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(72) Inventor: **FUJITA, Manabu**
Shibuya-ku, Tokyo 1510072 (JP)

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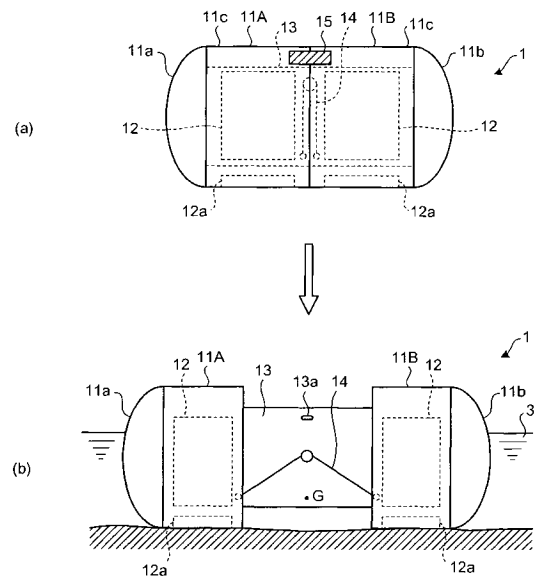
(74) Representative: **von Hellfeld, Axel**
Wuesthoff & Wuesthoff
Patent- und Rechtsanwälte
Schweigerstrasse 2
81541 München (DE)

(71) Applicant: **Olympus Medical Systems Corp.**
Tokyo 151-0072 (JP)

(54) **CAPSULE TYPE ENDOSCOPE, AND GASTER OBSERVATION METHOD**

(57) An object is to provide a capsule endoscope which allows an observation while floating on a liquid with a low specific gravity in total in an inside of a subject body without impairing an insertion property into the subject body even in including contents whose specific gravity is high. A shape memory alloy spring (14) presents a memorized shape of causing a volume changing unit (13) to be displaced to a storage position where the volume changing unit (13) is stored in a capsule casing (11) based on a body temperature of the subject body when the capsule endoscope is inserted into the subject body, so that a size not impairing the insertion property into the subject body can be realized. After the insertion into the subject body, water (3) is fed appropriately into the subject body and the shape memory alloy spring (14) then presents, based on a temperature of the water, a memorized shape of causing the volume changing unit (13) to be exposed to an outside of the capsule casing (11) and to be displaced to an exposure position where a volume of the casing is increased, so that the volume changing unit (13) can be displaced to the exposure position while absorbing an outer air into the inside from a ventilation hole (13a) in the subject body, the volume of the casing is increased, and an observation with the capsule endoscope floating on the water (3) can be performed due to a low specific gravity in total even in including contents (12) whose specific gravity is high.

FIG.2



Description

TECHNICAL FIELD

[0001] The present invention relates to a capsule endoscope which allows an observation of an inside of a subject body in a state of floating on a liquid fed into the subject body and an intra-stomach observing method.

BACKGROUND ART

[0002] Recently, a capsule endoscope including an imaging function and a wireless communication function has appeared in the field of endoscopes. The capsule endoscope has a configuration of travelling inside of organs such as the esophagus, the stomach, and the small intestine (inside of a body cavity) according to their peristalsis and of sequentially capturing images by using the imaging function during an observation period which starts when the capsule endoscope is swallowed for the purpose of an observation (examination) from a mouth of a test subject as a subject body (human body) and ends when it is naturally excreted from a living body of the test subject.

[0003] Here, a technology of making a capsule endoscope, whose specific gravity is set to not more than one and which is swallowed with a liquid (drinking water), float on the liquid inside the stomach to which the liquid is fed, and enabling an observation of a wall of the stomach is disclosed in Patent Document 1.

[0004]

Patent Document 1: International Publication Pamphlet No. 02/95351 (PCT National Publication No. 2004-529718)

Patent Document 2: Japanese Patent Application Laid-Open No. H10-213384

Patent Document 3: Japanese Patent Application Laid-Open No. 2004-305635

DISCLOSURE OF INVENTION

PROBLEM TO BE SOLVED BY THE INVENTION

[0005] However, the capsule endoscope houses contents including an imaging unit, an illumination unit, a wireless communication unit, a battery, and the like in a capsule casing, and a specific gravity of the contents is usually not less than one in most cases. Therefore, it is necessary to form the capsule casing in a size larger than the required size to make the specific gravity of the capsule endoscope not more than one, so that the capsule endoscope has a problem of having a difficulty in swallowing from an oral cavity of the test subject as shown in Patent Document 1.

[0006] The present invention has been achieved in view of the foregoing and an object of the present invention is to provide: a capsule endoscope which allows,

with a low specific gravity in total in a subject body, an observation in a state of floating on a liquid without impairing a property of an insertion into the subject body even when a specific gravity of contents of the capsule endoscope is high; and an intra-stomach observing method.

MEANS FOR SOLVING PROBLEM

[0007] To solve the problem described above and achieve the object, a capsule endoscope according to the present invention includes: a capsule casing which contains therein contents including an imaging unit and is inserted into an inside of a subject body; a hollow volume changing unit which is connected to the capsule casing in an air-tight state, and changes a connection position with the capsule casing to change a volume of the capsule casing; and an actuator which is connected to the capsule casing and changes the connection position.

[0008] In the capsule endoscope according to the present invention in the invention described above, the actuator operates based on a change in a temperature of an outside of the capsule casing.

[0009] In the capsule endoscope according to the present invention in the invention described above, the actuator is a shape memory alloy spring.

[0010] In the capsule endoscope according to the present invention in the invention described above, the connection position is a storage position where the volume of the capsule casing is minimum and an exposure position where the volume of the capsule casing is not minimum, a specific gravity of the capsule casing with respect to a water is not less than one at the storage position, and a specific gravity of the capsule casing with respect to the water is less than one at the exposure position.

[0011] In the capsule endoscope according to the present invention in the invention described above, the volume changing unit has a rigid body of a cylindrical shape and is connected to the capsule casing to be freely movable inward and outward with respect to the capsule casing.

[0012] In the capsule endoscope according to the present invention in the invention described above, the volume changing unit is formed of a soft member of an accordion shape and connected to be freely stretchable inward and outward with respect to the capsule casing.

[0013] In the capsule endoscope according to the present invention in the invention described above, the capsule casing is constituted by divided two casings, and the volume changing unit is connected between the two casings.

[0014] In the capsule endoscope according to the present invention in the invention described above, each of the two casings has a bottomed shape.

[0015] In the capsule endoscope according to the present invention in the invention described above, the

actuator is formed by a shape memory alloy spring which causes the volume changing unit to be displaced from the storage position to the exposure position at a temperature not more than a predetermined temperature.

[0016] The capsule endoscope according to the present invention in the invention described above further includes a sealing member which is formed of a material that dissolves when inserted into the subject body and retains the volume changing unit at the storage position against a memorized shape, which causes the displacement to the exposure position, of the shape memory alloy spring.

[0017] In the capsule endoscope according to the present invention in the invention described above, a ventilation hole is formed in the volume changing unit.

[0018] In the capsule endoscope according to the present invention in the invention described above, a center of gravity of the capsule endoscope is set at a position where the ventilation hole is oriented upward with respect to a gravity direction.

[0019] In the capsule endoscope according to the present invention in the invention described above, a sheet member which allows only a gas to pass through is attached to the ventilation hole.

[0020] An intra-stomach observing method includes the steps of: making a capsule endoscope before an examination at a predetermined temperature; making a subject swallow the capsule endoscope; making the subject take in a water whose temperature is lower than the predetermined temperature; increasing a volume of the capsule endoscope; and observing an inside of a stomach by the capsule endoscope.

[0021] An intra-stomach observing method includes the steps of: storing a capsule endoscope under an environment of a predetermined temperature; making a subject swallow the capsule endoscope; making the subject take in a water whose temperature is lower than the predetermined temperature; increasing a volume of the capsule endoscope; and observing an inside of a stomach by the capsule endoscope.

[0022] In the intra-stomach observing method according to the present invention in the invention described above, the predetermined temperature is about 36°C to 40°C and the temperature lower than the predetermined temperature is about 25°C.

[0023] An intra-stomach observing method includes the steps of: making a subject swallow the capsule endoscope; making the subject take in a water of a predetermined temperature and filling an inside of a stomach with a liquid; increasing a volume of the capsule endoscope; and observing the inside of the stomach by the capsule endoscope.

EFFECT OF THE INVENTION

[0024] A capsule endoscope and an intra-stomach observing method according to the present invention have advantageous effects that since an actuator changes a

connecting position of a volume changing unit with a capsule casing based on a body temperature of a subject body when the capsule endoscope is inserted into the subject body to change a volume of the casing, a volume condition which does not impair a property of an insertion into the subject body can be realized, when a liquid is arbitrarily fed into the subject body after the capsule endoscope is inserted into the subject body, the actuator changes the connecting position of the volume changing unit with the capsule casing based on a temperature of the liquid to change and increase the casing volume, and thereby a total specific gravity can be reduced and an observation can be performed with the capsule endoscope floating on the liquid even when a specific gravity of contents is high.

BRIEF DESCRIPTION OF DRAWINGS

[0025]

FIG. 1 is a view showing an observation of an inside of a subject body by using a capsule endoscope according to a first embodiment.

FIG. 2 is a schematic side view of examples of constitutions respectively before and after a volume increase of the capsule endoscope according to the first embodiment.

FIG. 3 is a schematic side view of examples of constitutions respectively before and after a volume increase of a capsule endoscope according to a second embodiment.

EXPLANATIONS OF LETTERS OR NUMERALS

[0026]

1	Capsule endoscope
2	Subject body
3	Water
11	Capsule casing
11A, 11B	Casing
12	Contents
13	Volume changing unit
13a	Ventilation hole
14	Shape memory alloy spring
15	Sealing member
16	Volume changing unit
16a	Ventilation hole

BEST MODE(S) FOR CARRYING OUT THE INVENTION

[0027] A capsule endoscope according to best modes (s) for carrying out the invention will be explained below with reference to the accompanying drawings.

First Embodiment

[0028] FIG. 1 is a view showing an observation of an inside of a subject body by using a capsule endoscope according to a first embodiment and FIG. 2 is a schematic side view of examples of constitutions respectively before and after a volume increase of the capsule endoscope according to the first embodiment.

[0029] As shown in FIG. 1, a capsule endoscope 1 according to the first embodiment is inserted into a subject body 2 by being swallowed from an oral cavity 2a of the subject body 2, and images and observes a stomach wall as a target site by floating on a surface of water 3 whose specific gravity is one in a stomach 2b to which a liquid, for example, the water 3 is fed. A numeral 4 denotes a receiver which receives image data wirelessly transmitted from the capsule endoscope 1 having an imaging function and a wireless communication function. The receiver 4 includes a receiving antenna 4a such as a loop antenna which is attached on an outside surface of the subject body 2, and receives the image data and the like wirelessly transmitted from the capsule endoscope 1 via the receiving antenna 4a.

[0030] Here, the capsule endoscope 1 according to the first embodiment is explained by taking, as one example, an application to a compound-eye capsule endoscope which can capture images at both sides in a longitudinal axis direction of the capsule, and includes a capsule casing 11 whose size is small enough to be swallowed from the oral cavity 2a of the subject body 2 and contents 12 including an imaging unit, an illumination unit, a wireless communication unit, a substrate member, a battery, and the like which are embedded in the capsule casing 11.

[0031] The capsule casing 11 includes semispherical, transparent or translucent head covers 11a and 11b and a body cover 11c which has a cylindrical shape and is formed of a colored material which does not allow visible light to pass through. The capsule casing 11 according to the embodiment, since the body cover 11c is divided into two pieces in the axial direction, is formed by separated two casings, that is, a first casing 11A and a second casing 11B. Both of the divided surfaces of the divided body cover 11c are configured to be bottomed and to seal insides of the casings 11A and 11B in a liquid-tight manner, respectively.

[0032] The illumination unit in the contents 12 is constituted by a light emitting element such as an LED which emits illumination light for illuminating a site to be imaged in the subject body 2 via the head covers 11a and 11b. The imaging unit in the contents 12 includes an imaging element such as a CCD and a CMOS sensor which receives reflection light by the illumination light via the head covers 11a and 11b and captures images of the site to be imaged, an image forming lens, and the like. The contents 12 are separated and embedded into the two casings 11A and 11B respectively to fit a symmetrical structure of the compound-eye capsule endoscope, and each

casing includes contents whose specific gravity in total is not less than one and higher than that of the water 3.

[0033] In addition to the configuration described above, the capsule endoscope 1 according to the embodiment includes a volume changing unit 13 and a shape memory alloy spring 14 as an actuator which activates the volume changing unit 13. The volume changing unit 13 is schematically a tank having a hollow rigid body of a cylindrical shape, arranged between the casings 11A and 11B with respect to the volume changing unit 13, and connected to be freely movable inward and outward with respect to the casings 11A and 11B along the longitudinal axis direction with an air-tight state with respect to the bottomed parts of the casings 11A and 11B maintained. By this, the volume changing unit 13 can be displaced to a storage position where the volume changing unit 13 is stored half and half by the casings 11A and 11B as shown at (a) in FIG. 2 and to an exposure position where the volume changing unit 13 is exposed outward from the casings 11A and 11B as shown at (b) in FIG. 2 to increase a total casing volume of the capsule endoscope 1 and make the specific gravity not more than one. To perform the displacement between the storage position and the exposure position, the volume changing unit 13 is provided, at a center part on a side surface, with one ventilation hole 13a through which an outer air is taken in and an inner air is discharged. Here, a heavy content in the contents 12, for example, a battery 12a is arranged on an inner wall opposite to the ventilation hole 13a in the casings 11A and 11B, so that a center of gravity G of the capsule endoscope 1 is set at a position where the ventilation hole 13a is oriented to an upper direction when the capsule endoscope 1 lies on its side.

[0034] The shape memory alloy spring 14, both ends thereof being connected to freely turn with respect to the bottomed parts of the casings 11A and 11B, causes the volume changing unit 13 to be displaced to the storage position by presenting a memorized shape of a folded shape as shown at (a) in FIG. 2 at a temperature around 36°C to 40°C corresponding to a body temperature of the subject body 2 and causes the volume changing unit 13 to be displaced to the exposure position by presenting a memorized shape of an expanded open shape as shown at (b) in FIG. 2 at a temperature around 25°C corresponding to a temperature of the water 3 fed into the subject body 2. The shape memory alloy spring 14 is arranged to the side of the center of gravity G position away from the side of the ventilation hole 13a position.

[0035] Besides, the capsule endoscope 1 according to the embodiment includes, on a front surface, a sealing member 15 which seals the casings 11A and 11B to be a connected state so that the volume changing unit 13 is maintained at the storage position against the memorized shape of the shape memory alloy spring 14 that causes the displacement to the exposure position under a condition of a normal temperature before the capsule endoscope 1 is swallowed by the subject body 2. The sealing member 15 is formed of an edible material such

as a wafer which dissolves by stomach juices and the like by being inserted into the subject body 15.

[0036] In this configuration, since the casings 11A and 11B are sealed by the sealing member 15, the volume changing unit 13 is maintained at the storage position against the memorized shape of the shape memory alloy spring 14 though the capsule endoscope 1 before starting an examination is under the condition of the normal temperature and the shape memory alloy spring 14 will try to present the memorized shape of the expanded open shape when the normal temperature is, for example, at about 25°C. By this, the capsule endoscope 1 can be maintained in a size of the state shown at (a) in FIG. 2 in which the casings 11A and 11B are coupled as one unit without causing the volume changing unit 13 to be exposed. The size is a normal capsule size and does not impair the swallowing performance from the oral cavity 2a.

[0037] At a time of starting the examination, the capsule endoscope 1 in the state as shown at (a) in FIG. 2 is swallowed from the oral cavity 2a and inserted into the stomach 2b. Upon the insertion into the subject body 2, the sealing member 15 dissolves by the stomach juices and the like and the sealed state is released. On this occasion, the capsule endoscope 1 is already inserted into the subject body 2 and subjected to a body temperature environment, the shape memory alloy spring 14 presents the memorized shape of the folded shape and therefore the volume changing unit 13 is maintained at the storage position even when the sealed state is released. By this, the capsule endoscope 1 can be maintained in the size of the state shown at (a) in FIG. 2 in which the casings 11A and 11B are coupled as one unit without causing the volume changing unit 13 to be exposed. In this state, the specific gravity of the capsule endoscope 1 is not less than one.

[0038] Thereafter, when the time is right, the water 3 at 25°C is taken little by little to be fed into the stomach 2b. On this occasion, though the specific gravity of the capsule endoscope 1 is not less than one and the capsule endoscope 1 does not float on a surface of the water 3 fed into the stomach 2b, the capsule endoscope 1 becomes a state of lying on its side in which the ventilation hole 13a is oriented upward according to the position of the center of gravity G. Then, the shape memory alloy spring 14 of the lying capsule endoscope 1 comes to be present in the fed water 3 (the water 3 is assumed to be an amount not causing the capsule endoscope 1 to go under the water as shown at (b) in FIG. 2 at this point) and performs the displacement to present the memorized shape of the expanded open shape from the folded shape according to the temperature (25°C) of the water 3. In response to the displacement to the expanded open shape of the shape memory alloy spring 14, the casings 11A and 11B are displaced to a direction of becoming away from each other, and the volume changing unit 13 connected between the casings 11A and 11B makes the displacement to the exposure position as shown at (b) in

FIG. 2 while absorbing an air through a cylinder effect from the ventilation hole 13a present at a position oriented to an upper direction and in the air in the stomach 2b. Due to the displacement of the volume changing unit 13 to the exposure position, the casing volume of the capsule endoscope 1 increases to be a state where the specific gravity is not more than one.

[0039] When an appropriate amount of the water 3 is further fed into the stomach 2b under this condition, the capsule endoscope 1 whose specific gravity is lowered to be not more than one can image and observe the wall of the stomach while floating on the surface of the fed water 3 as shown in FIG. 1.

[0040] After the examination is completed, the water 3 is discharged from the inside of the stomach 2b to a side of the small intestine. By this, the capsule endoscope 1 remaining in the stomach 2b is subjected to the environment of the body temperature of the subject body 2 and the shape memory alloy spring 14 makes the displacement from the expanded open shape to a direction to be folded to present the memorized shape of the bent shape. In response to this folding displacement of the shape memory alloy spring 14, the separated casings 11A and 11B are also displaced to a direction to be in contact with each other and the volume changing unit 13 connected between the casings 11A and 11B also makes the displacement to the storage position as shown at (a) in FIG. 2 while discharging the inner air from the ventilation hole 13a. By the displacement of the volume changing unit 13 to the storage position, the size of the capsule endoscope 1 returns to a normal capsule size. Then, the capsule endoscope 1 moves to the side of the small intestine according to the subsequent peristalsis as usual and is finally excreted to an outside of the subject body 2.

[0041] As described, since the shape memory alloy spring 14 presents the memorized shape of causing the volume changing unit 13 to be displaced to the storage position where the volume changing unit 13 is stored in the capsule endoscope 1 based on the body temperature of the subject body 2 when the capsule endoscope 1 according to the embodiment is inserted into the subject body 2, a volume condition which does not impair the insertion property into the subject body 2 can be realized. Besides, since the shape memory alloy spring 14 presents the memorized shape of causing the volume changing unit 13 to be displaced to the exposure position where the volume changing unit 13 is exposed to the outside of the casing of the capsule endoscope 1 and the casing volume is increased based on the temperature of the water 3 fed appropriately into the subject body 2 after the capsule endoscope 1 is inserted into the subject body 2, the volume changing unit 13 makes the displacement to the exposure position to increase the casing volume while absorbing the outer air into the inside through the ventilation hole 13a in the subject body 2, so that an observation in a state where the capsule endoscope 1 with a low specific gravity in total floats on the water 3 can be performed even when the specific gravity of the

contents 12 is high.

[0042] In addition, a common linear actuator may be provided instead of the shape memory alloy spring 14. A temperature sensor may further be equipped for controlling an operation of the linear actuator based on a temperature. By this, the volume changing unit 13 can be controlled with a greater flexibility.

Second Embodiment

[0043] FIG. 3 is a schematic side view of examples of constitutions respectively before and after a volume increase of a capsule endoscope according to a second embodiment. The same part as shown in the first embodiment is shown by using the same reference symbol.

[0044] In the second embodiment, a volume changing unit 16 which is a tank formed of a hollow soft member of an accordion shape is provided instead of the volume changing unit 13 which is a tank having a rigid body of a cylindrical shape. The volume changing unit 16 is arranged between the casings 11A and 11B with respect to the capsule casing 11 and connected, to be stretchable along the longitudinal axis direction, to the bottomed parts of the casings 11A and 11B with an air-tight state maintained. By this, the volume changing unit 16 can be displaced to a storage position where the volume changing unit 16 shrinks to be stored between the casings 11A and 11B as shown at (a) in FIG. 3 and to an exposure position where the volume changing unit 16 stretches out to be exposed outward from the casings 11A and 11B as shown at (b) in FIG. 3 to increase a total casing volume of the capsule endoscope 1 and make the specific gravity not more than one. To perform the displacement between the storage position and the exposure position, the volume changing unit 16 is provided, at a center part on a side surface, with one ventilation hole 16a through which an outer air is taken in and an inner air is discharged. Other constituents are the same as those in the first embodiment.

[0045] In this configuration, since the casings 11A and 11B are sealed by the sealing member 15, the volume changing unit 16 is maintained at the storage position against the memorized shape of the shape memory alloy spring 14 though the capsule endoscope 1 before starting an examination is under the condition of the normal temperature and the shape memory alloy spring 14 will try to present the memorized shape of the expanded open shape when the normal temperature is, for example, at about 25°C. By this, the capsule endoscope 1 can be maintained in a size of the state shown at (a) in FIG. 3 in which the casings 11A and 11B are coupled as one unit without causing the volume changing unit 16 to be exposed. The size is a normal capsule size and does not impair the swallowing performance from the oral cavity 2a.

[0046] At a time of starting the examination, the capsule endoscope 1 in the state as shown at (a) in FIG. 3 is swallowed from the oral cavity 2a and inserted into the

stomach 2b. Upon the insertion into the subject body 2, the sealing member 15 dissolves by the stomach juices and the like and the sealed state is released. On this occasion, the capsule endoscope 1 is already inserted into the subject body 2 and subjected to a body temperature environment, the shape memory alloy spring 14 presents the memorized shape of the folded shape and the volume changing unit 16 is maintained at the shrinking storage position even when the sealed state is released. By this, the capsule endoscope 1 can be maintained in the size of the state shown at (a) in FIG. 3 in which the casings 11A and 11B are coupled as one unit without causing the volume changing unit 16 to be exposed. In this state, the specific gravity of the capsule endoscope 1 is not less than one.

[0047] Thereafter, when the time is right, the water 3 at 25°C is taken little by little to be fed into the stomach 2b. On this occasion, though the specific gravity of the capsule endoscope 1 is not less than one and the capsule endoscope 1 does not float on a surface of the water 3 fed into the stomach 2b, the capsule endoscope 1 becomes a state of lying on its side in which the ventilation hole 16a is oriented upward according to the position of the center of gravity G. Then, the shape memory alloy spring 14 of the lying capsule endoscope 1 comes to be present in the fed water 3 (the water 3 is assumed to be an amount not causing the capsule endoscope 1 to go under the water as shown at (b) in FIG. 3 at this point) and performs the displacement to present the memorized shape of the expanded open shape from the folded shape according to the temperature (25°C) of the water 3. In response to the displacement to the expanded open shape of the shape memory alloy spring 14, the casings 11A and 11B are displaced to a direction of becoming away from each other and the volume changing unit 16 connected between the casings 11A and 11B also makes the displacement to the exposure position as shown at (b) in FIG. 3 while expanding by absorbing an outer air from the ventilation hole 16a present at a position oriented to an upper direction and in the air in the stomach 2b. Due to the displacement of the volume changing unit 16 to the exposure position according to the stretching, the casing volume of the capsule endoscope 1 increases to be a state where the specific gravity is not more than one.

[0048] When an appropriate amount of the water 3 is further fed into the stomach 2b under this condition, the capsule endoscope 1 whose specific gravity is lowered to be not more than one can image and observe the wall of the stomach while floating on the surface of the fed water 3 as shown in FIG. 1.

[0049] After the examination is completed, the water 3 is discharged from the inside of the stomach 2b to a side of the small intestine. By this, the capsule endoscope 1 remaining in the stomach 2b is subjected to the environment of the body temperature of the subject body 2 and the shape memory alloy spring 14 makes the displacement from the expanded open shape to a direction to be folded and present the memorized shape of the

bent shape. In response to this folding displacement of the shape memory alloy spring 14, the separated casings 11A and 11B are also displaced to a direction to be in contact with each other and the volume changing unit 16 connected between the casings 11A and 11B also makes the displacement to the storage position as shown at (a) in FIG. 3 while discharging the inner air from the ventilation hole 16a. By the displacement of the volume changing unit 16 to the storage position according to the shrinking, the size of the capsule endoscope 1 returns to a normal capsule size. Then, the capsule endoscope 1 moves to the side of the small intestine according to the subsequent peristalsis as usual and is finally excreted to an outside of the subject body 2. Hence, the case of the second embodiment shows the same advantageous effects as the case of the first embodiment.

[0050] Though the sealing by the sealing member 15 is adopted not to cause the capsule endoscope 1 before being swallowed to be displaced to a state of an increased volume in the first and the second embodiments, the capsule endoscope 1 may be, for example, stored under an environment of a constant temperature until a time right before being swallowed, so that the sealing member 15 may be eliminated. Or more specifically, the subject body 1 may hold the capsule endoscope 1 by hand and the like right before the swallowing to keep the capsule endoscope 1 under the body temperature environment, so that the sealing member 15 may be eliminated.

[0051] Besides, when there is a possibility that the water 3 comes into the inside of the volume changing units 13 and 16 respectively through the ventilation holes 13a and 16a due to a rotation and the like of the capsule endoscope 1, a sheet member such as a Gore-Tex (registered trademark) which allows only a gas to path through may be attached onto the ventilation holes 13a and 16a respectively of the volume changing units 13 and 16 to prevent an intrusion of the water 3. In addition, the displacement operation to the exposure position may be configured to be performed through an adjustment based on an inner pressure of the capsule endoscope 1 without providing the ventilation holes 13a and 16a. By this, the structure can be simplified.

[0052] Moreover, though the explanation in the first and the second embodiments is made as an application example to the compound-eye capsule endoscope, a single-eye capsule endoscope is similarly applicable. Specifically, in the case of using the single-eye capsule endoscope, the capsule casing may not be divided into two pieces like the casings 11A and 11B, a volume changing unit may be connected, to be displaced at an air-tight state, to one end which is not the side of capturing images, and a shape memory alloy spring connecting a capsule casing and a distal end side of the volume changing unit may be provided.

INDUSTRIAL APPLICABILITY

[0053] As described, a capsule endoscope and an intra-stomach observing method according to the present invention are useful for a case of observing an inside of a subject body in a state of floating on a liquid fed into the subject body, and specifically suitable for observing a stomach wall with the capsule endoscope floating inside the stomach to which the liquid is fed.

Claims

1. A capsule endoscope, comprising:
 - a capsule casing which contains therein contents including an imaging unit and is inserted into an inside of a subject body;
 - a hollow volume changing unit which is connected to the capsule casing in an air-tight state, and changes a connection position with the capsule casing to change a volume of the capsule casing; and
 - an actuator which is connected to the capsule casing and changes the connection position.
2. The capsule endoscope according to claim 1, wherein the actuator operates based on a change in a temperature of an outside of the capsule casing.
3. The capsule endoscope according to claim 1, wherein the actuator is a shape memory alloy spring.
4. The capsule endoscope according to claim 1, wherein the connection position is a storage position where the volume of the capsule casing is minimum and an exposure position where the volume of the capsule casing is not minimum, a specific gravity of the capsule casing with respect to a water is not less than one at the storage position, and a specific gravity of the capsule casing with respect to the water is less than one at the exposure position.
5. The capsule endoscope according to claim 1, wherein the volume changing unit has a rigid body of a cylindrical shape and is connected to the capsule casing to be freely movable inward and outward with respect to the capsule casing.
6. The capsule endoscope according to claim 1, wherein the volume changing unit is formed of a soft member of an accordion shape and connected to be freely stretchable inward and outward with respect to the capsule casing.
7. The capsule endoscope according to claim 1, where-

- in
the capsule casing is constituted by divided two casings, and
the volume changing unit is connected between the two casings. 5
8. The capsule endoscope according to claim 7, wherein each of the two casings has a bottomed shape.
9. The capsule endoscope according to claim 4, wherein the actuator is formed by a shape memory alloy spring which causes the volume changing unit to be displaced from the storage position to the exposure position at a temperature not more than a predetermined temperature. 10
10. The capsule endoscope according to claim 9, further comprising a sealing member which is formed of a material that dissolves when inserted into the subject body and retains the volume changing unit at the storage position against a memorized shape, which causes the displacement to the exposure position, of the shape memory alloy spring. 20
11. The capsule endoscope according to claim 1, wherein a ventilation hole is formed in the volume changing unit. 25
12. The capsule endoscope according to claim 11, wherein a center of gravity of the capsule endoscope is set at a position where the ventilation hole is oriented upward with respect to a gravity direction. 30
13. The capsule endoscope according to claim 11, wherein a sheet member which allows only a gas to pass through is attached to the ventilation hole. 35
14. An intra-stomach observing method, comprising the steps of: 40
- making a capsule endoscope before an examination at a predetermined temperature;
 - making a subject swallow the capsule endoscope;
 - making the subject take in a water whose temperature is lower than the predetermined temperature; 45
 - increasing a volume of the capsule endoscope;
 - and
 - observing an inside of a stomach by the capsule endoscope. 50
15. An intra-stomach observing method, comprising the steps of: 55
- storing a capsule endoscope under an environment of a predetermined temperature;
 - making a subject swallow the capsule endo-
- scope;
making the subject take in a water whose temperature is lower than the predetermined temperature;
increasing a volume of the capsule endoscope;
and
observing an inside of a stomach by the capsule endoscope.
16. The intra-stomach observing method according to claim 14 or 15, wherein the predetermined temperature is about 36°C to 40°C and the temperature lower than the predetermined temperature is about 25°C.
17. An intra-stomach observing method, comprising the steps of:
- making a subject swallow the capsule endoscope;
 - making the subject take in a water of the predetermined temperature and filling an inside of a stomach with a liquid;
 - increasing a volume of the capsule endoscope;
 - and
 - observing the inside of the stomach by the capsule endoscope.

FIG.1

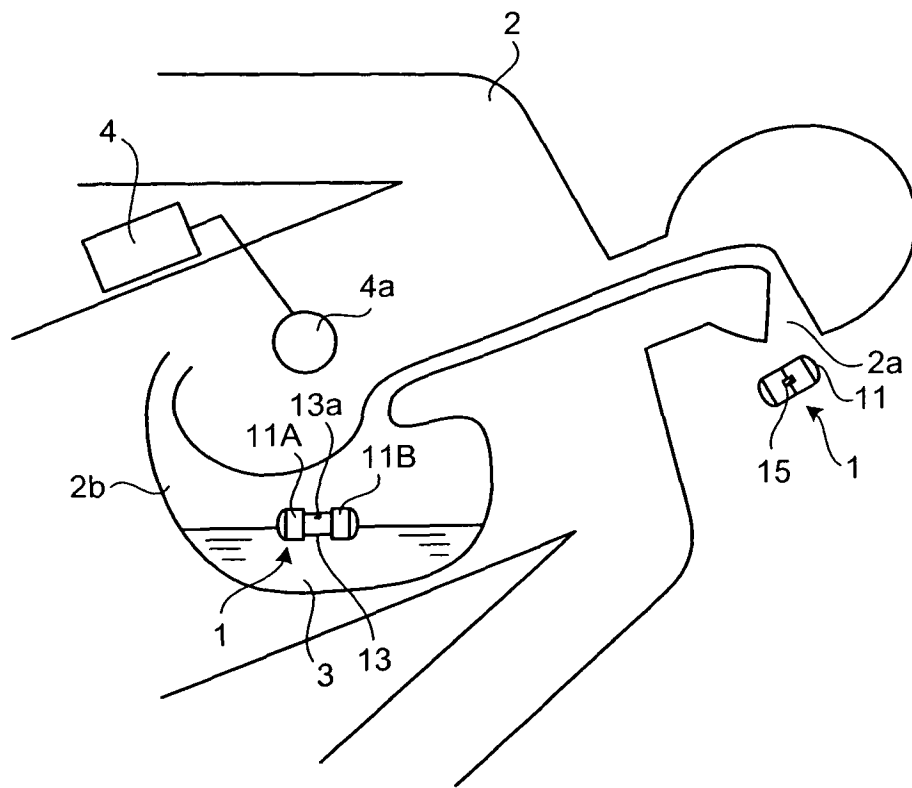


FIG.2

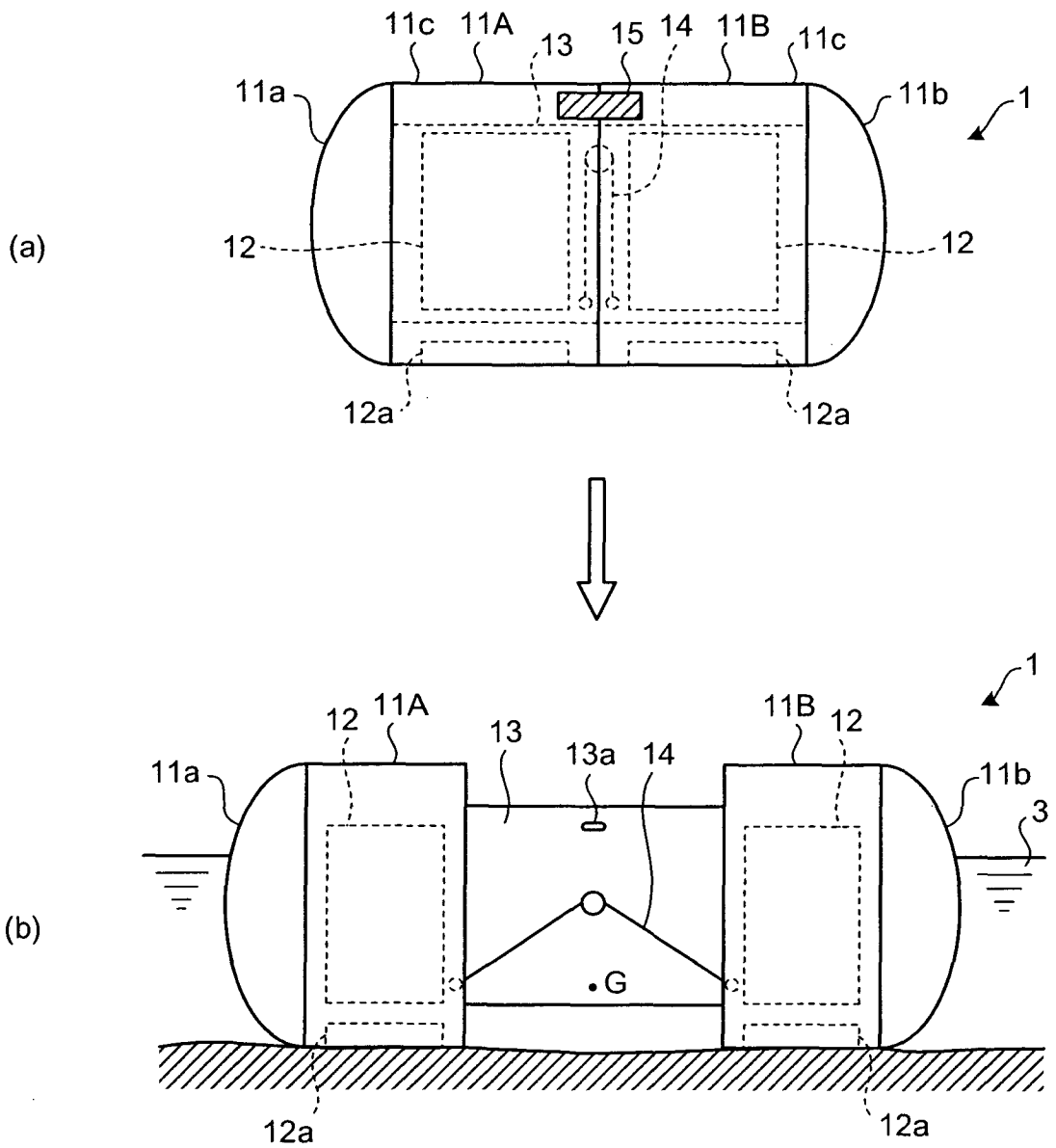
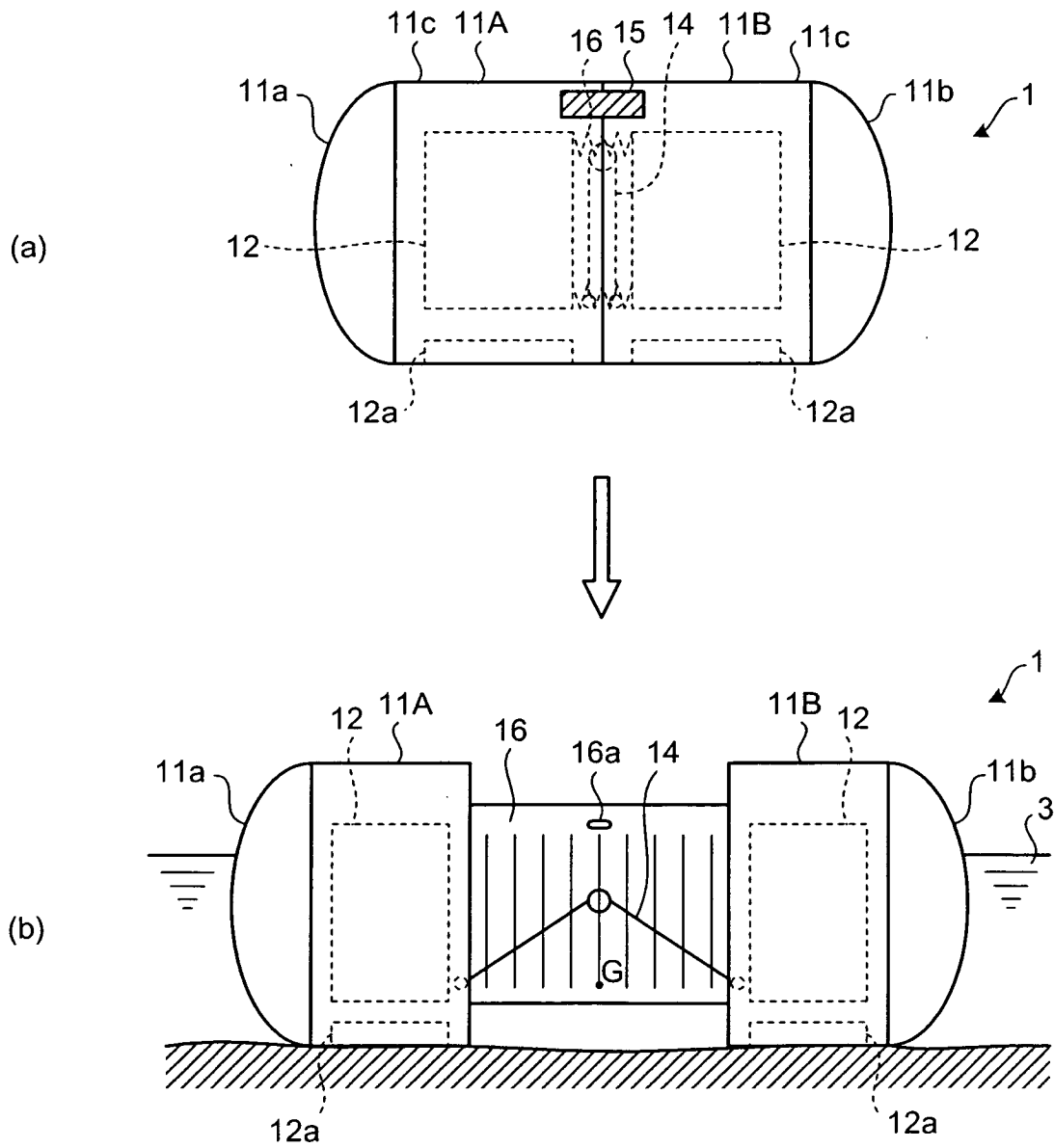


FIG.3



INTERNATIONAL SEARCH REPORT

International application No.

PCT/JP2007/068373

A. CLASSIFICATION OF SUBJECT MATTER A61B1/00(2006.01) i		
According to International Patent Classification (IPC) or to both national classification and IPC		
B. FIELDS SEARCHED		
Minimum documentation searched (classification system followed by classification symbols) A61B1/00		
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched Jitsuyo Shinan Koho 1922-1996 Jitsuyo Shinan Toroku Koho 1996-2007 Kokai Jitsuyo Shinan Koho 1971-2007 Toroku Jitsuyo Shinan Koho 1994-2007		
Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)		
C. DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	JP 2004-529718 A (Given Imaging Ltd.), 30 September, 2004 (30.09.04), Par. Nos. [0020], [0021] & US 2003/0018280 A1 & WO 2002/095351 A2	1-13
A	US 2005/0284233 A1 (Makoto Teraura), 29 December, 2005 (29.12.05), Fig. 14 & JP 2006-43432 A	1-13
P,A	JP 2007-190361 A (Konica Minolta Opto, Inc.), 02 August, 2007 (02.08.07), Fig. 5 (Family: none)	1-13
<input checked="" type="checkbox"/> Further documents are listed in the continuation of Box C. <input type="checkbox"/> See patent family annex.		
* Special categories of cited documents:		
"A"	document defining the general state of the art which is not considered to be of particular relevance	"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
"E"	earlier application or patent but published on or after the international filing date	"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
"L"	document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)	"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
"O"	document referring to an oral disclosure, use, exhibition or other means	"&" document member of the same patent family
"P"	document published prior to the international filing date but later than the priority date claimed	
Date of the actual completion of the international search 30 November, 2007 (30.11.07)	Date of mailing of the international search report 11 December, 2007 (11.12.07)	
Name and mailing address of the ISA/ Japanese Patent Office	Authorized officer	
Facsimile No.	Telephone No.	

INTERNATIONAL SEARCH REPORT

International application No. PCT/JP2007/068373
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C (Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
P, A	WO 2007/077922 A1 (Olympus Medical Systems Corp.), 12 July, 2007 (12.07.07), Par. Nos. [0389], [0397]; Fig. 39 (Family: none)	1-13

INTERNATIONAL SEARCH REPORT

International application No.

PCT/JP2007/068373

Box No. II Observations where certain claims were found unsearchable (Continuation of item 2 of first sheet)

This international search report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:

1. Claims Nos.: 14 - 17
because they relate to subject matter not required to be searched by this Authority, namely:
This is a method for observing the inside of a gaster by swallowing a capsule endoscope, and hence pertinent to the "method for diagnosing a human or animal body", as prescribed in PCT Rule 67.1(iv).
2. Claims Nos.:
because they relate to parts of the international application that do not comply with the prescribed requirements to such an extent that no meaningful international search can be carried out, specifically:
3. Claims Nos.:
because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).

Box No. III Observations where unity of invention is lacking (Continuation of item 3 of first sheet)

This International Searching Authority found multiple inventions in this international application, as follows:

1. As all required additional search fees were timely paid by the applicant, this international search report covers all searchable claims.
2. As all searchable claims could be searched without effort justifying additional fees, this Authority did not invite payment of additional fees.
3. As only some of the required additional search fees were timely paid by the applicant, this international search report covers only those claims for which fees were paid, specifically claims Nos.:
4. No required additional search fees were timely paid by the applicant. Consequently, this international search report is restricted to the invention first mentioned in the claims; it is covered by claims Nos.:

Remark on Protest

the

- The additional search fees were accompanied by the applicant's protest and, where applicable, payment of a protest fee.
- The additional search fees were accompanied by the applicant's protest but the applicable protest fee was not paid within the time limit specified in the invitation.
- No protest accompanied the payment of additional search fees.

Form PCT/ISA/210 (continuation of first sheet (2)) (April 2007)

REFERENCES CITED IN THE DESCRIPTION

This list of references cited by the applicant is for the reader's convenience only. It does not form part of the European patent document. Even though great care has been taken in compiling the references, errors or omissions cannot be excluded and the EPO disclaims all liability in this regard.

Patent documents cited in the description

- WO 0295351 A [0004]
- WO 2004529718 PCT [0004]
- JP H10213384 B [0004]
- JP 2004305635 A [0004]

专利名称(译)	胶囊型内窥镜和胃镜观察方法		
公开(公告)号	EP2064983A4	公开(公告)日	2010-03-31
申请号	EP2007828294	申请日	2007-09-21
[标]申请(专利权)人(译)	奥林巴斯医疗株式会社		
申请(专利权)人(译)	奥林巴斯医疗系统股份有限公司.		
当前申请(专利权)人(译)	奥林巴斯医疗系统股份有限公司.		
[标]发明人	FUJITA MANABU		
发明人	FUJITA, MANABU		
IPC分类号	A61B1/00 A61B1/04 A61B1/273 A61B5/00		
CPC分类号	A61B1/041 A61B1/2736 A61B5/0031		
优先权	2006257270 2006-09-22 JP		
其他公开文献	EP2064983A1 EP2064983B1		
外部链接	Espacenet		

摘要(译)

本发明的目的在于提供一种胶囊型内窥镜，该胶囊型内窥镜即使在包含比重高的内容物的情况下，也能够对象体内部的总比重较小的液体上漂浮的同时进行观察，而不会妨碍对被检体的插入性。形状记忆合金弹簧(14)呈现存储形状，使得体积改变单元(13)移位到存储位置，在该存储位置，体积改变单元(13)基于体温存储在胶囊壳体(11)中当胶囊内窥镜插入到对象体内时，对象体的角度可以实现，从而可以实现不损害对象体的插入性的尺寸。插入主体后，将水(3)适当地送入主体中，然后形状记忆合金弹簧(14)根据水的温度呈现使体积变化单元(13)暴露于外部的记忆形状。胶囊壳体(11)移动到暴露位置，其中壳体的体积增大，使得体积改变单元(13)可以移动到暴露位置，同时从通风吸收外部空气进入内部在主体中的孔(13a)中，壳体的体积增大，并且即使包括内容物(12)，由于总比重低，也可以进行胶囊内窥镜漂浮在水(3)上的观察。比重高。