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(54) Title: ESTIMATING DISTRIBUTION, FLUCTUATION AND/OR MOVEMENT OF ELECTRICAL ACTIVITY THROUGH
A HEART TISSUE

(57) Abstract: A computer implemented method for processing measurement data from electrocardiogram, ECG, electrodes on a subject. The method includes obtaining a 3D anatomical model of the torso of the subject, and obtaining a 3D image of the torso of the subject. The three dimensional image is aligned with the three-dimensional model. A position of each electrode in the three-dimensional model is determined from the three dimensional image. The positions of the electrodes in the three dimensional model are used for estimating the distribution, fluctuation and/or movement of electrical activity through heart tissue.



Title: Estimating distribution, fluctuation and/or movement of electrical activity through a heart tissue

FIELD OF THE INVENTION

The invention relates to electrocardiogram (ECG) technology. More in particular the invention relates to generating a model of a heart using ECG measurements. More in particular the invention relates to
5 estimating the distribution, fluctuation and/or movement of electrical activity through heart tissue. More in particular, the invention relates to locating heart dysfunction such as locating an origin of premature ventricular contraction (PVC) tachycardia (VT), atrial tachycardia (AT), Wolff-Parkinson-White syndrome (WPW) and conduction orders in a heart
10 on the basis of ECG measurements.

BACKGROUND TO THE INVENTION

The inventors have to date made progress in so called inverse computations where e.g. an activation sequence and/or other parameters of
15 the heart are estimated from surface electrocardiograms. Inverse imaging of electrical activity of a heart muscle is for instance described in published patent application US-2012-0157822-A1.

The inventors devised a computer program, herein referred to as Cardiac Isochrone Positioning System (CIPS), which using only the
20 standard 12-lead ECG quantitatively localizes the origin of PVCs in patients.

SUMMARY OF THE INVENTION

CIPS can use any electrode position on the chest wall:
25 consequently there are no misplaced electrodes. However, the exact location of the electrodes is critical to the outcome of CIPS. Therefore the inventors

developed three-dimensional (3D) Camera software integrated into CIPS that localizes the ECG electrodes.

The accurate electrode positions are required by the cardiac isochrones positioning system. Therefore a 3D camera based system was
5 developed to localize the electrodes.

The 3D camera is used to take 3D images of the torso of subjects with ECG electrodes attached. The software transforms the 3D quantitative image into a subject specific electrode torso model. These torso models were scaled to obtain an objective standard for electrode misplacement.

10 The 3D camera computer software automatically and rapidly detects misplacement of e.g. 12-lead ECGs electrodes.

The invention relates to a computer implemented method for processing measurement data from electrocardiogram, ECG, electrodes on a subject. The method includes obtaining a three-dimensional, 3D, anatomical
15 model of the torso of the subject. Preferably, the anatomical model includes both an outer surface and positional information on internal structures such as the heart and lungs. The three-dimensional anatomical model of the torso of the subject can e.g. be derived from a medical imaging modality, such as MRI, CT, PET-CT, ultrasound, or the like, or from a model database as set
20 out below.

The method also includes obtaining a three-dimensional image, such as a three-dimensional photograph, of the torso of the subject including position information of the electrodes. The three-dimensional image contains a three-dimensional representation of an outer surface of the torso
25 of the subject. The three-dimensional image also includes position information on the electrodes positioned on the outer surface of the torso. The three-dimensional image may be obtained using a 3D camera. The three-dimensional image may e.g. be a three-dimensional photograph or video recording. The position information of the electrodes may be formed or
30 derived from the electrodes being visible in the three-dimensional image.

The three dimensional image is aligned with the three-dimensional model. The aligning can include minimizing the distances between the three-dimensional image and the three-dimensional model. The aligning may involve translation and/or rotation of the three dimensional image and/or
5 the three dimensional model. Optionally the three dimensional image is scaled to the three-dimensional model, and/or the three-dimensional model is scaled to the three-dimensional image. For most applications the 3D image and 3D model represent the torso of a patient.

A position of each electrode in the three-dimensional model is
10 determined from the position of each electrode in the overlain three dimensional image. Using the positions of the electrodes in the three dimensional model the distribution, fluctuation and/or movement of electrical activity through heart tissue are estimated.

According to an aspect of the invention, a position of each
15 electrode in the three-dimensional model is determined from the aligned three dimensional image. The positions of the electrodes in the three dimensional model are used for estimating the distribution, fluctuation and/or movement of electrical activity through heart tissue.

A fastest route algorithm, in particular together with a equivalent
20 double layer model, allows for so-called inverse functional imaging of electrical activity (activation, recovery) of a heart muscle, in particular of a complete image of a heart, as well as particular areas of interest both on the outside (epicardium) and inside (endocardium) of the heart or both. As an algorithm that may lead to comparable results as the fastest route
25 algorithm, the fast marching algorithm, the shortest path algorithm, the ion kinetic model or the cellular automaton model may be used. This is for instance described in US2012/01257822, incorporated herein by reference.

An ECG is defined herein as any method that (preferably non-invasively) correlates actual electrical activity of the heart muscle to
30 measured or derived (electrical activity) of the heart. In case of a classical

electrocardiogram the differences in potential between electrodes on the body surface are correlated to the electrical activity of the heart. Derived ECG's can also be obtained in other ways (e.g. by measurement made by a so-called ICD (Implantable Cardioverter Defibrillator)). In order to obtain
5 such a functional image an estimation of the movement of the electrical activity has to be provided.

Optionally, the three-dimensional anatomical model of the torso of the subject is determined by selection from a database. Thereto is provided a database including a plurality of three dimensional anatomical models of
10 torsos. The 3D models can include geometries of torsos, optionally including geometries of one or more of lungs, heart, blood cavities, ribcage, fat and any other relevant tissue in the torso. The 3D anatomical models are mutually different. The 3D anatomical models may represent different possible subjects. The 3D anatomical models may e.g. be representative of subjects of
15 different gender, age, weight, body length, chest circumference, frame size, body-mass-index (BMI), etc.. The 3D anatomical models may also differ in view of medical criteria, such as blood pressure. It will be appreciated that each 3D anatomical model in the database can e.g. be derived from a medical imaging modality, such as MRI, CT, PET-CT, ultrasound, or the
20 like, from a respective reference subject. It is also possible that some or all 3D anatomical models in the database are fictitious renderings of fictitious reference subjects.

The method can then include selecting, from the plurality of 3D anatomical models in the database, the 3D anatomical model showing
25 closest conformity to the torso of the subject. The selection may be made on the basis of parameters, such as gender, age, weight, body length, chest circumference, frame size, BMI, etc.. Such selection may be automated on the basis of parameters of the subject that are already known, e.g. from measurements, questions or tests. From the 3D image several
30 measurements can be computed, e.g. chest circumference, height of the torso

etc. These measurements can be used in selecting the appropriate 3D model from the database.

The selection may also be based on visual comparison of the 3D image of the torso of the subject with the 3D models in the database. Such
5 selection may be automated on the basis of pattern recognition. This provides the advantage that it is not required to obtain a subject-specific 3D anatomical model for each subject. Instead it is possible to obtain a plurality of different 3D anatomical models and to select a quasi-subject-specific 3D anatomical model that best represents the subject. Optionally, the method
10 includes, after selecting a 3D anatomical model from the database, scaling the 3D anatomical model to the 3D image of the torso of the subject, and/or scaling the 3D image to the 3D anatomical model. This enhances conformity of the 3D anatomical model to the 3D image. The 3D anatomical model can be scaled so as to have the outer surface of the 3D anatomical model
15 correspond with the outer surface of the torso of the subject as obtained from the 3D image. When the 3D anatomical model is scaled, also dimensions and positions of internal structures such as the lungs and heart can be scaled.

It is also possible to take parameters of the subject into account
20 when scaling the 3D anatomical model. For example, the scaling can be dependent on the amount of body fat and frame size of the subject. In a subject with more body fat, the chest circumference can be larger in relation to the dimensions of heart and lungs, than in a subject with less body fat.

Optionally, the method includes placing a marker on the torso of
25 the subject, for example at the xyphoid. The marker is arranged to be identifiable in the 3D image of the torso of the subject. The marker can be used for determining the position of the heart. The marker at the xyphoid can be used as a reference for the lower end of the heart.

It is also possible to take parameters of the subject into account
30 when determining a position of the heart within the 3D anatomical model.

Such parameter can e.g. be weight or age of the subject. The weight can be indicative of a large belly, which pushes the heart upwards. Therefore, a vertical position of the heart in the 3D anatomical model can be modified on the basis of weight of the subject. The heart tends to be positioned more horizontally with increasing age. Therefore, a rotation of the heart in the 3D anatomical model can be modified on the basis of the age of the subject.

Thus, it is possible to provide a good approximation of a subject-specific 3D anatomical model, by selecting an appropriate standard 3D anatomical model from the database. Optionally, the selected 3D anatomical model is scaled to better conform with the 3D image of the torso of the subject. Optionally, such scaling of the selected 3D anatomical model involves scaling of the internal structures such as heart and/or lungs. Optionally, a position and/or orientation of the heart in the selected (and optionally scaled) 3D anatomical model is modified on the basis of subject-specific values of one or more parameter such as gender, age, weight, body length, chest circumference, frame size, BMI, etc..

It will also be possible to only select the internal structures from the database whereas the torso model will be derived from the 3D image. The internal structures can then be selected based on subject-specific values of one or more parameters such as gender, age, weight, body length, chest circumference, frame size, BMI, etc.. The dimensions, position and orientation of the internal structures, such as heart and/or lungs, can e.g. be selected on the basis of the weight and age of a patient (the heart is more horizontal for older patients or overweighted patients).

According to an aspect, the method further includes determining an identification of each electrode from the three-dimensional image. The identification can be one of a color, a shape, or a code. The method can further include detecting positions of each a plurality of electrodes, comparing the detected positions with predetermined positions and determining whether the electrodes are positioned approximately in the

correct predetermined position. Thus, it is for instance possible to determine whether or not the electrodes are positioned in swapped positions. Electrodes that are supposed to be positioned in an order V1, V2, V3, V4, may, e.g. be actually positioned in an order V1, V4, V3, V2. Once swapped
5 positions have been detected, the program may take these swapped positions into account. The program may internally swap the signals received from the swapped electrodes so that the processed signals correspond to the correct electrode positions. Therefore a need for repositioning swapped electrodes may be obviated.

10 According to an aspect, the method includes indicating whether the electrodes are positioned in a desired position. The electrodes may e.g. be positioned inaccurately. The program may be arranged for indicating a direction and/or distance for repositioning an electrode.

When the underlying anatomy of the patient is known (e.g. from a
15 MRI/CT model) the system can also be used to guide lead placement, i.e. make sure the electrodes are over the area of interest. This can be patient specific. For certain patients, (e.g. Brugada) it is known that the standard 12 lead ECG electrode positions do not measure the known deviations in the ECG. Electrodes need to be put higher in such case. How high can now be
20 related to the cardiac anatomy underneath the electrodes. This will also help CIPS to improve the diagnosis for these patients.

BRIEF DESCRIPTION OF THE DRAWINGS

Embodiments of the present invention will now be described in
25 detail with reference to the accompanying drawings.

Figure 1. Overview of the 4 modules of CIPS: PVC selection (equivalent to Selection of a single atrial or ventricular heart beat from the ECG), CT/MRI derived models, the in this application described new method to register the electrodes to the torso model derived from MRI/CT.

Figure 2. Left detection of QRS's (dotted and dashed lines, middle base line corrected, and selected beat (right).

Figure 3. The three volume conductor effects: a) proximity effect, b) spatial orientation, and c) volume conduction; bloods conducts better than myocardial tissue, lungs worse.

Figure 4. Rough tuning of the first activation sequence: For each node and node on the heart an activation sequence is created (left matrix). From these activation sequences the ECG can be computed (Eq 2). The activation (node) resulting in the highest correlation between measured and simulated ECG is taken as the initial estimate.

Figure 5. Reconstruction of a torso with a 3D camera.

Figure 6. How the 3D camera works

Figure 7. Alignment of 3D image with torso model

Figure 8. 3D image as taken with the Kinect camera. Clearly visible are the electrodes of V1-V4 at the standard positions and one intercostal space below and above.

Figure 9. Torso models with electrodes: The standard 12 lead ECG positions and the three misplaced electrode configurations 1), 2), and 3).

Figure 10A. the scaled height of the electrodes of the precordial leads with respect to the reference point of all 5 subjects. In solid lines the electrodes at the standard positions, in dotted lines electrodes were shifted one intercostal space up and in dashed lines one intercostal space lower.

Figure 10B. Extremity leads shown in the frontal plane. The thick line indicates the location of the LL electrode in the Mason-Likar position, which can easily be detected.

Figure 11. Precordial electrodes one intercostal space higher and lower: The standard 12 lead ECG of case 4 (dotted line) one intercostal space higher (solid line) and one intercostal space lower (dashed line). Note: the major differences in V1-4 that need to be corrected.

Figure 12. Misplaced Lead Reconstruction: standard 12 lead ECG of case 5 (dotted line), misplaced electrode positions (dashed line), and reconstructed ECG at the standard positions (solid line). Note; V2 and V3 were completely reconstructed whereas V1 was not.

5

DETAILED DESCRIPTION

CIPS can be used to localize the PVC origin or any other atrial or ventricular arrhythmia by electrodes accurately placed in the standard 12 lead ECG positions.

10 In this example the electrodes were moved up and down in 10mm increments. For each of these moved electrode positions, CIPS was used to localize the PVC origins. This change in PVC origin location as determined by CIPS was compared to the displacement of the ECG electrodes. To investigate the registration reproducibility of CIPS, 5 images were
15 registered manually to the MRI derived torso model on which the electrode positions were projected from the 3D image.

In seven patients, the PVC origin was localized correctly by CIPS to the ablation sites with accurately positioned electrodes. However, recorded changes in PVC origins varied greatly from 0 to 110 produced by
20 10mm increments up to a range of 9-110 mm when moving the electrodes 30 mm down. The registration error of integrating the 3D image with the MRI derived torso model was less than 2.5 mm per electrode.

Using CIPS, even with a 10mm change of the electrodes the error for localization of PVC are highly variable and large. The CIPS software
25 that integrates and registers the 3D camera image of the electrodes to the MRI derived torso model is reproducible.

The 3D camera is useful for quantitative localization of electrode positions for CIPS to accurately localize the origins of the PVCs, ventricular tachycardia (VT), atrial tachycardia (AT), Wolff-Parkinson-White syndrome
30 (WPW), conduction orders and Delta waves using the 12 lead ECG in the

electrophysiology (EP) Lab and in the general clinical setting. This example highlights the advantage of relating the accurate position of the electrodes to the cardiac anatomy as imaged with the 3D camera instead of using the standard position of the rib interspaces.

5 Figure 1 shows a schematic overview of a system 1 according to the invention. The system includes a model input unit 2 for obtaining a three-dimensional, 3D, anatomical model of the torso of the subject. In Figure 1 the 3D model data is obtained from a CT/MRI system 8. It will be appreciated that the 3D anatomical model may also be obtained from a
10 database 11. The system further includes an image input unit 2 for obtaining a three-dimensional image of the torso of the subject. In Figure 1 the 3D image data is obtained from a 3D camera 10, here a Kinect camera. The system further includes an ECG input unit 2 for obtaining ECG data.

 The system in figure 1 further includes a processor 4. The
15 processor 4 is arranged for aligning the three dimensional image with the three-dimensional model, determining a position of each electrode in the three-dimensional model from the three dimensional image; and using the positions of the electrodes in the three dimensional model for estimating the distribution, fluctuation and/or movement of electrical activity through
20 heart tissue.

 The process performed by the processor, such as by a computer program running on the processor, is described herein below.

Selection of a single atrial or ventricular heart beat from the ECG

 CIPS analyses single atrial or ventricular complexes. This
25 requires a QRS detection algorithm and a baseline correction procedure. From these signals automatically or manually the clinical interesting beats can be selected for analysis (see figure 2). This selection is done using a first module. The first module is herein also referred to as selection module.

CT/MRI derived models

A second module describes the model creation and the way these models are used to compute an ECG on any location on or inside the thorax:

- 1) Cardiac current source model linked to cardiac electrophysiology
(Equivalent double layer source model)
- 2) Volume conductor:
 - a. proximity effect, spatial orientation of the 9 ECG electrodes
 - b. inhomogeneous volume conductor
 - c. Patient's specific geometry from Computed Tomography (CT) or Magnetic Resonance Imaging (MRI) (Figure 1),

The first component, the cardiac current source model, is the equivalent double layer (EDL). The EDL represents the currents generated by the cardiac tissue during activation and recovery, which is equivalent to the currents generated by all coupled myocardial cells as recorded at endo- and epicardial surfaces [1], [2]. Consequently, the EDL is referred to the localization at the endo- and epicardial surface of the myocardium. For any position (node) on the triangulated ventricular surface, the time course of the local source strength is taken to be proportional to the transmembrane potential (TMP) of the nearby myocytes [3], [4]. The second component accounts for the volume conductor effects, being: a) proximity and spatial orientation of the 9 ECG electrodes and b) the differences in conduction properties of the various tissues. The proximity effect and spatial orientation is determined by the solid angle of the active cardiac tissue as observed from the ECG electrodes [5]. The solid angle accounts for the fact that ECG waveforms of electrodes close to the heart are dominated by the cardiac tissue underneath depending on the direction of the wave front. Previous studies indicated that an appropriate volume conductor model requires the incorporation of the heart, blood cavities, lungs and thorax [6], [7]. In this example, the conductivity values σ assigned to the individual

compartments were: thorax and ventricular muscle: 0.2 S/m, lungs: 0.04 S/m and blood cavities: 0.6 S/m. The mathematical method used to solve this volume conductor problem in a numerical way is referred to as the Boundary Element Method (BEM) [8], [9]. With the BEM a transfer matrix $\mathbf{A}$ can be computed taking into account the full complexity of the discretized volume conductor model. For the potentials at thorax node ℓ of the 12-lead electrodes is defined by

$$ECG(t; \ell) = \sum_n A(\ell, n) S(t; \delta_n, \rho_n), \quad \text{EQ1}$$

in which $S(t; \delta_n, \rho_n)$ is the local time dependent EDL source strength, and $A(\ell, n)$ the BEM derived transfer function relating the contribution of S at node n to the potentials ECG at thorax node ℓ , or in a matrix notation:

$$ECG = \mathbf{A} \mathbf{S} \quad \text{EQ2}$$

Estimation of cardiac activation and recovery

A fourth module estimates the cardiac activation through a rough- and fine tuning algorithm described in described [10] and in published patent application US-2012-0157822-A1, incorporated herein by reference. Briefly:

- a. The fastest route based initial estimate of cardiac activation provides the rough initial estimate.
- b. Optimization procedure is used for the fine-tuning.

The fourth module relates to patient-specific geometric models of the heart, lungs and thorax derived from, e.g., Multi Slice Computer Tomography (MSCT) (see Figure 1).

Previous studies have shown the importance of patient-specific models [11], [12]. These geometric models were created with morphing software [13]. With such software the boundaries of all relevant tissues were identified manually. For the ventricles these boundaries are the left- and right endocardium, epicardium, aorta and pulmonary artery. To capture the spatial orientation from the 12-lead electrodes, the epicardium and

endocardium, lungs, and thorax are morphed to match the manual drawn contour points. This yields a patient specific geometry.

The fourth module uses output from the first and second modules as well as from a third module described below to, preferably automatically, position the activation isochrones on the endo- and epicardial ventricular surface. The rough tuning step is an adapted version of the fastest route to obtain an electrophysiological based initial estimate of the activation sequence as described previously [10], [14]. In short: One or multiple foci are determined using the fastest route algorithm (see Figure 3). For each node an activation sequence is computed using a QRS derived propagation velocity. The first estimate of the activation isochrones is the one with the highest correlation between the actual measured ECG and the model derived ECG. In the next iteration an extra focus is added. The activation sequence is computed by the “first come, first served” principle. This procedure is then repeated until there is no increase in correlation found. The final activation isochrones are obtained by a Levenberg-Marquardt based optimization procedure in which the rough tuned activation isochrones are tuned to obtain matching ECGs.

The 3rd Module of CIPS: the 3D camera to locate and register the electrodes automatically

Localization of the ECG electrodes is important to reduce modeling errors, i.e. the transfer from the heart surface to the electrode positions on the chest surface. With a 3D camera, for instance a Kinect camera, the 3D reconstruction of an object is created (see Figure 4). This reconstructed shell of the thorax is used to create a 3D overlay to the thorax derived from MRI/CT (second module).

As CIPS needs location information of each the electrodes on the chest surface for every ECG recording it wants to analyze, an algorithm for automatically determining the location of each electrode is used in this example.

Thereto, the system is further provided with a 3D camera. The 3D camera obtains a 3D image of the torso of a patient. The 3D image of the patient provides patient specific 3D data of the outer surface of the torso of the patient. The 3D image contains spatial information in three dimensions on the outer surface of the torso of the patient. According to the invention the patient specific 3D torso data is aligned to a 3D torso model of that patient. The 3D torso model of the patient may be derived from MRI in the EP laboratory or may be approximated by selection from a database 11. This allows for the accurate localization of PVCs by the Cardiac Isochrones Positioning System.

When selecting the 3D anatomical model of the torso for a patient from a database, the database includes a plurality of mutually different 3D anatomical models. The 3D anatomical models can e.g. differ in dimensions of the torso and internal structures such as heart and lungs. The 3D anatomical models can represent reference torsos that correspond to different values for parameters such as one or more of gender, age, weight, body length, chest circumference, frame size, and body-mass-index. It will be appreciated that each 3D anatomical model in the database can e.g. be derived from a medical imaging modality, such as MRI, CT, PET-CT, ultrasound, or the like, from a respective reference subject. It is also possible that some or all 3D anatomical models in the database are fictitious renderings of fictitious reference patients.

Selecting the most appropriate 3D anatomical model from the database may be performed on the basis of the parameters, such as gender, age, weight, body length, chest circumference, frame size, BMI, etc.. Such selection may be automated on the basis of parameters of the subject that are already known, e.g. from measurements, questions or tests. The selection may also be based on visual comparison of the 3D image of the torso of the subject with the 3D models in the database. Such selection may be automated on the basis of computer recognition of the shape of the 3D

image of the torso and the shape of the torsos of the 3D anatomical models. It will be appreciated that the higher the number of different 3D models in the database, the better the match between one of the 3D models in the database and the torso of the patient. The 3D anatomical model selected
5 from the database can, for the purpose of this invention, be used as the patient-specific 3D anatomical model.

Conformity between the torso of the patient and the selected 3D model may be further enhanced by scaling the selected 3D model to the 3D image of the torso of the subject, and/or scaling the 3D image to the 3D torso
10 model. The 3D anatomical model can be scaled so as to have the outer surface of the torso in the model correspond with the outer surface of the torso of the subject as obtained from the 3D image. Such scaling may include skewing or warping of the 3D anatomical model. While the 3D anatomical model is scaled, also dimensions and positions of internal
15 structures such as the lungs and heart can be scaled.

Conformity between the torso of the patient and the selected 3D model can be further enhanced by taking values of the parameters of the subject into account when scaling the 3D anatomical model. For example, the scaling can be dependent on the amount of body fat and frame size of the
20 subject. In a subject with more body fat, the chest circumference can be larger in relation to the dimensions of heart and lungs, than in a subject with less body fat.

Conformity between the torso of the patient and the selected 3D model can be further enhanced by modifying a position of the heart in the
25 selected 3D anatomical model on the basis of values of parameters of the subject. Such parameter can e.g. be weight or age of the subject. The weight can be indicative of a large belly, which pushes the heart upwards. Therefore, a vertical position of the heart in the 3D anatomical model can be modified on the basis of weight of the subject. The heart tends to be
30 positioned more horizontally with increasing age. Therefore, a rotation of

the heart in the 3D model can be modified on the basis of the age of the subject.

Further, the 3D camera provides location data of the electrodes visible in the field of view of the 3D camera. The location data includes
5 position data in three dimensions for each electrode within the field of view of the 3D camera. Additionally, the 3D camera can be arranged to identify an identifier of each of the electrodes within the field of view of the 3D camera. The identifier can e.g. be a color, a shape, a number, a code or the like. Preferably each electrode has a unique identifier. The identifier of the
10 electrode associated with a certain channels of the ECG is made known to the system. For instance the channels/electrodes are color-coded. Thus, the position of each electrode can be detected automatically. Currently different color codes are used for the 12 lead ECG system.

The 3D camera can further be arranged to identify additional
15 markers placed on the torso of the patient, and identifiable in the 3D image. Such markers can be used for providing a reference point in the 3D image to be used in aligning and/or scaling with the 3D anatomical model. For example a marker can be placed at the xyphoid. This marker can be used for determining the position of the heart. The marker at the xyphoid can be
20 used as a reference for the lower end of the heart. The position of the heart in the 3D anatomical model can then be adjusted on the basis of the position of the xyphoid marker in the 3D image.

Thus, the invention provides for to the automatic alignment of a 3D image of the patient torso with the patient specific 3D model of the torso.
25 The invention also provides for the automatic detection of electrode positions on the chest wall.

The 3D image of the torso is automatically aligned to the 3D torso model derived from MRI/CT or database using a minimization procedure in which the distance between the image points in the 3D image and model
30 points in the torso model is reduced automatically. Once aligned, the head of

the patient can be removed automatically to ensure the patient privacy. This might be a requirement as photos of the patient are taken. In this example, on the basis all 3D image data above the shoulders is thereto removed. As the position of the shoulders is known from the 3D torso model,
5 this head removal can be automated in the system.

Next, electrode positions need to be located accurately on the 3D model of the torso. In this example colored electrodes are used. The electrode positions can then be automatically detected using the color as an identifying marker. Other identifying markers like text etc., can be used as
10 well. In the absence of electrode identifiers, the program can determine the electrode positioned closest to a predefined (e.g. optimum) electrode location, define this electrode as coupled to that predefined location, and determine the actual location of that electrode on the basis of the 3D image.

Notice that for every ECG recording a 3D image is required, as
15 electrodes can be place anywhere on the chest wall.

The ECG based Cardiac Isochrones Positioning System (CIPS) for example uses nine electrodes. The electrode positions on the torso are determined to estimating the distribution, fluctuation and/or movement of electrical activity through heart tissue, e.g. to localize accurately the origin
20 of the PVC, VT, AT and delta waves [15]. However, in the EP lab the electrodes are frequently not placed in the predetermined positions. An example of such predetermined positions are the standard twelve lead ECG positions. Placing the electrodes in other positions than the predetermined positions can be due to other attached system's patches. The system
25 includes a 3D camera and 3D camera software that automatically detects electrode misplacement. Optionally the program is further arranged to correct for such misplacements. The 3D quantitative image data is used to construct a subject specific torso geometry. To be able to compare electrode misplacement among subjects, in this example the torso models were scaled
30 to a standard height, assuming the ribcage scales linearly with torso height.

The triangulated torso geometry was additionally used to correct the ECG signals from the misplaced electrodes.

Example

In this example software is used using the Microsoft Kinect
5 software development kit (SDK) version 1.7. However, it will be appreciated that other 3D cameras and software kits can be used. This software retrieves the data from the Kinect camera [16] and processes the data to obtain the subject specific torso models.

Measurement setup

10 To test the ability to detect electrode misplacement from 3D image derived torso models, five subjects were included in this example study. On each subject the 12 lead electrodes were positioned accurately by an experienced technician. Additionally the precordial electrodes were positioned one intercostal space higher and one intercostal space lower (see
15 figure 8). Extremity electrode positions were unaltered during the ECG recording. For each configuration the ECG was recorded while the subject maintained a supine position.

In Figure 8 is the 3D image of a subject recorded in the Antero-posterior position with the attached electrodes. Therefore the accuracy of
20 the V5 and V6 electrodes could not be determined.

Torso model construction to detect electrode misplacement

In order to make a 3D computer model, in this example triangles are used to describe the surface of the human torso. To detect the misplacement of the electrodes a common reference point must be created.
25 This requires the definition of a reference point. For the reference model the z-coordinate of the reference point was defined at a quarter of the height of the torso model (figure 10B). The height of the torso was taken as the distance between the shoulders and the crotch. The center of the horizontal plane at the middle of the torso resulted in the x-coordinate and y-
30 coordinate of the reference point. All subsequent torso models were scaled to

match the height of the common reference model. The distance in the z direction with respect to the reference point was used to detect the misplacement of leads.

Method for ECG Lead correction

5 Three common electrode misplacements configurations were used to reconstruct the ECG signals at the standard positions:

- 1) V1,2 higher, V3 standard, and V4-6 lower
- 2) V1,2 and V6 standard, and V3-5 higher
- 3) V1-3 higher, and V4-6 standard

10 The ECGs recorded at these misplaced electrode positions were used to reconstruct the ECGs at the standard positions with a surface laplacian based interpolation method [17].

 The differences between reconstructed and recorded 12 lead ECG data were quantified using the relative difference (*rd*) measure: the root
15 mean square value of all matrix elements involved relative to those of the recorded ECG data.

Results

 As seen in table 1, the KINECT torso models derived chest
 circumferences had a close calibration to the measured chest
20 circumferences. The distance between the standard electrodes and the electrodes placed one intercostal space above was 43 ± 3.5 mm and 42 ± 3.5 mm for the electrodes below.

Table 1 Calibration of the 3D camera measurement: The chest circumference directly measured was compared with the 3D camera measurements. The circumference was measured at the height of 4th intercostal space and from the reconstructed torso model at approximately the same height. Note their similarity.

subject	age (years)	Chest circumference (cm)		height (cm)
		measured	3D camera	
KP001	65	108	110	188
KP002	54	107	110	186
KP003	21	87	91	173
KP004	41	84	91	177
KP005	42	85	90	192

As shown in Figure 10A, the electrodes placed one intercostal space above or below were calculated by the program to be significantly misplaced using the distance from leads V1-V6 to the reference point ($P \leq 0.01$).

The standard 12 lead ECGs were reconstructed from the three different misplaced lead configurations (figure 9). In table 2 the relative differences (rd) are listed for all subjects and the 3 different lead configurations. In five cases the rd increases, in all other cases the rd did improve. Only in 4 cases the rd was below 0.2, a value that corresponds to a correlation coefficient of more than 98%. Especially for lead configuration 1 the interpolation failed to reconstruct the standard 12 lead ECG accurately. An example of the reconstruction of the ECG at the standard positions from the third misplaced lead configuration is shown in figure 4. As shown in figure 5 the misplaced leads V2 and V3 are corrected by interpolation but not in V1.

Table 2. Correction of misplaced electrode ECGs: Relative difference (rd) before and after correction of the ECG signals. See Figure 2 for the used lead misplacement configurations. A rd of 0.2 corresponds to a correlation coefficient of more than 98%.

	1		2		3	
	before	after	before	after	before	After
KP001	0.37	0.44	0.22	0.20	0.28	0.47
KP002	0.24	0.27	0.34	0.34	0.21	0.26
KP003	0.23	0.26	0.20	0.09	0.24	0.19
KP004	0.23	0.27	0.20	0.13	0.24	0.22
KP005	0.41	0.26	0.39	0.24	0.36	0.15

5

The 3D camera proves to be an appropriate tool to obtain the torso geometry including the electrode positions on the chest wall. Thus this tool enables the patient specific torso reconstruction in the EP laboratory, a requirement for the accurate localization of PVCs by the Cardiac Isochrones Positioning System [15].

It is possible to detect electrode misplacement by using the visual information recorded by a 3D camera. The precordial electrodes located approximately 4 cm from the standard positions could be significantly classified as misplaced (figure 10). When using a database containing rd data the sensitivity and specificity of distances and angles misplaced leads can be determined accurately, and corrected position information for the misplaced leads can be estimated accurately.

In this example, the major underlying assumption in the Torso Model is that the height of the ribcage, and consequently the standard precordial electrode positions scales linearly with the torso length. This assumption is adequate to detect the electrode misplacement. Furthermore, other landmarks of the torso, such as the angle of Louis or the xyphoid, might be mathematically derived from these models as well.

20

Correct electrode placement of the 12 lead ECG is critical for correct computerized ECG diagnoses systems. The likelihood of misplacement can be incorporated in computerized ECG analysis algorithms, thus increasing the sensitivity and specificity of the applied ECG diagnosis algorithms. As shown in Figure 10B, the detection of the left leg (LL) electrode in the Mason-Likar position between the mid-left lower ribcage and the iliac crest.

This position can be converted by the program to the standard position on the left leg. This lead misplacement algorithm can also be applied in ambulances with equipment that transmit the acquired ECG's digitally to a hospital for on-line consulting and diagnosis.

In a significant percentage of the patients suffering from acute coronary syndrome the diagnosis based on the transmitted ECG's is incorrect [18]. This might result in the transportation of these patients to a hospital where a percutaneous coronary intervention (PCI) procedure cannot be performed. Using the 3D camera to detect electrode misplacement and the use of the program to correct the diagnosis could reduce the number of patients transported to the wrong facility.

As an experiment, the geometrical information of the torso was used to correct the standard 12 lead ECG from the recorded misplaced ECG signals. In figure 11 is demonstrated the leads that need to be corrected are V1-4. In figure 12 is shown that the correction method proposed by Oostendorp et al. [17] corrected V2-3, but not V1. As shown in Table 2 the electrode configuration with V1,2 too high, V3 standard, and V4-6 too low produced a reduced match for four out of the five subjects. The new technique presented herein has created a new tool to improve the diagnostic accuracy of the standard 12 lead ECG.

New 3D camera computer software can automatically and rapidly detect misplacement of 12-lead ECGs recording in the EP lab and other locations and thereby increase the accuracy of the 12 lead ECG. The

computer program is capable of correcting position information of most of these misplaced leads. This correction improves the results obtained from a diagnostic computerized ECG program.

Although the embodiments of the invention described with
5 reference to the drawings comprise computer apparatus and processes performed in computer apparatus, the invention also extends to computer programs, particularly computer programs on or in a carrier, adapted for putting the invention into practice. The program may be in the form of source or object code or in any other form suitable for use in the
10 implementation of the processes according to the invention. The carrier may be any entity or device capable of carrying the program.

For example, the carrier may comprise a storage medium, such as a ROM, for example a CD ROM or a semiconductor ROM, or a magnetic recording medium, for example a floppy disc or hard disk. Further, the
15 carrier may be a transmissible carrier such as an electrical or optical signal which may be conveyed via electrical or optical cable or by radio or other means, e.g. via the internet or cloud.

When a program is embodied in a signal which may be conveyed directly by a cable or other device or means, the carrier may be constituted
20 by such cable or other device or means. Alternatively, the carrier may be an integrated circuit in which the program is embedded, the integrated circuit being adapted for performing, or for use in the performance of, the relevant processes.

However, other modifications, variations, and alternatives are
25 also possible. The specifications, drawings and examples are, accordingly, to be regarded in an illustrative sense rather than in a restrictive sense.

For the purpose of clarity and a concise description features are described herein as part of the same or separate embodiments, however, it will be appreciated that the scope of the invention may include
30 embodiments having combinations of all or some of the features described.

In the claims, any reference signs placed between parentheses shall not be construed as limiting the claim. The word 'comprising' does not exclude the presence of other features or steps than those listed in a claim. Furthermore, the words 'a' and 'an' shall not be construed as limited to 'only one', but instead are used to mean 'at least one', and do not exclude a plurality. The mere fact that certain measures are recited in mutually different claims does not indicate that a combination of these measures cannot be used to an advantage.

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Claims

1. A computer implemented method for processing measurement data from electrocardiogram, ECG, electrodes on a subject including the computer:
 - obtaining a three-dimensional, 3D, anatomical model of the torso of
5 the subject ;
 - obtaining a three-dimensional image of the torso of the subject including position information of the electrodes;
 - aligning the three dimensional image and the three-dimensional model;
 - 10 - determining a position of each electrode in the three-dimensional model from the three dimensional image; and
 - using the positions of the electrodes in the three dimensional model for estimating the distribution, fluctuation and/or movement of electrical activity through heart tissue.
- 15 2. The method of claim 1, wherein the three-dimensional image is obtained with a 3D camera.
3. The method of claim 1 or 2, wherein three-dimensional model of
20 the torso of the subject is derived from a medical imaging system, such as MRI, CT, PET-CT, ultrasound, or the like.
4. The method of claim 1, 2 or 3, wherein the three-dimensional model of the torso of the subject is obtained from a database including a
25 plurality of different three-dimensional models of torsos.

5. The method of claim 4, wherein the three-dimensional models in the database are representative of subjects that differ in at least one of gender, age, weight, body length, chest circumference, frame size, and body-mass-index.

5

6. The method of claim 4 or 5, including the steps of:

- comparing the three-dimensional image with one or more three dimensional models stored in the database; and

- selecting the three-dimensional model that best corresponds to the three-dimensional image.

10

7. The method of any one of claims 1-6, wherein the aligning includes minimizing the distances between the three-dimensional image and the three-dimensional model.

15

8. The method of any one of claims 1-7, including scaling the three-dimensional image to the obtained three-dimensional model and/or scaling the obtained three-dimensional model to the three-dimensional image.

20 9. The method of any one of claims 1-8, including modifying a position and/or orientation of the heart in the obtained three-dimensional model on the basis of a subject-specific value of one or more of gender, age, weight, body length, chest circumference, frame size, and body-mass-index.

25 10. The method of any one of claims 1-9, further including determining an identification of each electrode from the three-dimensional image.

30 11. The method of claim 10, wherein the identification is one of a color, a shape, number, or a code.

12. The method of any one of claims claim 1-11, further including detecting positions of each of a plurality of electrodes, comparing the detected electrode positions with predetermined electrode positions and determining whether the electrodes are positioned approximately in the correct predetermined position.

13. The method of claim 12, further including determining whether electrodes are positioned in swapped positions.

14. The method of claim 13, further including swapping back signals of swapped electrodes.

15. The method of any one of claims 1-14, including indicating whether the electrodes are positioned in a desired position.

16. The method of claim 15, further including indicating a direction and/or distance for repositioning an electrode to the desired position.

17. The method of any one of claims 1-16, further including removing image data relating to a face of the subject from the three-dimensional image.

18. A system for processing measurement data from electrocardiogram, ECG, electrodes on a subject, the system including:

- a model input unit for obtaining a three-dimensional, 3D, anatomical model of the torso of the subject ;
- an image input unit for obtaining a three-dimensional image of the torso of the subject;
- a processor arranged for
 - aligning the three dimensional image with the three-dimensional model;

- determining a position of each electrode in the three-dimensional model from the three dimensional image; and
- using the positions of the electrodes in the three dimensional model for estimating the distribution, fluctuation and/or movement of electrical activity through heart tissue.

19. The system of claim 18, further including a 3D camera for providing the three-dimensional image.

20. The system of claim 18 or 19, wherein the processor is arranged for obtaining the three-dimensional model of the torso of the subject from a database including a plurality of different three-dimensional models of torsos.

21. The system of claim 20, wherein the three-dimensional models in the database are representative of subjects that differ in at least one of gender, age, weight, body length, chest circumference, frame size, and body-mass-index.

22. The system of claim 20 or 21, wherein the processor is further arranged for:

- comparing the three-dimensional image with one or more three dimensional models stored in the database; and
- selecting the three-dimensional model that best corresponds to the three-dimensional image.

23. The system of any one of claims 18-22, wherein the processor is further arranged for scaling the three-dimensional image to the obtained

three-dimensional model and/or scaling the obtained three-dimensional model to the three-dimensional image.

24. The system of any one of claims 18-23, wherein the processor is
5 further arranged for modifying a position and/or orientation of the heart in the obtained three-dimensional model on the basis of a subject-specific value of one or more of gender, age, weight, body length, chest circumference, frame size, and body-mass-index.

10 25. The system of any one of claims 18-24 further including display means for displaying electrode positions in relating to the three-dimensional image and/or three-dimensional model.

26. Non-transitory computer readable medium storing computer
15 implementable instructions which when implemented by a programmable computer cause the computer to

- process a three-dimensional, 3D, anatomical model of the torso of the subject ;
- process a three-dimensional image of the torso of the subject;
- 20 . align the three dimensional image with the three-dimensional model;
- determine a position of each electrode in the three-dimensional model from the three dimensional image; and
- use the positions of the electrodes in the three dimensional model
25 for estimating the distribution, fluctuation and/or movement of electrical activity through heart tissue.

Fig. 1

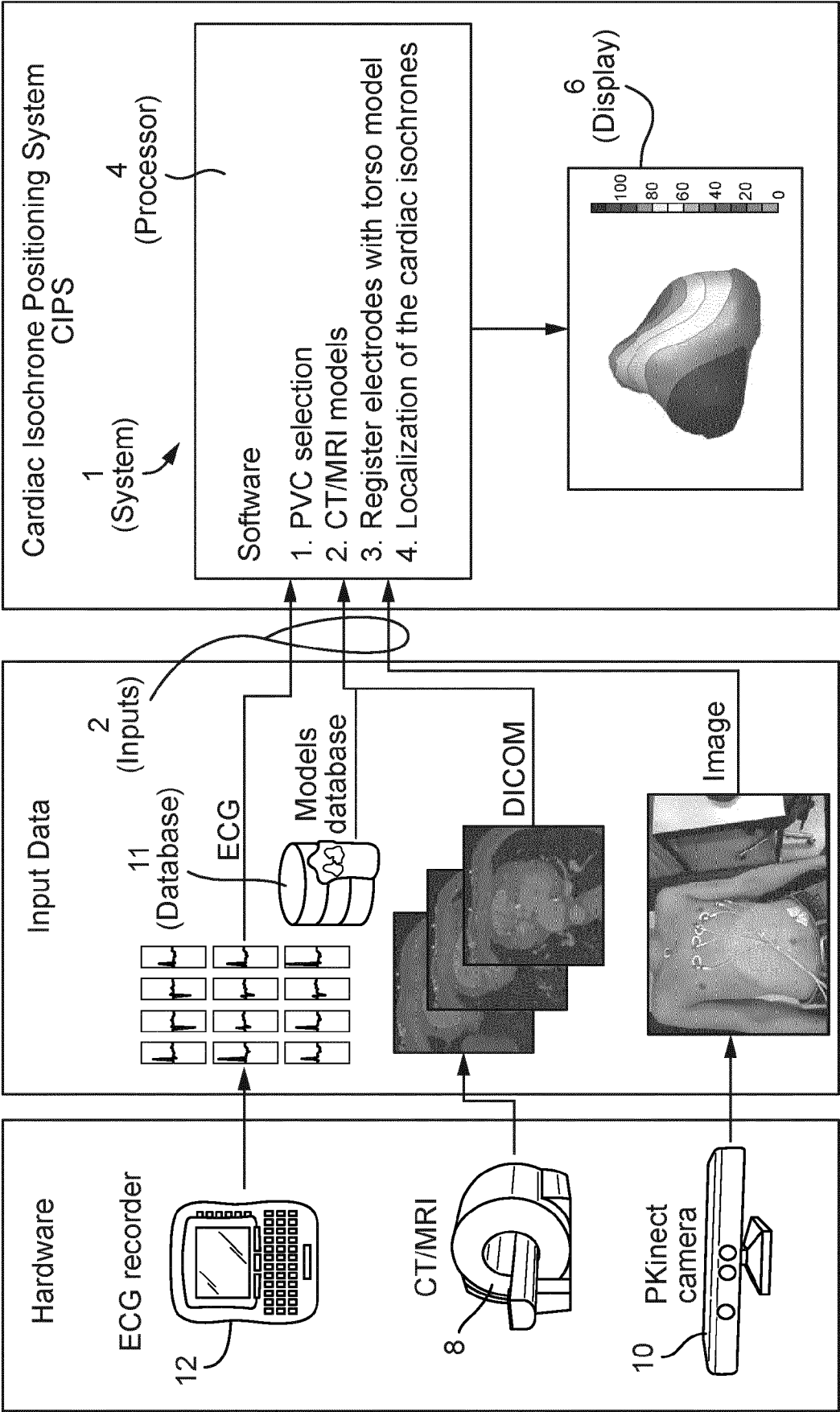


Fig. 2

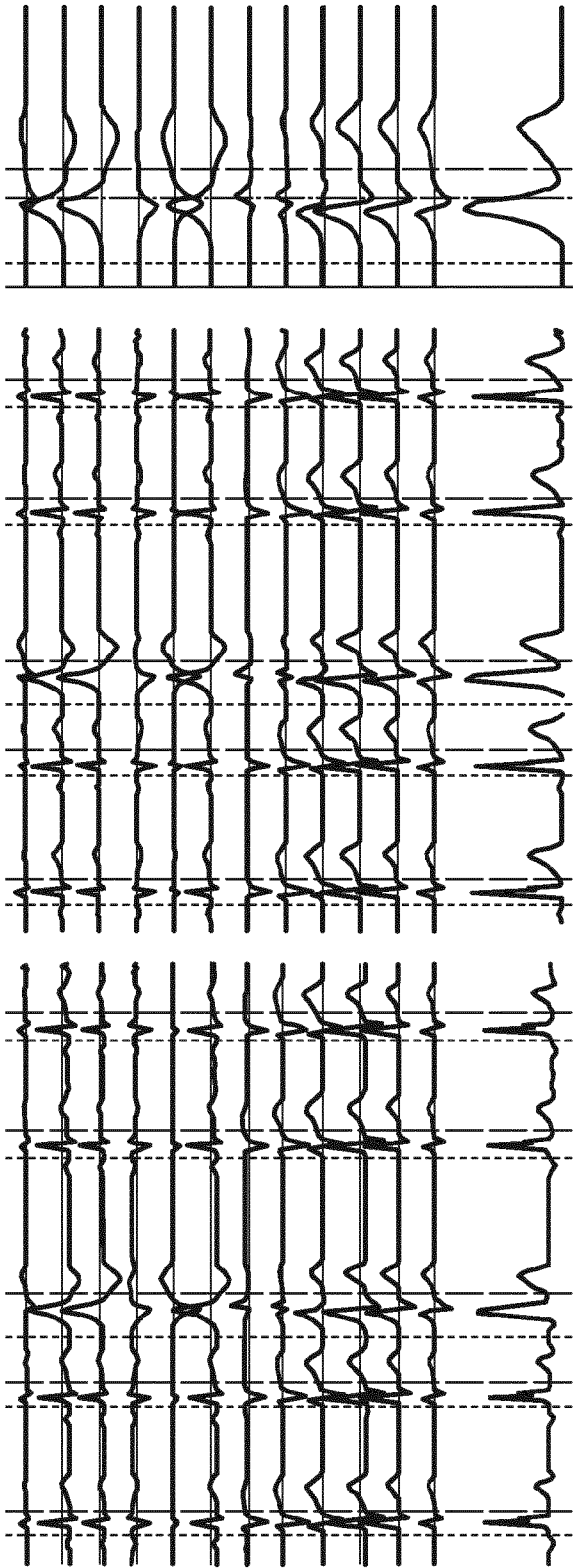


Fig. 3

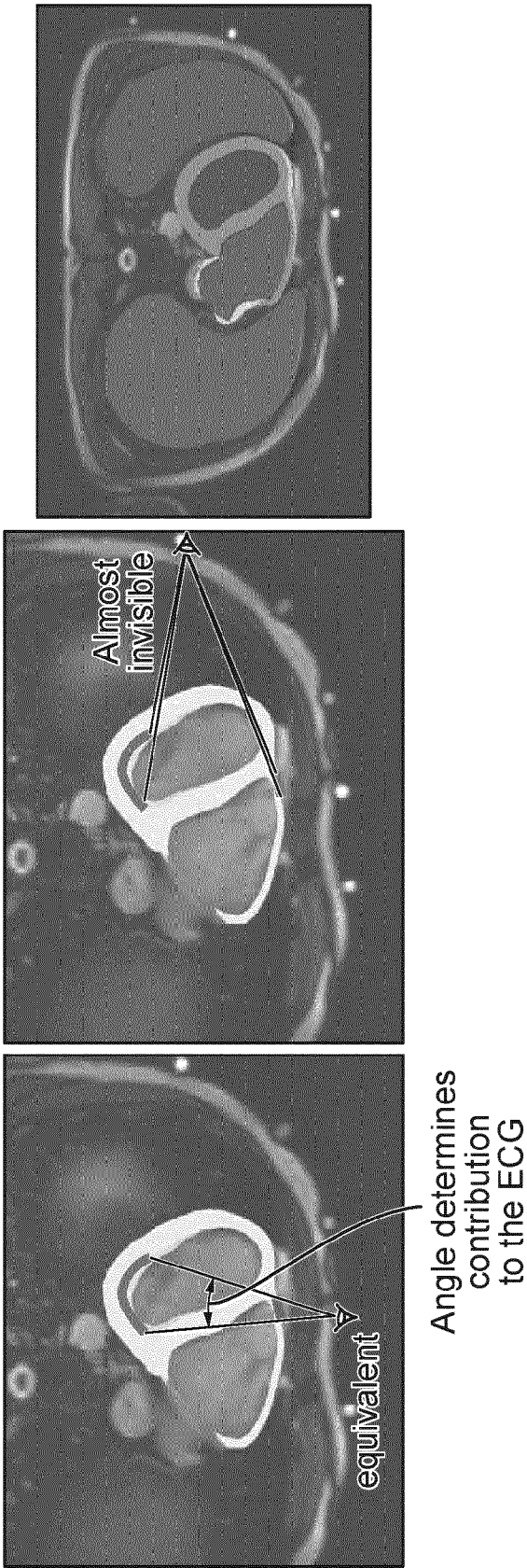
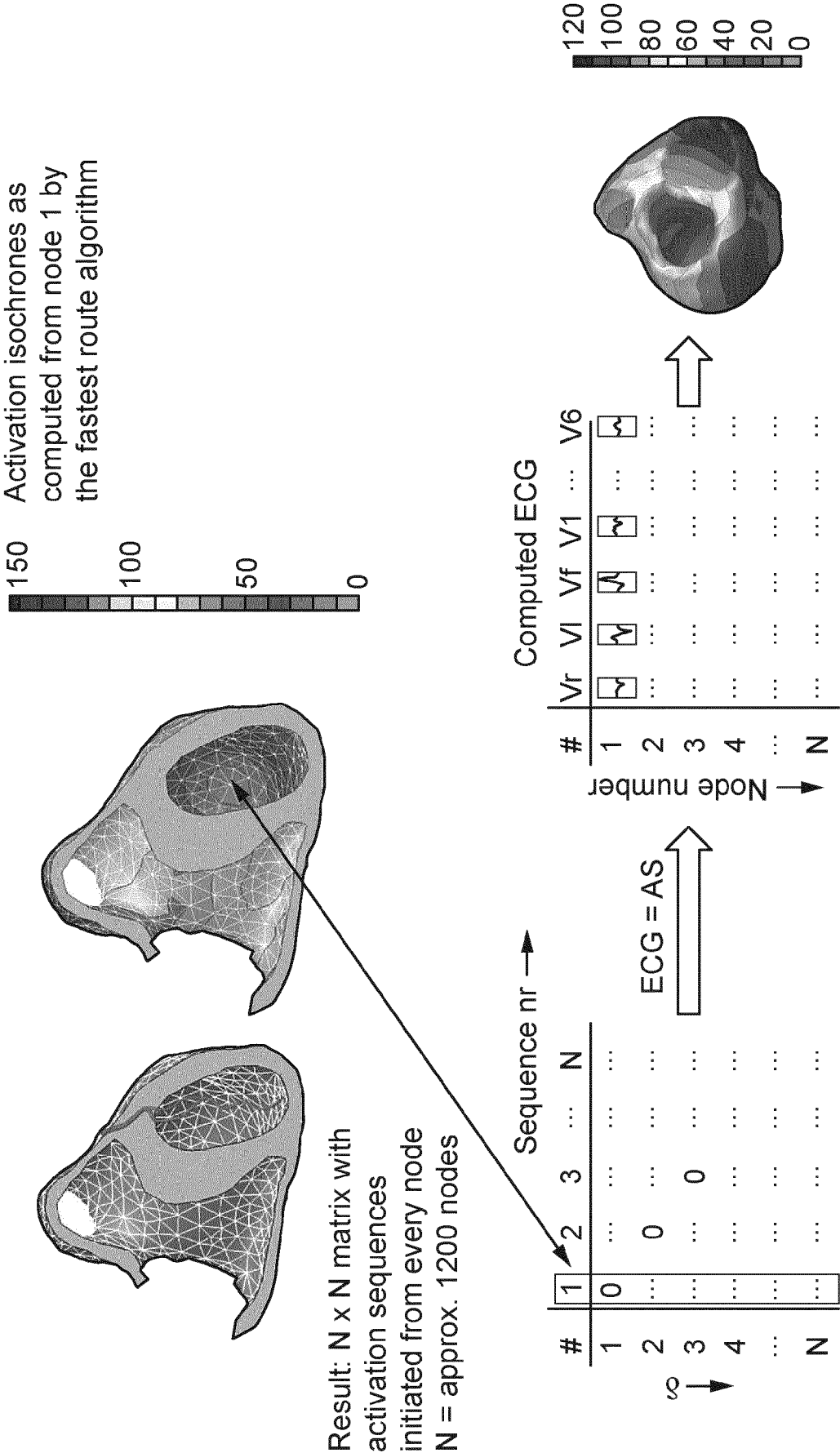


Fig. 4



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Fig. 5

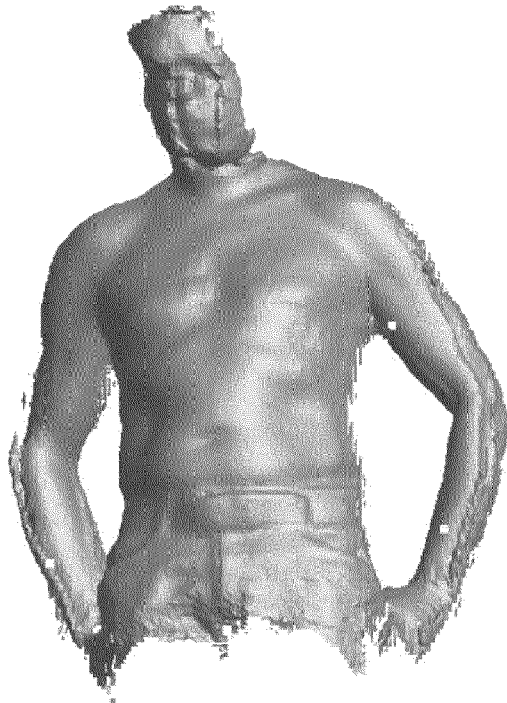
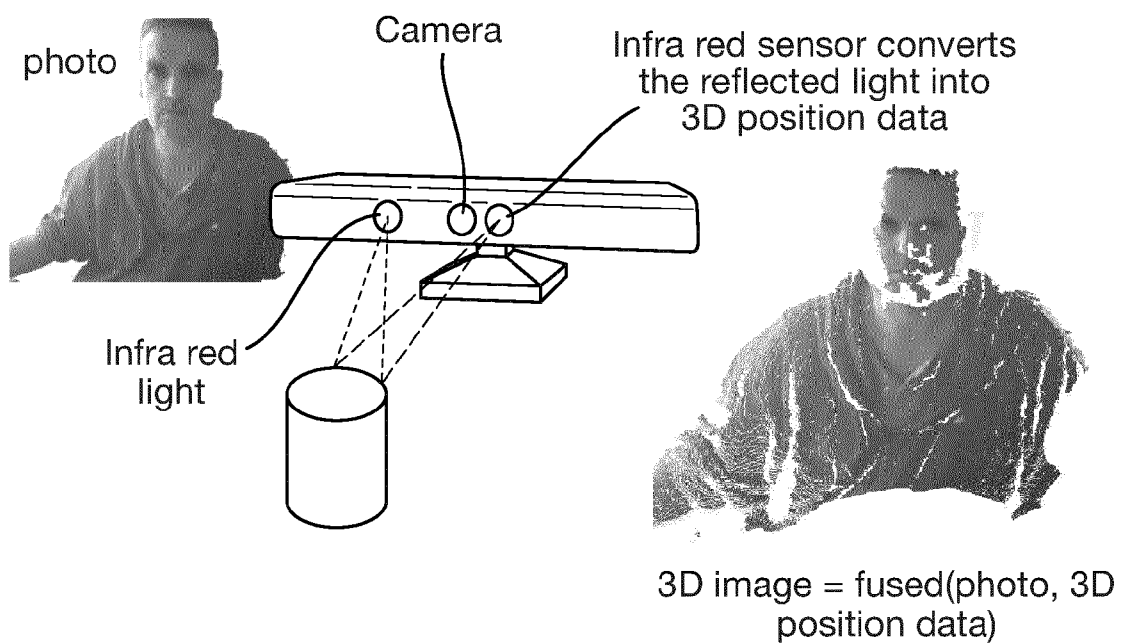


Fig. 6



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Fig. 7

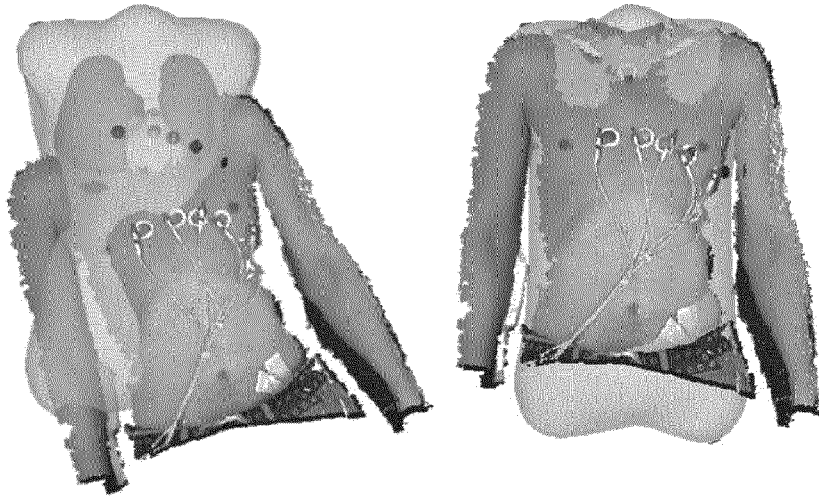


Fig. 8

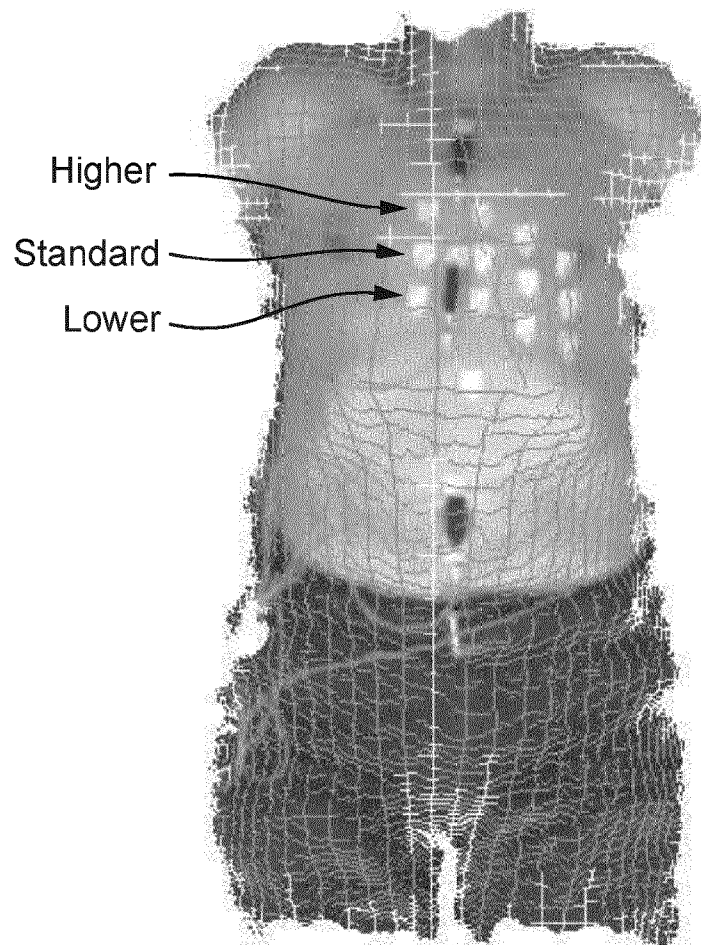
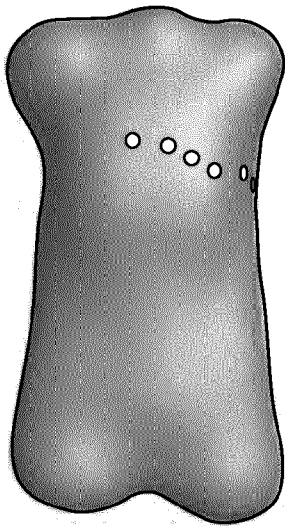
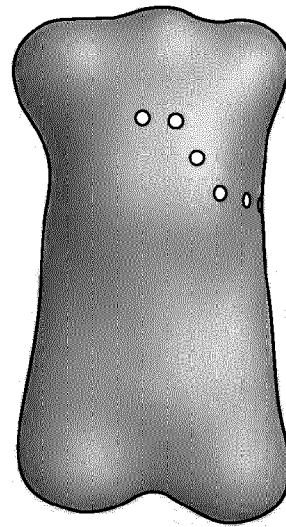


Fig. 9

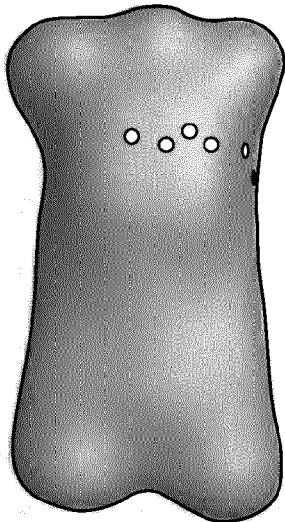
Standard positions



1) V1, V2 higher, V3 standard,
V4 - V6 lower



2) V1, V2, V6 standard,
V3 - V5 higher



3) V1 - V3 higher,
V4 - V6 lower

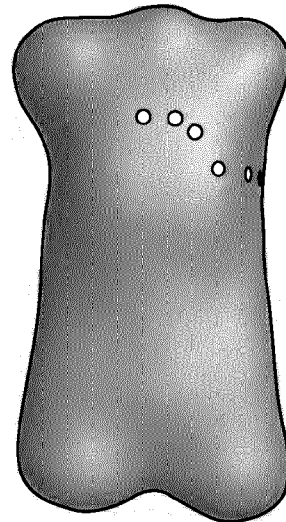


Fig. 10A

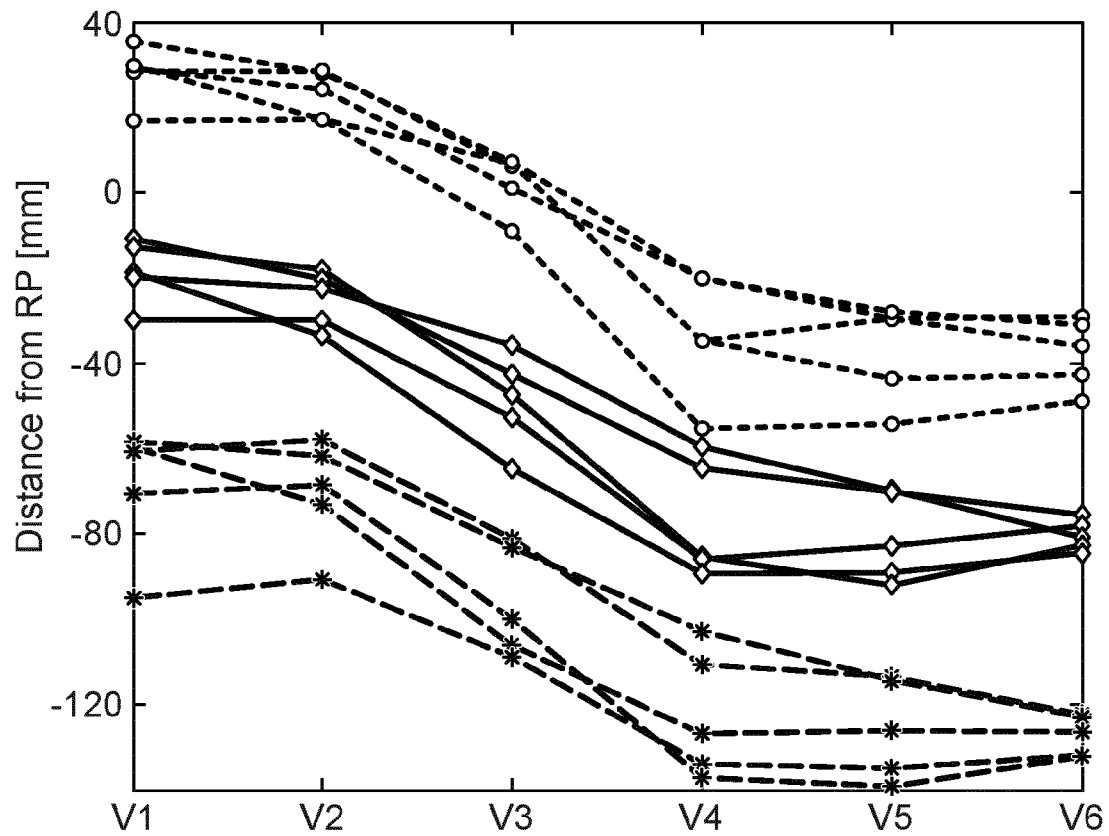
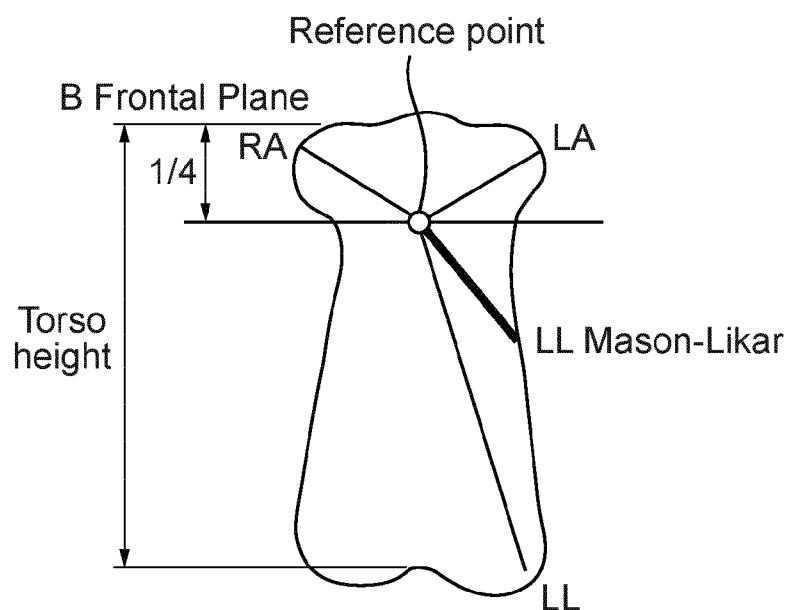
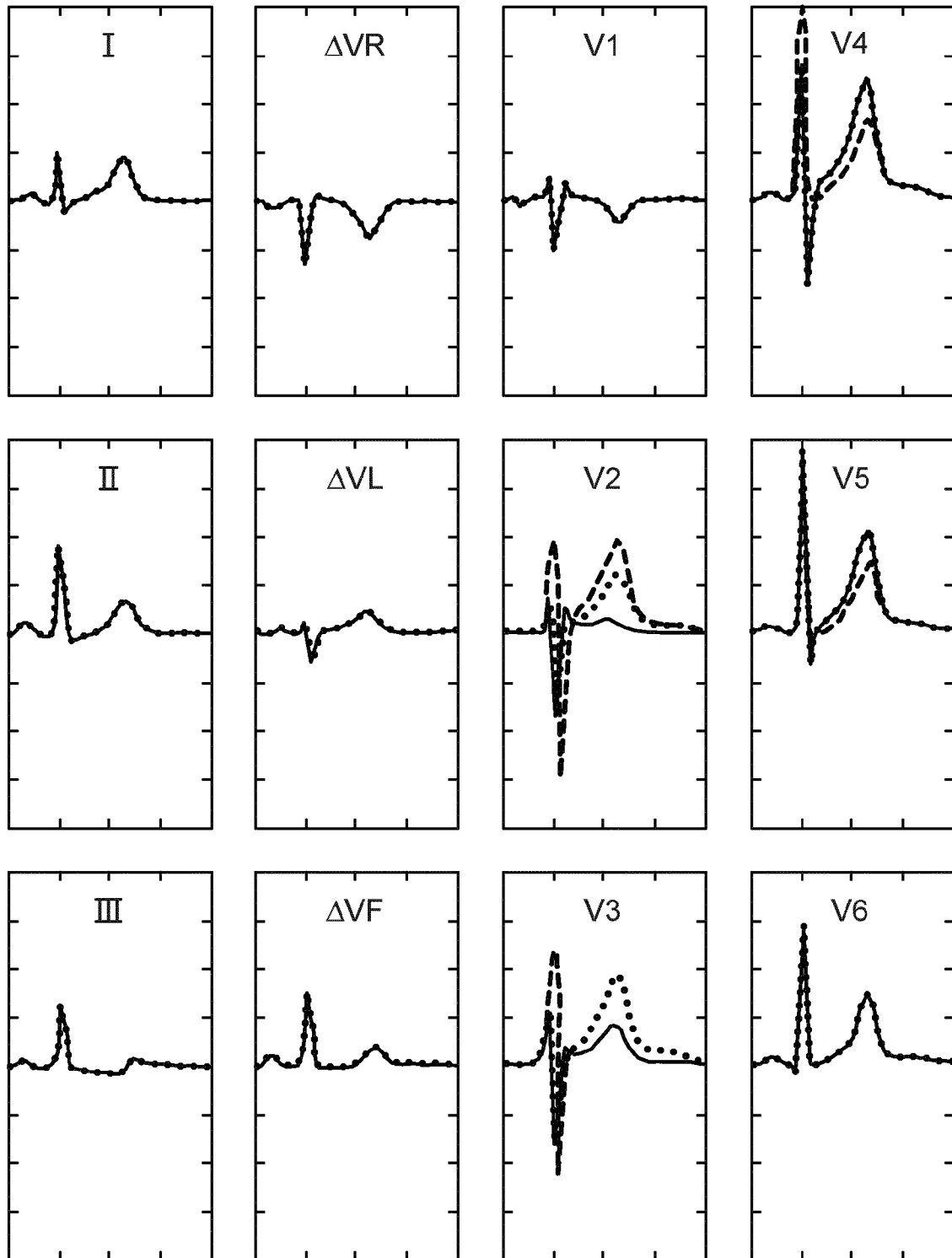


Fig. 10B



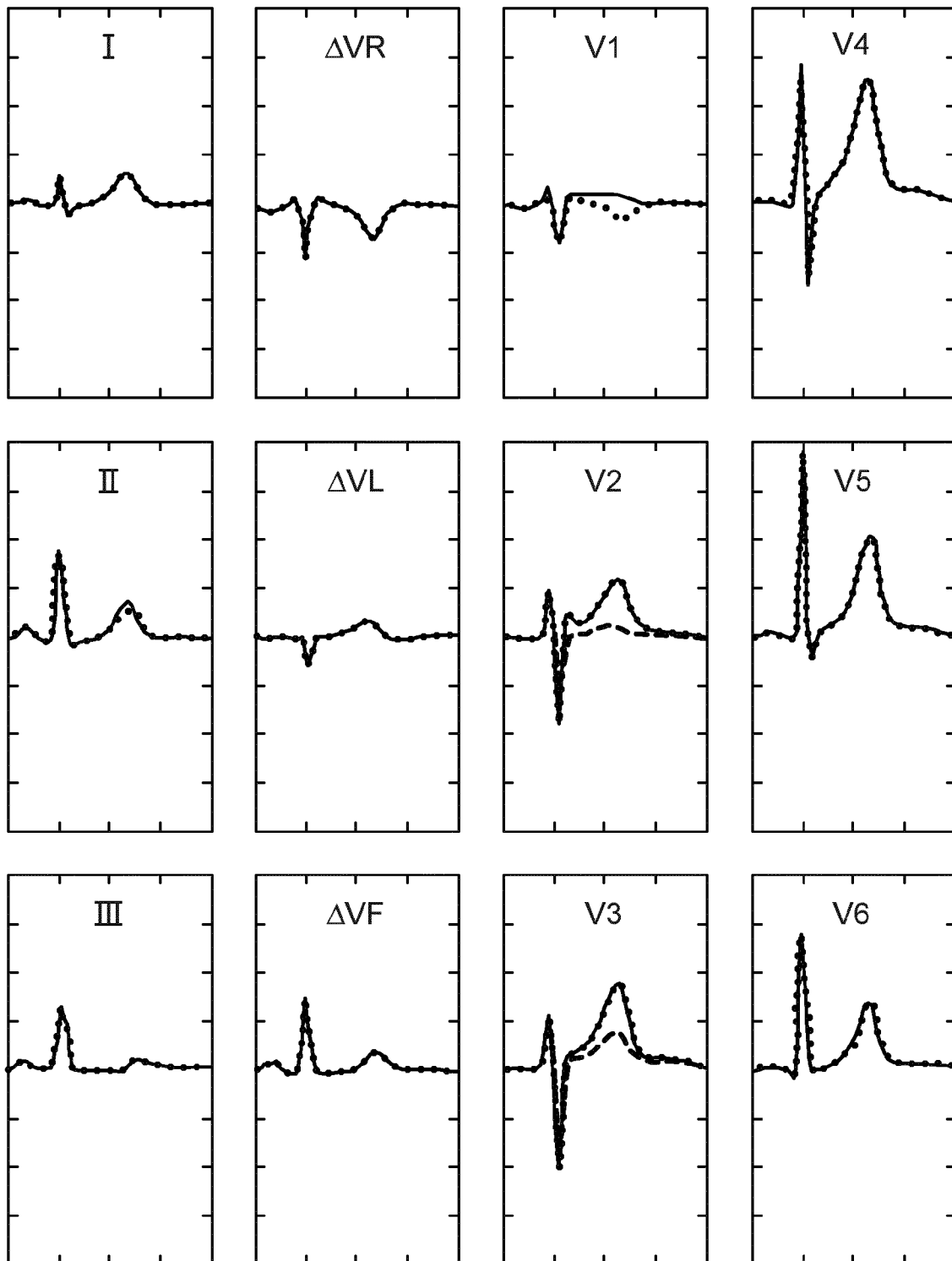
9/10

Fig. 11



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Fig. 12



INTERNATIONAL SEARCH REPORT

International application No

PCT/NL2015/050312

A. CLASSIFICATION OF SUBJECT MATTER

INV. A61B5/04 A61B5/0402 A61B5/0408
 ADD. A61B5/00 A61B5/06 G06T19/20 A61B18/00

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

A61B G06T

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 2012/283587 A1 (GOSH SUBHAM [US] ET AL) 8 November 2012 (2012-11-08) paragraph [0048] - paragraph [0060] paragraph [0095] - paragraph [0099] figures 5, 10 -----	1-26
X	US 2013/184697 A1 (HAN XIAODONG [CN] ET AL) 18 July 2013 (2013-07-18) paragraphs [0003], [0004], [0015], [0027], [0031] -----	1-3, 18, 19, 26
X	EP 2 675 354 A1 (KONINKL PHILIPS NV [NL]) 25 December 2013 (2013-12-25) paragraphs [0030], [0051], [0061], [0064] -----	1, 18, 26



Further documents are listed in the continuation of Box C.



See patent family annex.

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"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&" document member of the same patent family

Date of the actual completion of the international search

11 September 2015

Date of mailing of the international search report

17/09/2015

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Authorized officer

Kowalczyk, Szczepan

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No

PCT/NL2015/050312

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EP 2675354	A1	25-12-2013	CN	103391744 A		13-11-2013
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			US	2015038862 A1		05-02-2015
			WO	2012110940 A1		23-08-2012
			WO	2012110942 A1		23-08-2012

专利名称(译)	估计通过心脏组织的电活动的分布，波动和/或运动		
公开(公告)号	EP3139826A1	公开(公告)日	2017-03-15
申请号	EP2015729254	申请日	2015-05-06
[标]申请(专利权)人(译)	PEACS		
申请(专利权)人(译)	PEACS B.V.		
当前申请(专利权)人(译)	PEACS B.V.		
[标]发明人	VAN DAM PETER MICHAEL VAN DAM EELCO MATTIAS		
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摘要(译)

一种计算机实现的方法，用于处理来自对象的心电图，ECG，电极的测量数据。该方法包括获得对象的躯干的3D解剖模型，以及获得对象的躯干的3D图像。三维图像与三维模型对齐。从三维图像确定三维模型中每个电极的位置。三维模型中的电极位置用于估计通过心脏组织的电活动的分布，波动和/或运动。