



(11) **EP 1 526 800 B1**

(12) **EUROPEAN PATENT SPECIFICATION**

(45) Date of publication and mention  
of the grant of the patent:  
**10.09.2008 Bulletin 2008/37**

(51) Int Cl.:  
**A61B 1/00** <sup>(2006.01)</sup> **G02B 23/24** <sup>(2006.01)</sup>  
**A61B 5/00** <sup>(2006.01)</sup> **G02B 26/10** <sup>(2006.01)</sup>

(21) Application number: **03771743.6**

(86) International application number:  
**PCT/US2003/023019**

(22) Date of filing: **23.07.2003**

(87) International publication number:  
**WO 2004/010856 (05.02.2004 Gazette 2004/06)**

(54) **SCANNING MINIATURE OPTICAL PROBES WITH OPTICAL DISTORTION CORRECTION AND ROTATIONAL CONTROL**

SCANNENDE OPTISCHE MINIATURSONDE MIT KORREKTUR DER OPTISCHEN FEHLER UND KONTROLLE DER ROTATIONSBEWEGUNG

SONDES OPTIQUES MINIATURES A BALAYAGE AVEC CORRECTION DE DISTORSION OPTIQUE ET COMMANDE DE ROTATION

(84) Designated Contracting States:  
**AT BE BG CH CY CZ DE DK EE ES FI FR GB GR  
HU IE IT LI LU MC NL PT RO SE SI SK TR**

(30) Priority: **25.07.2002 US 205374**

(43) Date of publication of application:  
**04.05.2005 Bulletin 2005/18**

(73) Proprietor: **Lightlab Imaging, LLC  
Westford, MA 01886 (US)**

(72) Inventors:  
• **PETERSEN, L., Christopher**  
**Carlisle, MA 01741 (US)**  
• **MCNAMARA, Edward, I.**  
**Chelmsford, MA 01842 (US)**  
• **LAMPORT, Ronald, B.**  
**Pelham, NH 03076 (US)**  
• **ATLAS, Michael**  
**Arlington, MA 02474 (US)**  
• **SCHMITT, Joseph, M.**  
**Andover, MA 01810 (US)**

• **MAGNIN, Paul**  
**Andover, MA 01810 (US)**  
• **SWANSON, Eric, A.**  
**Acton, MA 01720 (US)**

(74) Representative: **Greenwood, John David et al**  
**Graham Watt & Co LLP**  
**St Botolph's House**  
**7-9 St Botolph's Road**  
**Sevenoaks**  
**Kent TN13 3AJ (GB)**

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12, 3 January 2001 (2001-01-03) & JP 2000 262461  
A (UNIV HOSPITAL OF CLEVELAND; OLYMPUS  
OPTICAL CO LTD), 26 September 2000  
(2000-09-26) -& US 6 615 072 B1 (OLYMPUS  
OPTICAL CO.) 2 September 2003 (2003-09-02)

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**EP 1 526 800 B1**

**Description****Field of Invention**

5   **[0001]** The field of invention relates to the design, fabrication, and use of ultra-small scanning imaging probes and more particularly to the design and fabrication and use of an ultra-small scanning imaging probes for prevention of rotational distortion.

**Background of Invention**

10   **[0002]** There is a pressing need for developing ultra-small scanning optical probes. These probes require ultra-small imaging lenses and associated scanning and beam director elements. Such probes are used in Optical Coherence Tomography (OCT) and other interferometric imaging and ranging systems, as well as for delivery of other imaging modalities (e.g. fluorescence) or therapeutic optical sources. Future medical (and nonmedical) optical probes will require  
15 these miniature probes to navigate small and torturous passageways such as arteries, veins, and pulmonary airways. Present technology generally is not adequate for meeting the needs of these small probes when the probes must be less than ~500  $\mu\text{m}$  in diameter, while simultaneously having a working distance that can extend up to several millimeters and performing controlled and potentially complex scan patterns.

20   **[0003]** Although the design and construction of small lenses is known, as exemplified by a design of a catheter that uses a small (~1 mm) GRIN lens coupled to a fold mirror for imaging the aperture of a single-mode fiber onto a vessel wall, the scaling of this design to less than 500  $\mu\text{m}$  is problematic. Although techniques exist for making very small lenses that have small working distances suitable for coupling to laser diodes and other optical components, these lenses generally do not offer the > 1mm working distance and the > 1mm depth-of-field required for many applications.

25   **[0004]** Further, there are a number of commercially available 'torque wires' - miniature wire-wound devices intended to transmit torque over a long and flexible shaft. Such devices are now commonly used in intravascular ultrasound (IVUS) procedures. Such ultrasound probes combined with torque wires perform rotational scanning in coronary arteries. Generally however, these devices are at least 1 mm in diameter, and are thus 2 to 4 times larger than the devices required by many applications. Presently, such torque wires are not scalable to the sizes required to permit the construction of small optical scanning probes.

30   **[0005]** Patent 6,165,127 ('127) discloses the use of a viscous fluid located inside the bore of an ultrasound catheter. The purpose of the fluid is to provide loading of a torque wire such that the wire enters the regime of high torsional stiffness at moderate spin rates. As described in the '127 patent, this fluid is housed within a separate bore formed inside the main catheter, increasing the overall size of the device, the fluid does not contact the imaging tip, nor does the ultrasound energy propagate through this fluid unlike the present invention.

35   **[0006]** Finally, achieving uniform rotational scanning at the distal tip of a single fiber, while maintaining an overall device size less than 500  $\mu\text{m}$  in diameter is a major challenge. Because it is highly undesirable to add a motor to the distal tip, with the attendant wires and size issues, a way must be found to apply torque to the proximal tip and transmit the torque to the distal tip which may be as much as three meters away in a catheter application. If the extremely low inherent rotational stiffness of a glass fiber is considered (approximately 1 millionth of a N-m of applied torque will cause  
40 a 1 cm length of standard 125  $\mu\text{m}$  diameter fiber to twist up one degree) the issues of uniformly spinning the distal tip by driving the proximal end can be appreciated. Uniform rotation is critically important in endoscopic techniques in order to obtain accurate circumferential images. The term 'NURD' (non-uniform rotational distortion) has been coined in the industry to describe these deleterious effects.

45   **[0007]** The present invention relates to a small optical fiber probe that experiences substantially no NURD.

50   **[0008]** JP-A-2000 262461 discloses an Optical Coherence Tomography (OCT) device which irradiates a biological tissue with low coherence light, obtains a high resolution tomogram of the inside of the tissue by low-coherent interference with scattered light from the tissue, and is provided with an optical probe which includes an optical fiber having a flexible and thin insertion part for introducing the low coherent light. When the optical probe is inserted into a blood vessel or a patient's body cavity, the OCT enables the doctor to observe a high resolution tomogram. In a optical probe, generally,  
a fluctuation of a birefringence occurs depending on a bend of the optical fiber, and this an interference contrast varies depending on the condition of the insertion. The OCT of the present invention is provided with polarization compensation means such as a Faraday rotator on the side of the light emission of the optical probe, so that the OCT can obtain the stabilized interference output regardless of the state of the bend.

55   **[0009]** WO-A2-01/11409 discloses an optical probe which has the features of the preamble of claim 1. The present invention is characterized by the features recited in the characterizing portion of claim 1. Optional features are recited in the dependent claims.

**[0010]** The invention relates to an optical probe including a sheath; a flexible, bi-directionally rotatable optical transmission system positioned within the sheath; and a viscous damping fluid located in the sheath. The optical transmission

system is capable of transmitting, focussing, and collecting light of a predetermined range of wavelengths. The sheath and the viscous damping fluid are transparent to at least some of the wavelengths of that light. The index of refraction of the viscous fluid is typically chosen to remove the optical effects induced by propagation through said sheath. In one embodiment, the optical transmission system is less than substantially 300  $\mu\text{m}$  in diameter. In some embodiments, the sheath is substantially cylindrical. In some embodiments the optical probe further comprises a lumen for providing catheter flushes. In other embodiments, the catheter flushes are maintained substantially at body temperature to minimize temperature induced-viscosity changes in the viscous damping fluid.

**[0011]** In another aspect, the optical transmission system includes an optical fiber and a focusing element optically coupled to a beam director. The focusing element creates an exit beam waist having a radius of less than 100  $\mu\text{m}$  with a working distance ranging from zero to several millimeters, and a depth of field up to several millimeters. In one embodiment, the sheath is less than substantially 500  $\mu\text{m}$  in diameter. In one embodiment, the transmission fiber is rotatably driven at its proximal end.

**[0012]** In one embodiment, the focussing element and the beam director comprises the transmission fiber attached to a first segment of silica fiber, which is attached to a graded index fiber attached to a second segment of coreless fiber. In another embodiment, the second segment of coreless fiber has one or more angled facets to form the beam director. In yet another embodiment, the focussing element and beam director includes a transmission fiber attached to a graded index fiber whose working aperture and index profile are designed to produce a beam waist with a radius of less than 100  $\mu\text{m}$  at a working distance, measured from the end of the lens, of several millimeters.

## **Brief Description of Drawings**

### **[0013]**

Figure 1 illustrates an embodiment of an imaging lens according to an illustrative embodiment of the invention;  
 Figure 2 illustrates the relationship between the spot size and the depth of field for the embodiment of the imaging lens shown in Figure 1 assuming a Gaussian beam;  
 Figure 3 illustrates an embodiment of a device known to the prior art;  
 Figure 4 illustrates an embodiment of the device constructed in accordance with the invention;  
 Figure 5 illustrates an embodiment of a device with a detached fold mirror constructed in accordance with the invention;  
 Figure 6A illustrates an embodiment of an imaging wire inside a protective housing;  
 Figure 6B illustrates an embodiment of optically compensated and uncompensated propagation through a sheath;  
 Figure 7 illustrates an embodiment of the invention with an optically transparent viscous damping fluid;  
 Figure 8 illustrates an embodiment of the invention utilizing total internal reflection inside a optical viscous fluid;  
 Figure 9 illustrates the use of the invention for imaging of a flat surface using NURD compensation;  
 Figure 10 illustrates the imaging of a flat surface without NURD compensation;  
 Figure 11 illustrates the use of the invention for imaging the inside of cylindrical tissue phantom using NURD compensation;  
 Figure 12 illustrates the imaging of the inside of cylindrical tissue phantom without NURD compensation; and  
 Figure 13 illustrates a miniature optical probe in accordance with an illustrative embodiment of the invention.

## **Description Of The Preferred Embodiment**

**[0014]** Figure 1 shows an example of an embodiment of an imaging lens. In this embodiment a single-mode fiber 10 is spliced or otherwise secured to a lens 12. The lens 12 is approximately the same diameter as the fiber 10. The fiber 10 may include a variety of thin protective coatings. A beam director 14, a 45 (or other suitable angle) degree fold mirror in one embodiment, is affixed to the lens 12 using fusion splicing or glue. The fold mirror 14 is either coated with a high-reflectance material or operates according to the principle of total internal reflection.

**[0015]** Still referring to Figure 1, in the embodiment shown, the lens 12 has a working distance 16 from the surface 18 of the fold mirror 14 to the waist location 20 of the Gaussian beam. The combination of the lens 12 and beam director 14 magnify (or reduce) the beam waist originally located at the exit of the single-mode fiber 10 and create a new waist 20 at the spot located at the working distance 16. At the working distance 16 the spot size is minimized, as shown in Figure 2, and the phase front is nearly flat.

**[0016]** In general, in highly multimode beams (mode number of approximately 10 or higher), the waist location 20 and the classical image location are nearly coincident. For the single-mode beams employed here, however, these locations can differ significantly. The lens/imaging system has a depth of focus 22 that is inversely related to the square of the spot size. For many imaging systems, including Optical Coherence Tomographic imaging systems, light emitted from the fiber is focused on a sample and retro-reflected light is then coupled back through the lens and into the single-mode

fiber. In these and other imaging or light delivery/collection applications the best optical performance is obtained when the light impinges on a sample that is located within the depth of focus or field 22.

[0017] Single-mode Gaussian beams expand from their minimum width (the 'waist' 20) according to the well-known relationship:

$$\omega(z) = \omega_0 \sqrt{1 + \left(\frac{z}{z_0}\right)^2} \quad (1)$$

where  $\omega(z)$  is the beam radius at location  $z$ ,  $\omega_0$  is the beam waist which occurs by definition at  $z=0$ , and  $z_0$  is the Rayleigh range and is the distance at which the peak intensity falls to  $1/2$  of its value as measured at the waist. The Rayleigh range is given by  $(\pi\omega_0^2/\lambda)$ , where  $\lambda$  is the wavelength of the light in a vacuum, and  $n$  is the index of refraction of the medium. The Rayleigh range thus dictates the depth of field 22, which is typically defined as twice  $z_0$  and is often called the confocal parameter. As shown in Figure 1, the distance 16 from the waist location 20 of the imaged beam back to the surface 18 is defined here as the working distance of the lens assembly 12/14. The total focussing length of the lens 12 itself additionally includes the optical path traversed in beam director 14.

[0018] The radius of curvature,  $R(z)$ , of a Gaussian beam follows another well-known relationship:

$$R(z) = z_0 \left( \frac{z}{z_0} + \frac{z_0}{z} \right) \quad (2)$$

[0019] Equation 2 demonstrates that a Gaussian beam has an infinite radius of curvature (i.e. flat phase front) at the waist, and that at distances which are large compared to the Rayleigh range, a Gaussian beam will propagate much as a spherical wave centered at  $z = 0$  and can be treated in this regime with classical (geometrical) optics. In the case at hand, however, the desired working distance( $z$ ) and depth of field( $z_0$ ) are comparable and classical optics cannot be used effectively. To solve the current problem, a desired working distance 16 and depth of field 22 are first chosen. This determines the required waist size which is to be created by the lens. The required waist size and desired location 16 in space in turn determine the required beam size as well as the phase front radius of curvature (of the outgoing beam) at the lens surface 27. Thus, the lens system 12 must allow the beam to expand from the exit of the fiber to match the beam size required at the lens surface 27, and must also bend the phase front of the incoming beam to match that of the outgoing beam. Hence the lens system can be uniquely determined given the two input requirements, the working distance 16 and the depth of field 22.

[0020] Forming microlenses out of graded index materials ('GRIN') is the preferred embodiment for the probes described herein, although lenses created from curved surfaces can be effectively used as well. The essential ingredient of a GRIN lens is the radial variation in the material index of refraction which causes the phase front to be bent in a way analogous to the phase bending in a conventional curved-surface lens. A simple instructive relationship between GRIN lenses and standard curved lenses can be formed by treating both as 'thin' lenses; essentially considering the length within the lenses as negligible. This relationship is:

$$\frac{n_1 - n_0}{R_l} = n_c \frac{A}{a^2} l_{grin} \quad (3),$$

where  $n_c$  is the center index of the GRIN material,  $A$  is the index gradient such that

$$n_r = n_c \left( 1 - \frac{A}{2} \left( \frac{r}{a} \right)^2 \right) \quad (4)$$

where  $n_r$  is the index at radius  $r$  from the center,  $l_g$  is the length of the GRIN material (Here the length is needed only to determine the focusing power of the 'thin' GRIN lens.), and  $a$  is the radius of the GRIN lens. Such materials are com-

mercially available as mentioned earlier. However, generally commercially available GRIN lenses do not exist to meet the present imaging requirements because the gradient profile  $A$  and the size of the GRIN material ( $a$ ) are such that the simultaneous achievement of the working distance 16 and depth of field 22 which are required here cannot be met.

**[0021]** Thus in one embodiment, customized GRIN materials are grown for the requirements described herein. In order to do this successfully, a more rigorous calculation is required, taking into account the length of the GRIN material for beam propagation as well as focusing strength. That is, as the Gaussian beam propagates through the GRIN material it is continuously modified by the gradient profile. Because the lenses here have requirements for relatively both large apertures and low focusing powers they cannot be considered 'thin' lenses as above.

**[0022]** Thus to calculate the required GRIN gradient profile, the well-known ABCD matrix formalism for treating Gaussian beam propagation in the paraxial approximation may be used. The ABCD matrix describing the propagation from the single mode fiber, through the GRIN material, and into the medium interface is given by:

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} \cos(l_{grin} A') & \frac{n_{smf}}{n_c A'} \sin(l_{grin} A') \\ -\frac{n_c A}{n_0} \sin(l_{grin} A') & \frac{n_{smf}}{n_0} \cos(l_{grin} A') \end{bmatrix} \quad (5)$$

**[0023]** Where  $A'$  is  $(\sqrt{A})/a$ , and  $n_{smf}$  is the index of the single-mode fiber. As is known in the art, the ABCD law for the transformation of Gaussian beams can be used here to solve for the  $A'$  parameter, given the other material parameters and, as before, the desired depth of field 22 and working distance 16. With some algebraic manipulation, two equations can be derived:

$$\frac{1}{\omega_f^2} = \frac{1}{\omega_i^2} \left( \cos^2(l_{grin} A') + \left( \frac{n_c A' \pi \omega_i^2}{\lambda} \right)^2 \sin^2(l_{grin} A') \right) \quad (6)$$

$$\frac{1}{W_D} = \left( \frac{n_{smf}}{n_0} \right)^2 \frac{1}{\sin(l_{grin} A') \cos(l_{grin} A') \left( \left( \frac{\pi \omega_i^2}{\lambda_{smf}} \right)^2 \frac{n_c A'}{n_0} - \frac{n_{smf}^2}{n_c n_0 A'} \right)} + \frac{n_c A' \sin(l_{grin} A')}{n_0 \cos(l_{grin} A')} \quad (7)$$

where  $w_f$  is the final (imaged) beam waist radius,  $w_i$  is the initial beam waist radius at the exit of the single mode fiber,  $\lambda$  is the free-space wavelength,  $\lambda_{smf}$  is the wavelength inside the single mode fiber, and  $W_D$  is the working distance (e.g. location of the imaged waist). For example, given a desired depth of field of 4 mm and a working distance of 3mm, with  $\lambda$  equal to 1.32  $\mu$ m, Equations (7) and (8) can be iteratively solved to yield  $A' = 1.2074 \text{ mm}^{-1}$  and  $l_{grin} = 1.41 \text{ mm}$ , starting with standard Corning SMF-28 fiber and imaging in air.

**[0024]** If the exact GRIN parameters cannot be achieved, especially the gradient coefficient  $A$  which in these designs is significantly lower than commercially available GRIN fibers, it is possible, as is known in the art, to affix an intermediate piece of fiber between the single mode fiber and the GRIN material. The purpose of this intermediate piece of fiber is to allow the beam to expand as it exits the single mode fiber and before it enters the GRIN fiber. This intermediate piece is preferably pure silica so it will have no beam shaping or guiding effects other than simple expansion. The combination of the expander and GRIN material allow a wider choice of gradient coefficients to be used and still achieve the desired working distance and depth of field. Adding the expander in the ABCD formalism is particularly easy because the matrix for the expander,

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} 1 & L \\ 0 & 1 \end{bmatrix} \quad (8)$$

need only multiply the matrix for the GRIN lens. If there are index differences between the expander and the GRIN lens, additional matrices accounting for the index difference can be inserted into the equation.

**[0025]** Figure 3 depicts an embodiment of a miniature imaging probes known to the art. In this embodiment, a single-mode fiber 10 (in one embodiment 125  $\mu\text{m}$  in diameter) is glued using ultraviolet-cured optical adhesive 11 ("UV glue") to a commercially available 700  $\mu\text{m}$  GRIN lens 12', which is, in turn, UV glued to a 700  $\mu\text{m}$  beam director prism 14'. This optical transmission system is contained inside a rotatable torque cable 40 that is affixed near the proximal end of the GRIN lens 12'. The entire assembly is contained within a sheath 44 that is transparent to the wavelength of light emitted by the single-mode fiber 10 or has a transparent window near the prism 14'. This imaging probe can achieve the resolution, depth of field, and spot sizes illustrated in Figure 2.

**[0026]** However, even though the fiber is only 125  $\mu\text{m}$  in diameter and the largest beam size required is less than 100  $\mu\text{m}$  as seen in Figure 2, the entire assembly is approximately 1 mm in diameter.

**[0027]** This large diameter limits the use of this device to openings significantly greater than 1 mm. For example, in imaging within small blood vessels the outside diameter (OD) of the probe must be less than 350  $\mu\text{m}$  for insertion in the guidewire lumens of existing catheters. Further, the design shown also suffers from large back reflections because it is difficult to match the indices of refraction of the various elements. These back reflections can significantly impact the imaging quality of the lens particularly in OCT applications. In OCT applications large back reflections lead to an effect known blindness, whereby a large reflection tends to saturate the front-end electronics, rendering small reflections undetectable.

**[0028]** Figure 4 depicts an embodiment of the optical assembly in which a single-mode transmission fiber 10 is attached to the GRIN lens 12', which in turn is attached a faceted beam director 14". The attachments are done via fiber fusion splices 48, which eliminate the need for optical epoxy, although epoxy can be used if required. The beam director 14" shown in this embodiment has two facets; the first facet 50 acts to reflect the light while the second facet 54 transmits the light and avoids beam distortions that would occur by passing light through the cylindrical fiber. In one embodiment the first facet 50 makes a 50 degree angle with the longitudinal axis of the fiber 10. Also in the embodiment, the second facet 54 makes a 5 degree angle with the longitudinal axis of the fiber 10.

**[0029]** The first facet 50 can then be either metal or dielectric coated or can be coated with a dichroic beam splitter to allow simultaneous forward and side viewing via different wavelengths. Alternatively, if the angle is greater than the angle for total internal reflection given by Snell's law (~43 degrees for a silica/air interface) then it is not necessary to coat the fiber. This results in a significant reduction in cost and complexity because coating the tip of the fiber for internal reflection (as opposed to much easier external reflection) is a significant technical challenge. The total diameter of the optical lens 12'/beam director 14" in Figure 4 can easily be made less than 300  $\mu\text{m}$  while meeting the desired beam parameters, such as those shown in Figure 2. Furthermore, the lens 12' can be made using standard fusion, splicing and polishing techniques and thus can be inexpensive, exhibit minimal back reflections and also focus precisely. It is preferred to make the attached beam director 14" of Figure 4 by first fusion splicing a short section of coreless fiber to the GRIN lens 12', then polishing the fold mirror facet 50, and then polishing the exit facet 54 at the required angles.

**[0030]** Special attention must be given to the relationships between the angles of the facets 50, 54 when imaging using optical coherence tomography. Since the sensitivity of OCT systems routinely exceeds 100 dB, it is important to prevent back reflections from the second facet 54 from coupling back into the transmission fiber 10. Even a 4% reflection (silica to air interface) is strong enough to saturate and effectively 'blind' a sensitive OCT system. Thus, the angles must be chosen such that the back reflection angle is greater than the acceptance angle of the single-mode transmission fiber 10. For example, a reflection facet 50 polished with an angle of incidence of 50 degrees, and a transmissive facet 54 polished at 5 degrees to the axis of the lens, will return a beam exceeding the acceptance angle of standard SMF-28 single mode fiber 10. These particular angles offer another advantage; the 50 degree angle exceeds the angle for total internal reflection for a glass-air interface (nominally 43 degrees). Furthermore, this design allows the fiber 10 lens 12'/beam director 14" assembly to be tested in air prior to any coating process.

**[0031]** Figure 5 depicts another embodiment in which the beam director 14"" (fold mirror) is detached from the lens 12. This approach has the advantage of allowing the beam director 14"" mirror to be coated for external reflection, a substantially easier process. However, this approach offers the disadvantage that the length of the device increases and the focal length of the lens 12 must be increased to compensate. Due to the limited aperture of 125  $\mu\text{m}$  diameter fibers 10, it is difficult to achieve both a long focal length and a small spot size, so compact beam director designs are generally preferred.

**[0032]** As shown in Figure 6A, in each embodiment, the fiber 10 and lens 12 assembly are encased inside a protective

sheath 44 or tube. The sheath 44 is required for several reasons. First and foremost is protection of the fiber 10. Second a sheath 44 improves the handling of long fiber catheters. Third the sheath 44 permits mechanical damping of the spinning fiber 10 to achieve uniform rotational speed, as detailed below.

**[0033]** However, the sheath 44 must allow the OCT light to exit with minimal loss and distortion to the outgoing beam in order to achieve the most optically efficient system possible. Without minimizing absorption, scattering, and distortion losses through the sheath 44, it is possible to lose more than 30 dB of system sensitivity. Of these losses, optical distortion is the more difficult to control (in a cylindrical sheath) and can account for 15-20 dB of loss. The distortion occurs as the beam passes through the curved surface of the sheath 44 which acts as lens. The power of lens is governed by the radius of the sheath 44 and the index differences between the sheath 44 and surrounding medium(s).

**[0034]** The sheath 44 may itself be transparent, or it may incorporate a suitable transparent material in the region of the beam director 14. A transparent sheath 44 is preferred since there are many materials that minimize absorption and scattering losses for OCT while still exhibiting good mechanical properties. Materials with these properties include Teflon, acrylic, polycarbonate, and several thermoplastics, such as Hytrel® from E.I. du Pont de Nemours Company. Hytrel is a thermoplastic polyester elastomer. Note that several of these materials can be opaque at visible wavelengths while still transmitting OCT wavelengths. A transparent sheath is also preferred since it allows the rotating fiber to be translated longitudinally within the sheath to perform three dimensional imaging without moving the sheath and fiber back and forth as a unit.

**[0035]** Flat window materials, or flats formed on the sheath 44 can of course be used to minimize the optical distortion effects, which makes the optical image properties easier to deal with, but greatly increases the fabrication complexity and costs. Also flat windows cannot be made to accommodate 360-degree scanning as required in a circumferential scanning device. If cylindrical sheaths 44 or windows are chosen, consideration must be given to the effects on the image quality that the window material and shape will impart.

**[0036]** Standard equations from classical (circular) optics give a good insight into the nature of the problems encountered:

$$\frac{n_1}{f_1} = \frac{n_2}{f_2} = \frac{n_2 - n_1}{R_1} - \frac{n_2 - n_3}{R_2} + \frac{(n_2 - n_3)(n_2 - n_1)t}{n_2 R_1 R_2} \quad (9)$$

where  $n_1$  is the optical index in the medium to the left of the sheath,  $n_2$  is the index of the sheath material itself,  $n_3$  is the index in the medium to the right of the sheath,  $R_1$  is the inner radius of curvature,  $R_2$  is the outer radius,  $f_{1,2}$  are the focal lengths to the left and right of the sheath, and  $t$  is the sheath thickness. In the case of the cylindrical sheath, the focal lengths in equation (9) apply only to the circumferential direction.

**[0037]** The optical effect of the sheath 44 on the transmitted beam is twofold. First, referring again to Figure 1, the beam waist size changes and second the location of the waist 20 changes. The coupling loss compared to the ideal case is best calculated by overlap integrals, but a good approximation for the one-dimensional additional loss in the circumferential direction is:

$$\eta = \frac{1}{1 + \frac{L}{z_0}} \quad (10)$$

where  $\eta$  is the efficiency  $L$  is the distance from the circumferential beam waist to the ideal beam waist, and  $z_0$  is the Rayleigh range, defined earlier.

**[0038]** It is apparent from examining the above equations that to minimize the optical effects of the sheath 44 (i.e., drive the focal lengths  $f_1$  and  $f_2$  towards  $\infty$  which is the equivalent of a flat surface), the most important issue is matching (equalizing) the three indices, followed by decreasing the thickness, followed by increasing the radius of curvatures. It is understood that the above equation is for a spherical surface, whereas here the effect is only in the direction perpendicular to the sheath axis. However, this serves to illustrate the effect. Generally, it is very difficult to match all three material indices; minimizing the thickness introduces mechanical integrity concerns; and increasing the radius leads to unacceptably large probe diameters. Another possibility is effectively 'neutralizing' the effect of the curved surface by choosing a medium inside the sheath such that the two refractive effects (inside and outside diameter of the sheath/window) cancel each other to first order. Choosing the proper index 'neutralizing' fluid can be accomplished using the following relationship:

$$\frac{n_2 - n_1}{R_1} = \frac{n_2 - n_3}{R_2} \quad (11)$$

[0039] Here  $n_1$  is the optical index of the neutralizing fluid or gel,  $n_2$  is the index of the window material, and  $n_3$  is the index of the surrounding medium. This approach gives one new degree of freedom, making it possible to balance the sheath size, thickness and available fluid indices to neutralize the optical effects to first order (e.g. reduce the effects to less than 10% of their original levels).

[0040] The effect of the neutralizing fluid is shown in Figure 6B. The uncompensated curve is for an air-filled acrylic sheath, 355  $\mu\text{m}$  in diameter and 50 microns thick, using a fiber lens 12 designed to produce a 30  $\mu\text{m}$  waist at a depth of 2 mm into saline. The uncompensated case has a rapidly diverging beam, giving an extrapolated waist of 6  $\mu\text{m}$  located approximately 400  $\mu\text{m}$  to the left of the interface. The compensated curve is also shown, using a commercially available fluorosilicone fluid, which gives a circumferential waist near 1800  $\mu\text{m}$  - very close to the ideal. The overall coupling losses are over 12 dB in the uncompensated case and less than 1 dB in the compensated case representing a 90% reduction in unwanted losses.

[0041] To avoid the complication of coating the internally reflective facet 50, total internal reflection is preferred. As noted, for a glass/air interface this occurs for any angle of incidence greater than 43 degrees. However, once the fiber is immersed in an environment such as water or saline in which the refractive index is much larger than unity (air), total internal reflection becomes impractical. Thus it is desirable to maintain the glass/air interface.

[0042] Figure 7 depicts a preferred method for achieving an air-backed beam director 14 such that total internal reflection can be used at practical angles within a fluid environment. A thin transparent inner sheath 44' is attached over the lens 12/beam director 14 and sealed 74 at the distal end. The inner sheath 44' may be attached by optical epoxy or by heat-induced shrinkage. The outer sheath 44 of Figure 6A is also shown in Figure 7.

[0043] Once the optical effects have been addressed, it is crucial to perform uniform rotational scanning so that high quality, understandable, and reproducible images may be obtained. In the endoscopic imaging industry, much effort has been devoted to this problem. Essentially three viable techniques have evolved in the prior art. The first is the development of torque wires 40, already discussed. The second is the development of phased array systems (in ultrasound imaging), which can effectively steer the beam via electronic control of the distal transducers. Lastly, software image correction can try to compensate for NURD by post-processing the image. As mentioned, torque wires 40 are generally not scalable to the sizes considered here and add significant cost. Phased array systems are highly complex since they involve many transducers and additional control electronics. Multiple fiber solutions are possible, but add significant costs. Lastly the software-based correction is quite complex and fallible and the resultant image is generally of much poorer quality than if the NURD had been prevented *a priori*.

[0044] A new method for controlling rotational speed variances for fiber optic probes is disclosed and described herein. Given the very low torsional stiffness of the glass fibers (as detailed earlier), significant winding of the fiber can be expected over a length and rotational speed practical for many applications, especially medical applications. For example, a 2 meter length of 125  $\mu\text{m}$  diameter fiber coated with 7.5  $\mu\text{m}$  of a polyimide coating, spinning at 10 Hz inside a water-filled catheter housing experiences over 10 complete turns of winding. Although the distal tip must spin on average at 10 Hz it will experience speed variations, (NURD) during fractions of a rotation due to winding and unwinding caused by frictional variations, slight eccentricities in the glass fiber itself, catheter movements, temperature variations, and so forth.

[0045] As conceptually depicted in Figure 8 (as well as Figure 7), it is possible to control these speed variations by using negative feedback control of the speed at the distal tip of the optical transmission system. Viscous damping localized at the tip can provide this feedback control. Introducing a viscous damping fluid 90 between the optical transmission system and the sheath 44 creates, in essence, an optically transparent journal bearing. An optical path is shown by the dotted arrow. The mechanical properties of journal bearings are well understood and documented thoroughly. Several relationships are:

$$\text{ShearStress } (\tau) = \mu \times \frac{V}{a} = \mu \times RPS \times \frac{2\pi r}{a} \quad (12)$$

$$\text{Torque} = \mu \times RPS \times \frac{2\pi r}{a} \times 2\pi \times l \times r \quad (13)$$



$$\frac{\text{Windup}}{\text{length}} = \frac{\text{Torque}}{G \cdot I_z} \quad (14)$$

where  $\mu$  is the viscosity,  $a$  is the clearance between the fiber and the sheath,  $V$  is the velocity, RPS is revolutions per second,  $l$  is the length over which the viscous fluid is applied within the sheath,  $G$  is the shear modulus (modulus of rigidity of the fiber), and  $I_z$  is the moment of inertia about the axis of the fiber.

**[0046]** Since the viscosity-induced torque loading increases with speed and will act to slow down an unwinding fiber, the negative feedback is established. By controlling the variables  $a$ ,  $l$ , and  $\mu$  it is possible to precisely control the rotational characteristics of the distal end of the optical transmission system. This technique offers the advantage of controllability, low cost, low complexity, and negligible increase in probe size while permitting NURD-free operation of endoscopic imaging systems. According to the invention even more control of NURD is achieved by placing different viscosity fluids at different locations where the inherent high viscosities help prevent mixing except near the fluid boundaries. This facilitates the isolation of the various fluids while still allowing free rotation. Distributing a viscous fluid over the entire length of the catheter is also possible, but distally located viscous damping is usually more effective for NURD control.

**[0047]** Finally, the fluid used for viscous control must also possess the required transmissive and preferably neutralizing optical characteristics as detailed earlier. There are a number of fluids and gels, for example fluorosilicone compounds, that are suitable both optically and mechanically for the purposes described herein. In addition, suitable viscous damping fluids typically have a kinematic viscosity index of between 500 and 20,000 centistokes and an optical index of refraction between 1.32 and 1.65 in some embodiments.

**[0048]** Several classes of compounds meet these requirements, fluorosilicones, syrups, synthetic and natural oils, even radiographic contrast agent used in many interventional cardiology procedures (such as RenoCal-76 (tm), a solution of Diatrizoate Meglumine and Diatrizoate Sodium, manufactured by Bracco Diagnostics of Princeton NJ).

**[0049]** Many viscous fluids exhibit a strong interdependency between viscosity and temperature. This can be used advantageously in various embodiments. Temperature effects can detrimentally impact the use of viscous fluids in some embodiments. One aspect of the invention relates to regulating viscous fluid temperatures in order to achieve a reduction in NURD. For example, an advantageous use of the temperature dependence is heating the viscous damping fluid to facilitate easy injection into a tight orifice, such as a long catheter sheath. A potentially detrimental effect is seen in intravascular imaging applications, where saline flushes are often used. If the saline is not at body temperature, the viscosity of the viscous damping fluid will change and the delivery fiber will wind or unwind (depending on whether the viscosity increases or decreases), causing the observed OCT image to spin. A simple solution is to ensure that any injected saline, or other suitable catheter flush, is maintained at or near body temperature. An example of this temperature sensitivity is given by MED-360, a silicone fluid manufactured by NuSil of Carpinteria, CA. For Med-360, the viscosity at room temperature (25C) is 1010 centistoke and drops to 750 centistoke at body temperature (38C).

**[0050]** Figure 9 depicts a NURD-free optical coherence tomographic image of a flat surface obtained using the catheter shown in Figure 7. Figure 10 is an image of the same surface obtained without the viscous fluid damping used to obtain the NURD free image of Figure 9. Similarly, Figure 11 is a NURD-free optical coherence tomographic image of the inside of a cylindrical tissue phantom obtained using the catheter shown in Figure 7. Figure 12 is the image of the same cylindrical tissue phantom obtained without viscous fluid damping. In both Figures 10 and 12 the distortion of the image is apparent due to the irregular rotational speed of the optical probe tip.

**[0051]** It is worth noting, that the concept of a distally located viscous fluid for NURD reduction can be applied to situations other than fiber optic imaging. For example an ultrasound catheter can use this technique in place of the standard and expensive torquewires.

**[0052]** Although this discussion has focused on medical applications it is clear that there are a large number of non-medical applications in industrial inspection and materials analysis that are possible. Furthermore, while single-mode fibers are preferred for OCT imaging, multimode fibers may be used as well in the embodiments described herein.

**[0053]** The interrelation of some of the various elements of the invention are shown in the illustrative embodiment of the probe 130 shown in Figure 13. A single mode fiber 10 is shown disposed within an inner sheath 44' of the probe 130. The inner sheath 44' typically has a sealed air gap. A focusing element 135 is shown in communication with a beam director 137. Both the focusing element 135 and the beam director 137 are disposed within the inner sheath 44'. The inner sheath is disposed within an outer sheath 44 as has been previously described in various embodiments. A viscous damping fluid 140 is disposed within the outer sheath 44 and surrounds a portion of the inner sheath 44'. In some embodiments, the entirety of the inner sheath 44' is surrounded by the viscous damping fluid 140. The diameter of the outer sheath 44 is under 500 micrometers in various embodiments as shown. A sealing ball 145 is typically disposed within the outer sheath to contain the viscous damping fluid 140 within a defined volume. A heat formed tip 150 is also present in various embodiments.

## Claims

1. An optical probe comprising:

5 a sheath (44)

a flexible, bi-directionally rotatable, optical transmission system comprising a transmission fiber (10), a beam director and a focusing element (12) optically coupled to the beam director (14) positioned within said sheath (44); said optical transmission system capable of transmitting, focussing and collecting light of a predetermined range of wavelengths;

10 the fiber (10) is slidably rotatable within said sheath (44) and is arranged to be rotatably driven at a proximal end; and **characterized by:**

a number of different viscous damping fluids located at different locations within the distal portion of the sheath, the viscosity of the fluids being selected to reduce non-uniform rotational distortion of the optical transmission system.

2. The optical probe of claim 1 wherein said optical transmission system is less than substantially 300  $\mu\text{m}$  in diameter.

3. The optical probe of claim 1 wherein said optical transmission system creates:

20 an exit beam waist less than 100  $\mu\text{m}$  in radius with a working distance ranging from 0 to 10 mm, and a depth of field to 10 mm.

4. The optical probe of claim 3 wherein said working distance and depth of field are applicable to either air-based or fluid based imaging conditions.

5. The optical probe of claim 1 wherein said sheath (44) less than substantially 500  $\mu\text{m}$  in diameter.

6. The optical probe of claim 1 wherein said focussing element (12) and the beam director (14) comprising the transmission fiber (10) attached to a first segment of coreless silica fiber, attached to a graded index fiber (135) attached to a second segment of coreless fiber (137), wherein said second segment of coreless fiber (137) has one or more angled facets to form the beam director.

7. The optical probe of claim 1 wherein said focusing element and beam director comprises:

35 a transmission fiber (10) attached to a piece of graded index fiber (12) whose working aperture and index profile are designed to produce a beam waist of less than 100  $\mu\text{m}$  in radius at a working distance measured from the lens end of up to 10 mm in either air or fluid; and a faceted piece of coreless fiber (14) attached to the graded index fiber (12).

8. The optical probe of claim 6, wherein said angled coreless fiber (14) is reflectively coated on one angled facet.

9. The optical probe of claim 6, wherein said faceted coreless fiber has a first facet angle such that the beam director directs the beam using total internal reflection.

10. The optical probe of claim 1 wherein said beam director consists of two facets, the first facet (50) acting as a reflector and the second facet (54) acting as a transmissive element, wherein the angle of residual back reflected light arising from the second facet and re-reflecting from the first facet through the focusing element exceeds the acceptance angle of the transmission fiber.

11. The optical probe of claim 6, wherein said second segment of said angled coreless fiber is coated on one facet by a dichroic coating such that optical energy is reflected substantially at one wavelength region and optical energy is transmitted at a substantially separate second wavelength region.

12. The optical probe of claim 1 wherein said sheath (44) comprises a plurality of regions, each region having a predetermined length and containing a fluid with a predetermined viscosity index.

13. The optical probe of claim 1 further comprising a lumen for providing catheter flushes.

14. The optical probe of claim 13, wherein catheter flushes are maintained at body temperature to minimize temperature-induced viscosity changes at the distal tip of the catheter.

15. An optical probe as claimed in claim 1, in which said optical transmission system comprises:

an inner sheath (44') defining a bore, said inner sheath (44') sealed at its distal end, said beam director being located within said bore of said inner sheath (44') and said focusing element being located within said bore of said inner sheath and optically coupled to said beam director located within said bore of said inner sheath; and said inner sheath defining a bore, said inner sheath being located within said bore of said sheath; and which said viscous damping fluid (140) is located within said bore of said sheath (44).

16. The optical probe of claim 15, wherein said optical transmission system is less than substantially 300  $\mu$  m in diameter.

17. The optical probe of claim 15, wherein said optical transmission system creates an exit beam waist (20) less than 100  $\mu$  m in radius with a working distance (16) ranging from 0 to 10 mm, and a depth-of-field up to 10 mm.

18. The optical probe of claim 15, wherein said beam director (14) utilized total internal reflection by an angled facet.

19. The optical probe of claim 15, wherein said sheath (44) is less than substantially 500  $\mu$  m in diameter.

20. The optical probe of claim 15, wherein said beam director (14) has only a single internally reflecting facet.

21. The optical probe of claim 15, wherein said focusing element comprises a coreless fiber with a radiused tip.

22. The optical probe of claim 15, further comprising a lumen for providing catheter flushes.

23. The optical probe of claim 22 wherein catheter flushes are maintained at body temperature to minimize temperature-induced viscosity changes at the distal tip of the catheter.

## Patentansprüche

1. Optische Sonde, umfassend:

eine Umhüllung (44)  
ein flexibles bidirektional drehbares Lichtübertragungssystem, das eine Übertragungsfaser (10), eine Strahlenlenkeinrichtung und ein fokussierendes Element (12) umfasst, das mit der Strahlenlenkeinrichtung (14) optisch gekoppelt ist, das in der Umhüllung (44) positioniert ist; wobei das Lichtübertragungssystem Licht eines vorbestimmten Bereichs von Wellenlängen übertragen, fokussieren und sammeln kann;  
wobei die Faser (10) in der Umhüllung (44) gleitend drehbar ist und so angeordnet ist, dass sie an einem proximalen Ende drehbar getrieben wird; und **gekennzeichnet durch:**  
eine Anzahl von unterschiedlichen viskosen Dämpfungsfluiden, die an unterschiedlichen Stellen im distalen Teil der Umhüllung angeordnet sind, wobei die Viskosität der Fluide ausgewählt ist, um eine ungleichförmige Drehverzeichnung des Lichtübertragungssystems zu verringern.

2. Optische Sonde nach Anspruch 1, bei der das Lichtübertragungssystem kleiner als im Wesentlichen 300  $\mu$ m im Durchmesser ist.

3. Optische Sonde nach Anspruch 1, bei der das Lichtübertragungssystem erzeugt:

eine Austrittsstrahltaile kleiner als 100  $\mu$ m im Radius mit einem Arbeitsabstand, der zwischen 0 und 10 mm liegt, und  
eine Tiefenschärfe von 10 mm.

4. Optische Sonde nach Anspruch 3, bei der der Arbeitsabstand und die Tiefenschärfe auf entweder luftbezogene oder fluidbezogene Abbildungsbedingungen anwendbar sind.

5. Optische Sonde nach Anspruch 1, bei der die Umhüllung (44) kleiner als im Wesentlichen 500  $\mu$ m im Durchmesser ist.

6. Optische Sonde nach Anspruch 1, bei der das fokussierende Element (12) und die Strahlenkeinrichtung (14) die Übertragungsfaser (10) umfassen, die an einem ersten Segment einer kernlosen Quarzfaser angebracht ist, die an einer Graded-Index-Faser (135) angebracht ist, die an einem zweiten Segment einer kernlosen Faser (137) angebracht ist,  
5 wobei das zweite Segment einer kernlosen Faser (137) eine oder mehrere Winkelfacetten aufweist, um eine Strahlenkeinrichtung zu bilden.
7. Optische Sonde nach Anspruch 1, bei der das fokussierende Element und die Strahlenkeinrichtung umfassen:  
10 eine Übertragungsfaser (10), die an einem Stück einer Graded-Index-Faser (12) angebracht ist, deren Arbeitsapertur und Indexprofil so ausgelegt sind, dass eine Strahltaile von weniger als 100 µm im Radius bei einem Arbeitsabstand erzeugt wird, der von dem Linsenende von bis zu 10 mm in entweder Luft oder Fluid gemessen ist; und  
15 ein facettiertes Stück von kernloser Faser (14), das an der Graded-Index-Faser (12) angebracht ist.
8. Optische Sonde nach Anspruch 6, bei der die kernlose Winkelfaser (14) auf einer Winkelfacette reflektierend beschichtet ist.
9. Optische Sonde nach Anspruch 6, bei der die facettierte kernlose Faser einen ersten Facettenwinkel aufweist, so  
20 dass die Strahlenkeinrichtung den Strahl unter Verwendung von innerer Totalreflexion lenkt.
10. Optische Sonde nach Anspruch 1, bei der die Strahlenkeinrichtung aus zwei Facetten besteht, wobei die erste Facette (50) als ein Reflektor wirkt und die zweite Facette (54) als ein lichtdurchlässiges Element wirkt, wobei der Winkel von zurückreflektiertem Restlicht, das von der zweiten Facette herrührt und von der ersten Facette durch  
25 das fokussierende Element hindurch nochmals reflektiert wird, den Öffnungswinkel der Übertragungsfaser überschreitet.
11. Optische Sonde nach Anspruch 6, bei der das zweite Segment der kernlosen Winkelfaser auf einer Facette durch eine dichroitische Beschichtung beschichtet ist, so dass Lichtenergie im Wesentlichen bei einem Wellenlängenbereich reflektiert wird und Lichtenergie bei einem im Wesentlichen getrennten zweiten Wellenlängenbereich durchgelassen wird.  
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12. Optische Sonde nach Anspruch 1, bei der die Umhüllung (44) eine Mehrzahl von Bereichen umfasst, wobei jeder Bereich eine vorbestimmte Länge aufweist und ein Fluid mit einem vorbestimmten Viskositätsindex enthält.  
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13. Optische Sonde nach Anspruch 1, weiter umfassend ein Lumen zur Bereitstellung von Katheterdurchspülungen.
14. Optische Sonde nach Anspruch 13, bei der Katheterdurchspülungen bei Körpertemperatur aufrechterhalten werden, um temperaturinduzierte Viskositätsänderungen an der distalen Spitze des Katheters zu minimieren.  
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15. Optische Sonde nach Anspruch 1, bei der das Lichtübertragungssystem umfasst:  
eine innere Umhüllung (44'), die eine Bohrung begrenzt, wobei die innere Umhüllung (44') an ihrem distalen Ende abgedichtet ist, wobei die Strahlenkeinrichtung in der Bohrung der inneren Umhüllung (44') angeordnet ist und das fokussierende Element in der Bohrung der inneren Umhüllung angeordnet ist und mit der Strahlenkeinrichtung optisch gekoppelt ist, die in der Bohrung der inneren Umhüllung angeordnet ist; und  
45 wobei die innere Umhüllung eine Bohrung begrenzt, wobei die innere Umhüllung in der Bohrung der Umhüllung angeordnet ist; und welches  
besagte Viskositätsdämpfungsfluid (140) in der Bohrung der Umhüllung (44) angeordnet ist.  
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16. Optische Sonde nach Anspruch 15, bei der das Lichtübertragungssystem kleiner als im Wesentlichen 300 µm im Durchmesser ist.
17. Optische Sonde nach Anspruch 15, bei der das Lichtübertragungssystem eine Austrittsstrahltaile (20) kleiner als  
55 100 µm im Radius mit einem Arbeitsabstand (16), der zwischen 0 und 10 mm liegt, und eine Tiefenschärfe von bis zu 10 mm erzeugt.
18. Optische Sonde nach Anspruch 15, bei der die Strahlenkeinrichtung (14) eine innere Totalreflexion durch eine

Winkelfacette verwendete.

19. Optische Sonde nach Anspruch 15, bei der die Umhüllung (44) kleiner als im Wesentlichen 500 µm im Durchmesser ist.
20. Optische Sonde nach Anspruch 15, bei der die Strahlenkeinrichtung (14) nur eine einzige innenreflektierende Facette aufweist.
21. Optische Sonde nach Anspruch 15, bei der das fokussierende Element eine kernlose Faser mit einer gerundeten Spitze umfasst.
22. Optische Sonde nach Anspruch 15, weiter umfassend ein Lumen zur Bereitstellung von Katheterdurchspülungen.
23. Optische Sonde nach Anspruch 22, bei der Katheterdurchspülungen bei Körpertemperatur aufrechterhalten werden, um temperaturinduzierte Viskositätsänderungen an der distalen Spitze des Katheters zu minimieren.

## Revendications

1. Sonde optique comprenant :

une gaine (44)

un système de transmission optique flexible tournant dans deux directions comprenant une fibre de transmission (10), un directeur de faisceau et un élément de focalisation (12) couplé optiquement au directeur de faisceau (14) positionné à l'intérieur de ladite gaine (44) ; ledit système de transmission optique pouvant transmettre, focaliser et recueillir de la lumière d'un intervalle prédéterminé de longueur d'onde ;

la fibre (10) tourne en glissant à l'intérieur de ladite gaine (44) et est conçue pour être entraînée en rotation à une extrémité proximale ; et **caractérisée par** :

plusieurs différents fluides d'amortissement visqueux se trouvant à des emplacements différents à l'intérieur de la partie distale de la gaine, la viscosité des fluides étant sélectionnée pour réduire une distorsion en rotation non-uniforme du système de transmission optique.

2. Sonde optique selon la revendication 1 dans laquelle ledit système de transmission optique a un diamètre sensiblement inférieur à 300 µm.

3. Sonde optique selon la revendication 1 dans laquelle ledit système de transmission optique crée :

une section minimale du faisceau de sortie inférieure à 100 µm de rayon avec une distance de travail de 0 à 10 mm, et

une profondeur de champ jusqu'à 10 mm.

4. Sonde optique selon la revendication 3 dans laquelle ladite distance de travail et ladite profondeur de champ s'appliquent à des conditions d'imagerie basées sur l'air ou sur un fluide.

5. Sonde optique selon la revendication 1 dans laquelle ladite gaine (44) a un diamètre sensiblement inférieur à 500 µm.

6. Sonde optique selon la revendication 1 dans laquelle ledit élément de focalisation (12) et le directeur de faisceau (14) comprenant la fibre de transmission (10) fixée à un premier segment de fibre de silice sans coeur, fixé à une fibre à gradient d'indice (135) fixée à un second segment de fibre sans coeur (137), dans laquelle ledit second segment de fibre sans coeur (137) présente une ou plusieurs facettes angulaires pour former le directeur de faisceau.

7. Sonde optique selon la revendication 1 dans laquelle ledit élément de focalisation et le directeur de faisceau comprennent :

une fibre de transmission (10) fixée à un fragment de fibre à gradient d'indice (12) dont l'ouverture de travail et le profil d'indice sont conçus pour produire une section minimale de faisceau avec un rayon inférieur à 100 µm à une distance de travail mesurée depuis l'extrémité de la lentille, qui est jusqu'à 10 mm dans l'air ou dans un

fluide ; et

un fragment à facettes de fibre sans coeur (14) fixé à la fibre à gradient d'indice (12).

- 5 8. Sonde optique selon la revendication 6, dans laquelle ladite fibre sans coeur angulaire (14) est revêtue de façon à réfléchir la lumière sur une facette angulaire.
9. Sonde optique selon la revendication 6, dans laquelle ladite fibre sans coeur à facettes possède un premier angle de facette tel que le directeur de faisceau dirige le faisceau en utilisant la réflexion totale interne.
- 10 10. Sonde optique selon la revendication 1 dans laquelle ledit directeur de faisceau consiste en deux facettes, la première facette (50) faisant office de réflecteur et la seconde facette (54) faisant office d'élément transmissif, dans laquelle l'angle de la lumière résiduelle réfléchie vers l'arrière venant de la seconde facette et se réfléchissant à partir de la première facette à travers l'élément de focalisation dépasse l'angle d'admission de la fibre de transmission.
- 15 11. Sonde optique selon la revendication 6, dans laquelle ledit second segment de ladite fibre sans coeur angulaire est revêtu sur une facette d'un revêtement dichroïque tel que l'énergie optique est réfléchie sensiblement dans un domaine de longueur d'onde et l'énergie optique est transmise dans un second domaine de longueur d'onde séparé.
- 20 12. Sonde optique selon la revendication 1 dans laquelle ladite gaine (44) comprend une pluralité de régions, chaque région ayant une longueur prédéterminée et contenant un fluide ayant un indice de viscosité prédéterminé.
13. Sonde optique selon la revendication 1 comprenant en outre une lumière pour effectuer des rinçages de cathéter.
- 25 14. Sonde optique selon la revendication 13, dans laquelle les rinçages de cathéter sont maintenus à une température corporelle pour minimiser des changements de viscosité induits par la température à l'embout distal du cathéter.
15. Sonde optique selon la revendication 1, dans laquelle ledit système de transmission optique comprend :  
30 une gaine interne (44') définissant un alésage, ladite gaine interne (44') étant fermée à son extrémité distale, ledit directeur de faisceau se trouvant à l'intérieur dudit alésage de ladite gaine interne (44'),  
et ledit élément de focalisation se trouvant à l'intérieur dudit alésage de ladite gaine interne et étant couplé optiquement audit directeur de faisceau se trouvant à l'intérieur dudit alésage de ladite gaine ; et  
ladite gaine interne définissant un alésage, ladite gaine interne étant située à l'intérieur dudit alésage de ladite gaine, et  
35 lequel dit fluide d'amortissement visqueux (140) se trouve à l'intérieur dudit alésage de ladite gaine (44).
16. Sonde optique selon la revendication 15, dans laquelle ledit système de transmission optique a un diamètre sensiblement inférieur à 300  $\mu\text{m}$ .
- 40 17. Sonde optique selon la revendication 15, dans laquelle ledit système de transmission optique crée une section minimale du faisceau de sortie (20) de moins de 100  $\mu\text{m}$  de rayon avec une distance de travail (16) de 0 à 10 mm, et une profondeur de champ jusqu'à 10 mm.
18. Sonde optique selon la revendication 15, dans laquelle ledit directeur de faisceau (14) utilise la réflexion interne totale créée par une facette angulaire.
- 45 19. Sonde optique selon la revendication 15, dans laquelle ladite gaine (44) a un diamètre sensiblement inférieur à 500  $\mu\text{m}$ .
- 50 20. Sonde optique selon la revendication 15, dans laquelle ledit directeur de faisceau (14) ne possède qu'une facette réfléchissante en interne.
21. Sonde optique selon la revendication 15, dans laquelle ledit élément de focalisation comprend une fibre sans coeur à bout arrondi.
- 55 22. Sonde optique selon la revendication 15, comprenant en outre une lumière destinée à effectuer des rinçages de cathéter.

- 23.** Sonde optique selon la revendication 22 dans laquelle les rinçages de cathéter sont maintenus à une température corporelle pour minimiser des changements de viscosité induits par la température à l'embout distal du cathéter.

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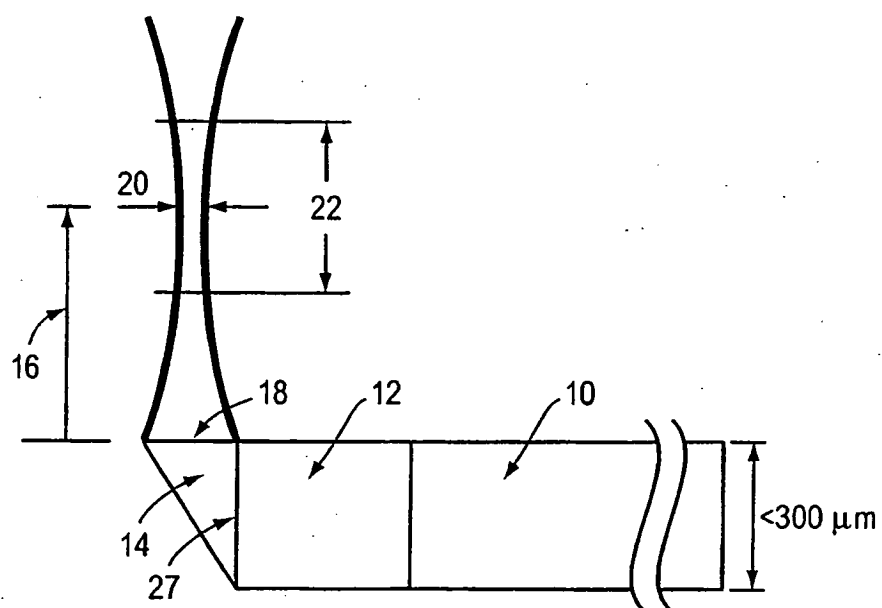


FIG. 1



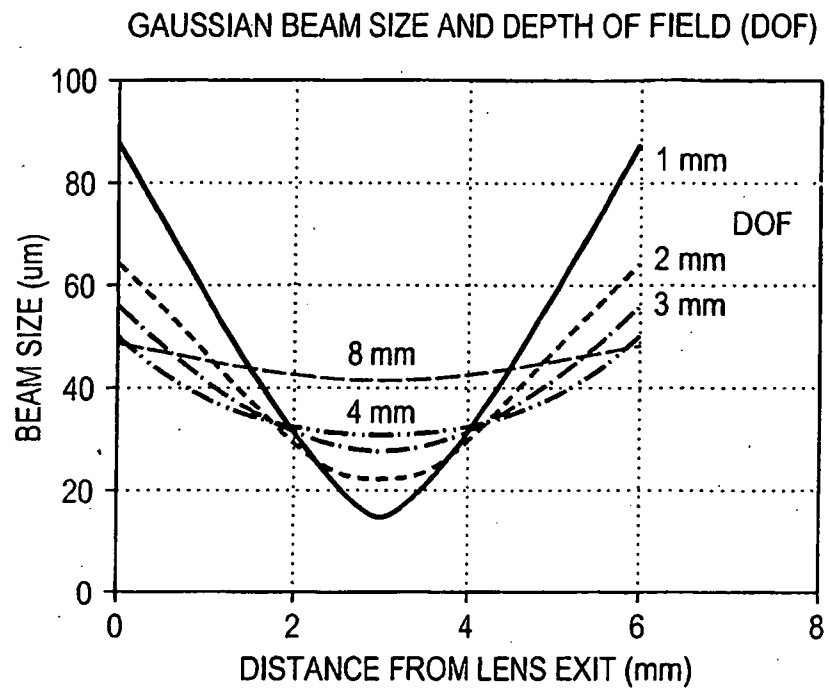


FIG. 2

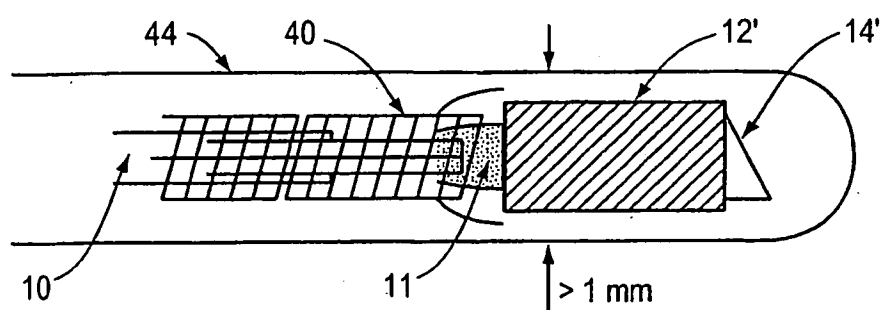


FIG. 3  
PRIOR ART

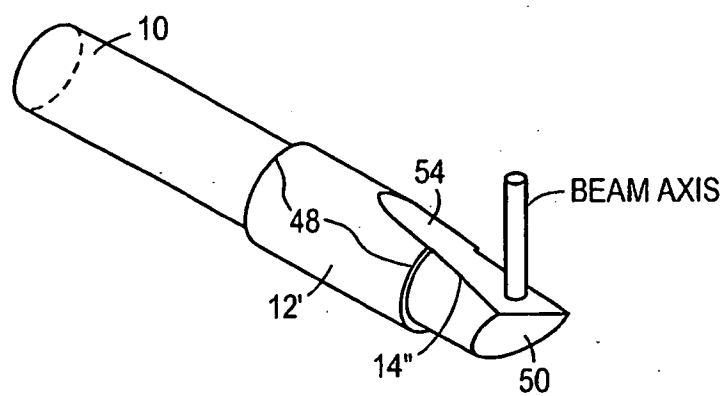


FIG. 4

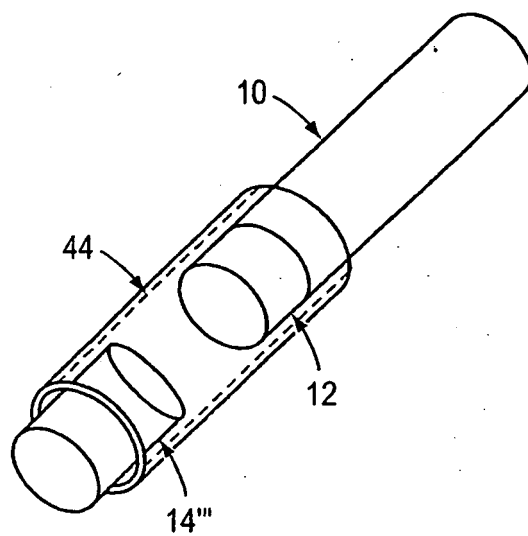


FIG. 5

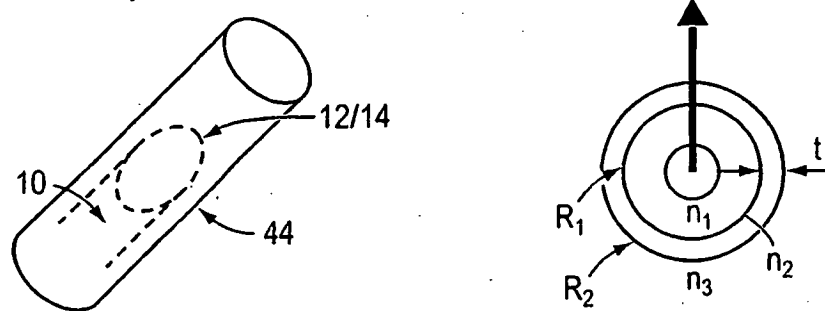


FIG. 6A

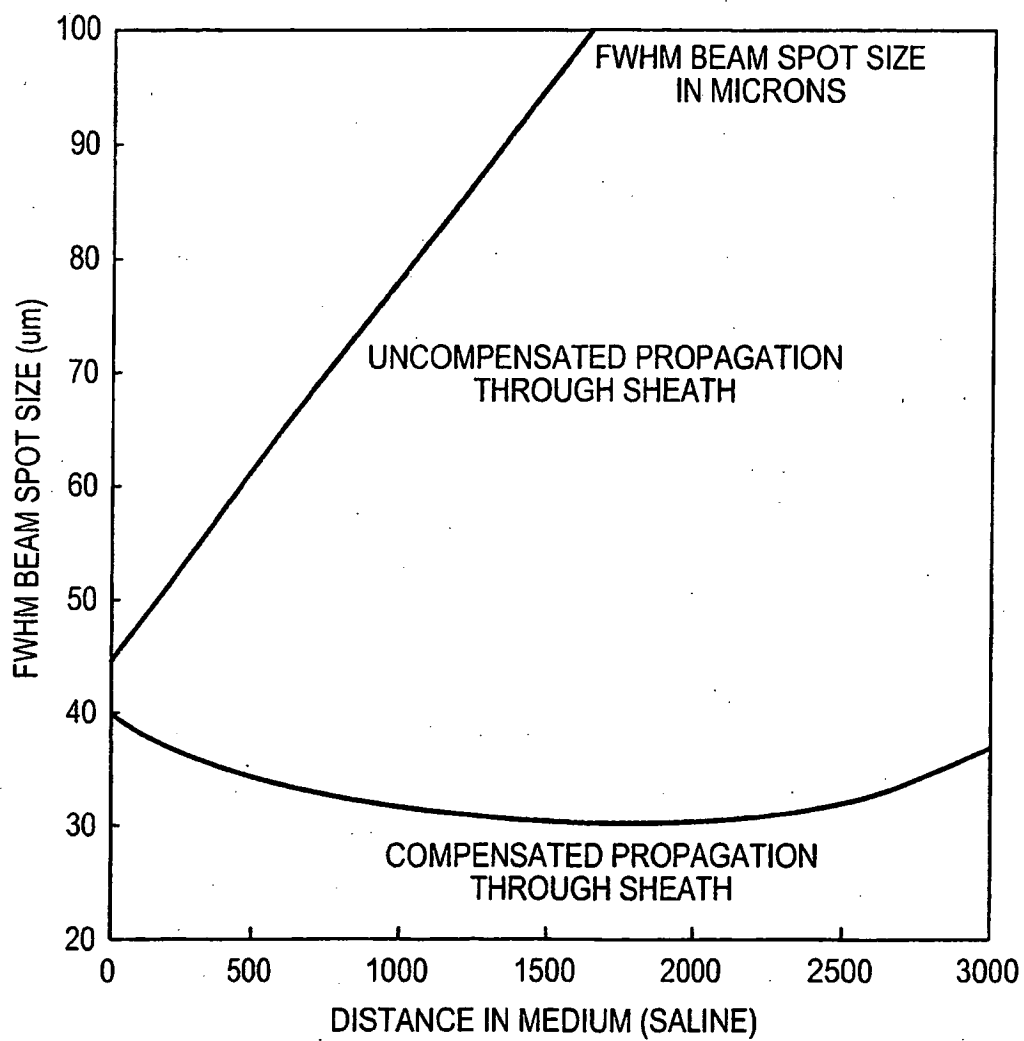


FIG. 6B

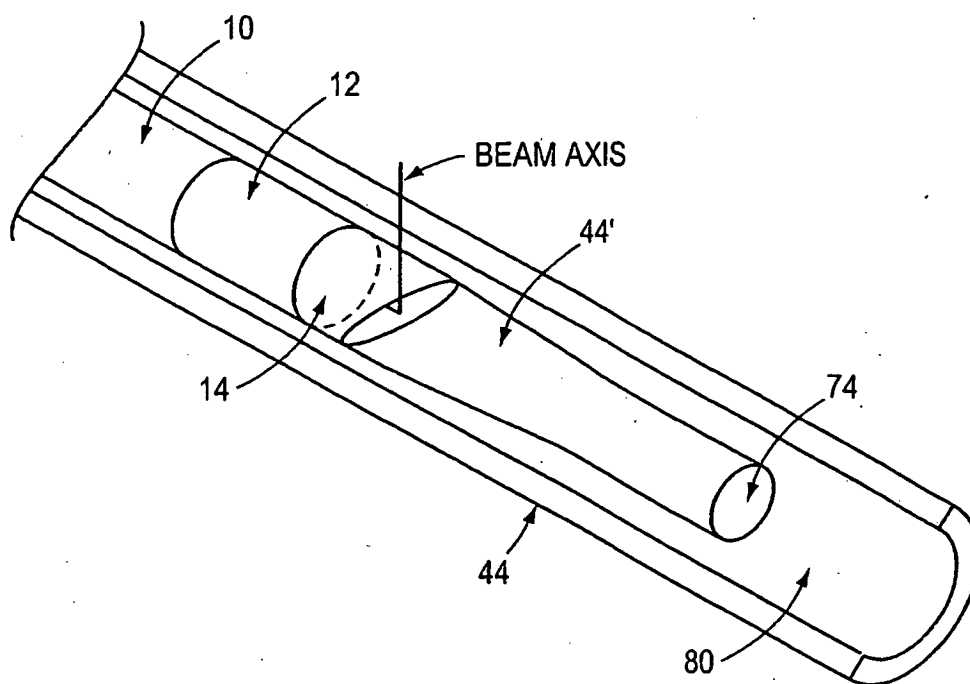


FIG. 7

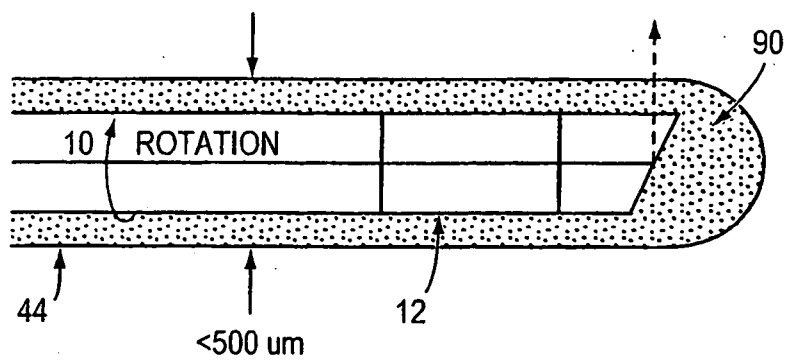


FIG. 8



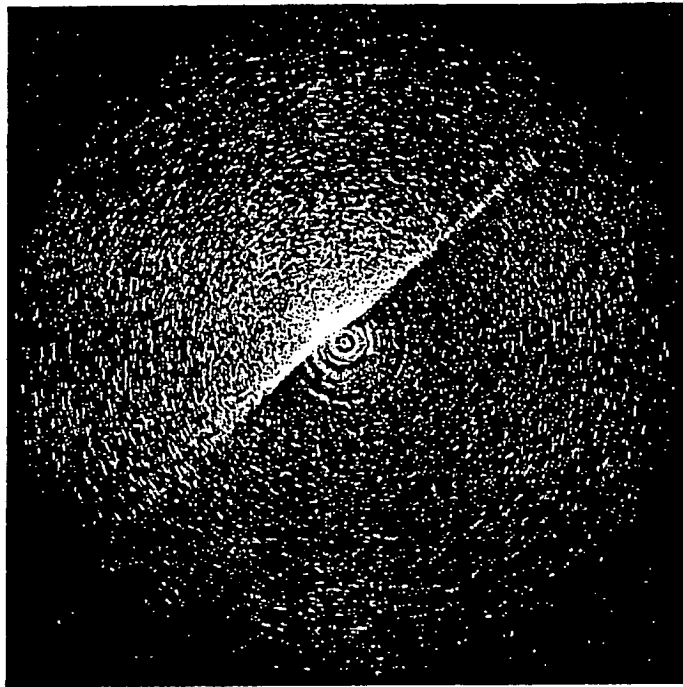


FIG. 9

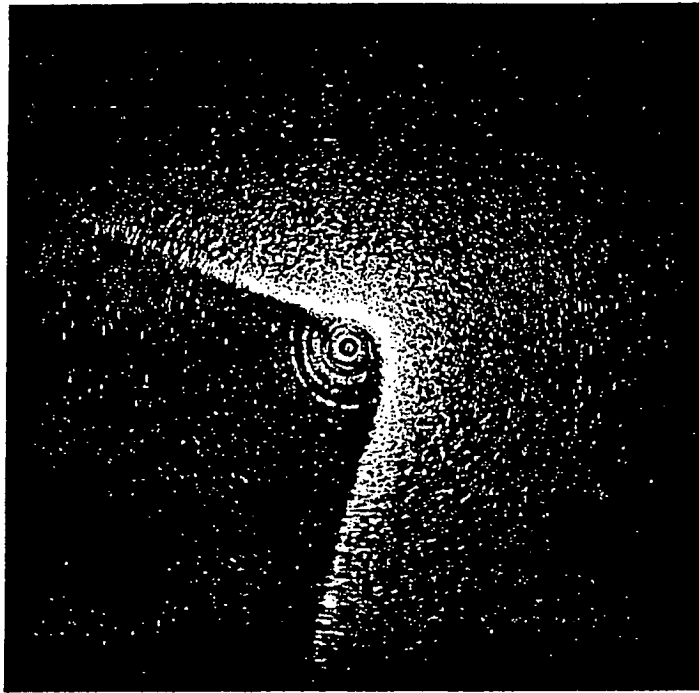


FIG. 10

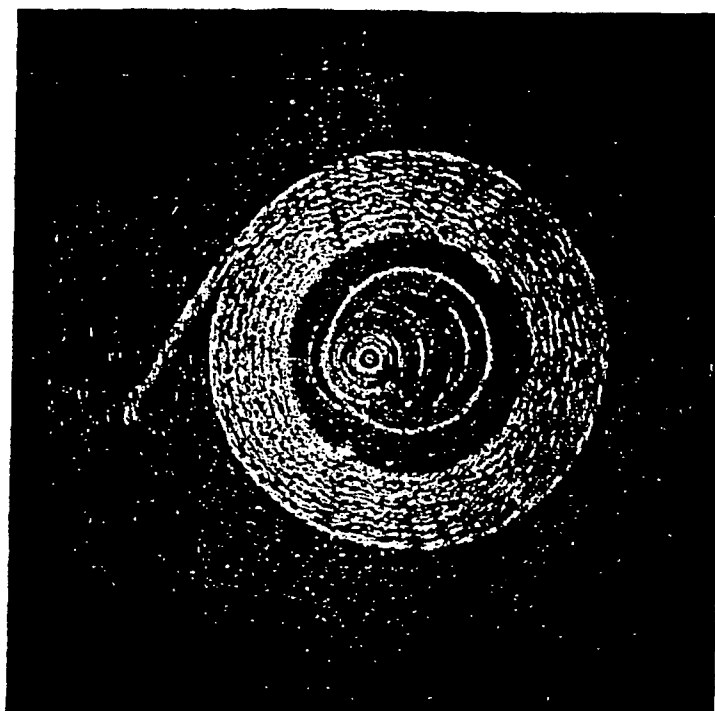


FIG. 11

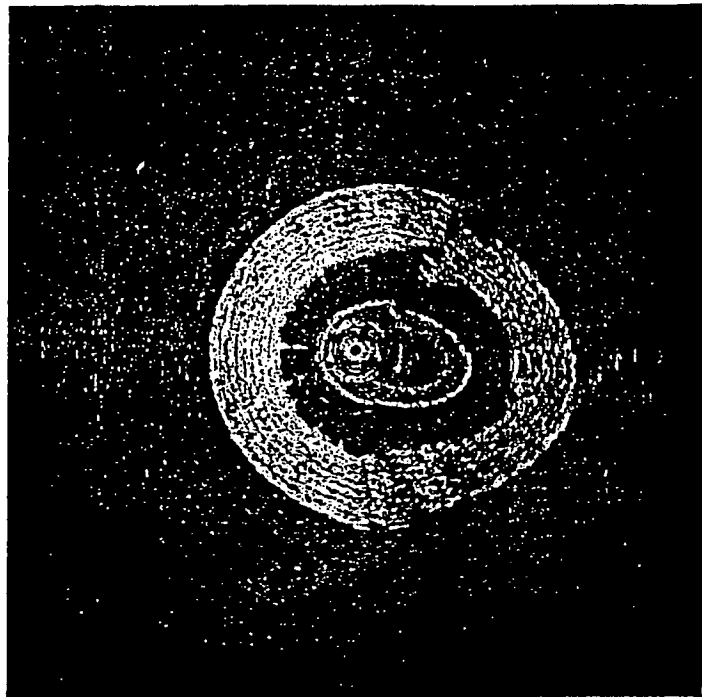


FIG. 12

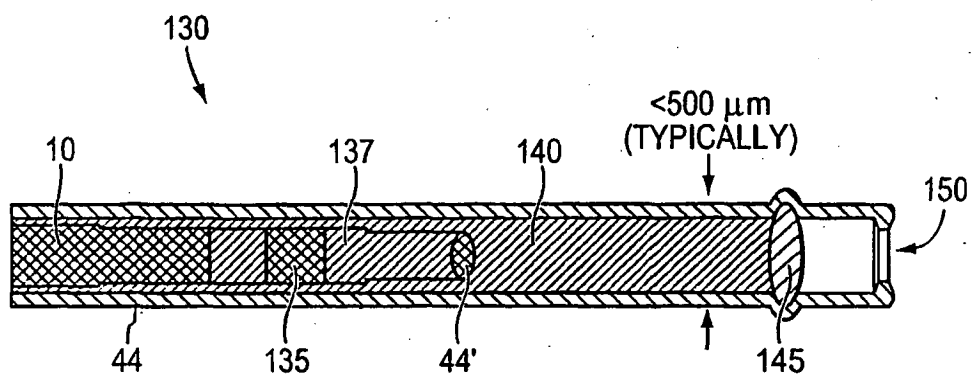


FIG. 13

**REFERENCES CITED IN THE DESCRIPTION**

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**Patent documents cited in the description**

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专利名称(译)	扫描微型光学探头，具有光学畸变校正和旋转控制		
公开(公告)号	<a href="#">EP1526800B1</a>	公开(公告)日	2008-09-10
申请号	EP2003771743	申请日	2003-07-23
[标]申请(专利权)人(译)	光学实验室成像公司		
申请(专利权)人(译)	LIGHTLAB成像，有限责任公司		
当前申请(专利权)人(译)	LIGHTLAB成像，有限责任公司		
[标]发明人	PETERSEN L CHRISTOPHER MCNAMARA EDWARD I LAMPORT RONALD B ATLAS MICHAEL SCHMITT JOSEPH M MAGNIN PAUL SWANSON ERIC A		
发明人	PETERSEN, L., CHRISTOPHER MCNAMARA, EDWARD, I. LAMPORT, RONALD, B. ATLAS, MICHAEL SCHMITT, JOSEPH, M. MAGNIN, PAUL SWANSON, ERIC, A.		
IPC分类号	A61B1/00 G02B23/24 A61B5/00 G02B26/10 G02B23/26		
CPC分类号	G02B23/2407 A61B5/0066 A61B5/0084 A61B5/6852 G01B9/0205 G01B9/02091		
优先权	10/205374 2002-07-25 US		
其他公开文献	EP1526800A1		
外部链接	<a href="#">Espacenet</a>		

#### 摘要(译)

本发明涉及一种包括护套的光学探针 ( 130 ) ;柔性的，可双向旋转的光学传输系统 ( 10,135,137 ) ，位于护套 ( 44 ) 内;和位于护套中的粘性阻尼液 ( 140 ) 。光传输系统能够传输，聚焦和收集预定波长范围的光。护套和粘性阻尼液体透过该光的至少一些波长。通常选择粘性流体的折射率以消除通过所述鞘传播而引起的光学效应。光学探针的直径小于500微米，用于扫描从长而高度柔软的纤维 ( 10 ) 到样品的光。在一个实施方案中，所述孔包括粘性阻尼液，其适于防止不均匀的旋转变形 ( NURD ) 。这种探针用于光学相干断层扫描 ( OCT ) 和其他 interferometric成像和测距系统，以及用于其他成像模态 ( 例如荧光 ) 或治疗光源的输送。

