(19) Europäisches Patentamt
European Patent Office
Office européen des brevets

(11) **EP 1 675 501 B1**

(12) **EUROPEAN PATENT SPECIFICATION**

(45) Date of publication and mention of the grant of the patent:
04.09.2013 Bulletin 2013/36

(21) Application number: **04770506.6**

(22) Date of filing: **12.09.2004**

(51) Int Cl.:
A61B 5/00 *(2006.01)*

(86) International application number:
PCT/IL2004/000835

(87) International publication number:
WO 2005/025399 (24.03.2005 Gazette 2005/12)

(54) **NONINVASIVE OPTICAL MONITORING OF REGION OF INTEREST**

NICHTINVASIVE OPTISCHE ÜBERWACHUNG EINER INTERESSIERENDEN REGION

METHODE ET APPAREIL DE SURVEILLANCE NON INVASIVE D'UNE REGION D'INTERET DANS LE CORPS D'UN INDIVIDU

(84) Designated Contracting States:
AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HU IE IT LI LU MC NL PL PT RO SE SI SK TR

(30) Priority: **12.09.2003 US 502212 P**
12.09.2003 US 502210 P
16.03.2004 US 553142 P
22.06.2004 US 581376 P

(43) Date of publication of application:
05.07.2006 Bulletin 2006/27

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EP 1 675 501 B1

Printed by Jouve, 75001 PARIS (FR)

Description

FIELD OF THE INVENTION

[0001] This invention relates to a method and apparatus for noninvasive monitoring of parameters of a region of interest in a human body, such as oxygen saturation and/or concentration of analyte(s) in blood.

BACKGROUND OF THE INVENTION

[0002] Monitoring of the well-being of the fetus inside the uterus is very important and is carried periodically with respect to various parameters of the fetus. One of the important parameters to be monitored is oxygen saturation. Various techniques have been developed to enable noninvasive measurements of oxygen saturation.

[0003] For example, U.S. Patent No. 5,494,032 discloses an oximeter for reliable clinical determination of blood oxygen saturation in a fetus. This technique utilizes a multiple frequency light source which is coupled to an optical fiber. The output of the fiber is used to illuminate blood containing tissue of the fetus. The reflected light is transmitted back to the apparatus where the light intensities are simultaneously detected at multiple frequencies. The resulting spectrum is then analyzed for determination of oxygen saturation. The analysis method uses multivariate calibration techniques that compensate for nonlinear spectral response, model interfering spectral responses and detect outlier data with high sensitivity.

[0004] A pulse oximetry based technique for determining the fetal arterial blood oxygenation is disclosed in the following article: A. Zourabian et al., "Trans-abdominal monitoring of fetal arterial blood oxygenation using pulse oxymetry", Journal of Biomedical Optics, Vol. 5, No. 4, October 2000, pp. 391-405.

[0005] U.S. Patent No. 6,041,248 describes a method and apparatus for frequency encoded ultrasound-modulated optical tomography of dense turbid media. The apparatus includes a function generator producing a frequency sweep signal which is applied to an ultrasonic transducer. The ultrasonic transducer produces ultrasonic wave in a turbid medium. Coherent light from a laser is passed through turbid medium where it is modulated by the ultrasonic wave. A photomultiplier tube detects the light which passes through the turbid medium. The signal from the photomultiplier tube is fed to an oscilloscope and then to a computer where differences in light intensity at different frequencies can determine the location of objects in the turbid medium.

[0006] The conventionally used techniques for monitoring the well-being of the fetus inside the uterus utilize measuring the fetal-heart-rate (FHR) by placing sensors on the skin of the mother's abdomen proximal to the fetus. These sensors transmit acoustic waves and provide data indicative of the Doppler shift of an acoustic wave reflected from the fetal heart, enabling calculation of the heart rate based on this shift. A normal fetal-heart-rate (FHR) pattern is usually associated with the delivery of a normal well-oxygenated infant. However, a non-reassuring FHR is not always associated with the delivery of a compromised infant.

[0007] In the case of non-reassuring FHR, the fetal blood oxygen saturation level can be measured only post membrane rupture by either fetal scalp sampling, which measures the pH level of the fetal blood, or by attaching a pulse oximeter to the presenting part of the fetal head during labor. Both of these methods are performed following the rupture of membranes where the fetal scalp and/or cheeks can be reached.

[0008] Another important procedure to be done to monitor the well-being of the fetus consists of assessing the maturity of fetal lungs, which is one of the major concerns of pre-term deliveries. If the baby is delivered and the lungs are not mature, the baby may develop Respiratory Distress Syndrome (RDS), which can result either in fetal death or in long-lasting periods of repeated respiratory difficulty.

[0009] In cases where intervention is considered in the course of pregnancy (such as caesarean section or induction of labor) and there is a need to assess the maturity of the lungs, amniotic fluid is drained. Measuring phospholipids in amniotic fluid as the lecithin/sphingomyelin ratio using the thin-layer chromatography method has been the established clinical procedure for predicting fetal lung maturity. Although it is the clinical "gold standard" method, it remains a time-consuming process, has a large intralaboratory and interlaboratory coefficient of variation, and requires expertise. In addition, the procedure of amniotic fluid drainage itself is invasive and suffers a small risk of abortion. Additional techniques that are used for assessing lung maturity levels include measuring the number of lamellar bodies in a volume of amniotic fluid, measuring the prostaglandin level in amniotic fluid and measuring the fluorescence polarization of a sampled amniotic fluid.

[0010] When a fetus is acutely distressed, for example as a result of strangulation by the umbilical cord, the bowel content, meconium, may be passed into the amniotic fluid (AF). Assessment of meconial contamination of AF is important in the management of late pregnancy. It appears in nearly one third of all fetuses by 42 weeks of gestation. In cases where the fetus gasps during delivery, inhaling the sticky meconium into the upper respiratory tract results in partial airways obstruction. Meconium aspiration syndrome occurs in 0.2% to 1% of all deliveries and has a mortality rate as high as 18%. The disease is responsible for 2% of all prenatal deaths.

[0011] To date, meconium stained amniotic fluid is diagnosed following the rupture of membranes, when the amniotic fluid is drained. However, in cases where the fetus head is tightly fitted in the pelvis, the amniotic fluid is not drained out resulting in misdiagnosis of the potential harmful outcome to the respiratory tract.

[0012] WO 02/08740 A discloses a method and an apparatus for detecting an effect of interactions of electromagnetic radiation with ultrasound radiation at different locations within a region of interest in a scattering medium to thereby enable imaging of said medium. The apparatus has only one detector that collects all scattered light.

[0013] US 5 293 873 A discloses the use of a single photo-detector to analyze a signal containing both modulated ("tagged") and non-modulated ("untagged"), and analyzes the "beat" between these two components. US 5 293 873 A discloses the general components of a system that uses ultrasound tagged light. Meaning that it comprises light sources, light detectors and an ultrasound transducer. The arrangement of these elements should be such that in the absence of a subject between the light source and the detector, the light emanating from the light source will reach the detector or when looking at scattering media, the specific configuration of Figure 3 is presented.

SUMMARY OF THE INVENTION

[0014] There is accordingly a need in the art to facilitate noninvasive monitoring of parameters of a region of interest in a human body, by providing a novel noninvasive method and apparatus.

[0015] The technique of the present invention provides for monitoring blood and/or tissue parameters and/or parameters of fluids of a region of interest in a human body, for example the concentration of an analyte in blood, fluid reservoirs or tissue regions in a human body; as well as fetus condition in utero (e.g., the fetal oxygen saturation level as well as the concentration of analyte in fetal blood; and the maturity of fetal lungs and the presence of meconium, prior to membrane rupture).

[0016] It should be understood that the term ***"region of interest"*** signifies a tissues region or a fluid contained in a reservoir or cavity inside a body. The region of interest may be a fetus region (e.g., fetus head), amniotic fluid, vicinity of blood vessels, etc. The term ***"fetus-related region of interest"*** used herein signifies either one of fetus and amniotic fluid regions.

[0017] The main idea of the present invention consists of non-invasively monitoring the optical properties of a region of interest in a human (or animal) body utilizing the principles of ultrasound tagging of light, which in the present invention is aimed at distinguishing between optical responses of the region of interest in the selected volume (e.g., fetus, amniotic fluid, blood vessel) and the surroundings outside the region of interest; and/or significantly improving pulse oximetry based measurements.

[0018] According to one aspect of the present invention, a body portion (e.g., the abdomen of a pregnant woman) containing a region of interest (fetus) is irradiated with light (e.g., of at least two different wavelengths) and is irradiated with acoustic waves, in a manner to ensure optimal operating condition for measurements. This operating condition is such that the illuminating light and acoustic waves overlap within the region of interest and thus light scattered from the region of interest is "tagged" by acoustic waves (i.e., the frequency of light is modulated by the frequency of the acoustic waves) while substantially do not overlap in a region outside the region of interest, and to ensure that detected light includes a portion of light scattered by the region of interest and tagged by acoustic waves and a portion of untagged light scattered by the region outside the region of interest. This allows for distinguishing between light responses of the region of interest and its surroundings (e.g., fetus and maternal tissues). It should be understood that the term "acoustic wave" refer to acoustic radiation of either one of the following type: continuous wave, pulses, bursts.

[0019] It should be understood that for the purposes of the present invention the term ***"maternal tissues"*** used herein refers to all the tissues within a region surrounding the fetus-related region of interest (fetus itself or amniotic fluid containing the fetus). Considering the region of interest is fetus, the term *"maternal tissues* " refers to maternal tissues, amniotic fluid, and uterine wall.

[0020] According to another aspect of the present invention, the above operating condition is used in pulse oximetry measurements for determining oxygen saturation level in a region of interest (in mammalian blood and/or blood vessels). Measured data that needs to be analyzed is, for example, in the form of a power spectrum of ultrasound-tagged light response of the region of interest, which is practically insensitive to minor movements of regions outside the region of interest, while pure pulse oximetric measurements are highly sensitive to such movements.

[0021] Preferably, the present invention in either of its aspects utilizes obtaining of measured data in the form of time dependent and/or wavelength dependent variations of ultrasound-tagged light signals for at least two wavelengths of illuminating light.

[0022] The present invention provides for non-invasively determining such parameters as oxygen saturation level in the region of interest (e.g., fetus, blood vessel), concentration of a substance or a structure within the region of interest (e.g., fetus, amniotic fluid), the presence and concentration of lamellar bodies in amniotic fluid for determining the level of lung maturity of the fetus, the presence and/or concentration of meconium in the amniotic fluid, presence and/or concentration of blood in the amniotic fluid; as well as for noninvasive monitoring the optical properties of other extravas-

cular fluids such as pleural, pericardial, peritoneal (around the abdominal and pelvis cavities) and synovial fluids. It is important to note that according to the invention, acoustic (ultrasound) radiation used for measurements needs not be focused, since the measurements utilize ultrasound tagging solely for the purposes of distinguishing between light responses of the region of interest and its surroundings, and/or for increasing signal to noise ratio of ultrasound tagging based measurements.

[0023] The present invention utilizes the principles of oximetry for processing the measured data. Accordingly, the illumination with at least two different wavelengths is applied. Preferably, the light response signals are collected over a time period larger than a heart beat, and the principles of pulse oximetry are used to determine the oxygen saturation.

[0024] Preferably, a measurement unit (an illumination assembly, a light detection assembly, and an ultrasound transducer arrangement) is placed in close contact with the respective body portion (e.g., maternal tissues being in contact with amniotic sac containing a fetus). As indicated above, the illumination assembly is configured and operable to illuminate the body portion with at least two wavelengths. The ultrasound transducer arrangement is configured and operable to transmit acoustic waves into the same volume from which the light detector collects scattered light.

[0025] The light detection assembly may be oriented for collecting both back scattered light and forward scattered light.

[0026] Preferably, the present invention utilizes ultrasound imaging, carried out prior to measurements and aimed at determining optimal positioning of the illumination assembly, light detection assembly and acoustic waves propagation to thereby provide the operating condition for measurements. The ultrasound imaging may and may not utilize the same ultrasound transducer arrangement that is used for measurements. Preferably, the invention also provides for using ultrasound radiation for determining such parameters of blood in the region of interest (e.g., fetus) as blood flow, tissue velocity profile, etc. To this end, reflections of ultrasound radiation from the irradiated region are analyzed using any known suitable Doppler-based techniques. The incident ultrasound radiation may be in the form of continuous waves or pulses (gates).

[0027] According to an embodiment of the present invention maternal oxygen saturation level is detected using the same apparatus being used to measure fetal oxygen saturation level.

[0028] The present invention can be used for measuring in more than one fetus presented inside the uterus. In this case, the oxygen saturation level (or other fetal parameters) of each fetus is measured independently using the same apparatus; or several different apparatuses, one for each fetus, all associated with the same control unit (data processing and analyzing utility). Each fetus is located using an ultrasound imaging system, and the optimal arrangement of the light sources, detectors and ultrasound transducers is determined for monitoring the oxygen saturation level of each fetus.

[0029] There is thus provided according to one aspect of the invention a monitoring system for use in non-invasively monitoring at least one parameter of a region of interest in a human body, the system comprising the features of claim 1.

[0030] According to yet another aspect of the invention, there is provided a method for operating a monitoring system configured for noninvasive monitoring at least one parameter of a region of interest in a human body, which system comprises an optical unit and an acoustic unit configured to generate acoustic waves of a predetermined ultrasound frequency range, the method comprising the features of claims 24 or 47.

[0031] The technique of the present invention may be used for noninvasive monitoring of various parameters of human blood and tissue. More specifically, the present invention is useful for monitoring fetal blood conditions and is therefore described below with respect to this application.

BRIEF DESCRIPTION OF THE DRAWINGS

[0032] In order to understand the invention and to see how it may be carried out in practice, preferred embodiment will now be described, by way of non-limiting examples only, with reference to the accompanying drawings, in which:

Fig. 1A schematically illustrates a non-claimed monitoring apparatus according to one embodiment of the invention for monitoring oxygen saturation or a fetus or any other region of interest in a human or animal body;
Fig. 1B exemplifies an operating method of the apparatus of Fig. 1A;
Fig. 2 schematically illustrates a monitoring apparatus, according to another embodiment of the present invention;
Fig. 3A schematically illustrates a monitoring apparatus according to the invention configured to be capable of monitoring the fetal and maternal oxygen saturation;
Fig. 3B illustrates a flow diagram of the main steps in a method of the invention using the apparatus of Fig. 3A;
Fig. 3C shows a flow diagram of a specific example of the method of Fig. 3B;
Fig. 3D schematically illustrates yet another example of a monitoring system of the present invention configured for monitoring the amniotic fluid condition;
Fig. 4 schematically illustrates a monitoring apparatus, according to yet another embodiment of the present invention;
Fig. 5 schematically illustrates a monitoring apparatus, according to yet another embodiment of the present invention;
Figs. 6A and 6B show bottom and side views, respectively, of a flexible probe according to one embodiment of the invention;

Figs. **7A and 7B** show bottom and side views, respectively, of a flexible probe according to another embodiment of the invention.

DETAILED DESCRIPTION OF THE INVENTION

[0033] Referring to **Fig. 1A,** there is schematically illustrated a monitoring apparatus which is not part of the claimed invention, generally designated **100,** constructed and operated as a fetal oxygen saturation monitor. It should, however, be understood that the apparatus configuration is suitable for measuring various other parameters of a fetus 2 (such as the concentration of an analyte in the fetal blood, or the perfusion of an analyte/metabolite in fetal or maternal tissues). It should be understood that the apparatus of the present invention may be used for monitoring blood or tissue parameters of a human being.

[0034] The apparatus **100** includes such main constructional parts as a measurement unit formed by an optical unit **101** including an illumination assembly **101A** and a light detection assembly **101B;** and an acoustic unit including a transducer arrangement **110.** In the present example of Fig. 1A, the detection assembly includes a single detection unit. In this connection, it should be noted that the term "single detection unit" not necessarily signifies a single detector, but may refer to an array of detectors, provided they are associated with the same location with respect to the illuminated region.

[0035] The optical and acoustic units are connectable to a control unit **120.** The control unit **120** is typically a computer system including *inter alia* a power supply, a control panel with input/output functions, a memory utility, a data presentation utility (e.g., display), a data acquisition assembly, and a data processing and analyzing utility (e.g. CPU). The control unit **120** includes a signal generator (e.g. function generator) **120A** to control the operation of the transducer arrangement **110,** and an appropriate utility **120B** for operating the optical unit **101.** The CPU is preprogrammed for receiving measured data coming from the detection assembly **101B** and processing this data to determine the desired parameter, e.g., oxygen saturation of the fetus.

[0036] In the present example, the optical unit **101** is configured as a portable probe including a support structure 103 carrying at least a part of the illumination assembly **101A** and at least a part of the detection assembly **101B.** The illumination assembly **101A** is preferably configured for generating light of at least two different wavelengths. To this end, the illumination assembly may include at least two light emitters (e.g., laser diodes), one emitting narrow bandwidth photons of a wavelength within the range of 605nm to 805nm and the other emitting photons of a wavelength within the range of 800nm to 1300nm. The illumination assembly **101A** may for example be preprogrammed to produce the different wavelength components at different times, or simultaneously produce wavelength components with different frequency- and/or phase-modulation. Accordingly, the control unit 120 is preprogrammed to identify, in a signal generated by the detection assembly **101B,** the corresponding wavelength of the irradiating light, using time, phase or frequency analysis.

[0037] The illumination assembly **101A** may include light emitter(s) carried by the support structure **103** and communicating with the control unit **120** via an output port **121** of the light emitter(s) using wires **106** or wireless signal transmission. Alternatively, the light emitter(s) may be located outside the support structure **103** (e.g., within the control unit **120)** and a light guiding assembly **106** (e.g., optical fibers) is used for guiding light to the output port **121** located on the support structure **103.**

[0038] The detection assembly **101B** includes one or more light detectors. This may be a photomultiplier tube, or preferably an image pixel array, e.g., CCD or an array of photodiodes. It should be noted that, for the purposes of the present invention, an input port **122** of the detection assembly **101B** is larger than that used for imaging by means of diffuse light. In diffuse light imaging, localization is achieved by small input ports, otherwise light from a large volume is collected. According to the invention, light collection from a large volume is desired, since localization is achieved by the ultrasound tagging. Hence, the input port 122 of the detection assembly **101B** is optimized to collect light from a substantially large volume of tissue and/or blood, for example by using large area detectors or CCD cameras or an array of detectors comprising a single input port.

[0039] As indicated above, the detection assembly **101B** may include two separate detectors or an array of detectors. Each detector may be coupled to a bandpass filter configured for transmitting light of a corresponding one of the wavelengths produced by the illumination assembly **101A.The** bandpass filters may include high-pass, low-pass and bandpass optical filters. Alternatively narrow bandwidth detectors can be used.

[0040] It should be understood that the detector(s) may be accommodated outside the support structure (probe) **103,** e.g., may be located within the control unit 120, and returned light (light response) may be guided from the input port **122** of the detection assembly via light guiding means **105** (e.g., optical fibers). It should also be understood that the connectors **105** and **106** may be electric wires connecting the control unit **120** to the illumination assembly and detection assembly located on the probe **103,** or the connection may be wireless.

[0041] Thus, generally, the terms *"illumination assembly"* and *"detection assembly"* or *"detection unit* " as carried by a support structure which is brought in contact with a human body, are constituted by at least light transmitting and receiving ports. Probes (kits) of the present invention including light transmitting and receiving ports and preferably also

acoustic ports, will be described further below with reference to Figs. 6A-6B and 7A-7B.

[0042] The control unit **120** (its signal generator **120A** and CPU) is connected to the transducer arrangement **110** using cables **107** and/or using wireless means.

[0043] An example of a monitoring method, using the apparatus **100,** will now be described with reference to **Fig. 1B**.

[0044] Step 1: Prior to performing the actual measurements, an optimal positioning of the assemblies of the optical unit and of the acoustic unit with respect to a region of interest (fetus) is provided to satisfy an operating condition for measurements. The operating condition is such that both light (at least a portion of the illuminating light) and the acoustic radiation irradiate the same region (volume) simultaneously, while substantially not overlapping in outside regions (maternal tissues **11**); and that the detection assembly detects light scattered from both the region of interest and regions outside thereof. Preferably, the region where the ultrasound and light overlap is the region of interest (fetus 2), but generally a region outside the region of interest may be selected to be overlapping region. Generally speaking, the positioning of the optical unit and transducer arrangement with respect to the fetus **2** is such as to enable distinguishing between scattered photons collected from the maternal tissues **11** and from the fetus 2 using ultrasound tagging of light.

[0045] This pre-positioning utilizes an ultrasound imaging of the region of interest. To this end, an imaging system of any known suitable configuration may be used, which may utilize the same transducer arrangement **110** used for the measurement process or another ultrasound transducer(s). Ultrasound images of the maternal tissues **11** (e.g. abdomen, uterus) and of the fetus **2** are acquired and analyzed by the control unit **120** (which in this case is installed with a suitable image processing utility) or another appropriately preprogrammed computer system, to determine the optimal positioning of the optical unit **101** (namely the illumination assembly **101A** and the detection assembly **101B)** relative to the fetus and relative to the acoustic unit **110.**

[0046] It is important to note that according to the invention, ultrasound tagging is utilized for the purposes of "tagging" a light response from a selected region of interest (fetus), thus enabling processing of detected tagged and untagged light portions to identify the light response of the selected region of interest. This is contrary to the known techniques where ultrasound tagging is used for imaging purposes to enable two and three-dimensional imaging.

[0047] The illumination assembly **101A** is preferably placed at the shortest distance to the fetus **2,** preferably to the fetal head. It should be understood that other organs or tissues of fetus **2** may be chosen for measurements as well. Preferably, the illumination assembly **101A** is placed such that a light path between the illumination assembly **101A** and the fetus **2** is that suffering the least attenuation at the wavelengths chosen for measurements, as compared to the other paths. The distance between the illumination assembly **101A** and the detection unit **101B** is preferably determined to be at least equal to and preferably larger than the distance between the illumination assembly **101A** and the head of the fetus **2.**

[0048] Preferably, the support structure **103** is configured to define various positions for attaching the detection unit **101B** and/or the illumination assembly 101A to be at the correct distance between them. For example, these positions may be determined by using a sliding bar (not shown) that is attached to the light detection unit **101B** and can be secured to the support structure **103** using a small screw or a latch. Alternatively, a plurality of light output ports and/or plurality of light input ports are provided on the support structure **103** and the control unit **120** operates to select the appropriate light source(s) and detector(s) (light output port and light input port) for measurements. This selection is based on the signals generated by each detector and on the geometry of the maternal tissues and the position of the fetus.

[0049] Additionally, the illumination assembly **101A** and the detection unit **101B** are placed such that the light output port **121** of the illumination assembly and the light input port **122** of the detection assembly are in close contact with an outer skin **10** of the maternal abdomen. Optionally, an index matching oil or adhesive is used to reduce reflection of light from the outer skin **10.** The adhesive may be used to secure the apparatus **100** to a specific location on the maternal abdomen. Alternatively, or additionally, a belt can be used to prevent movement of the apparatus **100.**

[0050] Once the position of the illumination assembly **101A** and the detection assembly **101B** is fixed, the ultrasound transducer arrangement **110** is positioned such that acoustic waves **150** generated by the transducer arrangement **110** are coupled into the maternal abdomen, propagate through uterus and amniotic fluid, and reach the fetus 2. For example, in the case the illumination assembly **101A** and detection assembly **101B** are appropriately placed to illuminate and collect light scattered by the fetus head, the transducer **110** is placed such that the acoustic waves **150** propagate through the same region of the head from which scattered photons **155** are detected by the detection assembly **101B.** The transducer **110** may be fixed to an appropriate location using an ultrasound transmitting adhesive or using gel for acoustic coupling, and optionally a belt for fixing the transducer to one location. Alternatively, the ultrasound transducer arrangement **110** is configured as a phased array transducer producing a focused beam that is being scanned over a region of skin **10** overlaying the maternal tissues **11.**

[0051] Step 2: Having optimally positioned the illumination assembly **101A,** detection unit **101B** and ultrasound transducer arrangement **110,** measurements are taken by appropriately operating the apparatus **100.** The control unit **120** actuates the illumination assembly **101A** to generate photons **155** of at least two wavelengths. The photons **155** propagate through maternal tissues, through the uterine wall, and reach the fetus **2.** A portion of photons **155** is absorbed by hemoglobin in the fetus blood, and a portion of photons **155** is scattered by tissues and cells of the fetus **2** and of the

mother. A portion of the scattered photons **155** propagates through the maternal tissues **11** and reaches the detection assembly **101B.** The latter collects at least a part of this portion of the scattered photons **155** and generates measured data indicative thereof, i.e., an electric signal in response to the number of photons that are collected at the input port **122** of the detection unit at a specific point in time for each irradiating wavelength generated by the illumination assembly **101A.**

[0052] It should be noted that, in the case the detection assembly **101B** is spaced from the illumination assembly **101A** a distance equal to or larger than twice the minimal distance between the fetus **2** and the illumination assembly **101A,** the detection unit **101B** collects both back and forward scattered photons. In the case the illumination assembly **101A** includes a laser with a coherence length larger than the optical path of scattered photons in the tissue, an interference pattern resulting in a speckle image is generated on the input port **122** of the detection assembly. In order to detect and analyze the speckle image, the detection assembly **101B** may include an array of detectors with an individual size comparable to that of individual speckle. The illumination assembly **101A** may be configured and operable to produce a continuous stream of photons **155** (CW), or a time modulated stream (at a certain frequency *W*), or a train of pulses.

[0053] In the present example of Fig. 1A, a portion of detected photons scattered by the fetus **2** are tagged by ultrasound waves, while detected photons scattered by the maternal tissues **11** are untagged. As photons **155** illuminate the fetus **2,** the transducer **110** generates acoustic waves **150** that propagate through maternal tissues to irradiate the same volume of the fetus **2** from which scattered photons **155** are detected by the detection assembly **101B.** The interaction of acoustic waves **150** with photons **155** results in that the frequency of photons **155** is shifted by the frequency of acoustic waves **150** (acousto-optic effect). These frequency-shifted or frequency-modulated photons are thus "tagged" and can be identified. The detection assembly **101B** detects both the frequency shifted photons ("tagged photons") and the photons at the original frequency ("untagged photons") at both wavelengths. The detection assembly **101B** generates measured data (electric signals) in response to both the tagged and untagged photons.

[0054] Step 3: The control unit **120** processes the measured data using an appropriate algorithm according to the type of detection used. For example: in the case of a single (large area) detector, heterodyne detection (e.g., as described by [Lev A. and B.G. Sfez Optics Letters (2002) 27 (7) 473-475]) is used to separate data indicative of the signal of the tagged photons; when a CCD camera is used and a full speckle image is detected, the technique described by [Leveque-Fort et al. in Optics Communication 196 127-131 (2001)] is used to determine the optical signal of photons scattered from the particular volume which is tagged by ultrasound waves.

[0055] Using the above, or other suitable, techniques, it is possible to determine the effective attenuation of photons 155 as they propagate through the fetus 2. To this end, ultrasound radiation may be applied such that acoustic waves 150 propagate through different depths of the fetal tissues (e.g., by displacing the transducer arrangement with respect to the body or by using a phase array transducer). Accordingly, the absorption coefficient and the reduced scattering coefficient can be isolated in the two wavelengths chosen for illumination. For example, using a similar equation to equation 4 of Lev et al. referenced above:

$$x = \frac{\gamma_6^O - \frac{\mu_{eff,6}}{\mu_{eff,8}}\gamma_8^O}{\left[\left(\gamma_8^H - \gamma_8^O\right) - \frac{\mu_{eff,6}}{\mu_{eff,8}}\left(\gamma_6^H - \gamma_6^O\right)\right]}$$

it is possible to determine the oxygen saturation level of the fetus. Here, x is the fraction of deoxyhemoglobin, γ are the molar extinction coefficients of oxyhemoglobin(O) and deoxyhemoglobin (H) at both wavelengths (in the referenced paper, 6 stands for 690nm and 8 for 820nm) and $\mu_{eff,6}$ and $\mu_{eff,8}$ are the measured attenuation coefficients at 690 and 820nm, respectively.

[0056] The ultrasound transducer **110** is kept at a specific location, which is optimal for propagating acoustic waves through the same volume of the fetal body (such as the head) from which scattered photons **155** are detected by the detection assembly **101B.** The beam size of transducer **110** is such that the cross section volume between photons **155** and acoustic waves **150** is as large as possible, whether focused or not, for increasing the signal to noise ratio (SNR) of the detection system, without compromising the sensitivity to detect only the fetal oxygen saturation and not the maternal one.

[0057] As indicated above, the present invention utilizes ultrasound tagging for the purposes of distinguishing between light responses of the regions of the fetus **2** and the region of maternal tissues **11.** Preferably, the frequency of acoustic waves generated by the transducer arrangement **110** is in the range of 50kHz-8MHz, and more preferably - lower than 1MHz. This frequency range provides a better SNR for ultrasound tagged light, as it increases the fraction of photons

that are tagged, but results in a lower focusing resolution. This is in contrast to imaging modalities known in the art, where it is desired to improve the imaging resolution and thus higher frequencies and minimal cross section are conventionally chosen. In addition, the detection assembly **101B** collects forward and back scattered photons according to the preferred geometry of FOSM **100.** Therefore, a number of photons collected by the detection assembly **101B** is higher than in cases of reflection based imaging disclosed in the above references, thus enabling an improved SNR. Hence, the invention enables using safer light energies for illumination. It should be understood that such a configuration, although rendering high resolution imaging more complicated than the case where primarily back scattered photons are detected, is highly suitable for fetal oximetry.

[0058] The control unit **120** analyzes both back and forward scattered tagged photons to determine the optical attenuation of light propagating through the fetal head. Consequently, the control unit **120** needs not perform high resolution imaging of the fetus, but rather just analyze the collected photons **155** scattered by a large volume of the fetal tissues.

[0059] Step 4: The control unit **120** processes that portion of the measured data, which is associated with tagged photons scattered from the fetus (identified as described above), to determine the desired parameter of the fetus - oxygen saturation in the present example. Two modalities can optionally be used to determine the oxygen saturation level of a fetus intrautero, one being based on measuring the average oxygen saturation level (known as oximetry) and the other being based on measuring the oxygen saturation level correlated with changes in the blood volume during the cardiac cycle (known as pulse oximetry).

[0060] Oxygen saturation *S* is a ratio between the concentration of oxygenated hemoglobin [HbO] and the total concentration of hemoglobin [HbT] in blood:

$$S=[HbO]/[HbT] \ (*100\%) \qquad [1]$$

$$[HbT]=[HbO]+[Hb] \qquad [2]$$

wherein [Hb] is the concentration of deoxygenated hemoglobin.

[0061] The saturation *S* can be extracted from the attenuation coefficient measured for at least two wavelengths λ_1 and λ_2, where the molar absorption and scattering coefficients for Hb and HbO at each wavelength are known in the literature. It should be noted that more than two wavelengths can be used, to improve sensitivity of the measurement.

[0062] As the arteries expand, a blood volume [HbT] is increased by [ΔHbT], therefore absorption changes periodically. The optical attenuation at λ_1 and λ_2 is measured at predetermined points (for example, the maxima and minima of a power spectrum of the tagged signal or the processed tagged signal, as defined below) generated by the detection assembly **101B** during a cardiac cycle. As indicated above, in the present example tagged signal is that associated with the fetus. The saturation *S* can be calculated from differences in attenuation of light (ΔOD) at each wavelength between maxima and minima.

$$\Delta OD^{\lambda} = (\mu^{\lambda}_{HbO}[HbO] + \mu^{\lambda}_{Hb}[Hb])d = (\mu^{\lambda}_{HbO}S + \mu^{\lambda}_{Hb}(1-S))[HbT]d \qquad [3]$$

wherein $\mu^{\lambda}_{HbO}, \mu^{\lambda}_{Hb}$ are the molar attenuation coefficient of oxygenated and deoxygenated hemoglobin respectively, at wavelength λ ($\lambda=\lambda_1,\lambda_2$) and *d* is the distance from the source to the target tissue (fetal or maternal).

[0063] Defining the ratio R between ΔOD^{λ} at each wavelength λ_1 and λ_2:

$$R = \frac{\Delta OD^{\lambda 1}}{\Delta OD^{\lambda 2}} = \frac{[\mu^{\lambda 1}_{HbO}S + \mu^{\lambda 1}_{Hb}(1-S)]}{[\mu^{\lambda 2}_{HbO}S + \mu^{\lambda 2}_{Hb}(1-S)]} \qquad [4]$$

saturation S is extracted from equation [4] when $\Delta OD^{\lambda 1}$) and $\Delta OD^{\lambda 2}$ are measured and the molar attenuation coefficients are known.

[0064] The control unit **120** analyzes signals generated by the detection assembly **101B** in response to each wavelength λ_1, λ_2 generated by the illumination assembly **101A.** The signals corresponding to tagged photons **155** are selected by the detection assembly **101B** using heterodyne detection, or by the control unit **120** using frequency analysis and/or speckle imaging. These signals are termed "tagged signals". The time dependent amplitude and/or phase of the tagged signals for each wavelength λ_1, λ_2 is stored in the memory of the control unit **120,** over a specified period of time of at least one fetal heart cycle. To determine the oxygen saturation level of the fetus, the control unit **120** determines the changes in attenuation of tagged signals at each wavelength.

[0065] Considering the determination of oxygen saturation of fetus 2 based on oximetry, the time averaged signals generated by the detection assembly **101B** in response to the tagged photons **155** of at least two illuminating wavelengths reaching the input port **122,** are used to determine the oxygen saturation level. Time averaging can be performed over longer time scales than the duration of a fetal heart cycle.

[0066] Considering pulse oxymetry used for determining oxygen saturation of a fetus, the temporal changes (due to the fetal cardiac cycle) in the blood volume of the fetus are monitored by the control unit **120** by monitoring the low-frequency changes (1-2.5Hz) in the signals generated by the detection assembly **101B** in response to the tagged photons **155**of at least two illuminating wavelengths reaching the input port **122** of the detection assembly. Since the ultrasound frequency is orders of magnitude higher than the fetal heart rate, it is possible to average the signals responsive to tagged photons over a fraction of the fetal heart cycle to improve the SNR of the measurement. Using methods of pulse oximetry, both the oxygen saturation and the pulse rate are determined simultaneously.

[0067] The control unit **120** displays the determined fetal oxygen saturation level, along with fetal heart rate, as a function of time. Fetal heart rate is determined by low-frequency analysis of the tagged signals. The control unit **120** optionally alerts using a suitable indication utility (e.g. sound and/or light signal), when oxygen saturation level drops below a certain threshold (for example 30% or 40%), or when fetal heart rate changes abnormally.

[0068] Preferably, monitoring apparatus **100** provides for calibrating for movements of fetus 2 during the measurement. To this end, the control unit **120** operates to determine the position of fetal head relative to the apparatus **100.** This is carried out either periodically, or upon detection of signals not corresponding to a normal heart rate or oxygen saturation level. The control unit **120** sends a control signal to the transducer arrangement **110** initiating an ultrasound echo measurement. In an echo measurement, the transducer arrangement **110** transmits acoustic waves **150** into maternal tissues, and collects acoustic waves **150** reflected by fetal and maternal tissues. The reflected signals are analyzed by the control unit **120** (using any conventional ultrasound imaging technique) to determine a position of the fetal head. If a substantial movement is detected, the control unit **120** sends a signal to the transducer arrangement **110** to optionally change a direction of acoustic waves **150** in a new direction corresponding to a new position of the fetus **2.** Additionally or alternatively, the control unit **120** alerts the operator of apparatus **100** to readjust the position of the apparatus accordingly.

[0069] Although the above description refers to a single fetus, it should be understood that the technique of the present invention can easily be adapted for monitoring several fetuses intrautero. The location of each fetus is determined using an ultrasound imaging system, and different monitoring apparatuses (i.e., optical and acoustic units) or an integrated multi-fetuses apparatus are used. All the monitoring apparatuses can be hooked to the common control system that controls each apparatus separately, and processes the signals using the same or different processing utilities. A display shows the oxygen saturation level of each fetus separately along with its heart rate and other parameters.

[0070] The present invention also provides for advantageously utilizing the principles of ultrasound tagging of light in pulse oximetry for monitoring oxygen saturation in a localized region of interest in a human or animal body (without a fetus). Turning back to **Fig. 1A**, the optical unit **101** is configured as a pulse oximeter, namely includes an illumination assembly **101A** configured to generate light of at least two different wavelengths and a light detector **101B**; and is used in combination with the transducer arrangement to significantly improve the pulse oximetric measurements. The monitoring apparatus **100** may be configured to operate in a transmission mode (light transmission based detection), such as the conventional pulse oximeter placed on a finger or earlobe. In this case, the support structure **103** is located such that the illumination assembly **101A** is colinear with the detection assembly **101B:** the illumination assembly **101A** is placed at one side of the tissue and the detection assembly **101B** is placed at the opposite side of the tissue, therefore ballistic and scattered light emitted from illumination assembly **101A** are detected by detection assembly **101B.** The transducer arrangement **110** is placed such that acoustic waves overlap with an illuminated region in the region of interest from which scattered light reaches the detection assembly **101B,** which is preferably the region encompassing a blood vessel (e.g. an artery) or a collection of arterial vessels. In other applications, requiring reflection based detection from a region of interest ("reflection mode"), the apparatus **100** is located as described for the fetus-related application, where the region of interest preferably encompasses a blood vessel (e.g. an artery) or a collection of arterial vessels. Such an arrangement is superior to conventional pulse oximeter as it is not affected by incoherent ambient light, and more importantly is less affected by motion of the tissue relative to illumination and detection assemblies, as long as the region

of interest is kept illuminated and the acoustic waves propagate through it.

[0071] It should be understood that using the ultrasound tagging of light in the pulse oximetry based measurements significantly improves the measurements, since the measured power spectrum of an ultrasound-tagged light signal is practically insensitive to movements of the region of interest under measurements, which is the common problem of the typical pure pulse oximetry measurements.

[0072] **Fig. 2** exemplifies another configuration of a fetal oxygen saturation monitor, generally designated 200, outside the scope of the present invention. To facilitate understanding, the same reference numbers are used for identifying components that are common in all the examples of the invention. In the apparatus **200,** an illumination assembly **101A** includes a light source **201A** mounted within a control unit **120** and an optical fiber **201B** guiding light from the light source to the region of interest (fetus). The optical fiber **201B** is inserted into the vaginal track of the pregnant woman (using suitable means, for example a flexible support structure which is not specifically shown). The optical fiber **201B** is positioned such that it is in close contact with the cervix or to amniotic membranes prior to rupture. Optionally, following membrane rupture optical fiber 201B is attached to the presenting part of the fetal head with the aid of a support structure. A light detection assembly **101B** is placed on the maternal abdomen, such that it collects photons scattered by the fetal blood. The detection assembly **101B** is connected to a suitable utility of the control unit **120** via wires (as shown in the figure) or wireless. An ultrasound transducer arrangement **110** is also placed transabdominally such that acoustic waves **150** can propagate through the part of the head of a fetal 2 being closest to the optical fiber **201B** and detection assembly **101B.** In some cases, it may be advantageous to introduce the transducer arrangement **110** also through the vaginal track.

[0073] Reference is made to **Fig. 3A** exemplifying a preferred embodiment of a monitoring apparatus **300** according to the invention. The apparatus **300** is configured generally similar to the above-described apparatus **100,** namely includes an acoustic transducer arrangement **110,** and an optical unit **101** having a probe 103 carrying at least a part of an illumination assembly **101A** and at least a part of a detection assembly. Here, the detection assembly is formed by two detection units **101B** and **101C** associated with different locations with respect to the illuminated region defined by a location of the illumination assembly **101A.** The additional detection unit **101C** is also attached to the support structure (probe) **103** and is connected to a control unit **120** via electrical cable (not shown) or wireless means.

[0074] One of the detection units - detection **101C** in the present example, is located in the proximity of the illumination assembly **101A,** and the other detection unit **101B** is located at a larger distance from the illumination assembly. In the present example, the detection unit **101C** is located between the illumination assembly **101A** and the detection unit **101B.** Generally, the arrangement of the illumination assembly and detection units is such that one of the detection units (detection unit **101C)** is located close to the illumination assembly to therefore detect photons **165** scattered from regions outside the fetus **2** (i.e., light reaches the detector **101C** prior to reaching the fetus); and the other detector **101B**) is more distant from the illumination assembly and thus detects photons **155** scattered from the fetus and propagating through the maternal tissues region and being thereby affected by the maternal tissues.

[0075] The transducer arrangement **110** is aligned and/or scanned, such that it transmits acoustic waves **150** to the volume within the illuminated region of the fetus from which photons **155** are detected by the detection unit **101B,** and substantially does not irradiate the maternal tissue region from which photons **165** are collected by the detection unit **101C.**

[0076] Signals (measured data) generated by the detection unit **101C** may be used by the control unit **120** to determine the maternal oxygen saturation level and heart rate simultaneously, which may thus be displayed. Generally, the use of the additional detection unit **101C** located close to the illumination assembly **101A** assists in separating a light response of the fetus region **2** from that of the maternal tissues' region **11,** since the detection unit **101C** so-positioned will detect scattering effect of light that traveled through the maternal tissues and did not reach the fetus, and which is thus indicative of the maternal region response only. The other detection unit **101B** practically detects photons **155** including the tagged response of the fetus and the tagged response of the maternal tissues.

[0077] It should be understood that generally the detection unit detects the tagged light response of the fetus affected by the maternal tissues. Hence, the expression "tagged response of the maternal tissues" means photons tagged (by ultrasound) inside the volume of the fetus being scattered by maternal tissue.

[0078] Both the tagged and untagged responses of the maternal tissues' region are identically frequency modulated by the mother's heart rate. Hence, the first measured data from the detection unit **101C,** which is mainly indicative of the untagged light response of the maternal tissues, can be used to analyze the second measured data from the detection unit **101B** to separate a signal indicative of a light response of the fetus from that of the maternal tissues.

[0079] **Fig. 3B** illustrates a flow chart of the main operational steps of a method of the invention utilizing the monitoring system **300.**

[0080] Step 1: First, optimal positioning of the illumination assembly, detection assembly and acoustic transducer arrangement is provided as described above. This positioning ensures that acoustic waves interact with the region of interest (fetus volume) from which photons **155** are detected at the detector **101C** and substantially do not interact with the region outside the region of interest (maternal tissues) from which photons **165** are detected by the detector **101C.**

[0081] Step 2: Actual measurements are performed when at the optimal positions of the illumination, detection and acoustic assemblies. Measured data includes:

[0082] (1) a first data portion generated by the detection unit **101C** and indicative of the untagged photons coming from the maternal tissues; and (2) a second data portion generated by the detection unit **101B** and indicative of the photons including tagged and untagged photons coming from the fetus, and untagged photons coming from the maternal tissues.

[0083] Step 3: The measured data is processed to filter out, the contribution of tagged and untagged photons scattered by regions outside the region of interest, to the measured signal, wherein this contribution is identified as that having frequency modulation by the mother's heart rate, as previously identified from the data portion (1). Hence, the so-separated light response of the fetus can be processed to determine the desired parameter of the fetus. The control unit **120** may use signals generated by the detection units **101B** and **101C** to determine fetal and optionally maternal oxygen saturation levels.

[0084] More specifically, the apparatus **300** operates as follows: The illumination assembly **101A** simultaneously generates photons of two different wavelengths (generally, at least two wavelengths). Photons denoted **155** are photons scattered from maternal and fetal tissues and reaching an input port **122** of the detection unit **101B,** i.e., photons scattered from a tagged volume of tissue, that is intermittently or continuously radiated by acoustic waves **150** generated by transducer **110.**

[0085] The transducer arrangement **110** may, for example, be operated to generate a burst of acoustic waves, with a delay of at least t_{on} between the end of one burst and the onset of another burst. Time t_0 is the time it takes the acoustic burst to reach the target fetal tissues (e.g. head). The duration of the burst Δt_0 is determined such that at time t_f, bounded by a condition $t_0 \leq t_f \leq (t_0+\Delta t_0)$, the acoustic pulse propagates primarily through target fetal tissues (i.e., through a volume ΔV of fetal tissues). Therefore, during this time t_f the acoustic burst reaches the target fetal tissues, and acoustic waves are hardly propagating through maternal tissues. A portion of photons **155** propagating through the same volume of fetal tissues during time t_f is tagged. Whereas, photons **165** are those propagating only through maternal tissues at the same time t_f and are therefore untagged (since they did not interact with the ultrasound irradiated region).

[0086] The detection unit **101C** is placed at a distance Q from the illumination assembly **101A,** such that its input port collects primarily photons **165** that are not scattered from the tagged volume. The detection unit **101C** is optionally moved until it does not collect tagged photons, and is then fixed in the appropriate position. It should be noted that, alternatively, the detection units **101B** and **101C** are fixed in place, and a position of the ultrasound transducer arrangement 110 is adjusted to be such that the tagged photons **155,** scattered from fetal tissues, primarily reach the detection unit **101B** and not the detection unit **101C.**

[0087] **Fig. 3C** more specifically exemplifies the data processing procedure for processing measured data from the apparatus **300.** The detection unit **101B** receives photons **155** including tagged and untagged photons scattered by the uterus and tagged photons scattered by the fetus, while the detection unit **101C** receives primarily only untagged photons 165 scattered by the maternal tissues. A signal that is generated by the detection assembly **101B** in response to collected photons **155** is referred to as "signal *A*". A signal generated by the detection unit **101C** in response to photons **165** is referred to as "signal *B*".

[0088] According to this example, two models are used to describe the propagation of light in a multi layer tissue system. Such models are described for example by Keinle et al. in Physics in Medicine and Biology 44: 2689-2702 (1999). One model (Model A) includes the parameters representing some of the tissues through which photons **165** propagate from the illumination assembly **101A** through a medium until they reach the detection unit **101C,** and the other model (Model B) includes the parameters representing some of the tissues in the medium through which tagged photons **155** propagate until they reach the detection unit **101B.** The models include known parameters, such as the molar absorption and scattering coefficients of blood cells, and of oxygenated hemoglobin and deoxygenated hemoglobin at each of the wavelengths of illuminating photons. In addition, the models may include the thickness of the layers (maternal and fetal), presence and volume of amniotic fluid in the light path and other parameters that are measured during the operation of apparatus 300 (as described above with reference to apparatus **100** of Fig. 1). Some tissue parameters in the model may be averaged or other manipulations of the known or measured parameters of the real tissues in models A and B may be carried out.

[0089] Given a certain source amplitude, and the known separation between the illumination assembly **101A** and the detection unit **101C,** model A is used to calculate the expected time dependent photon flux, or light intensity at the input port of the detection unit **101C.** The expected time dependent photon flux or light intensity is used to calculate the expected signal (termed "signal *C*") that can be generated by the detection unit **101C** in response to such a photon flux. Signal *C* actually presents theoretical data for untagged photons at the location of detection unit **101C,** while signal *B* presents real measured data for untagged photons collected by the detection unit **101C.** The parameters of model A are adjusted such that signal *C* is made equal to or closely resembles signal *B* (best fitting). Signal processing techniques based on optimization algorithms, such as neural network, can be used to optimally determine the parameters of model A. The parameters are used to calculate the optical properties of some of the tissues through which photons **165** propagate.

[0090] Additionally or alternatively, certain parameters of models A and B (such as thicknesses of maternal tissues,

in particular uterine wall, and/or tensions of muscles) may be unknown, and be determined during operation. During contractions, the thickness of the uterine wall and the tension of the muscles change. Controller **120** determines the thickness of the uterine wall as a function of time by optimizing primarily this parameter of model A. Once determined, these parameters are used to determine contractions' duration and amplitude. Alternatively, tissue velocity measurements are performed by ultrasound assembly **110,** using techniques known in the art for echocardiography. Transducer arrangement **110** emits acoustic pulses (not shown) that are reflected back by uterine muscles. The reflected pulses are Doppler shifted with respect to the emitted acoustic pulses. Controller **120** analyzes the reflected signals to determine the thickness and velocity of the muscles. During contractions the thickness and velocity change, therefore controller **120** monitors these changes as a function of time. Consequently, controller **120** displays the amplitude and duration of the contractions. The apparatus **300** thus provides information needed to monitor the progression of labor (contractions' duration and amplitude) in addition to fetal well being (heart rate and oxygen saturation).

[0091] In addition, signal *B* is optionally used to extract maternal oxygen saturation level, by using the time dependent amplitudes of the signals generated by the detection unit **101C** in response to photons **165** of at least two wavelengths.

[0092] It may generally be assumed that the optical properties of tissues outside the region of interest (outside fetus) through which both photons **155** and **165** propagate are similar (for example maternal abdominal tissues). Alternatively, it may be assumed that by determining the parameters and optical properties of the tissues through which photons **165** propagate, one can deduce, within a reasonable error, the optical properties of corresponding tissues (e.g., other areas of maternal abdominal tissues) through which photons **155** propagate. The parameters calibrated by signal *B* and the optical properties of the tissues through which photons **165** propagate are then used to calibrate model B that describes the propagation of photons **155** through maternal and fetal tissues.

[0093] The time dependent amplitude of signal *A* at all wavelengths of photons **155** is processed by the control unit 120 using techniques known in the art, such as digital Fourier transformations and analog or digital filtering, to extract, from the entire signal *A,* a signal portion corresponding to the tagged photons 155. This signal portion is termed "tagged signal *A"*. Tagged signal *A* is that modulated at the ultrasound frequency generated by the transducer arrangement 110. The amplitude of the power spectra of the tagged signal *A* at the ultrasound frequency (or related to the ultrasound frequency), the modulation width of its power spectra or other features of tagged signal *A,* such as its phase, are termed together as "processed tagged signal *A"* This processed tagged signal *A* is actually indicative of both the maternal tissues response and the fetus response tagged by ultrasound. In addition, the signal *A* contains information which is not modulated at the ultrasound frequency, termed "untagged signal *A"*.

[0094] According to this specific embodiment, untagged signal *A* may also be used in the data processing and analyzing procedure, for example to determine some of unknown parameters of model B and further optimize this model. For example, untagged signal *A* may contain signals which are modulated by maternal cardiac cycle, and have a modulation frequency of 0.5-2Hz corresponding to maternal heart rate F_m. Signal *B* is also modulated at the same frequency, as photons **165** propagate through maternal tissues containing the same pulsating blood. Consequently, untagged signal *A* and signal *B* may be used to calibrate model B relative to model *A*, where differences and similarities between untagged signal *A* and signal B are used to optimize the parameters of model B.

[0095] In addition, tagged signal *A* and/or processed tagged signal *A* are also modulated at maternal heart rate, as tagged photons **155** pass through maternal tissues before and after they pass through the tagged volume. Consequently, tagged signal *A* and/or processed tagged signal *A* modulated at this low frequency may be used in conjunction with untagged signal *A* and/or signal *B* to extract the portion of tagged signal *A* that is affected by absorption by fetal blood. This portion calculated for all wavelengths of photons **155,** is used to extract the fetal oxygen saturation level.

[0096] According to another embodiment of the invention, only tagged signal *A* and untagged signal *A* at all the wavelengths of photons **155** are used to extract fetal oxygen saturation levels. According to yet another embodiment, tagged signal *A* and/or processed tagged signal *A* are used to determine fetal oxygen saturation at all fetal heart rates F_f, where $F_f \neq F_m$ (or more precisely $F_f > F_m + BW$, where BW is the bandwidth of the detection system, as fetal heart rate is usually faster than maternal heart rate). First, tagged signal *A* is extracted (separated) by the control unit **120** as described above. Then, the modulation amplitudes of tagged signal *A* and processed tagged signal *A* at F_f and F_m are determined. Tagged photons **155** are modulated at F_f, however a modulation at F_m may also exist, as tagged photons **155** also propagate through maternal tissues. When this modulation is small, its contribution at higher harmonics (i.e., $2F_m$, $3F_m$) is negligible. The amplitudes of tagged signal *A*, processed tagged signal *A* and untagged signal *A* modulated at frequency F_m are optionally used to determine certain tissue parameters in model B. Using these parameters, tagged signal *A* is calibrated to correspond primarily to fetal contributions. Fetal oxygen saturation is extracted from features (such as the modulation amplitude, the bandwidth of the modulation, autocorrelation etc.) of the calibrated tagged signal *A* and/or processed tagged signal *A* modulated at F_f at all wavelengths of photons **155.**

[0097] In some cases where the modulation of tagged signal *A* at F_f in the range of $2F_m - BW < F_f < 2F_m + BW$ can not be neglected, signal *B* and untagged signal *A* are used to determine fractions of tagged photons **155** that are modulated by maternal blood, by fitting the parameters of models A and *B* as described above. Once the parameters are determined, fractions of tagged photons **155** that are modulated by maternal blood and fetal blood can be determined using known

methods, for example such as Monte Carlo simulations. Using the results of the simulations, tagged signal *A* is calibrated to correspond primarily to fetal contributions. The calibrated signal is then used to extract fetal oxygen saturation levels as described above.

[0098] Turning back to **Fig**. **3A,** it should be noted that the acoustic transducer arrangement may be accommodated such that acoustic waves propagate towards the fetus along an axis passing between the illumination assembly and the detection assembly. For example, the transducer arrangement or its associated ultrasound port is located on the same support structure **103.** The optical unit is preferably operated to start illumination/detection a certain predetermined time after the generation of the acoustic radiation, which is the time needed for the acoustic radiation of a given frequency to arrive at the region of interest (fetus). This ensures that light detected by the detection unit **101C** is not affected (tagged) by the acoustic radiation.

[0099] Alternatively or additionally, the apparatus of the present invention, for example configured as the above-described apparatus **300,** can be used to monitor the optical properties of the amniotic fluid surrounding the fetus. In this case, a region within the amniotic fluid presents a region of interest, and as indicated above the term "maternal tissues" refers to regions outside the region of interest. Optical properties of the amniotic fluid may include, for example, the absorption coefficient, the scattering coefficient, the reduced scattering coefficient and the refractive index of the fluid. Such optical properties are used to calculate the concentration of lamellar bodies, blood or meconium dispersed within the amniotic fluid. The calculated concentration is optionally compared to a threshold level as described below.

[0100] As illustrated schematically in **Fig. 3D,** to monitor amniotic fluid, apparatus **300A** is configured and positioned similar to the above-described apparatus **300,** whereas the region of interest **2A** is defined by a substantial volume of amniotic fluid, being at the shortest optical path to light output and/or input ports of illumination and detections assemblies. The substantial volume is that which allows for an overlap of illuminating light and an ultrasound beam within that volume. For example, in the case the illumination assembly **101A** and detection unit **101B** are appropriately placed to illuminate and collect light scattered by the amniotic fluid **2A,** a transducer arrangement **110** is placed such that acoustic waves **150** propagate through the same region of the amniotic fluid **2A** from which scattered photons **155** are detected by a detection unit **101B.** Preferably, the detection assembly is configured such that a detection unit **101C** collects untagged photons propagating through maternal tissues **11A** (a region outside the region of interest), and the detection unit **101B** collects tagged and untagged photons propagating through a substantial volume of the amniotic fluid (region of interest).

[0101] The apparatus **300A** may be used for determining the optimal positioning of illumination/detection and ultrasound assemblies, having a plurality of input and output ports, such that the ultrasound beam is scanned over different locations inside the body and the autocorrelation or power spectrum of signals generated by each detection unit are determined by a controller **120** in response to photons scattered from different volumes within the body overlapping with the ultrasound beam. As the line-width of the autocorrelation or power spectrum of the tagged signals, around the frequency of the ultrasound radiation, is different when tagging is performed inside a fluid volume than when performed in a tissue or bone volume, the controller **120** can determine, by monitoring the line width, when the ultrasound beam is used to optimally tag a volume of the amniotic fluid.

[0102] For monitoring amniotic fluid, the illumination assembly **101A** includes one or more light sources generating a plurality of wavelengths (either simultaneously or sequentially) from 300nm to 12μm. For example, a plurality of wavelengths that are absorbed and/or scattered by lamellar bodies contained in amniotic fluid is chosen for determining the concentration of lamellar bodies. Preferably, the plurality of wavelengths is less absorbed by water. Such wavelengths may be chosen in the range of near infrared, i.e., 600nm-1300nm.

[0103] At each wavelength, the control unit **120** optionally determines models A and B (as described above) for the overlaying maternal tissues **11A** (region outside the region of interest) and the amniotic fluid (region of interest), and determines tagged and untagged signal A and untagged signal B as described above. Processed tagged signal A and calibrated tagged signal A are used to determine the reduced scattering coefficient and the absorption coefficient of the tagged volume of amniotic fluid as explained below.

[0104] The control unit **120** then determines the concentration of lamellar bodies, blood or meconium in the amniotic fluid. The output of the control unit 120 is displayed on the integrated display or communicated via wireless means or cables to another display or electronic processor. Possible outputs include but are not limited to a light signal indicating higher or lower concentration of lamellar bodies relative to a predetermined threshold, a number shown on the display corresponding to the concentration of lamellar bodies in addition to a display of the threshold number for that value, a sound indicating high or low concentration of lamellar bodies relative to a threshold. The control unit **120** optionally displays a "mature" or "premature" signal, without quantitative information about the concentration of lamellar bodies, or displays "stained" or "clear" signal for the case of meconium staining.

[0105] Lamellar bodies are produced by type II alveolar cells in increasing quantities as fetal lungs mature. They are composed almost entirely of phospholipid and represent the storage form of the surfactant. Their diameter is about 0.5-2 μm, and their index of refraction is about 1.475. Consequently, when using the above wavelengths range, it is clear that Mie scattering dominates the scattering process of light from lamellar bodies. Choice of specific wavelengths depends on the optimal signal to noise ratio (SNR) of the apparatus used. The difference in wavelengths used for illumination

has to provide a sufficient change in the scattering coefficient that can be detected by the system. The relationship between the wavelength and the reduced scattering coefficient $\mu_{s'}$ of monodisperse scattering dielectric spheres is known in the literature to be:

$$\mu_{s'} = 3.28\pi a^2 \rho \left(\frac{2\pi a}{\lambda}\right)^{0.37} (m-1)^{2.09} \qquad [5]$$

wherein a is the radius of the dielectric spheres, p is their volume density, λ is the wavelengths in vacuum, $m = \frac{n_s}{n_0}$ where n_s and n_0 are the refractive indices of the spheres and the surrounding material respectively.

[0106] The reduced scattering coefficient $\mu_{s'}$ is related to the scattering coefficient μ_s using the following equation:

$$\mu_{s'} = (1-g)\mu_s \qquad [6]$$

wherein g is the anisotropy factor related to the size and geometry of the scattering centers.

[0107] Both the reduced scattering coefficient and the scattering coefficient can be determined according to an embodiment of the present invention.

[0108] As an example, light at a plurality of wavelengths is generated by the illuminating assembly **101A.** Wavelength selection is based on the absorption and scattering coefficients of the amniotic fluid. For example, amniotic fluid with no blood or meconium absorbs almost equally light at around 735nm and 780nm. Therefore, light distributions inside amniotic fluid at these two wavelengths will differ due to wavelength dependant changes of the reduced scattering coefficient of the fluid. This reduced scattering coefficient depends on the size, volume concentration and relative index of refraction of the lamellar bodies (as evident from equation 5 above). Therefore, by determining the reduced scattering coefficients at different wavelengths, the control unit **120** determines the concentration of lamellar bodies in the fluid using equation 5 (or a modified equation 5 which includes physiological parameters of lamellar bodies instead of monodisperse spheres).

[0109] In order to determine the presence of meconium in the fluid, a different selection of wavelengths is used. It is known that meconium primarily contains blood and billirubin, therefore at least two wavelengths are used: one that is absorbed by blood or billirubin (for example 660nm) and the other that is weakly absorbed by either one of them (for example 1064nm). These wavelengths may for example be used in addition to the above mentioned wavelengths 735 and 780nm. Irradiating the amniotic fluid with these two wavelengths (e.g., 660nm and 1064nm) will result in a different light distribution at the shorter wavelengths when meconium is present than in the case of no meconium. The absorption coefficient of the fluid at these wavelengths is also used to determine the concentration of meconium in the fluid.

[0110] The control unit **120** determines the processed tagged signal A at the plurality of wavelengths used to illuminate the tissues, and stores them in memory. Since the time dependant variations in the optical properties of the amniotic fluid are very slow, tagged signal A at each wavelength can be integrated over long periods (much longer than the fetal or maternal heart beats). At those wavelengths, which are absorbed almost equally in the fluid, the variations between the signals obtained at different wavelengths are proportional to the reduced scattering coefficient. From these variations of the measured parameters (listed below), the control unit **120** determines the reduced scattering coefficient.

[0111] The control unit **120** determines the reduced scattering coefficient of the amniotic fluid by determining, for each illuminating wavelength, at least one of the following parameters:

(a) The amplitude of the power spectra or autocorrelation of processed tagged signal *A* corresponding to the frequency of the ultrasound waves;
(b) The line width of the power spectra or autocorrelation of processed tagged signal *A* (for example, the full width at half max around the frequency of the ultrasound waves);
(c) The spatial attenuation of the amplitude of the power spectrum of tagged signal *A* corresponding to the ultrasound frequency.

[0112] In the latter case, the ultrasound beam scans the illuminated region such that the overlapping volume, within the amniotic fluid, is varied along the optical path between the illumination assembly **101A** and the detection unit **101B.** For each location, tagged signal A or processed tagged signal *A*, is stored in memory, and the attenuation of the amplitude of the power spectrum of tagged signal A corresponding to the ultrasound frequency is determined.

[0113] In order to determine the absorption coefficient, following the determination of the reduced scattering coefficient at the above wavelengths, different wavelengths which are differently absorbed in the fluid (such as 1064nm or 660nm) are used and the above parameters are determined according to a specific method from those listed above. The absorption coefficient depends on the product of the concentration of the chromophores or structures within the fluid and the molar absorption coefficients (which are known in the literature). In order to determine the absorption coefficient, following the determination of the reduced scattering coefficient at the above wavelengths (735nm and 780nm), different wavelengths which are differently absorbed in the fluid (such as 1064nm or 660nm) are used to illuminate the body region. From the determined parameters of the signals at each wavelengths, the optical attenuation is obtained. The optical attenuation μ_{eff} is known to depend on both the reduced scattering ($\mu_{s'}$) and (μ_a) absorption coefficients where $\mu_{eff} = \sqrt{3\mu_a(\mu_a + \mu_{s'})}$, since the reduced scattering coefficients were determined before, the absorption coefficients can be extracted.

[0114] Therefore, the concentration of absorbing centers (like meconium) is determined similar to the concentration of hemoglobin, as described above.

[0115] In some embodiments of the present invention, a threshold value for mature lungs is an input parameter to the control unit 120 prior to its operation. In some embodiments of the present invention, several parameters are being input into the control unit **120** prior to operation. Some parameters are measured by an ultrasound imager, such as, thickness of uterine wall or thickness of abdominal wall. Additional parameters may include weight of gravida and duration of gestation (relative to last menstrual period or based on other indicators). Some of these parameters are used to calculate the threshold value to which the optical properties of the amniotic fluid, or the concentration of lamellar bodies, are compared. These parameters can optionally be used to calculate the concentration of the lamellar bodies from the optical signals according to an algorithm that uses the optical properties of maternal tissues **11A** to extract the optical attenuation in amniotic fluid **2A** as explained above.

[0116] It should be noted that similar to the corifiguration of **Fig. 2,** illumination assembly **101A** can be inserted transvaginally to illuminate a volume of amniotic fluid through the cervix. Choice of wavelengths for transcervical illumination may be different than choice of wavelengths for abdominal illumination, since the composition of the different tissue layers in between the illumination assembly **101A** and the amniotic fluid **2A** is different for the two configurations. For example, skin (epidermis) contains melanin that highly absorbs in the ultraviolet region, whereas the cervix has little or no melanin.

[0117] While it is preferred that the control unit **120** determines the concentration of lamellar bodies or meconium, it is not always necessary to determine these concentrations. A database of signals can be defined by recording signals collected by the controller's memory or features of these signals (e.g. amplitude, phase, frequency, time dependence, wavelets or principal components). The database may contain data from measurement obtained for premature fetal lungs and mature fetal lungs. For lung maturity classification by the database, a similarity metric is defined. The obtained signals are classified according to the best fit to mature or immature lungs using clustering, neural networks and/or other classification algorithms. For meconium stained analyses, the database can contain signals from stained and clear amniotic fluid. Features from the ultrasound image taken prior or during the assay are used to categorize the measured signals in the database.

[0118] Whereas the above examples relate to measuring the optical properties of amniotic fluid, similar apparatus can be designed for noninvasive measuring the optical properties of other extravascular fluids such as pleural (around the lungs), pericardial (around the heart), peritoneal (around the abdominal and pelvis cavities) and synovial (around the joints) fluids.

[0119] Reference is made to **Fig. 4** exemplifying a monitoring apparatus **400** according to yet another embodiment of the invention. The apparatus is constructed and operable to enable determining properties of both maternal and fetal regions, for example detecting maternal and fetal oxygen saturation levels along with other tissue components. The apparatus **400** includes a measurement unit (optical and acoustic units) carried by a flexible probe **403;** and is connectable to a control unit **120.** The control unit **120** is similar to the above described control unit, namely is a computer system including *inter alia* a power supply, a control panel with input/output functions, a display unit, a function generator, electronic circuits, filters and processors, etc. Additionally, the control unit **120** may contain light sources, light detectors and acoustic sources. Electric wires, optical fibers and/or wireless means connect the control unit **120** to the elements of the measurement unit carried by the flexible probe **403.** The flexible probe **403** includes light output ports **121A** and **121B** associated with an illumination assembly **101A,** and light input ports **122A** and **122B** associated with a detection assembly **101B.** It should be understood that the elements **121A** and **121B** carried by the probe **403** may be light sources (such as lasers, laser diodes or LEDs) or the output faces of optical fibers (or fiber bundles) whose input faces are coupled to light sources contained outside the probe, e.g., in the control unit **120.** Similarly, elements **122A** and **122B** may be light detectors (such as for example diodes or CCD cameras) or the input faces of optical fibers or fiber bundles whose exit faces are coupled to light detectors located outside the probe, e.g., contained in the control unit **120.** In the

case actual detectors are placed on the flexible probe **403,** the detectors are preferably mechanically and electronically isolated such that acoustic waves propagating from an acoustic output port **245** minimally affect the collection of photons by the detectors and the transduction of light signals into electronic signals. If the ultrasound transducer arrangement **110** is also placed on the probe **403,** then the configuration is such as to prevent RF and other electronic signals generated by the transducer arrangement from interfering with the collection of photons by the detectors and with the transduction of light signals into electronic signals. Such a shielding of the detectors may for example include electrical isolation by appropriate materials that are poor conductors or create a Faraday cage around a detector, mechanical isolation by using appropriate material that attenuates the propagation of sheer acoustic waves through the probe itself or through maternal tissues. Detectors may be connected to the probe **403** using connecting parts (possibly detachable) that isolate mechanical and electrical signals at the frequencies generated by the ultrasound transducer arrangement and at other frequencies.

[0120] The detection assembly generates electronic signals in response to the amplitude and phase of photons reaching the input ports **122A** and **122B.** These electronic signals may be filtered by analog or digital filters, for example bandpass filters, that are appropriately provided being connected to the data processing utility of the control unit **120** or being a part of this processing utility. The bandwidth of these filters can be fixed or changed by the control unit **120.** Tuning of the bandwidth can be performed optically by heterodyne detection or by a plurality of filters having different bandwidths, or by tunable filters which are coupled to each detector. Alternatively, filters can be electronic.

[0121] It should be noted that more than two input and output light ports may be provided in the monitoring apparatus **400,** only two pairs of such ports being shown in the present example for the purposes of simplifying the illustration. In addition, each port may serve as a dual input and output light port by using a fiber combiner/splitter that couples light into and out of one optical fiber. The ports may be arranged in a one-dimensional array or a two-dimensional array to improve flexibility of use.

[0122] Preferably, the input and output ports are arranged such that an equal optical path through body tissues exists between pairs of output and input ports. For example, light input and output ports are arranged such that they are not coplanar, but rather form sets of isosceles triangles between output and input ports, having equal light paths between one output port and two input ports (or *vice versa).*

[0123] The flexible probe **403** also contains the ultrasound output port **245** from which acoustic waves **255** (shown as semicircles **255)** are directed towards the region of interest. Acoustic waves **255** are generated by the ultrasound transducer arrangement **110** that may be located on the flexible probe **403** and connected to a function generator in the control unit **120** using electric wires **236** or using wireless means. Alternatively, the ultrasound transducer **110** may be located outside the probe **403,** e.g., in the control unit **120,** and acoustic waves be transmitted to the output port **245** using suitable acoustic waveguides **236.** In the example of Fig. 4, the output port **245** is located between the light input and output ports. The output port **245** may be placed at any location of the flexible probe **403** (i.e. to the right of output port **121A** or the left of input port **122A).** Several ultrasound output ports, at different locations along the flexible probe **403,** may be used being coupled to the same ultrasound transducer arrangement or to different ultrasound transducer arrangements.

[0124] When different ultrasound transducer arrangements are used, the transducer arrangements may generate acoustic waves of the same frequency modulation, or each may generate a different frequency modulation. When different frequencies are being generated, the control unit **120** controls the modulation at each transducer arrangement according to the spatial locations of each output port associated with each transducer arrangement, such that light propagating through the same volume as the acoustic waves and collected through one or several light input ports is analyzed based on the correct frequency modulation of the corresponding transducer arrangement (as will be described below for one such transducer arrangement). Different transducer arrangements can generate acoustic waves at the same time intervals, or during different time intervals.

[0125] The flexible probe **403** is placed in contact with a maternal skin **10** in a region overlaying a fetal tissue 2 contained in maternal tissues. The positioning of the flexible probe **403** may be performed with the aid of an ultrasound imaging system that is used to determine the optimal location of light ports and acoustic output port relative to the fetus (as described above). Different fetal organs or tissues can be used to monitor fetal oxygen saturation including the placenta.

[0126] The flexible probe **403** is placed in contact with the maternal skin **10** using adhesive pads or by applying pressure to maternal abdomen using a belt. The acoustic output port **245** is coupled to the skin **10** using an acoustic coupling material such as gel or a hyrdrogel adhesive.

[0127] Upon attachment of the probe **403,** the control unit **120** is turned on in a calibration mode. During the calibration mode, the control unit **120** sends an electronic signal to the function generator connected to the ultrasound transducer arrangement causing it to generate a series of acoustic pulses. The acoustic pulses are transmitted through the ultrasound output port **245** and propagate through maternal tissues **11** and fetal tissues **2.** A portion of the acoustic pulses is reflected from each surface or impedance mismatched layer that the pulses encounter during their propagation. The reflected portion is collected through the acoustic output port **245** and transmitted to an ultrasound transducer of the imaging system (which may be the same transducer arrangement **110** used for measurements). The transducer arrangement

used for imaging may be a single acoustic transmitter, a single acoustic transceiver, an array of transmitters and/or receivers, an ultrasound Doppler imager, a phased array, or a complete imaging system capable of transmitting and receiving acoustic signals. The control unit **120** analyzes the signals generated by the transducer in response to the portion of reflected pulses and determines a distance between the ultrasound output port **245** and the fetal tissues 2 (by multiplying the speed of sound in the tissue by half the time difference $\Delta\tau$ between the emission of the acoustic pulses from the output port **245** and the collection of the reflected pulses in the said port **245).**

[0128] The control unit **120** then determines an appropriate distance to be provided between the light output port **121A** or **121B** and the light input port **122A** or **122B,** such that photons **250** emitted from the output port **121A** will propagate through fetal tissues 2 before reaching the input port **122A** or **122B.** The control unit **120** can select which output and input ports are used from a plurality of light ports arranged at different spatial locations, such that at least one input port collects photons, emitted from at least one output port, that propagate through the same fetal tissue **2** through which acoustic waves **255** propagate. The control unit **120** also determines which of the other light input ports collect photons that propagate through maternal tissues **11** and not through fetal tissues **2.** Additionally, during the calibration mode, the control unit **120** determines a desired frequency bandwidth Δf_1 that is to be used during the monitoring. For example, the control unit **120** selects the frequency bandwidth Δf_1 corresponding to that optimally filtered by analog or digital electronic filters connected to the light detectors.

[0129] Following the calibration mode, the control unit **120** operates an array of fixed output and input light ports by modulating (including time gating) the light sources connected only to the chosen output ports, or modulating the output ports themselves, and analyzing the signals generated by the detectors coupled to the chosen input ports.

[0130] As indicated above, the control unit **120** determines the desired frequency bandwidth Δf_1 to be used during the monitoring as that corresponding to a frequency bandwidth optimally filtered by analog or digital electronic filters connected to the light detectors. The bandwidth that these filters optimally transmit is fixed or varied by the control unit **120** during the operation of the apparatus **400.** The control unit **120** controls a portion of the frequency bandwidth generated by the function generator to correspond to the frequency bandwidth that is optimally transmittable by the electronic filters connected to the light detectors. Alternatively, the bandwidth of the filters is varied by the control unit **120** to correspond to a portion of the frequency bandwidth generated by the function generator. The control unit **120** also controls the frequency modulation of acoustic waves **255** such that waves having a frequency outside the frequency bandwidth Δf_1 are for example generated during different portions of the acoustic pulse.

[0131] The control unit **120** controls the time dependent generation of the frequency modulated acoustic waves. The control unit **120** determines a time period Δt_1 needed for signal acquisition such that optimal signal-to-noise ratio (SNR) for determining fetal oxygen saturation is obtained during the measurements. The time period Δt_1 is shorter than a time difference between the fetal heart beats, when pulse oximetry is used for data analysis. The control unit **120** also determines the frequency modulation parameters such that the desired frequency bandwidth Δf_1, (or phase) propagates through the fetal tissue **2** during the time period Δt_1. The onset of time period is at time t_1 equal to about $\Delta\tau/2$ where the acoustic pulse reaches the fetal tissues **2** and time t_2 is determined by $t_2=t_1+\Delta t_1$.

[0132] In the present example of **Fig. 4,** the operation of apparatus **400** in a "monitor mode" or actual measurement mode is shown. During the monitor mode, the control unit **120** activates the light source(s) associated with the output port **121A** to emit photons **250** and **251,** and actuates the light source(s) associated with the output port **121B** to emit photons **252.** The light ports may be associated with different light sources or with one or more common light sources. A single light source and preferably two light sources, emitting light of at least two different wavelengths simultaneously, are connected to the output ports, whereas one light source may be connected to more than one output port. Light sources connected to different output ports, or output ports themselves, may be activated during different time periods or with different characteristics (such as different modulation frequency or phase), such that the control unit **120** can distinguish between photons **251** and **252** reaching input port **122B** of the detection unit.

[0133] The control unit **120** also activates a function generator that, in turn, activates the ultrasound transducer arrangement 110 to generate acoustic waves **255** transmitted through the output port **245.** The acoustic wave frequency (or phase) generated by the function generator is modulated by the control unit **120** such that the acoustic waves reaching a region of the fetal tissue **2** illuminated by photons **250** will have a predetermined frequency bandwidth Δf_1. If the bandwidth Δf_1 is fixed, then the control unit **120** determines the frequency modulation of the function generator controlling the generation of ultrasound waves 255, such that acoustic waves **255** modulated at a frequency within Δf_1 reach the fetal tissues 2 at time t_1. In addition, acoustic waves with a frequency within Δf_1 substantially do not propagate through other tissues during the time period Δt_1 following time t_1. Accordingly, the control unit operates the detection assembly such that the light detectors associated with the input ports **122A** and **122B** start collection of photons at time t_1 and end the collection process during t_2. Alternatively or additionally, the control unit **120** controls the activation of light sources associated with the output ports **121A** and/or **121B** at time t_1 and ends the activation at time t_2. During the time period Δt_1, the input port **122A** and/or input port **122B** collect photons propagating through the same fetal tissues through which acoustic waves **255** propagate (a time delay in photon propagation through the tissue is neglected).

[0134] **Fig. 5** exemplifies a monitoring apparatus **500** of a somewhat different configuration. Apparatus **500** differs

from the above-described apparatus **400** in the arrangement of input and output ports (or light sources and detectors) within a flexible probe **403.** Here, light port **121A'** functions as an output port (associated with the illumination assembly), light ports **121B'** and **122A'** function as both output and input ports (associated with the illumination assembly and detection unit), and light port **122B'** functions as an input port (associated with the detection unit).

[0135] In addition, all input ports may be time gated to collect light propagating through specific tissues during a certain time period. Additionally or alternatively, the output ports may be activated during different time intervals. For example, the input ports **121B'** or **122B'** are activated during a time interval Δt_g, following the introduction of light from the output ports **121A'** or **122A',** respectively, such that only photons **256** propagating from the output port **121A'** to the input port **121B'** or photons **257** propagating from the output port **122A'** to the input port **122B'** are collected during that time interval. The output ports **121A'** and **122A'** are therefore activated at different time intervals, such that the input port **122B'** does not collect photons **251** and **257** simultaneously. During a time interval Δt_k, different from Δt_g, the input port **122A'** is activated, following the introduction of light from the output ports **121A',** such that only photons **250** propagating through fetal tissues 2, are detected. As will be explained below, during the time interval Δt_g the light input ports collect light propagating primarily through maternal tissues, being untagged. During time interval Δt_g acoustic waves **255** do not propagate through the same volume from which light is collected by the input ports **121B'** and **122B'.** During time interval Δt_k the light input ports collect light propagating primarily through maternal and fetal tissues, being tagged or untagged.

[0136] It is preferred that the time interval Δt_k corresponds to the time interval Δt_1 defined above, where both intervals start at t_1. It is preferred that the intervals Δt_k and Δt_g are closely spaced in time such that no substantial modulation in blood or tissue characteristics occurs in between these time intervals.

[0137] Alternatively, several light input ports may be activated during different time intervals corresponding to light propagation through either maternal tissues alone or maternal and fetal tissues, and different acoustic waves can optionally propagate through all volumes from which light is collected allowing both tagged and untagged light to be analyzed through every input port.

[0138] Tagged and untagged signals collected by all the input ports are used to determine the fetal oxygen saturation level based on the tissue models A and B described above. The amplitudes of the tagged and untagged signals are determined during the time intervals Δt_k and Δt_g respectively.

[0139] The filtered electronic signal at a selected bandwidth Δf_1, during the time period Δt_1, starting at t_1, corresponds to the amplitude of the tagged signal propagating through the fetal tissue **2.** Photons **250** propagating through other tissue regions, during the time period Δt_1, where the frequency of the ultrasound waves **255** is outside the frequency bandwidth Δf_1, will have a different modulation frequency and will be attenuated by the filters having the bandwidth of Δf_1. The electronic filters connected to the light detectors can have several bandwidths of optimal transmission ($\Delta f_{2...}\Delta f_n$) different from Δf_1. Detectors are configured such that during each time period Δt_i (i=1..n) starting at time t_i, where t_i is the time where portion of acoustic pulse having a frequency modulation with a bandwidth Δf_i reaches the fetal tissue **2,** the detectors are tuned to optimally convert photons, modulated by frequency Δf_i, to electrical signals.

[0140] For example, as the modulated ultrasound waves propagate through maternal and fetal tissues, at different time periods (Δt_2 ...Δt_n) different from Δt_1, acoustic waves at different frequency modulations propagate through the fetal tissues. The control unit 120 then operates each filter according to the order and duration of the different frequency modulations within the ultrasound pulse, such that each electronic filter having a frequency bandwidth Δf_i is activated at time periods At_i starting at t_i in accordance with the corresponding frequency bandwidth of the ultrasound wave. Additionally, the electronic filter can have a variable bandwidth that is controlled by the control unit **120** in accordance with the generation of the frequency modulation of the ultrasound wave. The control unit 120 then integrates the electronic signals generated by the light detectors and filtered by the electronic filters at all frequency bandwidths during the corresponding time periods. The control unit 120 then analyzes signals received from the electronic filters to determine the fetal and/or maternal oxygen saturation levels.

[0141] Referring to either one to **Figs. 4 and 5,** the control unit **120** analyzes tagged signals, reaching at least one of the input ports of the detection units and being modulated at frequency bandwidth Δf_m different from Δf_i (i=1..n), during a time period Δt_i starting at t_i, to determine the properties of maternal tissues through which photons **251** and/or **252** (in Fig. 4) propagate. These signals may optionally be used to determine maternal oxygen saturation levels. The control unit **120** then uses the tagged signals having a modulation corresponding to frequency bandwidth Δf_m in model B described above to determine characteristics of maternal tissues. The control unit **120** then calibrates model A as described above. The control unit **120** then uses tagged signals, reaching the input ports of the detection units and being modulated at the frequency bandwidth corresponding to Δf_i during the same time period Δt_i starting at t_i in accordance with model A to determine fetal oxygen saturation levels.

[0142] It should be noted with respect to the above-described examples, that the transducer arrangement **110** may include an ultrasound imaging system and/or and ultrasound Doppler imager, such that ultrasound images or Doppler signals are acquired during operation of the monitoring apparatus. Prior to and during the operation, an ultrasound image of tissues including the region of interest is first acquired. The control unit **120** (or the operator) identifies the region of

interest by marking this region on the first acquired ultrasound image. Transducer arrangement **110** is then fixed at the same location (by the operator or by using an adhesive), for duration necessary to obtain efficient tagged signals from the region of interest. The control unit **120** determines the corresponding distance, angle and size of the region of interest relative to the transducer arrangement **110.** Then, the control unit **120** operates to select input and output light ports to emit light and collect light propagating through the region of interest and the outside region, as described above (i.e., to ensure optimal positioning during the measurements). The control unit **120** synchronizes the activation of the light output ports and/or light input ports such that emission of ultrasound pulses to the region of interest corresponds to the propagation of light pulses through the region of interest. Alternatively, the control unit **120** synchronizes the emission of acoustic pulses by the transducer arrangement **110** such that the onset, duration and direction of these pulses correspond to the onset and duration of the activation of light input and/or output ports. The control unit **120** analyzes tagged and untagged signals generated by the detection assembly and determines the concentration of an analyte (for example, oxygenated hemoglobin) in the region of interest, as described above. More than one analyte can be monitored simultaneously by using different wavelengths of light, each having a characteristic absorption or scattering by the selected analytes. The control unit **120** then displays simultaneously (using, for example, color coded images) the local concentration of the analyte on the region of interest of the ultrasound image, in addition to any other form of display (e.g. numerical) that is understood by the operator and/or by a machine connected to the control unit **120.** In cases where more than one ultrasound pulse is needed for obtaining efficient tagged light signals, the transducer arrangement is operated without scanning the ultrasound beam, and a single beam is emitted in the direction of the region of interest for the duration needed for an efficient tagged signal acquisition. Yet another option suitable for cases when the transducer arrangement is moved during operation, such that distances and angles between the transducer arrangement 110 and the region of interest are changed, the control unit 120 tracks the position of the region of interest using techniques and algorithms such as of three-dimensional ultrasound imaging (F. Rousseau, P. Hellier, C. Barillot, "Calibration Method for 3D Freehand Ultrasound", In Medical Image Computing and Computer Assisted Intervention, MICCAI'03, Montreal, Canada, November 2003). The control unit 120 then determines the changed distance and angle to the region of interest, and dynamically selects and activates corresponding input and output light ports accordingly during the movement of the transducer arrangement **110.**

[0143] In another embodiment of the invention, an imaging apparatus may be used to monitor changes in the concentration of analyte(s) in a region of interest during therapeutic or surgical procedures (such as during the application of high power ultrasound pulses or wave, laser ablation, or chemical procedures). For example, the transducer arrangement **110** may be used for ablation of tumors or malformations in a tissue. During the application of high power ultrasound pulses, light is emitted and collected by illumination and detection assemblies, respectively, to determine the concentration of an analyte indicative of the treatment in the region being ablated. Alternatively, low power ultrasound pulses (that do not cause ablation) intermittently irradiate the region of interest, while low-power light pulses are emitted and collected by illumination and detection assemblies to determine the concentration of an analyte indicative of the treatment. For example, oxygenation of the region of interest is monitored. Such information is used for controlling and monitoring the treatment during application of ultrasound radiation.

[0144] Reference is now made to **Figs. 6A and 6B** exemplify yet another configuration of a flexible probe, generally designated **603,** suitable to be used in either one of the above described monitoring apparatuses. The flexible probe 603 includes a flexible support **301,** for example made of electrically isolating material(s), carrying light ports **303-316** (fiber-ends in appropriate housing, or light sources and/or light detectors as described above) and an acoustic output port **302** (or acoustic transducer arrangement). **Fig. 6A** presents a bottom view of the flexible probe **603** viewed from the side by which it is attachable to a skin, and **Fig. 6B** shows a side view diagram of the flexible probe **603.** Optical fibers or electric wires **330-336** and **340-346** connect the light ports **310-316** and **303-309,** respectively, to a common connector **320.** An isolated electric cable (or acoustic waveguides) connects the acoustic output port **302** to the same connector **320** associated with a control unit. The acoustic port **302** is preferably coupled to an ultrasound transducer arrangement **327** connected to the flexible support **301** using vibration controlling elements. The connector **320** couples the optical fibers and cables attached to the flexible support **301** with optical fibers and electric cables coupled to the control unit (not shown here). The connector **320** may be composed of several connector elements. An adhesive **325** is attached to the bottom side of the support **301,** such that the probe **603** can be fixed to the skin using this adhesive **325.** Adhesive **325** is preferably transparent and produces minimal scattering in a wavelength range used for measurements (i.e., emitted by light sources). Alternatively or additionally, the adhesive **325** may form an optical index matching layer between the light ports and the skin. Alternatively, the adhesive **325** may not cover the light ports at all, or may partially cover them. The adhesive **325** may contain pigments, chromophores or other materials for controlling the transmission of different wavelengths of light. An adhesive gel **326** is located below the acoustic port **302.** The adhesive gel **326** is made from the same or different material as the adhesive **325** and is designed for optimal acoustic coupling between the acoustic port **302** and the skin. Possible materials for adhesives **325** and **326** include hydrogel based adhesives.

[0145] The different elements of the flexible probe **603** may be assembled in different ways. For example, the complete

probe **603** is assembled prior to operation, and a user only needs to remove a thin layer covering the bottom side of adhesives **325** and **326.** In yet another example, the adhesive **326** is attached to the acoustic output port **302** (preferably including the acoustic transducer arrangement itself) which is not attached to the probe **603** prior to the device operation. The user first attaches the flexible support **301** to the skin using the adhesive **325,** and then inserts the acoustic port **302** through an appropriately provided opening in the support **301,** where the transducer **327** is optionally connected to the support **301** using conventional means and is attached to the skin using the adhesive **326.** The latter may be part of adhesive **325,** and only the acoustic output port **302** is inserted and attached to the upper part of the adhesive **326** (being a double sided adhesive). The user first attaches the adhesives **325** and **326** to skin, then attaches the acoustic port 302 to the adhesive **326,** and then connects the support **301** to the upper side of the adhesive **325** (being a double sided adhesive). Finally, the connector **320** is connected to the cables and fibers from the control unit to allow the operation of the probe. Each element of the flexible probe **603** and the complete probe **603** as a unit may be used only once and then discarded (i.e., is disposable), or used multiple times.

[0146] **Figs. 7A and 7B** show yet another example of a flexible probe **703** according to the present invention. Here, a support **301** carries light ports (or light sources) and several acoustic ports **302, 319** and **319A** (or acoustic transducer arrangements). Each of the acoustic ports **302, 319** and **319A** is coupled to a connector **320** using cables **338, 339** and **339A,** respectively. Adhesive gels **326, 329** and **329A** are used to couple the acoustic ports **302, 319** and **319A,** respectively, to the skin. Similarly, each of the acoustic ports may be separated from the probe **703** when not in use, and inserted by user for as preparation for operation.

[0147] Those skilled in the art will readily appreciate that various modifications and changes may be applied to the embodiments of the invention as hereinbefore described without departing from its scope defined in and by the appended claims.

Claims

1. A monitoring system (300, 300A, 400, 500) for use in non-invasively monitoring at least one parameter of a region of interest (2, 2A) in a human body, the system comprising:

- a measurement unit comprising
an optical unit (101) having an illumination assembly (101A) configured to define at least one output port (121, 121A, 121B) for illuminating light, and a light detection assembly configured to define first and second detection units (101B, 101C), at least the first detection unit (101B) configured to define at least one light input port (122); and
an acoustic unit (110) configured to generate acoustic waves (150) of a predetermined ultrasound frequency range;
the measurement unit being configured and operable to provide an operating condition such that the acoustic waves (150) of the predetermined frequency range overlap with an illuminating region within the region of interest (2, 2A) and substantially do not overlap with a region outside the region of interest (11, 11A), and that the first detection unit (101B) of the detection assembly collects light (155) scattered from the region of interest (2, 2A) and the second detection unit (101C) of the detection assembly collects light (165) scattered from the region outside the region of interest (11, 11A), the measured data being thereby indicative of:
scattered light collected at the first detection unit (101B) that includes an ultrasound tagged light portion that has been scattered from the region of interest (2, 2A), and
an untagged light portion collected at the second detection unit (101C) that contains primarily only untagged photons (165) that were scattered by the region outside the region of interest (11, 11A); and
- a control unit (120), which is connectable to the optical unit (101) and to the acoustic unit (110) to operate these units (101, 120), the control unit (120) being responsive to the measured data and preprogrammed to process and analyze the measured data to extract therefrom a data portion associated with the light response of the region of interest (2, 2A) and determine said at least one parameter of the region of interest (2, 2A), by separating, from the light portion of the measured data collected at the first detection unit (101B), the data portion associated with the light response of the region of interest (2, 2A), based on the light portion of the measured data collected at the second detection unit (101C) that contains primarily only untagged photons (165) that were scattered by the region outside the region of interest (11, 11A).

2. The system of Claim 1, wherein the acoustic unit (110) is configured for generating ultrasound radiation in the form of continuous wave or pulse or burst; and
carrying out at least one of the following:

(1) generating unfocused ultrasound radiation;
(2) generating focused ultrasound radiation, where a focal length corresponds to a distance from the acoustic unit (110) to the region of interest (2, 2A).

3. The system of Claim 1, wherein said at least one parameter is oxygen saturation of the region of interest (2, 2A).

4. The system of Claim 1, configured to utilize principles of either oximetry or pulse oximetry to determine the desired parameter of the region of interest (2, 2A).

5. The system of Claim 1, wherein the measurement unit is configured and operable to generate the measured data indicative of variations of the ultrasound tagged light signal as a function of at least one of time and wavelength of the illuminating light, the control unit (120) being configured to analyze the variations of the ultrasound tagged light signal to determine maxima/minima of the signal and calculate oxygen saturation.

6. The system of Claim 1, wherein the control unit (120) is preprogrammed and operable for carrying out at least one of the following:

(1) to provide optimal positioning of the optical unit (101) and the acoustic unit (110), said optimal positioning satisfying said operating condition;
(2) to operate the optical unit (101) a predetermined time after the operation of the acoustic unit (110), thereby providing said operating condition.

7. The system of Claim 1, wherein the control unit (120) is preprogrammed and operable for providing optimal positioning of the optical unit (101) and the acoustic unit (110), said optimal positioning satisfying said operating condition and the control unit (120) is operable to provide a relative displacement between a direction of propagation of the acoustic radiation and at least one of the illumination and detection assemblies so as to provide said optimal positioning.

8. The system of Claim 1, wherein the illumination assembly (101A) is configured to carry out at least one of the following: (1) define at least two of the spaced-apart light output ports (121, 121A, 121B); and (2) to generate the illuminating light of at least two different wavelengths.

9. The system of Claim 1, wherein the illumination assembly (101A) is configured to generate the illuminating light of at least two different wavelengths.

10. The system of Claim 8, wherein the control unit (120) is operable to select at least one of the light output ports (121, 121A, 121B) for measurements, to provide said operating condition.

11. The system of Claim 7, wherein the control unit (120) is operable to displace at least one of the light input or output ports (121, 121A, 121B) with respect to the direction of the acoustic waves (150) propagation.

12. The system of Claim 9, wherein the two different wavelengths are determined by at least one of the following conditions:

(1) to be differently absorbable by oxygenated and deoxygenated hemoglobin in the body;
(2) to be **characterized by** the same absorption by tissue or fluid components in the body;
(3) to be **characterized by** a different absorption by tissue or fluid components in the body; and
(4) to be differently scattered by tissue or fluid components in the body.

13. The system of Claim 9, wherein the illumination assembly (101A) is operable to generate said at least two different wavelengths at different times, respectively.

14. The system of Claim 9, wherein the at least two wavelengths are differently modulated by at least one of frequency and phase characteristics.

15. The system of Claim 13, wherein the at least two wavelengths are differently modulated by at least one of frequency and phase characteristics.

16. The system of Claim 1, wherein the control unit (120) is preprogrammed and operable to operate the optical unit

(101) a predetermined time after the operation of the acoustic unit (110), thereby providing said operating condition, said predetermined time corresponds to a time needed for the acoustic waves (150) of the predetermined frequency to reach the region where the overlapping with the illuminating light is to be provided.

17. The system of Claim 1, comprising a support structure (103) configured to be brought in contact with a body, said support structure (103) carrying at least the light output and light input ports (122, 122A, 122B) of the illumination and detection assemblies, respectively.

18. The system of Claim 17, wherein said support structure (103) has at least one of the following configurations:

(1) is configured for carrying the illumination and detection assemblies;
(2) is configured for carrying the acoustic unit (110);
(3) is configured for carrying an ultrasound output port (245) of the acoustic unit (110); and
(4) is flexible to wrap the body portion.

19. The system of Claim 1, wherein the acoustic unit (110) comprises a phase array of ultrasound transducers.

20. The system of Claim 1, wherein the control unit (120) is configured for receiving data indicative of reflections of the ultrasound waves (255) from an irradiated volume inside of the body for:

(a) creating data indicative of an image of the irradiated volume, and analyzing said image data to provide said operating condition for measurements; or
(b) determining data indicative of a Doppler shift in the ultrasound radiation reflections.

21. The system of Claim 1, wherein said predetermined frequency range of the ultrasound radiation is from 50kHz to 8MHz.

22. The system of Claim 1, wherein the ultrasound radiation is of a frequency lower than 1MHz.

23. The system of Claim 1, configured for use in monitoring at least one of the following parameters: oxygen saturation level of the region of interest (2, 2A), and concentration of a substance or structure in the region of interest (2, 2A).

24. A method for use in noninvasive monitoring at least one parameter of a region of interest (2, 2A) in a human body, the method comprising:

operating an optical unit (101) and an acoustic unit (110) so as to provide that ultrasound waves (255) of a predetermined frequency range and illuminating light overlap within the region of interest (2, 2A) and substantially do not overlap with a region outside the region of interest (11, 11A), thereby producing measured data indicative of collected light including scattered light having an ultrasound tagged light portion that has been scattered from the region of interest (2, 2A) that is collected at a first detection unit (101B), and an untagged light portion that contains primarily only untagged photons (165) that were scattered by the region outside the region of interest (11, 11A) that is collected at a second detection unit (101C); and
processing and analyzing the measured data to extract therefrom a data portion associated with the light response of the region of interest (2, 2A) and determining said at least one parameter of the region of interest (2, 2A), by separating, from the light portion of the measured data collected at the first detection unit (101B), the data portion associated with the light response of the region of interest (2, 2A), based on the light portion of the measured data collected at the second detection unit (101C) that contains primarily only untagged photons (165) that were scattered by the region outside the region of interest (11, 11A).

25. The method of Claim 24, comprising irradiating the region of interest (2, 2A) with unfocused or focused ultrasound radiation.

26. The method of Claim 24, for determining oxygen saturation of the region of interest (2, 2A).

27. The method of Claim 24, utilizing principles of oximetry or pulse oximetry to determine the desired parameter of the region of interest (2, 2A).

28. The method of Claim 24, comprising applying the illumination of at least two different wavelengths, and generating

the measured data indicative of variations of the ultrasound tagged light signal as a function of at least one of time and wavelength of the illuminating light.

29. The method of Claim 28, comprising analyzing the time variations to determine maxima, minima and average of the signal and calculate oxygen saturation of the region of interest (2, 2A).

30. The method of Claim 24, comprising providing a relative displacement between a direction of propagation of the acoustic radiation and at least one of illumination and detection assemblies of the optical unit (101).

31. The method of Claim 24, comprising selecting for measurements at least one light output port, from a plurality of spaced-apart light output ports, of the optical unit (101).

32. The method of Claim 30, comprising displacing at least one of light input or light output ports of the optical unit (101) with respect to the direction of the acoustic waves propagation.

33. The method of Claim 24, comprising applying ultrasound imaging to the region of interest (2, 2A) surrounded by the outside region.

34. The method of Claim 33, wherein the imaging is carried out using said acoustic unit (110).

35. The method of Claim 24, comprising detecting reflections of the ultrasound radiation from the irradiated body portion and determining a Doppler shift in the detected reflections.

36. The method of Claim 24, comprising operating an illumination assembly (101A) of the optical unit (101) to carry out at least one of the following:

(1) generate the illuminating light of at least two different wavelengths;
(2) to generate the illuminating light of at least two different wavelengths at different times, respectively;
(3) to generate the illuminating light of at least two different wavelengths differently modulated by at least one of frequency and phase characteristics.

37. The method of Claim 24, comprising operating an illumination assembly (101A) of the optical unit (101) to generate the illuminating light of at least two different wavelengths, said at least two different wavelengths being selected to satisfy at least one of the following conditions:

(a) to be differently absorbed by oxygenated and deoxygenated hemoglobin;
(b) equally absorbed by tissue or fluid components;
(c) to be differently absorbed by tissue or fluid components in the body; and
(d) to be differently scattered by tissue or fluid components.

38. The method of Claim 24, comprising operating the optical unit (101) a predetermined time after the operation of the acoustic unit (110), said predetermined time corresponding to a time needed for the acoustic waves (150) of the predetermined frequency to reach the region of interest (2, 2A) where the overlapping with the illumination light is to be provided.

39. The method of Claim 24, wherein said at least one desired parameter includes at least one of the following:

oxygen saturation level; and
concentration of a substrate or structure in the region of interest (2, 2A).

40. The method of Claim 24, for use in noninvasive monitoring a fetus (2) condition.

41. The method of Claim 24, wherein said at least one desired parameter includes at least one of the following:

a fetus (2) blood parameter;
an oxygen saturation level of the fetus (2);
concentration of a substance or a structure within the fetus (2);
concentration of a substance or a structure within amniotic fluid;

presence of meconium in the amniotic fluid and concentration thereof;
presence of blood in the amniotic fluid and concentration thereof; and a level of lung maturity of the fetus (2).

42. The method of Claim 41, wherein said at least one desired parameter includes the level of lung maturity of the fetus (2), the method comprising determining presence and concentration of lamellar bodies in the amniotic fluid.

43. The method of Claim 40, wherein the fetus-related region of interest (2) includes an amniotic fluid region only, said at least one desired parameter including at least one of the following:

a level of lung maturity of the fetus (2);
presence of lamellar bodies;
concentration of lamellar bodies;
presence of meconium;
concentration of meconium;
presence of blood; and
concentration of blood.

44. The method of Claim 40, wherein the fetus-related region of interest (2) includes the fetus (2) only, said at least one parameter includes at least one of oxygen saturation level and concentration of a substance or structure in the fetus region.

45. The method of Claim 24, for noninvasive monitoring optical properties of an extravascular fluid, such as pleural, pericardial, peritoneal and synovial fluids.

46. The method of Claim 24 for use in noninvasive monitoring of oxygen saturation level, the method comprising: applying ultrasound tagging of light in pulse oxymetric measurements, obtaining measured data indicative of variations of ultrasound tagged light signals scattered from a region of interest (2) as a function of at least one of time and wavelength of illuminating light, and analyzing the measured data to calculate the oxygen saturation level.

47. A method for operating a monitoring system (300, 300A, 400, 500) configured for noninvasive monitoring at least one parameter of a region of interest (2, 2A) in a human body, which system comprises an optical unit (101) and an acoustic unit (110) configured to generate acoustic waves (150) of a predetermined ultrasound frequency range, the method comprising:

operating the monitoring system (300, 300A, 400, 500) to provide an optimal positioning of the optical and acoustic units (101, 110) with respect to each other and with respect to the region of interest (2) to satisfy an operating condition for measurements, said operating condition resulting in that the ultrasound waves (255) of the predetermined frequency range overlap with illuminating light generated by the optical unit (101) within the region of interest (2, 2A), while substantially not overlapping in a region outside the region of interest (11, 11A), and in that a detection assembly of the optical unit (101) collects light scattered from the region of interest (2, 2A) using a first detection unit (101B), and collects light from the region outside the region of interest (11, 11A) using a second detection unit (101C),
thereby obtaining measured data indicative of scattered light collected at the first detection unit (101B) that includes an ultrasound tagged light portion that has been scattered by the region of interest (2, 2A), and an untagged light portion collected at the second detection unit (101C) that contains primarily only untagged photons (165) that were scattered by the region outside the region of interest (11, 11A), and enabling extraction from said measured data a data portion indicative of a light response of the region of interest (2, 2A), by separating, from the light portion of the measured data collected at the first detection unit (101B), the data portion associated with the light response of the region of interest (2, 2A), based on the untagged light portion of the measured data collected at the second detection unit (101C) that contains primarily only untagged photons (165) that were scattered by the region outside the region of interest (11, 11A).

Patentansprüche

1. Überwachungssystem (300, 300A, 400, 500) zur Anwendung bei der nichtinvasiven Überwachung von wenigstens einem Parameter einer Region von Interesse (2, 2A) in einem menschlichen Körper, wobei das System Folgendes umfasst:

- eine Messeinheit, die Folgendes umfasst:

eine optische Einheit (101) mit einer Beleuchtungsbaugruppe (101A), die zum Definieren von wenigstens einem Ausgangsanschluss (121, 121A, 121B) für Beleuchtungslicht konfiguriert ist, und eine Lichterkennungsbaugruppe, die zum Definieren einer ersten und zweiten Erkennungseinheit (101B, 101C) konfiguriert ist, wobei wenigstens die erste Erkennungseinheit (101B) zum Definieren von wenigstens einem Lichteingangsanschluss (122) konfiguriert ist; und
eine akustische Einheit (110), die zum Erzeugen von Schallwellen (150) eines vorbestimmten Ultraschallfrequenzbereichs konfiguriert ist;

wobei die Messeinheit so konfiguriert ist und betrieben werden kann, dass sie eine solche Betriebsbedingung bereitstellt, dass die Schallwellen (150) des vorbestimmten Frequenzbereichs mit einer Beleuchtungsregion in der Region von Interesse (2, 2A) überlappen und mit einer Region außerhalb der Region von Interesse (11, 11A) im Wesentlichen nicht überlappen, und dass die erste Erkennungseinheit (101B) der Erkennungsbaugruppe von der Region von Interesse (2, 2A) gestreutes Licht (155) sammelt und die zweite Erkennungseinheit (101C) der Erkennungsbaugruppe von der Region außerhalb der Region von Interesse (11, 11A) gestreutes Licht (165) sammelt, wobei die Messdaten somit Folgendes anzeigen:

an der ersten Erkennungseinheit (101B) gesammeltes gestreutes Licht, das einen ultraschallmarkierten Lichtteil beinhaltet, der von der Region von Interesse (2, 2A) gestreut wurde, und
einen an der zweiten Erkennungseinheit (101C) gesammelten unmarkierten Lichtteil, der hauptsächlich nur von der Region außerhalb der Region von Interesse (11, 11A) gestreute unmarkierte Photonen (165) enthält; und

- eine Steuereinheit (120), die mit der optischen Einheit (101) und der akustischen Einheit (110) verbunden werden kann, um diese Einheiten (101, 110) zu betreiben, wobei die Steuereinheit (120) auf die Messdaten anspricht und so vorprogrammiert ist, dass sie die Messdaten verarbeitet und analysiert, um einen Datenteil davon zu extrahieren, der mit der Lichtreaktion der Region von Interesse (2, 2A) assoziiert ist, und den genannten wenigstens einen Parameter der Region von Interesse (2, 2A) zu ermitteln, indem sie von dem Lichtteil der an der ersten Erkennungseinheit (101B) gesammelten Messdaten den mit der Lichtreaktion der Region von Interesse (2, 2A) assoziierten Datenteil auf der Basis des Lichtteils der an der zweiten Erkennungseinheit (101C) gesammelten Messdaten trennt, der hauptsächlich nur von der Region außerhalb der Region von Interesse (11, 11A) gestreute unmarkierte Photonen (165) enthält.

2. System nach Anspruch 1, wobei die akustische Einheit (110) zum Erzeugen von Ultraschallstrahlung in Form von kontinuierlichen Wellen oder Impulsen oder Bündeln; und
zum Ausführen von wenigstens einem der Folgenden konfiguriert ist:

(1) Erzeugen von unfokussierter Ultraschallstrahlung;
(2) Erzeugen von fokussierter Ultraschallstrahlung, wobei eine Brennweite einer Distanz zwischen der akustischen Einheit (110) und der Region von Interesse (2, 2A) entspricht.

3. System nach Anspruch 1, wobei der genannte wenigstens eine Parameter Sauerstoffsättigung der Region von Interesse (2, 2A) ist.

4. System nach Anspruch 1, das zum Nutzen von Prinzipien von Oxymetrie oder Pulsoxymetrie zum Ermitteln des gewünschten Parameters der Region von Interesse (2, 2A) konfiguriert ist.

5. System nach Anspruch 1, wobei die Messeinheit so konfiguriert ist und betrieben werden kann, dass sie die Messdaten erzeugt, die Variationen des ultraschallmarkierten Lichtsignals in Abhängigkeit von Zeit und/oder Wellenlänge des Beleuchtungslichts anzeigen, wobei die Steuereinheit (120) zum Analysieren der Variationen des ultraschallmarkierten Lichtsignals zum Ermitteln von Maxima/Minima des Signals und zum Berechnen von Sauerstoffsättigung konfiguriert ist.

6. System nach Anspruch 1, wobei die Steuereinheit (120) so vorprogrammiert ist und betätigt werden kann, dass sie wenigstens eines der Folgenden ausführt:

(1) Erzielen einer optimalen Positionierung der optischen Einheit (101) und der akustischen Einheit (110), wobei

die genannte optimale Positionierung das Erfüllen der genannten Betriebsbedingung beinhaltet;
(2) Betreiben der optischen Einheit (101) eine vorbestimmte Zeit nach dem Betreiben der akustischen Einheit (110), um dadurch die genannte Betriebsbedingung zu erzielen.

7. System nach Anspruch 1, wobei die Steuereinheit (120) so vorprogrammiert ist und betrieben werden kann, dass sie eine optimale Positionierung der optischen Einheit (101) und der akustischen Einheit (110) erzielt, wobei die genannte optimale Positionierung die genannte Betriebsbedingung erfüllt, und die Steuereinheit (120) die Aufgabe hat, eine relative Verschiebung zwischen einer Ausbreitungsrichtung der akustischen Strahlung und wenigstens einer der Beleuchtungs- und Erkennungsbaugruppen zu erzielen, um die genannte optimale Positionierung zu erzielen.

8. System nach Anspruch 1, wobei die Beleuchtungsbaugruppe (101A) zum Ausführen von wenigstens einem der Folgenden konfiguriert ist: (1) Definieren von wenigstens zwei der beabstandeten Lichtausgangsanschlüsse (121, 121A, 121B); und (2) Erzeugen des Beleuchtungslichts von wenigstens zwei unterschiedlichen Wellenlängen.

9. System nach Anspruch 1, wobei die Beleuchtungsbaugruppe (101A) zum Erzeugen des Beleuchtungslichts von wenigstens zwei unterschiedlichen Wellenlängen konfiguriert ist.

10. System nach Anspruch 8, wobei die Steuereinheit (120) die Aufgabe hat, wenigstens einen der Lichtausgangsanschlüsse (121, 121A, 121B) für Messungen auszuwählen, um die genannte Betriebsbedingung zu erzielen.

11. System nach Anspruch 7, wobei die Steuereinheit (120) die Aufgabe hat, wenigstens einen der Lichteingangs- oder -ausgangsanschlüsse (121, 121A, 121B) mit Bezug auf die Ausbreitungsrichtung der akustischen Wellen (150) zu verschieben.

12. System nach Anspruch 9, wobei die beiden unterschiedlichen Wellenlängen durch wenigstens eine der folgenden Bedingungen bestimmt werden:

(1) so dass sie unterschiedlich durch oxygeniertes und desoxygeniertes Hämoglobin im Körper absorbierbar sind;
(2) so dass sie durch dieselbe Absorption durch Gewebe- oder Fluidkomponenten im Körper charakterisiert sind;
(3) so dass sie durch eine unterschiedliche Absorption durch Gewebe- oder Fluidkomponenten im Körper charakterisiert sind; und
(4) so dass sie von Gewebe- oder Fluidkomponenten im Körper unterschiedlich gestreut werden.

13. System nach Anspruch 9, wobei die Beleuchtungsbaugruppe (101A) die Aufgabe hat, jeweils die genannten wenigstens zwei unterschiedlichen Wellenlängen zu unterschiedlichen Zeiten zu erzeugen.

14. System nach Anspruch 9, wobei die wenigstens zwei Wellenlängen durch wenigstens eine von Frequenz- und Phasencharakteristiken unterschiedlich moduliert werden.

15. System nach Anspruch 13, wobei die wenigstens zwei Wellenlängen durch wenigstens eine von Frequenz- und Phasencharakteristiken unterschiedlich moduliert werden.

16. System nach Anspruch 1, wobei die Steuereinheit (120) so vorprogrammiert ist und betrieben werden kann, dass sie die optische Einheit (101) eine vorbestimmte Zeit nach dem Betrieb der akustischen Einheit (102) betreibt, um dadurch die genannte Betriebsbedingung zu erzielen, wobei die genannte vorbestimmte Zeit einer Zeit entspricht, die die akustischen Wellen (150) der vorbestimmten Frequenz benötigen, um die Region zu erreichen, wo die Überlappung mit dem Beleuchtungslicht erzielt werden soll.

17. System nach Anspruch 1, das eine Tragstruktur (103) umfasst, die zum Inkontaktbringen mit einem Körper konfiguriert ist, wobei die genannte Tragstruktur (103) jeweils wenigstens die Lichtaus- und -eingangsanschlüsse (122, 122A, 122B) der Beleuchtungs- bzw. Erkennungsbaugruppe trägt.

18. System nach Anspruch 17, wobei die genannte Tragstruktur (103) wenigstens eine der folgenden Konfigurationen hat:

(1) sie ist zum Tragen der Beleuchtungs- und Erkennungsbaugruppen konfiguriert;

(2) sie ist zum Tragen der akustischen Einheit (110) konfiguriert;
(3) sie ist zum Tragen eines Ultraschallausgangsanschlusses (245) der akustischen Einheit (110) konfiguriert; und
(4) sie ist flexibel zum Umwickeln des Körperabschnitts.

19. System nach Anspruch 1, wobei die akustische Einheit (110) ein Phasenarray von Ultraschallwandlern umfasst.

20. System nach Anspruch 1, wobei die Steuereinheit (120) zum Empfangen von Daten konfiguriert ist, die Reflexionen der Ultraschallwellen (255) von einem bestrahlten Volumen innerhalb des Körpers anzeigen, zum:

(a) Erzeugen von Daten, die ein Bild des bestrahlten Volumens anzeigen, und Analysieren der genannten Bilddaten zum Erzielen der genannten Betriebsbedingung für Messungen; oder
(b) Ermitteln von Daten, die eine Doppler-Verschiebung in den Ultraschall-Strahlungsreflexionen anzeigen.

21. System nach Anspruch 1, wobei der genannte vorbestimmte Frequenzbereich der Ultraschallstrahlung 50 kHz bis 8 MHz beträgt.

22. System nach Anspruch 1, wobei die Ultraschallstrahlung eine Frequenz von weniger als 1 MHz hat.

23. System nach Anspruch 1, das zur Verwendung beim Überwachen von wenigstens einem der folgenden Parameter konfiguriert ist: Sauerstoffsättigungsniveau der Region von Interesse (2, 2A) und Konzentration einer Substanz oder Struktur in der Region von Interesse (2, 2A).

24. Verfahren zur Verwendung bei der nichtinvasiven Überwachung von wenigstens einem Parameter einer Region von Interesse (2, 2A) in einem menschlichen Körper, wobei das Verfahren Folgendes beinhaltet:

Betreiben einer optischen Einheit (101) und einer akustischen Einheit (110), um zu bewirken, dass sich Ultraschallwellen (255) eines vorbestimmten Frequenzbereichs und Beleuchtungslicht in der Region von Interesse (2, 2A) überlappen und mit einer Region außerhalb der Region von Interesse (11, 11A) im Wesentlichen nicht überlappen, um dadurch Messdaten zu erzeugen, die gesammeltes Licht einschließlich gestreutem Licht mit einem ultraschallmarkierten Lichtteil, der von der Region von Interesse (2, 2A) gestreut wurde, das in einer ersten Erkennungseinheit (101B) gesammelt wurde, und einem unmarkierten Lichtteil anzeigen, der hauptsächlich nur von der Region außerhalb der Region von Interesse (11, 11A) gestreute unmarkierte Photonen (165) enthält, das an einer zweiten Erkennungseinheit (101C) gesammelt wird; und
Verarbeiten und Analysieren der Messdaten, um einen mit der Lichtreaktion der Region von Interesse (2, 2A) assoziierten Datenteil davon zu extrahieren und den genannten wenigstens einen Parameter der Region von Interesse (2, 2A) zu ermitteln, durch Trennen, von dem Lichtteil der an der ersten Erkennungseinheit (101B) gesammelten Messdaten, des mit der Lichtreaktion der Region von Interesse (2, 2A) assoziierten Datenteils auf der Basis des Lichtteils der an der zweiten Erkennungseinheit (101C) gesammelten Messdaten, die hauptsächlich nur von der Region außerhalb der Region von Interesse (11, 11A) gestreute unmarkierte Photonen (165) enthält.

25. Verfahren nach Anspruch 24, das das Bestrahlen der Region von Interesse (2, 2A) mit unfokussierter oder fokussierter Ultraschallstrahlung beinhaltet.

26. Verfahren nach Anspruch 24 zum Ermitteln von Sauerstoffsättigung der Region von Interesse (2, 2A).

27. Verfahren nach Anspruch 24, das das Nutzen der Prinzipien von Oxymetrie oder Pulsoxymetrie zum Ermitteln des gewünschten Parameters der Region von Interesse (2, 2A) beinhaltet.

28. Verfahren nach Anspruch 24, das das Anwenden der Beleuchtung von wenigstens zwei unterschiedlichen Wellenlängen und das Erzeugen von Messdaten beinhaltet, die Variationen des ultraschallmarkierten Lichtsignals in Abhängigkeit von wenigstens einer von Zeit und Wellenlänge des Beleuchtungslichts anzeigen.

29. Verfahren nach Anspruch 28, das das Analysieren der Zeitvariationen zum Ermitteln von Maxima, Minima und Durchschnitt des Signals und zum Berechnen von Sauerstoffsättigung der Region von Interesse (2, 2A) beinhaltet.

30. Verfahren nach Anspruch 24, das das Erzielen einer relativen Verschiebung zwischen einer Ausbreitungsrichtung

der akustischen Strahlung und wenigstens einer der Beleuchtungs- und Erkennungsbaugruppen der optischen Einheit (101) beinhaltet.

31. Verfahren nach Anspruch 24, das das Auswählen von wenigstens einem Lichtausgangsanschluss für Messungen aus einer Mehrzahl von beabstandeten Lichtausgangsanschlüssen der optischen Einheit (101) beinhaltet.

32. Verfahren nach Anspruch 30, das das Verschieben von wenigstens einem der Lichtein- oder -ausgangsanschlüsse der optischen Einheit (101) mit Bezug auf die Ausbreitungsrichtung der akustischen Wellen beinhaltet.

33. Verfahren nach Anspruch 24, das das Anwenden von Ultraschallbilderzeugung auf die von der Außenregion umgebene Region von Interesse (2, 2A) beinhaltet.

34. Verfahren nach Anspruch 33, wobei die Bilderzeugung mittels der genannten akustischen Einheit (110) durchgeführt wird.

35. Verfahren nach Anspruch 24, das das Erkennen von Reflexionen der Ultraschallstrahlung von dem bestrahlten Körperteil und das Ermitteln einer Doppler-Verschiebung in den erkannten Reflexionen beinhaltet.

36. Verfahren nach Anspruch 24, das das Betreiben einer Beleuchtungsbaugruppe (101A) der optischen Einheit (101) zum Ausführen von wenigstens einem der Folgenden beinhaltet:

(1) Erzeugen des Beleuchtungslichts von wenigstens zwei unterschiedlichen Wellenlängen;
(2) Erzeugen des Beleuchtungslichts von wenigstens zwei unterschiedlichen Wellenlängen jeweils zu unterschiedlichen Zeiten;
(3) Erzeugen des Beleuchtungslichts von wenigstens zwei unterschiedlichen Wellenlängen, die mit wenigstens einer von Frequenz- und Phasencharakteristiken unterschiedlich moduliert sind.

37. Verfahren nach Anspruch 24, das das Betreiben einer Beleuchtungsbaugruppe (101A) der optischen Einheit (101) zum Erzeugen des Beleuchtungslichts von wenigstens zwei unterschiedlichen Wellenlängen beinhaltet, wobei die genannten wenigstens zwei unterschiedlichen Wellenlängen so gewählt sind, dass sie wenigstens eine der folgenden Bedingungen erfüllen:

(a) dass sie durch oxygeniertes und desoxygeniertes Hämoglobin unterschiedlich absorbiert werden;
(b) dass sie durch Gewebe- oder Fluidkomponenten gleichermaßen absorbiert werden;
(c) dass sie durch Gewebe- oder Fluidkomponenten im Körper unterschiedlich absorbiert werden; und
(d) dass sie durch Gewebe- oder Fluidkomponenten unterschiedlich gestreut werden.

38. Verfahren nach Anspruch 24, das das Betreiben der optischen Einheit (101) eine vorbestimmte Zeit nach dem Betreiben der akustischen Einheit (110) beinhaltet, wobei die genannte vorbestimmte Zeit einer Zeit entspricht, die benötigt wird, damit die Schallwellen (150) der vorbestimmten Frequenz die Region von Interesse (2, 2A) erreichen, wo die Überlappung mit dem Beleuchtungslicht erzielt werden soll.

39. Verfahren nach Anspruch 24, wobei der genannte wenigstens eine gewünschte Parameter wenigstens eines der Folgenden beinhaltet:

Sauerstoffsättigungsniveau; und
Konzentration einer Substanz oder einer Struktur in der Region von Interesse (2, 2A).

40. Verfahren nach Anspruch 24 zur Verwendung bei der nichtinvasiven Überwachung eines Fötuszustands (2).

41. Verfahren nach Anspruch 24, wobei der genannte wenigstens eine gewünschte Parameter wenigstens eines der Folgenden beinhaltet:

einen Fötus-Blutparameter (2);
ein Sauerstoffsättigungsniveau des Fötus (2);
die Konzentration einer Substanz oder Struktur in dem Fötus (2);
die Konzentration einer Substanz oder Struktur im Fruchtwasser;
die Anwesenheit und Konzentration von Mekonium im Fruchtwasser;

die Anwesenheit und Konzentration von Blut im Fruchtwasser; und ein Lungenreifeniveau des Fötus (2).

42. Verfahren nach Anspruch 41, wobei der genannte wenigstens eine gewünschte Parameter das Lungenreifeniveau des Fötus (2) beinhaltet, wobei das Verfahren die Ermittlung von Anwesenheit und Konzentration von lamellaren Körpern im Fruchtwasser beinhaltet.

43. Verfahren nach Anspruch 40, wobei die fötusbezogene Region von Interesse (2) nur eine Fruchtwasserregion beinhaltet, wobei der genannte wenigstens eine gewünschte Parameter wenigstens eines der Folgenden beinhaltet:

ein Lungenreifeniveau des Fötus (2);
die Anwesenheit von lamellaren Körpern;
die Konzentration von lamellaren Körpern;
die Anwesenheit von Mekonium;
die Konzentration von Mekonium;
die Anwesenheit von Blut; und
die Konzentration von Blut.

44. Verfahren nach Anspruch 40, wobei die fötusbezogene Region von Interesse (2) nur den Fötus (2) beinhaltet, der genannte wenigstens eine Parameter Sauerstoffsättigungsniveau und/oder Konzentration einer Substanz oder Struktur in der Fötusregion beinhaltet.

45. Verfahren nach Anspruch 24 zur nichtinvasiven Überwachung von optischen Eigenschaften eines extravaskulären Fluids, wie z.B. von pleuralen, perikardialen, peritonealen und synovialen Fluiden.

46. Verfahren nach Anspruch 24 zur Verwendung bei der nichtinvasiven Überwachung von Sauerstoffsättigungsniveaus, wobei das Verfahren Folgendes beinhaltet: Anwenden einer Ultraschallmarkierung von Licht in oxymetrischen Pulsmessungen, Gewinnen von Messdaten, die Variationen von von einem Bereich von Interesse (2) gestreuten, ultraschallmarkierten Lichtsignalen in Abhängigkeit von wenigstens einer von Zeit und Wellenlänge von Beleuchtungslicht anzeigen, und Analysieren der Messdaten zum Berechnen des Sauerstoffsättigungsniveaus.

47. Verfahren zum Betreiben eines Überwachungssystems (300, 300A, 400, 500), das zur nichtinvasiven Überwachung von wenigstens einem Parameter einer Region von Interesse (2, 2A) in einem menschlichen Körper konfiguriert ist, wobei das System eine optische Einheit (101) und eine akustische Einheit (110) umfasst, die zum Erzeugen von Schallwellen (150) eines vorbestimmten Ultraschallfrequenzbereichs konfiguriert ist, wobei das Verfahren Folgendes beinhaltet:

Betreiben des Überwachungssystems (300, 300A, 400, 500) zum Bereitstellen einer optimalen Positionierung der optischen und akustischen Einheit (101, 110) mit Bezug zueinander und mit Bezug auf die Region von Interesse (2), um eine Betriebsbedingung für Messungen zu erfüllen, wobei die genannte Betriebsbedingung dazu führt, dass die Ultraschallwellen (255) des vorbestimmten Frequenzbereichs mit von der optischen Einheit (101) in der Region von Interesse (2, 2A) erzeugtem Beleuchtungslicht überlappen und in einer Region außerhalb der Region von Interesse (11, 11A) im Wesentlichen nicht überlappen, und dazu, dass eine Erkennungsbaugruppe der optischen Einheit (101) von der Region von Interesse (2, 2A) gestreutes Licht mit einer ersten Erkennungseinheit (101B) sammelt und Licht von der Region außerhalb der Region von Interesse (11, 11A) mit einer zweiten Erkennungseinheit (101C) sammelt,
um dadurch Messdaten zu gewinnen, die an der ersten Erkennungseinheit (101B) gesammeltes gestreutes Licht anzeigen, das einen ultraschallmarkierten Lichtteil, der von der Region von Interesse (2, 2A) gestreut wurde, und einen an der zweiten Erkennungseinheit (101C) gesammelten unmarkierten Lichtteil beinhaltet, der hauptsächlich nur von der Region außerhalb der Region von Interesse (11, 11A) gestreute unmarkierte Photonen (165) enthält, und eine Extraktion eines Datenteils aus den genannten Messdaten zu ermöglichen, der eine Lichtreaktion der Region von Interesse (2, 2A) anzeigt, durch Trennen, von dem Lichtteil der an der ersten Erkennungseinheit (101B) gesammelten Messdaten, des mit der Lichtreaktion der Region von Interesse (2, 2A) assoziierten Datenteils auf der Basis des unmarkierten Lichtteils der an der zweiten Erkennungseinheit (101C) gesammelten Messdaten, der hauptsächlich nur von der Region außerhalb der Region von Interesse (11, 11A) gestreute unmarkierte Photonen (165) enthält.

Revendications

1. Système de surveillance (300, 300A, 400, 500) destiné à être utilisé pour surveiller de façon non invasive au moins un paramètre d'une région d'intérêt (2, 2A) dans un corps humain, le système comprenant :

   - une unité de mesure comportant :

     une unité optique (101) possédant un ensemble d'éclairement (101A) configuré de façon à définir au moins un port de sortie (121, 121A, 121B) pour une lumière d'éclairement, et un ensemble de détection de lumière configuré de façon à définir des première et seconde unités de détection (101B, 101C), la première unité de détection au moins (101B) étant configurée de façon à définir au moins un port d'entrée de lumière (122) ; et
     une unité acoustique (110) configurée de façon à générer des ondes acoustiques (150) ayant une gamme de fréquences ultrasoniques prédéterminées ;

   l'unité de mesure étant configurée et exploitable de façon à procurer un état opérationnel de sorte que les ondes acoustiques (150) de la gamme de fréquences prédéterminées présentent un chevauchement avec une région d'éclairement dans la région d'intérêt (2, 2A) et ne présentent sensiblement aucun chevauchement avec une région située en dehors de la région d'intérêt (11, 11A), et que la première unité de détection (101B) de l'ensemble de détection collecte la lumière (155) diffusée en provenance de la région d'intérêt (2, 2A), et la seconde unité de détection (101C) de l'ensemble de détection collecte la lumière (165) diffusée en provenance de la région située en dehors de la région d'intérêt (11, 11A), les données mesurées indiquant par conséquent les éléments suivants :

     une lumière diffusée collectée au niveau de la première unité de détection (101B) qui englobe une portion de lumière marquée ultrasonique qui a été diffusée à partir de la région d'intérêt (2, 2A), et
     une portion de lumière non marquée collectée au niveau de la seconde unité de détection (101C) qui ne contient principalement que des photons non marqués (165) qui ont été diffusés par la région située en dehors de la région d'intérêt (11, 11A) ; et

   - une unité de commande (120), qui est apte à être connectée à l'unité optique (101), et à l'unité acoustique (110), afin d'exploiter ces unités (101, 110), l'unité de commande (120) étant sensible aux données mesurées et préprogrammée pour traiter et analyser les données mesurées afin d'extraire de celles-ci une portion de données qui est associée à la réaction lumineuse de la région d'intérêt (2, 2A) et de déterminer ledit au moins un paramètre de la région d'intérêt (2, 2A) en séparant, à partir de la portion de lumière des données mesurées ayant été collectées au niveau de la première unité de détection (101B), la portion de données associée à la réaction lumineuse de la région d'intérêt (2, 2A), sur la base de la portion de lumière des données mesurées ayant été collectées au niveau de la seconde unité de détection (101C) laquelle ne contient principalement que des photons non marqués (165) qui ont été diffusés par la région située en dehors de la région d'intérêt (11, 11A).

2. Système selon la revendication 1, l'unité acoustique (110) étant configurée de façon à générer un rayonnement ultrasonique sous la forme d'une rafale ou d'une impulsion ou d'une onde continue ; et à exécuter au moins l'une des opérations suivantes, à savoir :

   (1) générer un rayonnement ultrasonique non focalisé ;
   (2) générer un rayonnement ultrasonique focalisé, cas dans lequel une longueur focale correspond à une distance allant de l'unité acoustique (110) à la région d'intérêt (2, 2A).

3. Système selon la revendication 1, ledit au moins un paramètre étant la saturation en oxygène de la région d'intérêt (2, 2A).

4. Système selon la revendication 1, configuré de façon à utiliser les principes soit de l'oxymétrie soit de l'oxymétrie du pouls pour déterminer le paramètre désiré de la région d'intérêt (2, 2A).

5. Système selon la revendication 1, l'unité de mesure étant configurée et exploitable de façon à générer les données mesurées lesquelles indiquent les variations dans le signal de lumière marquée ultrasonique en tant que fonction de l'un au moins des facteurs suivants, soit la durée soit la longueur d'onde de la lumière d'éclairement, l'unité de commande (120) étant configurée de façon à analyser les variations dans le signal de lumière marquée ultrasonique

afin de déterminer les valeurs maximales/minimales du signal et de calculer la saturation en oxygène.

6. Système selon la revendication 1, l'unité de commande (120) étant préprogrammée et exploitable de façon à exécuter au moins l'une des opérations suivantes, à savoir :

(1) procurer un positionnement optimal de l'unité optique (101) et de l'unité acoustique (110), ledit positionnement optimal satisfaisant ledit état opérationnel ;
(2) exploiter l'unité optique (101) pendant une durée prédéterminée après l'exploitation de l'unité acoustique (110), ce qui permet par conséquent de procurer ledit état opérationnel.

7. Système selon la revendication 1, l'unité de commande (120) étant préprogrammée et exploitable de façon à procurer un positionnement optimal de l'unité optique (101) et de l'unité acoustique (110), ledit positionnement optimal satisfaisant ledit état opérationnel, et l'unité de commande (120) étant exploitable de façon à procurer un déplacement relatif entre un sens de propagation du rayonnement acoustique et de l'un au moins des ensembles suivants, à savoir l'ensemble d'éclairement et l'ensemble de détection, de sorte à procurer ledit positionnement optimal.

8. Système selon la revendication 1, l'ensemble d'éclairement (101A) étant configuré de façon à exécuter au moins l'une des opérations suivantes, à savoir : (1) définir au moins deux des ports de sortie de lumière (121, 121A, 121B) lesquels sont espacés l'un de l'autre ; et (2) générer la lumière d'éclairement à deux différentes longueurs d'onde au moins.

9. Système selon la revendication 1, l'ensemble d'éclairement (101A) étant configuré de façon à générer la lumière d'éclairement à deux différentes longueurs d'onde au moins.

10. Système selon la revendication 8, l'unité de commande (120) étant exploitable de façon à sélectionner l'un au moins des ports de sortie de lumière (121, 121A, 121B) pour réaliser des mesures, afin de procurer ledit état opérationnel.

11. Système selon la revendication 7, l'unité de commande (120) étant exploitable de façon à déplacer au moins l'un des ports, à savoir le port d'entrée de lumière ou le port de sortie de lumière (121, 121A, 121B), par rapport au sens de la propagation des ondes acoustiques (150).

12. Système selon la revendication 9, les deux différentes longueurs d'onde étant déterminées par l'une au moins des conditions suivantes, à savoir :

(1) elles doivent être absorbables différemment par l'hémoglobine oxygénée et désoxygénée dans le corps ;
(2) elles doivent être **caractérisées par** le même degré d'absorption par les composants tissulaires ou fluidiques dans le corps ;
(3) elles doivent être **caractérisées par** un différent degré d'absorption par les composants tissulaires ou fluidiques dans le corps ; et
(4) elles doivent être diffusées différemment par les composants tissulaires ou fluidiques dans le corps.

13. Système selon la revendication 9, l'ensemble d'éclairement (101A) étant exploitable de façon à générer lesdites au moins deux différentes longueurs d'onde à des moments différents, respectivement.

14. Système selon la revendication 9, lesdites au moins deux longueurs d'onde étant modulées différemment par l'un au moins des facteurs suivants, à savoir des caractéristiques de fréquence et des caractéristiques de phase.

15. Système selon la revendication 13, lesdites au moins deux longueurs d'onde étant modulées différemment par l'un au moins des facteurs suivants, à savoir des caractéristiques de fréquence et des caractéristiques de phase.

16. Système selon la revendication 1, l'unité de commande (120) étant préprogrammée et exploitable de façon à exploiter l'unité optique (101) pendant une durée prédéterminée après l'exploitation de l'unité acoustique (110), ce qui permet par conséquent de procurer ledit état opérationnel, ladite durée prédéterminée correspondant à une durée requise pour que les ondes acoustiques (150) de la fréquence prédéterminée atteignent la région à l'endroit où le chevauchement avec la lumière d'éclairement doit être prévu.

17. Système selon la revendication 1, comprenant une structure de support (103) configurée de façon à être mise en contact avec un corps, ladite structure de support (103) portant au moins les ports de sortie de lumière et d'entrée

de lumière (122, 122A, 122B) des ensembles d'éclairement et de détection, respectivement.

18. Système selon la revendication 17, ladite structure de support (103) possédant au moins l'une des configurations suivantes :

(1) est configurée pour porter les ensembles d'éclairement et de détection ;
(2) est configurée pour porter l'unité acoustique (110) ;
(3) est configurée pour porter un port de sortie ultrasonique (245) de l'unité acoustique (110) ; et
(4) est souple afin d'envelopper la portion corps.

19. Système selon la revendication 1, l'unité acoustique (110) comprenant un groupe piloté en phase de transducteurs ultrasoniques.

20. Système selon la revendication 1, l'unité de commande (120) étant configurée de façon à recevoir des données lesquelles indiquent les réflexions des ondes ultrasoniques (255) en provenance d'un volume irradié à l'intérieur du corps pour :

(a) créer des données indiquant une image du volume irradié, et analyser lesdites données d'image afin de procurer ledit état opérationnel pour réaliser des mesures ; ou
(b) déterminer des données lesquelles indiquent un décalage par effet Doppler dans les réflexions du rayonnement ultrasonique.

21. Système selon la revendication 1, ladite gamme de fréquences prédéterminées du rayonnement ultrasonique étant de 50 kHz à 8 MHz.

22. Système selon la revendication 1, le rayonnement ultrasonique ayant une fréquence qui est inférieure à 1 MHz.

23. Système selon la revendication 1, configuré pour être utilisé dans la surveillance de l'un au moins des paramètres suivants, à savoir : niveau de saturation en oxygène de la région d'intérêt (2, 2A), et concentration d'une substance ou d'une structure dans la région d'intérêt (2, 2A).

24. Procédé destiné à être utilisé pour surveiller de façon non invasive au moins un paramètre d'une région d'intérêt (2, 2A) dans un corps humain, le procédé comprenant les opérations consistant à :

exploiter une unité optique (101) et une unité acoustique (110) pour faire en sorte que des ondes ultrasoniques (255) d'une gamme de fréquences prédéterminées et une lumière d'éclairement présentent un chevauchement dans la région d'intérêt (2, 2A) et ne présentent sensiblement aucun chevauchement avec une région située en dehors de la région d'intérêt (11, 11A), ce qui permet par conséquent de produire des données mesurées lesquelles indiquent la lumière collectée englobant la lumière diffusée avec une portion de lumière marquée ultrasonique ayant été diffusée à partir de la région d'intérêt (2, 2A) qui a été collectée au niveau d'une première unité de détection (101B), et une portion de lumière non marquée qui ne contient principalement que des photons non marqués (165) ayant été diffusés par la région située en dehors de la région d'intérêt (11, 11A) qui a été collectée au niveau d'une seconde unité de détection (101C) ; et
traiter et analyser les données mesurées afin d'extraire de celles-ci une portion de données qui est associée à la réaction lumineuse de la région d'intérêt (2, 2A) et déterminer ledit au moins un paramètre de la région d'intérêt (2, 2A) en séparant, à partir de la portion de lumière des données mesurées ayant été collectées au niveau de la première unité de détection (101B), la portion de données associée à la réaction lumineuse de la région d'intérêt (2, 2A), sur la base de la portion de lumière des données mesurées ayant été collectées au niveau de la seconde unité de détection (101C) laquelle ne contient principalement que des photons non marqués (165) qui ont été diffusés par la région située en dehors de la région d'intérêt (11, 11A).

25. Procédé selon la revendication 24, comprenant l'irradiation de la région d'intérêt (2, 2A) à l'aide d'un rayonnement ultrasonique non focalisé ou focalisé.

26. Procédé selon la revendication 24, pour déterminer la saturation en oxygène de la région d'intérêt (2, 2A).

27. Procédé selon la revendication 24, utilisant les principes de l'oxymétrie ou de l'oxymétrie du pouls pour déterminer le paramètre désiré de la région d'intérêt (2, 2A).

28. Procédé selon la revendication 24, comprenant les opérations consistant à appliquer l'éclairement à au moins deux différentes longueurs d'onde, et à générer les données mesurées lesquelles indiquent les variations dans le signal de lumière marquée ultrasonique en tant que fonction de l'un au moins des facteurs suivants, soit la durée soit la longueur d'onde de la lumière d'éclairement.

29. Procédé selon la revendication 28, comprenant l'opération consistant à analyser les variations de durée afin de déterminer les valeurs maximales, minimales et moyennes du signal et de calculer la saturation en oxygène de la région d'intérêt (2, 2A).

30. Procédé selon la revendication 24, comprenant l'opération consistant à procurer un déplacement relatif entre un sens de propagation du rayonnement acoustique et de l'un au moins des ensembles suivants, à savoir l'ensemble d'éclairement et l'ensemble de détection, de l'unité optique (101).

31. Procédé selon la revendication 24, comprenant l'opération consistant à sélectionner, en vue de la réalisation de mesures, au moins un port de sortie de lumière, parmi une pluralité de ports de sortie de lumière espacés l'un de l'autre, de l'unité optique (101).

32. Procédé selon la revendication 30, comprenant l'opération consistant à déplacer au moins l'un des ports, à savoir le port d'entrée de lumière ou le port de sortie de lumière, de l'unité optique (101) par rapport au sens de la propagation des ondes acoustiques.

33. Procédé selon la revendication 24, comprenant l'opération consistant à appliquer une imagerie ultrasonique à la région d'intérêt (2, 2A) entourée par la région externe.

34. Procédé selon la revendication 33, l'imagerie étant exécutée grâce à l'utilisation de ladite unité acoustique (110).

35. Procédé selon la revendication 24, comprenant l'opération consistant à détecter les réflexions du rayonnement ultrasonique en provenance de la portion irradiée du corps, et à déterminer un décalage par effet Doppler dans les réflexions ayant été détectées.

36. Procédé selon la revendication 24, comprenant l'exploitation d'un ensemble d'éclairement (101A) de l'unité optique (101) pour exécuter l'une au moins des opérations suivantes, à savoir :

(1) générer la lumière d'éclairement avec au moins deux différentes longueurs d'onde ;
(2) générer la lumière d'éclairement avec au moins deux différentes longueurs d'onde à des moments différents, respectivement ;
(3) générer la lumière d'éclairement avec au moins deux différentes longueurs d'onde lesquelles sont modulées différemment par l'un au moins des facteurs suivants, à savoir des caractéristiques de fréquence et des caractéristiques de phase.

37. Procédé selon la revendication 24, comprenant l'exploitation d'un ensemble d'éclairement (101A) de l'unité optique (101) afin de générer la lumière d'éclairement à deux différentes longueurs d'onde au moins, lesdites au moins deux différentes longueurs d'onde étant sélectionnées pour satisfaire au moins l'une des conditions suivantes, à savoir :

(a) elles doivent être absorbées différemment par l'hémoglobine oxygénée et désoxygénée;
(b) elles doivent être absorbées de façon égale par les composants tissulaires ou fluidiques ;
(c) elles doivent être absorbées différemment par les composants tissulaires ou fluidiques dans le corps ; et
(d) elles doivent être diffusées différemment par les composants tissulaires ou fluidiques.

38. Procédé selon la revendication 24, comprenant l'exploitation de l'unité optique (101) pendant une durée prédéterminée après l'exploitation de l'unité acoustique (110), ladite durée prédéterminée correspondant à une durée requise pour que les ondes acoustiques (150) de la fréquence prédéterminée atteignent la région d'intérêt (2, 2A), à l'endroit où le chevauchement avec la lumière d'éclairement doit être prévu.

39. Procédé selon la revendication 24, ledit au moins un paramètre désiré englobant au moins l'un des éléments suivants, à savoir :

un niveau de saturation en oxygène ; et
une concentration d'une substance ou d'une structure dans la région d'intérêt (2, 2A).

40. Procédé selon la revendication 24, destiné à être utilisé pour assurer une surveillance non invasive de l'état d'un foetus (2).

41. Procédé selon la revendication 24, ledit au moins un paramètre désiré englobant au moins l'un des éléments suivants, à savoir :

un paramètre de sang chez le foetus (2) ;
un niveau de saturation en oxygène du foetus (2) ;
une concentration d'une substance ou d'une structure dans le foetus (2) ;
une concentration d'une substance ou d'une structure dans le liquide amniotique ;
une présence de méconium dans le fluide amniotique et sa concentration ;
une présence de sang dans le fluide amniotique et sa concentration ; et un niveau de maturité des poumons chez le foetus (2).

42. Procédé selon la revendication 41, ledit au moins un paramètre désiré englobant le niveau de maturité des poumons chez le foetus (2), le procédé comprenant l'opération consistant à déterminer la présence et la concentration de corps lamellaires dans le fluide amniotique.

43. Procédé selon la revendication 40, la région d'intérêt liée au foetus (2) englobant uniquement une région à fluide amniotique, ledit au moins un paramètre désiré englobant au moins l'un des éléments suivants, à savoir :

un niveau de maturité des poumons chez le foetus (2) ;
une présence de corps lamellaires ;
une concentration de corps lamellaires ;
une présence de méconium ;
une concentration de méconium ;
une présence de sang ; et
une concentration de sang.

44. Procédé selon la revendication 40, la région d'intérêt liée au foetus (2) englobant uniquement le foetus (2), ledit au moins un paramètre incluant au moins l'un des éléments suivants, à savoir : un niveau de saturation en oxygène, et une concentration d'une substance ou d'une structure dans la région foetale.

45. Procédé selon la revendication 24, pour assurer une surveillance non invasive des propriétés optiques d'un fluide extravasculaire, par exemple un fluide pleural, péricardique, péritonéal et synovial.

46. Procédé selon la revendication 24, destiné à être utilisé pour assurer une surveillance non invasive du niveau de saturation en oxygène, le procédé comprenant les opérations consistant à : appliquer un marquage ultrasonique de lumière dans les mesures de l'oxymétrie de pouls, obtenir des données mesurées lesquelles indiquent les variations dans les signaux de lumière marquée ultrasonique diffusés à partir d'une région d'intérêt (2) en tant que fonction de l'un au moins des facteurs suivants, soit la durée soit la longueur d'onde de la lumière d'éclairement, et analyser les données mesurées dans le but de calculer le niveau de saturation en oxygène.

47. Procédé destiné à exploiter un système de surveillance (300, 300A, 400, 500), configuré pour une surveillance non invasive d'au moins un paramètre d'une région d'intérêt (2, 2A) dans un corps humain, alors que ce système comporte une unité optique (101) et une unité acoustique (110) configurée pour générer des ondes acoustiques (150) ayant une gamme de fréquences ultrasoniques prédéterminées, le procédé comprenant les opérations consistant à :

exploiter le système de surveillance (300, 300A, 400, 500) de façon à procurer un positionnement optimal des unités optique et acoustique (101, 110) l'une par rapport à l'autre, et par rapport à la région d'intérêt (2) afin de satisfaire un état opérationnel pour réaliser des mesures, ledit état opérationnel aboutissant au fait que les ondes ultrasoniques (255) de la gamme de fréquences prédéterminées présentent un chevauchement avec une lumière d'éclairement générée par l'unité optique (101) dans la région d'intérêt (2, 2A), alors qu'elles ne présentent sensiblement aucun chevauchement dans une région située en dehors de la région d'intérêt (11,

11A), et aboutissant au fait qu'un ensemble de détection de l'unité optique (101) collecte la lumière diffusée en provenance de la région d'intérêt (2, 2A) en vertu de l'utilisation d'une première unité de détection (101B), et collecte la lumière en provenance de la région située en dehors de la région d'intérêt (11, 11A), en vertu de l'utilisation d'une seconde unité de détection (101C),

ce qui permet par conséquent d'obtenir des données mesurées indiquant les éléments suivants, à savoir une lumière diffusée collectée au niveau de la première unité de détection (101B) qui englobe une portion de lumière marquée ultrasonique qui a été diffusée par la région d'intérêt (2, 2A), et une portion de lumière non marquée collectée au niveau de la seconde unité de détection (101C) qui ne contient principalement que des photons non marqués (165) qui ont été diffusés par la région située en dehors de la région d'intérêt (11, 11A), et d'assurer l'extraction, à partir desdites données mesurées,

d'une portion de données qui indique une réaction lumineuse de la région d'intérêt (2, 2A) en séparant, à partir de la portion de lumière des données mesurées ayant été collectées au niveau de la première unité de détection (101B), la portion de données associée à la réaction lumineuse de la région d'intérêt (2, 2A), sur la base de la portion de lumière non marquée des données mesurées ayant été collectées au niveau de la seconde unité de détection (101C) laquelle ne contient principalement que des photons non marqués (165) qui ont été diffusés par la région située en dehors de la région d'intérêt (11, 11A).

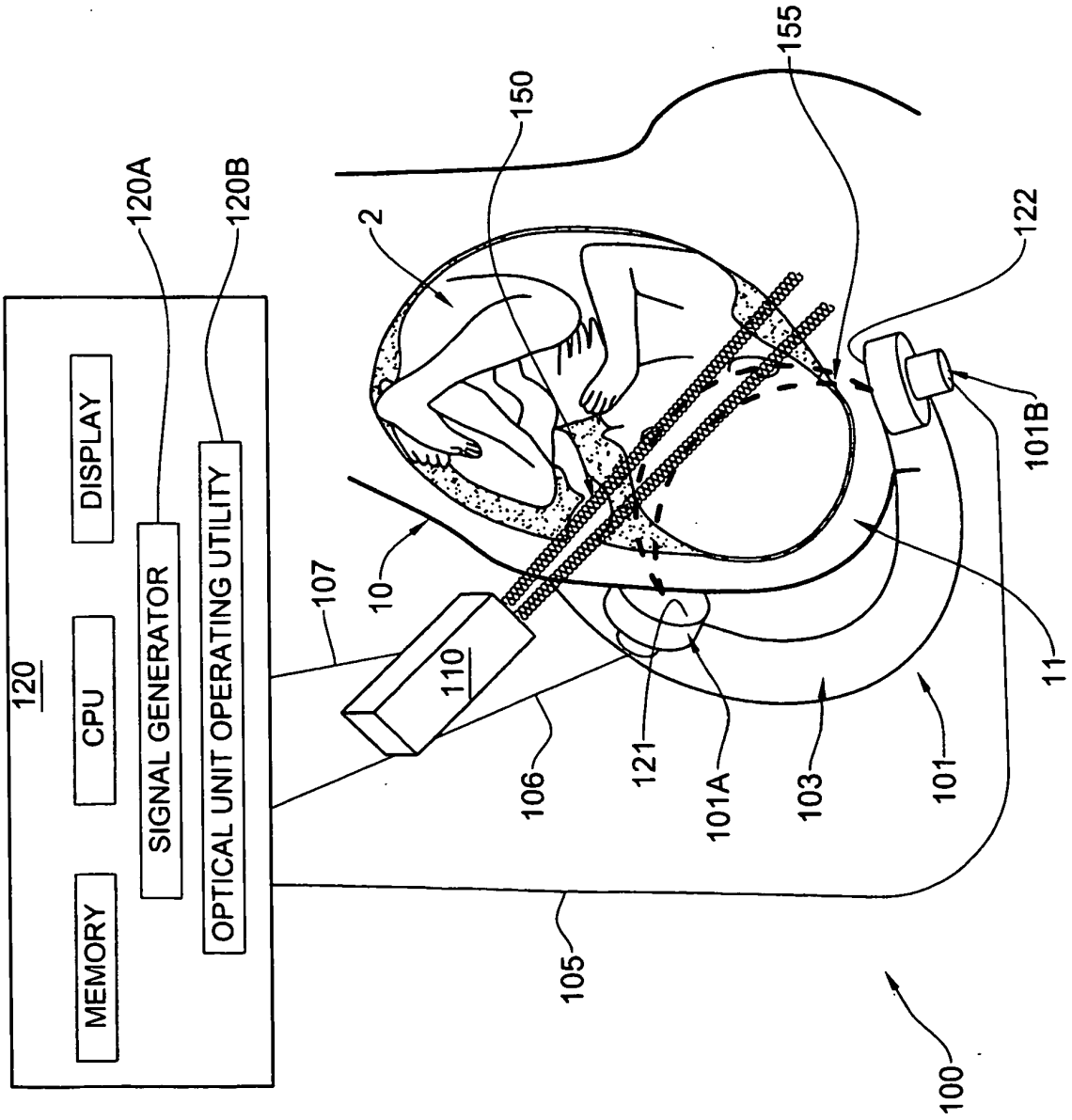
120
MEMORY
CPU
DISPLAY
SIGNAL GENERATOR
OPTICAL UNIT OPERATING UTILITY
120A
120B
107
10
110
2
150
155
122
101B
11
106
121
101A
103
101
105
100

FIG. 1A

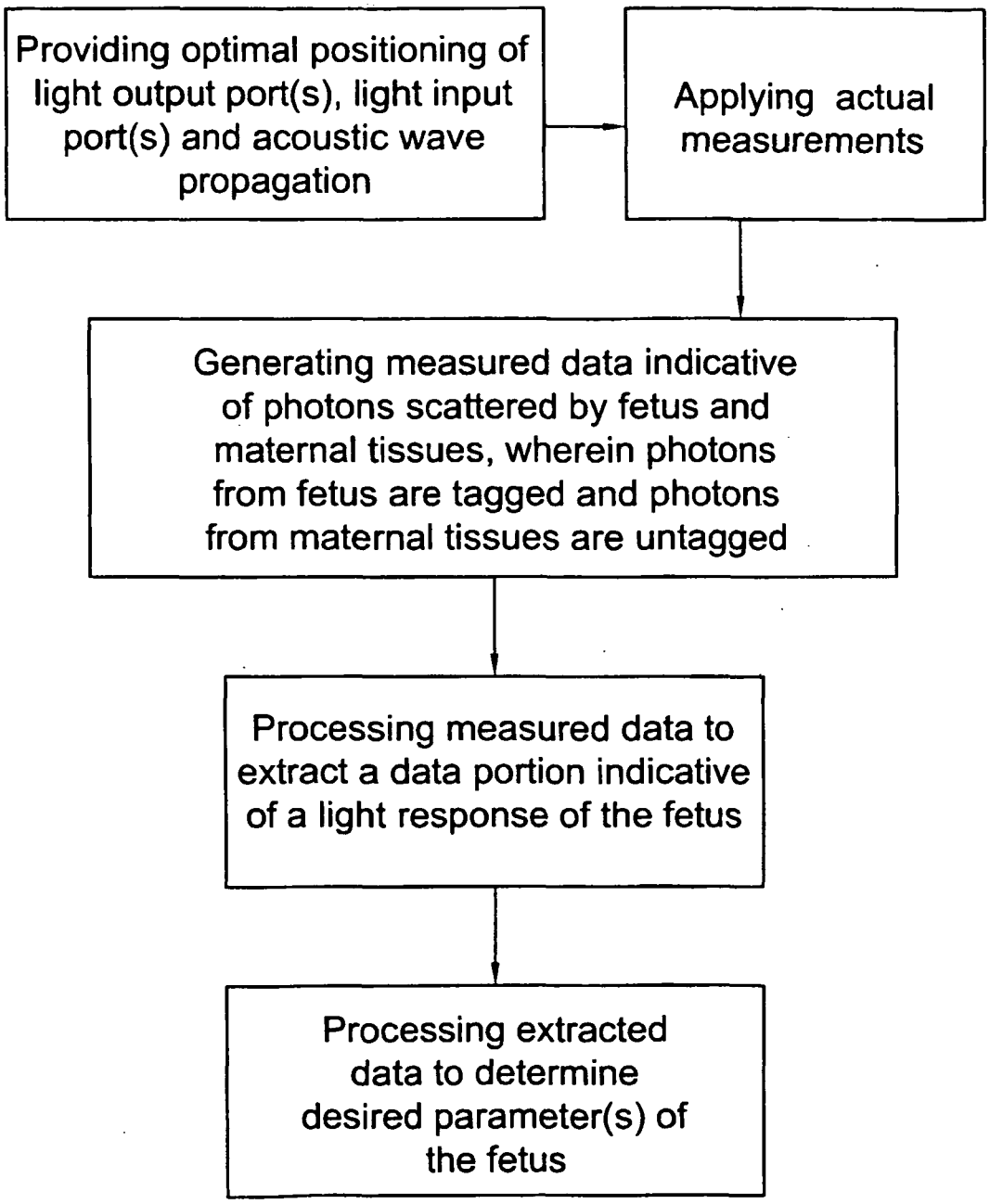
Providing optimal positioning of light output port(s), light input port(s) and acoustic wave propagation
Applying actual measurements
Generating measured data indicative of photons scattered by fetus and maternal tissues, wherein photons from fetus are tagged and photons from maternal tissues are untagged
Processing measured data to extract a data portion indicative of a light response of the fetus
Processing extracted data to determine desired parameter(s) of the fetus

FIG. 1B

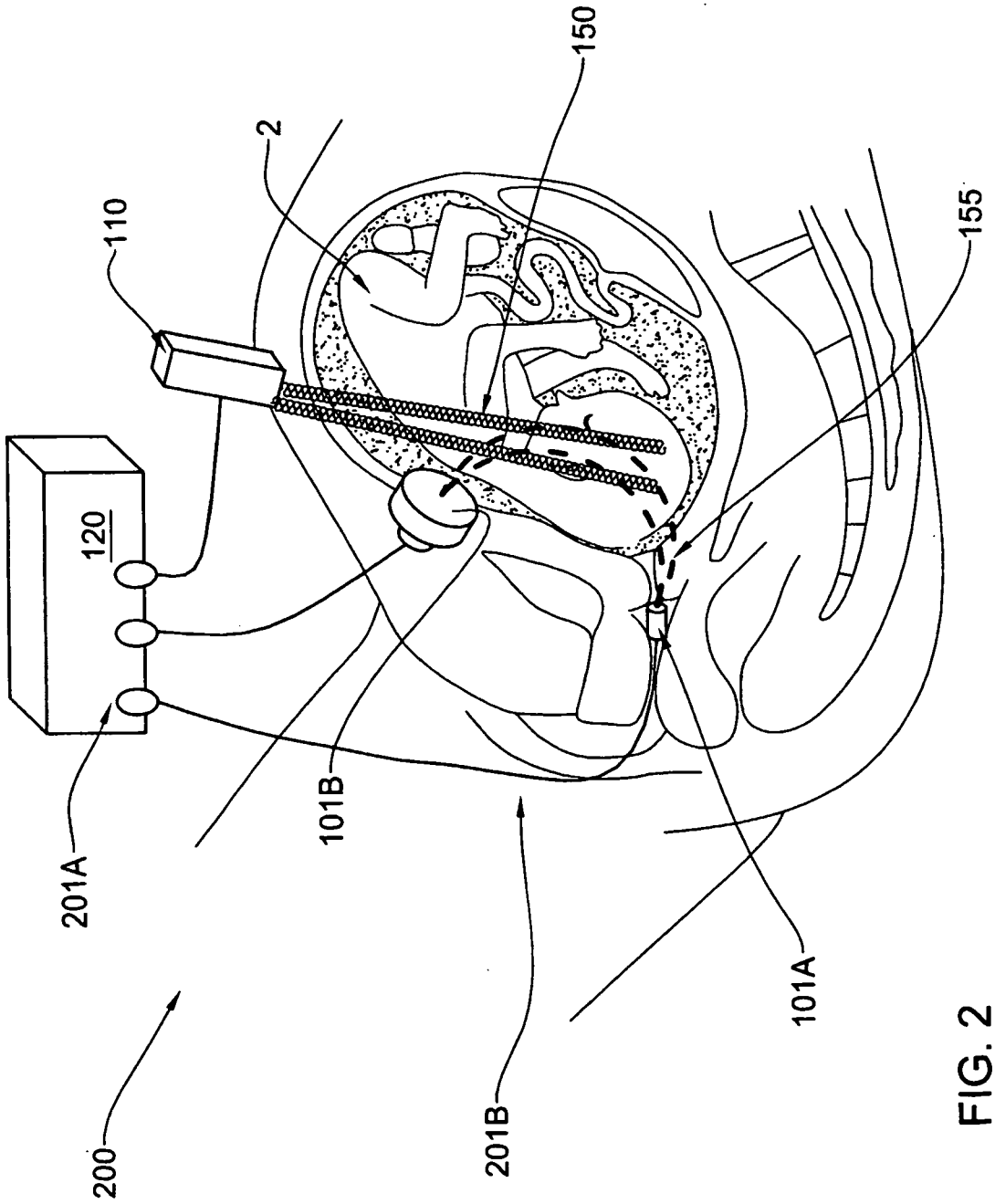

FIG. 2

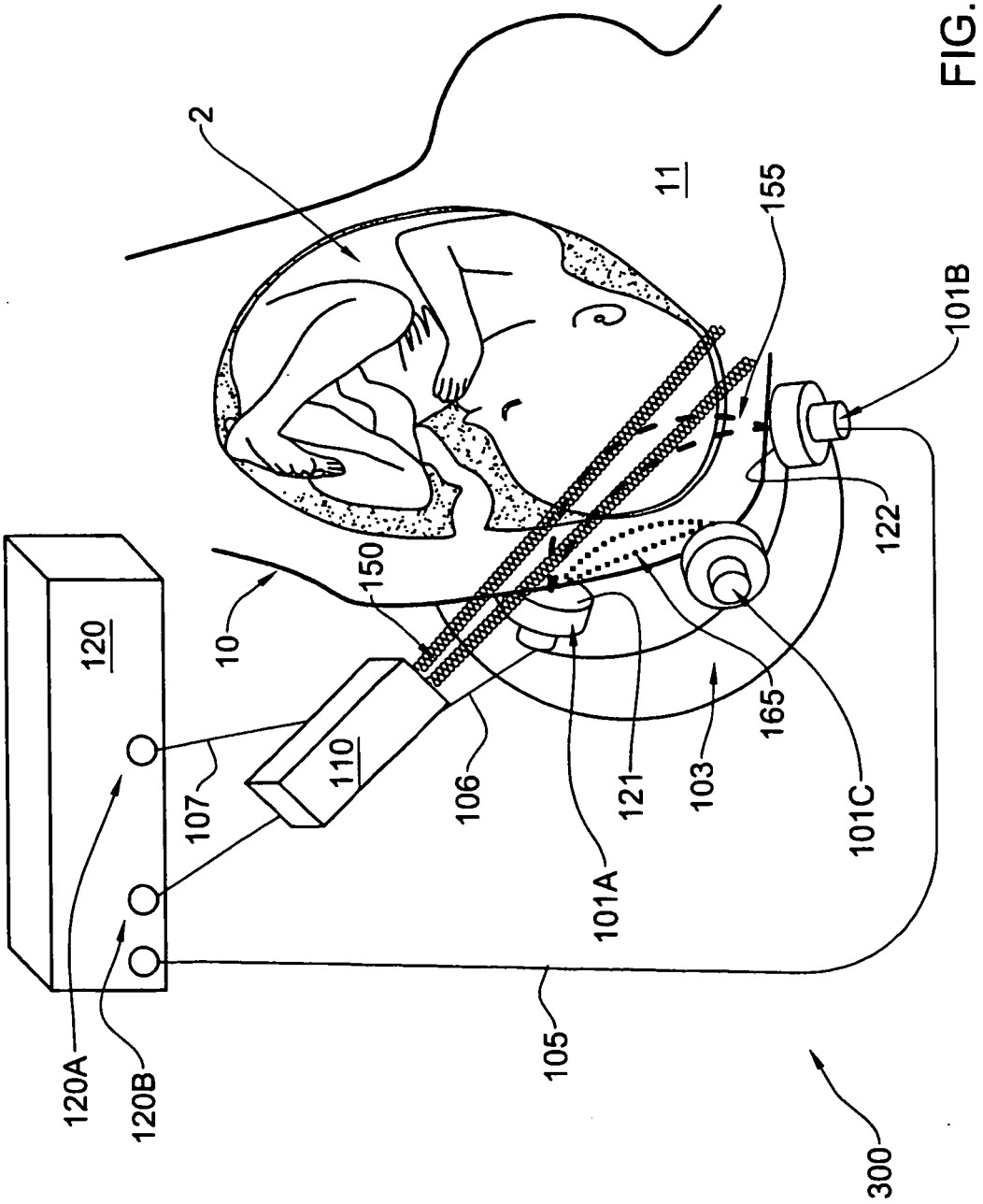
2
11
155
101B
122
150
10
120
110
107
106
121
103
165
101C
101A
105
120A
120B
300

FIG. 3A

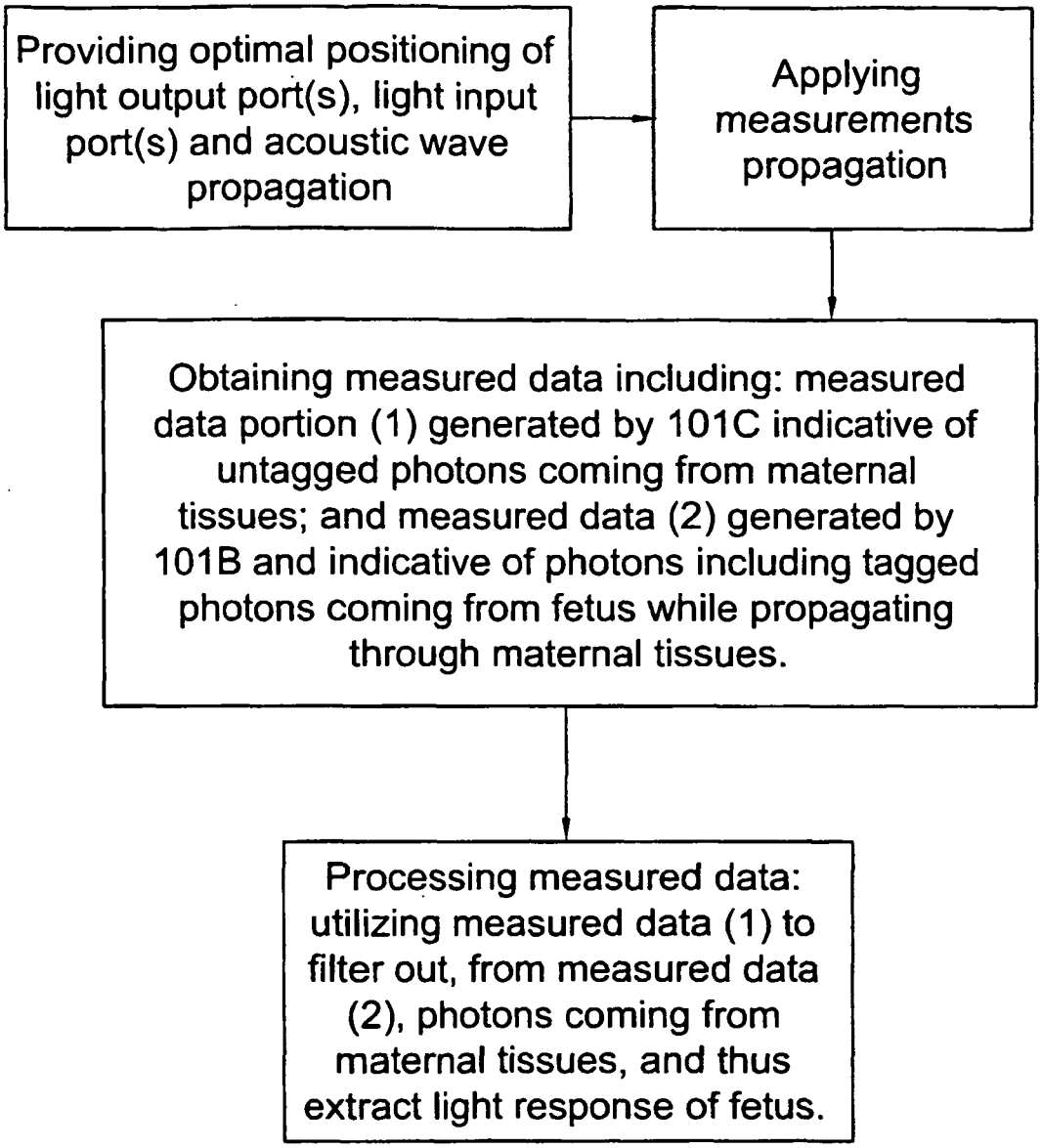
Providing optimal positioning of light output port(s), light input port(s) and acoustic wave propagation
Applying measurements propagation
Obtaining measured data including: measured data portion (1) generated by 101C indicative of untagged photons coming from maternal tissues; and measured data (2) generated by 101B and indicative of photons including tagged photons coming from fetus while propagating through maternal tissues.
Processing measured data: utilizing measured data (1) to filter out, from measured data (2), photons coming from maternal tissues, and thus extract light response of fetus.

FIG. 3B

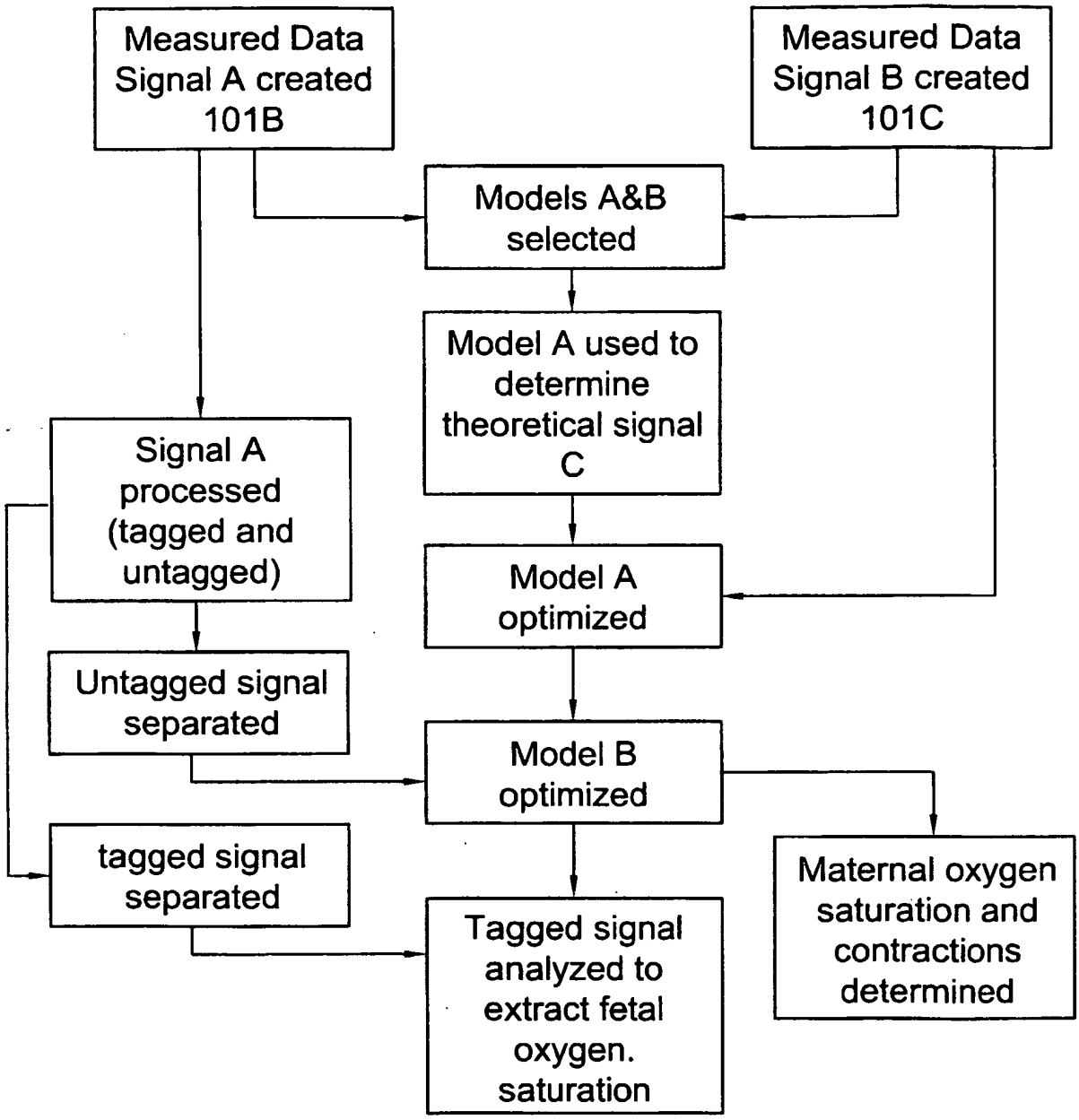
Measured Data Signal A created 101B
Measured Data Signal B created 101C
Models A&B selected
Model A used to determine theoretical signal C
Signal A processed (tagged and untagged)
Model A optimized
Untagged signal separated
Model B optimized
tagged signal separated
Maternal oxygen saturation and contractions determined
Tagged signal analyzed to extract fetal oxygen. saturation

FIG. 3C

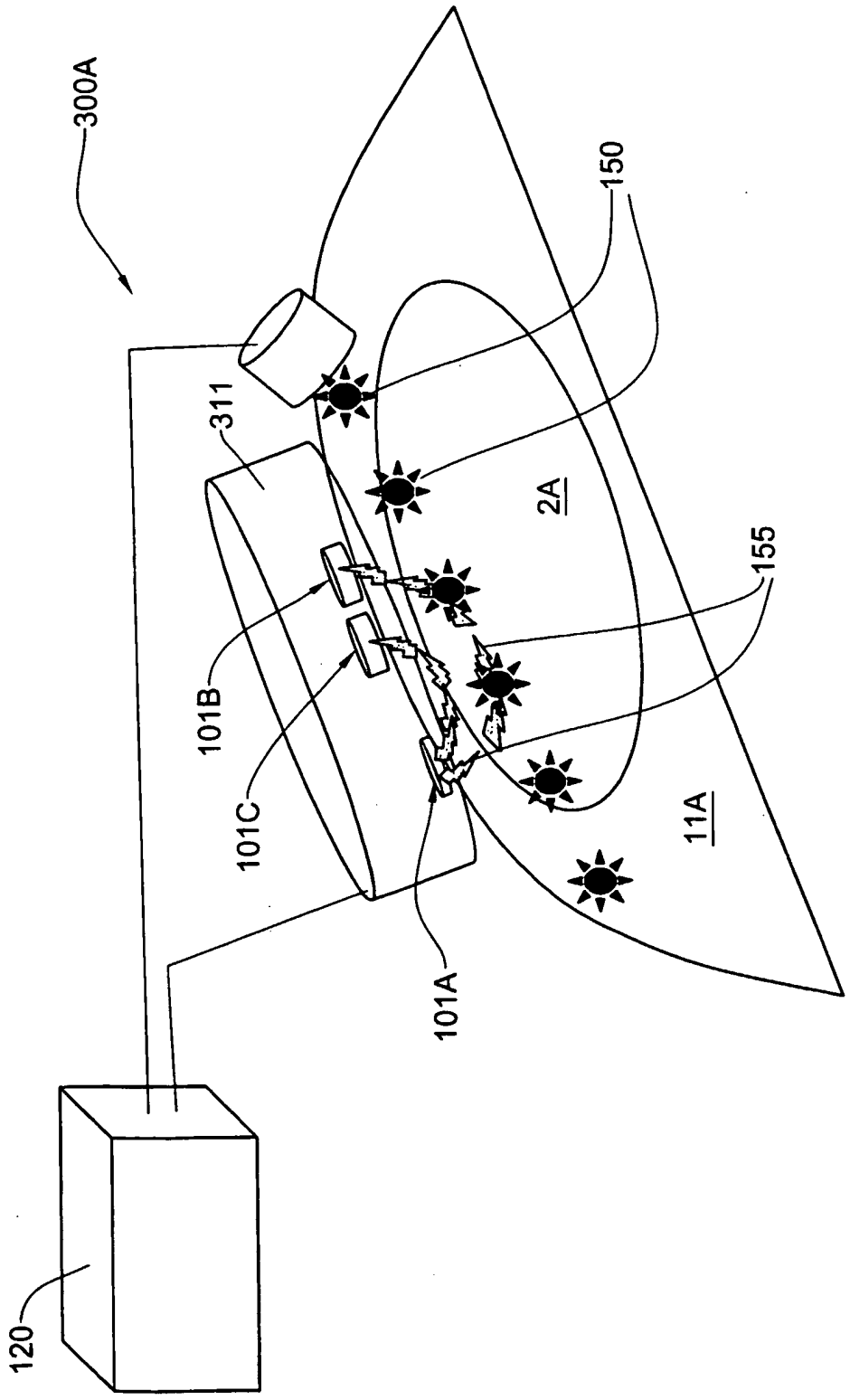

FIG. 3D

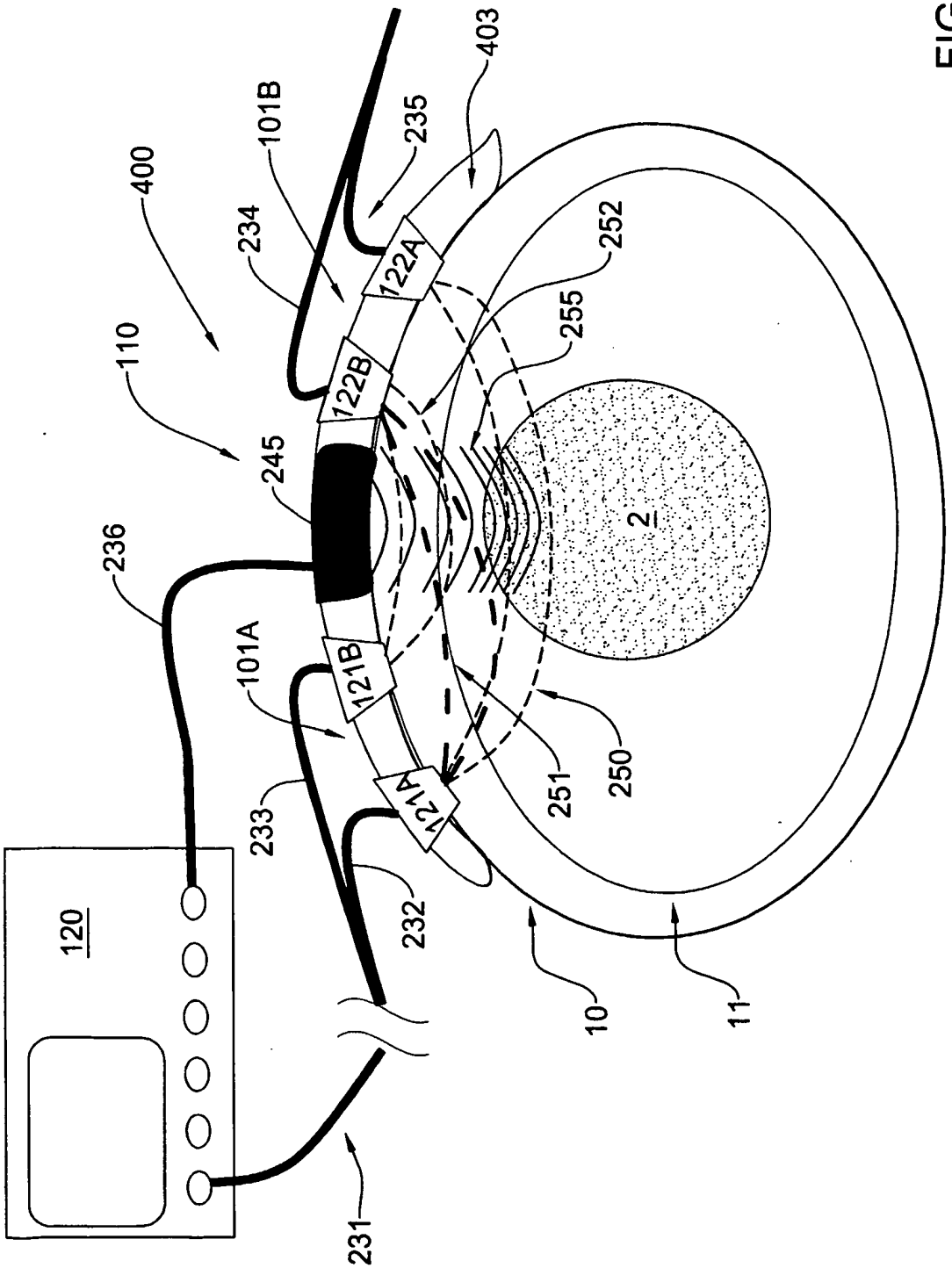
400
110
101B
234
235
403
122A
252
255
122B
245
236
101A
121B
233
121A
251
250
232
120
231
10
11
2

FIG. 4

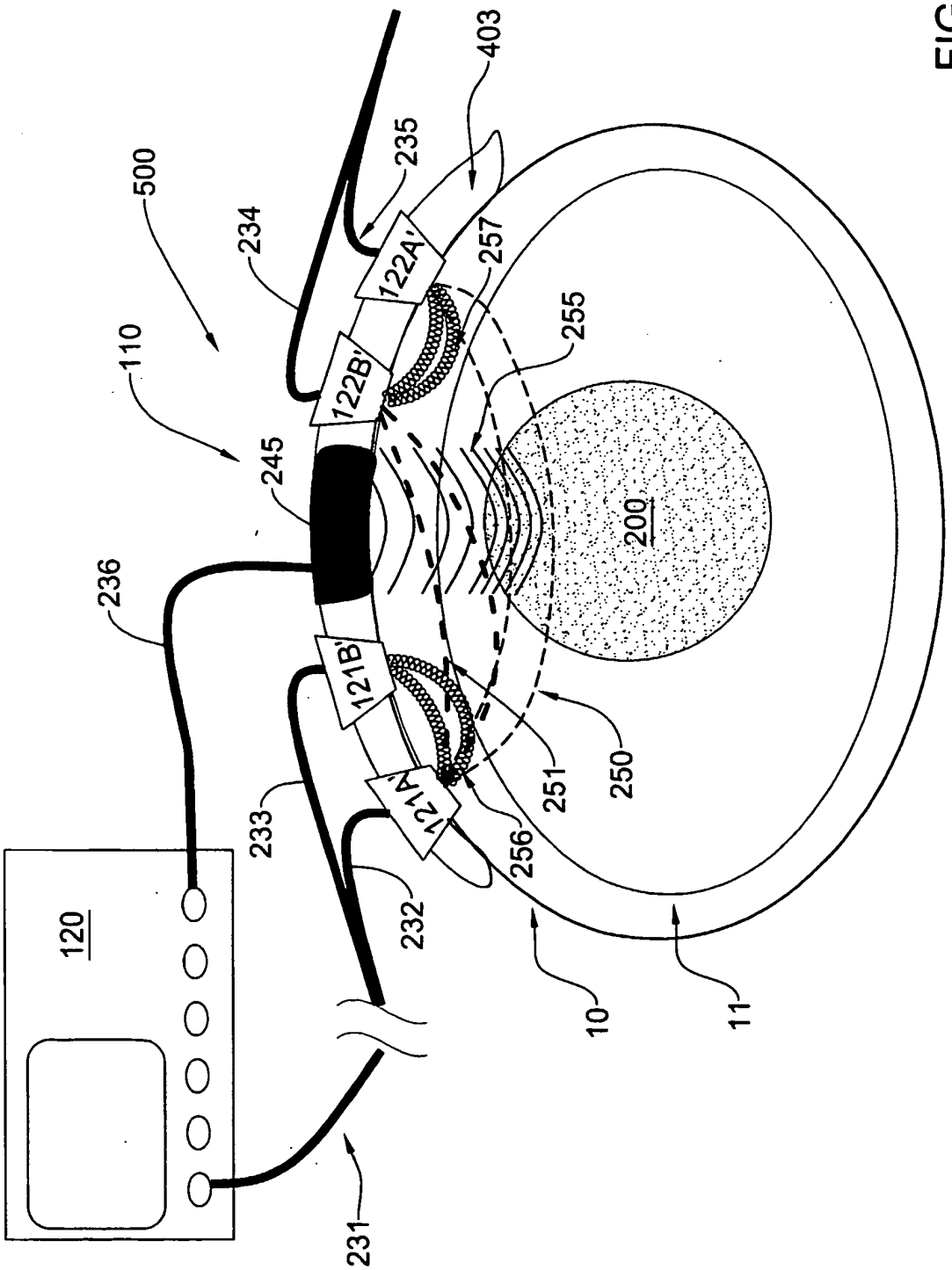
500
110
234
235
403
122A'
257
255
122B'
245
236
200
121B'
251
250
233
121A'
256
232
120
10
11
231

FIG. 5

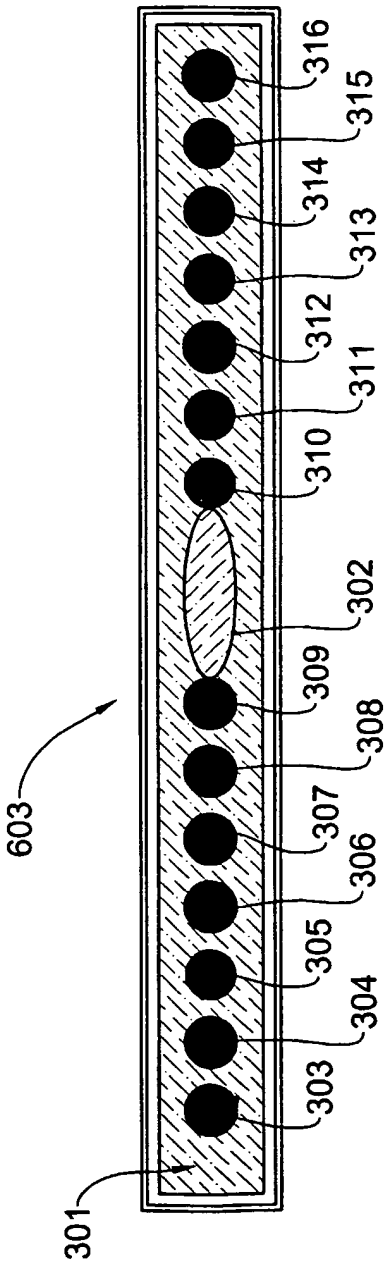
603
301
316
315
314
313
312
311
310
302
309
308
307
306
305
304
303

FIG. 6A

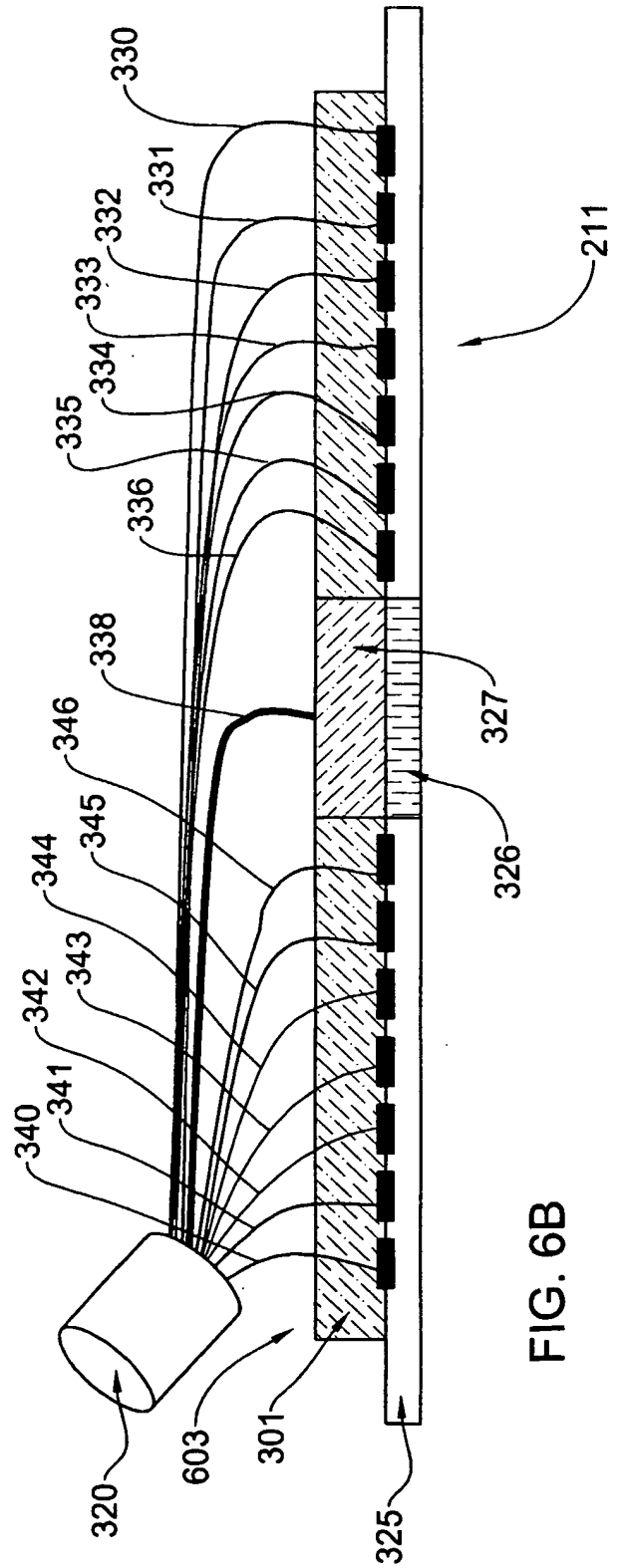
330
331
332
333
334
335
336
338
346
345
344
343
342
341
340
211
327
326
320
603
301
325

FIG. 6B

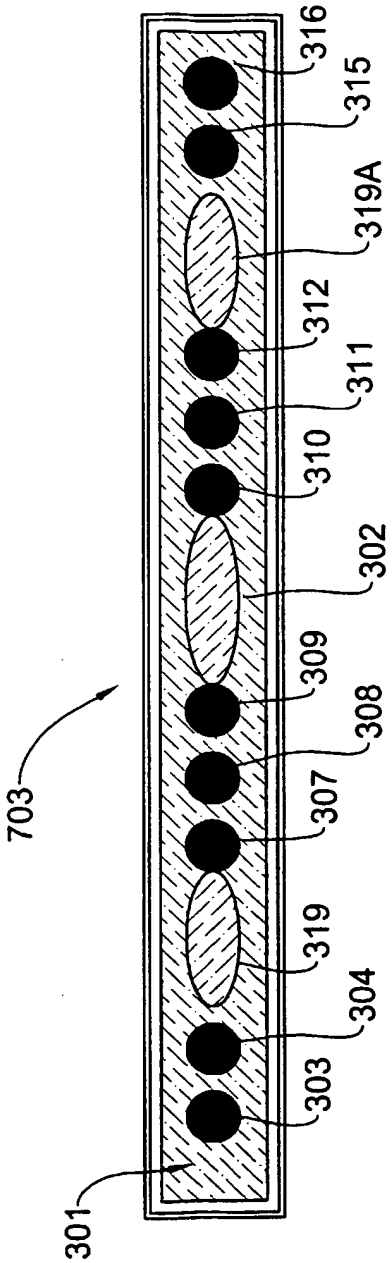
703
301
303
304
319
307
308
309
302
310
311
312
319A
315
316

FIG. 7A

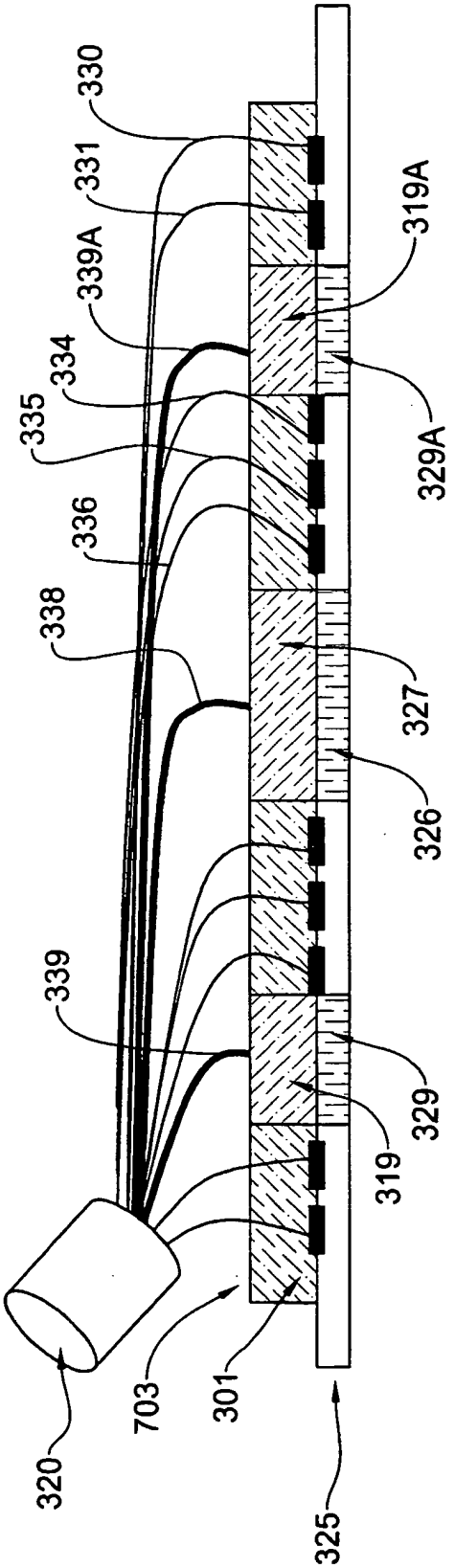
320
703
301
325
339
338
336
335
334
339A
331
330
319A
329A
327
326
329
319

FIG. 7B

REFERENCES CITED IN THE DESCRIPTION

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- **F. ROUSSEAU ; P. HELLIER ; C. BARILLOT.** Calibration Method for 3D Freehand Ultrasound. *Medical Image Computing and Computer Assisted Intervention, MICCAI'03,* November 2003 **[0142]**

专利名称(译)	无创光学监测感兴趣区域		
公开(公告)号	EP1675501B1	公开(公告)日	2013-09-04
申请号	EP2004770506	申请日	2004-09-12
[标]申请(专利权)人(译)	OR-NIM医疗有限公司		
申请(专利权)人(译)	OR-NIM MEDICAL LTD.		
当前申请(专利权)人(译)	OR-NIM MEDICAL LTD.		
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发明人	BALBERG, MICHAL PERY-SCHECHTER, REVITAL OLSHANSKY, MICHAL		
IPC分类号	A61B5/00 A61B A61B5/024 A61B5/08		
CPC分类号	A61B5/0097 A61B5/02411 A61B5/08 A61B5/14542 A61B5/1464 A61B5/7264 A61B2562/0233 A61B2562/043 G01S15/8968		
优先权	60/502212 2003-09-12 US 60/502210 2003-09-12 US 60/553142 2004-03-16 US 60/581376 2004-06-22 US		
其他公开文献	EP1675501A2 EP1675501A4		
外部链接	Espacenet		

摘要(译)

装置和方法包括用于监测人体中感兴趣区域的参数的探针装置。该装置的支撑结构承载光源组件的光输出端口，光检测组件的光输入端口和声学单元的声输出端口的布置。该布置使得能够选择光输出端口，光输入端口和声输出端口用于操作条件，在该操作条件下，来自声输出端口的声波和来自光输出端口的照明光在区域中重叠。在体内感兴趣的区域内，由此引起声波对光的标记，并且光输入端口收集从重叠区域散射的光和从感兴趣区域外部散射的光。还描述了其他实施例。