed and then obtains a new ultrasound image. However, it is difficult for the user to remember the location of the probe and the angle between the probe and the subject to be diagnosed which were used when the previous ultrasound image was obtained.

[0006] Accordingly, there is a need for a system that allows a user to easily obtain a 2-dimensional ultrasound image that he or she wants to view by using an ultrasound diagnosis apparatus.

[0007] Document US 2011/0306025 represents the closest prior art disclosing the preamble of claim 1.

SUMMARY OF THE THE INVENTION

[0008] The invention is defined in independent claims 1, 6 and 9.

[0009] The present invention provides a method and apparatus for providing ultrasound images that a user wants to view by controlling the location of a cut line or a cut surface on a three-dimensional image by using a sensor included in a probe.

[0010] According to an aspect of the present invention, there is provided a method of providing an ultrasound image, the method including: marking a cut line or a cut surface on a 3-dimensional (3D) ultrasound image of an object which is obtained by using a probe, wherein the cut line and the cut surface are used to view a cross section of the 3D ultrasound image; detecting motion information about the probe by using a sensor included in the probe; and changing a location of the cut line or the cut surface based on the detected motion information about the probe.

[0011] The method further includes displaying a 2 dimensional (2D) ultrasound image corresponding to the changed location of the cut line or the cut surface.

[0012] The method may further include capturing the displayed 2D ultrasound image.

[0013] The method includes: receiving a mode conversion command for converting a 3D image mode into a 2D image mode; and displaying a 2D ultrasound image corresponding to a location of the probe based on the mode conversion command in real time.

[0014] The receiving of the mode conversion command includes receiving the mode conversion command through a button included in the probe.

[0015] The displaying of the 2D ultrasound image in real time may further include: displaying the 2D ultrasound image corresponding to the location of the probe on a first region; and displaying on a second region a 3D ultrasound image on which a location corresponding to the 2D ultrasound image displayed on the first region is marked.

[0016] The motion information may include information about at least one selected from a tilting direction, tilting angle, rotational direction, and rotational angle of the probe.

[0017] The sensor may include at least one selected from a tilt sensor, a gyro sensor, a 3-axis magnetic sensor, and an acceleration sensor.

[0018] According to another aspect of the present invention, there is provided a ultrasound apparatus according to claim 6 including: a probe including a sensor for detecting motion information; a display unit for marking a cut line or a cut surface on a 3D ultrasound image of an object which is obtained by using the probe to view a cross section of the 3D ultrasound image; an image processor for changing a location of the cut line or the cut surface, based on motion information of the probe detected by using the sensor; and a controller for controlling the probe, the display unit, and the image processor.

BRIEF DESCRIPTION OF THE DRAWINGS

[0019] The above and other features and advantages of the present invention will become more apparent by describing in detail exemplary embodiments thereof with reference to the attached drawings in which:

FIG. 1 is a block diagram of a structure of an ultrasound apparatus according to an embodiment of the present invention;

FIG. 2 is a block diagram of a structure of a probe according to an embodiment of the present invention;

FIG. 3 is a flowchart of a method of providing an ultrasound image, according to an embodiment of the present invention;

FIG. 4 is a diagram for explaining a method of controlling the location of a cut line or a cut surface by using a sensor of a probe, according to an embodiment of the present invention;

FIG. 5 is a flowchart of a method of providing an ultrasound image, according to another embodiment of the present invention;

FIG. 6 is a diagram for explaining how an ultrasound image is provided in a 3-dimensional image mode according to an embodiment of the present invention; and

FIG. 7 is a diagram for explaining how an ultrasound image is provided in a 2-dimensional image mode according to an embodiment of the present invention.

DETAILED DESCRIPTION OF THE INVENTION

[0020] Expressions such as "at least one of," when preceding a list of elements, modify the entire list of elements and do not modify the individual elements of the list.

[0021] Most of the terms used herein are general terms that have been widely used in the technical art to which the present invention pertains. However, some of the terms used herein may be created to reflect the intentions of technicians in this art, precedents, or new technologies. Also, some of the terms used herein may be arbitrarily chosen by the present applicant. In this case, these terms are defined in detail below. Accordingly, the specific terms used herein should be understood based on the unique meanings thereof and the whole context of the present invention.

[0022] In the present specification, it should be understood that the terms, such as 'including' or 'having,' etc., are intended to indicate the existence of the features, numbers, steps, actions, components, parts, or combinations thereof disclosed in the specification, and are not intended to preclude the possibility that one or more other features, numbers, steps, actions, components, parts, or combinations thereof may exist or may be added. Also, the terms, such as 'unit' or 'module', etc., should be understood as a unit that processes at least one function

or operation and that may be embodied in a hardware manner, a software manner, or a combination of the hardware manner and the software manner.

[0023] Throughout the specification, the term "ultrasound image" refers to an image of an object obtained by using an ultrasound. The term 'object' may be understood to be a part of a human body. For example, the object may be an organ, such as the liver, the heart, or the womb, or a fetus.

[0024] Throughout the specification, the term 'user' may be a medical professional, e.g., a doctor, a nurse, a clinical pathologist, or a medical imaging professional, but is not limited thereto.

[0025] In the following detailed description, only certain exemplary embodiments of the present invention have been shown and described, simply by way of illustration. As those of ordinary skill in the art would realize, the described embodiments may be modified in various different ways, all without departing from the spirit or scope of the present invention. Accordingly, the drawings and description are to be regarded as being illustrative in nature and not restrictive. Also, in the drawings, elements that are not related to the description are not illustrated to clearly describe the present invention, and throughout the specification, like elements are denoted by like reference numerals.

[0026] FIG. 1 is a block diagram of a structure of an ultrasound apparatus 100 according to an embodiment of the present invention.

[0027] The ultrasound apparatus 100 according to the present embodiment of the present invention refers to a device that obtains an ultrasound image of an object by using ultrasound, and displays the obtained ultrasound image to a user. An ultrasound image according to an embodiment of the present invention may be an image that is generated in at least one mode selected from a brightness mode (B mode), a color mode (C mode), a motion mode (M mode), a pulsed-wave (PW) mode, a continuous wave (CW) mode, a two-dimensional (2D) mode, and a three-dimensional (3D) mode.

[0028] The ultrasound apparatus 100 may be embodied in various forms. For example, the ultrasound apparatus 100 described in the present specification may be implemented in a mobile terminal as well as a fixable terminal. Examples of the mobile terminal may include a laptop computer, a personal digital assistant (PDA), a tablet personal computer (PC), and the like.

[0029] According to an embodiment of the present invention, the ultrasound apparatus 100 may include a probe 110, a display unit 120, an image processor 130, and a controller 140. However, the elements of FIG. 1 are not indispensable elements. The ultrasound apparatus 100 may include a greater number of elements or a lesser number of elements.

[0030] The probe 110 may transmit an ultrasound signal to an object, and may receive an ultrasound echo signal from the object. The probe 110 may be at least one selected from 1D (dimension), 1.5D, 2D (matrix), and

3D probes. The probe 110 according to an embodiment of the present invention is described below in detail with reference to FIG. 2.

[0031] The display unit 120 may display and output information processed by the ultrasound apparatus 100. For example, the display unit 120 may display a 3D ultrasound image of the object. The 3D ultrasound image according to an embodiment of the present invention may be formed based on volume data.

[0032] The volume data refers to a data set based on voxels that are consecutive 2D slices. In this regard, like a pixel that is a unit of a 2D image, a voxel is a unit of a 3D image, and has a density value.

[0033] According to an embodiment of the present invention, the display unit 120 may display on a 3D ultrasound image a cut line or cut surface which are used to view a 2D cross-section of the 3D ultrasound image in an oblique mode. In this regard, the display unit 120 may also display a 2D ultrasound image corresponding to the cut line or the cut surface. A 2D ultrasound image corresponding to the cut line or the cut surface according to an embodiment of the present invention may vary in real time according to the location of the cut line or the cut surface.

[0034] Also, the 2D ultrasound image corresponding to the cut line or the cut surface may be displayed together with the 3D ultrasound image. In this regard, in a 3D image mode, the 3D ultrasound image may be displayed in a larger region than the 2D ultrasound image.

[0035] The display unit 120 may display a captured 2D ultrasound image. If there are a plurality of captured images, the display unit 120 may display the captured images on a single screen.

[0036] According to the present invention, when a mode conversion command for converting a 3D image mode into a 2D image mode is received, the display unit 120 displays a 2D ultrasound image corresponding to a location of the probe 110 in a 2D image mode. That is, the display unit 120 displays a 2D ultrasound image corresponding to the location of the probe 100 in real time based on the mode conversion command. In this regard, the display unit 120 may enlarge the 2D ultrasound image displayed in the 3D image mode and may display the enlarged image in the 2D image mode.

[0037] Also, the display unit 120 may display, in the 2D image mode, a 2D ultrasound image on a first region, and a 3D ultrasound image on which a location corresponding to the 2-dimensional ultrasound image displayed on the first region is marked on a second region. According to an embodiment of the present invention, the first region may be wider than the second region.

[0038] When the display unit 120 and a touch pad constitute a layer structure and thus form a touch screen, the display unit 120 may be used as an input apparatus as well as an output apparatus. The display unit 120 may include at least one selected from a liquid crystal display (LCD), a thin film transistor-liquid crystal display (TFT-LCD), an organic light-emitting diode (OLED), a flexible

display, and a 3D display.

[0039] The image processor 130 may generate a 2D ultrasound image or 3D ultrasound image of an object by using ultrasound echo signals obtained by using the probe 110. Also, the image processor 130 changes the location of the cut line or cut surface marked on the 3D ultrasound image based on motion information about the probe 110 detected by a sensor.

[0040] The controller 140 controls the probe 110, the display unit 120, and the image processor 130. The controller 140 may capture a 2D ultrasound image corresponding to the cut line or cut surface based on an input of a user.

[0041] Also, the controller 140 executes various modes. For example, the controller 140 may execute a 2D image mode, a 3D image mode, an oblique mode, or the like. A 2D image mode is a mode in which a 2D ultrasound image of an object is displayed. A 3D image mode is a mode in which volume data about the object is obtained and a corresponding 3D ultrasound image is displayed based on the obtained volume data. An oblique mode is a mode for displaying an image of an oblique cross-section obtained by cutting an arbitrary location of a 3D ultrasound image.

[0042] Also, the controller 140 receives a mode conversion command, and converts a mode that is currently executed in the ultrasound apparatus 100.

[0043] The controller 140 receives a command for converting a 3D image mode into a 2D image mode and converts the 3D image mode into the 2D image mode.

[0044] FIG. 2 is a block diagram of a structure of the probe 100 according to an embodiment of the present invention.

[0045] Referring to FIG. 2, the probe 110 may include a transducer 111, a sensor 113, and an input unit 115. However, the elements of FIG. 2 are not indispensable. The probe 110 may include a greater number of elements or a lesser number of elements.

[0046] The transducer 111 may transmit ultrasound signals to an object. Also, the transducer 111 may receive ultrasound echo signals from the object.

[0047] The sensor 113 detects motion information about the probe 110. The sensor 113 according to an embodiment of the present invention may be a tilt sensor, a gyro sensor, a 3-axis magnetic sensor, an acceleration sensor, or the like.

[0048] The motion information about the probe 110 according to an embodiment of the present invention refers to information about a degree of motion of the probe 110 in a 3D space. According to an embodiment of the present invention, the sensor 113 may have a reference location of the probe 110 which has been set in advance. Accordingly, when the probe 110 moves, the sensor 113 may compare the reference location of the probe 110 with a current location thereof and thus detect the motion information.

[0049] The motion information about the probe 110 according to an embodiment of the present invention may

include information about at least one selected from a tilting direction, a tilting angle, a rotational direction, and a rotational angle of the probe 110.

[0050] Also, the sensor 113 may be located inside or outside the probe 110.

[0051] The input unit 115 may generate input data for controlling an operation of the ultrasound apparatus 100 by a user, and may be, for example, a user interface. According to an embodiment of the present invention, the input unit 115 may be located in a button shape on a surface of the probe 110.

[0052] The input unit 115 according to an embodiment of the present invention may include a mode conversion button for executing a mode conversion command between a 2D image mode and a 3D image mode, an image capture button for capturing a displayed image, or the like.

[0053] Hereinafter, a method of providing an ultrasound image by using the respective constituents of the ultrasound apparatus 100, in particular, the probe 110 of the ultrasound apparatus 100 is described in detail below with reference to FIGS. 3 and 5.

[0054] Referring to FIG. 3, a method of providing an ultrasound image according to an embodiment of the present invention includes operations which are processed in time series by the ultrasound apparatus 100 of in FIGS. 1 and 2. Accordingly, even when not described below, if presented with reference to the ultrasound apparatus 100 of FIGS. 1 and 2, the description may also apply to the method of providing an ultrasound image described with reference to FIG. 3.

[0055] FIG. 3 is a flowchart of a method of providing an ultrasound image, according to an embodiment of the present invention.

[0056] The ultrasound apparatus 100 marks a cut line or cut surface on a 3D ultrasound image obtained through the probe 110 (Operation 310). The cut line or the cut surface according to an embodiment of the present invention is used to view an oblique cross-sectional image of the 3D ultrasound image.

[0057] The ultrasound apparatus 100 detects motion information about the probe 110 through the sensor 113 included in the probe 110 (Operation 320). The motion information about the probe 110 according to an embodiment of the present invention may include information about at least one selected from a tilting direction, tilting angle, rotational direction, and rotational angle of the probe 110.

[0058] For example, when a user tilts the probe 110 forward, the sensor 113 may detect a degree of the forward tilting of the probe 110, and may transmit this motion information to the controller 140 or the image processor 130.

[0059] Also, when a user rotates the probe 110 in a clockwise direction, the sensor 113 may detect the rotational angle (for example, 30°) and the rotational direction (clockwise direction), and may transmit the motion information to the controller 140 or the image processor 130.

[0060] Based on the motion information about the probe 110, the ultrasound apparatus 100 changes the location of the cut line or the cut surface (Operation 330). This changing process is described below in detail with reference to FIG. 4.

[0061] For example, as illustrated in FIG. 4A, when a user moves the probe 110 vertically, the ultrasound apparatus 100 may detect the vertical motion of the probe 110 through the sensor 113 included in the probe 110. Accordingly, the ultrasound apparatus 100 may move vertically a cut line or a cut surface marked on a 3D ultrasound image 410.

[0062] Also, as illustrated in FIG. 4B, when a user tilts or rotates the probe 110 laterally, the ultrasound apparatus 100 may detect the lateral motion of the probe 110 through the sensor 113 included in the probe 110. Accordingly, the ultrasound apparatus 100 may move laterally a cut line or a cut surface marked on a 3D ultrasound image 420.

[0063] That is, according to an embodiment of the present invention, a user may obtain an ultrasound image by using the probe 110 and may display the ultrasound image, and then, without manipulating a control panel, the user may control a cut line or cut surface on a 3D ultrasound image by moving the probe 110.

[0064] FIG. 5 is a flowchart of a method of providing an ultrasound image, according to another embodiment of the present invention. Referring to FIG. 5, a method of providing an ultrasound image according to an embodiment of the present invention includes operations which are processed in time series in the ultrasound apparatus 100 of in FIGS. 1 and 2. Accordingly, even when not described below, if presented with reference to the ultrasound apparatus 100 of FIGS. 1 and 2, the description may also apply to the method of providing an ultrasound image described with reference to FIG. 5.

[0065] According to an embodiment of the present invention, the ultrasound apparatus 100 may execute a 3D image mode (Operation 510). In this regard, the ultrasound apparatus 100 may obtain a 3D ultrasound image and may display the 3D ultrasound image together with a cut line or a cut surface. Also, the ultrasound apparatus 100 may display a 2D ultrasound image corresponding to the cut line or the cut surface (Operation 520).

[0066] A user may change the location of the cut line or the cut surface by tilting or rotating the probe 110 vertically or laterally. In this regard, according to motion information about the probe 110, a 2D ultrasound image on display may change in real time.

[0067] A user may identify a 2D ultrasound image which changes according to the change in the location of the cut line or cut surface. As soon as a 2D ultrasound image the user wants to view is displayed, the user fixes the location of the probe 110, and then inputs a command for conversion into a 2D image mode. In this regard, the ultrasound apparatus 100 may convert a 3D image mode into a 2D image mode based on the 2D image mode conversion command (Operation 530). By doing so, the

user may easily determine a location of the probe 110 which is appropriate for obtaining a 2D ultrasound image the user wants to view.

[0068] According to the present invention, the mode conversion command is input by using a button included in the probe 110.

[0069] According to an embodiment of the present invention, the ultrasound apparatus 100 may, in the 2D image mode, display a 2D ultrasound image on the first region (Operation 540). Also, the ultrasound apparatus 100 may display on the second region a 3D ultrasound image on which a location corresponding to the 2D ultrasound image is marked (Operation 550). The 3D ultrasound image on which a location corresponding to the 2D ultrasound image is marked according to an embodiment of the present invention may be displayed as an icon.

[0070] According to an embodiment of the present invention, the ultrasound apparatus 100 may receive a capture command with respect to a 2D ultrasound image (Operation 560). According to an embodiment of the present invention, a user may input a capture command by using either a button included in the probe 110 or a control panel of the ultrasound apparatus 100.

[0071] In this regard, the ultrasound apparatus 100 may capture a 2D ultrasound image and may display the captured image (Operation 570). According to an embodiment of the present invention, the ultrasound apparatus 100 may capture a plurality of 2D ultrasound images. That is, a user may capture a plurality of 2D ultrasound images obtained by changing the location of the cut line or the cut surface.

[0072] FIG. 6 is a diagram for explaining how an ultrasound image is provided in a 3-dimensional image mode according to an embodiment of the present invention.

[0073] Referring to FIG. 6, in a 3D image mode according to an embodiment of the present invention, a 3D ultrasound image 610, a 2D ultrasound image 620, and a capture image 630 may be displayed. In the 3D image mode according to an embodiment of the present invention, a 3D ultrasound image is displayed in the largest region.

[0074] A cut line or cut surface is marked on the 3D ultrasound image 610 according to the present invention. The 2D ultrasound image 620 according to an embodiment of the present invention may be an oblique cross-sectional image corresponding to the cut line or the cut surface on the 3D ultrasound image 610. The capture image 630 according to an embodiment of the present invention may include a plurality of 2D ultrasound images which are captured by a user.

[0075] The capture image 630 according to an embodiment of the present invention may be sequentially arranged according to time, or may be categorized according to a degree of relationship of images and displayed correspondingly. Alternatively, the capture image 630 may be displayed randomly.

[0076] FIG. 7 is a diagram for explaining how an ultra-

sound image is provided in a 2D image mode according to an embodiment of the present invention.

[0077] Referring to FIG. 7, in a 2D image mode according to an embodiment of the present invention, the ultrasound apparatus 100 may display a 2D ultrasound image 710 and a 3D ultrasound image 720 on which the location corresponding to the 2D ultrasound image 710 is marked. The 2D ultrasound image 710 in the 2D image mode may be displayed in a wider region than the 2D ultrasound image 620 in the 3D image mode.

[0078] According to an embodiment of the present invention, a user may determine the location of the cut line or the cut surface by moving the probe 110 as soon as an ultrasound image is obtained. Accordingly, the location of the probe 110 that corresponds to a 2D ultrasound image on display may be continuously identified. Accordingly, when the user needs to obtain another ultrasound image, the user may easily determine the location of the probe 110.

[0079] Embodiments of the present invention include a computer-readable recording medium including program commands for executing operations implemented through various computers. The computer-readable recording medium can store program commands, data files, data structures, or combinations thereof. The program commands recorded in the computer-readable recording medium may be specially designed and configured for the present invention or be known to those of ordinary skill in the field of computer software. Examples of a computer-readable recording medium include magnetic media such as hard disks, floppy disks, and magnetic tapes, optical media such as CD-ROMs and DVDs, magneto-optical media such as floptical disks, or hardware devices such as ROMs, RAMs, and flash memories, which are specially configured to store and execute program commands. Examples of the program commands include a machine language code created by a compiler and a high-level language code executable by a computer using an interpreter and the like.

[0080] While the present invention has been particularly shown and described with reference to exemplary embodiments thereof, it will be understood by those of ordinary skill in the art that various changes in form and details may be made therein without departing from the scope of the present invention as defined by the following claims.

Claims

1. A method of providing an ultrasound image, the method comprising:

marking a cut line or a cut surface on a 3-dimensional (3D) ultrasound image (610) of an object which is obtained by using a probe (110), wherein the cut line or the cut surface are used to view a cross section of the 3D ultrasound image

- (610);
 detecting motion information about the probe (110) by using a sensor (113) included in the probe (110); and
 changing a location of the cut line or the cut surface based on the detected motion information about the probe (110);
 displaying a 2-dimensional (2D) ultrasound image (620) corresponding to the changed location of the cut line or the cut surface;
characterised in
 receiving a mode conversion command for converting a 3D image mode into a 2D image mode through a button included in the probe (110); and
 displaying a 2D ultrasound image (710) corresponding to a location of the probe (110) based on the mode conversion command in real time.
2. The method of claim 1, further comprising capturing the displayed 2D ultrasound image (620) corresponding to the changed location of the cut line or the cut surface.
 3. The method of claim 1, wherein the displaying of the 2D ultrasound image (710) in real time further comprises:
 - displaying the 2D ultrasound image (710) corresponding to the location of the probe (110) on a first region; and
 - displaying on a second region a 3D ultrasound image (720) on which a location corresponding to the 2D ultrasound image (710) displayed on the first region is marked.
 4. The method of claim 1, wherein the motion information comprises information about at least one selected from a tilting direction, tilting angle, rotational direction, and rotational angle of the probe (110).
 5. The method of claim 1, wherein the sensor (113) comprises at least one selected from a tilt sensor, a gyro sensor, a 3-axis magnetic sensor, and an acceleration sensor.
 6. An ultrasound apparatus (100) comprising:
 - a probe (110) comprising a sensor (113) configured for detecting motion information and a button configured for receiving an input of a mode conversion command for converting a 3D image mode into a 2D image mode;
 - a display unit (120) configured for marking a cut line or a cut surface on a 3D ultrasound image (610) of an object which is obtained by using the probe (110) to view across section of the 3D ultrasound image (610);
 - an image processor (130) configured for changing a location of the cut line or the cut surface, based on motion information of the probe (110) detected by using the sensor (113); and
 - a controller (140) configured for controlling the probe (110), the display unit (120), and the image processor (130),
 wherein the display unit (120) is configured to display a 2D ultrasound image (620) corresponding to the changed location of the cut line or the cut surface,
 7. The ultrasound apparatus (100) of claim 6, wherein the controller (140) is configured to capture the displayed 2D ultrasound image (620) corresponding to the changed location of the cut line or surface. wherein the controller (140) is configured to receive the mode conversion command for converting the 3D image mode into the 2D image mode through the button, and the display unit (120) is configured to display a 2D ultrasound image (710) corresponding to a location of the probe (110), based on the mode conversion command, in real time.
 8. The ultrasound apparatus (100) of claim 6, wherein the display unit (120) is configured to display, in the 2D image mode, the 2D ultrasound image (710) corresponding to the location of the probe (110) on a first region, and a 3D ultrasound image (720) on which a location corresponding to the 2D ultrasound image (710) displayed on the first region is marked on a second region.
 9. A computer readable recording medium having recorded thereon a program for executing the method of claim 1.

Patentansprüche

1. Verfahren zum Erzeugen eines Ultraschallbilds, wobei das Verfahren Folgendes aufweist:

Markieren einer Schnittlinie oder einer Schnittfläche auf einem 3-dimensionalen (3D) Ultraschallbild (610) eines Gegenstands, die durch Verwenden eines Prüfkopfs (110) erlangt wird, wobei die Schnittlinie oder die Schnittfläche verwendet werden, um einen Querschnitt des 3D-Ultraschallbilds (610) zu betrachten;
 Detektieren von Bewegungsinformationen bezüglich des Prüfkopfs (110) durch Verwenden eines in dem Prüfkopf (110) enthaltenen Sensors (113); und
 Ändern einer Position der Schnittlinie oder der Schnittfläche basierend auf den detektierten Bewegungsinformationen bezüglich des Prüfkopfs (110);

- Anzeigen eines 2-dimensionalen (2D) Ultraschallbilds (620) entsprechend der geänderten Position der Schnitlinie oder der Schnittfläche; **gekennzeichnet durch**
- Empfangen eines Moduskonvertierungsbefehls zum Konvertieren eines 3D-Bildmodus in einen 2D-Bildmodus **durch** einen in dem Prüfkopf (110) enthaltenen Knopf; und
- Anzeigen eines 2D-Ultraschallbilds (710) entsprechend einer Position des Prüfkopfs (110) basierend auf dem Moduskonvertierungsbefehl in Echtzeit.
2. Verfahren nach Anspruch 1, welches des Weiteren das Erfassen des angezeigten 2D-Ultraschallbilds (620) entsprechend der geänderten Position der Schnitlinie oder der Schnittfläche aufweist.
3. Verfahren nach Anspruch 1, wobei das Anzeigen des 2D-Ultraschallbilds (710) in Echtzeit Folgendes aufweist:
- Anzeigen des 2D-Ultraschallbilds (710) entsprechend der Position des Prüfkopfs (110) auf einem ersten Bereich; und
- Anzeigen eines 3D-Ultraschallbilds (720) auf einem zweiten Bereich, auf dem eine dem auf dem ersten Bereich angezeigten 2D-Ultraschallbild (710) entsprechende Position markiert wird.
4. Verfahren nach Anspruch 1, wobei die Bewegungsinformationen Informationen über wenigstens eines aufweisen, das aus einer Neigungsrichtung, einem Neigungswinkel, einer Rotationsrichtung und einem Rotationswinkel des Prüfkopfs (110) ausgewählt ist.
5. Verfahren nach Anspruch 1, wobei der Sensor (113) wenigstens einen aufweist, der aus einem Neigungssensor, einem Gyrosensor, einem 3-Achsen-Magnetsensor und einem Beschleunigungssensor ausgewählt ist.
6. Ultraschallvorrichtung (100), welche Folgendes aufweist:
- einen Prüfkopf (110), der einen Sensor (113), der zum Detektieren von Bewegungsinformationen ausgebildet ist, und einen Knopf aufweist, der zum Empfangen einer Eingabe eines Moduskonvertierungsbefehls zum Konvertieren eines 3D-Bildmodus in einen 2D-Bildmodus ausgebildet ist;
- eine Anzeigeeinheit (120), die dafür vorgesehen ist, eine Schnitlinie oder eine Schnittfläche auf einem 3D-Ultraschallbild (610) eines Gegenstands zu markieren, die durch Verwenden des Prüfkopfs (110) erlangt wird, um einen Querschnitt des 3D-Ultraschallbilds (610) zu betrach-

ten;

einen Bildprozessor (130), der dafür vorgesehen ist, eine Position der Schnitlinie oder der Schnittfläche basierend auf Bewegungsinformationen des Prüfkopfs (110) zu ändern, die unter Verwendung des Sensors (113) detektiert wurden; und

einen Controller (140), der dafür vorgesehen ist, den Prüfkopf (110), die Anzeigeeinheit (120) und den Bildprozessor (130) zu steuern, wobei die Anzeigeeinheit (120) dafür vorgesehen ist, ein 2D-Ultraschallbild (620) entsprechend der geänderten Position der Schnitlinie oder der Schnittfläche anzuzeigen, wobei der Controller (140) dafür vorgesehen ist, den Moduskonvertierungsbefehl zum Konvertieren des 3D-Bildmodus in den 2D-Bildmodus durch den Knopf zu empfangen, und die Anzeigeeinheit (120) dafür vorgesehen ist, ein 2D-Ultraschallbild (710) entsprechend einer Position des Prüfkopfs (110) basierend auf dem Moduskonvertierungsbefehl in Echtzeit anzuzeigen.

7. Ultraschallvorrichtung (100) nach Anspruch 6, wobei der Controller (140) dafür vorgesehen ist, das angezeigte 2D-Ultraschallbild (620) entsprechend der geänderten Position der Schnitlinie oder der Schnittfläche zu erfassen.
8. Ultraschallvorrichtung (100) nach Anspruch 6, wobei die Anzeigeeinheit (120) dafür vorgesehen ist, in dem 2D-Bildmodus das 2D-Ultraschallbild (710) entsprechend der Position des Prüfkopfs (110) auf einem ersten Bereich und ein 3D-Ultraschallbild (720), auf dem eine dem auf dem ersten Bereich angezeigten 2D-Ultraschallbild (710) entsprechende Position auf einem zweiten Bereich markiert ist, anzuzeigen.
9. Computerlesbares Aufzeichnungsmedium, auf dem ein Programm zur Durchführung des Verfahrens nach Anspruch 1 aufgezeichnet ist.

Revendications

1. Procédé pour générer une image ultrasonique, ce procédé consistant à:
- former une ligne de coupe ou une surface de coupe sur une image ultrasonique (610) tridimensionnelle (3D) d'un objet qui est obtenue par l'utilisation d'une sonde (110), dans lequel la ligne de coupe ou la surface de coupe sont utilisées pour visualiser une section transversale de l'image ultrasonique (610) en (3D);
- détecter une information de mouvement relative à la sonde (110) en utilisant un capteur (113) comportant la sonde (110); et

- modifier une localisation de la ligne de coupe ou de la surface de coupe sur la base de l'information de mouvement détecté, relative à la sonde (110);
- afficher une image ultrasonique (620) bidimensionnelle (2D) correspondant au changement de localisation de la ligne de coupe ou de la surface de coupe; 5
- caractérisé en ce qu'on reçoit une commande de mode de conversion pour convertir un mode image 3D en un mode image 2D au moyen d'un bouton inclus dans la sonde (110); et** 10
- afficher une image ultrasonique (710) en 2D correspondant à une localisation de la sonde (110) sur la base de la commande du mode de conversion en temps réel. 15
2. Procédé selon la revendication 1, comprenant en outre la capture de l'image ultrasonique affichée (620) en 2D correspondant à la localisation modifiée de la ligne de coupe ou de la surface de coupe. 20
3. Procédé selon la revendication 1, dans lequel l'affichage de l'image ultrasonique (710) en 2D en temps réel, comprend en outre : 25
- l'affichage de l'image ultrasonique (710) en 2D correspondant à la localisation de la sonde (110) dans une première zone; et
- l'affichage dans une seconde zone d'une image ultrasonique (720) en 3D sur laquelle est marquée une localisation correspondant à une image ultrasonique (710) en 2D affichée dans la première zone. 30
4. Procédé selon la revendication 1, dans lequel l'information de mouvement comprend des informations sélectionnées relatives à au moins une direction inclinée, un angle aigu, une direction de rotation et un angle de rotation de la sonde (110). 35
5. Procédé selon la revendication 1, dans lequel le capteur (113) comporte au moins un des capteurs sélectionnés parmi un capteur d'inclinaison, un capteur de rotation, un capteur magnétique à trois axes et un accéléromètre. 40
6. Appareil ultrasonique (100) comportant :
- une sonde (110) comprenant un capteur (113) configuré pour détecter une information de mouvement et un bouton configuré pour recevoir un signal d'une commande de conversion de mode pour convertir une image en mode 3D en une image en mode 2D ; 50
- une unité d'affichage (120) configurée pour marquer une ligne de coupe ou une surface de coupe sur une image ultrasonique (610) en 3D d'un 55
- objet qui est obtenue par l'utilisation d'une sonde (110), pour visualiser une section transversale de l'image ultrasonique (610) en 3D;
- un processeur d'image (130) configuré pour détecter un changement de localisation de la ligne de coupe ou de la surface de coupe, sur la base de l'information de mouvement de la sonde (110) détectée par l'utilisation du capteur (113); et
- un contrôleur (140) configuré pour contrôler la sonde (110), l'unité d'affichage (120) et le processeur d'image (130), dans lequel l'unité d'affichage (120) est configurée pour afficher une image ultrasonique (620) en 2D correspondant au changement de localisation de la ligne de coupe ou de la surface de coupe, dans lequel le contrôleur (140) est configuré pour recevoir la commande de conversion de mode pour convertir un mode image en 3D dans le mode image 2D par le bouton, et l'unité d'affichage (120) est configurée pour afficher une image ultrasonique (710) en 2D, correspondant à la localisation de la sonde (110), sur la base de la commande de conversion de mode, en temps réel.
7. Appareil ultrasonique (100) selon la revendication 6, dans lequel le contrôleur (140) est configuré pour saisir l'image ultrasonique affichée (620) en 2D, correspondant à la localisation modifiée de la ligne de coupe ou la surface de coupe.
8. Appareil ultrasonique (100) selon la revendication 6, dans lequel l'unité d'affichage (120) est configurée pour afficher, en mode image 2D, l'image ultrasonique (710) correspondant à la localisation de la sonde (110) dans une première zone, et une image ultrasonique (720) en 3D sur laquelle une localisation correspondant à l'image ultrasonique (710) en 2D affichée dans la première zone est marquée dans une seconde zone.
9. Support lisible sur un ordinateur portant sous une forme enregistrée, un programme pour exécuter le procédé selon la revendication 1.

FIG. 1

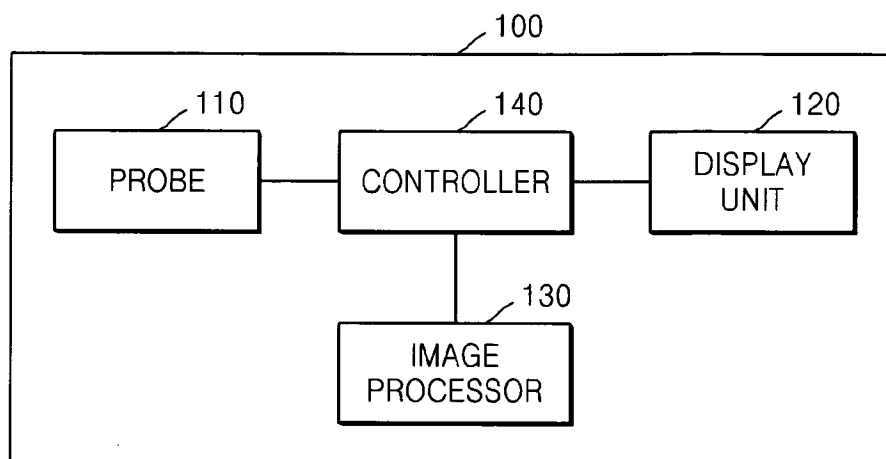


FIG. 2

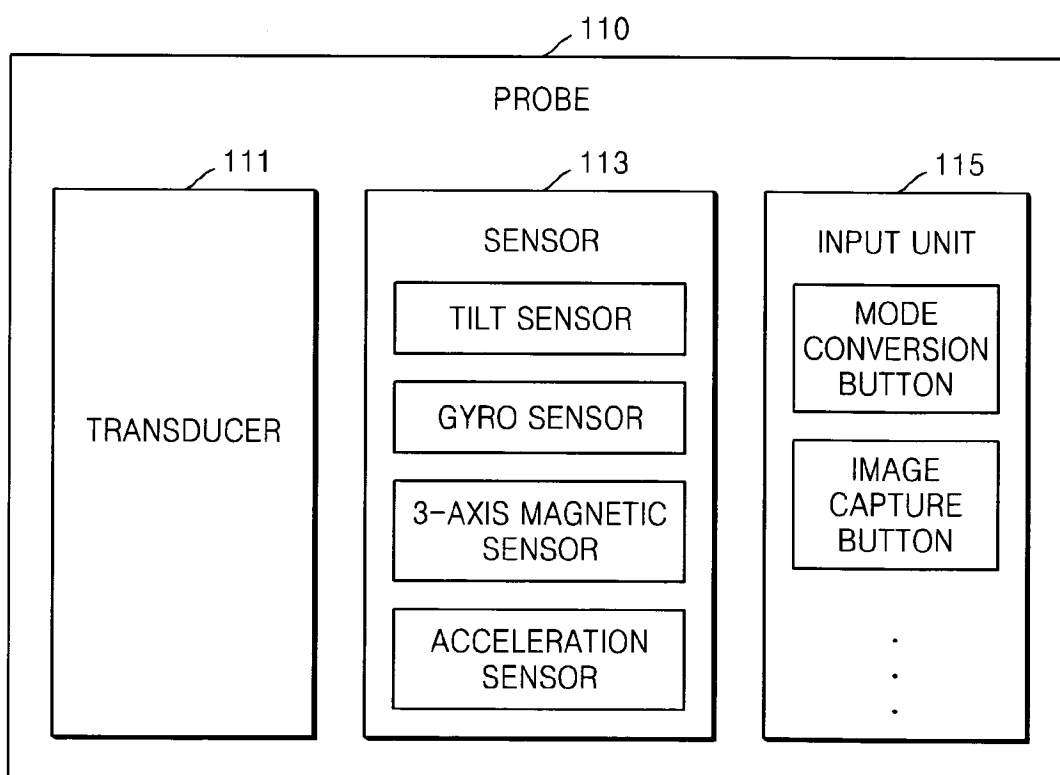


FIG. 3

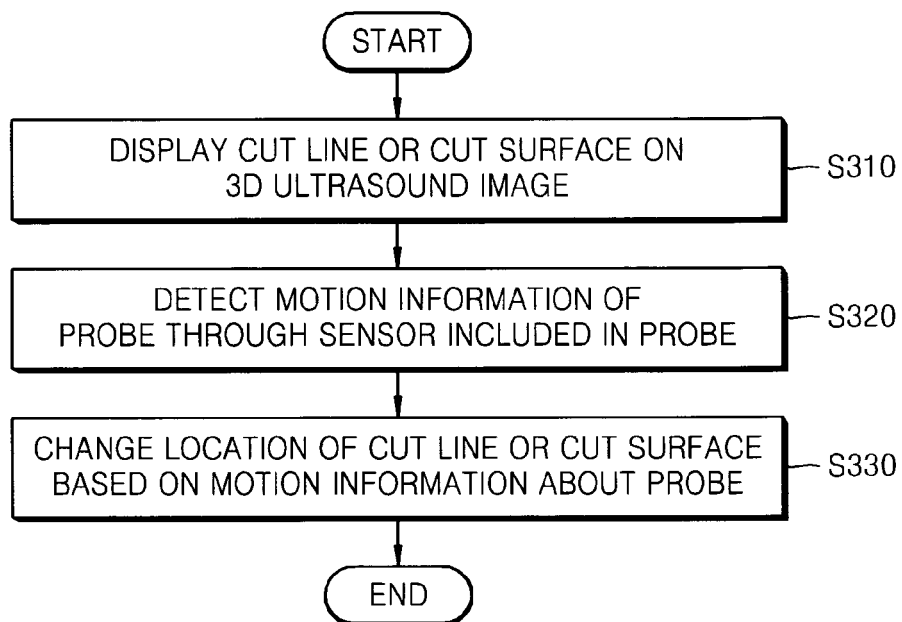


FIG. 4

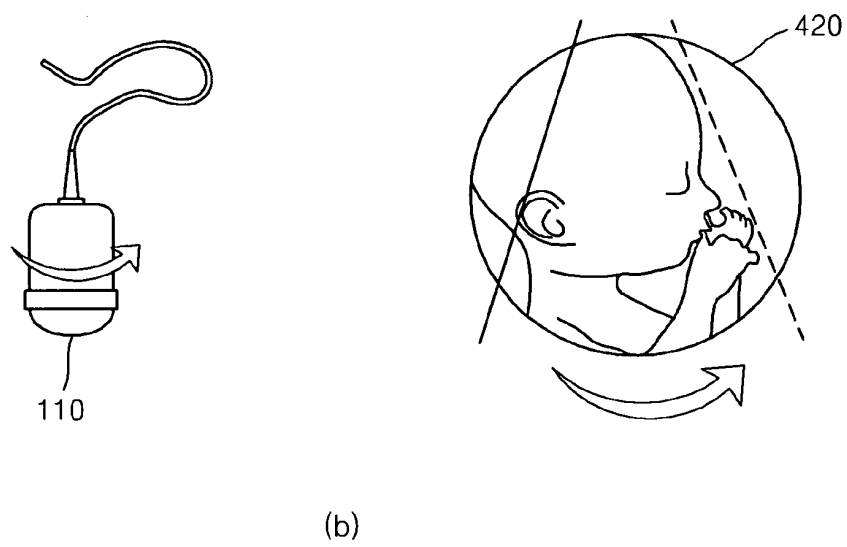
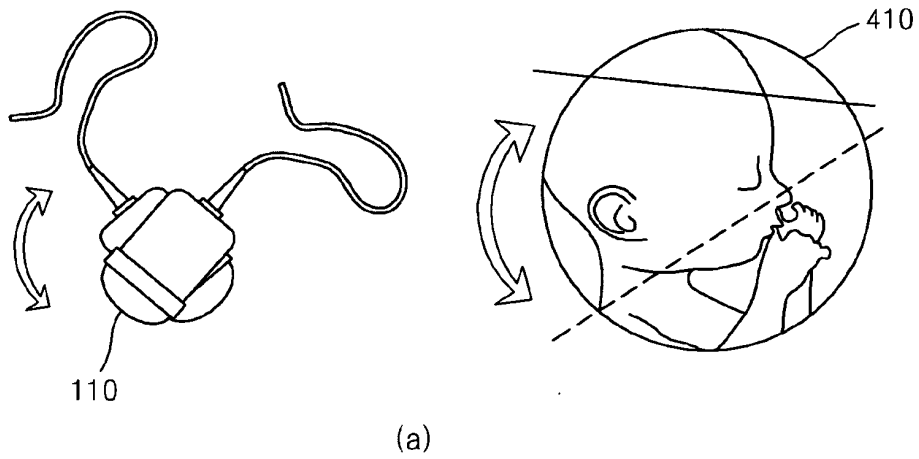


FIG. 5

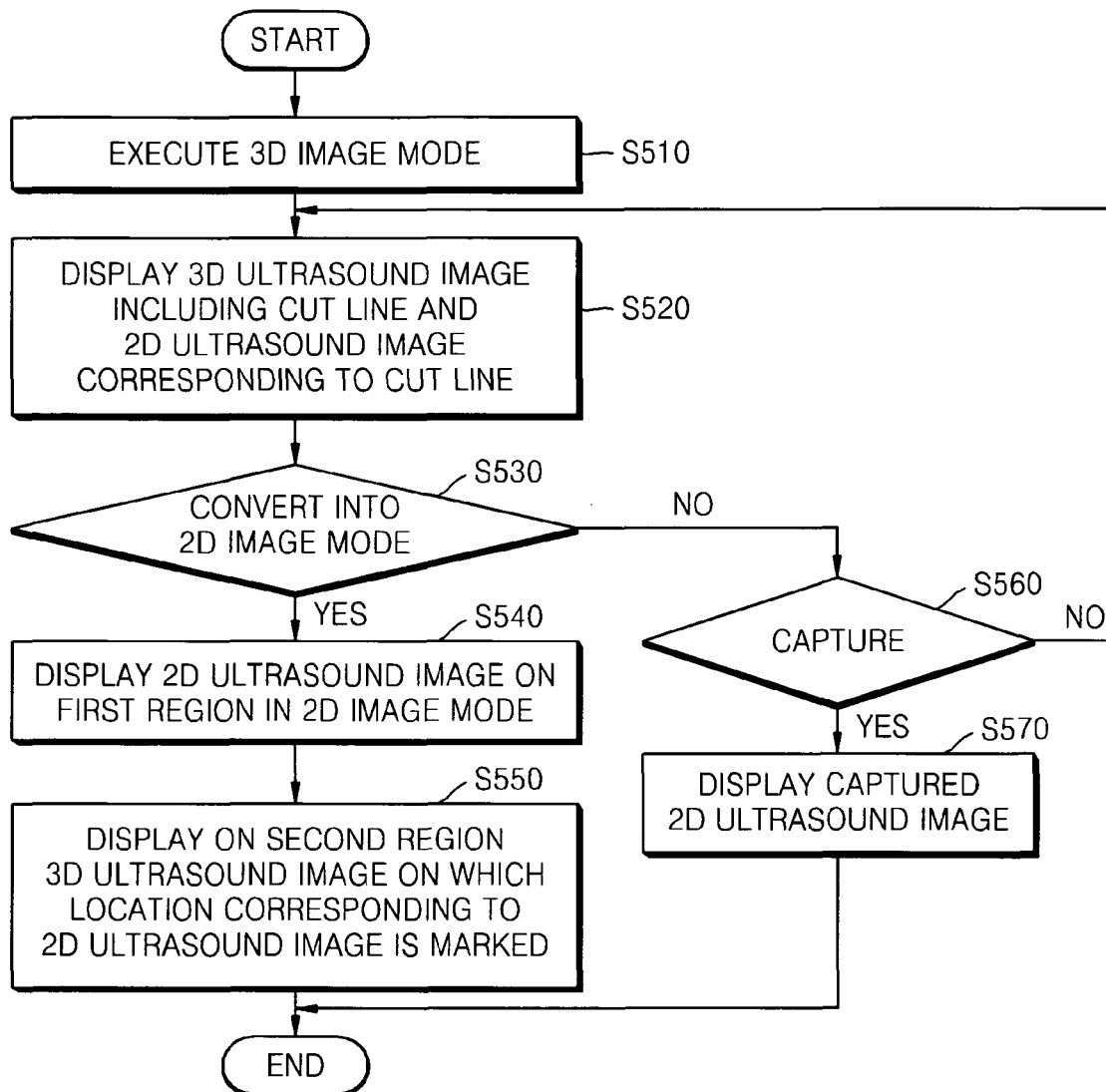


FIG. 6

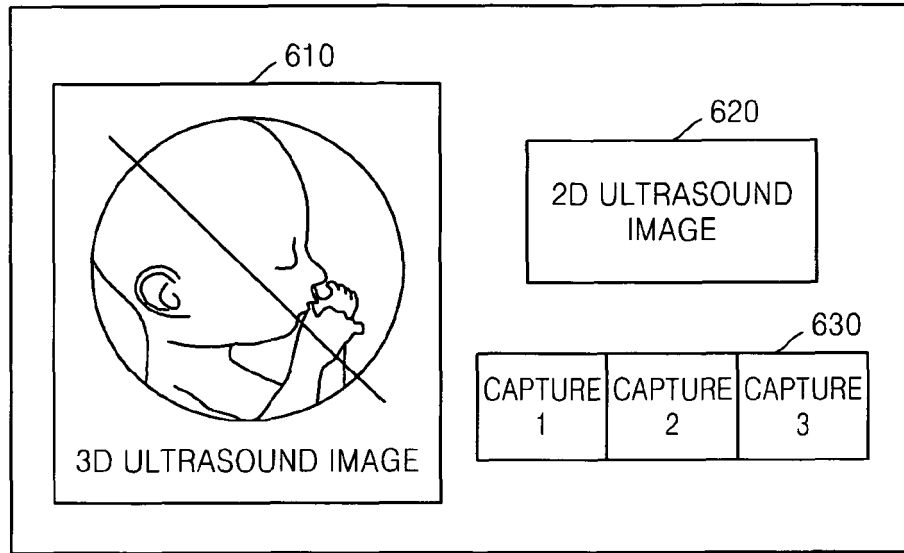
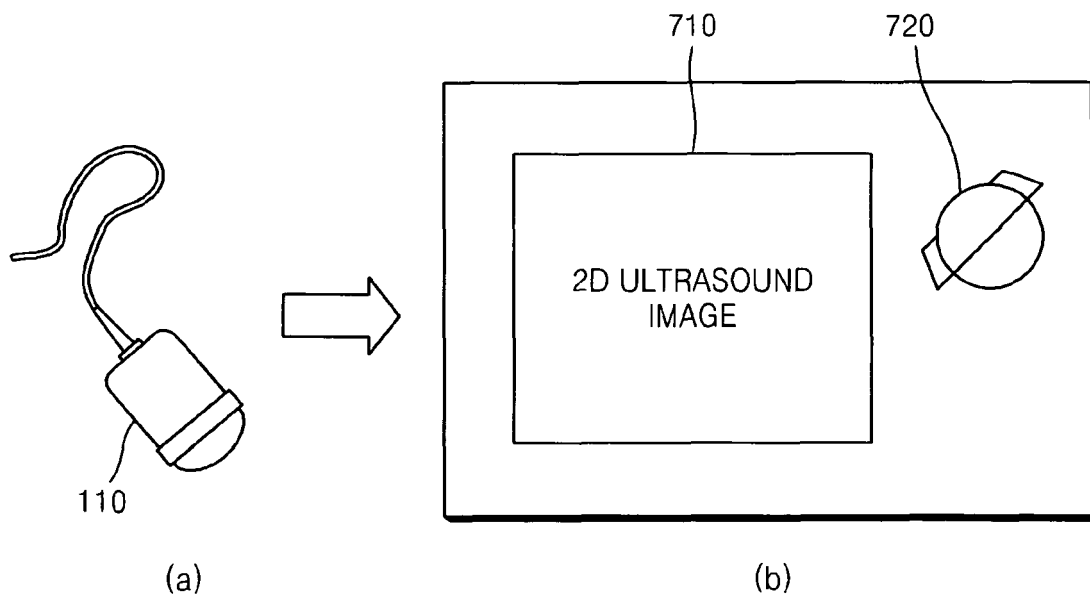


FIG. 7



REFERENCES CITED IN THE DESCRIPTION

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Patent documents cited in the description

- US 20110306025 A [0007]

专利名称(译)	用于提供超声图像的方法和超声设备		
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摘要(译)

一种提供超声图像的方法，该方法包括：在通过使用探针获得的物体的三维（3D）超声图像上标记切割线或切割表面，其中切割线和切割表面是用于观看3D超声图像的横截面；通过使用探头中包括的传感器检测关于探头的运动信息；并且基于检测到的关于探针的运动信息改变切割线或切割表面的位置。

FIG. 1

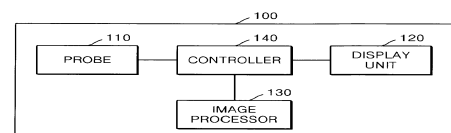


FIG. 2

