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(54) **ARM SUPPORT ASSEMBLY FOR MEDICAL EXAMINATION DEVICE**

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(57) **ABSTRACT**

An arm support assembly includes an armrest and connecting assembly. The armrest may meet regulatory or industry standards and is maneuverable into a variety of positions, including seated, blood pressure reading, supping or lying, and stowed or patient transfer positions. The armrest may be padded and/or upholstered. The connecting assembly includes first and second joints each selectively rotatable and an elongate member connecting them. The first joint rotatably mounts to the armrest, and the second joint mounts to the side of an examination device such as a table or chair. The joints include a rotary mechanism to engage between locked and unlocked positions, where rotational motion is enabled in unlocked positions. Rotation at first and second joints collectively result in maneuvering the armrest between the various positions.

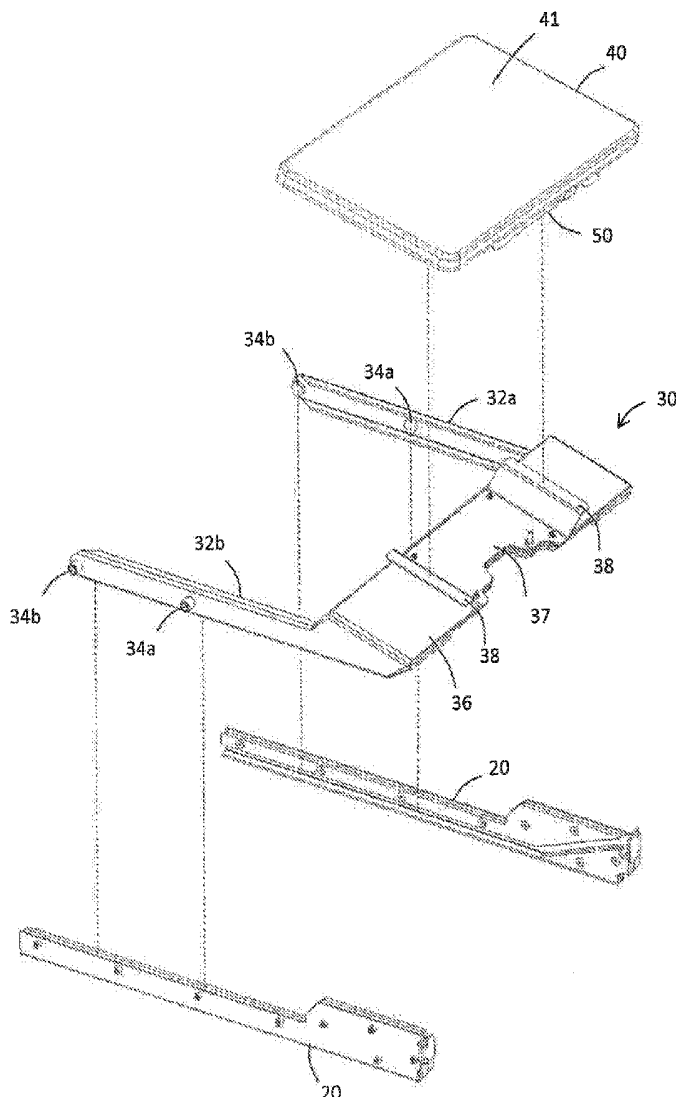
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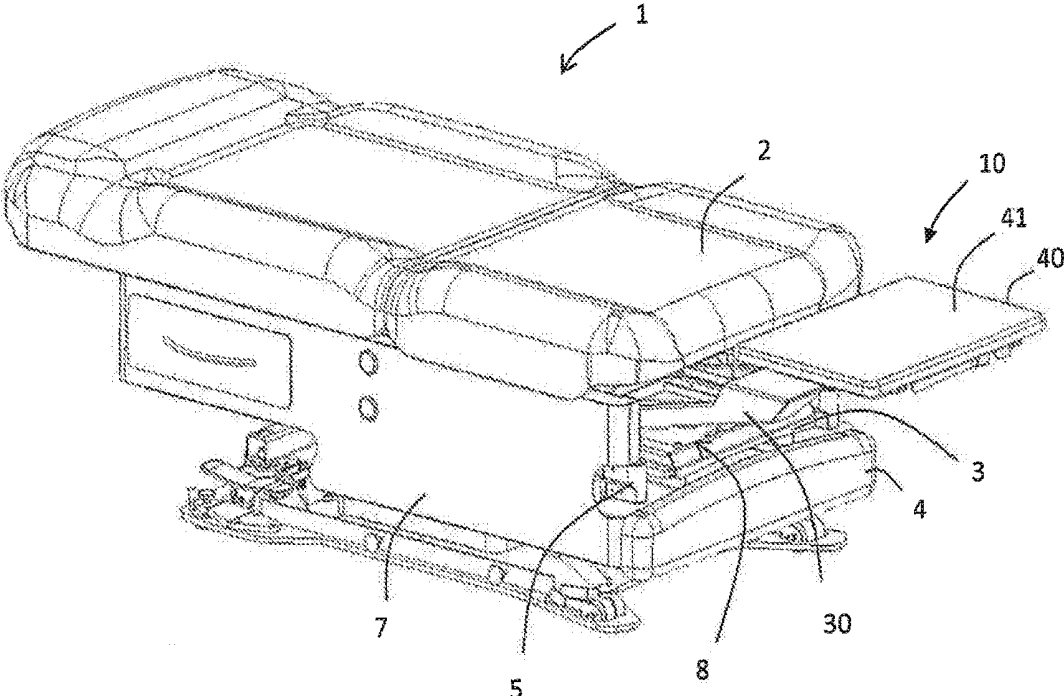


FIG. 1A

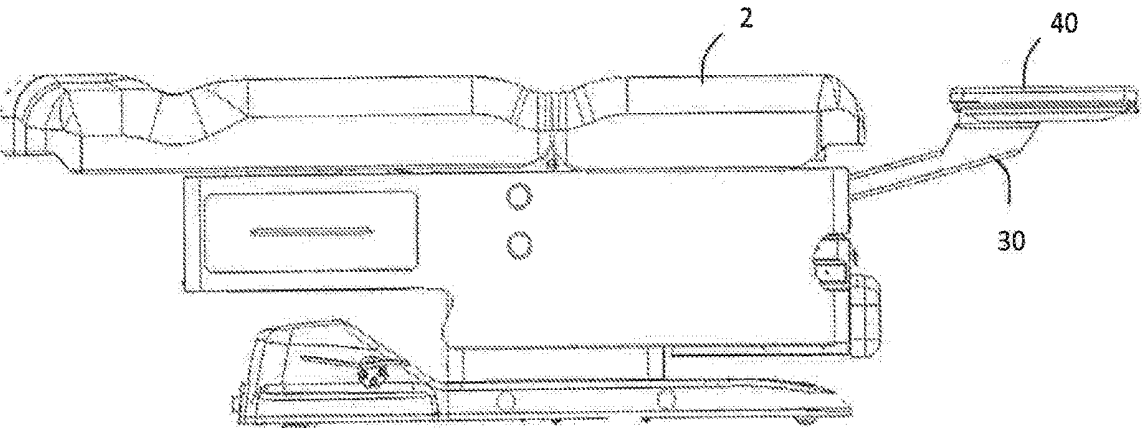


FIG. 1B

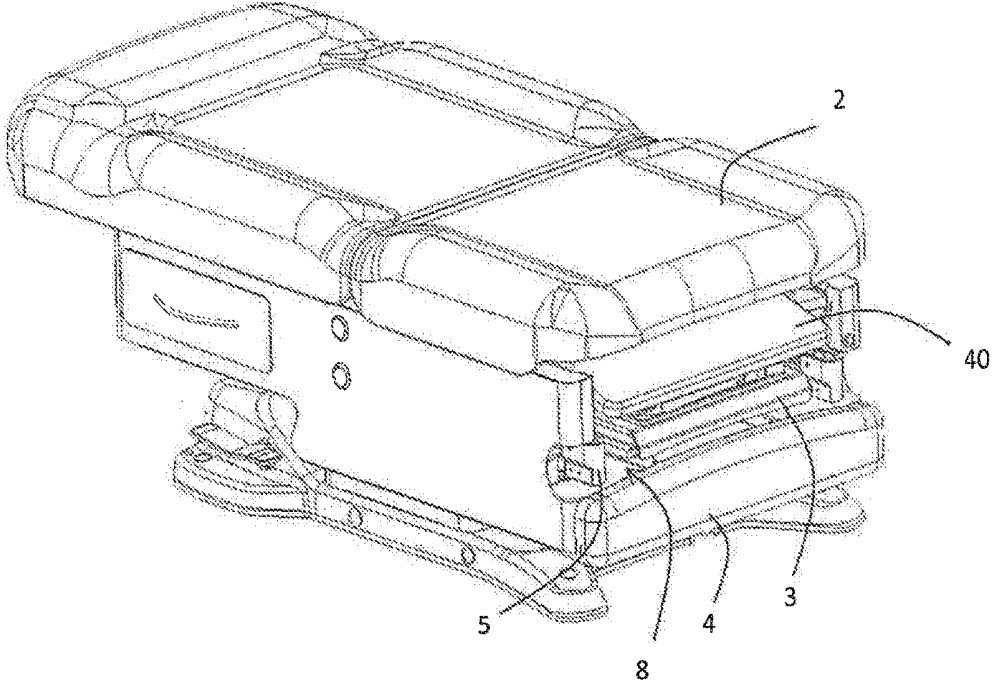


FIG. 2A

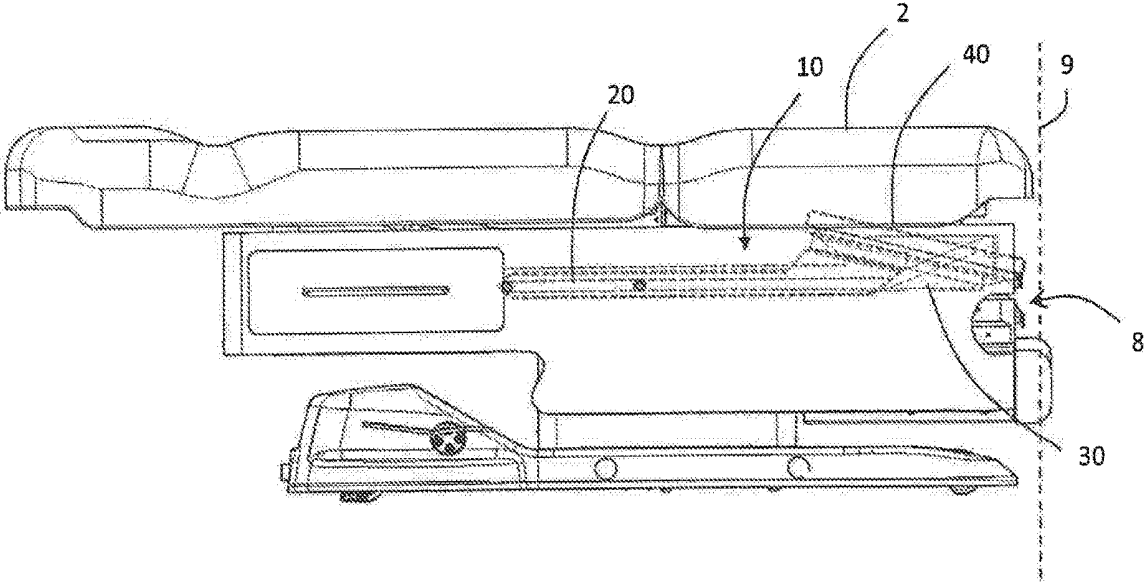


FIG. 2B

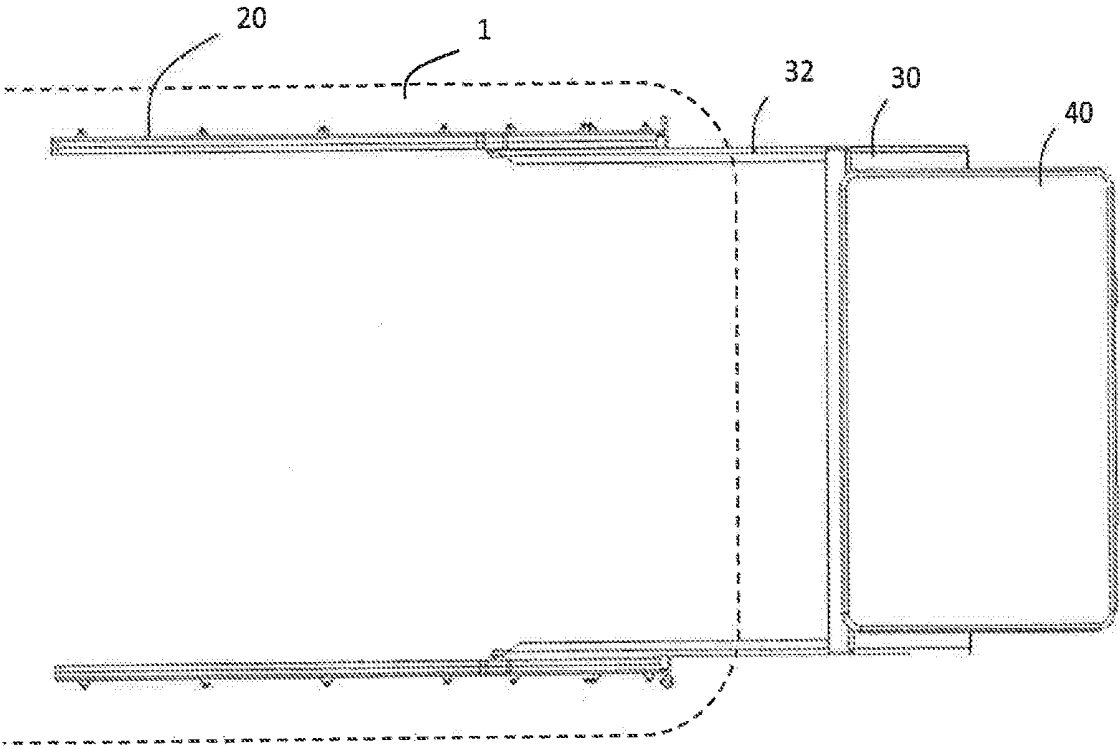


FIG. 3A

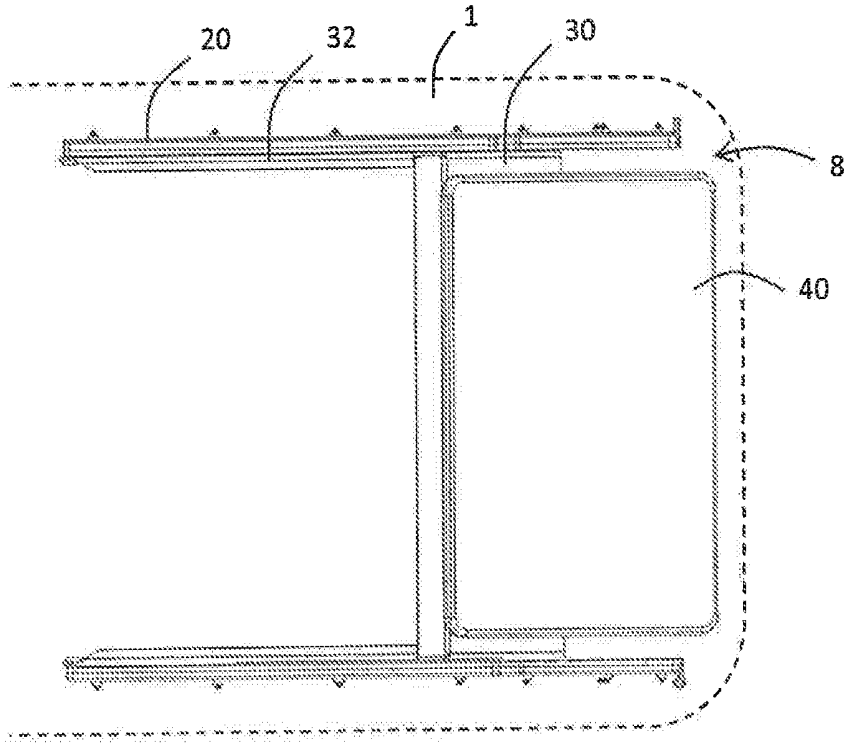


FIG. 3B

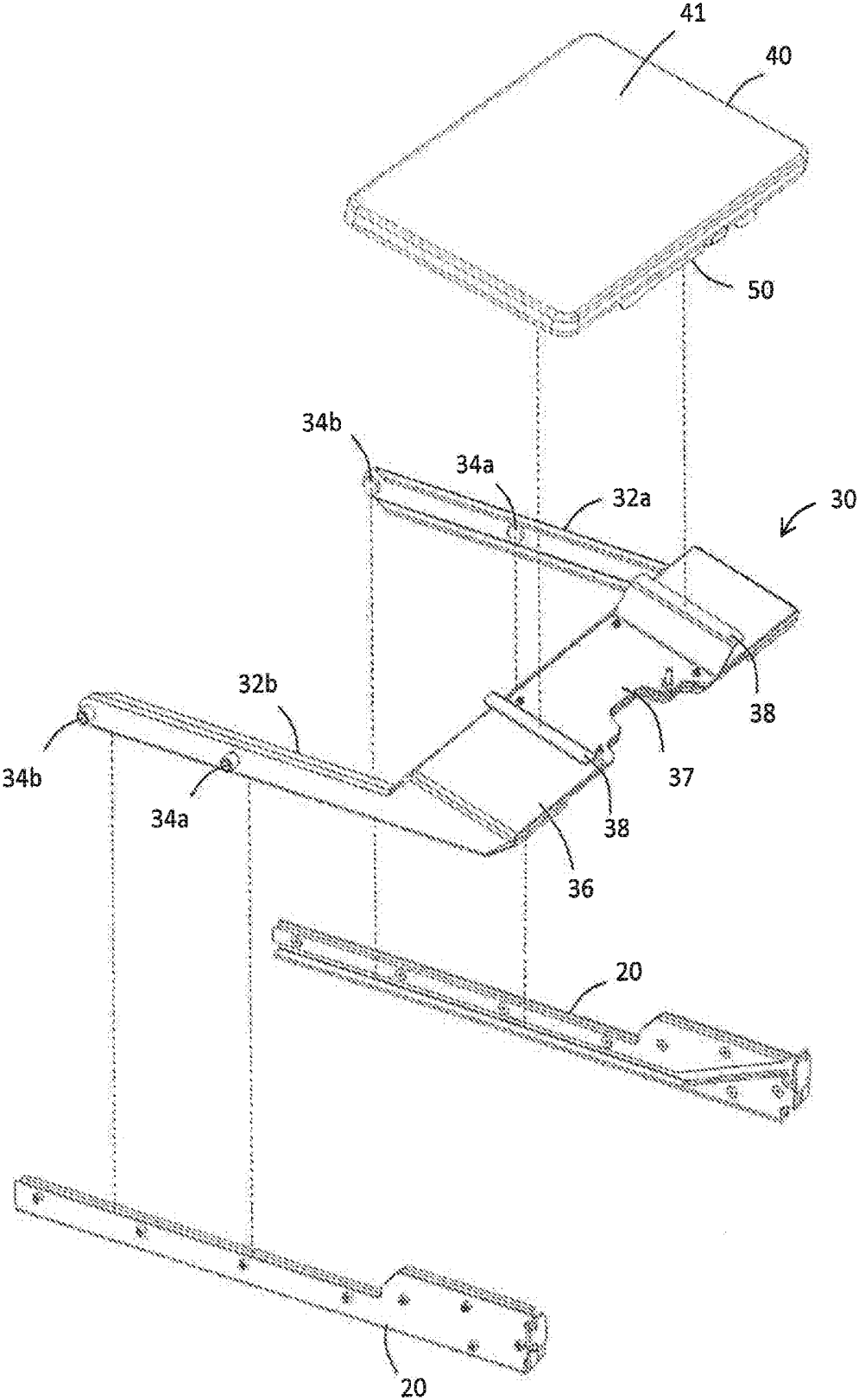


FIG. 4

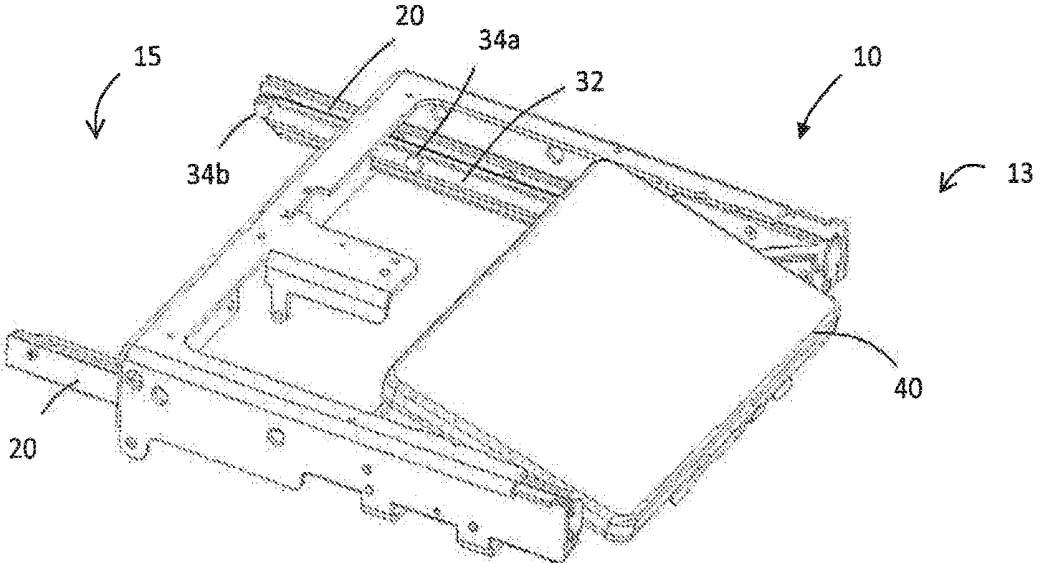


FIG. 5A

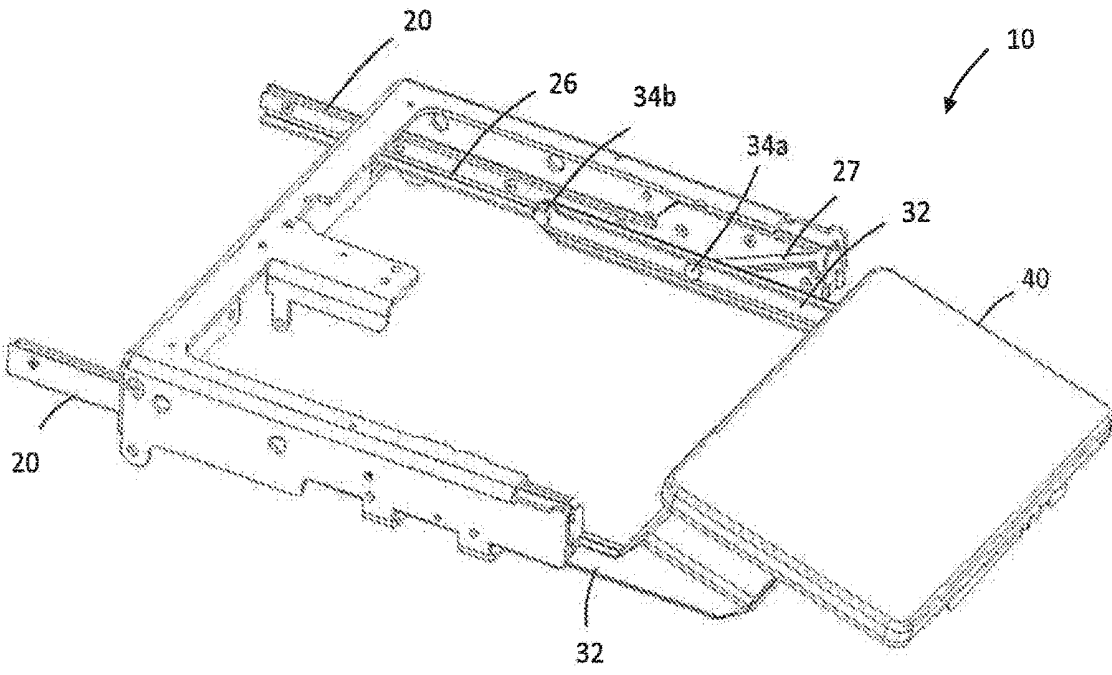


FIG. 5B

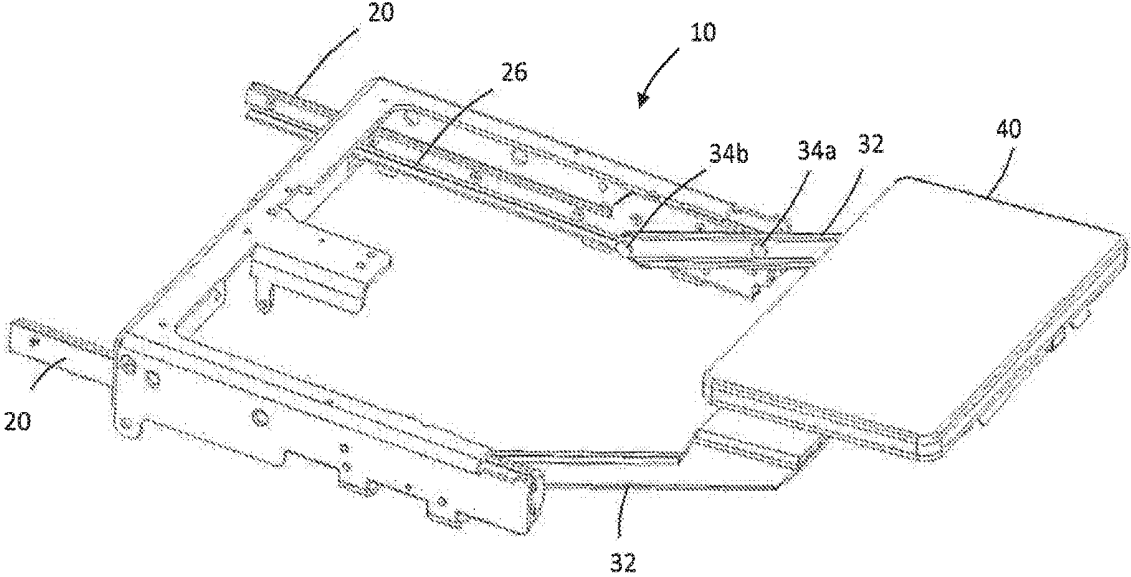


FIG. 5C

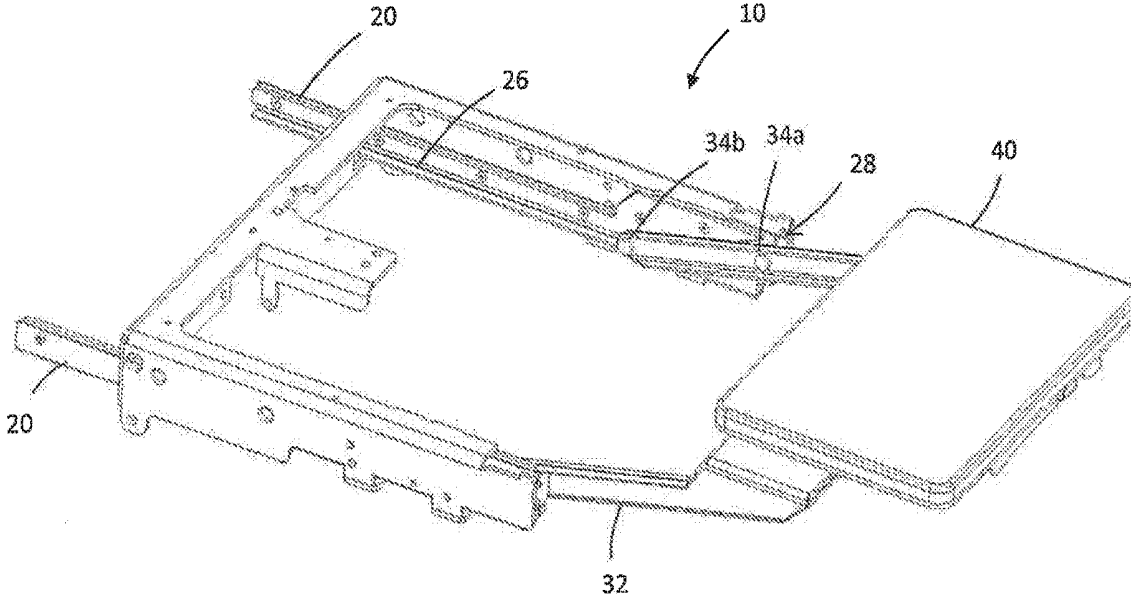


FIG. 5D

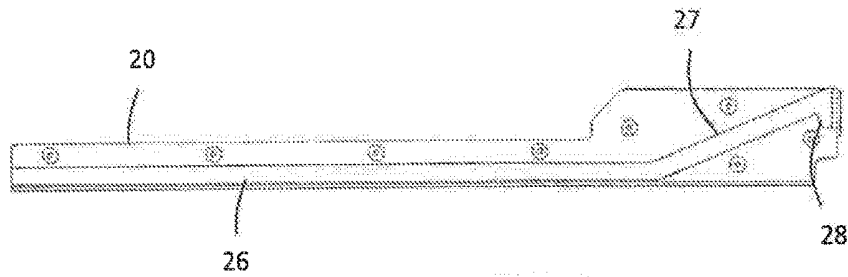


FIG. 6

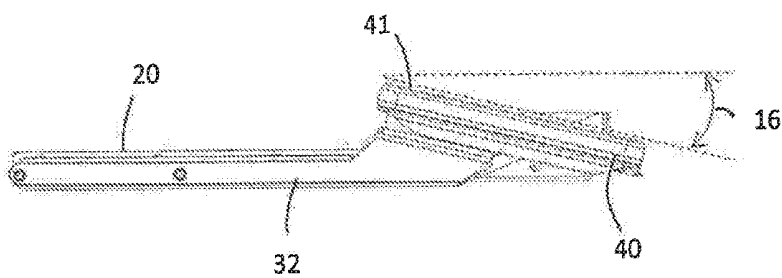


FIG. 7A

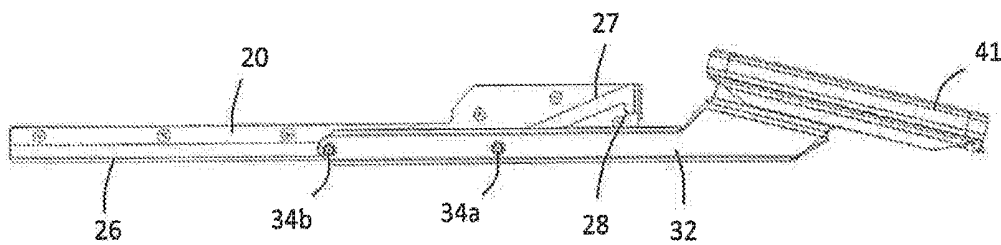


FIG. 7B

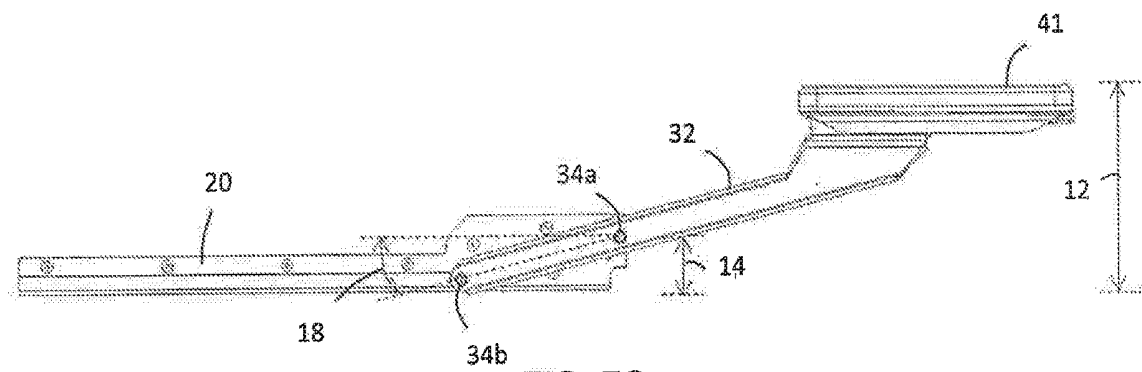


FIG. 7C

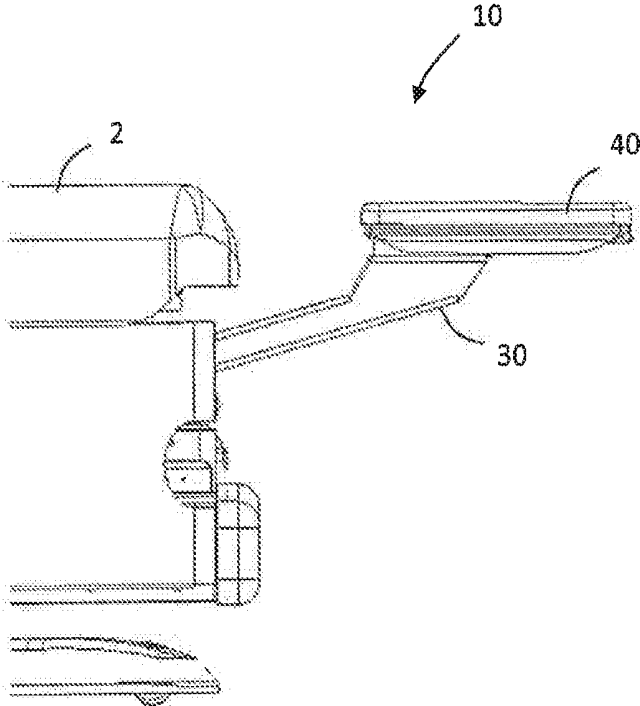


FIG. 8A

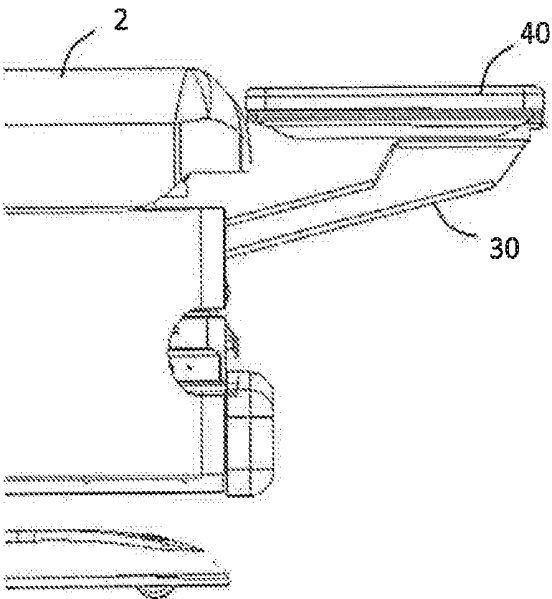


FIG. 8B

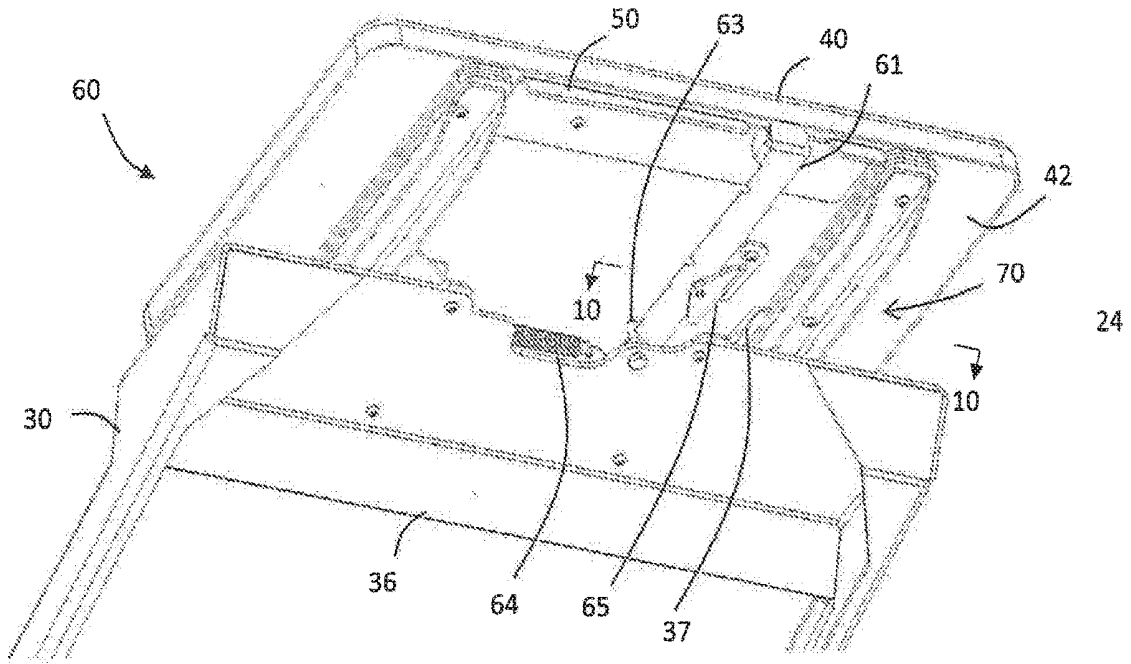


FIG. 9A

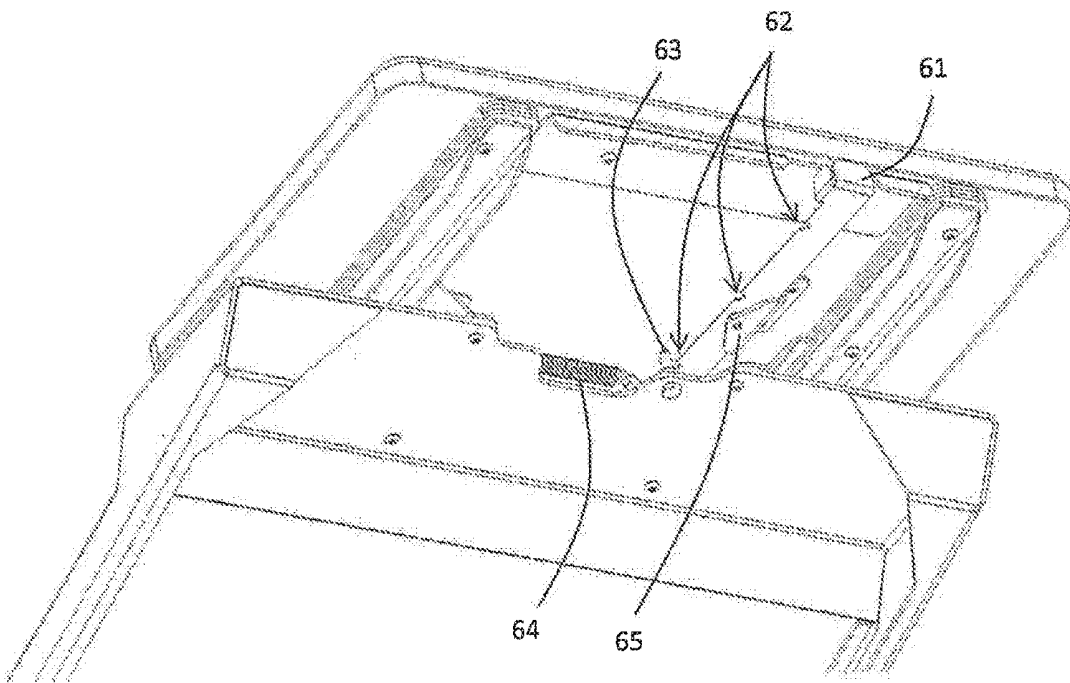


FIG. 9B

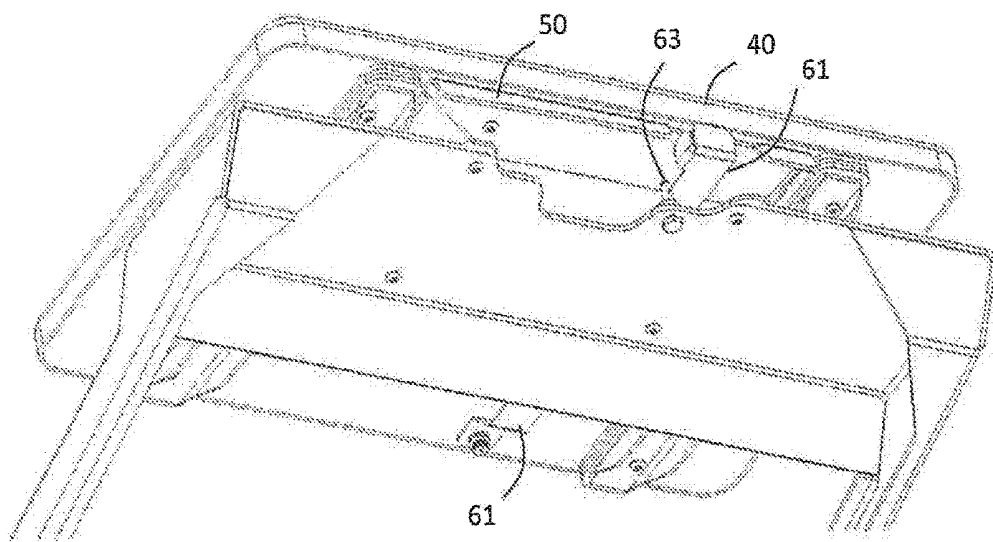


FIG. 9C

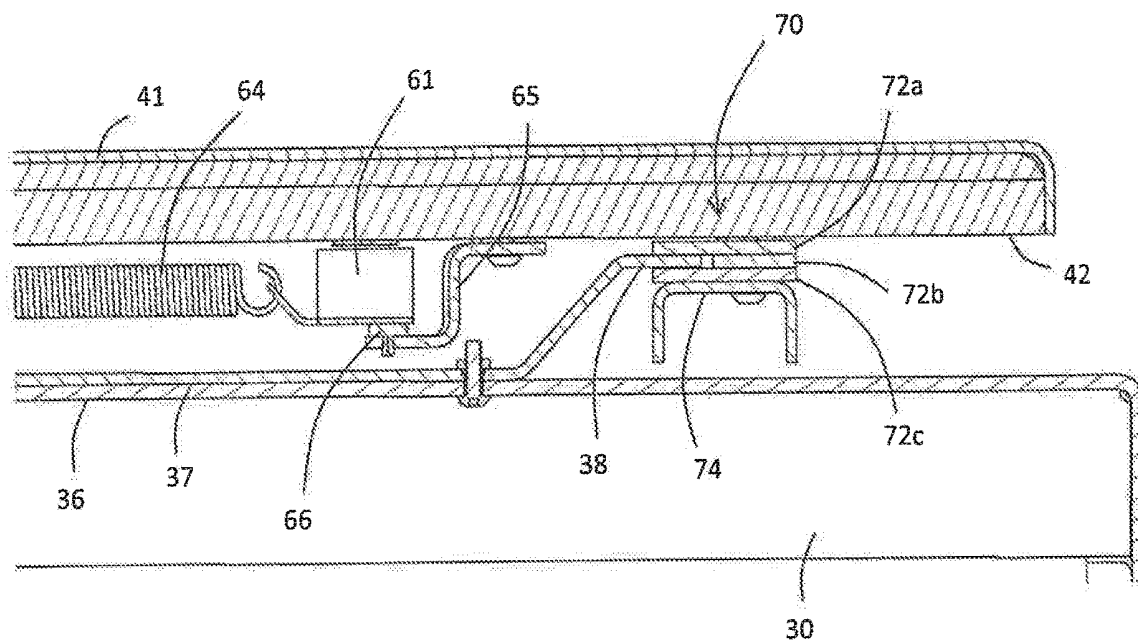


FIG. 10

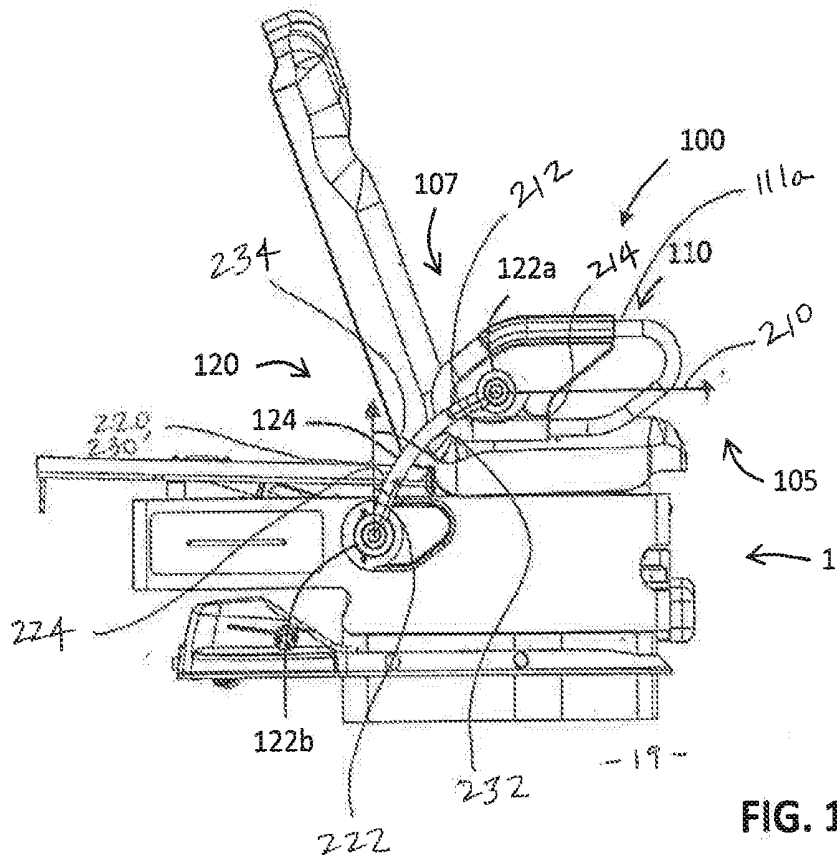


FIG. 11

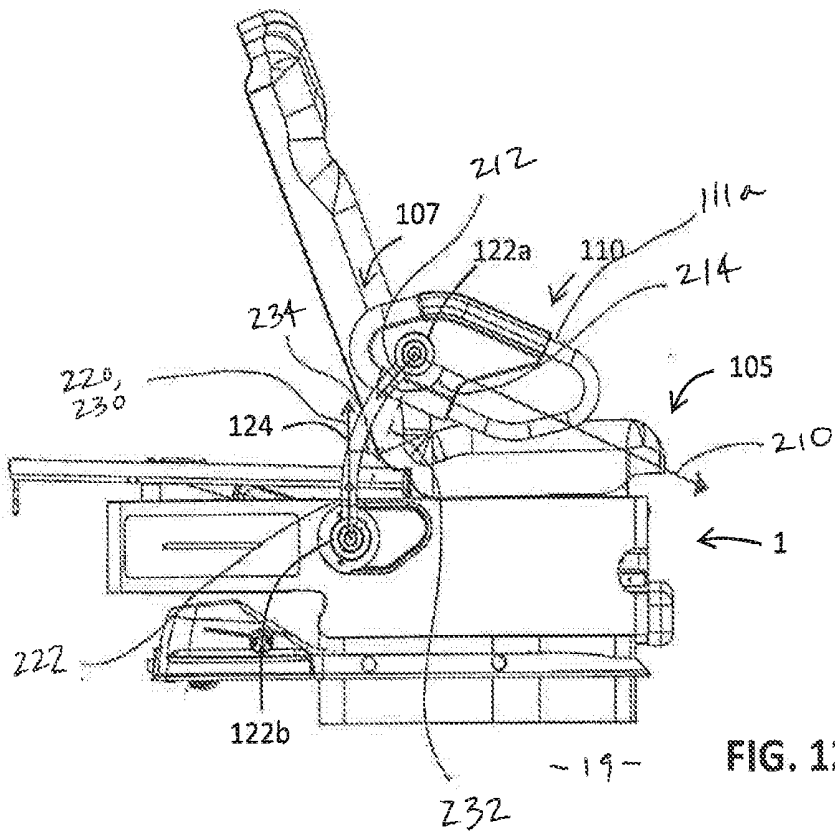


FIG. 12

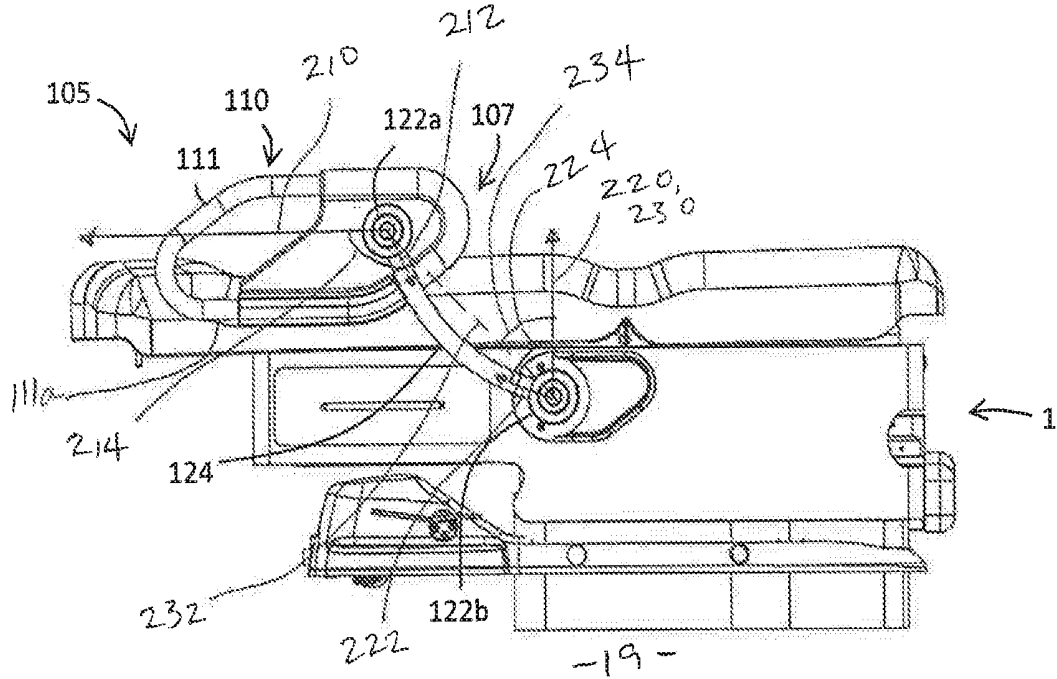


FIG. 13

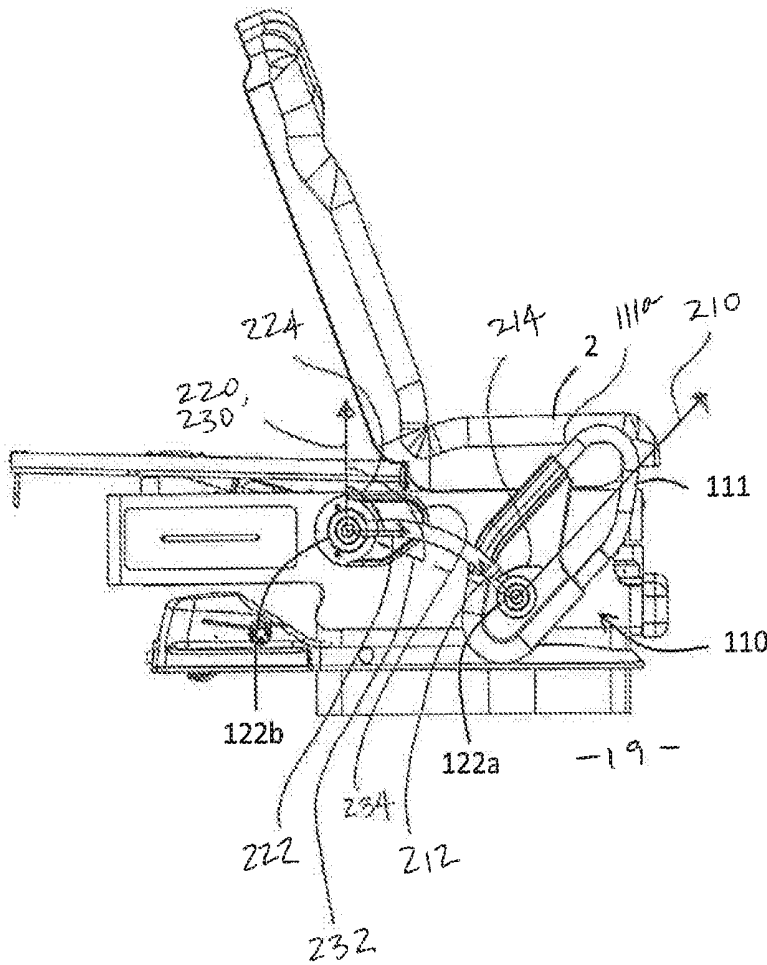


FIG. 14

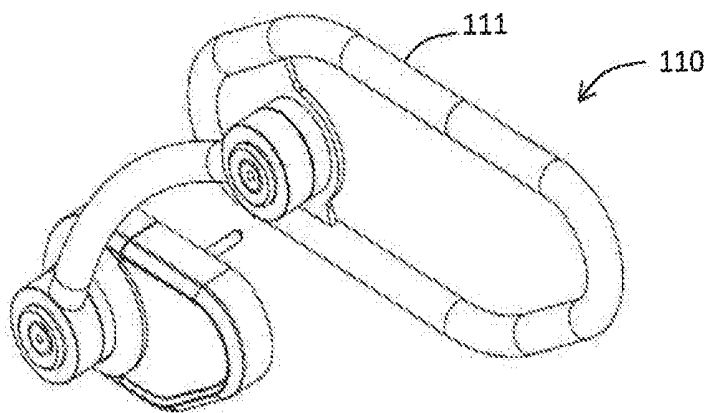


FIG. 15

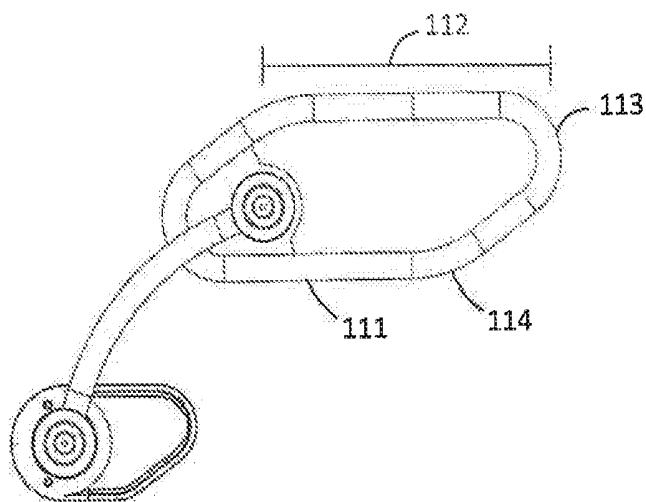


FIG. 16

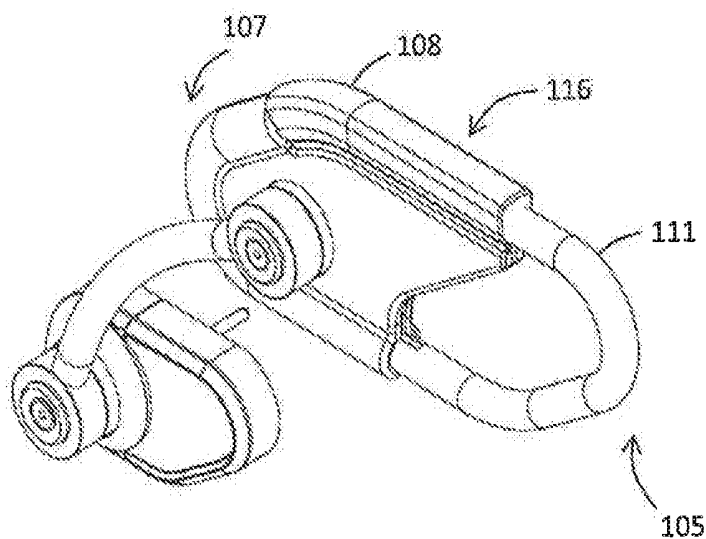


FIG. 17

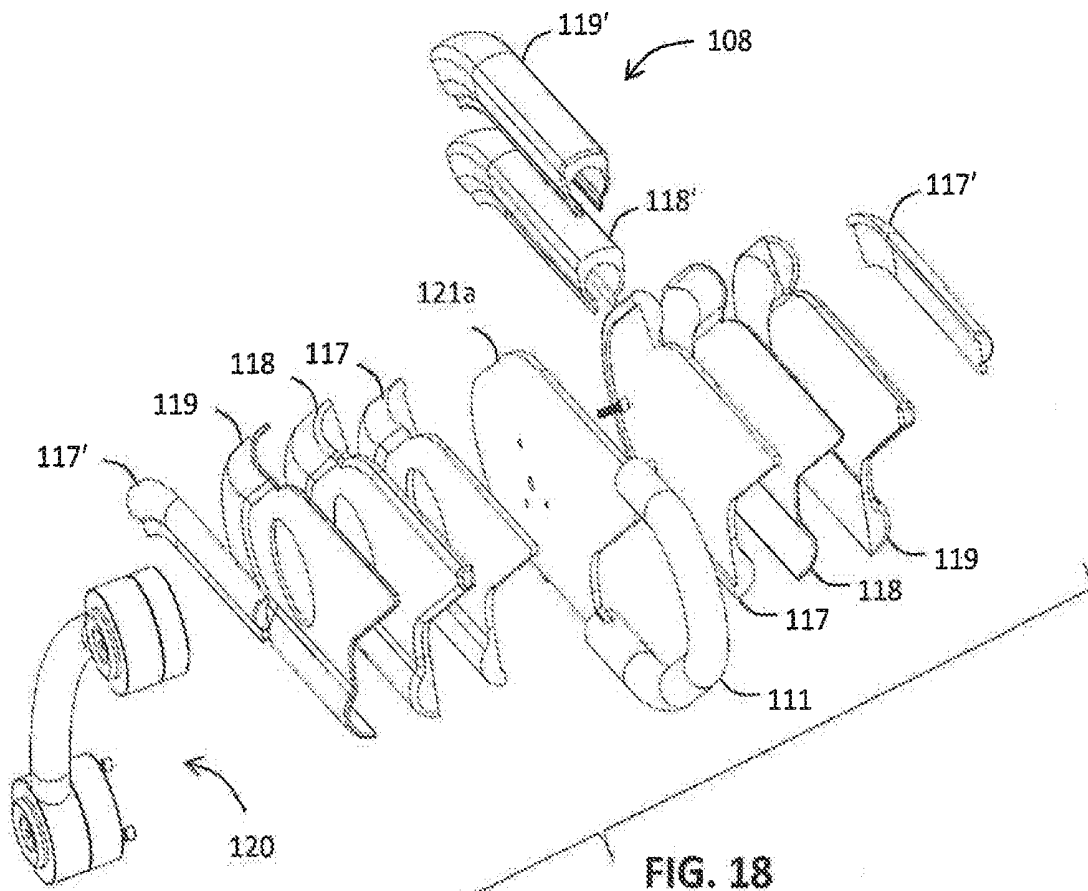


FIG. 18

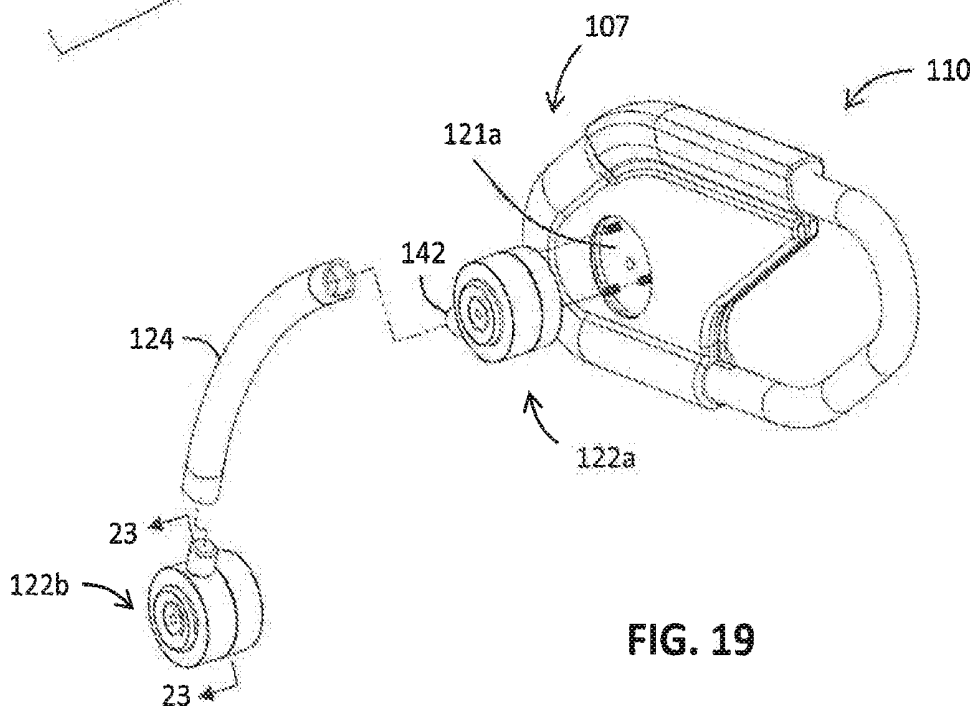


FIG. 19

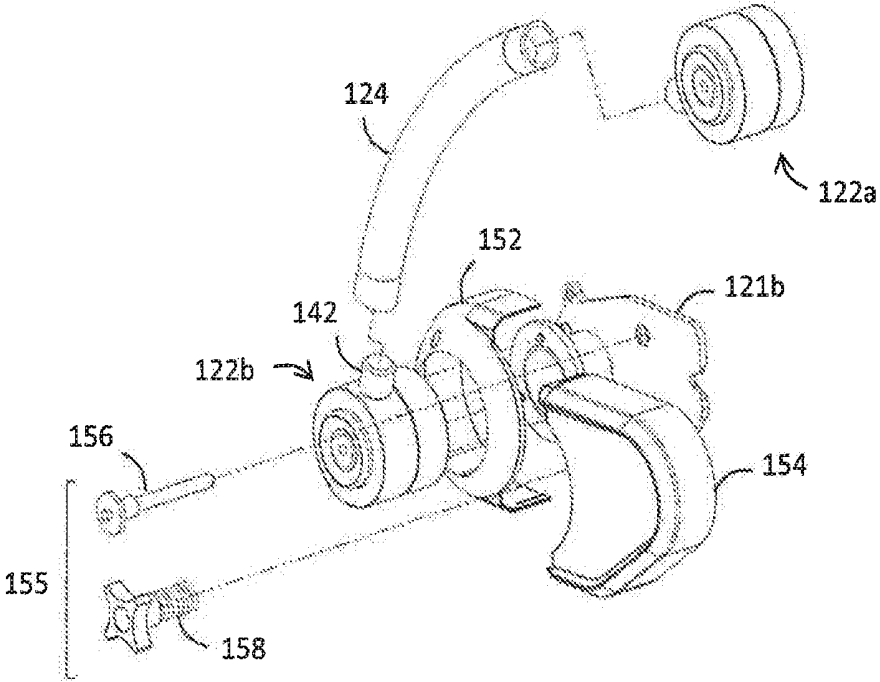


FIG. 20

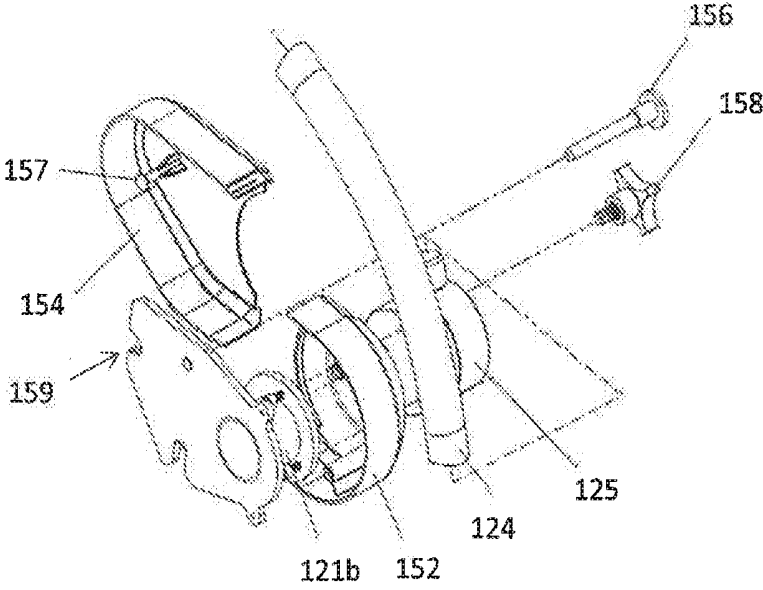


FIG. 21

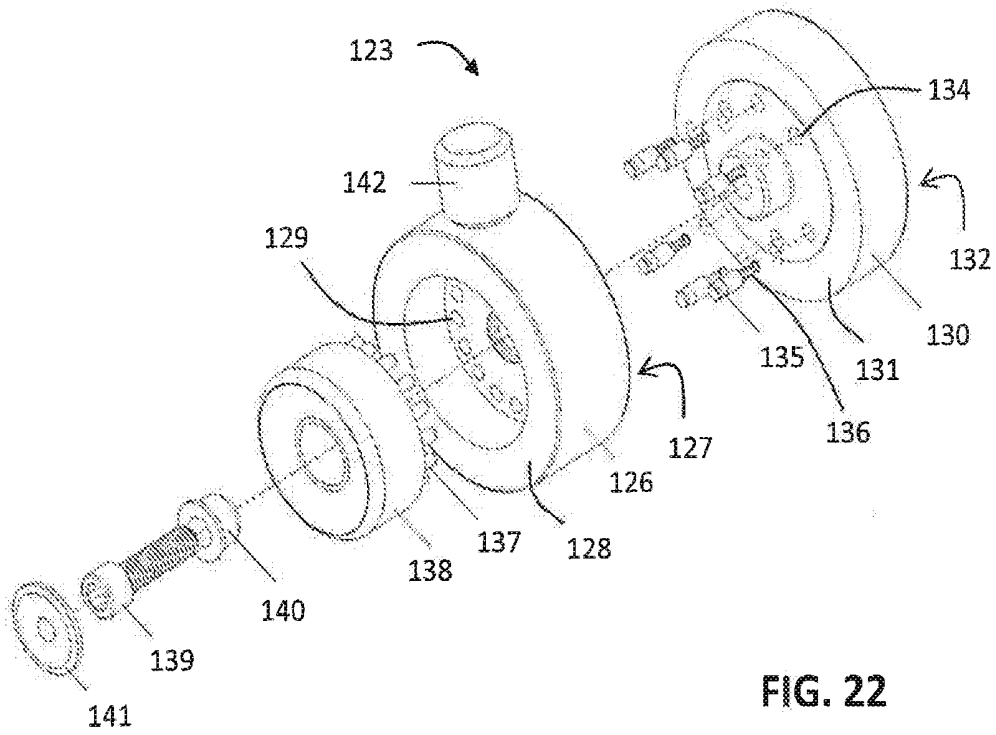


FIG. 22

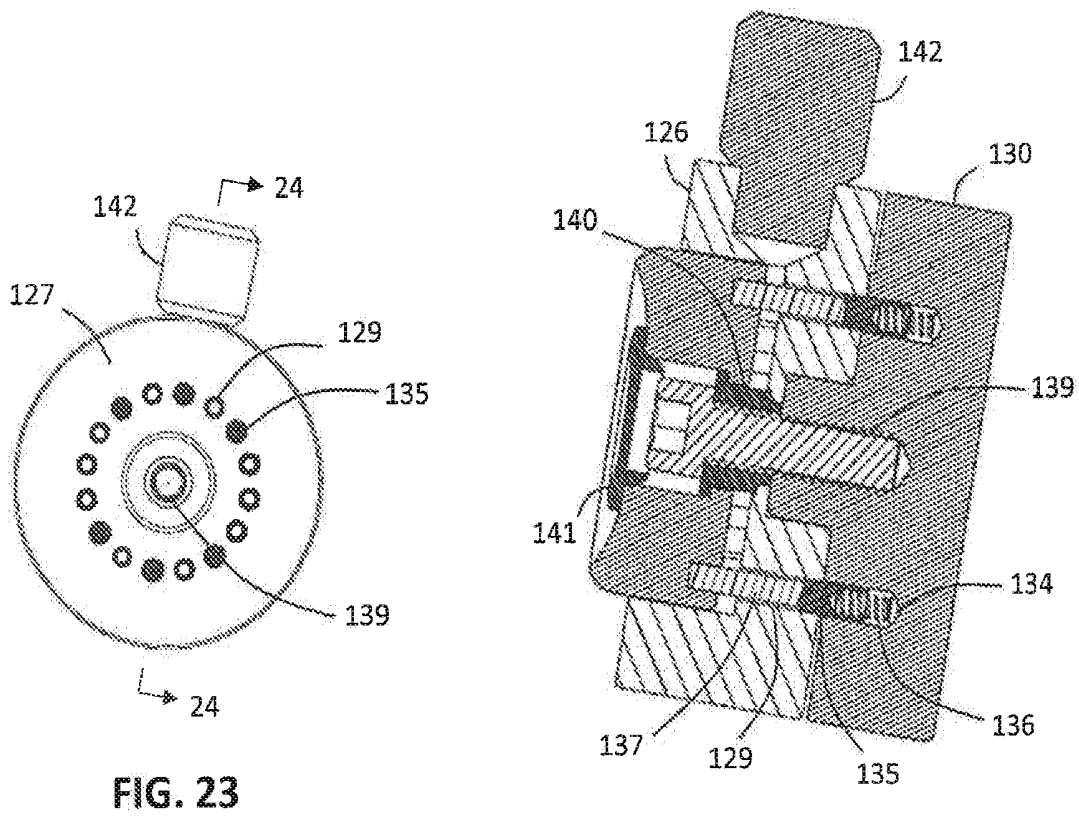


FIG. 23

FIG. 24

ARM SUPPORT ASSEMBLY FOR MEDICAL EXAMINATION DEVICE

FIELD OF THE INVENTION

[0001] This invention relates to medical examination devices such as tables and chairs, and more particularly, to leg and arm support assemblies for use on medical examination tables and chairs to improve examination effectiveness and patient comfort during examinations.

BACKGROUND

[0002] Medical examination devices, such as tables and procedure chairs, are commonly used in the medical industry to examine and treat patients in a seated or lying position. These devices are adjustable in the vertical direction to allow patients to get onto and off the device but bring the patient to the height the medical professional needs for the examination or treatment. The back is also adjustable to move from a seated position to a horizontal position allowing the patient to lie down. Often these adjustments are made once the patient is already on the table and may be made during the course of the examination or treatment. Medical examination tables also include a number of drawers, trays, pans, stirrups and other accessories that are stowed within the table, such as in a cavity underneath the seat cushion where the patient sits or lies. The drawers, trays and pans may hold supplies or instruments or may be used to collect fluids or other material that may run off the table during the examination or treatment. These accessories are stored flush with the front of the table so they do not obstruct the patient's legs hanging down from the table. However, they are still readily accessible so they may be pulled out of storage and used during the examination or treatment. Often the accessories are accessible from the front end of the table.

[0003] Once a patient is positioned lying back in a supine orientation, their legs extend past the edge of the table. Many medical examination tables have leg pads that are stowed in the table and extend horizontally out from the table to support the patient's legs. However, these leg pads are positioned lower than the body of the patient. This creates uncomfortable strain on the patient's lower back, hips and legs during the examination or treatment. It may also increase fluid flow to the legs, causing discomfort and swelling. It may also interfere with a clinician's ability to accurately perform an exam when the supine position is optimal for the patient. It is not a natural position in which to lie and so is generally uncomfortable or awkward for the patient. It would therefore be beneficial to have a way to support the patient's legs during an examination or treatment that is comfortable for the patient and a natural position.

[0004] Many medical examination devices such as tables and chairs have leg pads that are stowed in a vertical position along the base of the table and are rotated upward for deployment. However, this covers a substantial portion of the front end of the device, greatly limiting the use of pans, drawers and other accessories with the table or chair. It would therefore also be beneficial to have a medical examination device with leg support level with the device that permits the storage and use of drawers, pans, trays, and other accessories commonly found in medical examination tables.

[0005] Many medical examination devices such as tables and chairs also lack any form of arm support for the patient. This can be problematic, leaving the patient to support

themselves using only the table top or their own lap. Having an armrest is preferable for patients who may have to spend an extended period of time on the examination table, such as during or recovering from a procedure, or even just adjusting their positioning on the table. Procedure chairs, also used in the medical profession for examination and performing procedures, may include armrests that may be pivoted up and back to allow the patient access to and from the chair. While these provide some arm support, they are often not adjustable and provide only one deployed position in a seated position. Patients who are taller or shorter may find the positioning uncomfortable.

[0006] Furthermore, patients may have their blood pressure taken at the beginning of an examination or procedure, such as in collecting basic vital signs for patient records. This blood pressure reading is commonly taken while the patient is sitting before getting onto a medical examination device such as a table or chair since blood pressure readings should be taken when a patient is sitting with their feet placed firmly on a supporting surface such as the floor. More accurate readings are obtained when the patient's arm is raised so the bicep is level with or elevated above the heart, but this is an unnatural position that is awkward and may be difficult for a patient to maintain for the length of time needed to obtain an accurate blood pressure reading. In the medical industry, it is common to therefore rely on the substandard option of taking the blood pressure reading with the arm hanging down in a natural position with the hand on the lap or an armrest of a chair. Supporting the arm on an armrest of the table, bed or chair provides sufficient support for patient comfort, but sacrifices accuracy in the reading. Some have recently sought to address this problem by providing armrest covers that are adjustable into different angles, but these are separate from the armrest themselves and are subject to collapse when weight is applied. They do not provide sufficient support for a patient's arm.

[0007] It would therefore be beneficial to have an arm support that can comfortably and reliably support a patient's arm, and preferably may support the arm while taking blood pressure readings.

SUMMARY

[0008] The present invention addresses these concerns in a number of ways. For instance, a leg support assembly is configured to fit entirely within the cavity of a medical examination device, such as a table, for storage and may be pulled out for use. When deployed, the leg pad is brought out and up, bringing the leg pad level or co-planar with the seat cushion of the medical examination device. Therefore, with the seat back articulated downward so a patient can lay down, the leg support is ideally positioned level with the seat cushion for patient comfort, despite starting from a position below the level of the seat.

[0009] To accomplish this, the leg support assembly includes a track(s) that have a horizontal section, inclined section and detent. Guide members, such as pins or rollers, contacting the track(s) are moved from the horizontal section to the inclined section as the frame of the leg support assembly is pulled forward. As the first guide members contact the inclined section of track, the frame of the leg support assembly and the attached leg pad begin to elevate. At the top of the inclined section there is a detent into which the first guide member sits in the deployed position. Before dropping or otherwise positioning the frame so the first

guide member enters the detent, the leg pad is slightly above the level of the seat cushion. Once the first guide member is retained within the detent, the leg pad is brought level with the seat cushion. A second guide member at the rear of the track remains within the horizontal section throughout the deployment process and in both the stowed and deployed positions.

[0010] The frame that is movably attached to the tracks through the guide members is further configured to support the leg pad at an angle relative to the horizontal section of track. Accordingly, the leg pad is angled in a forward direction when stowed in the cavity of medical examination device. Rather than remaining at this downward angle once deployed, however, the configuration of the tracks changes the angle of presentation of the leg pad so that its upper surface is level or co-planar with at least the portion of the seat cushion on which the patient sits. This combination of the tracks, guide members and angle of leg pad mounting not only changes the presentation angle of the leg pad during deployment, but also achieves a greater vertical displacement of the leg pad between the stowed and deployed positions than the vertical space taken up by the leg support assembly within cavity of the medical examination device. This leg support assembly therefore minimizes space taken up in the cavity while maximizing the elevation achievable by the leg pad upon deployment and avoiding interference with other accessories also stored in the table. It is also easy to operate by the medical practitioner in an examination or treatment.

[0011] An arm support assembly is also provided that includes both an armrest and a connecting assembly for connecting to the medical examination device, such as a table or procedure chair. The armrest may be fully compliant with regulations and standards for transfer supports in medical diagnostic equipment. The connecting assembly and armrest are collectively adjustable to a number of locked positions to place the armrest in preferable orientations for a seated position, supine or lying position, blood pressure reading position, and stowed or patient transfer position. The connecting assembly includes first and second joints that are independently and selectively activated to engage a rotary mechanism and rotational motion of one portion of the joint in relation to another portion of the joint. A rigid elongate member connects the joints to each other, conveying motion from one end of the connecting assembly to the other. A first joint is mounted to the armrest and is a pivot point about which the armrest may be rotated. A second joint may be mounted to the side of the medical examination device, such as a table or chair, and may act as a pivot point for the elongate member. Accordingly, the arm support assembly provides a dual articulating system for full rotation about 360° when unlocked at two separate points to allow for increased freedom of movement and positioning than previous armrests can achieve.

[0012] The current leg support assembly and arm support assembly, together with their particular features and advantages, will become more apparent from the following detailed description and with reference to the appended drawings.

DESCRIPTION OF THE DRAWINGS

[0013] FIG. 1A is an isometric diagram of an embodiment of the medical examination device of the present invention showing the leg support assembly in a deployed position.

[0014] FIG. 1B is a side elevation view of the medical examination device of FIG. 1A.

[0015] FIG. 2A is an isometric diagram of the medical examination device of FIG. 1A showing the leg support assembly in a stowed position.

[0016] FIG. 2B is a side elevation view of the medical examination device of FIG. 2A.

[0017] FIG. 3A is a top plan view of the leg support assembly of FIG. 1A in a deployed position, showing the approximate location of the medical examination device in dotted lines.

[0018] FIG. 3B is a top plan view of the leg support assembly of FIG. 2A in a stowed position, showing the approximate location of the medical examination device in dotted lines.

[0019] FIG. 4 is an exploded view of the leg support assembly of the present invention.

[0020] FIG. 5A is an isometric view of the leg support assembly in the stowed position of FIG. 2A.

[0021] FIG. 5B is an isometric view of the leg support assembly of FIG. 5A in an intermediate extension position.

[0022] FIG. 5C is an isometric view of the leg support assembly of FIG. 5B in an intermediate inclined position.

[0023] FIG. 5D is an isometric view of the leg support assembly of FIG. 5C in a fully deployed position.

[0024] FIG. 6 is diagram of the interior side of one track of the leg support assembly.

[0025] FIG. 7A is a side elevation view of the leg support assembly of FIG. 5A in a stowed position.

[0026] FIG. 7B is a side elevation view of the leg support assembly of FIG. 5B in an intermediate extension position.

[0027] FIG. 7C is a side elevation view of the leg support assembly of FIG. 5D in a fully deployed position.

[0028] FIG. 8A is a side elevation view of the forward end of the medical examination device showing the leg support assembly in the deployed position.

[0029] FIG. 8B is a side elevation view of the medical examination device of FIG. 8A showing the leg pad of the leg support assembly in a retracted position.

[0030] FIG. 9A is an isometric bottom view of the leg support assembly in the fully deployed position and an embodiment of the slide mechanism in the extended position.

[0031] FIG. 9B is an isometric bottom view of the slide mechanism of FIG. 9A showing an unlocked position.

[0032] FIG. 9C is an isometric bottom view of the slide mechanism of FIG. 9A showing a retracted position.

[0033] FIG. 10 is a cross-sectional view of the leg support assembly of FIG. 9A along line 10-10.

[0034] FIG. 11 is a left side elevation of a medical examination device having one embodiment of the arm support assembly, shown in a seated position.

[0035] FIG. 12 is a left side elevation of a medical examination device having the arm support assembly of FIG. 11, shown in a blood pressure position.

[0036] FIG. 13 is a left side elevation of a medical examination device having the arm support assembly of FIG. 11, shown in a supine position.

[0037] FIG. 14 left side elevation of a medical examination device having the arm support assembly of FIG. 11, shown in a stored or patient transfer position.

[0038] FIG. 15 is an isometric view of a first embodiment of the arm support assembly.

[0039] FIG. 16 is a side plan view of the arm support assembly of FIG. 15.

[0040] FIG. 17 is an isometric view of a second embodiment of the arm support assembly, also shown in FIG. 11.

[0041] FIG. 18 is an exploded view of the armrest of the arm support assembly of FIG. 17.

[0042] FIG. 19 is a partially exploded view of one embodiment of the connecting assembly and armrest.

[0043] FIG. 20 is a partially exploded view of one embodiment of the connecting assembly and device attachment mechanism.

[0044] FIG. 21 is a partial exploded view of the shroud, device attachment mechanism and second joint of the arm support assembly FIG. 22 is an exploded view of a joint of the arm support assembly.

[0045] FIG. 23 is a plan view along the first surface of the first housing of a joint, shown along line 23-23 from FIG. 19.

[0046] FIG. 24 is a cross-sectional view of an assembled joint along line 24-24 from FIG. 23.

[0047] Like reference numerals refer to like parts throughout the several views of the drawings.

DETAILED DESCRIPTION

[0048] As shown in the accompanying drawings, the present invention is directed to a medical examination device 1 having at least one of an elevating leg support assembly 10 and/or an arm support assembly 100. As used herein, a medical examination device 1 may refer to a medical examination table, a procedure chair, or other piece of medical furniture that may be used to support a patient during an examination, diagnostic procedure, treatment procedure, or other medical attention. The medical examination device 1 having either or both leg support assembly 10 and/or an arm support assembly 100 provides an improved experience for both patient and practitioner. For instance, the leg support assembly 10 is co-planar with the seat cushion 2 of the examination device 1 when deployed for use, thereby providing improved patient comfort. The patient's legs no longer must be supported at a downward angle, as is the case with current examination tables. The fully flat position of the patient's legs relative to their body is more consistent with a natural supine position, such as when lying on a bed, as compared to having their legs at a downward angle relative to their body in a supine position. The patient may therefore feel more comfortable and stable in their position on the table. The co-planar positioning may also allow the practitioner to better access areas of the patient for examination and/or performance of procedures. Indeed, the level positioning of the patient's legs with their torso may be required for certain examinations and/or procedures, such as but not limited to abdominal exams and knee exams such as a sweep test. Further, the leg support assembly 10 is easily maneuverable by a practitioner for use and storage when not in use.

[0049] Turning now to FIGS. 1A-10, the medical examination device 1 includes a leg support assembly 10. Though reference is made to a "medical" examination table, it should be understood the leg support assembly 10 described herein may be used in conjunction with any type of examination table or support surface. Examples include, but are not limited to, for general medicine, internal medicine, ear nose and throat (ENT), gynecology, proctology, pediatric, gastrointestinal, podiatry, rheumatology, dentistry, optometry, ophthalmology, and imaging. Similarly, although described

herein as a table, the medical examination device 1 may be a table, chair, support device, or combination thereof. The medical examination device 1 may be adjustable in a variety of ways unrelated to the leg support assembly 10 or arm support assembly 100, such as but not limited to raising and lowering the support surface such as in a vertical direction, raising and lowering the back and/or headrest such as by rotating relative to the seat cushion 2, tilting the seat cushion 2 forward, rearward or side to side, and tilting the support surface, forward, rearward or side to side. Any or all of such medical examination device 1 adjustments may be performed manually or may be motorized.

[0050] Once the medical examination device 1 is positioned and adjusted as desired, the leg support assembly 10 may be positioned for use in a deployed position, as shown in FIGS. 1A-1B and 3A. The leg support assembly 10 includes at least one leg pad 40 positionable to receive and support a patient's leg(s) in the deployed position during examination or a procedure. The leg pad 40 may have any configuration suitable for receiving and supporting a patient's leg(s), such as but not limited to rectangular, square, round, oval, curved, grooved and bolstered. The leg pad 40 may be defined by a thickness measured in the vertical direction relative to the ground, a width measured along the side of the leg pad 40 that is parallel to the examination device 1, and a length measured along the side of the leg pad 40 that is perpendicular to the examination device 1. The leg pad 40 may have any suitable dimensions of thickness, width and height as may be appropriate for supporting a patient's leg(s). For instance, in at least one embodiment the width of the leg pad 40 may not exceed that of the examination device 1 and/or seat cushion 2. Similarly, the length of the leg pad 40 may be limited by the length of the examination device 1 or the total length of cushions placed on the examination device 1 (e.g. seat, back and head). Preferably, the leg pad 40 may have a slightly narrower in width than the examination device 1 and may be approximately one quarter of the length of the examination device 1. For instance, the leg pad 40 may measure from 12 to 30 inches wide by 6 to 24 inches long by 0.5 to 6 inches thick. In some embodiments, the leg pad 40 may measure 19.5 inches wide by 12.7 inches long by 0.85 inches thick. The thickness of the leg pad 40 will vary depending on the material of which it is made and the compressive and resilient characteristics of that material. However, the thickness as described herein is measured in the uncompressed state. The leg pad 40 may be made of any suitable material that provides sufficient compression to be comfortable to the patient but also stiffness or resilience to provide support. The material of the leg pad 40 may include upholstery that contacts the patient during use as well as foam, stuffing or padding underneath the upholstery for support, both of which provide support to the patient. For instance, the upholstery of the leg pad 40 may be cloth, microfiber, cotton, synthetic blends, nylon, polyester, leather, synthetic or imitation leather, rubber, silicone and combinations thereof, and may further include stitching. The padding may be made of foam, rubber, silicone, polymeric materials, composite materials, memory foam, beads or microbeads, gel- or fluid-filled cushion. These are but a few illustrative examples and are not intended to be limiting. The leg pad 40 may also include substrate 42 onto which the padding, cushioning and/or upholstery is affixed. Such substrate 42 is sufficiently rigid to provide structure to the leg pad 40 and

may define the underside of the leg pad 40 that is opposite of the upper surface 41 contacted by the patient's leg(s) in use. For instance, the substrate 42 may be made of wood, plastic, polymeric material, metal and metal alloys, or combinations thereof, to name a few non-limiting examples.

[0051] In some embodiments, the leg pad 40 may have a substantially planar configuration so as to receive and support the leg(s) of a patient thereon. As used herein, "substantially planar" means having a portion that extends along a plane for at least 50% of its top surface. Accordingly, in some embodiments as shown in FIGS. 1A-10, the leg pad 40 may be planar across its entire width and length. Such embodiments may be used universally for any suitable examination or procedure and can accommodate patient legs of any size, shape and length. In other embodiments, the leg pad 40 may include bolstering along at least one side, similar to that of the seat cushion 2 shown in FIGS. 1A-2B, such that bolstered sides of the leg pad 40 align with the bolstered sides of the seat cushion 2 and the center width of the leg pad 40 is substantially planar. In still further embodiments, the leg pad 40 may include more or less padding in various areas, creating a varying topography, with at least a portion of the leg pad 40 being planar. In still other embodiments, the leg pad 40 may have a curved or arcuate configuration in the vertical direction, such as being rounded or dipping in shape. In such embodiments, the leg pad 40 may include only a narrow strip that is planar in the length direction.

[0052] In the deployed position, the upper surface 41 of the leg pad 40 of the leg support assembly 10 aligns with at least a portion of the seat cushion 2 of the examination device 1. In other words, the upper surface 41 of the leg pad 40 measures the same distance from the floor or ground as the patient-receiving portion of the seat cushion 2. Accordingly, it may be said that at least a portion of the leg pad 40, such as the upper surface 41, is level with the seat cushion 2 in the deployed position. In some embodiments, this vertical measurement may be taken from anywhere along the centerline of the upper surface 41 of the leg pad 40 and the centerline of the top surface of the seat cushion 2. In some instances, it may be measured from a center of one side or the other of the leg pad 40 and seat cushion 2. The corresponding points measured may preferably be aligned in the longitudinal or length direction. In at least one embodiment, whether the leg pad 40 and seat cushion are aligned or level may involve a comparison of the adjacent edges of the leg pad 40 and seat cushion 2, respectively, in the deployed position.

[0053] As shown in the embodiment of FIGS. 1A-1B, the upper surface 41 of the leg pad 40 of the leg support assembly 10 may not only be aligned with but may be co-planar with the seat cushion 2 of the examination device 1. The term "co-planar" as used herein means a surface of the leg pad 40 that receives a patient's leg(s), such as an upper surface 41, extends along the same plane as the primary surface of the seat cushion 2 on which a patient sits during use of the examination device 1. For instance, the seat cushion 2 may have a substantially planar configuration, at least along the sitting portion, but may also include bolstering along the side edges, as shown in FIGS. 1A-1B. In such embodiments, the leg pad 40 of the leg support assembly 10 aligns with or is co-planar with the substantially planar primary surface the seat cushion 2.

[0054] In the deployed position, the leg pad 40 may be spaced apart a distance from the seat cushion 2 and/or

medical examination device 1, as in FIGS. 1B and 3A. The distance between the leg pad 40 and the seat cushion 2 and/or medical examination device 1 may be predetermined and may be defined by the dimensions and configuration of the leg support assembly 10, as described in greater detail later. For instance, the distance between the leg pad 40 and the seat cushion 2 and/or medical examination device 1 may be in the range of 3 to 12 inches, and preferably 6 inches in at least one embodiment. In further embodiments, the leg pad 40 may be positioned so that at least a portion of the leg pad 40 at least a portion of the seat cushion 2 and/or examination device 1 are adjacent or immediately next to one another in the deployed position, as in FIG. 8B. In some instances, the leg pad 40 may be positioned so that the leg pad 40 and seat cushion 2 contact, touch or are abutting one another. This may be beneficial for patients having shorter leg(s) or to ensure certain parts of the patient's leg is supported during the examination or procedure.

[0055] The leg pad 40 is also dimensioned to fit within a cavity 8 of the medical examination device 1 in a stowed position when not in use, which is depicted in FIGS. 2A-2B and 3B. In the stowed position, the entire leg support assembly 10 is housed within the medical examination device 1, such as underneath the seat cushion 2, back and head cushions in the rearward direction and does not extend beyond the plane 9 that defines the terminal forward edge of the examination device 1 and/or seat cushion 2. Accordingly, the cavity 8 may be defined as the space between the side panels 7 of the examination device 1, the underside of the seat cushion 2 or substrate to which it attaches, the floor or support structure underneath the medical examination device 1, and the terminal forward plane 9. The leg support assembly 10 may therefore have any dimensions such that at least the leg pad 40 and portions of the frame 30 and tracks 20 may be accommodated within the cavity 8 of a medical examination device 1. For instance, the cavity 8 may measure 6.5 inches by 14.9 inches by 24.3 inches. In at least one embodiment, and depending on the structure and various accessories, the cavity 8 may measure 13 inches by 32 inches by 32 inches.

[0056] In certain embodiments, the cavity 8 may be limited by the inclusion of other components or accessories stored within the medical examination device 1. For instance, a medical examination device 1 may include a pan 3 that may be used as a drip pan to collect errant fluids during an examination or procedure, or to hold instruments. A drawer 4 may also be included to hold various items such as instruments, linens, exam garments, covers, pillows, and medical equipment or supplies. Stirrups 5 may be present for use in gynecological examinations and procedures. As is common, these additional features may be stored within the medical examination device 1 under the seat cushion 2 and pulled out from a forward terminal end of the examination device 1 for use. When present, these features may reduce the size of the cavity 8 available for storing the leg support assembly 10. For instance, in certain embodiments, the leg support assembly 10 may have dimensions of 3.9 inches by 22 inches by 21.3 inches when a pan 3, drawer 4 and stirrups 5 are included. If any of these accessories are removed, there may be greater height available for the leg support assembly 10, such as up to 8 inches in certain embodiments. Ultimately, the upper limit of the dimensions for the leg support assembly 10 may be defined by the dimensions of the medical examination device 1 and the cavity 8 therein.

[0057] As is most evident from FIGS. 2A-2B and 7A, the leg pad 40 is positioned at an angle 16 relative to the horizontal when in the stowed position. This angle 16 may be any angle greater than zero degrees and less than 90 degrees relative to the horizontal and may be selected based on the size of the leg pad 40 and the dimensions of the cavity 8. In some embodiments, the angle 16 may be in the range of 10-40 degrees from the horizontal. In other embodiments, the angle 16 may be in the range of 12-15 degrees from the horizontal. In at least one embodiment, the angle 16 may be 13.5 degrees from the horizontal. It should be appreciated that angle 16 may be any angle, whole or fraction thereof, in the range of 0-90 degrees.

[0058] The leg support assembly 10 includes not only a leg pad 40, but also a frame 30 and tracks 20, shown in FIGS. 4-5D. With particular reference to FIG. 4, the frame 30 includes two elongate portions 32a, 32b disposed parallel to one another. A cross member 36 may span between the elongate members 32a, 32b at one end thereof, bridging the distance between them and connecting them. In at least one embodiment, the cross member 36 and elongate members 32a, 32b may be integrally formed with one another of a single piece construction. In some embodiments, however, they may be secured to one another such as by welding, soldering, melting, adhesive, or other permanent attachment. In still other embodiments, the cross member 36 may be secured to the elongate members 32a, 32b by non-permanent securing members, such as but not limited to bolts, screws and other like reversible securing mechanism. The ends of the elongate portions 32a, 32b at which the cross member 36 joins are formed at an angle relative to the horizontal such that the cross member 36 sits at an angle relative to the longitudinal axis of the elongate portions 32a, 32b. This angle defines the angle 16 of the leg pad 40 in the stowed position, as will become clear.

[0059] The frame 30 may be configured to support a leg pad 40. For instance, the frame 30 may connect directly or indirectly to the leg pad 40, which may be a secured or flexible connection. In at least one embodiment, the frame 30 may further include an attachment member 37 that joins the leg pad 40 to the frame 30. With reference to FIGS. 4 and 9C-10, the attachment member 37 secures to the cross member 36 with screws, bolts, nuts, adhesive or the like. The attachment member 37 may further include at least one extension 38 configured to project outwardly from the frame 36. For instance, in at least one embodiment as shown in FIGS. 4 and 10, the attachment member 37 may be a bracket or other similar joining mechanism where the extensions 38 are wings or arms extending upwardly at an incline and outwardly toward a peripheral edge of the frame 36. The incline of the extension 38 may be any angle up to and including 90 degrees relative to the surface of the cross member 37 to provide space between the cross member 37 and the terminal end of the extension 38. The terminal end of the extension 38 may extend parallel to the surface of the cross member 36 and may extend toward any of the peripheral edges of the frame 30. In some embodiments, as in FIG. 4, the attachment member 37 may include multiple extensions 38. Extensions 38 within the same attachment member 37 may extend at the same or different angles of incline relative to the surface of the cross member 36 as one another and may be directed toward the same or different peripheral edges of the frame 30. The length of the terminal ends of

each extension 38 may be the same or different from one another, and they may have the same or different configurations.

[0060] Further, the attachment member 37 may be secured to any location along the cross member 36. In some embodiments, there may be a plurality of attachment members 37, each secured to the cross member 36. The various attachment members 37 may be secured in different orientations relative to one another, or in the same orientation, along the cross member 36. The angle of incline and the direction and/or length of the terminal end of the extension 38 among the various different attachment member 37 may be the same or different from one another.

[0061] In at least one embodiment such as shown in FIGS. 4 and 10, the leg pad 40 includes a spacer assembly 70 that connects the leg pad 40 to the frame 30. Specifically, the spacer assembly 70 may include at least one buffer 72 that is secured to the underside of the leg pad 40 or substrate 42 thereof by a backing 74 and screw, nut and bolt, pin, or other suitable attachment mechanism that retains the buffer 72 between the underside of the leg pad 40 and the backing 74. The buffer 72 may be made of a rigid or semi-rigid material, such as but not limited to plastic(s), polymeric material, metal(s) and metal alloys. The backing 74 may be made of the same or different material as the buffer 72 and may have any suitable configuration for contacting the buffer 72. For instance, the backing 74 may have a U-shape as depicted in FIGS. 9C and 10, with the central portion contacting the buffer 72. In other embodiments, the backing 74 may be planar, curved, angular, C-shaped, L-shaped, V-shaped or other shapes capable of contacting the buffer 72 along at least a portion thereof, including as little as a point or line there along.

[0062] In at least one embodiment, as depicted in FIGS. 9C and 10, the spacer assembly 70 may include a plurality of buffers 72a, 72b, 72c positioned adjacent to one another in a contacting configuration, which may be stacked as shown. The buffers 72a, 72b, 72c may be made of a rigid or semi-rigid material, such as but not limited to plastics, polymeric material, metals and metal alloys. In at least one embodiment, the spacer assembly 70 is secured to the underside of the leg pad 40 or substrate 42 thereof by a screw, nut and bolt, pin, adhesive, or other suitable attachment mechanism that retains the buffers 72a, 72b, 72c in contacting relation to one another and against the underside of the leg pad 40.

[0063] At least one of the buffers 72b may have a different configuration from at least one of the adjacent buffers 72a, 72c to either side so that a space or groove is formed between the buffers 72a, 72b, 72c when in contact with one another. For instance, in some embodiments, non-contacting buffers 72a, 72c may have the same configuration, such as but not limited to a bar, block or other shape. The intermediate buffer 72b may have a smaller configuration but smaller in one direction. The difference in the configurations or shapes of the non-contacting buffers 72a, 72c and intermediate buffer 72b when positioned together forms the aforementioned space or groove. In other embodiments, the space or groove may be formed by a notch formed in one side of the intermediate buffer 72b. In some embodiments where there is only a single buffer 72, the space or groove may be a space adjacent to the buffer 72 and defined by adjacent edges of the underside of the leg pad 40, the buffer 72, and the backing 74. In at least one embodiment, the

spacer assembly 70 is secured to the underside of the leg pad 40 or substrate thereof with the space/groove facing inward toward the center of the leg pad 40. The leg pad 40 may include two or more such spacer assemblies 70, and each may be secured such that the space/groove of each is facing inward toward the center of the leg pad 40. In other embodiments, the space/groove may be facing outwardly from or at an angle relative to the center of the leg pad 40.

[0064] The space or groove formed in the spacer assembly 70 is sized and dimensioned to receive and retain at least the terminal end of the extension 38 of the attachment member 37 of the frame 30. With reference to FIGS. 4 and 10, the leg pad 40 may be attached to the frame 30 by positioning the leg pad 40 such that the spacer assembly 70, specifically the groove thereof, is aligned with the extension 38 of the attachment member 37. In at least one embodiment, the groove of the spacer assembly 70 receives the extension 38 of the attachment member 37, such as the terminal end thereof, shown in FIG. 10. The extension 38 may be retained within the groove of the spacer assembly 70 by gravity, since the backing 74 holds and affixes the spacer assembly 70 to the underside of the leg pad 40. Accordingly, in at least one embodiment the spacer assembly 70 may be held securely onto the leg pad 40, but not so tightly that the groove formed therein is compressed. The groove is dimensioned to allow the attachment member 37, specifically the extension 38 thereof, to be inserted therein, such as by a sliding action. In some embodiments, the extension 38 may also be freely slid out of the groove of the spacer mechanism 70, such as when it is desired to change the leg pad 40 for one with a different shape, configuration, material composition, etc. In other embodiments, however, the leg pad 40 may be firmly affixed to the frame 30 and not readily removable. For instance, the backing 74 may be secured to an initial tightness in assembling the spacer assembly 70, and then may be further tightened once the extension 38 of the attachment member 37 is inserted in the groove, thus including the extension member 38 in securing the attachment member 37 to the leg pad 40.

[0065] Returning to FIG. 4, once the leg pad 40 is connected to the frame 30 at the attachment member 37, the leg pad 40 assumes the angle 16 as previously discussed, since it is the same as the angle of the cross member 36 and/or attachment member 37 relative to the elongate members 32a, 32b of the frame 30. Indeed, in at least one embodiment, the end of the elongate members 32a, 32b that connect to the cross member 36 may be formed with a predetermined and fixed configuration producing an angle that is followed by the cross member 36, as shown in FIG. 4.

[0066] The frame 30 further includes at least a first guide member 34a and second guide member 34b affixed at predetermined locations along the length of an elongate member 32. In certain embodiments, the frame 30 may include pairs of first guide members 34a and pairs of second guide members 34b. The guide members 34a, 34b extend through the elongate member 32 and outwardly from the outer surface thereof. For the avoidance of doubt, references to “outer” or “exterior” throughout this disclosure refers to the direction of the periphery of the leg support assembly 10, whereas “inner” or “interior” may be used to refer to the direction toward the three-dimensional center of the leg support assembly 10. The guide members 34a, 34b may be pins, rollers, wheels and axles, rods, or other suitable structures that extend through the elongate member 32. In

some embodiments, the guide members 34a, 34b may include bearings, bushings, or other similar structures disposed coaxially or concentrically about at least a portion of the guide members 34a, 34b, such as the portion which extends beyond the outer surface of the elongate member.

[0067] A predefined fixed length separates the first and second guide members 34a, 34b, which may be any distance along the length of the elongate member 32. In at least one embodiment, for instance, the first and second guide members 34a, 34b may be separated by 7.5 inches. The first guide member 34a is positioned closer to the cross member 36 and the forward end 13 of the leg support assembly 10. In at least one embodiment, the second guide member 34b may be located at or near a terminal end of the elongate member 32 opposite from the cross member 36. It should be noted that, although the guide members 34a, 34b are positioned at fixed locations, they may be movably secured within the elongate member 32. For instance, the guide members 34a, 34b may be rollers or wheels free to rotate about an axis without changing their location along the length of the elongate member 32. In other embodiments, the guide members 34a, 34b may be fixedly secured within or to the elongate member 32, such as but not limited to pins or rods. In at least one embodiment, the frame 30 includes two elongate members 32 and each includes a first guide member 34a and a second guide member 34b. The first guide members 34a of parallel elongate members 32 may be aligned with one another, and the second guide members 34b of parallel elongate members 32 may be aligned with one another.

[0068] Referring to FIG. 4, the leg support assembly 10 further includes at least one track 20, and preferably a pair of tracks 20 that may be configured to correspond to the frame 30. For instance, each track 20 may have an elongate length similar in length and/or size to the elongate member 32 of the frame. Indeed, the elongate length of the tracks 20 correspond to the elongate members 32 of the frame 30. As shown in FIG. 4, each track 20 is dimensioned to receive the first and second guide members 34a, 34b of the frame 30. The first and second guide members 34a, 34b may be moved along the length of the track 20.

[0069] The track 20 includes a horizontal section 26, an inclined section 27 and a detent 28, such as is depicted in FIG. 6. The horizontal section 26 extends along at least a portion of the length of the track 20. In at least one embodiment, the horizontal section 26 may extend along a majority of the length of the track 20. The inclined section 27 extends from the horizontal section 26 at an angle thereto, which may be any angle greater than zero degrees and less than 90 degrees relative to the horizontal section 26. For instance, in some embodiments, the angle of incline of the inclined section 27 may be in the range of 10° to 60°, and in certain embodiments may be 22°. In at least one embodiment, the inclined section 27 extends from one end of the horizontal section 26 and is co-extensive and continuous with the horizontal section 26. The length of the inclined section 27 may be any length limited only by the length of the track 20. In at least one embodiment, for instance, the inclined section 27 may measure 5.9 inches. The detent 28 may extend from the inclined section 27 at an angle thereto, such as in the range of 10° to 90° relative to the horizontal section 26, and in some instances may be in the range of 18° to 45°. In at least one embodiment, the detent 28 extends from a terminal end of the inclined section 27 that is opposite from the horizontal section 26. Accordingly, the

detent 28 may be co-extensive and continuous with the inclined section 27. The detent 28 may have any shape or configuration, but generally is configured to support a first guide member 34a at a height that is lower than the highest point of the inclined section 27. The horizontal section 26, inclined section 27 and detent 28 may therefore collectively form a continuous contact surface for the first and second guide members 34a, 34b. In at least one embodiment, the detent 28 may be configured to receive and retain at least a portion of a guide member 34 therein to secure the guide members 34 along the track 20 and therefore to secure the leg support assembly 10 in a deployed position.

[0070] Each track 20 may be secured to the interior of the medical examination device 1, such as to the inside of the side panels 7 defining the cavity 8. The outer surface of each track 20 abuts and contacts the side panel 7 or frame of the medical examination device 1 and may be secured thereto by any suitable connection mechanism such as but not limited to screws, nuts, bolts, welding, soldering, and adhesive. The guide members 34a, 34b contact and are received by the tracks 20, slidably joining the frame 30 to the tracks 20. The leg pad 40 then affixes to the frame 30 through the attachment member 37, as described above.

[0071] The leg support assembly 10 remains stowed within the cavity 8 of the medical examination device 1 until it is needed. In the stowed position, as shown in FIGS. 2B, 5A and 7A, the leg pad 40, and specifically the upper surface 41 of the leg pad 40, is positioned at angle 16 relative to the horizontal and fits entirely within the cavity 8. When stowed, the leg pad 40 is angled downward in the forward position, as shown in FIGS. 2A-2B and 7A, and both sets of guide members 34a, 34b are in the horizontal section 26 of the track 20, shown in FIGS. 5A and 7A. In a fully stowed position, the second guide members 34b may be located at the rearward terminal end of the track 20.

[0072] When it is desired to have the leg pad 40 available for patient use, a practitioner or other user may grasp and pull the leg pad 40, such as by the handle 50 thereof, in a forward direction. As used herein, "forward" is the direction in which the cavity 8 of the medical examination device 1 opens and the direction in which a patient's legs extend off the table when seated therein, and is shown as the first end 13 in FIG. 5A. "Rearward" is the opposite direction, toward the head of the table, shown as the second end 15 in FIG. 5A. As the leg pad 40 moves forward, the attached frame 30 similarly moves. The guide members 34a, 34b move along a common track 20 in a forward direction, as shown in FIG. 5B. When the first guide members 34a reach the inclined section 37 of the track 20, the leg support assembly 10 has traveled the maximum amount of distance in a purely horizontal disposition and has reached an intermediate extension position shown in FIGS. 5B and 7B. Further forward movement of the leg pad 40 pulls the first guide members 34a into the inclined section 27. As the first guide members 34a move along the inclined section 27, the frame 30 and leg pad 40 moves both outward and upward, elevating the leg pad 40 from its original position. When the first guide members 34a reach the forward end of the inclined section 27, the leg pad 40 has achieved the maximum vertical displacement from its original position and may be slightly higher than the seat cushion 2 of the examination device 1. The second guide members 34b remain in the horizontal section 26 of the track 20, even at this forward-most position, shown in FIG. 5C. To lock the leg support

assembly 10 in a deployed position, shown in FIGS. 5D and 7C, the leg pad 40 is lowered vertically, moving the first guide member 34a into the detent 28 of the track 20. The detent 28 receives and retains the first guide member 34a, such as by gravity. When the leg pad 40 or handle 50 is released, the leg support assembly 10 remains in the deployed position, shown in FIGS. 5D and 7C. To return the leg support assembly 10 to the stowed position, the leg pad 40 or handle 50 is simply lifted to move the first guide member 34a out of the detent 28, at which point the first guide member 34a is free to slide rearward down the inclined section 27 and back along the horizontal section 26.

[0073] In the deployed position shown in FIGS. 5D and 7C, the upper surface 41 of the leg pad 40 is co-planar with at least a portion of the seat cushion 2 of the medical examination device 1, as depicted in FIG. 1A-1B. This is distinct from current medical examination tables in which the leg pad slides out from a stored position below the table but remains parallel to and below the level of the seat cushion. The present invention delivers a way to elevate the leg pad 40 so that it is level with the seat cushion 2 when deployed, providing greater comfort to the patient and benefitting the provider as well.

[0074] Not only does the leg support assembly 10 deploy the leg pad 40 so its upper surface 41 is even with the seat cushion 2, but the vertical distance 12 the leg pad 40 travels from the stowed position to the deployed position is greater than the vertical distance 14 the first guide member 34a travels within the slot 22, as shown in FIG. 7C. In other words, the present leg support assembly 10 is able to achieve greater elevation of the leg pad 40 than the height dimension of the cavity 8 where the leg support assembly 10 is stowed. The vertical distances 12, 14 will vary depending on the dimensions of the medical examination device 1, which will direct the available space in the cavity 8 and the maximum dimensions of the leg support assembly 10. For example, in some embodiments, vertical distance 12 may be about 6.7 inches whereas vertical distance 14 may be 1.7 inches. However, the ratio of vertical distance 12 to vertical distance 14 may be fixed and may be in the range of 1.5 to 10, such as about 3.9 in some embodiments. The particular ratio of vertical distance 12 to vertical distance 14 may depend on the size and strength of materials used in the tracks 20 and frame 30. For instance, a smaller ratio may be achieved with longer tracks 20 and frame elongate members 32, but requires stronger material, and vice versa.

[0075] The enhanced elevation is due in part to the angling of the leg pad 40 and the inclined nature of the slot 22. Specifically, the angle 18 formed between the guide members 34a, 34b when in the deployed position relative to the horizontal (or relative to the line formed by the guide members 34a, 34b in the stowed position) is substantially equivalent to the angle 16 of the leg pad 40 relative to the horizontal (or relative to the horizontal section 26 of the track 20) in the stowed position. As used herein, "substantially equivalent" means no appreciable difference perceived by the patient and may include within tolerance of ± 10 degrees, although greater deviations are also contemplated so long as the upper surface 41 of the leg pad 40 is substantially coplanar with at least a portion of the seat cushion 2. Angles 16 and 18 may be any angle greater than zero degrees and up to 90 degrees, limited only by the dimensions of the cavity 8 and leg pad 40. In at least one embodiment, angles 16 and 18 may be in the range of 2-20

degrees, and preferably be 13.5 degrees. Notably, angle 18 is not the same as the angle of the inclined section 27. Indeed, angle 18 may be smaller than the angle of the inclined section 27 relative to the horizontal, since angle 18 is formed by the positions of the guide members 34a, 34b in the deployed position in which the first guide member 34a is lowered into the detent 28, therefore changing the angle.

[0076] The leg support assembly 10 may be positioned in a number of deployed positions. The angles of the guide members 34a, 34b and leg pad 40 remain the same regardless of the deployed positions. However, in a first deployed position, shown in FIG. 8A, the leg pad 40 is co-planar with but spaced apart a distance from the seat cushion 2. In a second deployed position, as in FIG. 8B, the leg pad 40 is co-planar with and abutting, adjacent or contacting the seat cushion 2. For the avoidance of doubt, the terms “abutting,” “adjacent,” and “contacting” may be used interchangeably with reference to the relationship between the leg pad 40 and seat cushion 2 to mean at least one portion of the leg pad 40 is next to at least one portion of the seat cushion 2 so there is no appreciable distance between the relevant portions of each. In at least one embodiment, the first deployment position is achieved initially upon moving the leg support assembly 10 out of stowage. It may remain in this first deployed position or may be retracted horizontally into the second deployed position if so desired. For instance, it may be preferable to have the leg pad 40 abutting, adjacent or contacting the seat cushion 2, such as for patients with shorter legs, or if support of the patient’s legs throughout their length is preferred without a gap.

[0077] The leg support assembly 10 may include a slide mechanism 60 to facilitate the movement of the leg pad 40 between the first and second deployed positions. For instance, as shown in FIGS. 9A-10, the slide mechanism 60 includes a locking lever 61 attached to the leg pad 40. As before, attachment to the leg pad 40 may be directly to the leg pad 40 itself or to a substrate 42 to which the leg pad 40 padding and/or upholstery is secured. The locking lever 61 may preferably have a length that spans at least a portion of the length of the leg pad 40. The locking lever 61 may be attached to the underside of the leg pad 40 in any orientation, but in at least one embodiment is attached in the length dimension of the leg pad 40 between the forward and rearward sides of the leg pad 40, with the rearward side of the leg pad 40 being the closest to the seat cushion 2. The locking lever 61 may be pivotally attached to the underside of the leg pad 40 as shown in FIG. 10 and may be held in position with a biasing member 64, such as but not limited to a spring. The biasing member 64 pulls the locking lever 61 toward itself, which may be overcome by pushing against the locking lever 61 in the opposite direction. Accordingly, the locking lever 61 is movably secured to the leg pad 40.

[0078] The sliding mechanism 60 may further include a support member 65 spaced apart from and dimensioned to receive at least a portion of the locking lever 61. For instance, in at least one embodiment of FIGS. 9A and 10, the support member 65 may be secured to the leg pad 40 spaced apart a distance from the locking lever 61 in a lateral direction. The distance of separation may vary but is smaller than the total possible displacement of the locking member 61 when selectively moved, such as by pivoting. In at least one embodiment, the support member 65 may be secured to the leg pad 40 opposite from the biasing member 64, such that the locking lever 61 is positioned between the biasing

member 64 and the support member 65. The support member 65 is dimensioned to receive at least a portion of the locking member 65 in an unlocked position. In at least one embodiment, the unlocked position may be achieved by applying pressure to the locking lever 61 in a direction opposite from the biasing member 64.

[0079] In some embodiments, the support member 65 may also include a protrusion 66 that extends outwardly from the support member 65 and is configured to engage the locking lever 61, to hold it in a spaced relation to the support member 65 and provide support to the locking lever 61 so it need not cantilever from its pivot point. The protrusion 66 may be rubber, silicone, plastic or other suitable material that may provide support to the locking lever 61 but also permit movement of the locking lever 61 there along such as in the lateral direction. In such embodiments, the locking lever 61 may therefore contact a portion of the support member 65, such as the protrusion 66, even when the locking lever 61 is in a locked position. In such embodiments, the locking lever 61 remains spaced apart from at least one other portion of the support member 65, as shown in FIG. 10, which may receive the locking lever 61 upon application of force to overcome the biasing member 64.

[0080] In at least one embodiment, the locking lever 61 may include a plurality of notches 62 or similar structure formed therein. The notches 62 may be formed in one side of the locking lever 61, preferably the side that faces the biasing member 64. Each notch 62 corresponds to a different position in which the leg pad 40 may be moved closer to or further from the seat cushion 2. There may be any number of notches 62 in the locking lever 61 depending on the number of desired positions of the leg pad 40. The slide mechanism 60 may also include a locking member 63 configured to retain the slide mechanism 60, and therefore the leg pad 40, in a particular position. Specifically, the locking member 63 extends through the frame 30, such as the cross member 36, and may be perpendicular to the locking lever 61 and notches 62 disposed therein. The locking member 63 is configured to fit at least partially within the notch 62 of the locking lever 61. In at least one embodiment, the locking member 63 may be a screw, bolt, pin, or other similarly elongate structure that secures to the frame 30. Each notch 62 may have a diameter and/or shape corresponding to the diameter of the locking member 63, such as circular or semi-circular, so as to at least partially receive the locking member 63 therein.

[0081] In a locked position as in FIG. 9A, the locking lever 61 is biased by the biasing member 64 so that a notch 62 is biased against the locking member 63. FIG. 9A shows the leg pad 40 positioning and slide mechanism 60 in the initial deployed position of FIG. 8A. To move the leg pad 40 rearward, pressure is applied to the locking lever 61 in a direction away from the biasing member 64, as in FIG. 9B. This pressure overcomes the force of the biasing member 64 and moves the locking lever 61 in the direction of and against the support member 65, although contact is not required. The notch 62 is no longer in contact with the locking member 63, and the leg pad 40 is freely slidable in the axial direction of the locking lever 61. When another notch 62 aligns with the locking member 65, the pressure on the locking lever 61 may be released. The force of the biasing member 64 draws the locking lever 61 away from the support member 65 and pulls the notch 62 into contact with the locking member 63 so it receives at least a portion

of the locking member 63 therein. The locking member 63 in the notch 62 prevents axial movement of the leg pad 40 along the axis of the locking lever 61. This process may be repeated to move the leg pad 40 between the various positions delineated by the notches 62 present along the locking lever 61. It should be appreciated that the notches 62 need not be engaged sequentially, but rather the particular notch 62 for the corresponding position desired may be selected before releasing the pressure on the locking lever 61 against the support member 65. FIG. 9C depicts an embodiment of a fully retracted deployed position in which the leg pad 40 is abutting the seat cushion, as in FIG. 8B. Here, the forward-most notch 62 of the locking lever 61 engages the locking member 63. Accordingly, the fully extended deployment position of FIG. 8A may be achieved by engaging the rearward-most notch 62 along the locking lever 61.

[0082] In other embodiments, the leg pad 40 may be moved in along the continuum of the locking lever 61 to any position there along and is not limited by predefined notches 62. For example, the locking member 63 may be a clamp or similar structure capable of frictional engagement of the locking lever 61 at any point there along to prevent the axial movement of the leg pad 40. In such embodiments, the locking lever 61 may not include notches 62, but rather may engage the locking member 63 at any point there along.

[0083] The present invention is also directed to an arm support assembly 100, shown in FIGS. 11-21. The arm support assembly 100 may be provided on a medical examination device 1 or procedure chair and may be present in connection with or without a leg support assembly 10 as previously described. Although the present arm support assembly 100 may be used on either a medical examination device 1 or procedure chair, it should be noted that these are distinct medical devices and are not interchangeable. Further, the present arm support assembly 100 may be attached to any surface or device on which a patient may sit or lie for medical, dental, or health care examinations, procedures, administration, recovery, or evaluation.

[0084] As shown in FIGS. 11-21, the arm support assembly 100 of the present invention includes an armrest 110 configured to receive and support a patient's arm thereon, and a connecting assembly 120 configured to connect the armrest 110 to the medical examination device 1 or procedure chair. As will be described in greater detail below, the connecting assembly 120 is a double-articulating mechanism connecting to both the armrest 110 at one end and the device 1 or chair at the other end for selective adjustment to a number of different locked positions.

[0085] For example, the arm support assembly 100 may be placed in a common seated position as shown in FIG. 11, in which the back of the medical examination device 1 is raised to support the back of a patient in a seated position and the armrest 110 is configured to receive and support the arm of a patient with their forearm extending in a forward direction from the side of their body. This is a very natural position when seated. The back may be at any position relative to the medical examination device 1 as is common for a seated position, such as in the range of 90° to 120°, and in some embodiments may be about 112° to 115°. For instance, the back may be positioned at an angle of about 112° as shown in FIG. 11. In the seated position, the armrest 110 may be positioned parallel to the seat cushion 2 of the medical examination device 1 or procedure chair, and may further be adjacent to the seat cushion 2.

[0086] The arm support assembly 100 is also positionable into a blood pressure position, shown in FIG. 12, in which the forward end 105 of the armrest 110 is lowered and the rearward end 107 is elevated. This corresponds to lowering of the patient's hand and the raising of the elbow, respectively, which positions the arm so the point where a blood pressure cuff is placed to obtain a reading, such as the bicep, is at a height that is at least level with or higher than the heart. This provides optimal positioning for accurate blood pressure readings. Moreover, the patient's arm is fully supported by the armrest 110 in the blood pressure position of FIG. 12, reducing the awkwardness of the position so the patient may relax and a more accurate reading can be obtained.

[0087] The arm support assembly 100 may also be adjusted to a lying or supine position, as in FIG. 13. As used herein, "lying position" and "supine position" may be used interchangeably to refer to the same position. In this position, the armrest 110 is positioned at the head of the medical examination device 1, such that is near or adjacent to a patient's head when lying on the device 1. Although described as a "supine" position where a patient may be lying on their back, this position may also be used if the patient is in a prone position on their stomach or lying on one side. It may be horizontal such as parallel to the ground or seat cushion 2 in at least one embodiment, although it may also include deviations from true parallel or horizontal. In this position, the armrest 110 may be positioned with the underside of the armrest 110 receiving the arm of a patient, so that it is upside down relative to in the seated position of FIG. 11. Moreover, in the lying position of FIG. 13, the opening formed in the armrest 110 may be positioned adjacent or near the head of the patient, so the armrest 110 does not obstruct a medical practitioner's access to the patient for examination or performance of procedures. In other embodiments, the armrest 110 may maintain the same orientation in the seated and lying positions, but may simply be shifted more toward the head of the device 1 for the lying position.

[0088] The arm support assembly 100 may also be positioned in at least one storage or stowed position, such as shown in FIG. 14. In this position, the armrest 110 is moved below the plane of the seat cushion 2 of the examination device 1 or chair so that a patient may move (or be moved) on and off the examination device 1 or chair unimpeded. Accordingly, the stowed position may also be referred to as a patient transfer position. The armrest 110 may be moved below the plane and parallel to the seat cushion 2, with either the underside or top side of the armrest 110 adjacent to the surface of the seat cushion 2. In at least one embodiment, as shown in FIG. 14, the armrest 110 may be maneuvered below and at an oblique angle relative to the plane of the seat cushion 2. In other embodiments, the armrest 110 may be stored at a right angle to the plane of the seat cushion 2. In certain embodiments, such as depicted in FIG. 14, the armrest 110 may be used by the patient to facilitate their movement onto and off the examination device 1 or chair. For instance, the armrest 110 may be positioned so that the tubing 111 may be gripped by a person and used to pull themselves up or stabilize themselves while getting to their feet or sitting down. This can be particularly useful for people in wheelchairs that often pull up to a medical examination device 1 or chair catty-corner to the seat cushion 2. The armrest 110 positioned as in FIG. 14 is

aligned so the tubing **111** is located precisely where many people reach to stabilize themselves in getting out of or into a wheelchair. The armrest **110** is sufficiently rigid and locked in place such that it can support the weight and torque applied by a person in getting up and down between a wheelchair or other chair and the examination device **1** or chair.

[0089] The arm support assembly **100** may be maneuvered between various positions, including but not limited to the ones shown in FIGS. **11-14**, by selectively adjusting the connecting assembly **120**. As is depicted in the figures, the connecting assembly **120** includes a first joint **122a** connecting to the armrest **110**, a second joint **122b** connecting to the medical examination device **1** or procedure chair (not shown), and an elongate member **124** extending between the first and second joints **122a**, **122b**. Each joint **122a**, **122b** may be rotated about 360° when unlocked, permitting movement to any of a number of positions. Further, each joint **122a**, **122b** is independently operable so that movement or rotation of one joint **122a**, **122b** does not cause similar rotation of the other joint. Each joint **122a**, **122b** is fixedly secured to one end of the elongate member **124**. The elongate member **124** is of rigid construction, such as made of metal, metal alloys, or plastic, and retains its shape under pressure. The elongate member **124** may have any suitable shape, such as curved, linear, angular, curvilinear, arcuate, oblong or any suitable configuration. In the embodiments shown in FIGS. **11-14**, for instance, the elongate member **124** is curved or arcuate in shape.

[0090] Because the elongate member **124** is of rigid construction and is fixedly secured to each of the joints **122a**, **122b**, rotation of the second joint **122b** causes the elongate member **124** to rotate about the second joint **122b**, which acts a pivot point. The attached first joint **122a** is therefore also moved through space concentrically about the second joint **122b**, brought along by motion of the elongate member **124**. In this manner, counterclockwise rotation of the second joint **122b** from the seated position of FIG. **11** may be used to move the elongate member **124** to a more vertical orientation as shown in blood pressure position of FIG. **12**. Further counterclockwise rotation of the second joint **122b** may cause the elongate member **124** to move toward the head of the medical examination device **1**, as in the lying position of FIG. **13**. Clockwise (or further counterclockwise) motion of the second joint **122b** may cause the elongate member **124** to move toward the foot of the examination device **1**, as in the stowed or patient transfer position of FIG. **14**.

[0091] Rotation of the first joint **122a** may cause the attached armrest **110** to rotate about the first joint **122a** as a pivot point. The first joint **122a** may be rotated 360° when unlocked, permitting movement to any of a number of positions. For instance, clockwise rotation of the first joint **122a** from the seated position of FIG. **11** may cause the armrest **110** to move so the forward end **105** is lowered and the rearward end **107** is elevated, as shown in the blood pressure position of FIG. **12**. Counterclockwise rotation around the first joint **122a** may cause the armrest **110** to be inverted in orientation and positioned at the head of the device **1**, as in the lying or supine position of FIG. **13**. Counterclockwise rotation around the first joint **122a** may cause the armrest **110** to rotate relative to the plane of the seat cushion **2** for positioning into the stowed or patient transfer position of FIG. **14**.

[0092] Accordingly, the first and second joints **122a**, **122b** may be independently and selectively actuated to adjust the arm support assembly **100**, and specifically the armrest **110**, between any number of various possible positions. Coordination of the rotations of first and second joints **122a**, **122b**, the resultant movement of elongate member **124** and rotation of the armrest **110** may be utilized to fully maneuver the arm support assembly **100** between and among the various possible positions. The above are but a few exemplary positions and are not intended to be limiting. In further embodiments, at least one of the first and second joints **122a**, **122b**, elongate member **124** and armrest **110** may be moved collectively or simultaneously for adjustment and positioning of the arm support assembly **100**.

[0093] In at least one embodiment, the arm support assembly **100** may also include at least one indicia located anywhere along the surface of the first and second joints **122a**, **122b**, elongate member **124** or armrest **110** to assist a medical practitioner, user, patient or other person in identifying, selecting, and confirming positions of the arm support assembly **100**. For instance, these indicia may be words, letters, numbers, symbols, lines, shapes, colors, or other marking or combination thereof to denote various different positions. The indicia may be located on any part of the arm support assembly **100**, such as but not limited to the surface of the first and second joints **122a**, **122b** and armrest **110**.

[0094] Turning now to FIGS. **15-18**, the arm support assembly **100** includes an armrest **110** that is configured to receive and support a patient's arm thereon. The arm support assembly **100**, and the armrest **110** in particular, conform to the requirements for accessibility of health care equipment under the Americans with Disabilities Act, including the Standards for Accessible Medical Diagnostic Equipment set forth by the United States Access Board and published at 36 CFR Part 1195 (Jan. 9, 2017) (the "Standards"). For instance, in at least one embodiment the armrest **110** may be considered a transfer support per section M305.2 of the Standards and meets the requirements thereof. In at least one embodiment, the armrest **110** may be made of tubing **111** shaped to form an opening, as shown in FIGS. **15-17**. The tubing **111** may be of circular or non-circular cross-section, and may have an outer diameter in the range of 1.25 to 2 inches. For instance, in certain embodiments the tubing **111** may have a circular cross-section and an outer diameter of 1.25 inches. The tubing **111** may be made of any suitable material, which is preferably rigid and durable, such as but not limited to steel, aluminum, plastic, metals and metal alloys.

[0095] The tubing **111** of the armrest **110** may be formed into any shape as permits the receipt and support of a patient's arm thereon. For instance, in at least one embodiment as shown in FIGS. **11-18**, the armrest **110** may comprise a parallelogram shape, having parallel long sides and short sides. The long sides define a length **112** of the armrest **110**, which may be in the range of 12 to 28 inches long. In at least one embodiment, the armrest **110** may be 14 to 15 inches long. The parallelogram shape of the armrest **110** may be angular or curved. In at least one embodiment, the armrest **110** may be a curved parallelogram defined by the bend radii of first and second bends **113**, **114** that form the curves thereof. For instance, the tubing **111** of the armrest **110** may include first bends **113** having a smaller bend radius than second bends **114**, where the first and second bends **113**, **114** are alternated in the tubing **111** to form a parallelogram

shape. In a preferred embodiment, the first bends **113** may have the same bend radius as one another, although in other embodiments they may have different bend radii. The first bends **113** may have a bend radius in the range of 1.5 to 3.0 inches, measured as a center line radius measuring from the center of the tubing **111** rather than an outer or inner perimeter. In at least one embodiment, the first bends **113** may have a center line bend radius of 2.5 inches. The second bends **114** have a larger bend radius than the first bends **113**. In a preferred embodiment, the second bends **114** may have the same bend radius as one another, although in other embodiments they may have different bend radii. In some embodiments, the second bends **114** have a center line bend radius of 3.0 to 7.0 inches. In at least one embodiment, the second bends **114** may have a center line bend radius of 6.0 inches.

[0096] The armrest **110** also includes a joint plate **121a** secured between portions of the tubing **111**. In at least one embodiment, the joint plate **121a** is made of the same material as the tubing **111**, and may be welded, soldered, bonded, or otherwise affixed to the tubing **111**. In some embodiments, the joint plate **121a** may be formed of a unitary construction with the tubing **111**, such as in the case of mold or die casting, compression or injection molding, or 3D printing. In at least one embodiment, the joint plate **121a** spans between portions of the tubing **111**. The joint plate **121a** is configured and dimensioned to receive and retain the first joint **122a** thereto, and accordingly may be at least the size and shape of the first joint **122a**.

[0097] In certain embodiments, as shown in FIGS. 17-18, the armrest **110** may also include padding **116** that covers at least a portion of the armrest **110**. For instance, as shown in FIGS. 17-18 the padding **116** may cover at least a portion of the tubing **111**, such as along the rearward end **107**. Preferably, the padding **116** covers more than just the tubing **111**, and may span at least a portion of the opening formed in the armrest **110**, as shown in FIG. 17. The padding **116** is made of pliable, at least partially compressible and preferably resilient material to provide cushioning support to a patient's arm or hand when placed thereon. In at least one embodiment, the padding **116** may be integrally formed with the armrest **110** or may be permanently affixed to the armrest **110** at the manufacturer. In other embodiments, the padding **116** may be removable and may be selectively attached and removed, such as with a zipper, hook and loop fastener, buttons, snaps, or other selective type fastener. In some embodiments, the padding **116** may be slidingly positioned or otherwise positionable in covering engagement over at least a portion of the armrest **110**.

[0098] The padding **116** may have a composite structure, such as shown in the exploded view of FIG. 18, in which various layers make up the padding **116**. For instance, the padding **116** may include a substrate **117** such as wood or plastic, which is rigid and retains its shape. This substrate **117** may be secured to the surface(s) of the joint plate **121a**, at least to the areas not contacted by the first joint **122a**. The padding **116** may further include at least one compliant material **118** that may be pliable, at least partially compressible and preferably resilient to provide cushioning support to the padding **116**. For instance, in at least one embodiment the compliant material **118** may be foam, cotton, synthetic fibers, rubber, gels, liquids, and other suitable materials. There may be more than one compliant material **118** present in the padding **116**, which may be the same type or different

types from one another. The compliant material **118** is secured to the substrate **117**, such as by adhesive or friction. The padding **116** may further include upholstery **119** comprising the exterior of the padding **116**. The upholstery **119** may be any material suitable for contact with skin, such as but not limited to cloth, leather, imitation leather, synthetic fibers and microfiber. The upholstery **119** may contact the compliant material **118** on one side and be configured to receive the arm or hand of a patient on the other side. Accordingly, the upholstery **119** may present the exterior surface of the padding **116** and may be secured to at least one of the compliant material **118**, substrate **117** and joint plate **121a** to secure the padding **116** together.

[0099] In at least one embodiment, the padding **116** may further include a top cushion **108** to provide additional support for a patient's arm. The top cushion **108** may be positioned along the top surface of the armrest **110**, and may be in addition to the padding **116** already present in the armrest. The top cushion may be made of similar layers of substrate **117**, compliant material **118** and upholstery **119**, which may be the same or different than that used in the rest of the padding **116**. The top cushion **108** may be made by separate sub-assembly, as shown in FIG. 18, and may be added to the padding **116** of the armrest **110**. In other embodiments, the top cushion **108** may be formed with the rest of the padding **116**. Some embodiments may not include a top cushion **108**, and still further embodiments may contain no padding **116**.

[0100] As shown in FIG. 19, the joint plate **121a** of the armrest **110** receives and retains the first joint **122a** of the connection assembly **120**. For instance, the first joint **122a** may be secured to the surface of the joint plate **121a**, such as with screws, bolts, pins, adhesives or other suitable fasteners. The joint plate **121a** may be located at any position along the armrest **110**. In at least one embodiment, the joint plate **121a** is located at the rearward end **107** of the armrest **110**, as shown in FIG. 19. Accordingly, the first joint **122a** may connect to the armrest **110** anywhere along the armrest **110**, such as at the rearward end **107** thereof, and the opposite end such as the forward end **105** may be cantilevered. One end of the elongate member **124** is affixed or secured to the first joint **121a**. The opposite end of the elongate member **124** is affixed or secured to the second joint **122b**. The elongate member **124** may be secured to the first and second joints **122a**, **122b** such as by welding, soldering, bonding, adhesive, or other similar method of connection. In at least one embodiment, the elongate member **124** and first and second joints **122a**, **122b** may be formed of a unitary construction, such as but not limited to by mold or die casting, compression or injection molding, or 3D printing.

[0101] As shown in FIG. 20, the second joint **122b** secures to a joint plate **121b**, such as by screws, bolts, pins, adhesives or other suitable fasteners. The joint plate **121b** may have the same or different configuration, dimensions, and material as the joint plate **121a**, and may be substantially planar in at least one embodiment. The joint plate **121b** is in turn secured to the medical examination device **1** or procedure chair, such as with an attachment mechanism **155**.

[0102] In at least one embodiment, the attachment mechanism **155** may include at least one of a first connection member **156** and second connection member **158**. The first connection member **156** may be a pin that is insertable into a correspondingly configured receptacle in the side of the

medical examination device **1**, and the second connection member **158** may be a bolt or knob that rotates to threadingly engage a corresponding hole or aperture in the side of the medical examination device **1**. In some embodiments, the first and second connection members **156**, **158** may coordinate to collectively attach the joint plate **121b** to the medical examination device **1** or procedure chair. Accordingly, the arm support assembly **100** may be selectively secured to and removed from the medical examination device **1** or procedure chair by attaching or detaching the attachment mechanism **155**. The attachment mechanism **155** may be of the type already used in the medical industry to attach armrests or other components to the side of medical examination devices **1**. Accordingly, the attachment mechanism **155** may be used to retrofit the arm support assembly **100** of the present invention onto pre-manufactured medical examination devices **1**. In some embodiments, however, the second joint **122b** may connect directly to the side of the medical examination device **1** without the use of a joint plate **121b**.

[0103] The second joint **122b** may also include a shroud **150** dimensioned and configured to cover at least a portion of the second joint **122b** and/or the joint plate **121b** from view. In some embodiments the shroud **150** may protect the attachment mechanism **155** from accidental removal or loosening. In at least one embodiment, the shroud **150** may include a first shroud section **152** and a second shroud section **154**. The first shroud section **152** may be secured to at least one of the second joint **122b** and joint plate **121b** to provide an anchor point for the shroud **150**. The second shroud section **154** may be removably secured to the first shroud section **152**, allowing for selective access to the joint plate **121b** and attachment mechanism **155** for easy attachment, maintenance and removal. In at least one embodiment, the second shroud section **154** may be slidable relative to the first shroud section **152**, although in other embodiments the second shroud section **154** may simply be positioned in contact with the first shroud section **152** for attachment. The first and second shroud sections **152**, **154** may be releasably secured together such as by snap fit, mating components, lip and groove connections, and other similar methods of releasable attachment, where one component is located on the first shroud section **152** and the mating connection component is located on the second shroud section **154**. The second shroud section **154** may further include a spacer **157** configured to span at least part of the distance between the second shroud section **154** and the joint plate **121b** or side of the medical examination device **1**. In at least one embodiment, the spacer **157** may be configured to extend from an inner surface of the second shroud section **154** toward the joint plate **121b** or side of the medical examination device **1**. The spacer **157** is dimensioned to be at least the same length as portion of the attachment mechanisms **155** that extends from the surface of the medical examination device **1** or procedure chair. Accordingly, the spacer **157** is configured to provide structural support to the second shroud section **154** while also preventing damage to or accidental loosening of the attachment mechanism **155** during placement and removal of the second shroud section **154**. In at least one embodiment, the joint plate **121b** may include a groove **159**, as shown in FIG. **21**, that is dimensioned to receive and retain a portion of the spacer **157**, such as an enlarged head thereof, to facilitate alignment and securing of the second shroud section **154** in place.

[0104] Each of the first and second joints **122a**, **122b** includes a housing **125** and a rotary mechanism **123** configured to permit selective rotary motion of at least one portion of the first or second joints **122a**, **122b**. The component parts of the housing **125** and rotary mechanism **123** will be described in connection with one of the joints, but it should be understood that this description applies equally to each of the first and second joints **122a**, **122b**. The rotary mechanism **123** may be similar to that described in U.S. Pat. Nos. 5,689,999 and 5,586,363, the contents of both of which are incorporated by reference herein in their entireties.

[0105] Turning now to FIGS. **22-24**, each joint **122a**, **122b** includes a housing **125** dimensioned and configured to retain the various components of the rotary mechanism **123**. The housing **125** may include a first housing portion **126** with a first surface **127** and opposite second surface **128**, and a second housing portion **130** with a first surface **131** and opposite second surface **132**. The first and second housing portions **126**, **130** may be fitted together to form the composite housing **125**. The first surfaces **127**, **131** of each are positioned in facing, contacting, abutting, and/or adjacent relation to one another in the composite housing **125**. Accordingly, the first surfaces **127**, **131** may also be referred to as interior surfaces of the first and second housing portions **126**, **130**, respectively. Second surfaces **128**, **132** may therefore be referred to as exterior surfaces of the first and second housing portions **126**, **130**, respectively.

[0106] In at least one embodiment, the first surfaces **127**, **131** face each other and may contact one another. This contact may be a sliding contact that allows for rotary movement of the first surfaces **127**, **131** relative to one another as their respective first and second housing portions **126**, **130** are rotated relative to one another. In certain embodiments, the first surfaces **127**, **131** may not necessarily contact one another, but may be adjacent to one another in close proximity. This configuration may allow for a small space between the first surfaces **127**, **131** to permit rotational movement of the first and second housing portions **126**, **130** relative to one another without damaging the first surfaces **127**, **131**. In still other embodiments, the first surfaces **127**, **131** may contact one another at certain times, such as when the rotary mechanism **123** is in a locked position and may be spaced apart from one another at other times, such as when the rotary mechanism **123** is in an unlocked position.

[0107] The first housing portion **126** may further include a plurality of channels **129** extending therethrough between the first and second surfaces **127**, **128**. These channels **129** preferably have the same dimensions and are parallel to one another, but in certain embodiments may have different dimensions from one another and may be at angles relative to one another, such as oblique angles. The channels **129** may form any configuration within the first housing portion **126**. In at least one embodiment, the channels **129** are collectively form a circular configuration, as shown in FIGS. **22** and **23**. There may be any number of channels **129**, such as 6 to 20 in some embodiments. In certain embodiments, there may be 16 channels **129** in the first housing portion **126**. In at least one embodiment, the channels **129** may uniformly spaced apart from one another, as in FIG. **23**. In other embodiments, certain channels **129** may be spaced closer or further from other channels **129**. This spacing may be described as angular spacing. For instance, adjacent channels **129** may be spaced in the range of 10° to 80° relative to one another. In some embodiments, they may be

spaced 20° to 30° relative to one another. In at least one embodiment, as shown in FIG. 23, adjacent channels 129 may be spaced 22.5° from one another.

[0108] The second housing portion 130 may include a plurality of receivers 134 each defining a space formed in the second housing portion 130 and extending from the interior-facing first surface 131 thereof, as shown in FIG. 22. There may be any number of receivers 134 formed in the second housing portion 130, and they may be presented in any configuration. For instance, in the embodiment of FIG. 22, the receivers 134 may collectively form a circular configuration, and there may be 6 receivers. In other embodiments, there may be 2 to 20 receivers. The receivers 134 may be uniformly spaced from one another, or certain ones may be spaced closer or further apart from one another. The receivers 134 may be disposed at angles relative to one another or may be parallel to one another. In at least one embodiment, the angles of the receivers 134 in the second housing portion 130 may correspond with the angles of the channels 129 in the first housing portion 126 when the portions 126, 130 are joined.

[0109] Each receiver 134 is dimensioned to receive a locking member 135 and biasing element 136 therein. The locking members 135 may be a pin, rod, or other elongate device that has a rigid construction. The locking members 135 may be made of any suitably rigid material that does not deform under pressure, such as but not limited to plastic, metal, metal alloys and wood. The biasing elements 136 may be any biasing structure, such as but not limited to springs, coils, or other structure capable of transforming to absorb, retain, and release energy. In some embodiments, such as depicted in FIGS. 22 and 24, each receiver 134 includes a biasing element 136 mounted at a terminal end thereof and a locking member 135 is slidably received therein and abuts against the biasing element 136. The biasing element 136 exerts a biasing force on the locking member 135. The opposite end of the locking member 135 projects from the receiver 134 and extends beyond the first surface 131 of the second housing portion 130. In other embodiments, some of the receivers 134 include a biasing element 136 and locking member 135, whereas other receivers 134 remain empty. The pattern or configuration of locking members 135 disposed in receivers 134 and extending from the first surface 131 of the second housing portion 130 may be referred to as the “clocking” of the joint 122a, 122b. Accordingly, there may be any number of locking members 135 disposed in the receivers 134. In at least one embodiment as shown in FIGS. 22-23, there may be six locking members 135 clocked in groupings of three, although any pattern, configuration, number and grouping is contemplated. In some embodiments, the clocking may be described in terms of numbers of locking members 135, groupings of locking members 135 or the angular spacing between adjacent locking members 135. For instance, the clocking may be described as in the range of 10° to 60°. In some embodiments, the clocking may be at 20° to 30°. In certain embodiments, as in FIG. 23, the clocking may be 45°. Further, the torque-bearing strength of the joint 122a, 122b may be directly proportional to at least one of the number and clocking of locking members 135. For instance, greater numbers of locking members 135 may provide greater resistance to torque or rotational motion, and therefore stronger locking action, as will be described in greater detail below. Lower angular clocking values may

indicate adjacent locking members 135 are in closer proximity to one another, also increasing the strength of the locking action.

[0110] Each locking member 135 is also dimensioned to fit within and be slidably received by at least one channel 129 of the first housing portion 126, as shown in FIG. 24. The locking members 135 extend into different ones of the channels 129 in a locked position, as shown in FIGS. 23 and 24. The biasing force from the biasing element 136 may push the corresponding locking member 135 in the direction of the channels 129, and when a locking member 135 is aligned with a channel 129 it is received therein. A locking position may be defined by at least one locking member 135 disposed within or extending into a correspondingly aligned channel 129. In at least one embodiment, a locking position may be defined when all the locking members 135 are retained within their own respective channels 129, as in FIG. 23. Accordingly, there may be at least as many channels 129 as there are locking members 135. There may be any number of possible locked configurations, limited only by the number of channels 129 and locking members 135. In at least one embodiment, as in FIG. 23, each channel 129 is dimensioned to retain any of the locking members 135 such that different locking members 135 may be received and retained within the same channel 129 in different locking positions.

[0111] Each joint 122a, 122b may also include a plurality of release members 137, each dimensioned to fit within and be slidably received by a corresponding one of the channels 129 of the first housing portion 126. The release members 137 may have an elongate dimension and in at least one embodiment have the same length as the dimension of the first housing portion 126. There may be any number of release members 137, although in at least one embodiment there are the same number of release members 137 as there are channels 129. As seen in FIG. 24, each channel 129 may be configured to slidably receive and retain both a release member 137 from one side and a locking member 135 from the opposite side. However, each channel 129 need not have both a release member 137 and locking member 135 at the same time, even in a locked position. Some channels 129 will only have a release member 137 disposed therein when locked, depending on whether or not a locking member 135 was aligned with the particular channel 129.

[0112] The joint 122a, 122b may also include an actuator 138 to control the rotary mechanism 123 and whether it is in a locked or unlocked position. The actuator 138 may be configured to at least contact, if not receive, retain or secure, each of the release members 137. As shown in FIG. 22, the actuator 138 may be dimensioned to fit within a recess in the first housing portion 126. The actuator 138 may be depressed, pressed, pushed, or otherwise activated or engaged to select between unlocked and locked states of the rotary mechanism 123. Accordingly, the actuator 138 may be a button or other like structure.

[0113] When the actuator 138 is not engaged, the locking members 135 are retained within correspondingly aligned channels 129 and the rotary mechanism 123 is in a locked position. When the actuator 138 is activated, it presses on the release members 137, pushing them into the channels 129 to the furthest extent possible which is defined by the terminal ends of the release members 137 being flush, co-terminal or even with the first surface 127 of the first housing portion 126. The release members 137 that co-reside in a channel 129 with a locking member 135 push on the locking member

135 as they move, forcing the corresponding locking members **135** out the channels **129**. Once the locking members **135** are no longer retained within the channels **129**, the rotary mechanism **123** is in an unlocked position and the first and second housing portions **126**, **130** are freely rotatable relative to one another, such as about an axle **139** that may extend through at least the first and second housing portions **126**, **130**, but preferably through the entire joint **122a**, **122b**. A bearing **140** may also be concentrically disposed around at least a portion of the axle **139** to reduce friction and facilitate smooth rotational motion of the first and second housing portions **126**, **130** relative to one another. An end cap **141** may cover the end of the axle **139** and a portion of the actuator **138** to protect the rotary mechanism **123** and facilitate the activation of the actuator **138**.

[0114] The housing **125** may include an extension **142** extending radially outwardly from at least one of the first and second housing portions **126**, **130**. In at least one embodiment, the extension **142** extends from the first housing portion **126**, as in FIGS. 22-24. The extension **142** may be formed integrally with the housing portion(s) **126**, **130**, or may be secured or mounted thereto. The elongate member **124** of the connecting assembly **120** mounts to, is secured to, or is integrally formed with the opposite end of the extension **142** from the housing **125**, such that the extension **125** forms the connection point between the elongate member **124** and the housing **125** of a joint **122a**, **122b**. Accordingly, when the rotary mechanism **123** is in an unlocked position, the elongate member **124** of the connecting assembly **120** may be moved to rotate the first and second housing portions **126**, **130** of the first joint **122a** or second joint **122b** relative to one another. Similarly, the armrest **110** may be maneuvered in an unlocked position to rotate the first and second housing portions **126**, **130** of the first joint **122a** relative to one another in an unlocked position to move the armrest **110**.

[0115] Activation or engagement of the actuator **138** is maintained until the desired position is achieved for the armrest **110** and/or elongate member **124**, at which point the pressure is removed from the actuator **138**. As pressure is released, release members **137** correspondingly slide through the channels **129** in the direction of the actuator **138**, leaving a space in each of the channels **129** at the first surface **127**. The biasing elements **136** pushing against the locking members **135** force the locking members **135** toward the channels **129**. If the locking members **135** are aligned with channels **129**, the biasing force of the biasing element **136** pushes the locking members **135** into the space of the aligned channels **129** vacated by the retreating release members **137**. Once at least one of the locking members **135** enters the correspondingly aligned channel **129**, the rotary mechanism **123** is in a locked position and further rotational motion of the first and second housing portions **126**, **130** is precluded, as in FIG. 23. However, if the locking members **135** are misaligned with the channels **129** upon deactivation or disengagement of the actuator **138**, the locking members **135** may contact or press against the first surface **127** of the first housing portion **126**. This may not result in a locked position, but it may make rotational motion more difficult. In at least one embodiment, the first and second housing portions **126**, **130** will continue to be rotationally movable relative to one another until the locking members **135** become aligned with channels **129**, at which point they will slip into the correspondingly aligned channels and a locking position is achieved.

[0116] Now that the connection assembly **120** and the rotary motion of the first and second joints **122a**, **122b** has been described in detail, various illustrative locked positions shown in FIGS. 11-14 and discussed previously may now be further described. For instance, the various locked positions may be defined by the angle of rotation of each or a combination of the first and second joints **122a**, **122b**. The elongate member **124** and armrest **110** may be selectively positioned relative to one another by rotation of the first joint **122a** to a position defined by a first included angle **214**. The first included angle **214** is the smaller angle formed between a longitudinal axis **210** extending from the center of the first joint **122a** toward the forward end **105** of the armrest **110**, and a first measured ray **212** extending from the center of the first joint **122a** radially outwardly therefrom at the point where the elongate member **124** meets or is secured to the first joint **122a**. In the seated position of FIG. 11, the first included angle **214** may be in the range of 135° to 170°, and in some embodiments be about 157°. In the blood pressure position of FIG. 12, the first included angle **214** may be in the range of 100° to 120°, and in some embodiments may be about 110°. In the supine position of FIG. 13, the first included angle **214** may be in the range of 105° to 125°, and in some embodiments may be about 116°. In the stowed position of FIG. 14, the first included angle **214** may be in the range of 80° to 100°, and in some embodiments may be about 90°.

[0117] Similarly, elongate member **124** and medical examination device **1** may be selectively positionable relative to one another by rotation of the second joint **122b** to a position defined by a second included angle **224**. The second included angle **224** is the smaller angle formed between a reference ray **220** extending radially outwardly from the center of the second joint **122b** in the direction normal or perpendicular to a supporting surface **19** on which the medical examination device **1** rests, such as ground or floor, and a second measured ray **222** extending from the center of the second joint **122b** radially outwardly at point where the elongate member **124** meets or is secured to the second joint **122b**. For instance, in the seated position of FIG. 11, the second included angle **224** may be in the range of 5° to 20°, and in some embodiments be about 12°. In the blood pressure position of FIG. 12, the second included angle **224** may be in the range of 350° to 10°, and in some embodiments may be about 0°. In the supine position of FIG. 13, the second included angle **224** may be in the range of 55° to 85°, and in some embodiments may be about 68°. In the stowed position of FIG. 14, the second included angle **224** may be in the range of 80° to 100°, and in some embodiments may be about 90°.

[0118] The various locked positions may be described in terms of the first and second included angles **214**, **224** independently, or in combination with one another. For instance, a locked position may be defined when the first included angle **214** is any angle in the ranges of 135° to 170°, 100° to 120°, 105° to 125°, and 80° to 100°. In at least one preferred embodiment, the first included angle **214** may be one of about 157°, 110°, 116°, and 90°. Locked positions may also be defined when the second included angle **224** is any angle in the ranges of 5° to 20°, 350° to 10°, 55° to 85°, and 80° to 100°. In at least one preferred embodiment, the second included angle **224** is one of about 12°, 0°, 68°, and 90°. Any possible combination of the above first and second included angles **214**, **224** is also contemplated and may

define different locked positions. For instance, in at least one embodiment, locked positions may be defined where the first included angle **214** is any angle in the ranges of 135° to 170°, 100° to 120°, 105° to 125°, and 80° to 100°, and the second included angle **224** is any angle in the ranges of 5° to 20°, 350° to 10°, 55° to 85°, and 80° to 100°. Locked positions may also be defined when the first included angle **214** is one of about 157°, 110°, 116°, and 90°, and the second included angle **224** is one of about 12°, 0°, 68°, and 90°.

[0119] In some embodiments, the seated position of FIG. **11** may be defined by a first included angle **214** being any angle in the range of 135° to 170° and the second included angle **224** being any angle in the range of 5° to 20°. In some embodiments, it may be defined as the first included angle **214** being about 157° and the second included angle **224** being about 12°. The blood pressure position of FIG. **12** may be described as the first included angle **214** being any angle in the range of 100° to 120° and the second included angle **224** being any angle in the range of 350° to 10°. In some embodiments, it may be defined as the first included angle **214** being about 110° and the second included angle **224** being about 0°. The supine position of FIG. **13** may be defined as the first included angle **214** being any angle in the range of 105° to 125° and the second included angle **224** being any angle in the range of 55° to 85°. In some embodiments, it may be described as the first included angle **214** being about 116° and the second included angle **224** being about 68°. The stowed position of FIG. **14** may be described as the first included angle **214** being any angle in the range of 80° to 100° and the second included angle **224** being any angle in the range of 80° to 100°. In some embodiments, it may be defined as the first included angle **214** being about 90° and the second included angle **224** being about 90°.

[0120] The various locked positions may also be defined or described in terms of the overall angle of the connection assembly **120**, as measured by a connection line **232** extending between the center of the first and second joints **122a**, **122b**. Because the second joint **122b** remains fixed in space since it is secured to the medical examination device **1**, rotation of the first and/or second joints **122a**, **122b** and elongate member **124** results in the first joint **122a** moving concentrically about the second joint **122b** in space, where the elongate member **124** acts as a radius. The position of the connection line **232** in any locked position may be compared to a reference line **230** for the connection assembly **120**, which may be defined as normal or perpendicular to the supporting surface **19** under the medical examination device **1** and extending through the center of the second joint **122b**. A displacement angle **234** is formed by the intersection of the reference line **230** and connection line **232**, and provides angular positioning information of the connection assembly **120** overall in any of the various locked positions. For instance, the seated position of FIG. **11** may be defined by the displacement angle **234** being any angle in the range of 35° to 55°, and in some embodiments may be about 46°. The blood pressure position of FIG. **12** may be defined by the displacement angle **234** being any angle in the range of 10° to 30°, and in some embodiments may be about 20°. The supine position of FIG. **13** may be defined by the displacement angle **234** being any angle in the range of 300° to 320°, and in some embodiments may be about 313°. The stowed position of FIG. **14** may be defined by the displacement angle **234** being any angle in the range of 100° to 120°, and

in some embodiments may be about 111°. As noted above, the various locked positions shown in FIGS. **11-14** are illustrative, and any number of locked positions may be possible for each of the first and second joints **122a**, **122b**.

[0121] Since many modifications, variations and changes in detail can be made to the described preferred embodiments, it is intended that all matters in the foregoing description and shown in the accompanying drawings be interpreted as illustrative and not in a limiting sense. Thus, the scope of the invention should be determined by the appended claims and their legal equivalents. Now that the invention has been described,

What is claimed is:

1. An arm support assembly for a medical examination device, said arm support assembly comprising:

an armrest;

a connection assembly including:

- (i) a first joint secured to said armrest;
- (ii) a second joint secured to said medical examination device; and
- (iii) an elongate member extending between said first joint at one end and said second joint at an opposite end; and

each of said first and second joints having a rotation mechanism permitting rotational motion about 360° in an unlocked position and restricting rotational motion in any of a plurality of locked positions about 360°, said first and second joints being selectively actuatable to rotate said elongate member about said second joint and said armrest about said first joint to collectively position said arm support assembly in any of said plurality of locked positions.

2. The arm support assembly of claim 1, wherein said each of said plurality of locked positions of each of said first and second joints are rotationally spaced in a range of 10° to 60° from each adjacent one of said plurality of locked positions.

3. The arm support assembly of claim 2, wherein said each of said plurality of locked positions of each of said first and second joints are rotationally spaced about 20° from each adjacent one of said plurality of locked positions.

4. The arm support assembly of claim 1, wherein said armrest further comprises a forward end, an opposite rearward end and at least one longitudinal side;

wherein said elongate member and said armrest are selectively positionable with respect to each other in one of a plurality of positions defined by a first included angle formed by the intersection of (i) a longitudinal axis of said armrest originating at the center of said first joint and extending toward said forward end of said armrest, and (ii) a first measured ray originating at the center of said first joint and extending radially outwardly therefrom at the point where said elongate member is secured to said first joint; and

wherein said elongate member and said medical examination device are selectively positionable with respect to each other in a plurality of positions defined by a second included angle formed by the intersection of (iii) a reference ray originating at the center of said second joint and extending radially outwardly therefrom in a direction normal to the supporting surface of said medical examination device, and (iv) a second measured ray originating at the center of said second

joint and extending radially outwardly therefrom at the point where said elongate member is secured to said second joint.

5. The arm support assembly of claim 4, wherein said first included angle is selected from the group consisting of: (i) in the range of 135° to 170°, (ii) in the range of 100° to 120°, (iii) in the range of 105° to 125°, and (iv) in the range of 80° to 100°.

6. The arm support assembly of claim 5, wherein said first included angle is selected from the group consisting of (i) about 157°, (ii) about 110°, (iii) about 116°, and (iv) about 90°.

7. The arm support assembly of claim 4, wherein said second included angle is selected from the group consisting of: (i) in the range of 5° to 20°, (ii) in the range of 350° to 10°, (iii) in the range of 55° to 85°, and (iv) in the range of 80° to 100°.

8. The arm support assembly of claim 7, wherein said second included angle is selected from the group consisting of: (i) about 12°, (ii) about 0°, (iii) about 68°, and (iv) about 90°.

9. The arm support assembly of claim 4, wherein said first included angle is selected from any one of (i) in the range of 135° to 170°, (ii) in the range of 100° to 120°, (iii) in the range of 105° to 125°, and (iv) in the range of 80° to 100°, and said second included angle is selected from any one of (v) in the range of 5° to 20°, (vi) in the range of 350° to 10°, (vii) in the range of 55° to 85°, and (viii) in the range of 80° to 100°.

10. The arm support assembly of claim 9, wherein said first included angle is selected from any one of (i) about 157°, (ii) about 110°, (iii) about 116°, and (iv) about 90°, and said second included angle is selected from any one of (v) about 12°, (vi) about 0°, (vii) about 68°, and (viii) about 90°.

11. The arm support assembly of claim 4, wherein said plurality of locked positions includes:

- (i) a seated position defined by said first included angle being in the range of 135° to 170° and said second included angle being in the range of 5° to 20°;
- (ii) a blood pressure position defined by said first included angle being in the range of 100° to 120° and said second included angle being in the range of 350° to 10°;
- (iii) a supine position defined by said first included angle being in the range of 105° to 125° and said second included angle being in the range of 55° to 85°; and
- (iv) a stowed position defined by said first included angle being in the range of 80° to 100° and said second included angle being in the range of 80° to 100°.

12. The arm support assembly of claim 11, wherein said plurality of locked positions includes:

- (i) said seated position being defined by said first included angle being about 157° and said second included angle being about 12°;
- (ii) said blood pressure position being defined by said first included angle being about 110° and said second included angle being about 0°;
- (iii) said supine position being defined by said first included angle being about 116° and said second included angle being about 68°; and

(iv) said stowed position being defined by said first included angle being about 90° and said second included angle being about 90°.

13. The arm support assembly of claim 1, wherein said armrest has a shape defined by at least one first bend having a first bend radius and at least one second bend having a second bend radius, wherein said first bend radius is smaller than said second bend radius.

14. The arm support assembly of claim 13, wherein said at least one first bend has a center line bend radius in the range of 1.5 to 3.0 inches.

15. The arm support assembly of claim 14, wherein said at least one first bend has a center line bend radius of about 2.5 inches.

16. The arm support assembly of claim 13, wherein said at least one second bend has a center line bend radius in the range of 3.0 to 7.0 inches.

17. The arm support assembly of claim 16, wherein said at least one second bend has a center line bend radius of about 6.0 inches.

18. The arm support assembly of claim 13, wherein said armrest has a length in the range of 12 to 28 inches.

19. The arm support assembly of claim 18, wherein said armrest has a length of about 14 inches.

20. The arm support assembly of claim 1, wherein said armrest further comprises tubing having an outer diameter in the range of 1.25 to 2 inches.

21. The arm support assembly of claim 20, wherein said tubing has a circular cross-section and has an outer diameter of about 1.25 inches.

22. The arm support assembly of claim 1, wherein said armrest further comprises a forward end and an opposite rearward end, said first joint secured to said armrest at one of said rearward end and said forward end and the opposite end cantilevered.

23. The arm support assembly of claim 1, wherein said armrest further comprises padding configured to cover at least a portion of said armrest.

24. The arm support assembly of claim 23, wherein said padding further comprises at least one compliant material that is compressible and configured to provide resilient support to the patient's arm.

25. The arm support assembly of claim 23, wherein said padding is removable from said armrest.

26. The arm support assembly of claim 1, wherein said first joint, said elongate member, and said second joint are formed of a unitary construction.

27. The arm support assembly of claim 1, wherein said armrest further comprises a forward end and an opposite rearward end, said medical examination device further comprising a seat cushion having a surface, head and oppositely disposed foot, said arm support assembly being collectively and selectively positionable between at least:

- (i) a seated position defined by said armrest being parallel to said surface of said seat cushion and adjacent to said seat cushion;
- (ii) a blood pressure position defined by said forward end of armrest lowered and said rearward end of said armrest elevated relative to in said seated position;
- (iii) a supine position defined by said armrest being parallel to said surface of said seat cushion and positioned near said head; and
- (iv) a stowed position defined by said armrest being below a plane defined by said surface of said seat cushion.

28. The arm support assembly of claim **27**, wherein said stowed position is also a patient transfer position where said armrest is configured to be gripped by a patient moving onto or off said medical examination device.

* * * * *

专利名称(译)	医疗检查装置的手臂支撑组件		
公开(公告)号	US20200046296A1	公开(公告)日	2020-02-13
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[标]申请(专利权)人(译)	联合金属FABTORS INC D B—UMF医疗		
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摘要(译)

手臂支撑组件包括扶手和连接组件。扶手可能符合法规或行业标准，并且可以操纵到各种位置，包括坐着，血压读数，坐卧或躺卧以及收起或病人转移位置。扶手可以加垫和/或装饰。该连接组件包括第一和第二接头，每个接头可选择性地旋转，以及连接它们的细长构件。第一关节可旋转地安装在扶手上，第二关节可安装在检查设备（例如桌子或椅子）的侧面。关节包括旋转机构，以接合在锁定位置和解锁位置之间，在锁定位置和解锁位置之间可以进行旋转运动。第一和第二关节处的旋转共同导致在各个位置之间操纵扶手。

