



US010653318B2

(12) **United States Patent**
Welsh et al.

(10) **Patent No.:** **US 10,653,318 B2**
(45) **Date of Patent:** **May 19, 2020**

(54) **LOCALIZATION SYSTEM AND METHOD
USEFUL IN THE ACQUISITION AND
ANALYSIS OF CARDIAC INFORMATION**

(52) **U.S. CL.**
CPC **A61B 5/004** (2013.01); **A61B 5/0035**
(2013.01); **A61B 5/0044** (2013.01); **A61B**
5/042 (2013.01);

(71) Applicant: **Acutus Medical, Inc.**, Carlsbad, CA
(US)

(Continued)

(72) Inventors: **Daniel J. Welsh**, Encinitas, CA (US);
Marcus F. Julian, Vista, CA (US);
Graydon E. Beatty, Bloomington, MN
(US); **Xinwei Shi**, San Diego, CA (US);
Derrick R. Chou, San Diego, CA (US);
Randell L. Werneth, Boise, ID (US);
J. Christopher Flaherty, Auburndale,
FL (US)

(58) **Field of Classification Search**
CPC **A61B 5/004**; **A61B 5/0422**; **A61B**
2562/0209; **A61B 8/4416**; **A61B 8/12**;
(Continued)

(73) Assignee: **ACUTUS MEDICAL, INC.**, Carlsbad,
CA (US)

(56) **References Cited**

U.S. PATENT DOCUMENTS

4,173,228 A * 11/1979 Van Steenwyk **A61B 5/06**
600/409

5,041,973 A 8/1991 Lebron et al.
(Continued)

(*) Notice: Subject to any disclaimer, the term of this
patent is extended or adjusted under 35
U.S.C. 154(b) by 114 days.

FOREIGN PATENT DOCUMENTS

CA 2829626 9/2012
CN 201223445 4/2009

(Continued)

(21) Appl. No.: **15/569,457**

(22) PCT Filed: **May 13, 2016**

OTHER PUBLICATIONS

(86) PCT No.: **PCT/US2016/032420**

European Office Action dated Jan. 28, 2019 issued in corresponding
European Application No. 14748567.6.

§ 371 (c)(1),

(2) Date: **Oct. 26, 2017**

(Continued)

(87) PCT Pub. No.: **WO2016/183468**

PCT Pub. Date: **Nov. 17, 2016**

Primary Examiner — Lindsey G Wehrheim

(74) Attorney, Agent, or Firm — Onello & Mello, LLP

(65) **Prior Publication Data**

US 2018/0296114 A1 Oct. 18, 2018

Related U.S. Application Data

(60) Provisional application No. 62/161,213, filed on May
13, 2015.

(51) **Int. Cl.**

A61B 5/00 (2006.01)

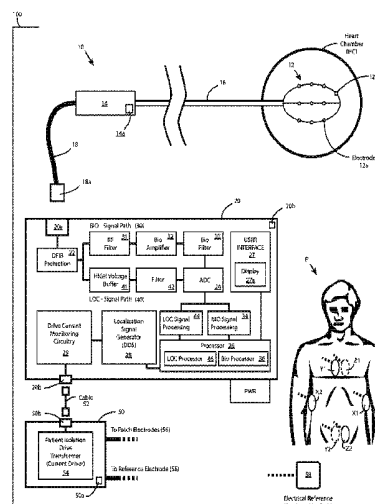
A61N 1/37 (2006.01)

(Continued)

(57) **ABSTRACT**

Provided are a localization system and method useful in the
acquisition and analysis of cardiac information. The local-
ization system and method can be used with systems that
perform cardiac mapping, diagnosis and treatment of cardiac
abnormalities, as examples, and in the retrieval, processing,
and interpretation of such types of information. The local-
ization system and method use high impedance inputs,
improved isolation, and relatively high drive currents for
pairs of electrodes used to establish a multi-axis coordinate

(Continued)



system. The axes can be rotated and scaled to improve localization.

25 Claims, 7 Drawing Sheets

(51) Int. Cl.

A61B 5/042 (2006.01)
A61B 5/06 (2006.01)
A61B 34/20 (2016.01)
A61B 5/04 (2006.01)
A61B 8/08 (2006.01)
A61B 8/12 (2006.01)
A61B 8/00 (2006.01)

(52) U.S. Cl.

CPC *A61B 5/0422* (2013.01); *A61B 5/061* (2013.01); *A61B 5/063* (2013.01); *A61B 5/6852* (2013.01); *A61N 1/3702* (2013.01); *A61B 5/04012* (2013.01); *A61B 5/6853* (2013.01); *A61B 5/6857* (2013.01); *A61B 5/6858* (2013.01); *A61B 5/6859* (2013.01); *A61B 8/0883* (2013.01); *A61B 8/12* (2013.01); *A61B 8/4416* (2013.01); *A61B 34/20* (2016.02); *A61B 2034/2051* (2016.02); *A61B 2034/2063* (2016.02); *A61B 2034/2065* (2016.02); *A61B 2562/0204* (2013.01); *A61B 2562/0209* (2013.01); *A61B 2576/023* (2013.01)

(58) Field of Classification Search

CPC ... *A61B 8/0883*; *A61B 8/6859*; *A61B 8/6858*; *A61B 8/6857*; *A61B 8/6853*; *A61B 5/04012*; *A61B 2034/2065*; *A61B 2034/2063*; *A61B 34/20*
 See application file for complete search history.

(56) References Cited

U.S. PATENT DOCUMENTS

5,156,151 A	10/1992	Imran	6,188,928 B1	2/2001	Noren et al.
5,293,868 A	3/1994	Nardella	6,216,027 B1	4/2001	Willis et al.
5,482,472 A	1/1996	Garoni et al.	6,216,043 B1	4/2001	Swanson et al.
5,499,981 A	3/1996	Kordis	6,240,307 B1	5/2001	Beatty et al.
5,555,883 A	9/1996	Avitall	6,301,496 B1	10/2001	Reisfeld
5,595,183 A	1/1997	Swanson et al.	6,396,198 B1	5/2002	Okimura et al.
5,601,084 A	2/1997	Sheehan et al.	6,400,981 B1	6/2002	Govari
5,647,367 A	7/1997	Lum et al.	6,490,474 B1	12/2002	Willis et al.
5,662,108 A	9/1997	Budd et al.	6,514,249 B1	2/2003	Maguire et al.
5,722,402 A	3/1998	Swanson et al.	6,574,492 B1	6/2003	Ben-Haim et al.
5,722,416 A	3/1998	Swanson et al.	6,640,119 B1	10/2003	Budd et al.
5,740,808 A	4/1998	Panescu et al.	6,716,166 B2	4/2004	Govari
5,749,833 A	5/1998	Hakki et al.	6,728,562 B1	4/2004	Budd et al.
5,759,158 A	6/1998	Swanson	6,772,004 B2	8/2004	Rudy
5,782,239 A	7/1998	Webster, Jr.	6,773,402 B2	8/2004	Govari et al.
5,795,298 A	8/1998	Vesley et al.	6,824,515 B2	11/2004	Suorsa et al.
5,795,299 A	8/1998	Eaton et al.	6,826,420 B1	11/2004	Beatty et al.
5,820,568 A	10/1998	Parker	6,826,421 B1	11/2004	Beatty et al.
5,830,144 A	11/1998	Vesely	6,839,588 B1	1/2005	Rudy
5,846,198 A *	12/1998	Killmann <i>A61B 5/04085</i>	6,895,267 B2	5/2005	Panescu et al.
		600/424	6,939,309 B1	9/2005	Beatty et al.
5,876,336 A	3/1999	Swanson et al.	6,950,689 B1	9/2005	Willis et al.
5,928,228 A	7/1999	Kordis et al.	6,970,733 B2	11/2005	Willis et al.
5,968,040 A	10/1999	Swanson et al.	6,978,168 B2	12/2005	Beatty et al.
6,014,590 A	1/2000	Wayne et al.	6,990,370 B1	1/2006	Beatty et al.
6,024,703 A	2/2000	Zanelli et al.	7,187,964 B2	3/2007	Khoury
6,066,096 A	5/2000	Smith et al.	7,187,973 B2	3/2007	Hauck
6,086,532 A	7/2000	Panescu et al.	7,258,674 B2	8/2007	Hillstead et al.
6,107,699 A	8/2000	Swanson	7,263,397 B2	8/2007	Hauck et al.
6,115,626 A	9/2000	Wayne et al.	7,285,119 B2	10/2007	Stewart et al.
6,187,032 B1	2/2001	Ohyu et al.	7,289,843 B2	10/2007	Beatty et al.
			7,291,146 B2	11/2007	Steinke et al.
			7,505,810 B2	3/2009	Harley et al.
			7,573,182 B2	8/2009	Savage
			7,689,261 B2	3/2010	Mohr et al.
			7,766,838 B2	8/2010	Yagi et al.
			7,841,986 B2	11/2010	He et al.
			7,918,793 B2	4/2011	Altmann et al.
			7,953,475 B2	5/2011	Harlev et al.
			8,103,327 B2	1/2012	Harlev et al.
			8,147,486 B2	4/2012	Honour et al.
			8,150,499 B2	4/2012	Gelbart et al.
			8,175,680 B2	5/2012	Panescu
			8,208,998 B2	6/2012	Beatty et al.
			8,233,972 B2	7/2012	Zhang
			8,311,613 B2	11/2012	Danehorn
			8,320,711 B2	11/2012	Altmann et al.
			8,346,339 B2	1/2013	Kordis et al.
			8,360,786 B2	1/2013	Duryea
			8,364,234 B2	1/2013	Kordis et al.
			8,412,307 B2	4/2013	Willis et al.
			8,417,313 B2	4/2013	Scharf et al.
			8,428,690 B2	4/2013	Li et al.
			8,447,377 B2	5/2013	Harlev et al.
			8,454,596 B2	6/2013	Ma et al.
			8,465,433 B2	6/2013	Zwirn
			8,478,388 B2	7/2013	Nguyen et al.
			8,512,255 B2	8/2013	Scharf et al.
			8,571,647 B2	10/2013	Harlev et al.
			8,700,119 B2	4/2014	Scharf et al.
			8,755,861 B2	6/2014	Harlev et al.
			8,825,130 B2	9/2014	Just et al.
			8,825,134 B2	9/2014	Danehorn
			8,918,158 B2	12/2014	Scharf et al.
			8,934,988 B2	1/2015	Persson et al.
			8,948,837 B2	2/2015	Harlev et al.
			8,968,299 B2	3/2015	Kauphusman et al.
			8,979,839 B2	3/2015	De La Rama et al.
			8,989,842 B2	3/2015	Li et al.
			9,011,423 B2	4/2015	Brewster et al.
			9,026,196 B2	5/2015	Curran et al.
			9,031,642 B2	5/2015	Ghosh
			9,037,259 B2	5/2015	Mathur
			9,044,245 B2	6/2015	Condie et al.
			9,167,982 B2	10/2015	Scharf et al.
			9,186,081 B2	11/2015	Afonso et al.
			9,186,212 B2	11/2015	Nabutovsky et al.
			9,192,318 B2	11/2015	Scharf et al.
			9,220,432 B2	12/2015	Bukhman

(56)

References Cited

U.S. PATENT DOCUMENTS

9,241,687	B2	1/2016	McGee	2010/0076426	A1	3/2010	de la Rama et al.
9,351,789	B2	5/2016	Novichenok et al.	2010/0094279	A1	4/2010	Kauphusman et al.
D758,596	S	6/2016	Perryman et al.	2010/0168578	A1	7/2010	Garson, Jr. et al.
9,358,398	B2	6/2016	Moffitt et al.	2010/0256627	A1	10/2010	Ma et al.
9,380,953	B2	7/2016	Houben et al.	2010/0279263	A1	11/2010	Duryea
9,474,486	B2	10/2016	Eliason et al.	2010/0286551	A1	11/2010	Harlev et al.
9,480,525	B2	11/2016	Lopes et al.	2010/0298690	A1	11/2010	Scharf
9,486,355	B2	11/2016	Gustus et al.	2011/0045130	A1	2/2011	Edens et al.
9,492,227	B2	11/2016	Lopes et al.	2011/0077526	A1	3/2011	Zwirn
9,492,228	B2	11/2016	Lopes et al.	2011/0092809	A1	4/2011	Nguyen et al.
9,504,395	B2	11/2016	Scharf et al.	2011/0118726	A1	5/2011	De La Rama et al.
9,526,573	B2	12/2016	Lopes et al.	2011/0125172	A1	5/2011	Gelbart et al.
9,549,708	B2	1/2017	Mercanzini et al.	2011/0144510	A1	6/2011	Ryu et al.
9,579,149	B2	2/2017	Kelly et al.	2011/0172658	A1	7/2011	Gelbart et al.
D782,686	S	3/2017	Werneth et al.	2011/0201951	A1	8/2011	Zhang
9,585,588	B2	3/2017	Marecki et al.	2011/0213231	A1	9/2011	Hall et al.
9,603,651	B2	3/2017	Ghosh	2011/0270237	A1	11/2011	Werneth et al.
9,610,024	B2	4/2017	Scharf et al.	2012/0078077	A1	3/2012	Harlev et al.
9,675,266	B2	6/2017	Afonso et al.	2012/0082969	A1	4/2012	Schwartz et al.
9,713,730	B2	7/2017	Mathur et al.	2012/0136231	A1	5/2012	Markel
9,717,555	B2	8/2017	Chan et al.	2012/0143298	A1	6/2012	Just et al.
9,717,559	B2	8/2017	Ditter et al.	2012/0165667	A1	6/2012	Altmann et al.
9,757,044	B2	9/2017	Scharf et al.	2012/0172859	A1	7/2012	Condie et al.
9,827,039	B2	11/2017	Dandler et al.	2012/0184863	A1	7/2012	Harlev et al.
9,913,589	B2	3/2018	Scharf et al.	2012/0271138	A1	10/2012	Kordis et al.
9,968,268	B2	5/2018	Scharf et al.	2012/0271139	A1	10/2012	Kordis et al.
10,004,459	B2	6/2018	Werneth et al.	2012/0277574	A1	11/2012	Panescu
10,082,395	B2	9/2018	Koyrakh et al.	2012/0302912	A1	11/2012	Moffitt et al.
2001/0007070	A1	7/2001	Stewart et al.	2012/0310064	A1	12/2012	McGee
2002/0026118	A1	2/2002	Govari	2013/0006238	A1	1/2013	Ditter et al.
2002/0128565	A1	9/2002	Rudy	2013/0085361	A1	4/2013	Mercanzini et al.
2002/0165441	A1	11/2002	Coleman et al.	2013/0096432	A1	4/2013	Hauck
2003/0036696	A1	2/2003	Willis et al.	2013/0158537	A1	6/2013	Deladi et al.
2003/0065271	A1	4/2003	Khoury	2013/0165916	A1	6/2013	Mathur
2003/0120318	A1	6/2003	Hauck	2013/0172715	A1	7/2013	Just et al.
2003/0153907	A1	8/2003	Suorsa et al.	2013/0190587	A1	7/2013	Lopes et al.
2003/0158477	A1	8/2003	Panescu	2013/0197614	A1	8/2013	Gustus et al.
2003/0176799	A1	9/2003	Beatty et al.	2013/0225983	A1	8/2013	Willis et al.
2003/0231789	A1	12/2003	Willis et al.	2013/0226017	A1	8/2013	Scharf et al.
2003/0236466	A1	12/2003	Tarjan et al.	2013/0245621	A1	9/2013	Persson et al.
2004/0039312	A1	2/2004	Hillstead et al.	2013/0253298	A1	9/2013	Harlev et al.
2004/0082870	A1	4/2004	Rudy et al.	2013/0267853	A1	10/2013	Dausch et al.
2004/0082948	A1	4/2004	Stewart et al.	2013/0274582	A1	10/2013	Afonso et al.
2004/0254437	A1	12/2004	Hauck et al.	2013/0282084	A1	10/2013	Mathur et al.
2005/0059880	A1	3/2005	Mathias et al.	2013/0304062	A1	11/2013	Chan et al.
2005/0101874	A1	5/2005	Beatty et al.	2013/0304065	A1	11/2013	Lopes et al.
2005/0113665	A1	5/2005	Mohr et al.	2013/0310827	A1	11/2013	Brewster et al.
2005/0148836	A1	7/2005	Kleen et al.	2013/0330701	A1	12/2013	Rubinstein et al.
2005/0203375	A1	9/2005	Willis et al.	2014/0024910	A1	1/2014	Scharf et al.
2006/0052716	A1	3/2006	Beatty et al.	2014/0095105	A1	4/2014	Koyrakh et al.
2006/0058663	A1	3/2006	Willis et al.	2014/0121470	A1	5/2014	Scharf et al.
2006/0058676	A1	3/2006	Yagi et al.	2014/0148677	A1	5/2014	Liempde et al.
2006/0058692	A1	3/2006	Beatty et al.	2014/0180150	A1	6/2014	Scharf et al.
2006/0058693	A1	3/2006	Beatty et al.	2014/0235988	A1	8/2014	Ghosh
2006/0084884	A1	4/2006	Beatty et al.	2014/0249505	A1	9/2014	Bukhman
2006/0084970	A1	4/2006	Beatty et al.	2014/0257069	A1	9/2014	Eliason et al.
2006/0084971	A1	4/2006	Beatty et al.	2014/0257071	A1	9/2014	Curran et al.
2006/0084972	A1	4/2006	Beatty et al.	2014/0275921	A1	9/2014	Harlev et al.
2006/0116576	A1	6/2006	McGee et al.	2014/0276733	A1	9/2014	VanScoy et al.
2007/0060832	A1	3/2007	Levin	2014/0276746	A1	9/2014	Nabutovsky et al.
2007/0083194	A1	4/2007	Kunis et al.	2014/0276789	A1	9/2014	Dandler et al.
2007/0106146	A1	5/2007	Altmann et al.	2014/0358143	A1	12/2014	Novichenok et al.
2007/0232949	A1	10/2007	Saksena	2015/0038862	A1	2/2015	Gijssbers et al.
2008/0009758	A1	1/2008	Voth	2015/0196219	A1	7/2015	Scharf et al.
2008/0146937	A1	6/2008	Lee et al.	2015/0208938	A1	7/2015	Houben et al.
2008/0287777	A1	11/2008	Li et al.	2015/0223757	A1	8/2015	Werneth et al.
2008/0319297	A1	12/2008	Danehorn	2015/0223863	A1	8/2015	Ghosh
2009/0024086	A1	1/2009	Zhang et al.	2015/0257732	A1	9/2015	Ryan
2009/0076483	A1	3/2009	Danehorn	2015/0257825	A1	9/2015	Kelly et al.
2009/0082691	A1	3/2009	Denison et al.	2015/0342491	A1	12/2015	Marecki et al.
2009/0131930	A1	5/2009	Gelbart et al.	2015/0366508	A1	12/2015	Chou et al.
2009/0143651	A1	6/2009	Kallback et al.	2015/0374252	A1	12/2015	de la Rama et al.
2009/0148012	A1	6/2009	Altmann et al.	2016/0007869	A1	1/2016	Scharf et al.
2009/0171274	A1	7/2009	Harlev et al.	2016/0038051	A1	2/2016	Scharf et al.
2009/0264781	A1	10/2009	Scharf et al.	2016/0051321	A1	2/2016	Salahieh et al.
				2016/0100770	A1	4/2016	Afonso et al.
				2016/0128771	A1	5/2016	Ditter et al.
				2016/0128772	A1	5/2016	Reinders et al.
				2016/0192902	A1	7/2016	Werneth et al.

(56)

References Cited

U.S. PATENT DOCUMENTS

2017/0035486 A1 2/2017 Lopes et al.
 2017/0100049 A1 4/2017 Scharf et al.
 2017/0202469 A1 7/2017 Scharf et al.
 2017/0258347 A1 9/2017 Scharf et al.
 2017/0311833 A1 11/2017 Afonso et al.
 2017/0319180 A1 11/2017 Henneken et al.
 2018/0055374 A1 1/2018 Scharf et al.
 2018/0146948 A1 5/2018 Chou et al.

FOREIGN PATENT DOCUMENTS

CN 201275144 7/2009
 CN 104462650 3/2015
 EP 1166714 1/2002
 EP 1760661 3/2007
 EP 1779787 5/2007
 EP 2051625 4/2009
 EP 2252203 11/2010
 EP 2683293 1/2014
 JP 08501477 2/1996
 JP 080504333 5/1996
 JP 10137207 5/1998
 JP 11504541 4/1999
 JP 2000510030 8/2000
 JP 2000510250 8/2000
 JP 2000358299 12/2000
 JP 2001070269 3/2001
 JP 2002051998 2/2002
 JP 2002113004 4/2002
 JP 2002522106 7/2002
 JP 2003511098 3/2003
 JP 2004350702 12/2004
 JP 2005536313 12/2005
 JP 2006-511296 4/2006
 JP 2006511296 4/2006
 JP 2008149132 7/2008
 JP 2009135109 6/2009
 JP 2009136679 6/2009
 JP 2011504363 2/2011
 JP 2011507656 3/2011
 JP 2014506171 3/2014
 JP 2014514031 6/2014
 WO 9406349 3/1994
 WO 9905971 2/1999
 WO 200007501 2/2000
 WO 200245608 6/2002
 WO 2002045608 6/2002
 WO 2003026722 4/2003
 WO 2004026134 4/2004
 WO 2006060613 6/2006
 WO 2008014629 2/2008
 WO 2009065042 5/2009
 WO 2009090547 7/2009
 WO 2011136867 11/2011
 WO 2012068471 5/2012
 WO 2012092016 7/2012
 WO 2012100184 7/2012
 WO 2012100185 7/2012
 WO 2012110942 8/2012
 WO 2012122517 9/2012
 WO 2014124231 2/2013
 WO 2014036439 3/2014
 WO 2014124231 8/2014
 WO 2014130169 8/2014
 WO 2015038607 3/2015
 WO 2015148470 10/2015
 WO 2016183179 11/2016
 WO 2016183285 11/2016
 WO 2017192769 11/2017
 WO 2017192775 11/2017
 WO 2019144103 7/2019
 WO 2019217430 11/2019

OTHER PUBLICATIONS

Australian Office Action dated Jan. 26, 2019 issued in corresponding Australian Application No. 2018211348.
 Japanese Office Action dated Jul. 23, 2019 issued in corresponding Japanese Application No. 2016-542062, with machine translation to English.
 International Search Report and Written Opinion dated Jul. 23, 2019 issued in corresponding International Application No. PCT/US2019/031131
 Japanese Notice of Allowance dated Jun. 11, 2019 issued in corresponding Japanese Application No. 2018-024907, with English translation.
 Extended European Search Report dated Oct. 4, 2018 issued in corresponding European Application No. 16793503.0.
 Canadian Office Action dated Nov. 7, 2018 issued in corresponding Canadian Application No. 2932956.
 Extended European Search Report dated Dec. 5, 2018 issued in corresponding European Application No. 16793622.8.
 Japanese Office Action dated Dec. 11, 2018 issued in corresponding Japanese Application No. 2018-024907, with machine translation to English.
 Office Action dated Mar. 17, 2018 issued in corresponding Australian Application No. 2013308531.
 Anatomy Warehouse, "Axis Heart Model", 2014, pp. 1-3, at <http://www.anatomywarehouse.com/axis-scientific-2-part-deluxe-life-size-human-heart-a-104269>. (Year: 2014).
 Japanese Office Action dated Feb. 19, 2019 issued in corresponding Japanese Application No. 2016-558799, with machine translation to English.
 Japanese Notice of Allowance dated Mar. 5, 2019 issued in corresponding Japanese Application No. 2018061040, with English translation.
 Decision dated Jan. 18, 2018 issued for European Patent Application No. 13176658.6.
 Decision dated Jan. 16, 2018 issued for European Patent Application No. 09702094.5.
 Australian Examination Report dated Feb. 8, 2019 issued in corresponding Australian Application No. 2018250516.
 European Office Action dated Feb. 6, 2019 issued in corresponding European Application No. 14843283.4.
 Japanese Notice of Allowance dated Feb. 27, 2018 issued in corresponding Japanese Application No. 2015-530101, with English language translation.
 Canadian Office Action dated Jan. 22, 2018 issued in corresponding Canadian Application No. 2932956.
 Jackson JD, "Classical Electrodynamics", 3rd edition, Dec. 1998, pp. 31-34.
 Australian Office Action dated Feb. 26, 2018 issued in Australian Application No. 2017201560.
 Japanese Office Action dated Feb. 16, 2016 issued in corresponding Japanese Application No. 2013-557-926, with English language summary.
 Japanese Notice of Allowance dated Jul. 11, 2017 issued in corresponding Japanese Application No. 2013-557-926, with English language summary.
 Patent Examination Report No. 2 dated Jun. 14, 2018 in related Australian Application No. 2014214756.
 He et al. "An equivalent body surface charge model representing three-dimensional bioelectrical activity" IEEE Transactions on Bio-medical Engineering, 42.7 (Jul. 7, 1995) pp. 637-646.
 Wolfgang Nolting: Elektrodynamik—Grundkurs Theoretische Physik 3, Springer Spectrum, Feb. 28, 2016, p.89-91, XP009188752.
 Office Action dated Apr. 27, 2016 in corresponding Canadian Application No. 2,747,859.
 Christoph Scharft et al. Declaration under 37 C.F.R. 1.132, Nov. 15, 2012.
 Canadian Office Action dated Apr. 26, 2017 issued in corresponding Canadian Application No. 2932956.
 Canadian Office Action dated Mar. 30, 2017 issued in corresponding Canadian Application No. 2747859.
 Canadian Office Action dated Nov. 27, 2017 issued in corresponding Canadian Application No. 2829626.

(56)

References Cited

OTHER PUBLICATIONS

Chinese Office Action dated Apr. 17, 2017 issued in corresponding Chinese Application No. 201480018328.4.

European Office Action dated Apr. 28, 2014, issued in corresponding European Application No. 09 702 094.5—1660.

European Office Action dated Feb. 29, 2016 issued in corresponding European Application No. 07 785 075.8—1657.

European Office Action dated Mar. 21, 2017 issued in corresponding European Application No. 07785075.8.

Extended European Search Report dated Mar. 14, 2017 issued in corresponding European Application No. EP14843283.4.

Extended European Search Report dated Oct. 18, 2017, issued in European Application No. 15768711.

International Search Report and Written Opinion dated Jun. 26, 2015 issued in International Application No. PCT/US2015/022187.

ISRWO dated Aug. 4, 2017, issued in Application No. PCT/US17/30915.

International Search Report dated Mar. 10, 2015 issued in corresponding International Application No. PCT/US14/54942.

ISRWO dated Sep. 25, 2017, issued in Application No. PCT/US17/30922.

International Search Report dated Apr. 14, 2008 in related International Application No. PCT/CH2007/000380.

Invitation to Pay Additional Fees dated Jan. 8, 2014 in corresponding International Application No. PCT/US2013/057579.

ISRWO dated May 20, 2014 in International application No. PCT/US14/15261.

Japanese Office Action dated Jan. 31, 2017 issued in corresponding Japanese Application No. 2013-557926, with English language summary.

Japanese Office Action dated Jun. 27, 2017 issued in corresponding Japanese Application No. 2015-530101, with English language translation.

Japanese Office Action dated Sep. 26, 2017 issued in corresponding Japanese Application No. 2017-155346, with English translation.

Office Action dated Nov. 7, 2017, issued in European Application No. 15768711.

Office Action dated Oct. 10, 2017, issued in Application No. 2015-557091 with machine translation to English.

Office Action dated Mar. 9, 2016 in corresponding European Patent Application No. 13176658.6.

Office Action dated May 30, 2016 in related Australian Patent Application No. 2012225250.

Office Action dated Oct. 4, 2013 in corresponding Canadian Patent Application No. 2,659,898.

PCT ISRWO dated Jun. 5, 2014, issued in corresponding PCT Application No. PCT/US2013/057579.

Della Bella et al. "Non-contact mapping to guide catheter ablation of untolerated ventricular tachycardia" *European Heart Journal*, May 2002, 23(9)742-752.

Examination report dated Jul. 6, 2017 issued in Australian Patent Application No. 2014214756.

Examination Report dated Jun. 27, 2017 issued in Australian Application No. 2013308531.

Examiner's Report dated Dec. 22, 2015 in related Canadian Application No. 2656898.

Extended European Search Report for related Application No. 13176658 dated Sep. 29, 2014.

Extended European Search Report dated Jul. 8, 2016 in related European Application No. 14748567.6.

Gupta et al. "Point of view cardiac mapping; utility or futility? Non-contact endocardial mapping" *Indian Pacing and Electrophysiology Journal* 2:2Q-32 (2002).

He et al. "An equivalent body surface charge model representing three-dimensional bioelectrical activity" *IEEE Transactions on Biomedical Engineering*, 42.7 (1995) pp. 637-646.

International Search Report and Written Opinion in related Application No. PCT/US2012/028593 dated Mar. 5, 2013.

International Search Report in related Application No. PCT/IB2009/000071 dated Oct. 7, 2009.

Jackson, JD, "Surface Distributions of Charges and Dipoles and Discontinuities in the Electric Field and Potential", *Classical Electrodynamics*, 3rd edition, Dec. 1998, pp. 31-34.

Leif et al., "Geometric modeling based on polygonal meshes". *Eurographics 2000 Tutorial*, Aug. 21, 2000.

Office Action dated Mar. 9, 2016 in corresponding European Patent Application No. 09702094.5.

Partial European Search Report dated Apr. 29, 2014 in corresponding European Application No. 13176658.

Patent Examination Report No. 3 dated Sep. 21, 2016 in related Australian Application No. 2012225250.

Pullan et al. "The inverse problem of electrocardiology" *Northeastern University Electrical and Computer Engineering*, Feb. 23, 2007.

Van Oosterom A: "Solidifying the solid angle." 2002 *Journal of Electrocardiology* 2002 vol. 35 Suppl pp. 181-192 ISSN: 0022-0736.

William G. Stevenson et al: "Recording Techniques for Clinical Electrophysiology" *Journal of Cardiovascular Electrophysiology*, vol. 16 No. 91, Sep. 2005, pp. 1017-1022.

Wolfgang Nolting: *Elektrodynamik—Grundkurs Theoretische Physik* 3 Springer Spektrum pp. D 89-91.

ISRWO dated Aug. 11, 2016 issued in corresponding International Application No. PCT/US2016/032017.

ISRWO dated Aug. 8, 2016 issued in corresponding European Application No. PCT/US2016/031823.

ISRWO dated Aug. 18, 2016 issued in corresponding International Application No. PCT/US16/32420.

International Search Report and Written Opinion dated Dec. 12, 2017 issued in corresponding International Application No. PCT/US2017/056064.

Japanese Office Action dated Oct. 15, 2019 issued in corresponding Japanese Application No. 2018-195960, with machine translation to English.

International Search Report and Written Opinion dated Apr. 8, 2019, issued in corresponding International Application No. PCT/US19/14498.

Extended European Search Report dated Nov. 26, 2019 issued in corresponding European Application No. 19184148.5.

Japanese Notice of Allowance dated Sep. 18, 2018 issued in corresponding Japanese Application No. 2015-557091, with English language translation.

Japanese Office Action dated Aug. 28, 2018 issued in corresponding Japanese Application No. 2016-542062, with machine translation into English.

Australian Examination Report dated Jun. 28, 2018, issued in corresponding Australian Patent Application No. 2014318872.

Canadian Office Action dated Oct. 29, 2018 issued in corresponding Canadian Application No. 2829626.

Office Action dated Jan. 31, 2018 issued for European Patent Application No. 13763151.1.

European Office Action dated Apr. 23, 2018 issued in corresponding European Application No. 07785075.8.

Summons To Attend Oral Proceedings dated Dec. 20, 2019 issued in corresponding European Application No. 13763151.1.

Japanese Office Action dated Jan. 7, 2020 issued in corresponding Japanese Application No. 2016-558799, with machine translation to English.

Australian Office Action dated Jan. 15, 2020 issued in corresponding Australian Application No. 2016262547.

International Search Report and Written Opinion dated Jan. 14, 2020 issued in International Application No. PCT/US2019/060433.

Australian Office Action dated Mar. 16, 2020 issued in corresponding Australian Application No. 2016260522.

Japanese Office Action dated Mar. 10, 2020 issued in corresponding Japanese Application No. 2017-559320, with machine translation to English.

Japanese Office Action dated Mar. 17, 2020 issued in corresponding Japanese Application No. 2019-071004, with machine translation to English.

Australian Office Action dated Dec. 22, 2019 issued in corresponding Australian Application No. 2018278959.

* cited by examiner

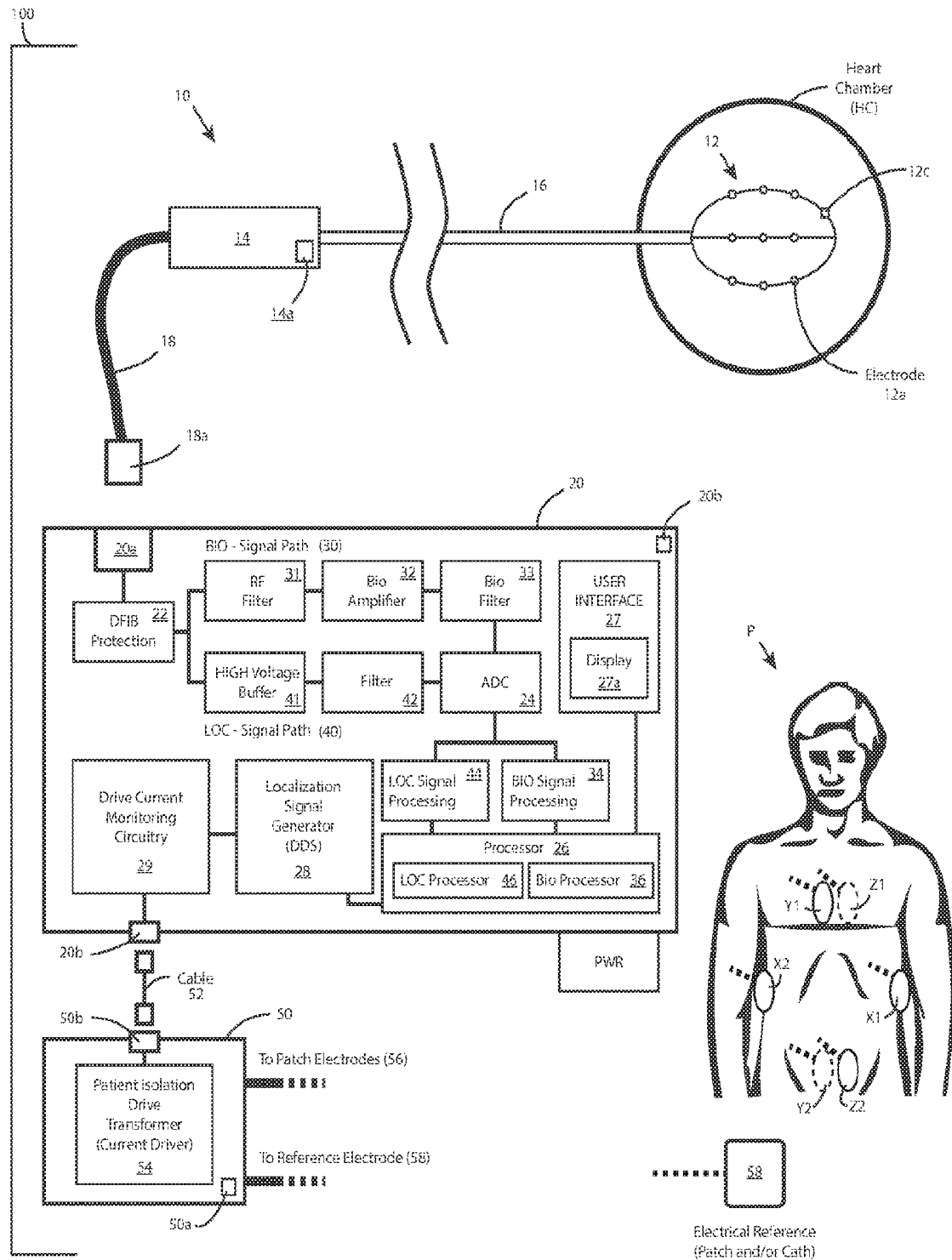


FIG 1

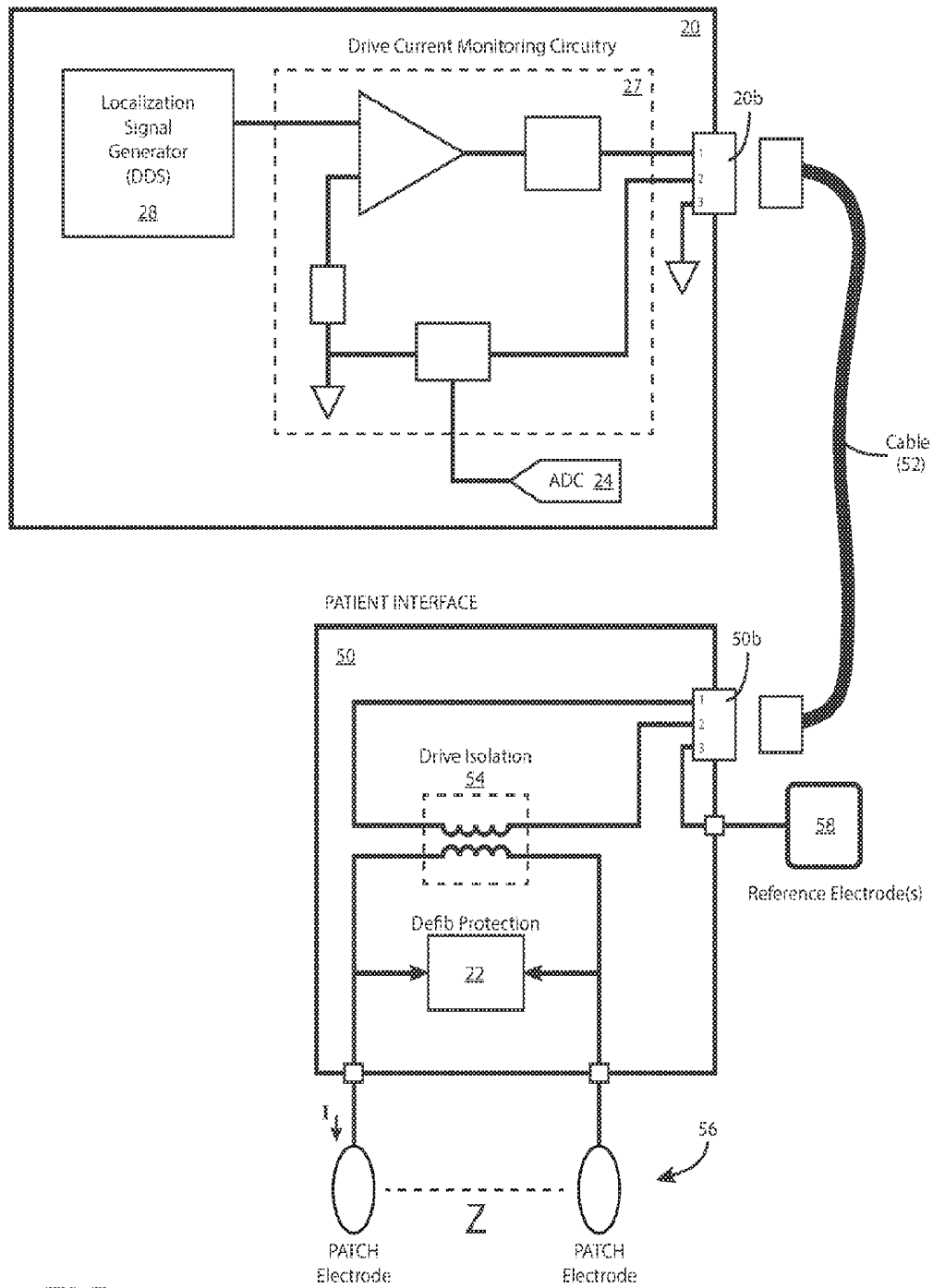


FIG 2

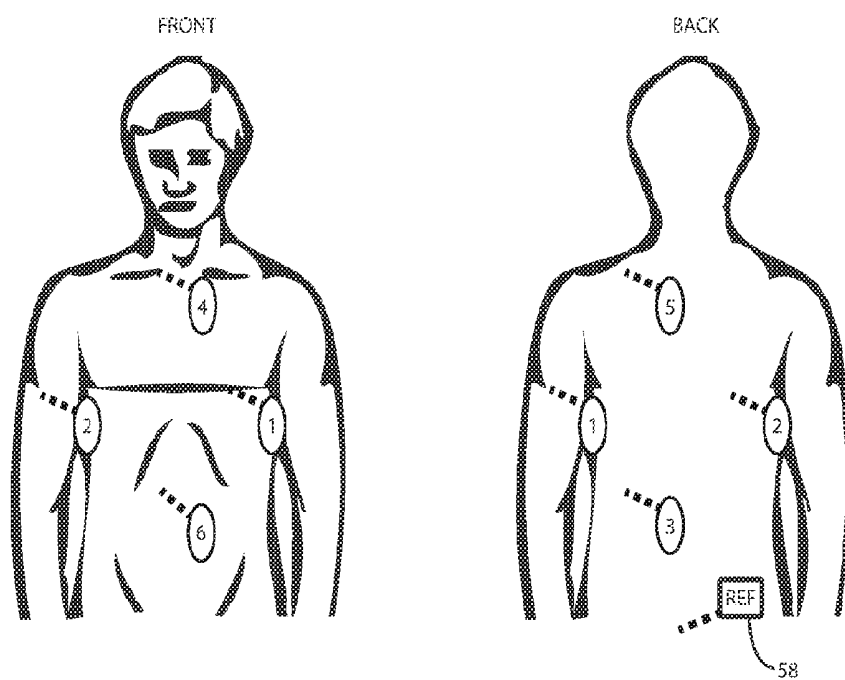


FIG 3

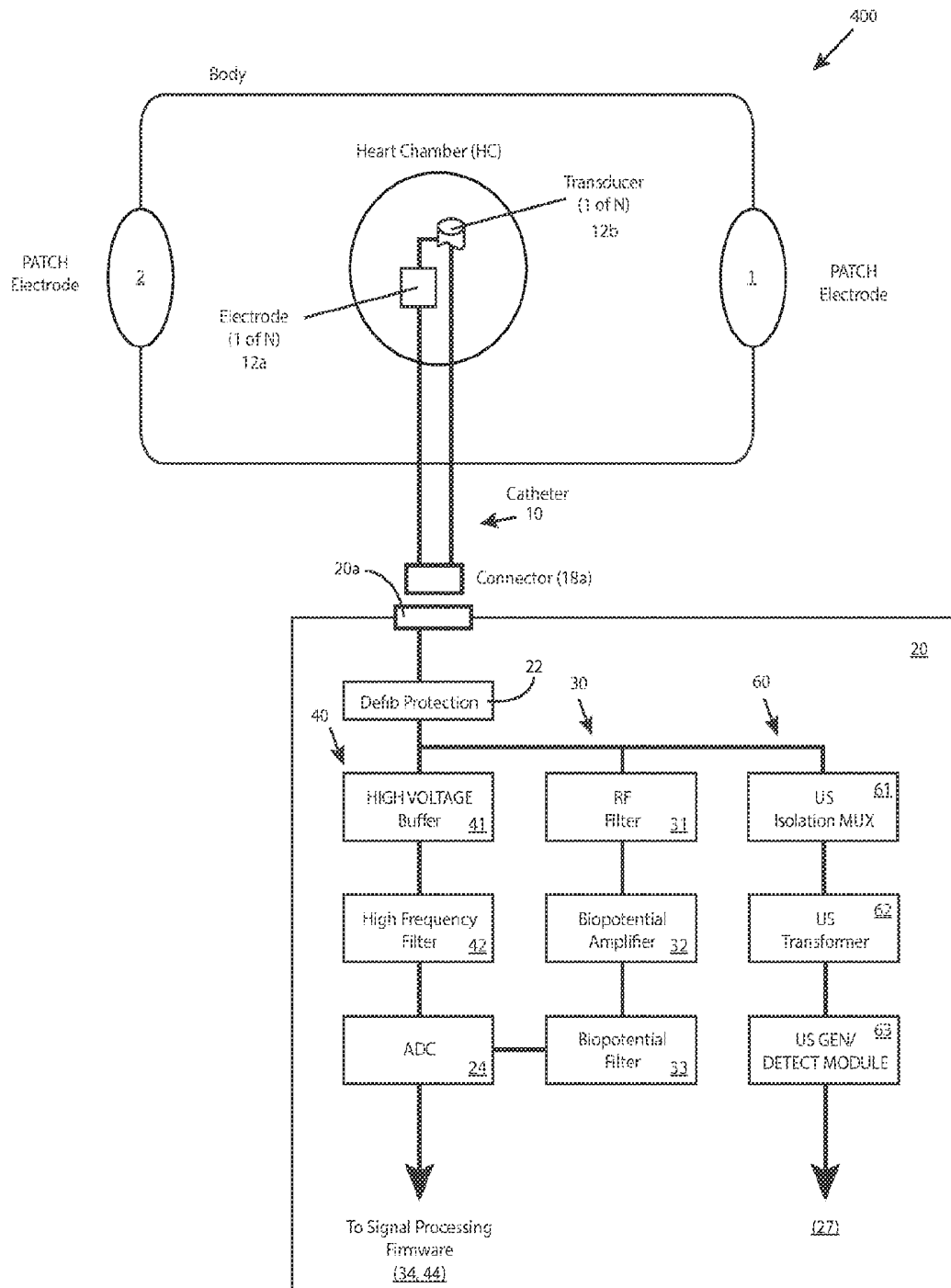


FIG 4

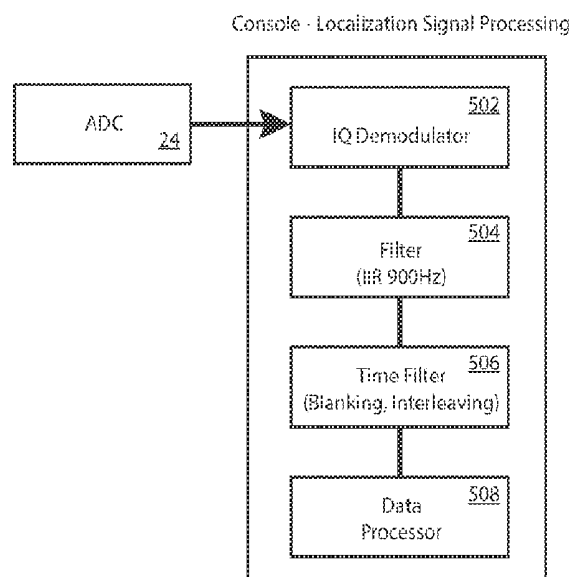


FIG 5

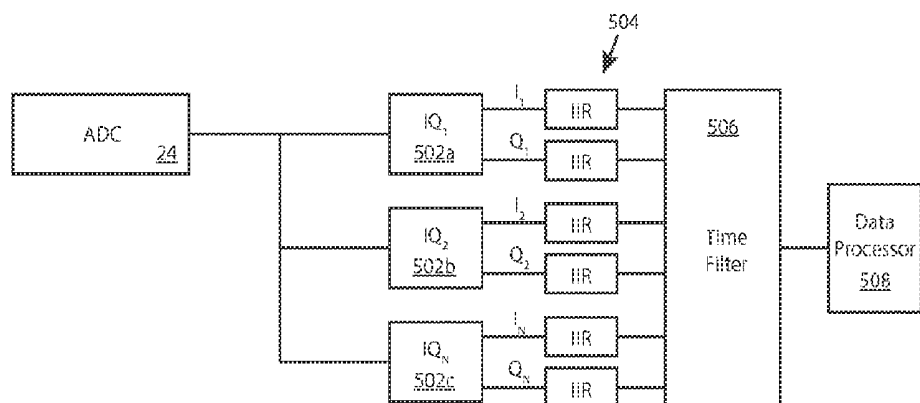


FIG 6

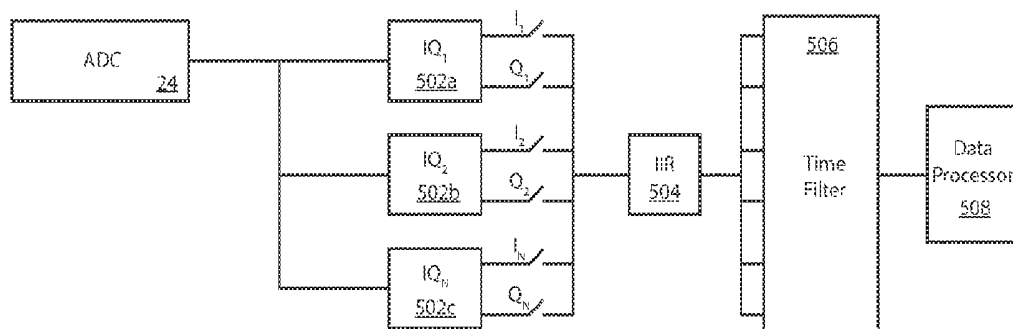


FIG 7

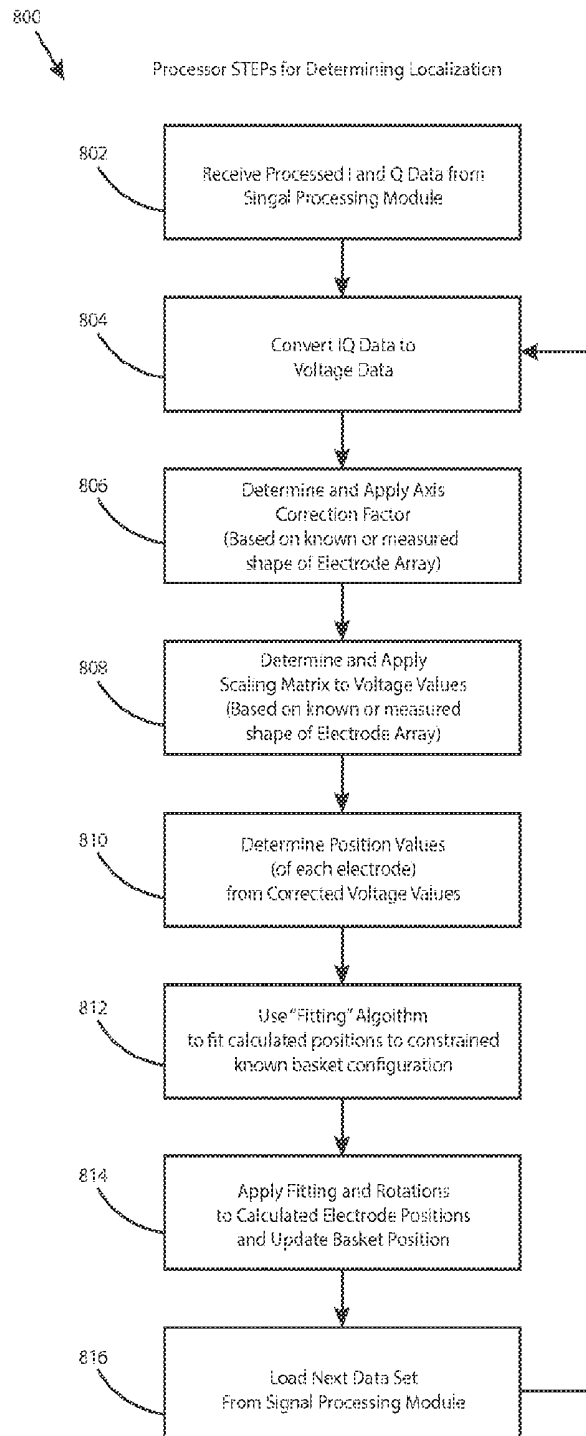


FIG 8

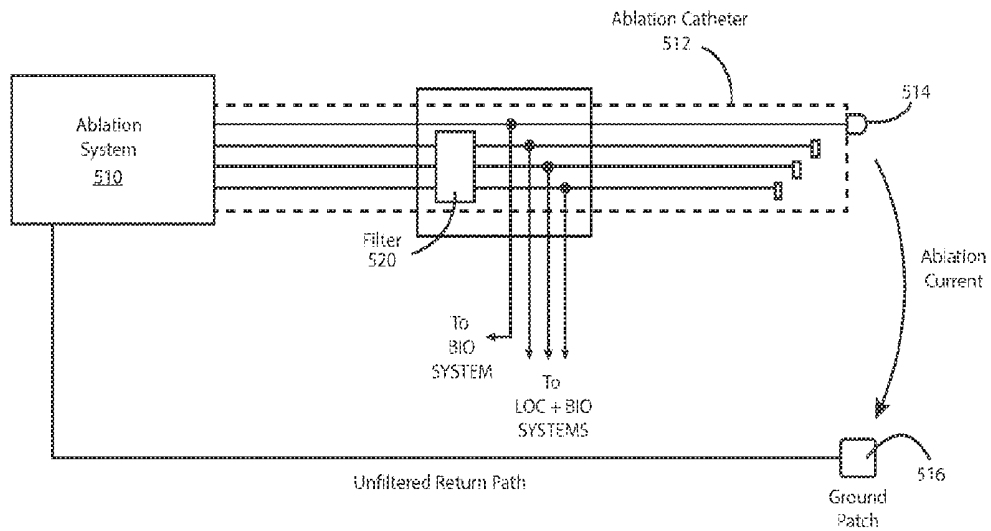


FIG 9

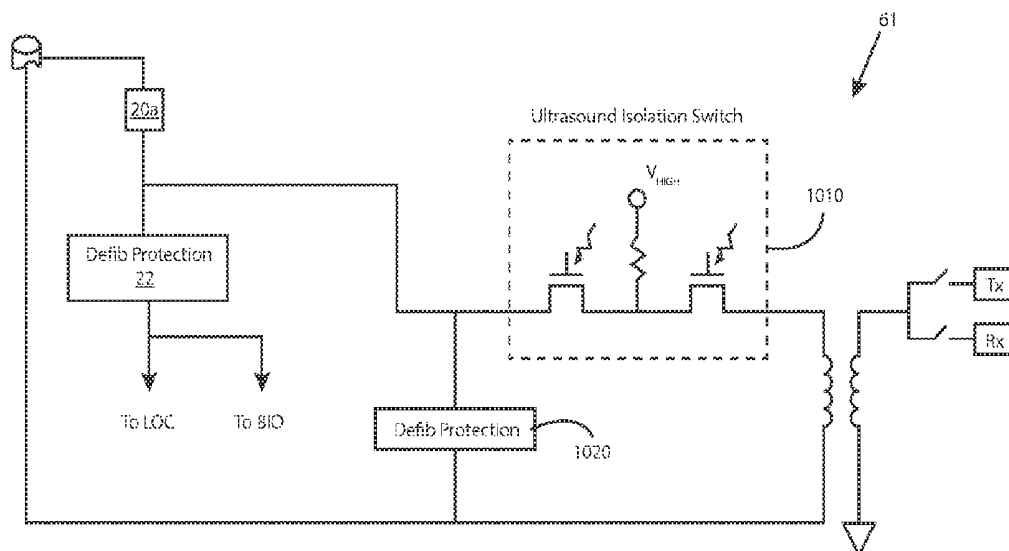


FIG 10

LOCALIZATION SYSTEM AND METHOD USEFUL IN THE ACQUISITION AND ANALYSIS OF CARDIAC INFORMATION

RELATED APPLICATIONS

The present application claims priority under 35 USC 119(e) to U.S. Provisional Patent Application Ser. No. 62/161,213, entitled “Localization System and Method Useful in the Acquisition and Analysis of Cardiac Information”, filed May 13, 2015, which is incorporated herein by reference in its entirety.

The present application, while not claiming priority to, may be related to U.S. patent application Ser. No. 14/865,435, entitled “Method and Device for Determining and Presenting Surface Charge and Dipole Densities on Cardiac Walls”, filed Sep. 25, 2015, which is a continuation of U.S. Pat. No. 9,167,982 (hereinafter the ‘982 patent), entitled “Method and Device for Determining and Presenting Surface Charge and Dipole Densities on Cardiac Walls”, issued Oct. 27, 2015, which is a continuation of U.S. Pat. No. 8,918,158 (hereinafter the ‘158 patent), entitled “Method and Device for Determining and Presenting Surface Charge and Dipole Densities on Cardiac Walls”, issued Dec. 23, 2014, which is a continuation of U.S. Pat. No. 8,700,119 (hereinafter the ‘119 patent), entitled “Method and Device for Determining and Presenting Surface Charge and Dipole Densities on Cardiac Walls”, issued Apr. 15, 2014, which is a continuation of U.S. Pat. No. 8,417,313 (hereinafter the ‘313 patent), entitled “Method and Device for Determining and Presenting Surface Charge and Dipole Densities on Cardiac Walls”, issued Apr. 9, 2013, which was a 35 USC 371 national stage filing of Patent Cooperation Treaty Application No. CH2007/000380, entitled “Method and Device for Determining and Presenting Surface Charge and Dipole Densities on Cardiac Walls”, filed Aug. 3, 2007, published as WO 2008/014629, which claimed priority to Swiss Patent Application No. 1251/06 filed Aug. 3, 2006, each of which is hereby incorporated by reference.

The present application, while not claiming priority to, may be related to U.S. patent application Ser. No. 14/886,449, entitled “Device and Method For the Geometric Determination of Electrical Dipole Densities on the Cardiac Wall”, filed Oct. 19, 2015, which is a continuation of U.S. Pat. No. 9,192,318 (hereinafter the ‘318 patent), entitled “Device and Method For the Geometric Determination of Electrical Dipole Densities on the Cardiac Wall”, issued Nov. 24, 2015, which is a continuation of U.S. Pat. No. 8,512,255, entitled “Device and Method for the Geometric Determination of Electrical Dipole Densities on the Cardiac Wall”, issued Aug. 20, 2013, published as US2010/0298690 (hereinafter the ‘690 publication), which was a 35 USC 371 national stage application of Patent Cooperation Treaty Application No. PCT/IB09/00071 filed Jan. 16, 2009, entitled “A Device and Method for the Geometric Determination of Electrical Dipole Densities on the Cardiac Wall”, published as WO2009/090547, which claimed priority to Swiss Patent Application 00068/08 filed Jan. 17, 2008, each of which is hereby incorporated by reference.

The present application, while not claiming priority to, may be related to U.S. application Ser. No. 14/003,671, entitled “Device and Method for the Geometric Determination of Electrical Dipole Densities on the Cardiac Wall”, filed Sep. 6, 2013, which is a 35 USC 371 national stage filing of Patent Cooperation Treaty Application No. PCT/US2012/028593, entitled “Device and Method for the Geometric Determination of Electrical Dipole Densities on the

Cardiac Wall”, published as WO2012/122517 (hereinafter the ‘517 publication), which claimed priority to U.S. Patent Provisional Application Ser. No. 61/451,357, each of which is hereby incorporated by reference.

The present application, while not claiming priority to, may be related to U.S. Design application Ser. No. 29/475,273, entitled “Catheter System and Methods of Medical Uses of Same, Including Diagnostic and Treatment Uses for the Heart”, filed Dec. 2, 2013, which is a 35 USC 371 national stage filing of Patent Cooperation Treaty Application No. PCT/US2013/057579, entitled “Catheter System and Methods of Medical Uses of Same, Including Diagnostic and Treatment Uses for the Heart”, filed Aug. 30, 2013, which claims priority to U.S. Patent Provisional Application Ser. No. 61/695,535, entitled “System and Method for Diagnosing and Treating Heart Tissue”, filed Aug. 31, 2012, which is hereby incorporated by reference.

The present application, while not claiming priority to, may be related to U.S. application Ser. No. 14/762,944, entitled “Expandable Catheter Assembly with Flexible Printed Circuit Board (PCB) Electrical Pathways”, filed Jul. 23, 2015, which is a 35 USC 371 national stage filing of Patent Cooperation Treaty Application No. PCT/US2014/15261, entitled “Expandable Catheter Assembly with Flexible Printed Circuit Board (PCB) Electrical Pathways”, filed Feb. 7, 2014, published as WO2014/124231, which claims priority to U.S. Patent Provisional Application Ser. No. 61/762,363, entitled “Expandable Catheter Assembly with Flexible Printed Circuit Board (PCB) Electrical Pathways”, filed Feb. 8, 2013, which is hereby incorporated by reference.

The present application, while not claiming priority to, may be related to Patent Cooperation Treaty Application No. PCT/US2015/11312, entitled “Gas-Elimination Patient Access Device”, filed Jan. 14, 2015, which claims priority to U.S. Patent Provisional Application Ser. No. 61/928,704, entitled “Gas-Elimination Patient Access Device”, filed Jan. 17, 2014, which is hereby incorporated by reference.

The present application, while not claiming priority to, may be related to Patent Cooperation Treaty Application No. PCT/US2015/22187, entitled “Cardiac Analysis User Interface System and Method”, filed Mar. 24, 2015, which claims priority to U.S. Patent Provisional Application Ser. No. 61/970,027, entitled “Cardiac Analysis User Interface System and Method”, filed Mar. 28, 2014, which is hereby incorporated by reference.

The present application, while not claiming priority to, may be related to U.S. application Ser. No. 14/916,056, entitled “Devices and Methods for Determination of Electrical Dipole Densities on a Cardiac Surface”, filed Mar. 2, 2016, which is a 35 USC 371 national stage filing of Patent Cooperation Treaty Application No. PCT/US2014/54942, entitled “Devices and Methods for Determination of Electrical Dipole Densities on a Cardiac Surface”, filed Sep. 10, 2014, published as WO2015/038607, which claims priority to U.S. Patent Provisional Application Ser. No. 61/877,617, entitled “Devices and Methods for Determination of Electrical Dipole Densities on a Cardiac Surface”, filed Sep. 13, 2013, which is hereby incorporated by reference.

FIELD

The present invention is generally related to systems and methods that may be useful for the diagnosis and treatment of cardiac arrhythmias or other abnormalities, in particular,

the present invention is related to systems, devices, and methods useful in performing localization of such arrhythmias or other abnormalities.

BACKGROUND

For localizing the origin(s) of cardiac arrhythmias it is common practice to measure the electric potentials located on the inner surface of the heart by electrophysiological means within the patient's heart. One method is to insert electrode catheters into the heart to record cardiac potentials during normal heart rhythm or cardiac arrhythmia. If the arrhythmia has a regular activation sequence, the timing of the electric activation measured in voltages at the site of the electrode can be accumulated when moving the electrode around during the arrhythmia, to create a three-dimensional map of the electric activation. By doing this, information on the localization of the source of arrhythmia(s) and mechanisms, i.e., re-entry circuits, can be diagnosed to initiate or guide treatment (radiofrequency ablation). The information can also be used to guide the treatment of cardiac resynchronization, in which implantable pacing electrodes are placed in specific locations within the heart wall or chambers to re-establish a normal level of coordinated activation of the heart.

A method using external sensors measures the electrical activity of the heart from the body surface using electrocardiographic techniques that include, for example, electrocardiograms (ECG) and vectorcardiography (VCG). These external sensor techniques can be limited in their ability to provide information and/or data on regional electrocardiac activity. These methods can also fail to localize bioelectric events in the heart.

A method using external sensors for the localization of cardiac arrhythmias utilizes body surface mapping. In this technique, multiple electrodes are attached to the entire surface of the thorax and the information of the cardiac electrograms (surface ECG) is measured in voltages that are accumulated into maps of cardiac activation. This measurement can be problematic because the electrical activity is time dependent and spatially distributed throughout the myocardium and also fails to localize bioelectric events in the heart. Complex mathematical methods are required to determine the electric activation upon the outer surface of a heart model (i.e. epicardium), for instance, one obtained from CT or MRI imaging giving information on cardiac size and orientation within the thoracic cavity.

Alternatively, recordings of potentials at locations on the torso, for example, can provide body surface potential maps (BSPMs) over the torso surface. Although the BSPMs can indicate regional cardiac electrical activity in a manner that can be different from conventional ECG techniques, these BSPM techniques generally provide a comparatively low resolution, smoothed projection of cardiac electrical activity that does not facilitate visual detection or identification of cardiac event locations (e.g., sites of initiation of cardiac arrhythmias) and/or details of regional activity (e.g., number and location of arrhythmogenic foci in the heart).

Since the localization of cardiac arrhythmias by the use of potentials is imprecise, the successful treatment of cardiac arrhythmias has been difficult and has demonstrated limited success and reliability. There is, therefore, a need for improved methods of localizing, diagnosing and treating cardiac arrhythmias.

SUMMARY

In accordance with an aspect of the inventive concept, provided is a localization system, comprising: at least one

catheter configured for delivery of one or more biopotential electrodes to a body cavity defined by surrounding tissue; a patient interface module comprising a plurality of localization electrodes configured for fixed orientation relative to the body; a cardiac information console configured to process localization signals from the localization electrodes to establish a manipulatable coordinate system for the tissue and to process the biopotential signals to orient the biopotential electrodes within the coordinate system.

In various embodiments, the cavity is a heart chamber and the surrounding tissue is one or more walls of the heart chamber.

In various embodiments, the one or more biopotential electrodes is a plurality of biopotential electrodes coupled to a distal end of the at least one catheter.

In various embodiments, the biopotential electrodes are disposed on a 3D array.

In various embodiments, the 3D array includes a plurality of splines.

In various embodiments, the 3D array is a basket array, a spiral array, a balloon, radially deployable arms, and/or other expandable and compactible structures.

In various embodiments, the patient interface module includes a patient isolation drive system, a set of patch electrodes, and one or more reference electrodes.

In various embodiments, the localization electrodes include one or more pairs of localization electrodes.

In various embodiments, the localization electrodes include two pairs of localization electrodes.

In various embodiments, each pair of localization electrodes defines an axis of the coordinate system.

In various embodiments, the localization electrodes include three pairs of localization electrodes, each pair of localization electrodes defining one axis of the coordinate system.

In various embodiments, a first pair of localization electrodes has two patch electrodes placed on opposite sides of the ribs; a second pair of localization electrodes has one patch electrode placed on the lower back and one patch electrode placed on the upper chest; and a third pair of localization electrodes has one patch electrode placed on the upper back and one patch electrode placed on the lower abdomen.

In various embodiments, the axes are non-orthogonal to a natural axis of the body.

In various embodiments, the pairs of localization electrodes are placed such that the axes intersect at an origin, and the origin is located in the heart.

In various embodiments, the origin of the three intersecting axes is centered on an atrial volume.

In various embodiments, the isolation drive system is configured to isolate the localization signals from the cardiac information console to prevent current leakage.

In various embodiments, the isolation drive system is configured to maintain simultaneous output on all axes generated by the localization electrode pairs.

In various embodiments, each pair of localization electrodes is driven by a different localization signal.

In various embodiments, each localization signal has a different frequency.

In various embodiments, the signals generated for the first pair of electrodes has a frequency of about 39 kHz; the signals generated for the second pair of electrodes has a frequency of about 48 kHz; and the signals generated for the third pair of electrodes has a frequency of about 52 kHz.

In various embodiments, the cardiac information console is further configured to rotate the coordinate system to adjust and correct an electronic representation of the 3D array of biopotentials.

In various embodiments, the cardiac information console is further configured to scale the coordinate system to adjust and correct an electronic representation of the 3D array of biopotentials.

In various embodiments, the cardiac information console is further configured to fit an electronic representation of the 3D array of biopotentials to a known or determined geometry of the 3D array of biopotentials.

In various embodiments, the system further comprises a user interface system configured to display the 3D array of biopotential electrodes and the coordinate system.

In various embodiments, the user interface system includes a mechanism that enables a user to rotate and/or scale the coordinate system to graphically adjust and correct an image of the 3D array of biopotentials.

In various embodiments, the cardiac information console further comprises, for each electrode, a biopotential signal path having a high impedance input and configured to receive biopotential signals from the biopotential electrodes; and/or a localization signal path having a high impedance input and configured to receive localization signals from the localization electrodes.

In various embodiments, the cardiac information console further comprises, for each electrode, a DFIB protection circuit coupled between the biopotential signal path and the localization signal path.

In various embodiments, the cardiac information console further comprises, for each electrode, an ADC coupled to outputs of the biopotential signal path and the localization signal path.

In various embodiments, the cardiac information console further comprises, coupled to an ADC output, a biopotential signal processor configured to provide cardiac activity mapping from processed biopotential data and a localization signal processor configured to localize the biopotential electrodes.

In various embodiments, the system further comprises an IQ demodulator, for each electrode, coupled to the output of the ADC and configured to separate the magnitude and phase of a received data signal; a narrow band IIR filter coupled to the IQ demodulator, and a time filter coupled to the IIR filter, and configured to selectively filter out portions of data on a time basis.

In various embodiments, there is one IIR filter, comprising an I portion and a Q portion, for each IQ demodulator.

In various embodiments, there is one multichannel IIR filter for a plurality of IQ demodulators.

In various embodiments, the system further comprises one or more auxiliary catheters.

In various embodiments, the one or more auxiliary catheters comprises at least one of an ablation catheter or a reference catheter.

In various embodiments, the at least one catheter further includes ultrasound electrodes configured to collect image data to generate one or more images of the tissue.

In various embodiments, the cardiac information console further comprises an ultrasound signal path having a high impedance input and configured to receive ultrasound signals from the ultrasound electrodes.

In various embodiments, the system comprises one or more sensors configured to produce one or more signals indicating a presence of, an absence of, and/or a change in at least one sensed condition.

In various embodiments, the one or more sensors comprises at least one catheter sensor.

In various embodiments, the at least one catheter sensor comprises a sensor mounted to or integral with: a catheter handle of the at least one catheter and/or a catheter array coupled to a distal end of the at least one catheter.

In various embodiments, the at least one catheter sensor comprises a patient physiologic sensor selected from the group consisting of: a blood pressure sensor; a blood gas sensor; a temperature sensor; a blood glucose sensor; a pH sensor; a respiration sensor; an average clotting time (ACT) sensor; and combinations of one or more of these.

In various embodiments, the one or more sensors comprises at least one cardiac information console sensor.

In various embodiments, the one or more sensors comprises at least one patient interlace system sensor.

In various embodiments, the one or more sensors comprises a plurality of sensors, including at least two sensors selected from the group consisting of: a catheter sensor; a cardiac information console sensor; a patient interface system sensor; and combinations of one or more of these.

In various embodiments, the one or more sensors comprise at least one sensor selected from the group consisting of: a force sensor; a pressure sensor; a strain gauge; an optical sensor; an imaging sensor; a sound sensor; a hall effect sensor; a pH sensor; a magnetic sensor; a temperature sensor; and combinations of one or more of these.

In various embodiments, the imaging sensor includes a lens and/or optical fiber.

In various embodiments, the sound sensor includes an ultrasound sensor.

In various embodiments, the one or more of sensors comprise at least one transducer selected from the group consisting of: a heating element; a cooling element; a vibrating element; a drug or other agent delivery element; a magnetic field generating element; a light delivery element; an imaging element; and combinations of one or more of these.

In various embodiments, the imaging element includes a lens and/or optical fiber.

In various embodiments, the system is configured to analyze the one or more signals produced by the one or more sensors.

In various embodiments, the system is configured to perform an analysis of one or more signals produced by the one or more of sensors in combination with voltage data, dipole density data, surface charge data, and/or anatomical data sensed and/or calculated by the system.

In various embodiments, the one or more signals from the one or more sensors are used by system to perform a function selected from the group consisting of: improve an anatomical image displayed by system; improve cardiac information displayed by system (e.g. dipole density and/or surface charge information); detect a malfunction of system; provide physiologic data of a patient; and combinations of one or more of these.

In various embodiments, the cardiac information displayed by system includes at least one of dipole density information and/or surface charge information.

In accordance with another aspect of the inventive concept, provided is a localization method, comprising: delivering one or more biopotential electrodes to a body cavity defined by surrounding tissue using at least one catheter; receiving biopotential signals from the one or more biopotential electrodes; establishing a manipulatable coordinate system for the tissue using localization electrodes having a fixed orientation relative to the body; and processing the

biopotential signals to orient and/or reorient the biopotential electrodes within the coordinate system.

In various embodiments, the cavity is a heart chamber and the surrounding tissue is one or more walls of the heart chamber.

In various embodiments, the one or more biopotential electrodes is a plurality of biopotential electrodes coupled to a distal end of the at least one catheter.

In various embodiments, the biopotential electrodes are disposed on a 3D array.

In various embodiments, the 3D array includes a plurality of splines.

In various embodiments, the 3D array is a basket array, spiral array, a balloon, radially deployable arms, and/or other expandable and compactible structures.

In various embodiments, the localization electrodes include a set of patch electrodes and one or more reference electrodes.

In various embodiments, the localization electrodes include one or more pairs of localization electrodes.

In various embodiments, the localization electrodes include two pairs of localization electrodes.

In various embodiments, each pair of localization electrodes defines an axis of the coordinate system.

In various embodiments, the localization electrodes include three pairs of localization electrodes, each pair of localization electrodes defining one axis of the coordinate system.

In various embodiments, a first pair of localization electrodes has two patch electrodes placed on opposite sides of the ribs, a second pair of localization electrodes has one patch electrode placed on the lower back and one patch electrode placed on the upper chest, and a third pair of localization electrodes has one patch electrode placed on the upper back and one patch electrode placed on the lower abdomen.

In various embodiments, the axes are non-orthogonal to a natural axis of the body.

In various embodiments, the pairs of localization electrodes are placed such that the axes intersect at an origin, and the origin is located in the heart.

In various embodiments, the origin of the three intersecting axes is centered on an atrial volume.

In various embodiments, the method further comprises maintaining simultaneous output on all axes generated by the localization electrode pairs.

In various embodiments, the method further comprises driving each pair of localization electrodes with a different localization signal.

In various embodiments, each localization signal has a different frequency.

In various embodiments, the method further comprises generating the signals for the first pair of electrodes at a frequency of about 39 kHz; generating the signals for the second pair of electrodes at a frequency of about 48 kHz; and generating the signals for the third pair of electrodes at a frequency of about 52 kHz.

In various embodiments, receiving biopotential signals from the one or more biopotential electrodes includes: using at least one processor, rotating the coordinate system to adjust and correct an electronic representation of a 3D array of biopotentials sensed and/or recorded by the one or more biopotential electrodes.

In various embodiments, the method further comprises using at least one processor, scaling the coordinate system to adjust and correct an electronic representation of the 3D array of biopotentials.

In various embodiments, the method further comprises fitting an electronic representation of the 3D array of biopotentials to a known or determined geometry of the 3D array of biopotentials.

In various embodiments, the method further comprises displaying the 3D array of biopotential electrodes and the coordinate system on at least one display of a user interface system.

In various embodiments, the method further comprises rotating and/or scaling the coordinate system to graphically adjust and correct an image of the 3D array of biopotentials in response to user interaction with the user interface system.

In various embodiments, processing the biopotential signals includes: receiving I and Q data based on the receiving biopotential signals; converting the IQ data to voltage data; applying an axis correction factor to the voltage data, based on a known and/or measured shape of the electrode array; determining a scaling matrix and applying the scaling matrix to the sensed voltage data, based on a known and/or measured shape of the electrode array; calculating position values of each electrode, each electrode having a corrected voltage value based on the axis correction and scaling of the voltage data; and fitting the calculated position values of each electrode to a known basket configuration.

In various embodiments, the method further comprises applying fitting and rotations to the calculated electrode positions; and updating the electrode positions.

In various embodiments, the method further comprises, if a next set of biopotential data exists, repeating the method for the next set of biopotential data.

In various embodiments, the localization electrodes include a plurality of pairs of localization electrodes and there are is one axis for each pair of localization electrodes, and the method comprises rotating, scaling and/or deskewing one or more of the axes until the electrode array takes a predetermined shape.

In various embodiments, the electrode array is a 3D basket array.

In various embodiments, the method further comprises displaying the electrode array on a display of a user interface subsystem.

In various embodiments, applying the scaling matrix comprises, if a length or a size of the electrode array is incorrect, based on known or determined proportions of the electrode array, scaling one or more of the axes of the electrode array longer or shorter until the known or determined proportions of the electrode array is/are achieved.

In various embodiments, the method further comprises, for each electrode: receiving biopotential signals from the biopotential electrodes via a biopotential signal path having a high impedance input; and/or receiving localization signals from the localization electrodes via a localization signal path having a high impedance input.

In various embodiments, the method further comprises, for each electrode: coupling a DFIB protection circuit between the biopotential signal path and the localization signal path.

In various embodiments, the method further comprises, for each electrode: coupling outputs of the biopotential signal path and the localization signal path to an ADC.

In various embodiments, the method further comprises coupling a biopotential signal processor and a localization signal processor to an ADC output; providing cardiac activity mapping from processed biopotential data using the biopotential signal processor; and localizing the biopotential electrodes using the localization signal processor.

In various embodiments, the method further comprises for each electrode, coupling an IQ demodulator to the output of the ADC and separating a magnitude and a phase of a received biopotential signals; coupling a narrow band IIR filter to the IQ demodulator; and coupling a time filter to the IIR filter, and selectively filtering out portions of data on a time basis.

In various embodiments, there is one IIR filter, comprising an I portion and a Q portion, for each IQ demodulator.

In various embodiments, there is one multichannel IIR filter for a plurality of IQ demodulators.

In various embodiments, the method further comprises delivering one or more auxiliary catheters to the body cavity.

In various embodiments, the one or more auxiliary catheters comprises at least one of an ablation catheter or a reference catheter.

In various embodiments, the at least one catheter further includes ultrasound electrodes, and the method includes collecting image data from the ultrasound electrodes to generate an image of the tissue.

In various embodiments, the method further comprises receiving ultrasound signals from the ultrasound electrodes via an ultrasound signal path having a high impedance input.

In accordance with aspects of the inventive concept, provided is a localization method as shown and/or described.

In accordance with aspects of the inventive concept, provided is a localization system as shown and/or described.

In accordance with aspects of the inventive concept, provided is a cardiac information processing system as shown and/or described.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 provides a block diagram of an embodiment of a cardiac information processing system, in accordance with aspects of the inventive concept.

FIG. 2 provides a circuit diagram of an embodiment of the localization driving circuitry and UI system of FIG. 1.

FIG. 3 is a drawing providing a front view and a back view of a patient and relative electrode placement, in accordance with aspects of the inventive concept.

FIG. 4 provides a block diagram of another embodiment of a cardiac information processing system, in accordance with aspects of the inventive concept.

FIG. 5 provides a block diagram of an embodiment of functional elements that cooperate to perform localization signal processing, in accordance with aspects of the inventive concept.

FIG. 6 is a block diagram of an embodiment of functional elements that cooperate to perform localization signal processing, as one implementation of the approach of FIG. 5, in accordance with aspects of the inventive concept.

FIG. 7 is a block diagram of an embodiment of functional elements that cooperate to perform localization signal processing, as another implementation of the approach of FIG. 5, in accordance with aspects of the inventive concept.

FIG. 8 is an embodiment of a localization method, in accordance with aspects of the inventive concepts.

FIG. 9 is a schematic diagram of an ablation catheter, in accordance with aspects of the inventive concept.

FIG. 10 is a schematic diagram of an ultrasound high input impedance switch, in accordance with aspects of the inventive concept.

DETAILED DESCRIPTION

Various exemplary embodiments will be described more fully hereinafter with reference to the accompanying draw-

ings, in which some exemplary embodiments are shown. The present inventive concept can, however, be embodied in many different forms and should not be construed as limited to the exemplary embodiments set forth herein.

It will be understood that, although the terms first, second, etc. are used herein to describe various elements, these elements should not be limited by these terms. These terms are used to distinguish one element from another, but not to imply a required sequence of elements. For example, a first element can be termed a second element, and, similarly, a second element can be termed a first element, without departing from the scope of the present invention. As used herein, the term “and/or” includes any and all combinations of one or more of the associated listed items. And a “combination” of associated listed items need not include all of the items listed, but can include all of the items listed.

It will be understood that when an element is referred to as being “on” or “attached”, “connected” or “coupled” to another element, it can be directly on or connected or coupled to the other element or intervening elements can be present. In contrast, when an element is referred to as being “directly on” or “directly connected” or “directly coupled” to another element, there are no intervening elements present. Other words used to describe the relationship between elements should be interpreted in a like fashion (e.g., “between” versus “directly between,” “adjacent” versus “directly adjacent,” etc.).

The terminology used herein is for the purpose of describing particular embodiments only and is not intended to be limiting of the invention. As used herein, the singular forms “a,” “an” and “the” are intended to include the plural forms as well, unless the context clearly indicates otherwise. It will be further understood that the terms “comprises,” “comprising,” “includes” and/or “including,” when used herein, specify the presence of stated features, steps, operations, elements, and/or components, but do not preclude the presence or addition of one or more other features, steps, operations, elements, components, and/or groups thereof.

Spatially relative terms, such as “beneath,” “below,” “lower,” “above,” “upper” and the like can be used to describe an element and/or feature’s relationship to another element(s) and/or feature(s) as, for example, illustrated in the figures. It will be understood that the spatially relative terms are intended to encompass different orientations of the device in use and/or operation in addition to the orientation depicted in the figures. For example, if the device in the figures is turned over, elements described as “below” and/or “beneath” other elements or features would then be oriented “above” the other elements or features. The device can be otherwise oriented (e.g., rotated 90 degrees or at other orientations) and the spatially relative descriptors used herein interpreted accordingly.

Various exemplary embodiments are described herein with reference illustrations of idealized or representative structures and intermediate structures. As such, variations from the shapes of the illustrations as a result, for example, of manufacturing techniques and/or tolerances, are to be expected. Thus, exemplary embodiments should not be construed as limited to the particular shapes of regions illustrated herein but are to include deviations in shapes that result, for example, from manufacturing.

To the extent that functional features, operations, and/or steps are described herein, or otherwise understood to be included within various embodiments of the inventive concept, such functional features, operations, and/or steps can be embodied in functional blocks, units, modules, operations and/or methods. And to the extent that such functional

blocks, units, modules, operations and/or methods include computer program code, such computer program code can be stored in a computer readable medium, e.g., such as non-transitory memory and media, that is executable by at least one computer processor.

Referring now to FIG. 1, provided is a block diagram of an embodiment of a cardiac information processing system 100, in accordance with aspects of the inventive concept. The cardiac information processing system 100 can be or include a system configured to perform cardiac mapping, diagnosis, and/or treatment, such as for treating abnormalities such as arrhythmia. Additionally or alternatively, the system can be a system configured for teaching and or validating devices and methods of diagnosing and/or treating cardiac abnormalities or disease of a patient P.

The cardiac information processing system 100 includes a catheter 10, a cardiac information console 20, and a patient interface module 50 that can be configured to cooperate to accomplish the various functions of the cardiac information processing system 100. Preferably, cardiac information processing system 100 includes a single power supply (PWR), which can be shared by the cardiac information console 20 and the patient interface module 50. Unlike typical systems, use of a single power supply in this way can greatly reduce the chance for leakage currents to propagate into the patient interface module 50 and cause errors in localization.

The catheter 10 includes an electrode array 12 that can be percutaneously delivered to a heart chamber (HC). The array of electrodes has a known spatial configuration. For example, in the expanded state the physical relationship of the electrodes can be known or reliably assumed. Diagnostic catheter 10 also includes a handle 14, and an elongate flexible shaft 16 extending from handle 14. Attached to the distal end of shaft 16 is the electrode array 12, such as a 3D array in the form of a radially expandable and/or compactible assembly. In this embodiment, the electrode array 12 is shown as a basket array, but the electrode array could take other forms in other embodiments. In some embodiments, expandable electrode array 12 is constructed and arranged as described in reference to applicant's co-pending Patent Cooperation Treaty Patent Application Serial Number PCT/US2013/057579, titled "System and Method for Diagnosing and Treating Heart Tissue", filed Aug. 30, 2013, the content of which is incorporated herein by reference by its entirety. In other embodiments, expandable electrode array 12, as a 3D array, can comprise a balloon, radially deployable arms, spiral, and/or other expandable and compactible structure.

Shaft 16 and expandable electrode array 12 are constructed and arranged to be inserted into a body (e.g. an animal body or a human body, such as the body of Patient P), and advanced through a body vessel, such as a femoral vein or other blood vessel. Shaft 16 and electrode array 12 can be constructed and arranged to be inserted through an introducer (not shown), such as when electrode array 12 is in a compacted state, and slidably advanced through a lumen of a shaft into a body space, such as a chamber of the heart (HC), such as the right atrium or the left atrium, as examples.

Expandable electrode array 12 can further comprise multiple splines, each spline having a plurality of electrodes 12a. Three splines are visible in FIG. 1, but the basket array is not limited to three splines; more or less splines can be included in the basket array. Each electrode 12a can be configured to record a voltage, such as the voltage present on a surface of the heart or at a location within a heart chamber HC. As a non-limiting example, the three electrodes 12a are

shown on each spline in this embodiment. However, in other embodiments the basket array can include more or less electrodes.

Catheter 10 can comprise a cable or other conduit, such as cable 18, configured to electrically, optically, and/or electro-optically connect catheter 10 to the cardiac information console 20 via connectors 18a and 20a, respectively.

The patient interface module 50 can be configured to electrically isolate one or more components of the cardiac information console 20 from patient P (e.g., to prevent undesired delivery of a shock or other undesired electrical energy to patient P). The patient interface module 50 can be integral with cardiac information console 20 and/or it can comprise a separate discrete component (e.g. separate housing), as is shown. The cardiac information console 20 comprises one or more connectors 20b, each comprising a jack, plug, terminal, port, or other custom or standard electrical, optical, or electro-optical connector. Similarly, the patient interface module 50 includes one or more connectors 50b. At least one cable 52 connects the patient interface module 50 with the cardiac information console 20, via connectors 20b and 50b.

The patient interface module 50 includes a patient isolation drive system 54 and a set of localization electrodes. In this embodiment, the set of localization electrodes includes a set of patch electrodes 56 and one or more reference electrode 58. The isolation drive system 54 isolates localization signals from the rest of system to prevent current leakage, e.g., signal loss—resulting in performance degradation. The isolation drive system 54 can minimize drift in localization positions and maintain a high isolation between axes. Additionally, the isolation drive system 54 maintains simultaneous output on all axes, while also increasing the sampling rate at each electrode position. In some embodiments, the sampling rate comprises a rate between 10 kHz and 1 MHz, such as a sampling rate of approximately 625 kHz.

In this embodiment, the set of patch electrodes 56 include three (3) pairs of patch electrodes: an "X" pair having two patch electrodes placed on opposite sides of the ribs (X1, X2); a pair having one patch electrode placed on the lower back (Z1) and one patch electrode placed on the upper chest (Z2); and a "Y" pair having one patch electrode placed on the upper back (Y1) and one patch electrode placed on the lower abdomen (Y2). The patch electrode 56 pairs can be placed on any orthogonal and/or non-orthogonal sets of axes. In the embodiment of FIG. 1, the placement of electrodes is shown on patient P, where electrodes on the back are shown in dashed lines.

The placement of electrodes 56 defines a coordinate system made up of three axes, one axis per pair of patch electrodes 56. In some embodiments, the axes are non-orthogonal to a natural axis of the body: head-to-toe, chest-to-back, and side-to-side (i.e., rib-to-rib). The electrodes can be placed such that the axes intersect at an origin, such as an origin located in the heart. For instance, the origin of the three intersecting axes can be centered in an atrial volume. System 100 can be configured to provide an "electrical zero" that is positioned outside of the heart, such as by locating a reference electrode 58 such that the resultant electrical zero is outside of the heart (e.g. to avoid crossing from a positive voltage to a negative voltage at a location being localized).

Through processing by the cardiac information console 20, the axes can be rotated from the normal physiological orientation, i.e., anterior-posterior, cranial-caudal, left-right. Rotated axes provide improved spatial resolution. Once the desired rotation is achieved, each axis can be scaled, i.e.,

made longer or shorter, as needed. The rotation and scaling are performed based on comparing expected or known electrode array **12** shape and relative dimensions with a representation of the electrode array in the patch electrode established coordinate system. In such a case, rotation and scaling is performed to bring an incorrect representation into a more accurate representation. Therefore, shaping and scaling the representation of the electrode array **12** serves to adjust and correct the orientation and relative sizes of the axes for far more accurate localization.

The reference electrode(s) **58** can be or include a patch electrode and/or an electrical reference catheter, as a patient reference. A patch electrode can be placed on the skin, and will act as a return for current for defibrillation. An electrical reference catheter can include a unipolar reference electrode used in baseline and restore functions, and can be used for common mode rejection. Another form of electrical reference catheter can be an internal analog reference electrode, which can act as a low noise “analog ground” for all internal catheter electrodes. Each of these types of reference electrodes can be placed in relatively similar locations, such as near lower back in internal vessel (as a catheter) and/or on lower back (as a patch). In some embodiments, system **100** comprises a reference catheter **58** including a fixation mechanism (e.g. a user activated fixation mechanism), which can be constructed and arranged to reduce displacement (e.g. accidental or otherwise unintended movement) of one or more electrodes of the reference catheter **58**. The fixation mechanism can comprise a mechanism selected from the group consisting of: spiral expander; spherical expander; circumferential expander; axially actuated expander; rotationally actuated expander; and combinations of two or more of these.

In FIG. 1, aspects of the receiver components of the cardiac information console **20** are depicted. The cardiac information console **20** includes an input defibrillation protection module **22** connected to connector **20a**, which is configured to receive cardiac information from the catheter **10**. The DFIB protection module **22** is configured to have a precise clamping voltage and a minimum capacitance. Functionally, the DFIB protection module **22** acts a surge protector.

The DFIB protection module **22** is coupled to two signal paths, a biopotential (BIO) signal path **30** and a localization (LOC) signal path **40**. Generally, the BIO path **30** filters noise and preserves the measured biopotential data, and also enables the biopotential signals to be read while ablating, which is not the case in other systems. Generally, the LOC path **40** allows high voltage inputs, while filtering noise from received localization data.

The BIO signal path **30** includes an RF filter **31** coupled to the DFIB protection module **22**. In this embodiment, the RF filter **31** operates as a low-pass filter having a high input impedance. The high input impedance is preferred in this embodiment because it minimizes the loss of voltage from the source, e.g., catheter **10**, thereby better preserving the received signals. The RF filter **31** is configured to allow biopotential signals from the electrodes **12a** on catheter **10** to pass, e.g., frequencies less than 500 Hz, such as frequencies in the range of 0.1 Hz to 500 Hz. However, high voltages, such as from ablation, are filtered out from the biopotential signal path **30**. RF filter **31** can comprise a bandwidth between 10 kHz and 12 kHz.

A BIO amplifier **32** is preferably a low noise single-ended input amplifier that amplifies the RF filtered signal. A BIO filter **33** filters noise out of the amplified signal. BIO filter **33** can comprise an approximately 3 kHz filter. In some

embodiments, BIO filter **33** comprises an approximately 7.5 kHz filter, such as when system **100** is configured to accommodate pacing of the heart (e.g. avoid significant signal loss and/or degradation during pacing of the heart).

The LOC signal path **40** includes a high voltage buffer **41** coupled to the DFIB protection module **22**. In this embodiment, the high voltage buffer **41** is configured to accommodate the relatively high RF voltages used in treatment techniques, such as RF ablation. For example, the high voltage buffer can have ± 100 voltage rails. The high voltage buffer **41** also has a high input impedance, such as when the high voltage buffer **41** does not include a pre-filter stage, and has good performance at high frequencies. A high frequency bandpass filter **42** is coupled to the high voltage buffer **41**, and has a passband frequency range of about 20 kHz to 80 kHz for use in localization. Preferably, the filter **42** has low noise with good gain, e.g., a gain of 1.

An AD (analog-to-digital) converter ADC **24** is coupled to the BIO filter **33** of the BIO signal path **30** and to the high frequency filter **42** of the LOC signal path **40**. The ADC **24** has high oversampling to allow noise shaping and filtering, e.g., with an oversampling rate of about 625 kHz. In some embodiments, sampling is performed at or above the Nyquist frequency of system **100**. The ADC **24** is a multi-channel circuit that can combine BIO and LOC signals or keep them separate. In one embodiment, as a multi-channel circuit, the ADC **24** can be configured to accommodate 48 biopotential electrodes **12a** and 32 auxiliary electrodes (e.g., for ablation or other processes), for a total of 80 channels. In other embodiments, more or less channels can be provided. In FIG. 1, for example, almost all of the elements of the cardiac information console **20** can be duplicated for each channel, e.g., except for the UI system **27**. For example, the cardiac information console **20** can include a separate ADC for each channel, or an 80 channel ADC.

Consistent with the two different signals and signal paths **30**, **40**, signal information from each path is input to and output from the various channels of the ADC **24**. Outputs from the channels of the ADC **24** are coupled to either the BIO signal processing module **34** or the LOC signal processing module **44**, which pre-process their respective signals for subsequent processing as described herein below. In each case, the preprocessing prepares the received signals for the processing by their respective dedicated processors discussed below. The BIO signal processing module **34** and the LOC signal processing module **44** can be implemented in firmware, in whole or in part, in some embodiments.

The biopotential signal processing module **34** can provide gain and offset adjustment and digital RF filtering having a non-dispersive low pass filter and intermediate frequency band. The intermediate frequency band can eliminate ablation and localization signals. Additionally, the biopotential signal processing can also include pace blanking, which is the blanking of received information during a timeframe when, for example, a physician is “pacing” the heart. Cardiac pacing is applied clinically by standard means. The pacing may be used to temporarily alter the heart rhythm, trigger the heart beat from specific locations on the cardiac wall, or for checking the health of the cardiac tissue by looking at propagation velocities of the pacing pulses.

To accomplish the foregoing, active and passive pacing trigger and input algorithmic trigger determination can be performed. The algorithmic trigger determination can use subsets of channels, edge detection and/or pulse width detection to determine if pacing has occurred. The biopotential signal processing module **34** can also include digital

biopotential filtering, which can be a non-dispersive low pass filter with an optimized output sample rate.

The localization signal processing module **44** can provide individual channel/frequency gain calibration, IQ demodulation with tuned demodulation phase, synchronous and continuous demodulation (no MUXing), narrow band IIR filtering, and time filtering (Interleaving, blanking, etc.), as discussed herein below.

A data processor **26**, which may include one or more of a plurality of types of processing circuits (e.g., a microprocessor) and memories, executes computer instructions necessary to perform the processing of the pre-processed signals from the BIO signal processing module **34** and localization signal processing module **44**. The data processor **26** can be configured to perform calculations, as well as perform data storage and retrieval, necessary to perform the functions of the cardiac information processing system **100**.

In this embodiment, data processor **26** includes a biopotential (Bio) processor **36** and a localization (LOC) processor **46**. The biopotential processor **36** can perform processing of measured biopotentials. The LOC processor **46** can perform processing of localization signals.

The biopotential processor **36** can be configured to perform various calculations. For example, the BIO processor **36** can include an enhanced common mode rejection filter, which can be bidirectional to minimize distortion and which may be seeded with a common mode signal. The BIO processor **36** can also include an optimized ultrasound rejection filter and be configured for selectable bandwidth filtering.

The localization processor **46** can be configured to perform various calculations. As discussed in more detail below, the LOC processor **46** can electronically make (calculate) corrections to an axis based on the known shape of electrode array **12**, make corrections to scaling of one or more axis based on the known shape of the electrode array **12**, and perform “fitting” to align measured electrode positions with known possible configurations, which can be optimized with one or more constraints (e.g. physical constraints such as distance between two electrodes **12a** on a single spline, distance between two electrodes **12a** on two different splines, maximum distance between two electrodes **12a**; minimum distance between two electrodes **12a**, minimum and/or maximum curvature of a spine).

The cardiac information console **20** also includes localization driving circuitry, including a localization signal generator **28** and a localization drive current monitor circuit **29**. The localization driving circuitry provides high frequency localization drive signals (e.g., 10 kHz-1 MHz, such as 10 kHz-100 kHz). Localization using drive signals at these high frequencies reduces the cellular response effect on the localization data, e.g., from blood cell deformation, and/or allow higher drive currents, e.g., to achieve a better signal-to-noise ratio. The signal generator **28** produces a high resolution digital synthesis of a drive signal, e.g., sine wave, with ultra-low phase noise timing. The drive current monitoring circuitry provides a high voltage, wide bandwidth current source, which is monitored to measure impedance of the patient P.

The cardiac information console **20** can also include a user interface (UI) subsystem **27** configured to output results of the localization and biopotential processing. The UI subsystem **27** can include at least one display **27a** to graphically render such results in 2D, 3D, or a combination thereof. The user interface system **27** can include one or more mechanisms that enable a user to rotate and/or scale the coordinate system to graphically adjust and correct an

image of the 3D array of biopotentials. Such mechanisms can include a touchscreen, mouse, keyboard, light pen, track ball, microphone, and so on.

In some embodiments, system **10** comprises one or more sensors, each configured to produce a signal, a sensor of catheter **10** (e.g. sensor **14a** of handle **14** or sensor **12c** of array **12**), a sensor **20b** of cardiac information console **20** and/or a sensor **50a** of patient interface module **50**, each as shown in FIG. **1**. In some embodiments, system **10** comprises two or more of sensors **12c**, **14a**, **20b**, and/or **50a**. In some embodiments, sensors **12c**, **14a**, **20b**, and/or **50a** comprise a sensor selected from the group consisting of: a force sensor; a pressure sensor; a strain gauge; an optical sensor; an imaging sensor (e.g. a lens or optical fiber); a sound sensor such as an ultrasound sensor; a hall effect sensor; a pH sensor; a magnetic sensor; a temperature sensor; and combinations of one or more of these. In some embodiments, sensor **12c** comprise a patient physiologic sensor, such as a sensor selected from the group consisting of: a blood pressure sensor; a blood gas sensor; a temperature sensor; a blood glucose sensor; a pH sensor; a respiration sensor; an average clotting time (ACT) sensor; and combinations of one or more of these. In some embodiments, system **10** is configured to analyze a signal produced by one, two or more of sensors **12c**, **14a**, **20b**, and/or **50a**. In some embodiments, system **10** (e.g. cardiac information console **20**) is configured to perform an analysis of one or more signals produced by one, two or more of sensors **12c**, **14a**, **20b**, and/or **50a** in combination with voltage data, dipole density data, surface charge data, and/or anatomical data (e.g. anatomical data collected by one or more ultrasound transducers **133**). In some embodiments, signals from one or more sensors **12c**, **14a**, **20b**, and/or **50a** are used by system **10** to perform a function selected from the group consisting of: improve an anatomical image displayed by system **10**; improve cardiac information displayed by system **10** (e.g. dipole density and/or surface charge information); detect a malfunction of system **10**; provide physiologic data of a patient; and combinations of one or more of these. In some embodiments, one or more of sensors **12c**, **14a**, **20b**, and/or **50a** can comprise a transducer (e.g. as an alternative to being a sensor or in addition to being a sensor), such as a transducer selected from the group consisting of: a heating element; a cooling element; a vibrating element; a drug or other agent delivery element; a magnetic field generating element; a light delivery element; an imaging element (such as a lens, and/or optical fiber); and combinations of one or more of these.

FIG. **2** provides a circuit diagram of an embodiment of the localization driving circuitry and UI system of FIG. **1**. FIG. **2** shows portions of the UI subsystem **27**, the localization signal generator **28**, and the localization drive current monitor circuit **29** of FIG. **1**.

The localization signal generator **28** is a DDS (Direct Digital Synthesizer) that generates waveforms for localization, such as sine waves. One waveform is generated per “axis,” currently a 3 axes system. High frequency sine waves are generated for each axis, such as 3 sine waves at different frequencies. For example, the signals generated for the X pair of electrodes can be at 39 kHz; the signals generated for the Y pair of electrodes can be at 48 kHz; and the signals generated for the Z pair of electrodes can be at 52 kHz.

The drive current monitoring circuitry **29** provides a feedback system for monitoring and maintaining current delivered by the localization system to the patient P, using the ADC as an output. The drive current monitoring circuitry

29 can monitor current output and determine physical parameters of the system, such as impedance of the body, issues with patch placement, changes in physical parameters, and/or hardware error and/or failure.

In this embodiment, the cardiac information console 20 and patient interface module 50 share a common ground, through use of a single power source. As shown, the patient interface module 50 provides localization driver isolation using a transformer. This provides better isolation, while driving different pairs of electrodes, e.g., currently 3 pairs of electrodes are simultaneously driven with 3 different frequencies.

In FIG. 2, the impedance between two electrodes in a pair of electrodes is indicated by "Z" (the customary symbol for impedance).

FIG. 3 is a drawing providing a front view and a back view of a patient and relative electrode placement, in accordance with aspects of the inventive concept. This figure demonstrates a preferred patch electrode placement, as discussed above. In FIG. 1, for example, the X electrodes X1 and X2 are shown as patch electrodes 1 and 2, respectively; the Z electrodes Z1 and Z2 are shown as patch electrodes 3 and 4, respectively; and the Y electrodes Y1 and Y2 are shown as patch electrodes 5 and 6, respectively. Thus, patches 1 and 2 are placed on the ribs, forming X axis within the body; patches 3 and 4 are placed on the lower back and upper chest (respectively), forming the Z axis; and patches 5 and 6 are placed on the upper back and lower abdomen (torso) (respectively), forming the Y Axis. The three axis are of similar length, and not aligned with "natural" axis of the body (i.e., head to toe, chest to back, and side to side).

The reference patch electrode 58 can be placed on the lower back/buttocks. Additionally, or alternatively, a reference catheter can be placed in similar location within a body vessel.

As described hereabove, a patch pair can operate differentially, i.e. neither patch 56 in a pair operates as a reference electrode, and are both driven by system 100 to generate the electrical field between the two. Alternatively or additionally, one or more of the patch electrodes 56 can serve as the reference electrode 58, such that they operate in a single ended mode. One of any pair of patch electrodes 56 can serve as the reference electrode 58 for that patch pair, forming a single-ended patch pair. One or more patch pairs can be configured to be independently single-ended. One or more of the patch pairs can share a patch as a single-ended reference or can have the reference patches of more than one patch pair electrically connected.

Through processing performed by the cardiac information console 20, the axes can be transformed, e.g., rotated, from a first orientation, e.g., a non-physiological orientation based on the placement of electrodes 56, to a second orientation. The second orientation can comprise a standard Left-Posterior-Superior (LPS) anatomical orientation, i.e., the "x" axis is oriented from right to left of the patient, the "y" axis is oriented from the anterior to posterior of the patient, and the "z" axis is oriented from cauda to cranial of the patient. Placement of patch electrodes 56 and the non-standard axes defined thereby can be selected to provide improved spatial resolution when compared to patch electrode placement resulting in a normal physiological orientation of the resulting axes, e.g. due to preferred tissue characteristics between electrodes 56 in the non-standard orientation. For example, non-standard electrode placement can result in diminished influence of the low-impedance volume of the lungs on the localization field. Furthermore, electrode placement can be selected to create axes which pass through the body of the

patient along paths of similar or equivalent lengths. Axes of similar length will possess more similar energy density per unit distance within the body, yielding a more uniform spatial resolution along such axes. Transforming the non-standard axes into a standard orientation can provide a more straightforward display environment for the user. Once the desired rotation is achieved, each axis can be scaled, i.e., made longer or shorter, as needed. The rotation and scaling are performed based on comparing pre-determined, e.g., expected or known, electrode array 12 shape and relative dimensions, with measured values that correspond to the shape and relative dimensions of the electrode array in the patch electrode established coordinate system. For example, rotation and scaling can be performed to transform a relatively inaccurate, e.g., uncalibrated, representation into a more accurate representation. Shaping and scaling the representation of the electrode array 12 can adjust, align, and/or otherwise improve the orientation and relative sizes of the axes for far more accurate localization.

The reference electrode(s) 58 can be or include a patch electrode and/or an electrical reference catheter, as a patient reference. A patch electrode 58 can be placed on the skin, and will act as a return for current for defibrillation. An electrical reference catheter can include a unipolar reference electrode used to enhance common mode rejection. The unipolar reference electrode, or other electrodes on a reference catheter, can be used to measure, track, correct, or calibrate physiological, mechanical, electrical, or computational artifacts in a cardiac signal. In some embodiments, these artifacts may be due to respiration, cardiac motion, or artifacts induced by applied signal processing, such as filters. Another form of electrical reference catheter can be an internal analog reference electrode, which can act as a low noise "analog ground" for all internal catheter electrodes. Each of these types of reference electrodes can be placed in relatively similar locations, such as near the lower back in an internal vessel (as a catheter) and/or on the lower back (as a patch). In some embodiments, system 100 comprises a reference catheter 58 including a fixation mechanism (e.g. a user activated fixation mechanism), which can be constructed and arranged to reduce displacement (e.g. accidental or otherwise unintended movement) of one or more electrodes of the reference catheter 58. The fixation mechanism can comprise a mechanism selected from the group consisting of: spiral expander; spherical expander; circumferential expander; axially actuated expander; rotationally actuated expander; and combinations of two or more of these.

Referring now to FIG. 4, provided is a block diagram of an embodiment of a cardiac information processing system 400, in accordance with aspects of the inventive concept. The system 400 in FIG. 4 is similar to that of the system 100 in FIG. 1, except in FIG. 4 the catheter includes ultrasound transducers 12b, here located in the splines of the basket electrode array 12 with the electrodes 12a. In this embodiment, a single electrode 12a (e.g., for localization) is paired with an ultrasound transducer 12b (e.g., for anatomical representation). In one embodiment, there are 48 of such pairs on the electrode array 12. In other embodiments, the system can also localize electrodes not paired with transducers, such as with an AUX catheter and/or a catheter with only electrodes on an array. The catheter 10 also connects to cardiac information console 20 as described in FIG. 1.

With respect to the multiple "pairs" of electrical components, for example, at least one pair comprises an electrode 12a and an ultrasound transducer 12b. Each electrode 12a can be configured to record a voltage (or biopotential), such

as the voltage present on a surface of the heart or at a location within a heart chamber HC. Each ultrasound transducer **12b** can be configured to send and/or receive ultrasound signals, such as to produce an anatomical image of the tissue of at least a portion of the heart or other patient anatomical location. When such information is accumulated for multiple pairs **12a**, **12b** over time, an anatomical image of the heart with a superimposed mapping of cardiac activity can be produced for display via US subsystem **27**.

In this embodiment, the cardiac information console **20** includes the same biopotential signal path **30** and localization signal path **40** described above with respect to FIG. **1**, as well as DFIB protection module **22** and ADC **24**. The BIO signal processing module **34** or the LOC signal processing module **44** are also included within cardiac information console **20**, as well as UI subsystem **27**. The power supply PWR and processor **26** can also be included, including BIO processor **36** and LOC processor **44**.

Unlike FIG. **1**, an ultrasound (US) signal path **60** is provided, which includes a US isolation MUX **61**, US transformer **62**, and US generation and detection module **63**. The US isolation MUX **61** is connected to the DFIB protection module **22**, and is used for turning on/off the US transducers **12b**, such as in a predetermined order or pattern. The US isolation MUX **61** can be a set of high input impedance switches that, when open, isolate the US system and remaining US signal path elements, decoupling the impedance to ground (through the transducers and the US signal path **60**) from the input of the LOC and BIO paths. The US isolation MUX **61** also multiplexes one transmit/receive circuit to one or more multiple transducers **12b** on the catheter **10**. The US transformer **62** operates in both directions between the US isolation MUX **61** and the US generation and detection module **63**. US transformer **62** isolates the patient from the current generated by the US transmit and receive circuitry in module **63** during ultrasound transmission and receiving by the US transducers **12b**. The switches of US transformer **62** selectively engage the transmit and/or receive electronics of module **63** based on the mode of operation of the transducers **12b**, such as to activate one or more of the associated transducers **12b**, such as in a predetermined order or pattern. That is, in a transmit mode, the module **63** receives a control signal from an US processor (within a data processor **26**) that activates the US signal generation and connects an output of the transmit amplifier to US transformer **62**. The US transformer **62** couples the signal to the US isolation MUX **61** which selectively activates the US transducers **12b**. In a receive mode, the US isolation MUX **61** receives reflection signals from one or more of the transducers **12b**, which are passed to the US transformer **62**. The US transformer **62** couples signals into the receive electronics of the US generation and detection module **63**, which in-turn transfers reflection data signals to the US processor for processing and use by the user interface system **27** and display **27a**.

In this embodiment, the ADCs and the signal processing are all contained in the cardiac information console **20** for BIO, LOC, and ultrasound. Output to the ADC(s) is a sequence of individual biopotential voltage points for each electrode. As discussed below, these have been filtered and CMRR improved and normalized on a channel-by-channel basis with each channel handled independently. Output to the ADC is also a sequence of localization voltage points for each axis of each patch electrode. And output to the ADC **24** is also a collection of 48 (in this embodiment) reflection distances measured at a single time for ultrasound.

The algorithmic computations are done in the cardiac information console **20**, including: process 48 or 80 channels at one time; measure propagation delays between signals; turn x, y, z data into a spatial distribution of location of electrodes; compute and apply corrections to the collection of positions; and/or turn individual distances into a point cloud and manipulate the point cloud.

FIG. **5** is a block diagram of an embodiment of functional elements that cooperate to perform localization signal processing, in accordance with aspects of the inventive concept. An IQ demodulator **502** receives outputs from an ADC **24**, and analyzes the magnitude and phase of the received signal. In this embodiment, using IQ demodulation provides for maximum noise rejection. Narrowband filter **504** minimizes interference and a time filter **506** prevents intermodulation with ultrasound pulses by enabling selective filtering of signals from any time period. As examples, the time filter **506** can be used for blanking and interleaving signals, e.g., mapping signals, localization signals, and/or ultrasound imaging signals.

A data processor **508** can be configured to perform the computational algorithms applied to global data sets used in localization signal processing.

FIG. **6** is a block diagram of an embodiment of functional elements that cooperate to perform localization signal processing, as another implementation of the approach of FIG. **5**, in accordance with aspects of the inventive concept.

The embodiment of FIG. **6** shows simultaneous demodulation of multiple frequencies, in a parallel arrangement formed between the ADC **24** and the time filter **506**. This embodiment produces highest throughput for localization and allows oversampling to reduce noise. There is an IQ demodulator **502a**, **502b**, **502c**, for each channel coming from the ADC **24**. As is shown, there is independent IIR filtering of I and Q components. This approach gives the highest possible signal integrity, with the narrowest band pass possible and the shortest real time delay. The time filter **506** prevents intermodulation with ultrasound pulses.

This approach provides a total synchronous processing chain and allows easy time/state dependent filters.

FIG. **7** is a block diagram of an embodiment of functional elements that cooperate to perform localization signal processing, as another implementation of the approach of FIG. **5**, in accordance with aspects of the inventive concept.

The embodiment of FIG. **7** is similar to that of FIG. **6**, except there is not a dedicated IIR filter for each I and Q. Instead, there is a time multiplexing of IQ components, using switches, from the IQ demodulators into a multi-channel IIR filter **504**. The multi-channel IIR filter **504** includes a sufficient number of channels to accommodate all Is and Qs. In other embodiments, the number of IIR filters **504** can be more than 1 and less than the number of Is and Qs.

This approach reduces computational resources with no additional time delay.

FIG. **8** is an embodiment of a localization method, in accordance with aspects of the inventive concepts. The method **800** of FIG. **8** can be implemented by the various systems described herein.

In step **802**, processed I and Q data is received from the signal processing module. In step **804**, the IQ data is converted into voltage data. In some embodiments, the voltage data is filtered for abnormal signals and/or outlier data and this data can be excluded from further calculations. In step **806**, an axis correction factor is determined and applied, which can be based on a known or measured shape of the electrode array, such as the 48 electrode array **12**.

There is one axis for each pair of localization electrodes, e.g., reference electrodes **56**. For instance, if the shape of the basket is incorrect, one or more axis can be rotated, scaled, and/or deskewed until the basket takes the proper shape, which could be visible on a display of the UI subsystem **27** and manipulatable user mechanisms of the user interface module **27**. In step **808**, a scaling matrix is determined and applied to the voltage values, again based on the known or measured shape of the electrode array. Here, if the length or size of the array is incorrect, based on the known or determined proportions of the electrode array, one or more of the axes can be scaled (longer or shorter) until the proper size is achieved.

In step **810**, position values of the electrodes in the electrode array (e.g., electrode array **12**) can be determined, and will have voltage values that are corrected based on steps **806** and **808**. In step **812**, a fitting algorithm can be performed to fit the calculated electrode positions to the known basket configuration. Additionally, in step **814**, additional fitting and rotations can be applied to the calculated electrode positions and the electrode positions on the electrode array can be updated. This fitting step is more precise than the first fitting step, so provides better localization accuracy. In step **816**, a next data set is loaded and the method returns to step **804** for further processing.

FIG. **9** is a schematic diagram of an embodiment of an ablation system and an ablation catheter, in accordance with aspects of the inventive concept. There is an ablation system **510** coupled to an ablation catheter **512**. An ablation tip **514** is located on a distal end of the ablation catheter **512**. The ablation tip **514** delivers ablation energy to the tissue, e.g., RF ablation energy.

In this embodiment, there is no alteration to the “power path”, e.g., no filtering of the power path, so no impedances are added to the chain and no ablation power is wasted in filters. There are filters **520** connected to non-ablation electrodes, e.g., electrodes used as part of a localization system. A high input impedance is maintained for the localization system, which allows localization during delivery of ablation energy. Additionally, in this embodiment, less ablation noise or artifact is coupled into the BIO and/or LOC signals than in the alternate configuration of a filter in the return path between the ablation system **510** and the ground patch **516**.

FIG. **10** is a schematic diagram of an embodiment of ultrasound circuitry including an ultrasound high input impedance MUX **61**, in accordance with aspects of the inventive concept. The ultrasound high input impedance switch includes ultrasound isolation switches **1010** (single switch shown). Ultrasound isolation switch **1010** connects in front of defibrillation (DFIB) protection module **22** discussed above, and has a separate DFIB protection circuit **1020** which connects to a port to which the localization, mapping, and auxiliary catheters (e.g., an ablation catheter) are connected (See, e.g., connector **20a** FIG. **1**).

This approach provides isolation of ultrasound from BIO and LOC signals. It is a minimum capacitance implementation, in which high voltage bias reduces capacitance and a symmetric switch minimizes charge injection. The high voltage also shortens the time for which the switch reaches an “on” state, and minimizes time of distortion for biopotential and localization signals. In one embodiment, OptoFETs isolate the control electronics from DFIB protection circuit **1020**.

While the foregoing has described what are considered to be the best mode and/or other preferred embodiments, it is understood that various modifications can be made therein and that the invention or inventions may be implemented in

various forms and embodiments, and that they may be applied in numerous applications, only some of which have been described herein. It is intended by the following claims to claim that which is literally described and all equivalents thereto, including all modifications and variations that fall within the scope of each claim.

We claim:

1. A localization system, comprising:

at least one catheter configured for delivery of one or more biopotential electrodes to a body cavity defined by surrounding tissue;

a patient interface module comprising a plurality of localization electrodes configured for fixed orientation relative to the body, wherein the body cavity is a heart chamber and the surrounding tissue is one or more walls of the heart chamber; and

a cardiac information console configured to process both the magnitude and phase of localization signals from the localization electrodes to establish a manipulatable coordinate system for the tissue based on both the magnitude and phase of the localization signals, and to process biopotential signals to orient the biopotential electrodes within the coordinate system.

2. A localization system, comprising:

at least one catheter configured for delivery of one or more biopotential electrodes to a body cavity defined by surrounding tissue, wherein the biopotential electrodes are disposed on a 3D array;

a patient interface module comprising a plurality of localization electrodes configured for fixed orientation relative to the body; and

a cardiac information console configured to process both the magnitude and phase of localization signals from the localization electrodes to establish a manipulatable coordinate system for the tissue based on both the magnitude and phase of the localization signals, and to process biopotential signals to orient the biopotential electrodes within the coordinate system.

3. The localization system of claim 2, wherein the 3D array includes a plurality of splines.

4. The localization system of claim 2, wherein the 3D array is a basket array, a spiral array, a balloon, radially deployable arms, and/or other expandable and compactible structures.

5. The localization system of claim 2, wherein the cardiac information console is configured to generate an electronic representation of the 3D array of biopotential electrodes from the biopotential signals.

6. The localization system of claim 5, wherein the cardiac information console is further configured to rotate the coordinate system to adjust and correct the electronic representation of the 3D array of biopotential electrodes.

7. The localization system of claim 6, wherein the cardiac information console is further configured to fit the electronic representation of the 3D array of biopotential electrodes to a known or determined geometry of the 3D array of biopotential electrodes.

8. The localization system of claim 5, further comprising: a user interface system configured to display the electronic representation of the 3D array of biopotential electrodes and the coordinate system.

9. The localization system of claim 8, wherein the user interface system includes a mechanism that enables a user to rotate and/or scale the coordinate system to graphically adjust and correct an image of the electronic representation of the 3D array of biopotential electrodes.

23

10. A localization system, comprising:
 at least one catheter configured for delivery of one or more biopotential electrodes to a body cavity defined by surrounding tissue;
 a patient interface module comprising a plurality of localization electrodes configured for fixed orientation relative to the body, wherein the patient interface module includes a patient isolation drive system, a set of patch electrodes, and one or more reference electrodes; and
 a cardiac information console configured to process both the magnitude and phase of localization signals from the localization electrodes to establish a manipulatable coordinate system for the tissue based on both the magnitude and phase of the localization signals, and to process biopotential signals to orient the biopotential electrodes within the coordinate system.
11. The localization system of claim 10, wherein the localization electrodes include one or more pairs of localization electrodes.
12. The localization system of claim 11, wherein each pair of localization electrodes defines an axis of the coordinate system.
13. The localization system of claim 12, wherein the isolation drive system is configured to maintain simultaneous output on all axes generated by the localization electrode pairs.
14. The localization system of claim 11, wherein the localization electrodes include three pairs of localization electrodes defining axes, each pair of localization electrodes defining one axis of the coordinate system.
15. The localization system of claim 14, wherein:
 a first pair of localization electrodes has two patch electrodes placed on opposite sides of the ribs;
 a second pair of localization electrodes has one patch electrode placed on the lower back and one patch electrode placed on the upper chest; and
 a third pair of localization electrodes has one patch electrode placed on the upper back and one patch electrode placed on the lower abdomen.
16. The localization system of claim 14, wherein the axes are non-orthogonal to a natural axis of the body.
17. The localization system of claim 11, wherein each pair of localization electrodes is driven by a different localization signal.
18. The localization system of claim 17, wherein each localization signal has a different frequency.
19. A localization system, comprising:
 at least one catheter configured for delivery of one or more biopotential electrodes to a body cavity defined by surrounding tissue;
 a patient interface module comprising a plurality of localization electrodes configured for fixed orientation relative to the body; and
 a cardiac information console configured to process both the magnitude and phase of localization signals from the localization electrodes to establish a manipulatable

24

- coordinate system for the tissue based on both the magnitude and phase of the localization signals, and to process biopotential signals to orient the biopotential electrodes within the coordinate system, wherein the cardiac information console comprises, for each electrode:
 a biopotential signal path having a high impedance input and configured to receive biopotential signals from the biopotential electrodes; and/or
 a localization signal path having a high impedance input and configured to receive localization signals from the localization electrodes.
20. The localization system of claim 19, wherein the cardiac information console further comprises, for each electrode:
 a DFIB protection circuit coupled between the biopotential signal path and the localization signal path.
21. The localization system of claim 19, wherein the cardiac information console further comprises:
 an ADC, for each electrode, coupled to outputs of the biopotential signal path and the localization signal path;
 an IQ demodulator, for each electrode, coupled to an output of the ADC;
 a narrow band IIR filter coupled to the IQ demodulator; and
 a time filter coupled to the IIR filter, and configured to selectively filter out portions of data on a time basis.
22. The localization system of claim 21, wherein there is one IIR filter, comprising an I portion and a Q portion, for each IQ demodulator.
23. The localization system of claim 21, wherein there is one multichannel IIR filter for a plurality of IQ demodulators.
24. A localization system, comprising:
 at least one catheter configured for delivery of one or more biopotential electrodes to a body cavity defined by surrounding tissue, wherein the at least one catheter further includes ultrasound electrodes configured to collect image data to generate one or more images of the tissue;
 a patient interface module comprising a plurality of localization electrodes configured for fixed orientation relative to the body; and
 a cardiac information console configured to process both the magnitude and phase of localization signals from the localization electrodes to establish a manipulatable coordinate system for the tissue based on both the magnitude and phase of the localization signals, and to process biopotential signals to orient the biopotential electrodes within the coordinate system.
25. The localization system of claim 24, wherein the cardiac information console further comprises:
 an ultrasound signal path having a high impedance input and configured to receive ultrasound signals from the ultrasound electrodes.

* * * * *

专利名称(译)	定位系统和方法可用于获取和分析心脏信息		
公开(公告)号	US10653318	公开(公告)日	2020-05-19
申请号	US15/569457	申请日	2016-05-13
[标]申请(专利权)人(译)	阿库图森医疗有限公司		
申请(专利权)人(译)	五步蛇MEDICAL , INC.		
当前申请(专利权)人(译)	五步蛇MEDICAL , INC.		
[标]发明人	WELSH DANIEL J JULIAN MARCUS F BEATTY GRAYDON E SHI XINWEI CHOU DERRICK R WERNETH RANDELL L FLAHERTY J CHRISTOPHER		
发明人	WELSH, DANIEL J. JULIAN, MARCUS F. BEATTY, GRAYDON E. SHI, XINWEI CHOU, DERRICK R. WERNETH, RANDELL L. FLAHERTY, J. CHRISTOPHER		
IPC分类号	A61B5/00 A61B8/00 A61B8/12 A61N1/37 A61B8/08 A61B5/04 A61B34/20 A61B5/06 A61B5/042		
CPC分类号	A61B5/0422 A61B5/061 A61N1/3702 A61B5/0035 A61B5/042 A61B5/004 A61B5/6852 A61B5/0044 A61B5/063 A61B2576/023 A61B5/6857 A61B2034/2063 A61B2562/0204 A61B2562/0209 A61B5/6859 A61B34/20 A61B8/12 A61B2034/2065 A61B5/04012 A61B5/6858 A61B2034/2051 A61B5/6853 A61B8/0883 A61B8/4416 G16H30/40		
优先权	62/161213 2015-05-13 US		
其他公开文献	US20180296114A1		
外部链接	Espacenet		

摘要(译)

提供了一种在心脏信息的获取和分析中有用的定位系统和方法。例如，该定位系统和方法可以与执行心脏定位，心脏异常的诊断和治疗的系统一起使用，并且可以在此类信息的检索，处理和解释中使用。定位系统和方法对于用于建立多轴坐标系的成对电极使用高阻抗输入，改善的隔离度和相对较高的驱动电流。轴可以旋转和缩放以改善定位。

