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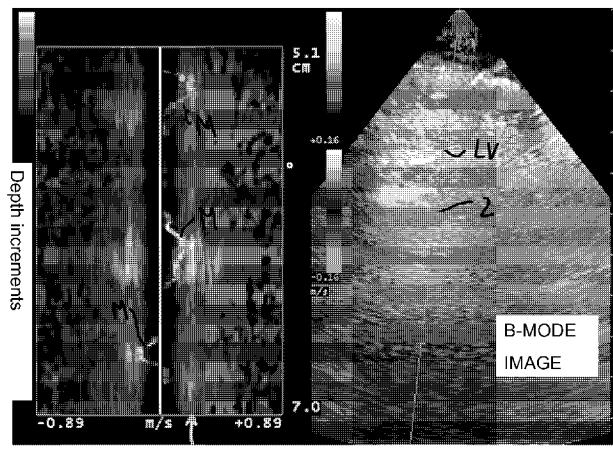


Fig. 1

(57) Abstract: A method for ultrasonic detection and imaging of hemodynamic information, particularly venous blood flow information, which method comprises the steps of: transmitting ultrasonic pulses into a body under examination, which pulses are generated by an array of electro-acoustic transducers arranged according to a predetermined order and design; receiving reflected pulses resulting from the reflection of transmit pulses by an array of receiving electro-acoustic transducers, which generate receive signals upon stimulation of pulses reflected from the body under examination; said succession of pulses transmitted to the body under examination and/or pulses received from the body under examination being focused along one or more scan lines; generating at least one Doppler frequency shift signal resulting from the reflection of pulses transmitted by a blood flow into a vessel intersected by said scan line, in at least one point and along at least said scan line, or along a direction of propagation of a pulse; determining the direction of blood flow velocity in at least said point from the average frequency value of the spectrum of Doppler shift frequencies and displaying said direction of blood flow velocity by graphical and/or chromatic representation differentiating opposite directions.

Method and apparatus for ultrasonic detection and imaging of hemodynamic information, particularly venous blood flow information

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The present invention relates to a method for ultrasonic detection and imaging of hemodynamic information, particularly venous blood flow information, which method comprises the steps of 10 acquiring and displaying Doppler data from a subject under study in an ultrasound system,

Ultrasound beams for non invasively detecting velocity information of moving reflectors in a body under study is a well known technique. Several 15 alternative ways are known and currently used for determining the velocity of a scatterer from the frequency or phase shift which affects a back-scattered ultrasound beam according to the Doppler effect.

20 One of these method is the so called Multigate Doppler processing method this method comprising the steps of:

- a) transmitting ultrasound waves into the subject under study;
- 25 b) generating back-scattered signals in response to the ultrasound waves back-scattered from the subject under study;
- c) generating a plurality of Doppler signal samples representing a predetermined range of depth 30 increments within said subject in response to said back-scattered signals;
- d) generating a plurality of Doppler frequency signals representing said predetermined range of

depth increments in response to said Doppler signal samples;

5 e) displaying a first Doppler graph representing said Doppler frequency along a first axis and said range of depth increments along a second axis in response to said Doppler frequency signals;

Indeed Multigate Doppler processing is a particular PW Doppler technique which allows to divide in a predefined range several smaller sample 10 volumes corresponding to a certain number of successive depths increments along a transmitted beam a bigger sample volume (gate) within a subject under study in which Doppler frequency shift profile has to be determined. Doppler frequency profiles as a 15 function of the said depths increments means the velocity profiles of moving particles within the said succession of smaller sample volumes. The processing of the Doppler signal samples backscattered from the subject at each of the said smaller samples volumes, 20 i.e. the depths increments is carried out essentially in parallel.

Concerning the above equivalence between sample volumes and depth increment along a transmitted beam this is due to the fact that in order to acquire 25 Doppler data with a PW technique a pulsed ultrasound beam has to propagate along a certain direction preferably at an angle relatively to the direction of motion of the reflectors.

A number of further different methods for 30 ultrasonic detection of hemodynamic information are known and widely used in the art, which allow determination of the average Doppler shift frequency and hence the average blood flow velocity in a

predetermined point or the spectral representation of Doppler shifts in a predetermined point and show the distribution of the velocities of the blood particles of said flow in said point.

5 A method commonly known as CFM (Color Flow Mapping), which is used for determining the average Doppler shift frequency and hence the average velocity of a blood flow, consists in determining, for a predetermined point at one vessel, the mean of  
10 the spectral distribution of Doppler shift frequencies of ultrasonic pulses in said point. As an acquisition and processing method, CFM is known and widely used. See for instance US 5,246,006. The ultrasonic signals are transmitted, received and  
15 processed to detect, for predetermined points along a predetermined scan line, the average spectrum frequency value in said point. Said average frequency is an estimate of the average displacement velocity of the reflector that moves through said point and  
20 hence of blood flowing through said point.

The visual result of the CFM method includes indication of the flow direction by one of two different colors, each being uniquely associated with one of the two directions, towards and away from the probe. Furthermore, the hue of said color indicates the intensity of the signal and hence the flow and/or  
25 the modulus of the average velocity.

As a rule, at the same time as Doppler processing of ultrasonic signals a morphological (anatomic) image is also generated along a scan plane in the so-called B-Mode, particularly along a scan plane that contains the scan line/s used for CFM detection. The signals required for generation of the

B-mode image are generally transmitted, received and processed in alternation to transmission, reception and processing of Doppler signals.

Colors are added to the pixels of the B-mode 5 image that coincide with the area or point at which the Doppler frequency shift has been detected.

As well known furthermore since a pulse of finite length is transmitted the pulse will have a certain bandwidth and not only the fundamental 10 frequency. Furthermore within each sample volume (gate) several different kinds of moving reflector can be provided so that the backscattered wave have a certain bandwidth and a certain spectral distribution of the frequencies within the said bandwidth.

15 In addition to the determination of the average velocity value, i.e. the component of the mean frequency of the spectrum of Doppler frequency shifts, Doppler techniques are known in which the whole spectrum of Doppler frequencies associated with 20 a given sample point or volume is extracted. As already indicated above these methods, known as Pulsed Wave (PW) methods require more complex processing of ultrasonic signals, due to the much larger amount of information to be processed as 25 compared with CFM. An extension of the PW technology is the so-called Multigate which includes sequential Doppler spectrum detection through multiple sequential points (known as gates), arranged along a scan line, or a part of it, for reconstructing the 30 velocity profile along said line.

The Multigate method is described in detail in the following documents:

P. Tortoli, G. Manes, C. Atzeni, Velocity profile reconstruction using ultrafast spectral analysis of Doppler ultrasound, *IEEE Transactions on Sonics and Ultrasonics*, Vol. SU 32, N.4, 5 pp.555-561, July 1985.

P. Tortoli, F. Andreuccetti, G. Manes, C. Atzeni, Blood Flow Images by a SAW-Based Multigate Doppler system, *IEEE Transactions on Ultrasonics, Ferroelectrics & Frequency Control*, vol. 35, n. 5, 10 pp.545-551, September 1988.

P. Tortoli, F. Guidi, G. Guidi, C. Atzeni, Spectral velocity profiles for detailed ultrasound flow analysis, *IEEE Trans. on Ultrasonics, Ferroelectrics & Frequency Control*, vol.43, n.4, 15 pp.654-659, July 1996.

An FFT-Based Flow Profiler for High-Resolution In Vivo Investigations, Piero Tortoli et al. *Ultrasound in Med. & Biol.* Vol.23 No.6 pp. 899-910, 1997;

20 US 6,450,959.

Further details of the CFM and PW methods may be found in the following documents:

US 4,913,159, US 4,817,618, US 5,724,974 and WO 01/71376.

25 As shown by the above documents, whose disclosures are incorporated herein by reference, the above techniques have been long known and widely used. The technology known as Multigate or Multigate Spectral Doppler allows quick real-time determination 30 of the spectral profile of Doppler shifts according to the depth of penetration of ultrasonic pulses into the body under examination, with no excessive burden on processing units. The spectra of Doppler

frequencies and/or the corresponding velocities are represented as frequencies or corresponding velocities along a first axis and as depths along a second axis of a Cartesian coordinate system.

5 As clearly shown by the description of the above techniques, all these techniques are based on the Doppler effect and do not allow assessment of the direction of a moving reflector and the direction of the blood flow when the axis of the beam of acoustic  
10 pulses, i.e. the direction of propagation thereof are perpendicular to the displacement direction of the reflector. Indeed the frequency shift according to the Doppler effect depends from the angle of propagation of a beam impinging against a moving  
15 reflector and the function is a cosine which gives a zero factor when the angle of incidence of the beam is 90°.

In PW Doppler in general, and particularly in Multigate technologies the whole frequency content of  
20 the received echo signals corresponding to the back-scattered ultrasound beam by a certain sample volume is determined. When the direction of propagation of ultrasounds is perpendicular to the moving reflector and in the specific case of application of the  
25 present invention to the blood flow direction, the spectral frequency distribution at the sample volume (gate or depth increment) is symmetric with respect to the line that corresponds to the zero Doppler frequency shift and hence to the zero velocity. On  
30 the other hand since in such kind of representation the brightness of the image corresponds to the intensity of the received signal and thus to the number of moving reflectors which are present in a

certain sample volume, in the image displayed in which the Doppler frequency signals of each sample volume are depicted one adjacent to the following sample volume according to the order of sequence of 5 the said sample volumes, using the entire frequency content of the Doppler frequency signals at each sample volume will a better determination of the sample volumes in which the flow is considerable and also the determination of axis of propagation of the 10 flow. On the other hand when the incidence angle of the beam relatively to the flow direction is 90° or approximately 90° it will not be possible to determine the direction of the flow since the Doppler frequency distribution within the spectrum of the 15 Doppler frequency signal is symmetric being composed of specular positive and negative spectral components.

Multigate technology can be used for simultaneously highlighting and imaging multiple 20 vessels at different penetration depths, i.e. at different distances from the origin of the ultrasonic pulses, within the overall range of penetration depth increments of the Multi-gate process.

In short, with prior art technologies, when the 25 displacement direction of the reflector, and hence of a blood flow, is perpendicular to the direction of the axis of propagation of the incident beam of ultrasonic pulses, neither the CFM method, nor the PW, and particularly the Multi-gate method, allow 30 assessment of the blood flow direction.

Otherwise than what it might appear, the above condition in which the displacement direction of the reflector and hence of a blood flow, is perpendicular

to the direction of the axis of propagation of the incident beam of ultrasonic pulses is not a rare condition in diagnostic imaging. For example, in hemodynamic imaging of cerebral vessels in the 5 cranium, there are only a few windows through which the ultrasonic beam can be directed to said vessels. Unfortunately, the direction of the ultrasonic pulse beam is often oriented perpendicular to the flow in said vessels.

10 Furthermore, it is often needed or desired to simultaneously image the flow conditions in adjacent or parallel vessels at different penetration depths of the ultrasonic beam, whereby the direction of the beam axis or the direction of propagation of the 15 acoustic front is fixed and determined by the requirement that all the vessels to be imaged must be intersected thereby.

Further difficulties arise if Doppler imaging is used with venous blood flow. Here, vessels have a 20 small size and the venous blood flow is relatively slow. Furthermore blood flux is not constant but varies according to the heart cycle and to the inspiration expiration cycle, so that for each sample volume the blood flow can vary its velocity from a 25 maximum velocity to nearly zero or even to a negative velocity, i.e. to an opposite flow direction. This has the effect that the frequency signal will pass from a maximum value to a value which can be approximately zero or negative and the displayed 30 signal will blink or even change color in the displayed Doppler graph. The variation of the status of appearance of the pixels in the image representing the value of the frequency signals will change from a

certain color and brightness when a flux is detected, i.e. when there are moving blood particles to a quite black and/or very low brightness status of appearance when the flux is absent or very slow. A particular 5 application in which these conditions occur is simultaneous determination of blood flow characteristics in Galen's vein, middle internal cerebral vein and Rosenthal's vein. The determination of venous blood flow in these veins seems to have a 10 considerable clinical and diagnostic relevance for early diagnosis of multiple sclerosis, as reported in Chronic Cerebrospinal venous insufficiency in patients with multiple sclerosis, Paolo Zamboni et al., J. Neurol. Neurosurg. Psychiatry, 5 Dec. 2008. 15 Now, in this case the cranial windows through which ultrasonic pulses are transmitted for acoustic treatment of the deep regions containing the veins whose blood flow has to be controlled for diagnostic purposes are such that the above unfavorable 20 condition occurs and the direction of blood flows is not currently detectable.

Therefore, the invention is based on the problem of providing a method for detection and imaging of hemodynamic information, particularly venous blood 25 flow information, which allows assessment of blood flow direction even in the most unfavorable conditions, especially in the condition in which the blood flow direction is perpendicular to the axis of the ultrasonic pulse beam transmitted into the body 30 under examination.

A further object of the invention is to ensure the above result without requiring longer times for

Doppler mode acquisition and processing of ultrasonic diagnostic images.

The present invention fulfils the above objects by providing a method for ultrasonic detection and 5 imaging of hemodynamic information, particularly venous blood flow information, as described herein before, which is a method for

for acquiring and displaying Doppler data from a subject under study in an ultrasound system, the said 10 method comprising the following steps:

a) transmitting ultrasound waves into the subject under study;

b) generating back-scattered signals in response to the ultrasound waves back-scattered from the 15 subject under study;

c) generating a plurality of Doppler signal samples representing a predetermined range of depth increments within said subject in response to said back-scattered signals;

20 d) generating a plurality of Doppler frequency signals representing said predetermined range of depth increments in response to said Doppler signal samples;

e) displaying a first Doppler graph representing 25 said Doppler frequency along a first axis and said range of depth increments along a second axis in response to said Doppler frequency signals;

f) generating Doppler mean frequency signals at each of the said range depth increments from the said 30 Doppler frequency signals;

g) displaying a second Doppler graph representing said Doppler mean frequency along the said first axis and said range depth increments along

the said second axis by setting the parameters defining a status of appearance of the pixels forming the displayed image of the said second Doppler graph in such a way as to visually differentiate the said 5 pixels from the pixels of the image of the said first Doppler graph;

h) repeating the above sequence of steps with a certain repetition frequency;

10 i) setting the persistence of the status of appearance of the pixels forming the image of the said second Doppler graph in such a way that the said pixels maintains their status of appearance regardless of any attenuation or termination of the said Doppler frequency signals for a predetermined 15 period of time and/or until new Doppler signals with greater absolute mean frequency values are generated from Doppler signal samples acquired during at least one of the said repetitions steps h);

20 j) the said new values of the said Doppler mean frequency signals being used to upgrade the displayed image of the said second Doppler graph by setting the status of the appearance of the pixels forming the said image.

According to a first improvement of the above 25 method a further step is provided of filtering out the low frequency component of the Doppler frequency signals before generating the Doppler mean frequency signals.

30 This allows to enhance the polarisation effect of the mean Doppler frequency values relatively to the direction of the flow.

According to one embodiment the above mentioned step g) consist in enhancing the brightness of the

pixels forming the image of the said second Doppler graph.

This step can be provided either alone or in combination with a further step consisting in 5 reducing the brightness of the pixels forming the image of the first Doppler graph.

In order to further enhance the indication of the direction, which is the fact that a trace of brightness enhanced pixels is either on the left or 10 on the right side of the zero value for the Doppler frequency or velocity in a graphic representation in a Cartesian system with one axis representing Doppler frequencies or velocities and the other axis the depths increments or sample volumes, a step of 15 changing the frequency scale along the corresponding axis representing the values of the Doppler frequency is carried out.

The different scale can be chosen in such a way that it enlarges the dimensions of the image of the 20 said second graph in relation to the dimensions of the said first graph along the said first axis.

The same effect could be obtained by providing an enhancing parameter which is multiplied to the determined values of the mean Doppler frequencies.

25 As already indicated above the method is particularly dedicated a subject under study comprising at least a blood vessel and blood flux in the said vessel having a flux velocity varying in time between a maximum velocity and a velocity which 30 is approximately zero or in the opposed direction. In this case the predetermined range of depth increments being set in order to cover the entire cross section of the said al least one vessel, the Doppler

frequency signals and the Doppler mean frequency signals being representative of the velocity of the blood flux in the vessel at the said depth increments. Furthermore the method is applied in a 5 manner that the persistence of the status of appearance of the pixels forming the image of the said second Doppler graph being maintained until new Doppler signals with greater absolute mean frequency values are generated from Doppler signal samples 10 acquired during at least one of the said repetitions steps h) coinciding with a greater, in absolute value, blood flux velocity.

Furthermore the method according to the invention can be applied to back-scattered signals 15 which are received from a first region of interest within said subject resulting in said Doppler signal samples and from at least second or more further regions of interest within said subject.

If possible in the above case, the transmitted 20 ultrasound waves comprises an ultrasound beam optimized for Doppler data acquisition which is directed along a direction crossing at least two or more of the said region of interests.

Also in the case of this embodiment the said 25 regions of interests are different blood vessels and a plurality of Doppler signal samples being generated in response to said back-scattered signals representing a predetermined ranges of depth increments each one of which crosses at least 30 partially one of the said vessels.

As usual in may methods of displaying echographic Doppler data the present method comprises further steps consisting in acquiring and displaying

B-mode data from the subject under study in an ultrasound system.

As known the said steps consists in generating B-mode data for a region of interest containing the 5 subject under study and displaying the B-mode image and displaying in a superimposed way on the said B-mode image the scan line along which the Doppler beam is focussed and the range of depth increments on the corresponding region of interests.

10 The method according to the above invention allows to extract direction information of the blood flows based on the fact that in practical cases it will be very improbable that the transmitted beams will have an angle of incidence relatively to the 15 flux direction which is perfectly  $90^\circ$ , which is the condition in which no frequency shift will be generated. Under normal practical conditions it is more probable that the angle of incidence will be very near to the  $90^\circ$  but not quite  $90^\circ$  and will vary 20 also within a certain tolerance in time due for example of the motion of the body under study or the motion of the person holding and orienting the ultrasound probe. In this condition, there will be a very low Doppler frequency shift of the backscattered 25 waves relatively to the frequency of the transmitted waves. So the Doppler frequency shift spectrum at a certain sample will contain direction information due to very small frequency shifts either positive or negative and the processing and displaying steps of 30 the Doppler frequency signals according to the present invention helps in enhancing and displaying such frequency shifts in order to extract and indicate also the direction of the moving scatterer,

i.e. the blood flux in a vessel.

According to a further improvement of the invention, the above method steps can be provided in combination with further steps allowing to further 5 differentiate the angle of incidence of the transmitted ultrasound waves relatively to the direction of motion of a moving scatterer, such as the direction of flow of a blood flux.

According to these further steps a transmit and 10 a receive array of ultrasound transducers is provided, respectively for emitting ultrasound waves upon excitation by means of excitation signals the said emitted waves being transmitted to the subject under study and for detecting the ultrasound waves 15 backscattered from the subject under study and generating corresponding receive signals the said arrays of transducers having a certain aperture. The method according to the invention provides that the ultrasound waves are transmitted using a first sub- 20 array of the transmit array of transducers, the said sub-array being formed by only a part of the ultrasound transducers of the transmit array and having a first aperture different from the aperture of the said transmit array and generating an 25 ultrasound beam having a direction of propagation which is different from the direction of propagation which would have had an ultrasound beam generated by the complete transmit array of transducers, the said direction of propagation of the ultrasound beam emitted by the said sub-array being defined in order 30 to at least partially cross one or more region of interests within the subject under study;

While the back-scattered ultrasound beams are

received by a second sub-array of the receive array of transducers or by the complete array of transducers.

The second sub-array of receive transducers may 5 be different from the first sub-array of receive transducers.

According to a further improvement the transmit and receive array of transducers consist of the same array of transducers in combination with a switch 10 connecting alternatively the transducers of the array to a generator of excitation signals of the transducers and to a processing device of the receipt signals generated by the backscattered ultrasound waves impinging on the said transducers

15 Thanks to the above method steps during transmission only some of the transmitting electro-acoustic transducer elements are used, which forms a sub-array of transducers which is eccentric relatively to the central axis perpendicular to the 20 complete array of transducers. The central axis of the said sub-array of transducers being thus laterally off-set relatively to the central axis of the complete array. When transmitting, electro-acoustic elements of the sub-array are excited in 25 such a manner that the transmit pulse beam is focused against a subject. The above introduced eccentricity of the sub-array of transducers relatively to the said central axis of the entire array of a probe, determine a slight steering of the beam generated by 30 the subarray in the direction towards the center axis of the entire array.

Considering the situation in which the entire array is excited in order to generate a transmit beam

focused on a volume sample, it appears clearly that the beam generated by the eccentric sub-array and focused on the same volume sample would have a different angle of incidence than the beam generated 5 by the entire array and if the angle of incidence of the beam generated by the entire array is  $90^\circ$ , than the angle of incidence of the beam generated by the sub-array is different from  $90^\circ$  so that Doppler frequency signals would be enhanced.

10 The backscattered ultrasound waves can be received by means of a sub-array which can be a different sub-array as the one for transmitting the ultrasound beam or by the entire array in order to have as much signal intensity as possible for the 15 receipt signals.

As an alternative to the above, eccentricity may be specularly obtained by operating on the receiving elements instead of the transmitting elements. Nevertheless, this will require the use of a smaller 20 number of receiving elements, and hence cause a reduction of sensitivity, that cannot be easily compensated for. Conversely, any reduction in the number of transmitting elements may be compensated for by pulsing a higher voltage.

25 Double eccentricity may be also provided, with respect to the center line, by using a first sub-array of transducers determining a first aperture which are on one side of the center of the entire array at least along one dimension of the array for 30 generating the ultrasound transmit beam and a second sub-array of transducers determining a second aperture which are on the other side of the center of the entire array at least along one dimension of the

array for receiving the backscattered ultrasound beams

The first and second sub-array and the corresponding first and second apertures can be 5 symmetric relatively to the center of the entire array of transducers at leas relatively one of its dimensions.

Indeed transducers can be linear transducer or two dimensional transducers. In one case the center 10 of the transducer and the symmetry relatively to it is clearly defined. In the case of a two dimensional array, different alternatives can be chosen since the center of the transducer is the point which is at the center of the two directions along which the 15 transducers are aligned and the definition of the position of the sub-array relatively to the center depends on the position along each one of the said two directions.

Nevertheless, the above alternative embodiment 20 in addition to reduced sensitivity, as mentioned above, this causes excessive displacement of the window of view from the orthogonal position, which would prevent simultaneous imaging of vessels disposed substantially parallel to the probe, like in 25 the case of the above mentioned cerebral vessels. However, in certain other cases this receiving mode might be used.

In a variant embodiment of the invention, the first and second sub-array and the corresponding 30 first and second apertures can be asymmetric relatively to the center of the entire array of transducers at leas relatively one of its dimensions.

Considering a one dimensional array of transducers among the transducers those that are used for beam generation are eccentric to the direction of propagation of the ultrasonic pulse beam which 5 corresponds to the one that would have had an ultrasonic beam generated by all the elements of the array of electroacoustic transducers. By providing the focusing point/s on said direction of propagation, to focus an ultrasonic beam generated 10 only by part of the transducers of the array positioned in an area of the array, which is eccentric relatively to the direction of propagation, direction of propagation of the beam shall necessarily be laterally offset thereby introducing 15 the above mentioned slight steering. The above arrangement allows to obtain angles of incidence of the transmit pulse beam relative to blood flow direction of about 87° to 85° when the angle of incidence of the beam generated by the entire probe 20 would have been of 90°.

In practice, considering a phased array probe which comprises a linear array of 128 elements, the direction of propagation of the beam is the center axis, which separates the array of adjacent electro-acoustic elements into two halves, each comprising 25 64 elements. The center axis of the sub-array consisting in one of the two halves of the linear array of electro-acoustic elements, is provided at the 32nd or 96th element, whereby if the ultrasonic transmit 30 pulse beam is focused to one or more points along said central axis of the entire array the direction of propagation of the beam generated by the sub-array

will be inclined relatively to the said central axis and intersect it at the focusing points.

Thus the above described improvement of the present invention combines the method steps improving 5 the multigate processing of PW Doppler data acquisition and display in which, a plurality of points or sample volumes are defined along at least one scan line, which points or sample volumes are represents a range of increments of the penetration 10 depth of ultrasonic pulses into the body under examination along said at least one scan line;

whereas the backscattered ultrasound beams are processed in order to generate Doppler frequency signals for each of said points or sample volumes and 15 the said Doppler frequency signals are displayed in a graph as a function of penetration depth in which graph

20 said increments of penetration depth being represented along one axis and the Doppler frequencies being represented along a second axis perpendicular to the former and

25 and further Doppler mean frequency signals are generated which are also displayed in a superimposed way on the said Graph by enhancing the appearance of the pixels representing the said mean frequency values relatively to the pixels representing the Doppler frequency signals as a function of depths increments

30 with the steps of providing at least for the generation of the transmit beam a different aperture of the array such that the direction of propagation of the ultrasound beam is stirred relatively to the

one which would be obtained under traditional ways of driving the array.

This features in combination also with the further features disclosed in the above allows to 5 further enhance the detection of the direction of the moving scatterers such as blood flux also when the angle of incidence of the transmit ultrasound waves is perpendicular to the direction of movement of the scatterers.

10 In a particular application, designed for Doppler imaging of internal cerebral veins, particularly for simultaneous Doppler imaging according to the method of the present invention, 8 equally spaced foci are provided on the first axis of 15 the ultrasonic pulse beam, which correspond to a limitation of successive penetration depth increments, located at the following penetration depths: 25, 40, 55, 70, 85, 100, 115, 130 mm.

Advantageously, a phased array probe is used in 20 the method of the present invention.

According to a variant embodiment, the method of the present invention may include parallel acquisition and overlapped or side-by-side display of the B-mode gray-scale image of the area that contains 25 the vessels whose blood flow has been detected.

As it appears from the previous disclosure, the Multigate-based method of the present invention, as compared with the traditional CFM method, allows simultaneous CFM imaging with both low PRF (involving 30 high sensitivity but excessive aliasing, i.e. identification of vessels, but not their direction) and high PRF (involving low sensitivity, but identification of flow direction), which would not be

5 feasible with the use of the CFM method only. This will simultaneously afford the same sensitivity as the one provided by the CFM method with low PRF and the same flow direction identification ability as the one provided by the CFM method with high PRF.

10 The invention also relates to an ultrasound imaging system for implementing the method for ultrasonic detection and imaging of hemodynamic information, particularly venous blood flow information, which system comprises:

an ultrasonic probe comprising an array of transmitting and receiving electro-acoustic transducers, which elements are arranged according to a predetermined order and design;

15 each transmitting electro-acoustic transducer element having its own independent line for connection to a unit for generating and transmitting electric excitation signals for the corresponding electro-acoustic transducer element;

20 each receiving electro-acoustic transducer having its own independent line for connection to at least one processing unit;

25 at least one unit for Multigate processing of image data, for generating Doppler frequency signals from the Doppler signal sample received from the sample volumes at the different depths increments at least one processing unit for calculating the average frequency of signals of the Doppler frequency signals relating to at least some of the sample volumes;

30 means for displaying a first Doppler graph representing said Doppler frequency along a first axis and said range of depth increments along a second axis in response to said Doppler frequency

signals;

and for displaying a second Doppler graph representing said Doppler mean frequency along the said first axis and said range depth increments along 5 the said second axis by setting the parameters defining a status of appearance of the pixels forming the displayed image of the said second Doppler graph in such a way as to visually differentiate the said pixels from the pixels of the image of the said first 10 Doppler graph;

According to an improvement, the apparatus may further comprise:

means for transmission and reception of electro-acoustic pulse beams for anatomic B-mode 15 imaging;

and a receive signal processing unit for generating B-mode image data and means for displaying the B-mode image in side-by-side relation with the image that displays the average frequencies of the 20 spectral profiles of Doppler shift frequencies and the spectral profiles of Doppler shift frequencies as a function of the penetration depth of the transmit ultrasonic pulse beam.

In this case the system may further comprise 25 means for graphically drawing a line on the B-mode image and for selecting the said line as the line along which a beam for Doppler data acquisition has to be focused;

Means for selecting a predetermined range of 30 depths increments along said line at one or more regions of the said line;

Means for calculating the beam focusing parameters for driving the transducers of the array

of the probe in such a way as to focus the beam at the said line and for setting a receive signal processing unit of an ultrasound apparatus in such a way as to extract and process the receipt signal 5 contribution relating to the ultrasound beams backscattered from each of the sample volumes corresponding to the said depths increments;

Means for tracking the position and orientation 10 fo the probe and determining the orientation of the line along which the ultrasound transmit beam will be focused and for displaying the said line on the B-mode image;

Means for triggering the transmission of the 15 ultrasound beam when the line on which the beam is focused coincides with the line drawn on the B-mode image.

As a further improvement the system is provided with switching means for connecting to the unit for generating and transmitting electric excitation 20 signals a number of selected transducers less than the total numbers of transducers of the array, the said number of transducers being selected in such a way to form a sub-array of transducers having a aperture which is different from the aperture of the 25 complete array of transducers and eccentric relatively to the center of the said array of transducers

And with switching means for connecting to the unit for processing receipt signals a number of 30 selected transducers of the array of receipt transducers, the said number of transducers being selected in such a way that the said number of transducers can vary from the total number of

transducers to a number less than the total number of the transducers in order to form a sub-array of transducers having a aperture which is different from the aperture of the complete array of transducers and 5 eccentric relatively to the center of the said array of transducers.

According to a further improvement, the said switching means are automatically driven by control means which vary the number of selected transducers 10 of the array of transmit transducers and/or of the array of receipt transducers by computing the corresponding aperture from the data determined by the physical law of propagation of acoustic waves and the orientation of the line drawn on the b-mode image 15 along which the transmit beam has to be focused and the position on that line of the sample volumes defined by the said range of depth increments.

According to a further improvement further means can be provided which vary the number and the 20 position on the array of the said transmit and or receipt transducers to be selected for maximizing the value of the maximum mean Doppler frequency detected.

Further improvements of the invention will form the subject of the dependent claims.

25 These and other features and advantages of the present invention will appear more clearly from the following description of a few embodiments, illustrated in the annexed drawings, in which:

Fig. 1 shows an example of the screen that shows 30 hemodynamic information concerning deep cerebral veins, and particularly Galen's vein, the middle internal cerebral vein and Rosenthal's vein, as simultaneously detected by the method and apparatus

of the present invention, reproducing the velocities of the flows as derived from the spectral profiles of Doppler frequency shift and the average frequency of said spectral profiles in penetration depth ranges 5 corresponding to the above veins.

Fig. 2 schematically shows a phased array ultrasonic probe having 64 elements, and the transmission of an ultrasonic pulse beam according to the method of the present invention.

10 Fig. 3 is a view like Figure 1 that shows how the receive ultrasonic pulse beam is focused.

Fig. 4 is a block diagram of an apparatus for implementing the method of the present invention.

According to the present invention, Doppler 15 signals are processed using a Multigate spectral Doppler technique, which provides spectral profile information as a function of a certain depth of penetration. This is achieved by defining a plurality of focusing points along a line of view at different 20 penetration depths increments of the ultrasonic pulse beam in a subject under study. The said focussing points are defined as volume samples which correspond to the said depths increments and this definition is coherent since each ultrasonic beam has a transverse 25 pattern and also an axial pattern which have finite dimensions.

Here, the Doppler frequency signals generated by the multigate processing have a certain spectral frequency distribution within a certain bandwidth and 30 the frequency which are present in the spectrum of each Doppler frequency signal relative to each sample volume or depth increment are displayed as a function of the said penetration depth increments of the beam,

which is represented by the y-axis of a Cartesian coordinate system, whereas the x-axis represents the Doppler shift frequencies, i.e. flow velocities (see image on the left of Figure 1).

5 As it appears from figure 1 the first graph, this means the Doppler frequencies at the sample volumes are represented by the two vertical grey stripes divided by a black area centered on the Y-axis at the zero velocity. Since the angle of  
10 incidence of the ultrasound beam indicated by LV in the B-mode image on the right-hand side of the image of figure 4 is about 90° relatively to the direction of flow in the vessels, the multigate processed image data is symmetric relatively to the y-axis crossing  
15 the x-axis at zero velocity value. The only information which can be obtained is the information relatively to the depth increments or sample volumes which coincides with the different vessels. This is show by the higher brightness of the pixels at the  
20 level of certain depth increments. So in the special condition of a beam which has an angle of incidence of 90° or quite 90° relatively to the flow direction the traditional multigate Doppler processing and display can only give information to the position  
25 along the direction of propagation of the ultrasound transmit beam of a blood flux.

According to the method of the present invention in order to extract also information about the direction of the blood flow the Doppler frequency 30 signals are processed for determination of average frequency values at least for the sample volumes at certain penetration depth of the ultrasonic pulse beam. Especially the said penetration depths are the

ones at which the brightness of the pixels in the Doppler graph reveals the presence of a flux.

Since it is highly improbable that the angle of incidence of the ultrasound beam relatively to the direction of the blood flux is precisely  $90^\circ$ , the Doppler frequency signals must contain signal contribution which relates to the direction of the said flux but which are very small and cannot be revealed with traditional way of processing and displaying the said signals. The present method has shown that the said mean Doppler frequency signals enhances the indication of the direction of the flux, since the spectral components of the Doppler frequency signal which are symmetric about the zero Doppler frequency will reciprocally cancel. Here it is clear that the term Doppler frequency in the present description and in the claims means Doppler frequency shift which is equivalent with Doppler phase shift or velocity. Indeed by determining the mean Doppler frequency for the Doppler frequency signals related to the sample volumes or depth increments coinciding with the position of the blood fluxes in the right hand part of figure 1, and displaying the said values as a pixel trace in a superimposed way on the Doppler frequency graph representing the spectral components of each Doppler frequency signal by using the same coordinate system the Doppler frequency profiles, i.e. the blood flux velocity profile within each vessel appears as a pixel trace only on one side of the line passing through the zero frequency or velocity value thus indicating the direction of the flux and also the velocity distribution of the flux within the lumen of

the vessel. These images are represented by the arched lines indicate by M.

As shown the combination of Multigate techniques and the calculation of the average frequency of 5 Doppler shift spectral profiles caused by the blood flows under examination, can overcome the limitations of prior art technologies as briefly described above, namely the limitations of the Doppler imaging technique known as Color Flow Mapping, which are 10 caused by the contrasting requirements of achieving sufficient signal sensitivity and detecting flow direction, in setting the pulse repetition frequency (PRF).

Figure 1 relates to Doppler imaging of deep 15 cerebral veins, particularly Galen's vein, the middle internal cerebral vein and Rosenthal's vein.

Ultrasound Doppler imaging of these veins is particularly indicative of the problems that this invention is designed to solve, because intracranial 20 ultrasound imaging is limited by the presence of very few ultrasonic beam penetration windows in the cranium. Using these windows, the above mentioned vessels are located in a position, relative to the lines of view, in which the flow is actually 25 perpendicular to the direction of penetration of the acoustic front and hence of the axis of ultrasonic pulse beams, if traditional techniques are used.

On the left side of Figure 1, a diagram in which the y-axis represents penetration depths and the x-axis represents Doppler shift frequencies, i.e. blood 30 flow velocities, shows the spectral profiles as determined at the different the penetration depth increments along the line of view LV on which the

foci 2 of ultrasonic pulse beams are located. The spectral profiles are given by the areas of varying brightness. It may be observed that the spectral profiles clearly highlight denser and brighter zones 5 that correspond to the three vessels, i.e. Galen's vein, the middle internal cerebral vein and Rosenthal's vein, which are substantially parallel to each other and perpendicular to the possible line of view, considering the small size of the windows 10 designed for the passage of ultrasonic pulses that are available in the cranium.

The graphs M of the mean Doppler velocity or frequency as a function of the depth increment shows that the flows of the two vessels at lower depths are 15 oriented in the same direction, whereas the flow of the third vessel, the one at higher depths, is directed opposite to those of the other two vessels.

According to a further improvement that is shown in Figure 1, parallel to Doppler imaging, anatomic B-mode imaging is performed, and the B-mode image is displayed adjacent to the one of spectral profiles and Doppler shift averages. This is shown on the right side of the image of Figure 1. The B-mode image is typically a gray-scale image. Furthermore a Color 20 Flow Mapping Doppler image, also obtained parallel to 25 the others, may possibly be displayed thereon.

The B-mode image shows the vessels, with the line of view LV and the focusing ranges 2 possibly set thereon.

30 For minimized processing burden and real-time imaging, a certain limited number of foci may be reset along the line of view, to define a predetermined number of range gates within a

penetration depth increment or sample volume in which the maximum and minimum end values can be also set. The number of foci along the line of view and the penetration depth range, i.e. the minimum and maximum 5 end values of said range may be set according to anatomic conditions and relevant requirements.

As a rule and particularly for intracranial Doppler imaging of deep cerebral veins, a number of eight foci has been selected to define a penetration 10 depth range from 25 to 130 mm, said foci being located at the depths of 25, 40, 55, 70, 85, 100, 115 and 130 mm.

During reception, the number of foci is the traditional number of 32 foci, which are dynamically 15 focused.

The method of the present invention includes additional improvement steps which assist enhancement obtained by the generation and display of the mean frequency signals, i.e. the direction of blood flow 20 in the corresponding vessel in the image of Figure 1.

Concerning the image, according to a first improvement of the invention, the brightness of the image of the first graph relating to the display of the frequency components of the spectrum of each 25 Doppler frequency signal at the different depth increments is attenuated with respect to commonly used values. Such attenuation may be selected by users in a customized manner and/or according to predetermined fixed levels.

30 A further feature consists in that the low frequency components of the spectrum of each Doppler frequency signal are massively filtered out, whereby

the average obtained there from is more significant in terms of flow direction information.

According to still another improvement the brightness and/or color of the image (pixel trace M) relating to the graph representing the mean Doppler frequency as a function of the depth increments can be incremented in order to be highlighted relatively to the image on which it has been superimposed.

This enhancement can be carried out in an automatic way by determining the brightness of the pixels in the surrounding of the pixel representing the values of the mean frequency.

Furthermore in order to have a more clear indication of the direction of flow, the values of the mean frequency can be rescaled. A new scale can be defined for the x axis which allows zooming of the trace of pixels so that it ranges wider in the x direction. Alternatively or in combination the scale can be maintained the same and the values of the mean frequency can be multiplied by an enhancing factor.

A further arrangement concerning the displayed image consists in providing an asymmetric persistence of the spectral average image. This is relevant for blood flows and particularly for venous flows which occurs during inspiration. Upon inspiration, the Doppler frequency signals and hence their representation is at a maximum, whereas intensity decreases with time, substantially disappears during expiration and reaches the maximum value again during the next inspiration step. This physiological condition would involve progressive reduction of the spectral average plot in the displayed image. In order to prevent such fluctuation, at least the mean

frequency signals but also the Doppler frequency signals are displayed and maintained at the maximum level throughout each entire inspiration and expiration cycle and is replaced by the display of 5 the new Doppler frequency signals and the corresponding mean frequency signals relatively to the backscattered beams received during the new subsequent inspiration. Thus, signal persistence is asymmetric with reference to the inspiration and 10 expiration cycle.

The said feature can be applied for every kind of moving scatterer which velocity varies cyclically upon time between a maximum and a minimum value. In this case the displayed signals are relative to the 15 ones determined during the phase in which the velocity is a maximum and the said image is maintained throughout the following phases of the cycle till the next phase the velocity of the scatterer is again at its maximum value, the new signals are 20 then generated and displayed in substitution to the previous ones.

Referring to the present disclosure, ultrasound imaging is deemed to be part of the base knowledge of the skilled person, both in terms of anatomic 25 ultrasound imaging, particularly using B-mode, and in terms of Doppler and color Doppler ultrasound imaging, i.e. spectral Doppler imaging and Doppler color flow imaging, such as Color Flow Map or the like.

30 Besides the above mentioned documents, B-mode and Doppler ultrasound imaging has been long known in a number of different variants. A summary of Doppler imaging techniques has been published and is

available for download from <http://echoincontext.mc.duke.edu/doppler04.pdf> that is part of an educational web site of Duke University. The authors of this summary are also the 5 authors of the book Doppler color flow imaging by JA Kisslo, DB Adams, RN Belkin - 1988 - Churchill Livingstone.

Special reference will be made herein below for 10 simplicity, clarity and brevity to the inventive method arrangements, which surpass the technical basics of common prior art methods and apparatus.

Concerning blood flow detection technologies, as anticipated above a technology known as Multigate has been known for about ten years. The theoretical bases 15 of this technology are described in the following documents:

P. Tortoli, F. Guidi, G. Guidi, C. Atzeni, Spectral velocity profiles for detailed ultrasound flow analysis, IEEE Trans. on Ultrasonics, 20 Ferroelectrics & Frequency Control, vol.43, n.4, pp.654-659, July 1996.

An FFT-Based Flow Profiler for High-Resolution In Vivo Investigations, Piero Tortoli et al. Ultrasound in Med. & Biol. Vol.23 No.6 pp. 899-910, 25 1997;

Detection of vascular hemodynamics through a high-speed velocity profiler, Piero Tortoli et. Al. European Journal of Ultrasound 9 (199) 231-244;

and WO01/71376, which addresses a particular 30 method of displaying flow velocity information.

As it will appear more clearly from the following description of figures 2 and 3 the effect obtained by means of the above disclosed method can

be enhanced applying improvements at the stage of transmission and or receipt of the ultrasound signals.

According to these improvement further steps are 5 provided according to which a transmit and a receive array of ultrasound transducers is provided, respectively for emitting ultrasound waves upon excitation by means of excitation signals the said emitted waves being transmitted to the subject under 10 study and for detecting the ultrasound waves backscattered from the subject under study and generating corresponding receive signals the said arrays of transducers having a certain aperture. The method according to the invention provides that the 15 ultrasound waves are transmitted using a first sub- array of the transmit array of transducers, the said sub-array being formed by only a part of the ultrasound transducers of the transmit array and having a first aperture different from the aperture of the said transmit array and generating an 20 ultrasound beam having a direction of propagation which is different from the direction of propagation which would have had an ultrasound beam generated by the complete transmit array of transducers, the said 25 direction of propagation of the ultrasound beam emitted by the said sub-array being defined in order to at least partially cross one or more region of interests within the subject under study while the back-scattered ultrasound beams are received by a 30 second sub-array of the receive array of transducers or by the complete array of transducers.

The second sub-array of receive transducers may be different from the first sub-array of receive

transducers. The transmit and receive array of transducers may consist of the same array of transducers in combination with a switch connecting alternatively the transducers of the array to a 5 generator of excitation signals of the transducers and to a processing device of the receipt signals generated by the backscattered ultrasound waves impinging on the said transducers.

Thanks to the above method steps during 10 transmission only some of the transmitting electro acoustic transducer elements are used, which forms a sub-array of transducers which is eccentric relatively to the central axis perpendicular to the complete array of transducers. The central axis of 15 the said sub-array of transducers being thus laterally off-set relatively to the central axis of the complete array. When transmitting electro acoustic elements of the sub-array are excited in such a manner that the transmit pulse beam is focused 20 against the said subject. The above introduced eccentricity of the sub-array of transducers relatively to the said central axis of the entire array of a probe, determine a slight steering of the beam generated by the sub-array in the direction 25 towards the center axis of the entire array.

Considering the situation in which the entire array is excited in order to generate a transmit beam focused on a volume sample, it appears clearly that the beam generated by the eccentric sub-array and 30 focused on the same volume sample would have a different angle of incidence than the beam generated by the entire array and if the angle of incidence of the beam generated by the entire array is 90°, than

the angle of incidence of the beam generated by the sub-array is different from 90° so that Doppler frequency signals would be enhanced.

5 The backscattered ultrasound waves can be received by means of a sub-array which can be a different sub-array as the one for transmitting the ultrasound beam or by the entire array in order to have as much signal intensity as possible for the receipt signals.

10 Then above general principle is explained with a simplified special example of a linear array illustrated in the figures 2 and 3. The skilled person will be able to extend the teaching of the said example to the general case depicted above.

15 Figure 2 shows an array 1 of electro-acoustic transducer elements which is composed of individual electro-acoustic transducer elements 101. In the illustrated embodiment, 64 transducer elements are provided, the first of which is designated by numeral 20 101(1) and the last by numeral 101(64).

25 The probe is preferably of the phased array type, such as the probe PA240 manufactured by Esaote S.p.A. Each transmitting transducer element has an independent line for feeding electric excitation pulses which are supplied thereto from an excitation section as described below.

30 Considering the line of view LV which coincides, in this example, with the center axis of the array 1 of the transducer elements 101(1) to 101(64) and divides said array 1 into two halves, each with 36 transducer elements, from 101(1) to 101(36) and from 101(37) to 101(64) respectively, this line of view LV is orthogonal to the direction of the flows F1 and F2

in the two vessels V1 and V2 intersected by said line of view. Therefore, by successively focusing the beam of transmit ultrasonic pulses generated by the whole array 1 of transducer elements to said line of view 5 LV at the depths defined by the focusing points 2 arranged along said line of view LV, no flow direction information can be retrieved from Doppler frequency shift data. As shown in Figure 1, the line of view LV forms angles  $\Theta_{LV}$  of  $90^\circ$  with the flows F1 10 and F2 in the vessels V1 and V2.

A schematic and simplified representation of beam focusing would be similar to the one as shown in Figure 2 which is a simplified and schematic example of focusing during reception.

15 In order to introduce an angle of incidence of the transmit ultrasonic pulse beam which is other than  $90^\circ$ , according to the present invention, only some of the 64 electro-acoustic transducer elements 101 are used, which form a sub-array of transmitting 20 electro-acoustic elements in direct side-by-side relation and whose transmitting surface is eccentric to the center axis of the overall array 1 of electro-acoustic transducers, i.e. the overall transmitting surface. In the illustrated embodiment, said sub- 25 array of electro-acoustic transducer elements comprises the electro-acoustic transducer elements of one of the two halves of the array 1 on one of the two sides of the center axis LV. Particularly referring to Figure 1, said sub-array comprises the 30 electro-acoustic transducer elements 37 to 63, designated by numerals 101(37) to 101(64).

In this case, the axis of the transmit pulse beam is defined as the axis that starts from the

center point of the transmitting surface of the electro-acoustic transducer elements of said sub-array, with the center axis AC (shown as a broken line) of said sub-array, designated as 1' in Figure 5 1, passing through said point.

It will be appreciated that, assuming a line of view LV and the foci 2 thereon, focusing of the beams of transmit ultrasonic pulses transmitted by the electro-acoustic transducer elements of the sub-array 10 1' only, causes the direction of propagation of the acoustic front, i.e. the axis AF of each of the beams of transmit ultrasonic pulses successively focused to said foci 2 on the line of view LV, to form an angle  $\Theta_{AF}$  with the directions of blood flows F1 and F2 15 which is other than  $90^\circ$  and in this case smaller than  $90^\circ$  when the line of view LV is perpendicular to the directions of the blood flows F1 and F2.

During reception, as shown in Figure 3, the whole array 1 is used and the receiving electro-acoustic transducer elements are actuated in such a 20 manner as to focus the receive ultrasonic pulse beams to the axis that coincides with the line of view LV, here coinciding with the center axis perpendicular to the transmitting surface of the whole array 1. 25 Alternatively a sub-array having a different aperture as the sub-array used during transmission or the aperture of the entire array can be used also for receiving the back-scattered ultrasound beams.

By this arrangement, slight steering of transmit 30 pulse beams is introduced, and causes a further polarization of Doppler information as a function of the direction of the blood flow under examination.

Steering angles are relatively small, of the order of 83 to 87°, or (180-83)° to (180-87)°, a slight Doppler frequency shift occurs whereby, using prior art technologies such as Color Flow Mapping or 5 spectral Doppler technologies such as Multigate, flow direction information will be difficult to be extracted.

In the case of Color Flow Mapping technologies which determine the average frequency value at one 10 point, in order to reach sufficient signal sensitivity, the pulse repetition frequency (PRF) shall be maintained at a low value, whereas retrieval and display of flow direction information introduced by the above described steering would require a high 15 pulse repetition frequency (PRF), which would cause an excessive sensitivity reduction and hence signal losses.

In the case of spectral Doppler imaging technologies, such as the one known as Multigate, the 20 above described steering is of no use in making spectral profiles asymmetric with respect to the zero axis, i.e. to a zero shift or a zero flow velocity.

On the contrary using the said steering method of the transmit and/or backscattered beam in 25 combination with the method according to the present invention consisting in extracting the mean Doppler frequency from the Doppler frequency signals and representing the said mean Doppler frequency as a function of the corresponding sample volume along the 30 penetration depths of the transmit beam by enhancing the appearance of the said image provides improved and clear indication of the direction of motion when the angle of incidence of the transmit beam is very

close to 90° relatively to the said direction of motion.

Figure 3 schematically shows an ultrasound imaging system adapted for implementing the method of 5 the present invention.

Also in this case, the functional sections provide features and constructions known per se and widely used.

An ultrasonic probe comprises an array 1 of 10 electro-acoustic transducer elements. The probe is preferably of the phased array type and the transducers are each connected separately from the others and via a switch 12 alternately to a transmit beamformer 16 and a receive beamformer 13. The 15 transmit beamformer 16 receives electric excitation pulses for the electro-acoustic transducer elements of the array 1 from a pulse generator 17. The pulses are fed to the individual transducers according to a particular mode, i.e. with excitation delays set for 20 each electro-acoustic transducer element, so that the pulse beam is focused along a predetermined line of view or successively along a plurality of adjacent lines of view to cover a two-dimensional area. Selection is dependent upon the desired imaging mode.

25 Excitation pulses are also repeated with a predetermined frequency, also in this case according to known methods, widely used in current ultrasound imaging apparatus. In Figure 3 two sections 18 and 19 are indicated in differentiated manners to show that 30 forming and excitation of electro-acoustic transducer elements for Doppler imaging are different from those traditionally used and particularly from those as used for generation of anatomic or B-mode images.

Particularly, such excitation methods are those as previously described with reference to Figure 1. The one or more lines of view and the foci of the transmit ultrasonic pulse beams on said line/s of view 5 may be manually selected in a user-customized manner. Otherwise, the user may select among different combinations of fixed settings, which are stored for selection, or the apparatus automatically sets said parameters when the Doppler imaging feature 10 is set. The above is embodied by section 20, which may be a data input interface for a user or a memory that automatically provides the parameters for setting the line of view and the foci.

During reception the beamformer 13 is also 15 controlled by a section that supplies the focusing data as described above. Particularly, as shown by the two sections 14 and 15, the methods for focusing the receive pulse beam may be different for Doppler imaging according to the method of the present 20 invention and for parallel B-mode imaging.

The receive signals that come out of the receive beamformer are processed in a known manner to obtain the desired image. Processing for retrieving image data and converting it into images to be displayed on the screen 27 is known per se and will not be 25 described in further detail, because the knowledge of such processing is part of the know-how of a person of ordinary skill in the art.

The receive signals are processed by a Multigate 30 Doppler processor designated by numeral 21, which retrieves spectral profile information from Doppler shifts at various penetration depths. As shown by the functional unit 24, image data is generated for

display of said spectral profiles, as shown in Figure 3 and Figure 4, whereas numeral 25 designates a section for determining the average frequency from the spectral Doppler shift profiles for at least some 5 penetration depth ranges and particularly for those that coincide with the flows detected from spectral profiles. An image processing section 26 converts said spectral profile data and spectral average data for said profiles into images to be displayed.

10 The sections 24 and 25 and, concerning the image, the section 26 also carry out one or more processing steps of those provided and listed above and particularly perform the steps of:

attenuating the display of the spectral profile, 15 as compared with standard display, to enhance the overlapped average;

strongly filtering out the low frequency components of the spectrum to extract a more significant average;

20 enhancing the average components in terms of range to give clear direction information;

introducing an asymmetric persistence, that enhances flow arrival (typically during forced inspiration) and "maintains" it as it decreases.

25 A B-mode image processor 23 may be provided and may allow the B-mode image to be displayed adjacent to Multigate Doppler images, through the image processing section 26.

30 Possibly, as shown by a box outlined by broken lines 22, an image processing unit may be provided for generating Color Flow Mapping (CFM) images, which may be displayed over the B-mode image.

The means 20 for the input of line of view of focus parameters may be equipped with a graphical user interface, which allows both the line of view and the individual foci therealong to be plotted on 5 the B-mode image. The graphical input data are both displayed and converted into parameters to be fed to the transmit beamformer 16 through the focusing control sections 19.

According to a further improvement the system of 10 figure 3 is further provided with a Graphic user interface and means such as a mouse or similar for drawing a Line off view LV on a B-mode image. Furthermore the system can be provided with means for graphically drawing on the said Line LV several 15 depths increments such as the ones indicated with numeral 2 on figure 1. The image processor 26 determines the geometric parameters such as orientation and position relatively to the B-mode image of the drawn lines and depths increments. These 20 data may be converted by the scanline and range gate input data unit 20 in corresponding settings of the ultrasound systems relatively to the transmit beamformer 16 and to the multigate processor 21.

Furthermore depending on the orientation of the 25 Line of view LV and the position of the chosen depth increments on said line, the system can determine automatically which of the single transducers of the array of transducers 1 has to be activated as an element for a sub-array of transmit and or receipt 30 transducers in order to enhance polarization of the flow direction information in the Doppler signal samples.

The above determined settings and the selected transducers for forming transmit and/o receipt sub-arrays having different apertures can be changes automatically during scanning operations if a 5 reduction in the polarization of the direction information is determined. This could be evaluated by monitoring the maximum mean frequency across the lumen of a vessel or an average value of the mean frequency profile across the lumen of a vessel.

10 As a further improvement the system according to figure 3 could be provided with means fro tracking the position and orientation of the probe carrying the array of transducers. This means that the position and orientation of the array of transducers 15 and of the beam generated by the said array can be tracked. Thus the system allows to trace an optimal whished line of view by the graphic user interface and also to track fi the probe is held by the user in a correct way so that the beam transmitted is 20 oriented along the chosen line of view. The line of view generated by the probe can be displayed on the B-mode image helping the user to displace the probe and thus the array of transducers in such a way that the ultrasound beam generated is oriented along the 25 Line of view chosen. When the two lines come to coincide the image processor can be designed to generate a trigger output signal which starts the imaging process for transmitting and receiving the ultrasound signals and displaying the Doppler 30 velocity information.

## CLAIMS

1. A method for acquiring and displaying Doppler data from a subject under study in an ultrasound system, the said method comprising the following 5 steps:

a) transmitting ultrasound waves into the subject under study;

10 b) generating back-scattered signals in response to the ultrasound waves back-scattered from the subject under study;

c) generating a plurality of Doppler signal samples representing a predetermined range of depth increments within said subject in response to said back-scattered signals;

15 d) generating a plurality of Doppler frequency signals representing said predetermined range of depth increments in response to said Doppler signal samples;

20 e) displaying a first Doppler graph representing said Doppler frequency along a first axis and said range of depth increments along a second axis in response to said Doppler frequency signals;

25 f) generating Doppler mean frequency signals at each of the said range depth increments from the said Doppler frequency signals;

30 g) displaying a second Doppler graph representing said Doppler mean frequency along the said first axis and said range depth increments along the said second axis by setting the parameters defining a status of appearance of the pixels forming the displayed image of the said second Doppler graph in such a way as to visually differentiate the said pixels from the pixels of the image of the said first

Doppler graph;

h) repeating the above sequence of steps with a certain repetition frequency;

5 i) setting the persistence of the status of appearance of the pixels forming the image of the said second Doppler graph in such a way that the said pixels maintains their status of appearance regardless of any attenuation or termination of the said Doppler frequency signals for a predetermined 10 period of time and/or until new Doppler signals with greater absolute mean frequency values are generated from Doppler signal samples acquired during at least one of the said repetitions steps h);

15 j) the said new values of the said Doppler mean frequency signals being used to upgrade the displayed image of the said second Doppler graph by setting the status of the appearance of the pixels forming the said image.

2. A method according to claim 1 in which the further step is provided of filtering out the low frequency component of the Doppler frequency signals before generating the Doppler mean frequency signals.

3. A method according to claims 1 or 2, in which the step g) consist in enhancing the brightness of 25 the pixels forming the image of the said second Doppler graph.

4. A method according to claim 3, in which the further step is provided consisting in reducing the brightness of the pixels forming the image of the first Doppler graph.

30 5. A method according to one or more of the preceding claims further comprising the step of changing the frequency scale along the first axis

representing the values of the Doppler mean frequency of the said Doppler mean frequency signals.

6. A method according to claim 5 in which the scale is enlarged in order to enlarge the dimensions 5 of the image of the said second graph in relation to the dimensions of the said first graph along the said first axis.

7. A method according to one or more of the preceding claims in which the subject under study 10 comprises at least a blood vessel and blood flux in the said vessel having a flux velocity varying in time between a maximum velocity and a velocity which is approximately zero or in the opposed direction;

the predetermined range of depth increments 15 being set in order to cover the entire cross section of the said at least one vessel;

the Doppler frequency signals and the Doppler mean frequency signals being representative of the velocity of the blood flux in the vessel at the said 20 depth increments;

the persistence of the status of appearance of the pixels forming the image of the said second Doppler graph being maintained until new Doppler signals with greater absolute mean frequency values 25 are generated from Doppler signal samples acquired during at least one of the said repetitions steps h) coinciding with a greater, in absolute value, blood flux velocity.

8. A method according to one or more of the preceding claims in which said back-scattered signals 30 are received from a first region of interest within said subject resulting in said Doppler signal samples and from at least second or more further regions of

interest within said subject.

9. A method according to one or more of the preceding claims in which said transmitted ultrasound waves comprises an ultrasound beam optimized for 5 Doppler data acquisition which is directed along a direction crossing at least two or more of the said region of interests.

10. A method according to claims 8 and 9, in which the region of interests are different blood vessels a plurality of Doppler signal samples being generated in response to said back-scattered signals representing a predetermined ranges of depth increments each one of which crosses at least partially one of the said vessels.

15 11. A method according to one or more of the preceding claims in which the further steps are provided of acquiring and displaying B-mode data from the subject under study in an ultrasound system comprising the step of generating B-mode data for a 20 region of interest containing the subject under study

Displaying the B-mode image and displaying in a superimposed way on the said B-mode image the scan line along which the Doppler beam is focussed and the range of depth increments on the corresponding region 25 of interests.

12. A method according to one or more of the preceding claims in which a transmit and a receive array of ultrasound transducers is provided, the said array having a certain aperture, the ultrasound waves 30 are transmitted using a first sub-array of the said array of transducers, the said sub-array being formed by only a part of the ultrasound transducers of the array and having a first aperture different from the

aperture of the said array of transducers and generating an ultrasound beam having a direction of propagation which is different from the direction of propagation a ultrasound beam generated by the 5 complete array of transducers, the said direction of propagation of the ultrasound beam emitted by the said sub-array being defined in order to at least partially cross one or more region of interests within the subject under study;

10 While the back-scattered ultrasound beams are received by a second sub-array of the receive array of transducers or by the complete receive array.

13. A method according to claim 12, in which the second sub-array is different from the first sub- 15 array.

14. A method according to claim 13 in which the transmit and receive array of transducers consist of the same array of transducers in combination with a switch connecting alternatively the transducers of 20 the array to a generator of excitation signals of the transducers and to a processing device of the receipt signals generated by the backscattered ultrasound waves impinging on the said transducers

15. An apparatus for carrying out the method for 25 ultrasonic detection and imaging of hemodynamic information, particularly venous blood flow information, as claimed in one or more of claims 1 to 14, which system comprises:

30 an ultrasonic probe comprising an array of transmitting and receiving electro-acoustic transducers, which elements are arranged according to a predetermined order and design;

each transmitting electro-acoustic transducer

element having its own independent line for connection to a unit for generating and transmitting electric excitation signals for the corresponding electro-acoustic transducer element;

5 each receiving electro-acoustic transducer having its own independent line for connection to at least one processing unit;

10 at least one unit for Multigate processing of image data, for generating Doppler frequency signals from the Doppler signal sample received from the sample volumes at the different depths increments at least one processing unit for calculating the average frequency of signals of the Doppler frequency signals relating to at least some of the sample volumes;

15 means for displaying a first Doppler graph representing said Doppler frequency along a first axis and said range of depth increments along a second axis in response to said Doppler frequency signals;

20 and for displaying a second Doppler graph representing said Doppler mean frequency along the said first axis and said range depth increments along the said second axis by setting the parameters defining a status of appearance of the pixels forming 25 the displayed image of the said second Doppler graph in such a way as to visually differentiate the said pixels from the pixels of the image of the said first Doppler graph;

16. An apparatus as claimed in claim 15,  
30 characterized in that it further comprises:

According to an improvement, the apparatus may further comprise:

means for transmission and reception of electro-

acoustic pulse beams for anatomic B-mode imaging;  
and a receive signal processing unit for generating B-mode image data and means for displaying the B-mode image in side-by-side relation with the 5 image that displays the average frequencies of the spectral profiles of Doppler shift frequencies and the spectral profiles of Doppler shift frequencies as a function of the penetration depth of the transmit ultrasonic pulse beam.

10 17 An apparatus according to claim 15 or 16 characterized in that it comprises:

means for graphically drawing a line on the B-mode image and for selecting the said line as the line along which a beam for Doppler data acquisition 15 has to be focused;

Means for selecting a predetermined range of depths increments along said line at one or more regions of the said line;

20 Means for calculating the beam focusing parameters for driving the transducers of the array of the probe in such a way as to focus the beam at the said line and for setting a receive signal processing unit of an ultrasound apparatus in such a way as to extract and process the receipt signal 25 contribution relating to the ultrasound beams backscattered from each of the sample volumes corresponding to the said depths increments;

30 Means for tracking the position and orientation of the probe and determining the orientation of the line along which the ultrasound transmit beam will be focused and for displaying the said line on the B-mode image;

Means for triggering the transmission of the ultrasound beam when the line on which the beam is focused coincides with the line drawn on the B-mode image.

5 18. An apparatus according to claim 17 characterized in that it is provided with switching means for connecting to the unit for generating and transmitting electric excitation signals a number of selected transducers less than the total numbers of  
10 transducers of the array, the said number of transducers being selected in such a way to form a sub-array of transducers having a aperture which is different from the aperture of the complete array of transducers and eccentric relatively to the center of  
15 the said array of transducers;

And with switching means for connecting to the unit for processing receipt signals a number of selected transducers of the array of receipt transducers, the said number of transducers being selected in such a way that the said number of transducers can vary from the total number of transducers to a number less than the total number of the transducers in order to form a sub-array of transducers having a aperture which is different from the aperture of the complete array of transducers and eccentric relatively to the center of the said array of transducers.

19. An apparatus according to claim 18, characterized in that the said switching means are automatically driven by control means which vary the number of selected transducers of the array of transmit transducers and/or of the array of receipt transducers by computing the corresponding aperture

from the data determined by the physical law of propagation of acoustic waves and the orientation of the line drawn on the b-mode image along which the transmit beam has to be focused and the position on 5 that line of the sample volumes defined by the said range of depth increments.

20. An apparatus according to one or more of the preceding claims 15 to 19 characterized in that it is provided with means which vary the number and the 10 position on the array of the said transmit and or receipt transducers to be selected for maximizing the value of the maximum mean Doppler frequency detected.

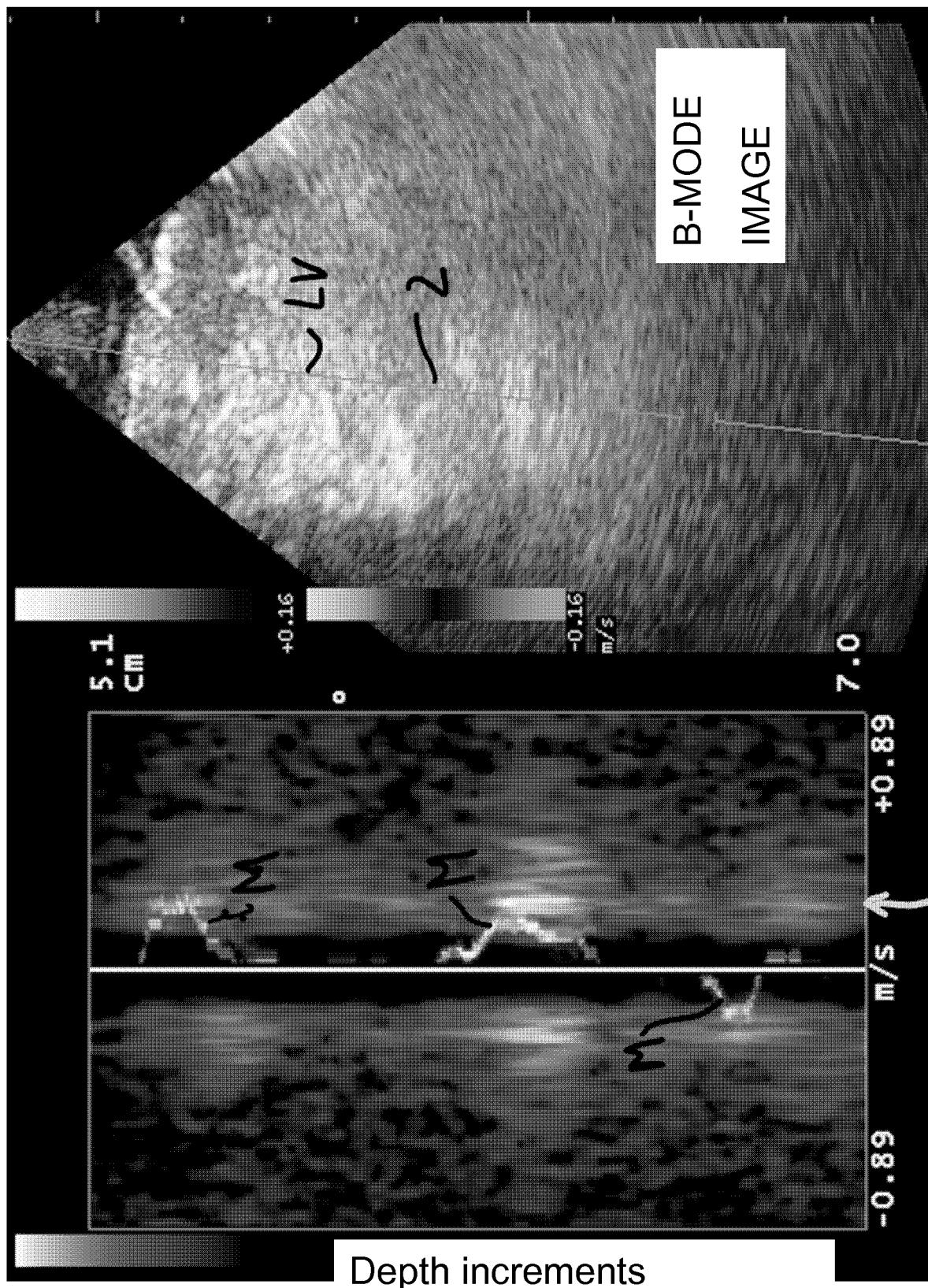


Fig. 1

Velocity spectra from Doppler frequency signals

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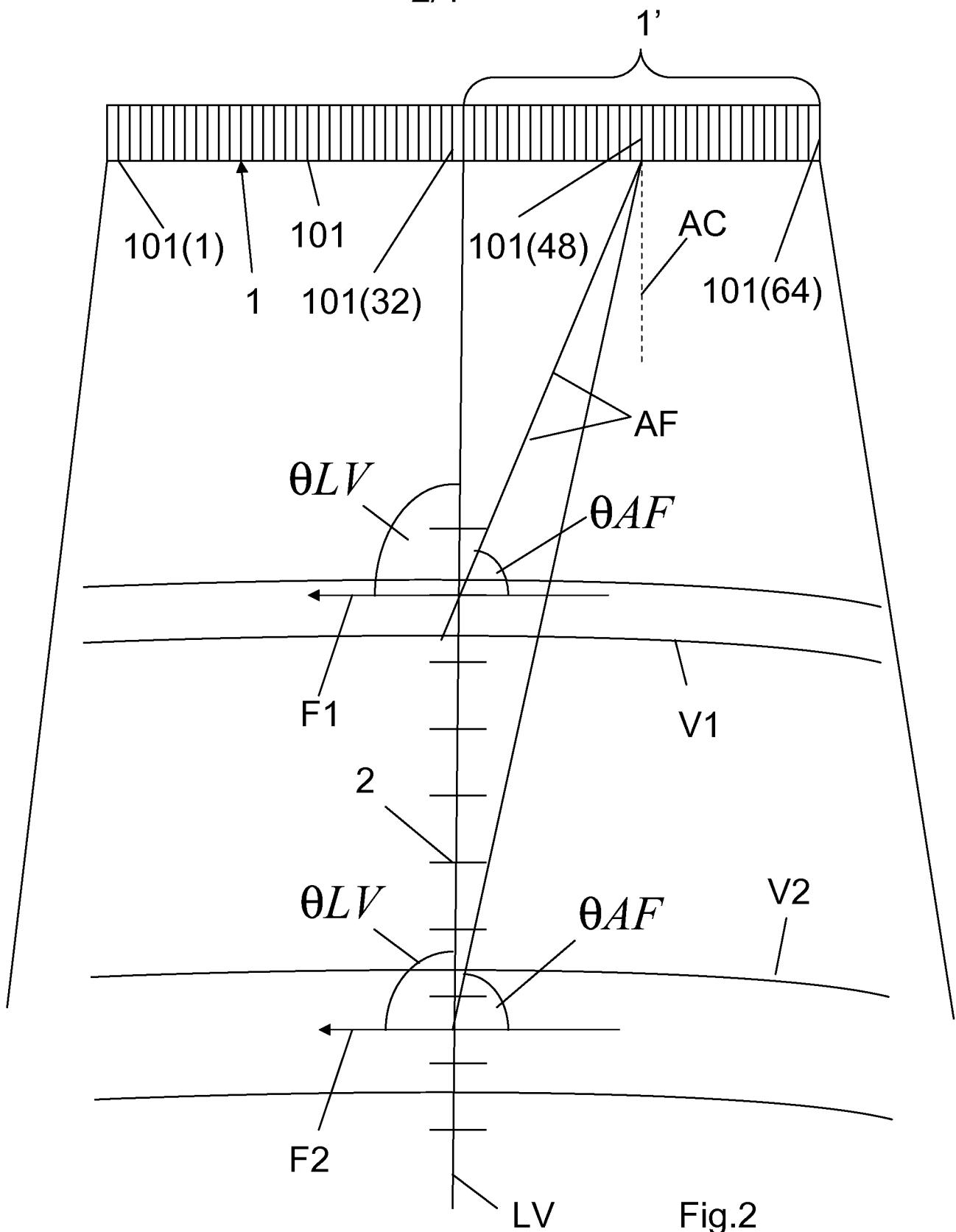
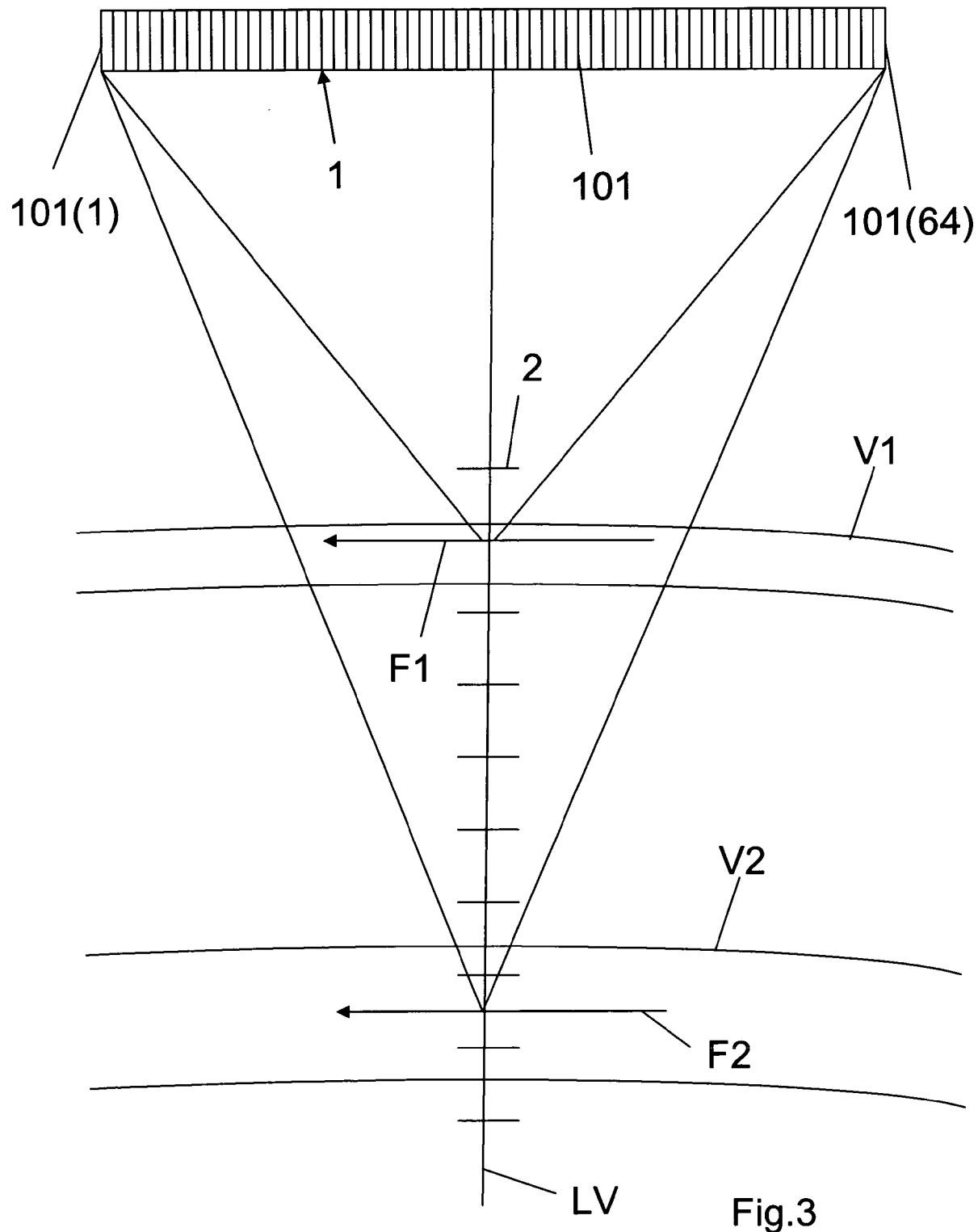


Fig.2

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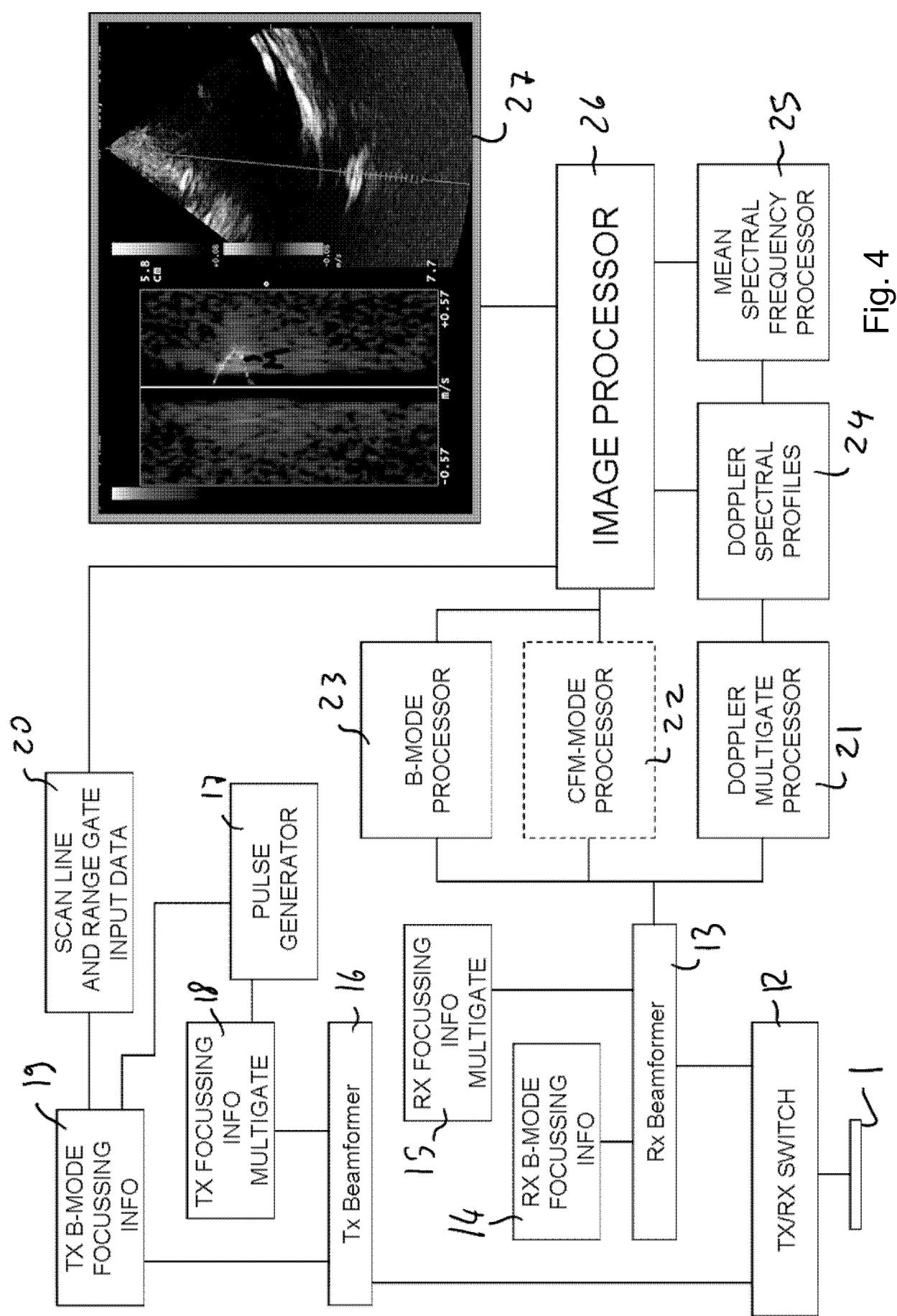


Fig. 4

# INTERNATIONAL SEARCH REPORT

International application No

PCT/EP2010/062556

**A. CLASSIFICATION OF SUBJECT MATTER**  
 INV. A61B8/06 A61B8/08 G01S15/89 G01S15/58  
 ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

**B. FIELDS SEARCHED**

Minimum documentation searched (classification system followed by classification symbols)  
**A61B G01S**

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

**EPO-Internal**

**C. DOCUMENTS CONSIDERED TO BE RELEVANT**

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 5 785 655 A (GOODSELL JR LEONARD JAMES [US] ET AL) 28 July 1998 (1998-07-28) figure 8C	1-20
A	US 5 615 680 A (SANO AKIHIRO [JP]) 1 April 1997 (1997-04-01) figure 32B	1-20
A	WO 2009/072092 A1 (KONINKL PHILIPS ELECTRONICS NV [NL]; SHI XUEGONG [US]) 11 June 2009 (2009-06-11) paragraph [0034]	1-20
A	WO 00/68697 A1 (B K MEDICAL AS [DK]; JENSEN JOERGEN ARENDT [DK]) 16 November 2000 (2000-11-16) page 14; figure 13	1-20
	----- -/-	

Further documents are listed in the continuation of Box C.

See patent family annex.

\* Special categories of cited documents :

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"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.

"&" document member of the same patent family

Date of the actual completion of the international search

Date of mailing of the international search report

21 October 2010

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Anscombe, Marcel

## INTERNATIONAL SEARCH REPORT

International application No  
PCT/EP2010/062556

## C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
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A	US 2009/105594 A1 (REYNOLDS CONNELL [US] ET AL) 23 April 2009 (2009-04-23) figure 3 -----	1-20
A, P	US 2010/022884 A1 (USTUNER KUTAY F [US] ET AL) 28 January 2010 (2010-01-28) paragraph [0053] -----	1-20

**INTERNATIONAL SEARCH REPORT**

Information on patent family members

International application No PCT/EP2010/062556	
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Patent document cited in search report		Publication date		Patent family member(s)		Publication date
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US 5615680	A	01-04-1997		NONE		
WO 2009072092	A1	11-06-2009	EP US	2232299 A1 2010249597 A1	29-09-2010 30-09-2010	
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US 2009105594	A1	23-04-2009		NONE		
US 2010022884	A1	28-01-2010		NONE		

专利名称(译)	用于血液动力学信息，特别是静脉血流信息的超声检测和成像的方法和设备		
公开(公告)号	<a href="#">EP2473113A1</a>	公开(公告)日	2012-07-11
申请号	EP2010745661	申请日	2010-08-27
[标]申请(专利权)人(译)	百胜集团		
申请(专利权)人(译)	ESAOTE S.P.A.		
当前申请(专利权)人(译)	ESAOTE S.P.A.		
[标]发明人	ANDREUCCETTI FABIO TORTOLI PIERO		
发明人	ANDREUCCETTI, FABIO TORTOLI, PIERO		
IPC分类号	A61B8/06 A61B8/08 G01S15/89 G01S15/58		
CPC分类号	G01S15/8913 A61B8/06 A61B8/0816 A61B8/13 A61B8/463 A61B8/488 G01S7/52066 G01S15/8927 G01S15/8984		
优先权	102009901761418 2009-08-31 IT		
其他公开文献	EP2473113B1		
外部链接	<a href="#">Espacenet</a>		

#### 摘要(译)

一种用于血液动力学信息，特别是静脉血流信息的超声检测和成像的方法，该方法包括以下步骤：将超声脉冲发射到被检查的身体中，该脉冲由根据预定的布置的电声换能器阵列产生。订单和设计;接收由接收电声换能器阵列反射发射脉冲产生的反射脉冲，其在刺激从被检查身体反射的脉冲时产生接收信号;所述连续的脉冲传输到被检查的身体和/或从被检查的身体接收的脉冲沿着一条或多条扫描线聚焦;产生至少一个多普勒频移信号，该信号是由血流传输到与所述扫描线相交的血管中的脉冲的反射，在至少一个点上并且沿着至少所述扫描线，或者沿着脉冲的传播方向产生的;从多普勒频移频谱的平均频率值确定至少所述点的血流速度的方向，并通过区分相反方向的图形和/或彩色表示显示所述血流速度的方向。